

Asymptotically scale-invariant occupancy of phase space makes the entropy S_q extensive

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Phase space can be constructed for N equal and distinguishable subsystems that could be probabilistically either *weakly* correlated or *strongly* correlated. If they are locally correlated, we expect the Boltzmann–Gibbs entropy $S_{BG} \equiv -k \sum_i p_i \ln p_i$ to be *extensive*, i.e., $S_{BG}(N) \propto N$ for $N \rightarrow \infty$. In particular, if they are independent, S_{BG} is *strictly additive*, i.e., $S_{BG}(N) = NS_{BG}(1)$, $\forall N$. However, if the subsystems are globally correlated, we expect, for a vast class of systems, the entropy $S_q \equiv k[1 - \sum_i p_i^q]/(q - 1)$ (with $S_1 = S_{BG}$) for some special value of $q \neq 1$ to be the one which is extensive [i.e., $S_q(N) \propto N$ for $N \rightarrow \infty$]. Another concept which is relevant is strict or asymptotic *scale-freedom* (or *scale-invariance*), defined as the situation for which all marginal probabilities of the N -system coincide or asymptotically approach (for $N \rightarrow \infty$) the joint probabilities of the $(N - 1)$ -system. If each subsystem is a binary one, scale-freedom is guaranteed by what we hereafter refer to as the *Leibnitz rule*, i.e., the sum of two successive joint probabilities of the N -system coincides or asymptotically approaches the corresponding joint probability of the $(N - 1)$ -system. The kinds of interplay of these various concepts are illustrated in several examples. One of them justifies the title of this paper. We conjecture that these mechanisms are deeply related to the very frequent emergence, in natural and artificial complex systems, of scale-free structures and to their connections with nonextensive statistical mechanics. Summarizing, we have shown that, for asymptotically scale-invariant systems, it is S_q with $q \neq 1$, and not S_{BG} , the entropy which matches standard, clausius-like, prescriptions of classical thermodynamics.

The entropy $S_q(1)$ is defined through^{§¶}

$$S_q \equiv k \frac{1 - \sum_{i=1}^W p_i^q}{q - 1} \quad (q \in \mathcal{R}; S_1 = S_{BG} \equiv -k \sum_{i=1}^W p_i \ln p_i), \quad [1]$$

where k is a positive constant ($k = 1$ from now on) and BG stands for Boltzmann–Gibbs. This expression is the basis of *nonextensive statistical mechanics* (16–18) (see <http://tsallis.cat.cbpf.br/biblio.htm> for a regularly updated bibliography), a current generalization of BG statistical mechanics. For $q \neq 1$, S_q is nonadditive (hence nonextensive) in the sense that for a system composed of (probabilistically) *independent* subsystems, the total entropy differs from the sum of the entropies of the subsystems. However, the system may have special probability correlations between the subsystems such that extensivity is valid, not for S_{BG} , but for S_q with a particular value of the index $q \neq 1$. In this paper, we address the case where the subsystems are all equal and distinguishable. Their correlations may exhibit a kind of scale-invariance. We may regard some of the situations of correlated probabilities as related to the remark (see refs. 19–23 and references therein) that S_q for $q \neq 1$ can be appropriate for nonlinear dynamical systems that have phase space unevenly occupied. We return to this point later.

We shall consider two types of models. The first one involves N binary variables ($N = 1, 2, 3, \dots$), and the second one involves N

continuous variables ($N = 1, 2, 3$). In both cases, certain correlations that are scale-invariant in a suitable limit can create an intrinsically inhomogeneous occupation of phase space. Such systems are strongly reminiscent of the so called scale-free networks (24, 25), with their hierarchically structured hubs and spokes and their nearly forbidden regions.

