

Top 25 Most-Cited Articles on Robotic-Assisted Lumbar Spine Surgery

ANDY TON, BS¹; NICOLE HANG, BA¹; WILLIAM LIU, BS¹; RYAN LIU, BS¹; PATRICK C. HSIEH, MD²;
JEFFREY C. WANG, MD¹; RAYMOND J. HAH, MD¹; AND RAM K. ALLURI, MD¹

¹Department of Orthopedic Surgery, Keck School of Medicine at The University of Southern California, Los Angeles, CA, USA; ²Department of Neurological Surgery, Keck School of Medicine at The University of Southern California, Los Angeles, CA, USA

ABSTRACT

Background: Robot-guided lumbar spine surgery has evolved rapidly with evidence to support its utility and feasibility compared with conventional freehand and fluoroscopy-based techniques. The objective of this study was to assess trends among the top 25 most-cited articles pertaining to robotic-guided lumbar spine surgery.

Methods: An “advanced document search” using Boolean search operator terms was performed on 16 November 2022 through the Web of Science and SCOPUS citation databases to determine the top 25 most-referenced articles on robotic lumbar spine surgery. The articles were compiled into a directory and hierarchically organized based on the total number of citations.

Results: Cumulatively, the “Top 25” list for robot-assisted navigation in lumbar spine surgery received 2240 citations, averaging 97.39 citations annually. The number of citations ranged from 221 to 40 for the 25 most-cited articles. The most-cited study, by Kantelhardt et al, received 221 citations, averaging 18 citations per year.

Conclusions: As utilization of robot-guided modalities in lumbar spine surgery increases, this review highlights the most impactful studies to support its efficacy and implementation. Practical considerations such as cost-effectiveness, however, need to be better defined through further longitudinal studies that evaluate patient-reported outcomes and cost-utility.

Clinical Relevance: Through an overview of the top 25 most-cited articles, the present review highlights the rising prominence and technical efficacy of robotic-guided systems within lumbar spine surgery, with consideration to pragmatic limitations and need for additional data to facilitate cost-effective applications.

Level of Evidence: 5

Lumbar Spine

Keywords: robotic spine surgery, lumbar, pedicle screw, navigation, clinical outcomes

INTRODUCTION

With continuous strides toward refining minimally invasive surgery (MIS) techniques and optimizing clinical outcomes, the cross integration of technological developments has given rise to advancements within the field of spine surgery. The advent of robotic surgical systems is one such area of growth aimed at improving surgical precision and has gained considerable traction since its foremost applications within joint arthroplasty procedures.^{1,2} Within spine surgery, robotic-assisted technology has been shown to confer benefits to both surgeons and patients by minimizing fatigue, visual errors, and perioperative complications.^{3,4}

In view of its initial success, robotics guidance has expanded surgical capabilities in the field of lumbar spine surgery. Studies have shown that robotics-assisted posterior instrumentation in lumbar spine fusion is both safe and highly effective and moreover allows spine surgeons to preserve surgical accuracy and fine motor control through extended procedures.⁵ In assessments

of pedicle screw placement accuracy, reports across the literature have demonstrated significant reductions in screw malpositioning, postoperative complications, and subsequent revision risk with robotic-assisted procedures compared with conventional freehand techniques and fluoroscopy-guided navigation.^{4,6} Incorporation of robotic surgical platforms further enables additionally detailed preoperative planning for tailored selection of implants fitted to patients’ individualized anatomy.⁷ With evidence to support its utility, applications of robotic systems have conjointly expanded with that of newly developing techniques within the field, including single-position lumbar interbody fusions.^{8,9} As evidence unfolds to substantiate contemporary iterations of robotic surgical platforms, the use of robotic-guided modalities within spine surgery will likely continue to evolve. As such, understanding and awareness of the most impactful studies to support the application, feasibility, and efficacy of robotics within spine surgery is important to contend with its expanding role; to

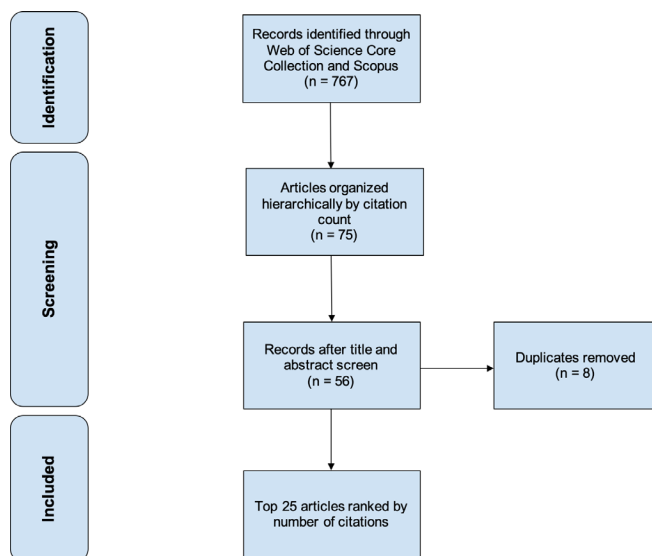


Figure 1. Flowchart diagram outlining the systematic review process used to identify the top 25 most-cited articles.

