Functional analysis of the foot and ankle myology of **gibbons and bonobos**

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Abstract

This study investigates the foot and ankle myology of gibbons and bonobos, and compares it with the human foot. Gibbons and bonobos are both highly arboreal species, yet they have a different locomotor behaviour. Gibbon locomotion is almost exclusively arboreal and is characterized by speed and mobility, whereas bonobo locomotion entails some terrestrial knuckle-walking and both mobility and stability are important. We examine if these differences in locomotion are reflected in their foot myology. Therefore, we have executed detailed dissections of the lower hind limb of two bonobo and three gibbon cadavers. We took several measurements on the isolated muscles (mass, length, physiological cross sectional area, etc.) and calculated the relative muscle masses and belly lengths of the major muscle groups to make interspecific comparisons. An extensive description of all foot and ankle muscles is given and differences between gibbons, bonobos and humans are discussed. No major differences were found between the foot and ankle musculature of both apes; however, marked differences were found between the ape and human foot. The human foot is specialized for solely one type of locomotion, whereas ape feet are extremely adaptable to a wide variety of locomotor modes. Apart from providing interesting anatomical data, this study can also be helpful for the interpretation of fossil (pre)hominids.

Key words ankle; bonobo; foot myology; gibbon; locomotion.

Introduction

In this study we set out to investigate to what extent the specific locomotor adaptations of apes are reflected in their functional morphology. In primates both hands and feet interact with the environment and are therefore most likely to reflect the locomotor behaviour and habitat of the species (Sigmon & Farslow, 1986). However, we chose to focus on the foot and ankle complex of apes because the hand morphology might show some locomotion-manipulation compromises (Tuttle, 1972) and because we were particularly interested in hind-limbdominated locomotor modes, such as bipedalism.

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The human foot is paradigmatic in reflecting the species' locomotor adaptations, because of its striking specializations for habitual bipedalism (Morton, 1935). However, the form–function relationship of the foot of non-human primates is undoubtedly as significant in an evolutionary context. Arboreal primates are known to have a flexible foot, with powerful grasping muscles and an opposable hallux (Morton, 1924; Tuttle, 1970, 1972). Terrestrial primates, by contrast, and ultimately humans, possess a more robust and compact foot with lever and shock-absorbing capabilities (Jacob, 2001). Establishing viable form–function relationships in the foot and ankle complex of extant primates is not only crucial for thorough investigation of primate locomotion but can also be helpful in the reconstruction of the locomotor behaviour of extinct hominoids.

Comparisons of the linear proportions of the various foot segments have repeatedly been used to investigate the adaptation of the primate foot (Morton, 1924; Schultz, 1963, 1973; Lessertisseur & Jouffroy, 1973). Clearly, this is of considerable functional relevance, but

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the importance of the muscles, as actuators of these foot segments, should not be underestimated. In addition, bone is a dynamic structure, sensitive to mechanical loading, and the observed structure might therefore rather be a reflection of activity patterns than of actual adaptations. Gross anatomical features of the musculature, such as the distribution, origin and insertion, and the presence or absence of muscles, are more conservative than bony structure and might thus better reflect the evolutionary pathway and adaptations of the species (Gibbs et al. 2002).

Unfortunately, previous papers investigating the foot and ankle myology of non-human apes are very scarce. Bisschoff (1870) and Kohlbrügge (1890/91) provide a gross anatomical description of the gibbon, and Wilder (1863), Miller (1952), Sokoloff (1972) and Swindler & Wood (1973) give information on the gross anatomical musculature of bonobos and chimpanzees. A more detailed description of the hip and thigh musculature is given by Sigmon (1974, 1975), and Tuttle (1970, 1972) provides a functional analysis of the hand and foot morphology of non-human apes. Other researchers have used EMG to investigate the recruitment of the hind limb muscles during gait (e.g. Tuttle et al. 1978; Stern & Susman, 1981; Shapiro & Jungers, 1988, 1994). More recently, Thorpe et al. (1999) and Payne (2001) have made detailed studies that provide quantitative data on the fore- and hind limb musculature of all ape species. These are all very valuable studies but to date the only information on the foot and ankle myology of primates is provided by Langdon (1990). In this work he combines observations from original dissections (*n* = 67) and from the literature to investigate the variation in cruropedal musculature throughout different primate taxa (14 families), including the apes. Although this is an extensive and very comprehensible work, a detailed functional description of the hominoid foot and ankle myology is still warranted.

We chose to study gibbons (*Hylobates* sp.), bonobos (*Pan paniscus*) and compare them with modern humans because their locomotor anatomy and behaviour are strikingly different. In addition, gibbons, bonobos and humans all belong to the same superfamily Hominoidea (Goodman et al. 1994; Gibbs et al. 2002) and all three species can and do walk bipedally despite their markedly different morphology (Carpenter, 1964; Susman et al. 1980).