Discrete Models

Some Basic Concepts. The most general probabilistic sets for N equal and distinguishable binary subsystems are given in Fig. 1 with

$$\sum_{n=0}^N \frac{N!}{(N-n)!} \pi_{N,n} = 1$$

$$(\pi_{N,n} \in [0, 1]; N = 1, 2, 3, \dots; n = 0, 1, \dots, N). \quad [2]$$

Let us from now on call *Leibnitz rule* the following recursive relation:

$$\pi_{N,n} + \pi_{N,n+1} = \pi_{N-1,n} \quad (n = 0, 1, \dots, N-1; N = 2, 3, \dots). \quad [3]$$

This relation guarantees what we refer to as *scale-invariance* (or *scale-freedom*) in this article. Indeed, it guarantees that, for any value of N , the associated *joint probabilities* $\{\pi_{N,n}\}$ produce *marginal probabilities* which coincide with $\{\pi_{N-1,n}\}$. Assuming $\pi_{10} + \pi_{11} = 1$, and taking into account that the N th row has one more element than the $(N - 1)$ th row, a particular model is characterized by giving *one* element for each row. We shall adopt the convention of specifying the set $\{\pi_{N,0} \in [0, 1], \forall N\}$. Everything follows from it. There are many sets $\{\pi_{N,0}\}$ that satisfy Eq. 3. Let us illustrate with a few simple examples:

(i) $\pi_{N,0} = (2\pi_{10})^N / N + 1$ ($0 \leq \pi_{10} \leq 1/2; N = 1, 2, 3, \dots$). We have that all 2^N states have nonzero probability if $0 < \pi_{10} \leq 1/2$.

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[§]In the field of cybernetics and control theory, the form $S_\alpha \equiv 2^\alpha - 1/2^\alpha - 1 - 1(1 - \sum_i p_i^\alpha)$ was introduced in ref. 2, and was further discussed in ref. 3. With a different prefactor, it was rediscovered in ref. 4, and further commented in ref. 5. More historical details can be found in refs. 6–8. This type of entropic form was rediscovered once again in 1988 (16–18) and it was postulated as the basis of a possible generalization of Boltzmann–Gibbs statistical mechanics, nowadays known as *nonextensive statistical mechanics*.

[¶]Many entropic forms are related with S_q . A special mention is deserved by the Renyi entropy $S_q^R \equiv (\ln \sum_i p_i^q)/(1 - q) = \ln[1 + (1 - q)S_q]/(1 - q)$, and by the Landsberg–Vedral–Abe–Rajagopal entropy (or just *normalized S_q entropy*) $S_q^{LVAR} \equiv S_q/\sum_{i=1}^W p_i^q = [1 - (\sum_{i=1}^W p_i^q)^{-1}]/(1 - q) = S_q/[1 + (1 - q)S_q]$. The Renyi entropy was, according to ref. 9, first introduced in ref. 10, and then in ref. 11. The Landsberg–Vedral–Abe–Rajagopal entropy was independently introduced in ref. 12 and in ref. 13. Both S_q^R and S_q^{LVAR} are monotonic functions of S_q ; consequently, under identical constraints, they are all optimized by the *same* probability distribution. A two-parameter entropic form was introduced in ref. 14 which reproduces both S_q and Renyi entropy as particular cases. This scheme has been recently enlarged elegantly in ref. 15. S_{BG} and S_q (as well as a few other entropic forms that we do not address here) are concave and Lesche-stable for all $q > 0$, and provide a *finite* entropy production per unit time; S_q^R , S_q^{LVAR} , the Sharma–Mittal, and the Masi entropic forms (as well as others that we do not address here) violate all of these properties.

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$(N = 0)$	1
$(N = 1)$	$\pi_{10} \quad \pi_{11}$
$(N = 2)$	$\pi_{20} \quad \pi_{21} \quad \pi_{22}$
$(N = 3)$	$\pi_{30} \quad \pi_{31} \quad \pi_{32} \quad \pi_{33}$
$(N = 4)$	$\pi_{40} \quad \pi_{41} \quad \pi_{42} \quad \pi_{43} \quad \pi_{44}$

Fig. 1. Most general sets of joint probabilities for N equal and distinguishable binary subsystems.

