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# Author Correction: Mobilise-D insights to estimate real-world walking speed in multiple conditions with a wearable device

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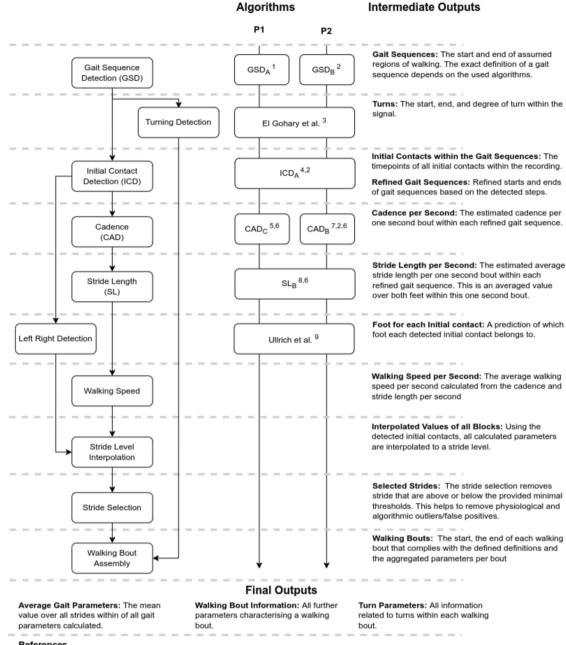
Correction to: Scientific Reports https://doi.org/10.1038/s41598-024-51766-5, published online 19 January 2024

The original version of this Article contained an error in Figure 7 where an incorrect reference was cited for one of the recommended algorithms for Gait Speed Detection (GSD). The original Figure 7 and accompanying legend appear below.

In addition, the Supplementary Information 1 file published with this Article contained errors in Tables 1 and 2. The Intraclass Correlation Coefficients (ICCs) for walking speed were incorrectly reported instead of the correct ICC values for stride length and cadence.

The original Supplementary Information 1 file is provided below.

The original Article and the Supplementary Information 1 file that accompanies the original Article have been corrected.



- 1 Iluz et al., "Automated Detection of Missteps during Community Ambulation in Patients with Parkinson's Disease."
- 2 Paraschiv-lonescu et al., "Locomotion and cadence detection using a single trunk-fixed accelerometer: validity for children with cerebral palsy in daily life-like conditions."
- 3 El-Gohary et al., "Continuous Monitoring of Turning in Patients with Movement Disability."
  4 McCamley et al., "An Enhanced Estimate of Initial Contact and Final Contact Instants of Time Using Lower Trunk Inertial Sensor Data."
- 5 Shin and Park, "Adaptive Step Length Estimation Algorithm Using Optimal Parameters and Movement Status Awareness."
- 6 Soltani et al., "Algorithms for Walking Speed Estimation Using a Lower-Back-Worn Inertial Sensor."
- 7 Lee et al., "Computational Methods to Detect Step Events for Normal and Pathological Gait Evaluation Using Accelerometer."
- 8 Zijlstra and Hof, "Assessment of Spatio-Temporal Gait Parameters from Trunk Accelerations during Human Walking."
- 9 Ullrich et al., "Machine Learning-Based Distinction of Left and Right Foot Contacts in Lower Back Inertial Sensor Gait Data."

Figure 7. Overview over the different algorithmic steps of the analytical pipeline with short explanations of the intermediate and final outputs of each of the algorithmic blocks; gait sequence detection (GSD), initial contact detection (ICD), cadence estimation (CAD) and stride length estimation (SL). Te algorithm column indicates the used algorithms for the two pipelines P1 (HA, COPD, CHF). (MS, PD, PFF) and P2 (MS, PD, PFF) Short citations for the algorithms are provided below the fgure. For more details see Table 1 in<sup>26</sup>.

## Additional information

**Supplementary Information** The online version contains supplementary material available at https://doi.org/1 0.1038/s41598-024-79454-4.

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