Gibbons are lightly built apes, specialized for very fast ricochetal arm-swinging or brachiation (Chang

et al. 2000). Beside this, their locomotor repertoire also contains climbing (4–20%), leaping (6–20%) and bipedal walking on large branches (4–11%), all executed at high speeds (Carpenter, 1964; Ellefson, 1967; Tuttle, 1972; Andrew & Groves, 1976; Fleagle, 1976; Gittins, 1983; Sati & Alfred, 2002). They live in the middle to upper levels of the forest canopy and rarely come to the ground (Carpenter, 1964; Tuttle, 1972). Observations of terrestrially walking gibbons are infrequent in the wild and occur predominantly when crossing gaps and roads in fragmented forested regions (Sati & Alfred, 2002; B. Rawson and G. Thampy, personal communication). Thus, the gibbon is characterized by a fast arboreal locomotion. This combination of swift movements and a complex three-dimensional environment requires highly mobile and flexed limbs (Schmitt, 1999). When a gibbon swings at high speed through the forest, it must have the ability to grasp a branch in almost every orientation and it must also be capable of quickly changing direction and speed. Obviously, arm-swinging is a forelimb-dominated locomotion type and the hind limbs are mostly kept flexed at hip and knee (Jungers & Stern, 1976). Nevertheless, mobility of the hind limb and foot are also crucial, as these swinging phases are alternated with short and fast bipedal bouts on large branches, with jumps, and with quadrumanous climbing (Tuttle, 1972). In view of their important prehensile function, flexibility of both hands and feet is essential in gibbon locomotion.

In bonobo locomotion, by contrast, different features can be premised. Although bonobos are larger and heavier than gibbons, they are also gracile and arboreal apes. They most commonly travel using arboreal quadrupedalism, quadrumanous climbing and scrambling (Susman et al. 1985; Doran, 1993), often performed at a slow deliberate pace. Faster locomotion types, such as diving, leaping and arm-swinging, are observed in agitated or fleeing animals but fast ricochetal brachiation as seen in gibbons is absent (Susman et al. 1985; Doran, 1993). In contrast with the fully arboreal gibbons, bonobos regularly come to the ground and travel terrestrially (Susman et al. 1985; Doran, 1993; Doran & Hunt, 1994). They most often do so using quadrupedal knuckle-walking, supporting 40% of their body weight on the knuckles of the forelimbs and 60% on the hind limbs (Reynolds, 1985; Susman et al. 1985; Doran, 1993). Beside this, bipedalism and tripedalism are also occasionally used during terrestrial travel (Susman et al. 1985; Kano, 1992; Doran, 1993). A robust and compact foot

is most suitable for terrestrial walking, in order to support high compressive stresses and to generate large propulsive forces (Morton, 1935). However, high foot mobility seems equally important for their arboreal locomotor behaviour. Thus, the bonobo foot combines a prehensile and a propulsive function and its morphology should therefore be a compromise between stability and mobility.

Human locomotion is exclusively terrestrial and, as a consequence, the human foot has lost its prehensile function. However, the generation of propulsion has become extremely important during bipedal locomotion, so stability seems to be the ultimate requisite of the human foot–ankle complex (Morton, 1935).

Based on the above considerations, we hypothesize that gibbons will have relatively slender extrinsic foot muscles, allowing fast contraction and a wide range of motion. In addition, we expect that gibbons will have relatively stronger deep hind flexors and larger intrinsic foot muscles, in view of the important prehensile foot function. Bonobos, by contrast, should have more bulky extrinsic foot muscles, especially the plantar flexors, to generate large propulsive forces but also allowing a wide range of motion. Undeniably, a deeper knowledge of the morphology of the foot and ankle is needed to gain insight into the mechanics of ape and human locomotion. Thus, besides testing the abovementioned hypothesis, we wish to provide a functional description of the foot and ankle muscles of gibbons and bonobos, useful for further kinesiological and comparative research on primate locomotion.

Materials and methods

Dissection data (Table 1) for the bonobo (*Pan paniscus*) were obtained from two adult specimens, a male,

which is the same individual as in the study of Payne (2001), and a female. The male died of a heart attack, the female from a severe wound at the hand. The female had some arthrosis at her left ankle, but the remaining part of the musculoskeletal system of both cadavers was in good condition. Both bonobos were obtained from the Royal Zoological Society of Antwerp, Belgium. The data for the gibbon were obtained from two *Hylobates lar* specimens and from one *Nomascus leucogenys* specimen. The female *H. lar* (black variant) was put-down because of old age and some severe disorders (distortion of the vertebral column and blindness). The other *H. lar* (pale brown variant) was a male that died from his injuries after an aggressive attack by its father. Both *lar* gibbons were put at our disposal by the Royal Zoological Society of Antwerp, Belgium. The white-cheeked gibbon (*N. leucogenys*) was supplied by the 'Parc Animalier de Branféré', Brittany, France, and cause of death was drowning. The presented gibbon data are based on the dissection of the male *lar* gibbon and the dissections of the other two specimens were used for verification.