$(N = 0)$	(1, 1)
$(N = 1)$	(1, 1/2) (1, 1/2)
$(N = 2)$	(1, 1/3) (2, 1/6) (1, 1/3)
$(N = 3)$	(1, 1/4) (3, 1/12) (3, 1/12) (1, 1/4)
$(N = 4)$	(1, 1/5) (4, 1/20) (6, 1/30) (4, 1/20) (1, 1/5)

Fig. 2. The left numbers within the parentheses correspond to Pascal triangle. The right numbers correspond to the Leibnitz harmonic triangle ($d = N$).

The particular case $\pi_{10} = 1/2$ recovers the original Leibnitz triangle itself (26) (see Fig. 2).

(ii) $\pi_{N,0} = (\pi_{10})^{N^\alpha}$ ($\alpha \geq 0; N = 1, 2, 3, \dots$). The $\alpha = 1$ instance corresponds to independent systems, i.e., $\pi_{N,n} = (\pi_{10})^{N-n} (1 - \pi_{10})^n$. If $0 < \pi_{10} < 1$, then all 2^N states have nonzero probability. The $\alpha = 0$ instance corresponds to $\pi_{N,0} = \pi_{10}, \pi_{N,n} = 0$ ($n = 1, 2, \dots, N - 1$) and $\pi_{N,N} = 1 - \pi_{10}$. If $0 < \pi_{10} < 1$, then only two among the 2^N states have nonzero probability, $\forall N$, namely the states associated with $\pi_{N,0}$ and $\pi_{N,N}$.

We may relax the Leibnitz rule to some extent by considering those cases where the rule is satisfied only asymptotically, i.e.,

$$\lim_{N \rightarrow \infty} \frac{\pi_{N,n} + \pi_{N,n+1}}{\pi_{N-1,n}} = 1 \quad (n = 0, 1, 2, \dots). \quad [4]$$

Such cases will be said to be not strictly but *asymptotically scale-invariant* (or *asymptotically scale-free*). This is, for a variety of reasons, the situation in which we are primarily interested. The main reason is that what vast classes of natural and artificial systems typically exhibit is not precisely power-laws, but behaviors which *only asymptotically become power-laws* (once we have corrected, of course, for any finite size effects). This is consistent with the fact that within nonextensive statistical mechanics S_q is optimized by q -exponential functions (see ref. 1 and references therein and refs. 27 and 28), which only asymptotically yield power-laws. It is consistent also with a new central limit theorem that has been recently conjectured (29) for specially correlated random variables.^{||}

Let us now introduce a further concept, namely *q-describability*. A model constituted by N equal and distinguishable subsystems will be called *q-describable* if a value of q exists such as $S_q(N)$ is *extensive*, i.e., $\lim_{N \rightarrow \infty} S_q(N)/N < \infty$. If that special value of q equals unity, this corresponds to the usual BG universality class. If that value of q differs from unity, we will have nontrivial universality classes. If the subsystems $\{A_i\}$ are not necessarily equal, the system is *q-describable* if an entropic index q exists such that $\lim_{N \rightarrow \infty} [S_q(A_1 + A_2 + \dots + A_N)/\sum_{i=1}^N S_q(A_i)] < \infty$. It should be clear that we could equally well demand the extensivity of say S_{2-q} [or even of $S_{Q(q)}$, where $Q(q)$ is some monotonically decreasing function of q satis-

fying $Q(1) = 1$] instead of that of S_q . This would of course have the effect of having nontrivial solutions for $q > 1$ whenever we had solutions for $q < 1$ if the extensivity that was imposed was that of S_q .

Finally, let us point out that we might consider the subsystems of a probabilistic system to be either *strongly* (or *globally*) *correlated* or *weakly* (or *locally*) *correlated*. The trivial case of *independence*, i.e., when the subsystems are *uncorrelated*, is of course a particular case of weakly correlated. Let us make these notions more precise. A system is weakly correlated if for every generic (different from zero and from unity) joint probability $\pi_{i_1 i_2 \dots i_N}^{A_1 + A_2 + \dots + A_N}$ a set of individual probabilities $\{\pi_i^{A_i}\}$ exists such that $\lim_{N \rightarrow \infty} (\pi_{i_1 i_2 \dots i_N}^{A_1 + A_2 + \dots + A_N}) / \prod_{r=1}^N \pi_i^{A_r} = 1$. Otherwise, the system is said to be strongly correlated. The particular case of independence corresponds to

$$\pi_{i_r}^{A_r} = \sum_{i_1, i_2, \dots, i_{r-1}, i_{r+1}, \dots, i_N} \pi_{i_1 i_2 \dots i_N}^{A_1 + A_2 + \dots + A_N} \quad (r = 1, 2, \dots, N).$$