accomplish these aims, this review examines the top 25 most-cited articles on robotic lumbar surgery.

MATERIALS AND METHODS

Articles of interest were queried through a systematic search performed on November 2022 using Boolean operator terms within SCOPUS and Clarivate Analytics' Web of Science database, which comprises the Web of Science Core Collection, MEDLINE (Pubmed), and BIOSIS databases. These databases were selected based on their ability to hierarchically organize peer-reviewed articles by number of citations, which is suited for the purposes of this study. Only articles written in English were included in our study. The 25 most-cited articles were compiled into a ranked list after sorting results in descending order based on the total number of citations (Figure 1). The following details were extracted from the 25 articles: year of publication, journal title, total citation count, the average number of citations annually, and study summary. Duplicate entries between the Web of Science and SCOPUS databases were excluded. Article content was assessed to determine a summative "Top 25" list on robotic-assisted lumbar spine surgery.

RESULTS

An initial search of the Web of Science database for robotic-assisted lumbar spine surgery yielded 445 articles, amassing a total of 5927 citations. Similarly, the SCOPUS database search generated 322 articles with a combined 3951 citations. The

leading 25 articles were ranked based on total citation count (Table 1).^{4-6,10-31} The resulting list was further screened to ensure adherence to the inclusion criteria and pertinence to the intended topic search.

Overall, the "Top 25" most-cited articles totaled 2240 citations, averaging 97.39 citations annually. The most-cited article by Kantelhardt et al received 221 citations in total, averaging 18 citations annually since publication in 2011.¹⁰ Devito et al authored the second most-cited article in 2010 with 215 citations overall and an annual average of 17 citations.¹¹ Relative to the preceding studies, the third most-cited article was published more recently, in 2017, by Hyun et al and has since garnered 148 citations with an average of 30 per year.¹² The 25 most-cited article by Wolf et al accrued 40 citations overall at a yearly rate of 2 citations since 2001.³¹

Article publication year ranged from 2001 to 2020. Among the top 25, the highest number of articles published on this topic was in 2017 ($n = 6$; Figure 2). Regarding publication trends, *Spine* published the highest number of articles, producing 7 of the 25 most-cited articles on robotic-assistance in lumbar spine surgery (Figure 3). *Neurosurgical Focus* and *The European Spine Journal* each published 3 articles, making these 2 journals tied for the second-highest number of publications on this subject.

A comprehensive review revealed that our "Top 25" cohort consisted of 18 case series, 7 cohort studies, 2 systematic reviews/meta-analyses, and 1 technical review. The Newcastle-Ottawa scale, a validated scoring metric, was used to assess the quality of case series included within our ranked list. This system considers several metrics including comparability, selection, and ascertainment of exposure/outcome of interest^{6,32,33} (Table 2). Articles are scored using a 9-point scale, with 0 corresponding to lower quality and 9 denoting the highest quality. Among our ranked list, scores ranged from 5 to 8, with the average score being 6.6. To evaluate cohort studies, the Joanna Briggs Institute critical appraisal tool was selected as it is the only validated instrument to assess cohort studies on the basis of trustworthiness, relevance, and results.³⁴ This scoring system allocates scores from 0 to 10, with the lowest quality studies obtaining 0 and the highest quality studies achieving 10. Our cohort received scores ranging from 3 to 10, with the average score being 6.5 (Table 3).

Table 1. Top 25 most-cited articles on robotic-assisted lumbar spine surgery ranked hierarchically by cumulative number of citations.