All specimens were eviscerated during post-mortem examination and were stored in freezers until dissection took place. The dissections were performed on fresh, non-fixed cadavers. The gross dissection of the hind limb muscles of the adult bonobo male was executed in cooperation with Dr M. M. Günther from the University of Liverpool. The detailed dissections of the foot–ankle complex of the bonobo and gibbon cadavers were executed by E.E.V. During these dissections the muscles were isolated one by one and their origin and insertion were noted. The action of the muscles was deduced from their sites of attachment, their trajectory and by pulling on them with the foot placed in a neutral position. In addition, several measurements were taken

*Wild born specimens; RZCA, B = Royal Zoological Society Antwerp, Belgium; PAB, F = Parc Animalier de Branféré, France.

Table 1 Subject data of the dissected specimens

Fig. 1 Illustration of the different measurements taken on the isolated muscles. Muscle fibre length (FL) and pennation angle (PA) are measured on the longitudinally dissected muscle belly (lower inset). Legend: Length = total muscle–tendon length, $BL =$ muscle belly length, BW = belly width, LET = length of the external tendon, $FL =$ muscle fibre length and $PA =$ pennation angle.

to determine the muscle mechanics of the gibbon and bonobo foot and ankle complex. These measurements are illustrated in Fig. 1, and include the (wet) muscle mass; the muscle length, measured from origin to the insertion of the muscle; the muscle belly length, BL, which is the distance from the origin of the most proximal muscle fibres to the insertion of the most distal muscle fibres; the muscle belly width, BW, i.e. the width of the muscle belly measured perpendicular to the forcegenerating axis of the muscle; the tendon length, TL, the distance from the most proximal origin of the tendon to the insertion of the tendon on the bone; the length of the external tendon, LET, i.e. the distance from the most distal muscle fibres to the insertion of the tendon on the bone; pennation angle, PA, the average angle of the muscle fibres relative to the force-generating axis; and the fibre length, FL, which is the approximate length of the muscle fibres.

All linear measurements were taken with a digital calliper (Mitutuyo) and pennation angles were measured on digital images in CorelDraw! 9 (see also Ledoux et al. 2001). The data provided for fibre length and pennation angle are average values of at least three independent measurements taken on different places on the longitudinally dissected muscle belly. Pennation angle and LET values are lacking for the bonobo, because these were not taken during dissection and recovery of the data from the preserved muscles was impossible. Additionally, we have also calculated the physiological cross-sectional area (PCSA), using the formula provided by Mendez & Keys (1960): PCSA = muscle mass * cos (PA)/ 1060 kg m⁻³ * fibre length. However, because the largest pennation angle (PA) was 30°, the cosine of which is 0.87, we omitted the PA-factor in our calculations of the PCSA (see also Payne, 2001). To allow comparison between gibbons, bonobos and humans, the PCSA data were scaled to body mass to the two-thirds. The PCSA was not calculated for the smallest muscles, because accurate fibre lengths were not available for these muscles. The abbreviations of the foot and ankle muscles are given in Table 2 and the raw muscle data of the gibbon (Table A1) and bonobo (Table A2) dissections are given in the Appendix. The anatomical data of the female *lar* gibbon are not included in these tables because we are not confident about the accuracy of these data. Apart from severe distortions of the spine we also observed marked modifications in the appendicular skeleton of the cadaver and it is thus not unlikely that the soft tissue characteristics (muscles masses, PCSA, etc.) of this specimen are also affected. Therefore, the dissection of this specimen was only used to check the attachment

sites and the presence or absence of the lower leg muscles, and muscle dimension data were omitted.

We have calculated the relative masses and belly lengths of the major muscle groups of the gibbon and bonobo specimens. The relative muscle belly length is determined as the proportion of the muscle belly length to total muscle tendon length. The relative muscle masses are calculated as percentages of the total extrinsic or total intrinsic foot muscle mass to allow comparison between the different sized species. We have also included human data for the extrinsic foot muscle masses, which are provided by Wickiewicz et al. (1983).

Results and discussion

Gross anatomical description of the foot and ankle complex of gibbons and bonobos

This article focuses on the musculature of the foot and ankle complex of gibbons and bonobos but we consider that it is appropriate first to summarize the main skeletal features of gibbons and bonobos that were investigated previously by Schultz (1963, 1973) and Tuttle (1970, 1972). We also provide an illustration of the major anatomical landmarks of the lower hind limb and foot skeleton of both apes to clarify the attachment sites of the muscles that are described in the following paragraphs (Fig. 2).

The gibbon is a small ape with long arms, relatively long hind limbs and very slender feet. Owing to a great elongation of the limb bones, without a corresponding increase in thickness, these bones have become extremely gracile (Schultz, 1973). The foot skeleton is narrow and has a short heel, indicating a lessened leverage of the calf muscles (the relative length of the heel is the functional power arm of the foot; Morton, 1924; Schultz, 1963). The phalanges of the toes are curved and strikingly elongated, accounting for over 40% of the total foot length, and the hallux, i.e. the first metatarsal and digit, is long and is not enclosed in the foot sole (Tuttle, 1972; Schultz, 1973). The bonobo skeleton is clearly more robust and the foot has a relatively large heel or power arm (cf. common chimpanzee: Tuttle, 1970). The phalanges are relatively shorter than in gibbons and the tarsal region is relatively more elongated although the mid-tarsal bones (i.e. the navicular, the cuboid and the cuneiforms) are compressed in an antero-posterior direction (Morton, 1924). Both apes lack a longitudinal foot arch and have a rather robust fibula (Tuttle, 1970).