If the subsystems are equal and binary, this definition becomes as follows: a system is weakly correlated if, for generic $\pi_{N,n}$, a probability p_0 exists such that $\lim_{N \rightarrow \infty} \pi_{N,n} / p_0^{N-n} (1 - p_0)^n = 1$. Otherwise the system is said to be strongly correlated. The particular case of independence corresponds to $p_0 = \pi_{10}$. In the present sense, weakly correlated systems could also be thought and referred to as *asymptotically uncorrelated*. The interplay of scale-invariance, q -describability, and global correlation is schematized in Fig. 3.

We have verified that all systems illustrated in *i* and *ii* above belong to the $q = 1$ class (see examples in Fig. 4). We next address $q \neq 1$ systems.

A Discrete Model That Is Not Asymptotically Scale-Invariant. Let us consider the probabilistic structure indicated in Fig. 5, where, for given N , only the $d + 1$ first elements are different from zero, with $d = 0, 1, 2, \dots, N$.

As we see, $\pi_{N,n}^{(d)} = 0$ for $N \geq d + 1$ and $n = d + 1, d + 2,$

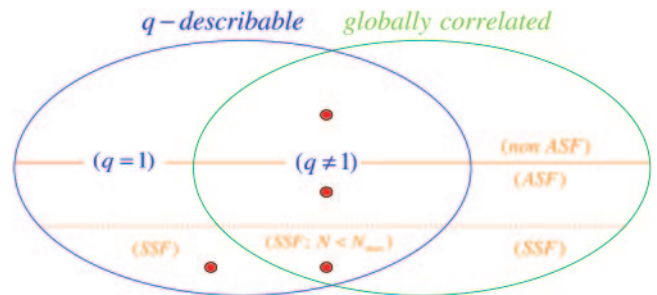


Fig. 3. Scheme representing the systems that are q -describable, globally correlated, asymptotically scale-free (ASF), and strictly scale-free (SSF). The $q = 1$ region corresponds to “locally” correlated systems. The Leibnitz rule is strictly satisfied for SSF, but only asymptotically satisfied for ASF. Below (above) the continuous red line we have the ASF (non ASF) systems. The SSF systems (below the dashed red line) constitute a subset of the ASF subset. The red spots correspond to the four families of discrete systems illustrated in the present paper: $q \neq 1$ non ASF (upper spot; Eqs. 12 and 14); $q \neq 1$ ASF but non SSF (middle spot; Eqs. 17 and 24); $q \neq 1$ SSF (right bottom spot; Eq. 8); $q = 1$ SSF (left bottom spot; examples *i* and *ii* in the text).