Author and Publication Year	Journal	Summary Description	Times Cited (Total)	Citations Per Year	Robot System
1. Kantelhardt et al (2011) ¹⁰	European Spine Journal	Retrospective cohort analysis of 112 consecutive patients demonstrating shorter intraoperative fluoroscopy time and increased screw accuracy within open robotic-assisted vs conventional open pedicle screw placement.	221	20	SpineAssist
2. Devito et al (2010) ¹¹	Spine	Retrospective observational case series of 3271 pedicle screw and guide-wire insertions with SpineAssist guidance across 14 hospitals from June 2005 to June 2009, wherein clinical acceptance and accuracy were assessed and compared with freehand techniques as reported by the literature.	215	18	SpineAssist
3. Hyun et al (2017) ¹²	Spine	Randomized clinical trial of 60 patients showing significantly reduced fluoroscopy exposure and length of stay in patients undergoing single- and two-level robotic-guided lumbar fusion relative to conventional fluoroscopic guidance.	148	30	Renaissance
4. Schatlo et al (2014) ¹³	Journal of Neurosurgery: Spine	Retrospective cohort analysis of 95 consecutive patients with degenerative lumbar pathologies showing comparable surgical time, length of stay, and screw placement accuracy in robotic-assisted vs fluoroscopy.	130	16	SpineAssist
5. Kim et al (2017) ¹⁴	International Journal of Medical Robotics and Computer-Assisted Surgery	Randomized controlled trial of 78 patients with lumbar spinal stenosis showing superior outcomes with respect to facet joint violation and convergence orientation with robotic-assisted PLIF vs conventional freehand techniques.	122	24	Renaissance
6. Lieberman et al (2006) ¹⁵	Neurosurgery	Observational cadaveric case study substantiating screw placement accuracy with SpineAssist when comparing actual screw and planned screw trajectories on postprocedure computed tomography.	120	8	SpineAssist
7. Pechlivanis et al (2009) ¹⁶	Spine	Prospective observational case series of 31 patients validating accuracy of pedicle screw placement in patients undergoing PLIF with percutaneous posterior pedicle screw insertion using passive guidance provided by a bone-mounted miniature robotic device (SpineAssist).	118	9	SpineAssist
8. Lonjon et al (2016) ⁴	European Spine Journal	Prospective 1:1 matched-cohort analysis of 20 consecutive patients reporting higher screw placement precision using robotic-assistance (ROSA) over freehand techniques.	111	19	ROSA
9. van Dijk et al (2015) ¹⁷	Spine	Retrospective case series of 112 consecutive patients undergoing PLIFs with SpineAssist demonstrating accurate screw placement, wherein intraoperative screw placement was consistent with preoperative plan.	92	13	SpineAssist
10. Lieberman et al (2012) ¹⁸	Journal of Spinal Disorders and Techniques	Prospective cohort analysis of 12 cadavers across 17 surgeons showing decreased radiation exposure, fluoroscopy time per screw, procedure time, screw placement deviation, and pedicle wall breaches while maintaining increased accuracy of percutaneous pedicle screw placement with the use of the SpineAssist system compared with freehand techniques.	91	9	SpineAssist
11. Keric et al (2017) ¹⁹	Neurosurgical Focus	Retrospective case series of 413 patients who underwent spinal screw implantation with Renaissance showing high reliability and accuracy in screw placement with lower peri- and early postoperative complications relative to other percutaneous screw placement techniques across the literature.	81	16	Renaissance
12. Barzilay et al (2006) ²⁰	International Journal of Medical Robotics and Computer-Assisted Surgery	Prospective case series of 15 patients who underwent robot-assisted lumbar spine fusion with the SpineAssist system which identified technical and clinical variables contributing to difficult cases.	77	5	SpineAssist
13. Lefranc et al (2016) ²¹	Expert Review of Medical Devices	Technical review outlining surgical technique, indications for use, future directions, and advantages associated with use of the new ROSA robot in performing accurate pedicle screw placement and minimally invasive percutaneous surgical procedures.	73	12	ROSA
14. Khan et al (2019) ⁵	Operative Neurosurgery	Retrospective case series of 20 patients who underwent robotically assisted pedicle screw insertion performed by a single surgeon with preliminary results showing 98.7% accuracy in 75 pedicle screw placements, reinforcing feasibility of robotic guidance in lumbar spine surgery.	71	24	Mazor X

Table 1. Continued.