Fig. 2 Illustration of the skeleton of the lower hind limb and foot of a gibbon (A) and a bonobo (B) with indication of the major anatomical landmarks. Legend: (1) lateral condyle; (2) fibula head; (3) fibula shaft; (4) medial condyle; (5) tibial head; (6) tibial shaft; (7) membrana interossea; (8) lateral malleolus; (9) medial malleolus; (10) calcaneus; (11) talus; (12) cuboid; (13) the metatarsus, consisting of five metatarsal bones (I–V); (14) the digits, each consisting of three phalanges; (15) the cuneiform bones (laterale, intermedium and mediale); and (16) the hallux. Note also the presence of sesamoid bones on the hallux and a prominent tuberosity on the naviculare (ton) and on the fifth metatarsal (tom).

A gross anatomical description of the extrinsic and intrinsic foot muscles of gibbons and bonobos is provided in Tables 3 and 4. Details on the morphological appearance of the different muscles are provided in the next paragraph.

Functional morphological comparison of the foot and ankle muscles of gibbons, bonobos and humans

The extrinsic foot muscles

The triceps surae

The triceps surae, or calf muscles, consist of the gastrocnemius, plantaris and soleus muscle and their main action is plantar flexion of the ankle joint. In all three species the m. gastrocnemius and m. soleus are very large as they are important power generators during

locomotion (see also Morton, 1924). The plantaris muscle, however, is small and is frequently absent in bonobos (32–48%; Loth, 1913; Langdon, 1990) and humans (7–10%; Loth, 1913; Langdon, 1990) and is rare in gibbons (Kohlbrügge, 1890/91; Loth, 1913; Sigmon & Farslow, 1986; Langdon, 1990). The gastrocnemius, plantaris and soleus muscle are fused distally into the Achilles tendon, which shows a different development in the three species. Bonobos have a short Achilles tendon, which accounts for only up to 10% of the total muscle length (Table 5). In gibbons, the tendon is remarkably long compared with the other apes and accounts for 45% of the muscle length, although variation within the Hylobatidae is high (Bisschof, 1870; Kohlbrügge, 1890/91; Table 5). In humans, the strong, well-developed Achilles tendon accounts for up to 65% of the muscle length (Prejzner-Morawska & Urbanowicz, 1981) and it functions as an energy-saving mechanism, acting like a spring during running (Alexander, 1992; Hof et al. 2002).

The attachment sites of the gastrocnemius muscle are similar in gibbons, bonobos and humans. In gibbons,

we observed sesamoid bones at the posterior side of the lateral femoral condyle, in the tendon of the lateral head (i.e. the lateral fabella) and near the calcaneus in the Achilles tendon. Some authors have also described the presence of a sesamoid bone in the medial head of the m. gastrocnemius (i.e. the medial fabella; Sigmon & Farslow, 1986; Lewis, 1989; Payne, 2001), although Kohlbrügge (1890/91) found none. Sesamoid bones in the medial and lateral gastrocnemius head are present in common chimpanzees (Sigmon & Farslow, 1986; Lewis, 1989) but were not seen in our bonobo specimens. In humans, a lateral fabella is infrequent (13–21%; Lewis,

Table 4a Origin, insertion and function of the extrinsic foot muscles of *Hylobates lar*

1989) and a medial one is very rare (Sigmon & Farslow, 1986; Lewis, 1989; Sarin et al. 1999).

The soleus muscle is slender in gibbons and is closely associated with the m. gastrocnemius. In bonobos, the m. soleus is very large and has a broad attachment site onto the fibular head. In humans, there is an extra

attachment of the m. soleus onto the tibia, which is sometimes also present in *Pan* (i.e. the popliteal line; Sigmon & Farslow, 1986; Lewis, 1989; Gibbs et al. 2002).

Although a plantaris muscle is frequently absent in common chimpanzees (Wilder, 1863; Loth, 1913; Sigmon & Farslow, 1986; Langdon, 1990; Deloison, 1993; Thorpe **Table 4b** Origin, insertion and function of the intrinsic foot muscles of *Hylobates lar*

et al. 1999; Gibbs et al. 2002), we did find a plantaris muscle in both bonobo specimens (also described by Miller, 1952). It originates together with the lateral head of the m. gastrocnemius but it is clearly distinct distally and has a long, thin tendon that merges distally into the Achilles tendon. According to several researchers (Kohlbrügge, 1890/91; Bisschoff, 1870; Sigmon & Farslow,

1986; Langdon, 1990) a plantaris muscle is absent in gibbons. Groves (1972), however, noticed the absence of a plantaris muscle in *Hylobates syndactylus* and *H. lar* but he did find an m. plantaris in *H. hoolock*. We found a small plantaris muscle in our adult *lar* specimen, which was fused with the large lateral head of the m. gastrocnemius, but in the juvenile and adult male gibbon a distinct