^{||}On the basis of what we have called here the *Leibnitz rule*, L. G. Moyano, C.T., and M.G.-M. (44) obtained interesting preliminary numerical results based on the so called q -product (30, 31) and its relation to the possible q -generalization of the central limit theorem. More precisely, imposing the Leibnitz rule with $\pi_{N,0}^{-1} = p^{-1} \otimes_q p^{-1} \otimes_q \dots \otimes_q p^{-1} = [Nq^{-1} - (N - 1)]^{1/q}$ (with $\pi_{N,0} = p^N$ for $q = 1$), one verifies for $p = 1/2$ that, as N increases, the distribution probability appears to approach a q -generalized Gaussian $P(n, N)$. The centered and rescaled distribution $P(n, N)/N/2$ gradually becomes (say for even N) proportional to $(1 - x^2)^{1/(1 - q^{exp})}$, where $x = [n - (N/2)]/(N/2)$. Numerically, the exponent appears to satisfy $q_{exp} = 2 - (1/q)$. This relation is obtained by applying the $q \rightarrow (2 - q)$ transformation after the $q \rightarrow 1/q$ transformation (notice that this relation can be rewritten as $q = 1/(2 - q_{exp})$, which is the application of the same two transformations in the other possible order). The combinations of these two transformations define an interesting mathematical structure which might well be at the basis of the q -triple conjectured in (32) and recently confirmed (33) with data received from the spacecraft Voyager 1 in the distant heliosphere. The q -triple observed in the solar wind is given by $q_{sen} = -0.6 \pm 0.2, q_{rel} = 3.8 \pm 0.3,$ and $q_{stat} = 1.75 \pm 0.06$ (33). These values are consistent with $q_{rel} + (1/q_{sen}) = 2$ and $q_{stat} + (1/q_{rel}) = 2$, hence $1 - q_{sen} = [1 - q_{stat}]/[3 - 2q_{stat}]$. Therefore, we expect only one q of the triplet to be independent. The most precisely determined value in ref. 33 is $q_{stat} = 1.75 = 7/4$. It immediately follows that $q_{sen} = -1/2$ (neatly consistent with -0.6 ± 0.2) and $q_{rel} = 4$ (neatly consistent with 3.8 ± 0.3). There may be some difficulties with this approach, and efforts are being made to clear up the situation.