Author and Publication Year	Journal	Summary Description	Times Cited (Total)	Citations Per Year	Robot System
15. Kim et al (2015) ²²	Spine	Prospective randomized controlled study that demonstrated similar quality of performance and accuracy as measured by a cumulative summation test in pedicle screw fixation in 20 patients who underwent robot-assisted MIS PLIF and 20 patients who underwent conventional open PLIF using freehand technique.	67	10	Renaissance
16. Schatlo et al (2015) ²³	Acta Neurochirurgica	Retrospective chart review of 258 patients requiring thoracic and/or lumbar spine surgery with posterior instrumentation showed that robot-assisted screw placement is safe with a 3.8% screw malposition rate.	67	10	TiRobot
17. Gao et al (2018) ²⁴	European Spine Journal	Systematic review and meta-analysis of 6 studies incorporating 158 patients (688 pedicle screws) in the robot-assisted group and 148 patients (672 pedicle screws) in the conventional freehand group demonstrated that both groups exhibited similar accuracy rate of pedicle screw implantation, but the robot-assisted technique was associated with longer operative time.	65	16	N/A (5 Mazor, 1 Tianji)
18. Le et al (2018) ⁶	World Neurosurgery	Retrospective matched-cohort study of 58 patients undergoing pedicle screw insertion through the cortical bone for lumbar fixation that demonstrated perfect trajectory for 87.2% of robotic-assisted screw insertion and 66.9% of conventional freehand screw instrumentation.	59	15	Renaissance
19. Urakoy et al (2017) ²⁵	Neurosurgical Focus	Retrospective review of prospectively collected data from 33 patients who underwent robot-assisted thoracolumbar pedicle instrumentation that showed no correlation regarding speed and accuracy of instrumentation between surgeon's years of operative experience and commitment to spine surgery as their future speciality.	49	10	Renaissance
20. Li et al (2020) ²⁶	Spine	Meta-analysis of 9 randomized controlled trials with 696 patients demonstrated that robot-assisted pedicle screw placement reduced radiation dose and decreased intraoperative radiation exposure time while showing greater accuracy compared with pedicle screw instrumentation by conventional freehand technique.	47	24	TiRobot
21. Schröder et al (2017) ²⁷	Neurosurgical Focus	Retrospective cohort study of 72 patients who had undergone an MIS PLIF or MIS TLIF and completed a follow-up ≥12 months demonstrated that robot-guided screw trajectories are more accurate compared with trajectories established by freehand techniques which reduce rate of revision surgery for screw malposition and improve visual analog scale and Oswestry Disability Index scores.	46	9	Renaissance
22. Fan et al (2017) ²⁸	Medical Science Monitor	Prospective cohort study of 890 pedicle screws placed in 190 patients for treatment of degenerative lumbar disease demonstrated that robot-assisted technique unsuccessfully showed significant differences for accuracy of pedicle screw insertion compared with freehand technique but greatly reduced blood loss, fluoroscopy time per screw, and postoperative stay.	45	9	SpineAssist
23. Kuo et al (2016) ²⁹	PLoS ONE	Retrospective review of 64 patients who either underwent or did not undergo TLIF demonstrated that the Renaissance robotic system can accurately place pedicle screws, and secondary registration enhances accuracy by providing intraoperative evaluation of screw positioning.	45	8	Renaissance
24. Tian et al (2020) ³⁰	Neurospine	Case series of 62 thoracolumbar pedicle screws implanted in 12 patients using 5G telerobotic remote telecommunication showed the potential of utilizing telemedical service in the future.	40	20	TiRobot
25. Wolf et al (2001) ³¹	Spine	Observational case series of morphometric data using computed tomography of the lumbar spine of 55 patients who provided additional information on vertebrae geometry and its relation to entry points for screw insertion for spinal procedures.	40	2	N/A

Abbreviations: MIS, minimally invasive surgery; PLIF, posterior lumbar interbody fusion; TLIF, transforaminal lumbar interbody fusion.