	Gibbon		Bonobo		
Muscle	adult	juvenile	male	female	
Triceps surae					
Galat	0.72	0.55	0.92		
Gamed	0.62	0.50	0.92		
Soleus	0.67	0.84	0.96		
Deep hind flexors					
FT	0.64	0.69	0.49	0.65	
FF	0.52	0.52	0.56		
Dorsiflexors					
TA	0.86	0.77	0.70	0.74	
EDL	$0.45*$	0.61	0.61	0.72	
EHL	0.58	0.59	0.66	0.70	
Evertors					
Plong	0.62	0.65	0.65	0.72	
Pbrev	0.69	0.67	0.83	0.87	
Invertors					
TP	0.57	0.49	0.77	0.74	

Table 5 Relative muscle belly lengths for the extrinsic foot muscles of the gibbon and bonobo

*Mean of both EDL heads.

plantaris muscle was absent. However, in the latter specimens the lateral head of the m. gastrocnemius could be divided into two parts, possibly including a firmly fused plantaris muscle. In *Homo*, a plantaris muscle is present but is reduced compared with the plantaris of the non-hominoid primates (Sigmon & Farslow, 1986).

The dorsiflexors

The extensor digitorum longus, the extensor hallucis longus and the tibialis anterior muscle are grouped into the dorsiflexors, pointing to their main function. They are located in the anterior compartment of the lower leg and all have very long tendons. The three muscles have a similar distribution and function in gibbons, bonobos and humans and there is little variation in the organization of the long extensors (see also Langdon, 1990). The tibialis anterior muscle, however, shows some muscular variation and is much larger than the long extensors.

In gibbons and bonobos, the m. extensor digitorum longus (EDL) can be split up to a varying degree. In the male *lar* gibbon, the EDL muscle was divided in two small muscle heads, a short head with two long external tendons inserting onto digits II and III, and a long head with two tendons inserting onto digits IV and V. In the other gibbon specimen no such separation was found and Kohlbrügge (1890/91) did not refer to a two-headed EDL muscle in his cadavers. Sometimes a tendon to the

Fig. 3 Medial view of a bonobo foot. Lig. n-m = naviculometatarsal ligament.

fifth digit may be lacking (Payne, 2001). In bonobos, the four tendons of the EDL are sometimes proximally grouped in two larger tendons (Miller, 1952) but in our specimen we found four separate tendons originating from one muscle head, as observed in humans.

In gibbons and bonobos, the tendon of the m. extensor hallucis longus (EHL) passes through the short naviculometatarsal ligament at the medial side of the foot, together with the TA and TP tendons (Fig. 3). This ligament keeps the tendon in position during abduction of the hallux. In gibbons, the EHL muscle is slightly fused with the extensor digitorum longus muscle at the medial fibular shaft.

The tibialis anterior (TA) muscle runs obliquely over the anterior side of the tibia and passes through the transverse crural ligament and in both apes also through the naviculo-metatarsal ligament, before inserting at the medial side of the foot. Because of this medial insertion, the tibialis anterior muscle acts also as an invertor. There is some variation in attachment sites and structure of the muscle between gibbons, bonobos and humans. In gibbons, the muscle inserts with one or two strands onto the navicular bone, the base of the first metatarsal and/or the medial cuneiform bone. The tendon contains a sesamoid bone near insertion, the so-called 'prehallux', but we did not observe a divided muscle belly as has been described by Lewis (1989). In bonobos (and in common chimpanzees; Wilder, 1863), the tibialis anterior muscle is divided into a large and a small muscle belly, sometimes referred to as the m. abductor hallucis longus (Deloison, 1993). Both heads are slightly fused at their origin but have a separate tendon inserting onto the medial sesamoid bone of the first metatarsal and onto the medial cuneiform bone. The presence of a two-headed TA muscle in *Pan*, and in other non-human primates, points to a powerful and prehensile hallux (Deloison, 1993). In humans, the tibialis anterior muscle is usually one-headed but it inserts also onto the first metatarsal and the medial cuneiform bone.

Fig. 4 Schematic distribution of the m. flexor fibularis (FF, in black) and m. flexor tibialis (FT, in white) tendons and the mm. lumbricales (red) in the gibbon (A) and bonobo (B) foot.

The deep hind flexors and the mm. lumbricales

The deep hind flexors, which include the m. flexor fibularis (FF) and the m. flexor tibialis (FT), are both strong digital flexors and plantar flexors of the foot. In the ancestral mammalian condition the tendons of the two muscles were fused at the sole of the foot before dividing in separate strands for insertion onto each of the digits (Lewis, 1964, 1989). In the extant apes, however, both muscles have lost some tendons and there is considerable variation in the specific distribution of the tendons towards the digits (Langdon, 1990). In gibbons and bonobos, the tendons of deep hind flexors are arranged in a superficial (FT) and a deep (FF) plantar layer, which are slightly interconnected and which might allow independent flexion of the toes. Below, we describe the most common organization observed in both apes (Fig. 4; see also Sokoloff, 1972; Lewis, 1989; Langdon, 1990; Deloison, 1993). In humans these muscles have undergone a functional division in a hallucal (FF) and digital (FT) flexor and are therefore called m. flexor hallucis longus and m. flexor digitorum longus in human anatomy (Lewis, 1989).