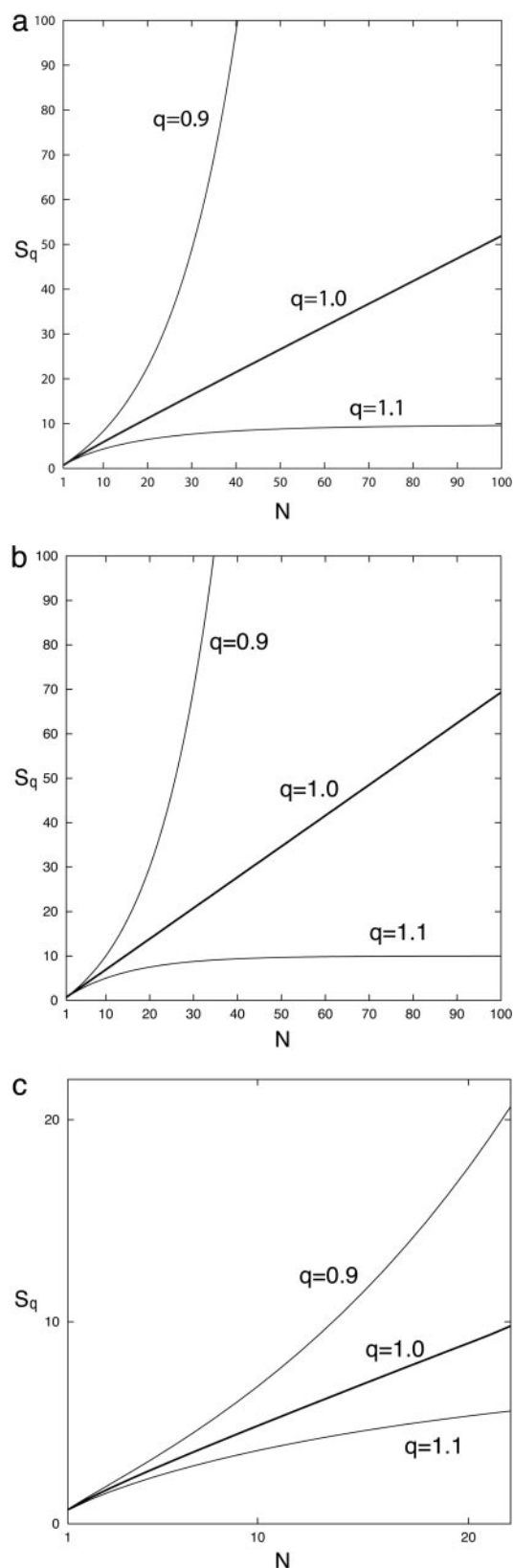


Fig. 4. $S_q(N)$ for the Leibnitz triangle [the explicit expression $\pi_{N,n} = 1/(N+1)(N-n)!n!/N!$ has been used to calculate $S_q(N)$] (a) $\alpha = 1$ (i.e., independent subsystems) with $\pi_{10} = 1/2$ [the explicit expression $\pi_{N,n} = (\pi_{10})^{N-n}(1-\pi_{10})^n$ has been used to calculate $S_q(N)$] (b) and $\alpha = 1/2$ with $\pi_{10} = 1/2$ [the recursive relation 3 has been used to calculate $S_q(N)$] (c). Only for $q = 1$ we have a finite value for $\lim_{N \rightarrow \infty} S_q(N)/N$; it vanishes (diverges) for $q > 1$ ($q < 1$).

\dots, N . The total number of states is given by $W(N) = 2^N$ ($\forall d$), but the number of states with nonzero probability is given by

$$W_{\text{eff}}(N, d) = \sum_{k=0}^d \frac{N!}{(N-k)!k!}, \quad [5]$$

where eff stands for effective. For example, $W_{\text{eff}}(N, 0) = 1$, $W_{\text{eff}}(N, 1) = N + 1$, $W_{\text{eff}}(N, 2) = \frac{1}{2}N(N+1) + 1$, $W_{\text{eff}}(N, 3) = \frac{1}{6}N(N^2+5) + 1$, and so on. For fixed d and $N \rightarrow \infty$ we have that

$$W_{\text{eff}}(N, d) \sim \frac{N^d}{d!}. \quad [6]$$

Let us now make a simple choice for the nonzero probabilities, namely *equal probabilities*. In other words,

$$\pi_{N,n}^{(d)} = 1/2^N \text{ (if } N \leq d),$$

$$\pi_{N,n}^{(d)} = \frac{1}{W_{\text{eff}}(N, d)} \text{ (if } N > d \text{ and } n \leq d), \text{ and} \quad [7]$$

$$\pi_{N,n}^{(d)} = 0 \text{ (if } N > d \text{ and } n > d).$$

See Fig. 6 for an illustration of this model.

The entropy for this model is given by

$$S_q(N) = \ln_q W_{\text{eff}}(N, d) \equiv \frac{[W_{\text{eff}}(N, d)]^{1-q} - 1}{1-q} \\ \sim \frac{N^{d(1-q)}}{(1-q)(d!)^{1-q}}, \quad [8]$$

where we have used now Eq. 6. Consequently, S_q is *extensive* [i.e., $S_q(N) \propto N$ for $N \rightarrow \infty$] if and only if

$$q = 1 - \frac{1}{d}. \quad [9]$$

Hence, if $d = 1, 2, 3, \dots$, the entropic index monotonically approaches the BG limit from below. We can immediately verify in Fig. 6 (and using Eq. 7) that this model violates the Leibnitz rule for all N , including asymptotically when $N \rightarrow \infty$. Consequently, it is neither strictly nor asymptotically scale-free. However, it is q -describable (see Fig. 3).

An Asymptotically Scale-Invariant Discrete Model. Starting with the Leibnitz harmonic triangle, we shall construct a heterogeneous distribution $\pi_{N,n}^{(d)}$. The Leibnitz triangle is given in Fig. 2 and satisfies

$$p_{N,n} = p_{N+1,n} + p_{N+1,n+1}, \quad [10]$$

$$p_{N,n} = \frac{1}{(N+1)} \frac{(N-n)!n!}{N!}. \quad [11]$$

We now define

$$\pi_{N,n}^{(d)} \equiv \begin{cases} p_{N,n} + l_{N,n}^{(d)} s_N^{(d)} & (n \leq d) \\ 0 & (n > d) \end{cases} \quad [12]$$

where the *excess probability* $s_N^{(d)}$ and the *distribution ratio* $l_{N,n}^{(d)}$ (with $0 < \varepsilon < 1$) are defined through