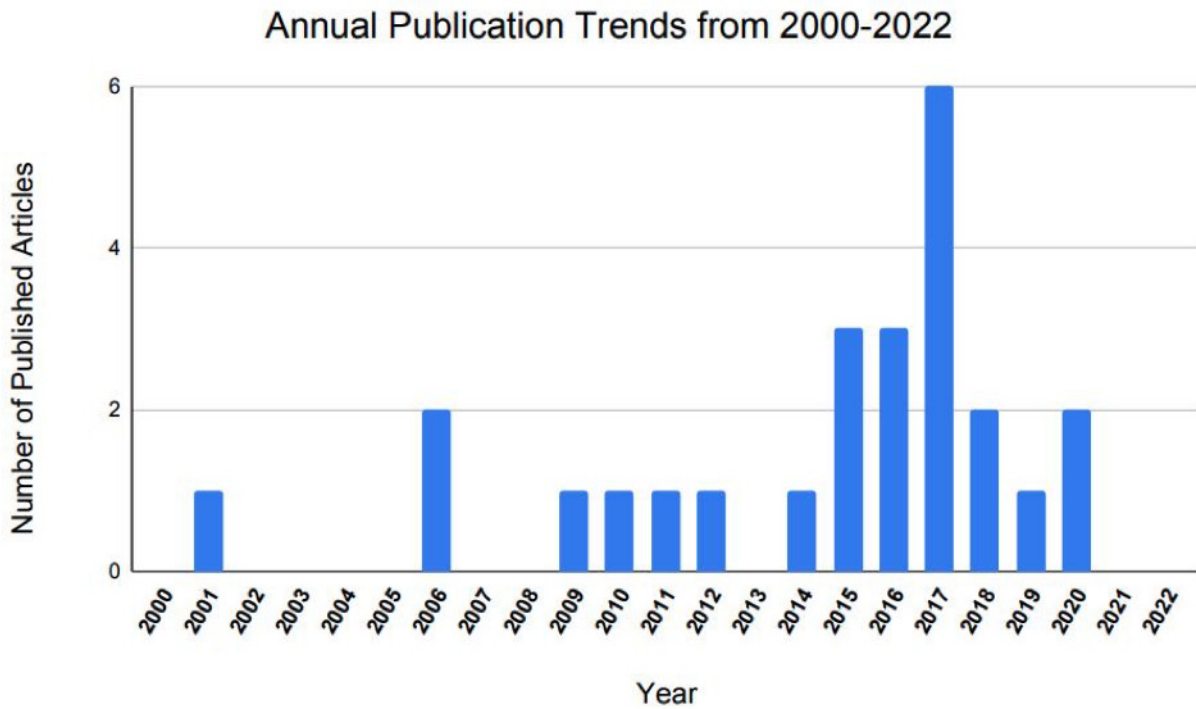


Figure 2. Annual publication trends in articles on robotic lumbar spine surgery from 2000 to 2022.

