

Correction

Correction: Yi et al. A Software Platform for Quadruped Robots with Advanced Manipulation Capabilities. *Sensors* 2023, 23, 8247

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In the original publication [1], the Funding information was incorrectly printed. The correct Funding information appears below:

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The authors state that the scientific conclusions are unaffected. This correction was approved by the Academic Editor. The original publication has also been updated.

Reference

1. Yi, J.-B.; Nasrat, S.; Jo, M.-s.; Yi, S.-J. A Software Platform for Quadruped Robots with Advanced Manipulation Capabilities. *Sensors* **2023**, *23*, 8247. [[CrossRef](#)] [[PubMed](#)]

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