$$s_N^{(d)} \equiv \sum_{k=d+1}^N p_{N,k} = \frac{N-d}{N+1} \quad [13]$$

$(N = 0)$	$(1, 1)$	$(1, 1)$
$(N = 1)$	$(1, \pi_{10}^{(1)}) (1, \pi_{11}^{(1)})$	$(1, \pi_{10}^{(2)}) (1, \pi_{11}^{(2)})$
$(N = 2)$	$(1, \pi_{20}^{(1)}) (2, \pi_{21}^{(1)}) (1, 0)$	$(1, \pi_{20}^{(2)}) (2, \pi_{21}^{(2)}) (1, \pi_{22}^{(2)})$
$(N = 3)$	$(1, \pi_{30}^{(1)}) (3, \pi_{31}^{(1)}) (3, 0) (1, 0)$	$(1, \pi_{30}^{(2)}) (3, \pi_{31}^{(2)}) (3, \pi_{32}^{(2)}) (1, 0)$
$(N = 4)$	$(1, \pi_{40}^{(1)}) (4, \pi_{41}^{(1)}) (6, 0) (4, 0) (1, 0)$	$(1, \pi_{40}^{(2)}) (4, \pi_{41}^{(2)}) (6, \pi_{42}^{(2)}) (4, 0) (1, 0)$

Fig. 5. Probabilistic models with $d = 1$ (Left) and $d = 2$ (Right).

$(N = 0)$	$(1, 1)$	$(1, 1)$
$(N = 1)$	$(1, 1/2) (1, 1/2)$	$(1, 1/2) (1, 1/2)$
$(N = 2)$	$(1, 1/3) (2, 1/3) (1, 0)$	$(1, 1/4) (2, 1/4) (1, 1/4)$
$(N = 3)$	$(1, 1/4) (3, 1/4) (3, 0) (1, 0)$	$(1, 1/7) (3, 1/7) (3, 1/7) (1, 0)$
$(N = 4)$	$(1, 1/5) (4, 1/5) (6, 0) (4, 0) (1, 0)$	$(1, 1/11) (4, 1/11) (6, 1/11) (4, 0) (1, 0)$

Fig. 6. Uniform distribution model with $d = 1$ (Left) and $d = 2$ (Right).

$(N = 0)$	$(1, 1)$	$(1, 1)$
$(N = 1)$	$(1, 1/2) (1, 1/2)$	$(1, 1/2) (1, 1/2)$
$(N = 2)$	$(1, 1/2) (2, 1/4) (1, 0)$	$(1, 1/3) (2, 1/6) (1, 1/3)$
$(N = 3)$	$(1, 1/2) (3, 1/6) (3, 0) (1, 0)$	$(1, 3/8) (3, 5/48) (3, 5/48) (1, 0)$
$(N = 4)$	$(1, 1/2) (4, 1/8) (6, 0) (4, 0) (1, 0)$	$(1, 2/5) (4, 3/40) (6, 1/20) (4, 0) (1, 0)$

Fig. 7. Leibnitz-triangle-based $\varepsilon = 0.5$ probability sets: $d = 1$ (Left), and $d = 2$ (Right).

$$I_{N,n}^{(d)} \equiv \begin{cases} 1 - \varepsilon & (n = 0) \\ (1 - \varepsilon)\varepsilon^n \frac{(N - n)!n!}{N!} & (0 < n < d) \\ \varepsilon^d \frac{(N - d)!d!}{N!} & (n = d) \end{cases} \quad [14]$$

(see Fig. 7). We have verified for $d = 1, 2, 3, 4$ and $N \rightarrow \infty$ a result that we expect to be correct for all $d < N/2$, namely that $0 < \pi_{N,n+1} \ll \pi_{N,n} \sim \pi_{N-1,n} \ll 1$, hence

$$\lim_{N \rightarrow \infty} \frac{\pi_{N-1,n}^{(d)}}{\pi_{N,n}^{(d)} + \pi_{N,n+1}^{(d)}} = 1, \quad [15]$$

$$\lim_{N \rightarrow \infty} \frac{\pi_{N-1,d}^{(d)}}{\pi_{N,d}^{(d)} + 0} = 1. \quad [16]$$