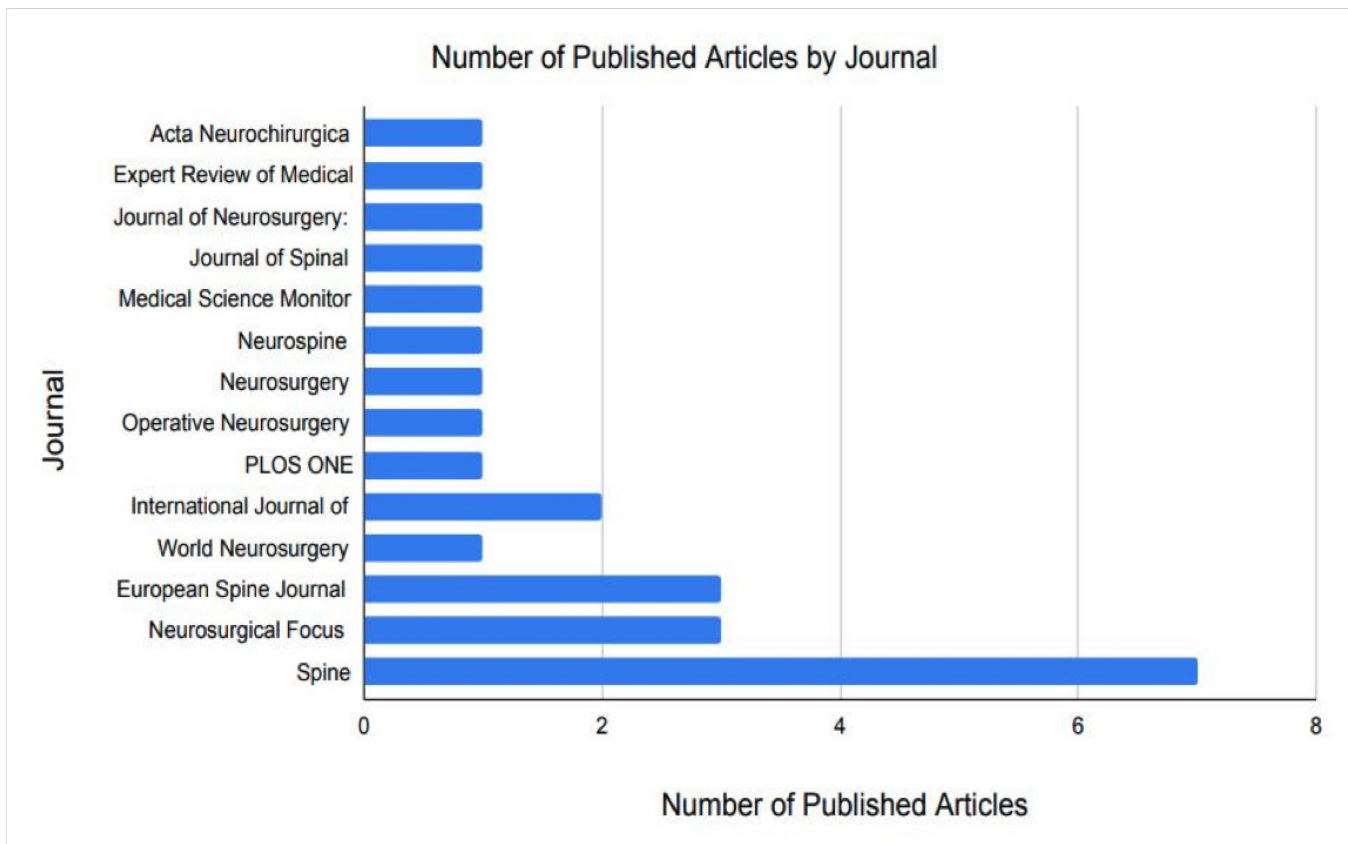


Figure 3. Number of published articles by journal on robotic lumbar spine surgery from 2000 to 2022.

Table 2. Newcastle-Ottawa assessment scale of cohort studies within the top 25 most-cited articles ordered by citation ranking.

Study	Representative of Cohorts	Selection of Nonexposed Cohort	Ascertainment of Exposure	Outcome of Interest Absent at Start of Study	Cohort Comparability	Outcome Assessment	Sufficient Follow-up	Adequacy of Follow-up	Total Score
1. Kantelhardt et al (2011) ¹⁰	*	*	*	*	*	*	*	*	8
3. Hyun et al (2017) ¹²	*	*	*	*	**	*	*	*	9
4. Schatlo et al (2014) ¹³	*	*	*	*	**	*	*	*	9
5. Kim et al (2017) ¹⁴	*	*	*	*	**	*	*	*	9
8. Lonjon et al (2016) ⁴	*	*	*	*	**	*	*	*	9
10. Lieberman et al (2012) ¹⁸	-	-	*	-	-	*	*	*	4
15. Kim et al (2015) ²²	*	*	*	*	-	*	*	*	7
18. Le et al (2018) ⁶	-	-	*	*	*	*	*	*	6
19. Urakov et al (2017) ²⁵	-	-	-	-	-	-	-	-	0
21. Schröder et al (2017) ²⁷	-	-	-	-	-	-	-	-	0
22. Fan et al (2017) ²⁸	*	*	*	*	-	*	*	*	7

DISCUSSION

The current study found that the top 25 most-cited articles on robotic-assisted lumbar spine surgery were largely descriptive case series followed by cohort studies. The most highly cited article was published in *European Spine Journal* by Kantelhardt et al in 2011, totaling 221 citations. The authors performed a single-institution retrospective cohort analysis using Spine-Assist (Mazor Surgical Technologies, Caesarea, Israel) to compare intra- and perioperative metrics including pedicle screw placement accuracy, fluoroscopy duration, and postoperative opioid use between robotic-assisted approaches, both open and percutaneous, to conventional open procedures. The study included 112 consecutive cases with pedicle screw fixation from 2006 to 2009, with all approaches being performed across 6 surgeons.¹⁰ Kantelhardt et al describe improved screw accuracy and significantly decreased x-ray duration (34 vs 77 seconds), postoperative opioid use (46% vs 89%), and incidence of intraoperative adverse events (4.7% vs 9.1%) with robotics-guidance compared with conventional techniques.¹⁰ No significant differences were

found with respect to operative duration, even when accounting for time attributed to configuring the robotics system. The heterogeneity of indications included within the study, along with its retrospective design, remains an important limitation to consider. In spite of this, these findings provide evidence to support implementation of robotic-assisted lumbar spine surgery.

The second most highly cited article, published in 2010 by Devito et al, was a multicenter retrospective case series in which the authors described the clinical acceptance and implant placement accuracy across 14 institutions using SpineAssist. Overall, the study involved 3721 pedicle screw and guide-wire insertions over 840 cases from 2005 to 2009, spanning the subsequent years after which SpineAssist—the first robotic-based platform in spine surgery—received US Food and Drug Administration approval in 2004.³⁵ Clinical acceptance was established for 98% ($n = 3204$) of implants using intraoperative fluoroscopy. Accuracy was assessed using postoperative computed tomography (CT) across 646 placed pedicle screws, with 89.3% of screws placed entirely within the pedicle, and 9% of

Table 3. Joanna Briggs Institute (JBI) critical appraisal tool assessments of case series within the top 25 most-cited articles ordered by citation ranking.