In gibbons (Fig. 4A), the FF muscle has lost its contribution to the tendon of digit V and splits into four tendons at the plantar side of the foot, inserting onto the phalanges of digits I, II, III and IV. The mm. lumbricales II, III and IV originate from these tendons. In our specimens, the FT muscle had retained two tendons inserting onto the plantar side of the phalanges of digits I and V but other patterns have been described as well (see Langdon, 1990). The lumbricale V muscle originates from the FT tendon towards digit V. The two muscle bellies of the deep layer of the FDB originate also from the FT tendon. The FT tendon towards digit I is fused with the FF tendon and the long tendon inserting onto the fifth digit sends some fibres to the tendons of digits II and IV of the FF muscle. In bonobos (Fig. 4B), the FF muscle has lost its contribution to the tendons of digits II and V and retains the tendons inserting onto digits I, III and IV. These FF tendons are fused with the tendons of the FT, which insert onto digit II and V and which are also fused with the FDB muscle. A similar tendon distribution has been observed in common chimpanzees (Langdon, 1990). The mm. lumbricales are closely associated with both long flexors. In humans, the homologues of FT and FF, the m. flexor digitorum longus and the m. hallucis longus, act as separate flexors of the lateral toes and the hallux.

The m. quadratus plantae (or m. flexor accessorius) was only found in one foot of the adult male bonobo and was absent in all gibbon specimens. In the bonobo, the muscle was weakly developed and one-headed. It originated from the latero-plantar side of the calcaneus and was distally fused with the FT tendon towards digit V. The muscle is also often reduced or absent in other higher primates (Sokoloff, 1972; Lewis, 1989). In humans, however, it is a strong, double-headed muscle originating from both sides of the calcaneus and it provides a firm base for the m. flexor digitorum longus when contracted. This allows simultaneous contraction of the long and short digital flexors during toe-off and it also assists in foot eversion, which is important in terrestrial (bipedal) walking (Sigmon & Farslow, 1986).

The invertors and evertors of the foot

The m. tibialis posterior (TP) is the main invertor of the foot in both apes and in humans. In apes, it is important for inversion during arboreal locomotion and grasping. In humans, the muscle has a broad insertion and is particularly well developed because it has an important role in supporting the medial longitudinal foot arch (Langdon, 1990).

A sesamoid bone is sometimes present near the insertion of the TP tendon of gibbons (our personal observation; Kohlbrügge, 1890/91). In bonobos (and in common chimpanzees; Deloison, 1993), a sesamoid bone is absent but there is a strong tendon with a

broad attachment site, which is related to the presence of a prominent tuberosity of the navicular bone in bonobos (Fig. 2). The m. tibialis posterior of humans has sometimes a sesamoid bone in its tendon, near the talus or near the navicular bone (Gray, 1918). In humans, it is a strong muscle with two or three strands inserting onto the navicular bone and onto the three cuneiform bones. Other attachments, onto the cuboid, the metatarsal bases and onto the tendon sheet of the m. peroneus longus, can occur and fusion with the m. flexor hallucis brevis is variable (Otis & Gage, 2001). These multiple insertions are bipedal specializations, which provide powerful action of the m. tibialis posterior and stabilize the longitudinal arch with help from the m. flexor hallucis brevis (Lewis, 1964).

The peronei are powerful foot evertors in apes and humans. The m. peroneus longus acts also as a hallucal flexor and adductor in apes. Organization of the peronei is similar in gibbons, bonobos and humans.

The m. peroneus longus (Plong) has a long tendon that runs downward along the lateral side of the fibula and lies above the m. peroneus brevis tendon at the ankle joint. It runs behind the lateral malleolus and crosses the plantar side of the foot through a canal (i.e. the sulcus tendinis m. peronei longi). At the entrance of the canal, near the cuboid bone, the tendon often contains a sesamoid bone. Such sesamoid bone was lacking in our bonobo specimens but was observed by Miller (1952). In gibbons and bonobos, the peroneus longus muscle is fused with the muscle belly of m. peroneus brevis at its origin and the tendon inserts onto the first metatarsal. In humans, there is also an insertion onto the medial cuneiform and a sesamoid bone is rare (Macalister, 1875).

Both in apes and in humans, the m. peroneus brevis (Pbrev) is much smaller than the m. peroneus longus and its attachment onto the fibula extends to the malleolus lateralis. At this point the external tendon emerges and inserts laterally onto the tuberosity of metatarsal V.

The m. peroneus tertius (or m. fibularis tertius; Eliot & Jungers, 2000) is usually present in *Homo* (95%) but variable in *Hylobates* (30*–*50%) and rare in *Pan* (0*–*5%; Miller, 1952; Deloison, 1993; Jungers et al. 1993; Thorpe et al. 1999; Gibbs et al. 2000). However, in our dissections we found an m. peroneus tertius in the adult female bonobo and none in the gibbon specimens. The muscle arises from the lower third of the anterior surface of the fibula and from the lower part of the interosseous membrane. The tendon, after passing under the transverse and cruciate crural ligaments, inserts

into the dorsal surface of the base of the metatarsal bone of the little toe (Gray, 1918). The m. peroneus tertius functions as an evertor and dorsiflexor of the foot during the swing phase. The muscle works in concert with the m. tibialis anterior and the EDL muscle to level the foot and to cause toe clearance during bipedal walking (Jungers et al. 1993). The function of the m. peroneus tertius in apes is, however, questionable, considering the highly variable occurrence of the muscle.