In other words, the Leibnitz rule is asymptotically satisfied for the entire probability set $\{\pi_{N,n}\}$, i.e., this system has asymptotic scale invariance. Its entropy is given by

$$S_q(N, d) = \frac{1 - \sum_{k=0}^d [N!/(N - k)!k!] [\pi_{N,k}^{(d)}]^q}{q - 1}, \quad [17]$$

and we verify that a value of q exists such that $\lim_{N \rightarrow \infty} S_q(N, d)/N$ is finite. Our numerical results suggest that, for $0 < \varepsilon < 1$ (see Fig. 8),

$$q = 1 - \frac{1}{d}. \quad [18]$$

For a description of a strictly scale-invariant discrete model and a continuous model, see *Supporting Text* and Figs. 9–17, which are published as supporting information on the PNAS web site.

Final Remarks

Let us now critically re-examine the physical entropy, a concept which is intended to measure the nature and amount of our

ignorance of the state of the system. As we shall see, extensivity may act as a guiding principle. Let us start with the simple case of an isolated classical system with *strongly* chaotic nonlinear dynamics, i.e., at least one *positive* Lyapunov exponent. For almost all possible initial conditions, the system quickly visits the various admissible parts of a *coarse-grained* phase space in a virtually homogeneous manner. Then, when the system achieves *thermodynamic equilibrium*, our knowledge is as meager as possible (*microcanonical ensemble*), i.e., just the Lebesgue measure W of the appropriate (hyper) volume in phase space (continuous degrees of freedom), or the number W of possible states (discrete degrees of freedom). The entropy is given by $S_{BG}(N) \equiv k \ln W(N)$ [Boltzmann principle (34)].** If we consider independent equal subsystems, we have $W(N) = [W(1)]^N$, hence $S_{BG}(N) = NS_{BG}(1)$. If the N subsystems are only *locally* correlated, we expect $W(N) \sim \mu^N$ ($\mu \geq 1$), hence $\lim_{N \rightarrow \infty} S_{BG}(N)/N = \mu$, i.e., the entropy is *extensive* (i.e., *asymptotically additive*).

Consider now a strongly chaotic case for which we have more information, e.g., the set of probabilities $\{p_i\}$ ($i = 1, 2, \dots, W$) of the states of the system. The form $S_{BG} \equiv -k \sum_{i=1}^W p_i \ln p_i$ yields $S_{BG}(A + B) = S_{BG}(A) + S_{BG}(B)$ in the case of independence ($p_{ij}^{A+B} = p_i^A p_j^B$). This form, although more general than $k \ln W$ (corresponding to equal probabilities), still satisfies additivity. It frequently happens, though, that we do not know the *entire set* $\{p_i\}$, but only some constraints on this set, besides the trivial one $\sum_{i=1}^W p_i = 1$. The typical case is Gibbs' canonical ensemble (Hamiltonian system in longstanding contact with a thermal

**A. Einstein: "Usually W is set equal to the number of ways (complexions) in which a state, which is incompletely defined in the sense of a molecular theory (i.e. coarse grained), can be realized. To compute W one needs a complete theory (something like a complete molecular-mechanical theory) of the system. For that reason it appears to be doubtful whether Boltzmann's principle alone, i.e. without a complete molecular-mechanical theory (Elementary theory) has any real meaning. The equation $S = k \log W + const.$ appears [therefore] without an Elementary theory—or however one wants to say it—devoid of any meaning from a phenomenological point of view." [translated by E. G. D. Cohen (34)]. A slightly different translation also is available: ["Usually W is put equal to the number of complexions. . . . In order to calculate W , one needs a *complete* (molecular-mechanical) theory of the system under consideration. Therefore it is dubious whether the Boltzmann principle has any meaning without a complete molecular-mechanical theory or some other theory which describes the elementary processes. $S = R/N \log W + const.$ seems without content, from a phenomenological point of view, without giving in addition such an *Elementartheorie*" (35)].

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