JBI Assessment Categories	2. Devito et al (2010)	6. Lieberman et al (2006)	7. Pechlivanis et al (2009)	9. van Dijk et al (2015)	11. Keric et al (2017)	12. Barzilay et al (2006)	14. Khan et al (2019)	16. Schatlo et al (2015)	23. Kuo et al (2016)	24. Tian et al (2020)	25. Wolf et al (2001)
Clear inclusion criteria	No	No	Yes	Yes	Yes	No	Yes	Yes	Yes	No	No
Reliable data collection	No	Yes	No	Yes	Yes	No	Yes	Yes	Yes	No	No
Valid methodology for assessing outcomes	Yes	Yes	Yes	Yes	Yes	No	Yes	Yes	Yes	No	No
Consecutive series	Yes	No	Yes	Yes	Yes	Yes	Yes	Yes	Yes	No	No
Inclusion of all possible participants/cases	No	No	Yes	No	Yes	Yes	Yes	Yes	Yes	No	Yes
Relevant demographics reported	Yes	No	Yes	Yes	Yes	Yes	No	No	Yes	Yes	Yes
Baseline clinical characteristics reported	No	No	No	No	Yes	Yes	No	No	Yes	No	No
Clear description of outcomes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Study site/setting described	Yes	No	No	No	Yes	Yes	No	No	Yes	Yes	No
Appropriate statistical analysis	Yes	Yes	Yes	Yes	Yes	No	Yes	Yes	Yes	Yes	Yes
Total Score (/10)	6	4	7	7	10	6	8	7	10	4	3

breached screws being within 2 mm.¹¹ Stratifying by region, the authors found that 79% (30/38) thoracic and 90% (547/608) lumbar screw placements were contained entirely within the pedicle compared with 56% thoracic and 87.3% lumbar screws for freehand techniques.³⁶ All comparisons, however, were made relative to the existing literature and, therefore, presented a limitation within this study. Nonetheless, the article was significantly impactful in establishing the clinical efficacy of robotic-assisted spine surgery—particularly in consideration of SpineAssist being the foremost model in clinical practice. The study has since garnered 215 citations, with an annual average of 19.5 citations since publication in 2010.

The third most-cited article was published in 2017 by Hyun et al. Herein, the authors designed a prospective randomized clinical trial to assess radiation exposure and patient-reported outcomes (PROs) between fluoroscopy-guided open procedures and robotic-assisted MIS approaches using the Renaissance system (Mazor Robotics Ltd) for patients undergoing lumbar fusion.¹² Their study was conducted with consideration of the high levels of radiation exposure commensurate with the learning curves for MIS techniques. Their study revealed significantly reduced radiation exposure and hospital length of stay with robotic-guided MIS relative to fluoroscopic open procedures. Among PROs, visual analog scale back and leg pain scores were improved for robotic-assisted cases, while Oswestry Disability Index scores remained similar across both groups.¹² Relative to the 2 preceding studies, the total number of citations, 148, for this article was noticeably reduced; it is important to note, however, that this article was published significantly later in 2017 compared with Devito et al in 2010 and Kantelhardt et al in 2011, respectively. Further analysis reveals that Hyun et al carried the highest average annual citation rate at 30 per year, which was the highest by this metric among the top 25 articles on robotic-assisted lumbar spine surgery.

Interestingly, 2017 was the most common publication year within this list—comprising 6 articles overall—followed by 2015 and 2016, with 3 articles for each.^{12,14,19,25,27,28} Publications from 2015 to 2017 represented 48% (12/25) of the articles within the top 25 most-cited list. Of the articles published in 2017, 5/6 (83%) reviewed the Renaissance robotic-guidance system, with the remaining study by Fan et al²⁸ over-viewing SpineAssist, the foremost iteration, which was designed by Mazor Robotics.