The intrinsic foot muscles

The hallucal muscles

The muscles that move the hallux are closely associated and well-developed in non-human apes. But the hallucal muscles are also relatively large in humans, despite the adducted position of the hallux in the human foot. This might be related to the important propulsive function of the hallux during bipedal walking.

In gibbons, the *m. abductor hallucis* (AbdH) consists of two muscle bellies that are fused proximally and insert separately onto the hallux (Fig. 5A). Although a twoheaded *m. abductor hallucis* has also been described for common chimpanzees (Sokoloff, 1972), we did not observe such an organization in the bonobo foot. In bonobos and humans, the m. abductor hallucis is a thick, one-headed muscle, with a broad insertion onto the medial sesamoid bone and hallux (Fig. 5B).

In non-human apes, the m. adductor hallucis is a large two-headed muscle, consisting of a small 'oblique head' (AddHo) and a massive 'transverse head' (AddHt), which are closely associated (Fig. 6). Insertion of both heads is similar in gibbons, bonobos and humans but the place of origin is different. In humans, the two heads of the m. hallucal adductor are not fused and the transverse head is weakly developed, reflecting the absence of an opposable hallux.

In gibbons, the m. flexor hallucis brevis (FHB) is a rather broad and flat muscle with a complex organization. The muscle belly is proximally fused with the AddHo muscle and distally with the AbdH I tendon. It has a sesamoid bone near the site of origin (in the annular ligament) and at insertion. In bonobos, the m. flexor hallucis brevis is a two-headed muscle, lying just beneath the AbdH. There is also a lig. annulare near its base, through which the tendon of the FF runs, but a sesamoid bone is absent (Figs 4B and 5B). The FHB has a similar organization in humans and bonobos; the medial head is fused with the AbdH and the lateral

Fig. 5 Muscles in the upper plantar layer of a gibbon (A) and bonobo (B) foot.

head is fused with the AddH at insertion (Fig. 5B). This muscle is larger in humans than in apes and reflects the importance of hallucal flexion during bipedal locomotion (Aiello & Dean, 1990).

In gibbons, the muscle belly of m. extensor hallucis brevis (EHB) has parallel orientated fibres and is not fused with the muscle bellies of the m. extensor digitorum brevis. In bonobos, the muscle belly of m. extensor hallucis brevis is bipennate and is slightly fused at is base with the muscle bellies of the m. extensor digitorum brevis. A similar organization is found in humans.

The short digital extensors

These are small muscles with thin tendons that work in concert with the EDL to extend the digits. However, contraction of the short digital extensors permits extension of the toes independently of ankle dorsiflexion (Langdon, 1990). In gibbons, bonobos and humans there is a clear division between the hallucal extensor and the digital extensors (inserting onto digits II–IV) but the amount of association between both intrinsic extensors differs. The distribution and function of the short extensors is similar in gibbons, bonobos and humans but the fibre architecture of the muscle bellies is variable. A tendon to the fifth toe is usually lacking.

The m. extensor digitorum brevis (EDB) has three thin muscle bellies lying on the dorsum pedis, each of which sends a small tendon to digits II, III and IV. In gibbons, they are unipennate muscles, which are slightly interconnected but the belly to the fourth digit was separate in one specimen. A tendon to the fifth toe was reported for *H. syndactylus* and *H. hoolock* (Groves, 1972; see also Lewis, 1989) but was absent in all our specimens (and in the specimens reported by Langdon, 1990). In bonobos, they are bipennate muscles and in the left foot of the adult male a tendon towards the third digit was lacking. In humans, the EDH and EDB are proximally fused, as in bonobos, and occasionally one or more tendons are lacking.

The short digital flexors and associated muscles

The m. flexor digitorum brevis (FDB) is a small muscle lying in the upper plantar muscle layer. The FDB tendons are perforated by the tendons of the deep hind flexors before insertion onto the distal phalanges (Fig. 5). The muscle has a different organization in apes

Fig. 6 Hallucal muscles in the upper plantar layer of a gibbon (A) and bonobo (B) foot.

and humans and there is a high intraspecific, and even intra-individual, variation in both apes in the distribution of the tendons towards the digits (see also Wilder, 1863; Kohlbrügge, 1890/91; Sokoloff, 1972; Langdon, 1990). Even in humans some variation in tendon distribution is present (Macalister, 1875).

In both apes, the muscle is arranged into a deep and superficial head. The superficial head of the FDB has a strong origin onto the medial calcaneal process and can contract separately from the other flexors. Thus, phalangeal flexion of the middle toes (II and III) is independent from the position of the foot, plantar flexion in particular, which strengthens the grasping capability of the ape foot. The deep layer, however, is fused with the FT tendon and flexion of the fourth (and fifth) toe will be accompanied by plantar flexion of the foot due to the simultaneous contraction of FT and FDB II.