Despite other models such as ROSA Spine by Zimmer Biomet having received FDA clearance in

2016, Renaissance was approved in 2011 and therefore allowed for longitudinal studies spanning multiple years. Moreover, FDA clearance of SpineAssist in 2004 marked the introduction of robotics use in spine surgery; as such, subsequent models produced by Mazor Robotics had already gained considerable traction as the sole proprietor during this time.³⁷ Relative to Renaissance, publications revolving around SpineAssist saw greater remportal distribution, which was likely due to limited accessibility as the first commercially available robotic system apt for spine surgery applications.³⁸ Following acquisition of Mazor Robotics by Medtronic in 2018, newer models such as the Mazor X and Mazor X Stealth Edition have been implemented with improved preoperative planning and intraoperative navigation systems for the latter.³⁹ These developments have augmented the minimally invasive nature of these systems and obviate the use of K wires and percutaneous pins as required by previous models.⁴⁰ Nonetheless, the advent of robotic-assisted spine surgery has since fostered an array of models, including ROSA ONE Spine (Zimmer Biomet, Warsaw, IN), ExcelsiusGPS (Globus Medical Inc., Audubon, PA), and TiRobot (TINAVI Medical Technologies, Beijing, China).⁴¹ With technological advancements driving further growth in robotic capabilities, future developments should anticipate the integration of other evolving facets within spine surgery.

As the utilization of robotic systems in spine surgery expands, high-quality prospective studies evaluating clinical and patient-centered outcomes are crucial to substantiate pragmatic and cost-effective applications.⁴² While the evidence presented within the top 25 most-cited articles pointedly advocate for robotics use in spine surgery, the comparative analyses are entirely premised on freehand techniques and/or conventional fluoroscopic guidance. Intraoperative CT navigation offers another avenue by which pedicle screw instrumentation accuracy has improved and at a significantly lower cost than contemporary robotic systems.⁴² Comparative studies have primarily focused on implant-related metrics, wherein robotic systems enabled optimal implant dimensions with comparable screw accuracy, while reducing fluoroscopy and screw placement time over CT navigation alone.^{43,44} While CT navigation further provides granular visualization and real-time visualization, latest-generation robotic platforms integrate real-time CT navigation to optimize work-flow efficiency and instrumentation accuracy.⁴⁰ Nonetheless, further biomechanical and clinical studies are required to assess potential long-term impact on clinical outcomes as current evidence indicates minimal benefits

in PROs.^{45,46} Park et al conducted a randomized controlled trial and found no differences in ODI and VAS leg and back score improvement between patients who underwent posterior lumbar interbody fusion using robot-assisted pedicle screw fixation or conventional freehand techniques.⁴⁷ As reimbursement shifts toward value-based care, understanding the impact of robotic platforms on PROs becomes increasingly important—especially in consideration of forthcoming technological developments.

Overall, economic advantages offered with robotics platforms are largely proposed upon improved implant accuracy and subsequent reduction in revision risk. Menger et al conducted a retrospective analysis of 557 thoracolumbar instrumentation cases and found that robotic assistance significantly reduced postoperative infection, length of stay, operative time, and revision risk, resulting in an estimated \$608,546 in savings over a year.⁴⁸ Ezeokoli et al reported higher variable direct costs for robotic-assisted spine procedures primarily owed to operating room time and supply-related expenses.⁴⁹ Psasias et al likewise discovered higher rates of complications and costs for robotic-guided procedures compared with open and MIS techniques.⁵⁰ Both studies, however, acknowledged potential confounding effects of surgeons' learning curves on cost-effectiveness measures, which was supported by Hu and Lieberman, who demonstrated significant improvements with increasing experience.⁵¹ As such, an accurate cost-utility analysis therefore calls for longitudinal, prospective studies that are able to capture the entire scope of practical considerations with implementation of robotics systems in spine surgery.

Limitations

The present study has several limitations. First, self-citation is a potential confounding factor that may disproportionately inflate the citation count of articles with lesser impact. Additionally, our database search was restricted to articles written in English, which might have resulted in the exclusion of pertinent articles that may have contributed significantly to the subject matter. Furthermore, the heterogeneity of study designs precluded the application of a uniform, standardized assessment scale throughout our ranked list. Finally, our analysis merely represents a snapshot of the literature at the time our literature search was conducted. As new research emerges and our comprehension of robotic-assistance in lumbar spine surgery expands, relative citation counts may fluctuate, leading to alternative conclusions.

CONCLUSIONS

This study provides our analysis of the current literature on robotic-assistance within spine surgery. Utilizing the 25 most-cited articles relating to this topic, publication trends regarding the efficacy and expanded capabilities of various robotic models are discussed. The predominant representation of select models among the same developers, however, underlines the need for further high-quality studies focusing on alternative models, which have since been implemented within clinical practice. Given that robotics platforms are being increasingly adopted, this review is intended to serve as a resource that outlines some of the most impactful evidence for its utility in spine surgery as further technological advancements continue to unfold.

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Corresponding Author: Andy Ton, Department of Orthopaedic Surgery, Keck Medical Center of USC, 1450 San Pablo St, HC4 Suite 5400, Los Angeles, CA, 90033, USA; andyton@usc.edu

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