In gibbons, the superficial layer has one muscle belly and the deep layer has two or three smaller muscle bellies (Fig. 5A). The tendons of the deep layer insert onto digits III, IV and V but the fifth tendon is not perforated and is frequently absent (Kohlbrügge, 1890/91; Langdon, 1990). In one specimen the tendon to the fourth digit was not perforated either. The superficial head has a long tendon inserting onto the second digit. In bonobos, the arrangement of the tendons is variable, even between the left and right foot of the same specimen (see also Wilder, 1863, and Sokoloff, 1972, on *P. troglodytes*)*.* The tendon of the superficial layer runs towards digit II and the tendon of the deep layer runs towards digit IV (Fig. 5B). Insertion onto digit III can be either by a tendon of the superficial layer or by a tendon of the deep layer. A tendon towards the fifth digit is absent in bonobos and is also frequently lacking in common chimpanzees (Sokoloff, 1972; Langdon, 1990; Deloison, 1993) and humans (in 23% of the cases, Gray, 1918). The FDB muscle of humans has 3–4 muscle bellies but is arranged in one (superficial) layer, which is closely connected with the plantar aponeurosis (Sigmon & Farslow, 1986; Deloison, 1993). However, a deep head is found in some human populations, e.g. the South African Bushmen, and is associated with a weakly developed superficial head and a small medial process of the calcaneal tuberosity or 'heel process' (Sarmiento, 1983; Lewis, 1989).

The mm. lumbricales are very small muscles located in the middle plantar layer of the foot and are closely associated with the deep hind flexors (see above; Figs 4 and 5). They assist in metatarso-phalangeal flexion.

The muscles of the fifth toe

There are several separate muscles that assist in both flexion and abduction of the fifth digit. These are mostly tiny muscles that are closely associated with each other and hence difficult to identify separately.

In gibbons, the m. abductor digiti minimi (AbdV) is thin and its entire tendon is fused with the FlexV muscle (Fig. 5A). In bonobos, the m. abductor digiti minimi is distally fused with the FlexV muscle, and has two long, separate tendons at insertion. The same organization has been described for common chimpanzees (Wilder, 1863). It is a very thick muscle, which forms the lateral part of the sole of the foot (Fig. 5B). In humans, the muscle is even more prominent, and originates from both calcaneal processes. It stabilizes the human foot during bipedal walking (Mann & Inman, 1964).

In gibbons, the m. flexor digiti minimi brevis (FlexV) is a small muscle located at the metatarsal V shaft that is fused at its whole length with the AbdV tendon (Fig. 5A). In bonobos, the FlexV muscle consists of two parallel muscle bellies, running over the whole length of the fifth metatarsal, and both bellies are fused at origin and insertion with the AbdV tendon. The FlexV muscle is one-headed in humans but is more prominent than in the apes and is only slightly fused with the AbdV tendon at insertion.

The m. opponens digiti minimi (ODM) and the m. contrahens V are very small muscles, located in the deep plantar layer of the foot. The ODM and contrahens V muscles have been described for most non-human primates but observations in hominoids are infrequent (Kohlbrügge, 1890/91; Miller, 1952; Sokoloff, 1972; Sigmon & Farslow, 1986; Lewis, 1989; Deloison, 1993). These small muscles

are often fused (Jouffroy, 1962; Grand, 1967; Lewis, 1989). In the male *lar* gibbon we have identified a very small muscle, originating from the lateral cuneiform bone and inserting onto the plantar side of the fifth metatarso-phalangeal joint, which is probably the ODM muscle (Fig. 6A). We have also found a presumed ODM muscle in the deep plantar layer of one bonobo foot, running obliquely from the cuboid-metatarsal IV joint to the metatarso-phalangeal V joint (Fig. 6B). The muscle was lying on top of the mm. plantar interossei and had a small tendon at its insertion. The ODM, which is sometimes described as a deep part of the FlexV muscle, is often present in the human foot and is a minor flexor of the fifth metatarsal (Gray, 1918). An m. contrahens V is rarely seen in modern humans.

The mm. interossei

These are small, bipennate muscles that are located between the metatarsal bones and run from the bases of the metatarsal bones to the bases of the first phalanges of the same toe. They are divided into the dorsal and ventral mm. interossei in humans but this distinction is less clear in gibbons and bonobos (and *P. troglodytes*; Sokoloff, 1972). The mm. interossei are very small and the dorsal and ventral group are located very close to each other. Thus, it is practically difficult to study the exact origin and insertion of these groups (see also Wilder, 1863; Grand, 1967; Sigmon & Farslow, 1986). There are four dorsal mm. interossei that are arranged around the functional axis of the foot. In higher non-human primates the axis is the third digit (mesaxonic pattern); in humans it is the second digit (entaxonic pattern; Sigmon & Farslow, 1986; Lewis, 1989). The dorsal mm. interossei abduct digits II and IV from the third digit and also cause metatarsophalangeal flexion of digits II, III and IV. There are three plantar mm. interossei, at the lateral side of metatarsal II and the medial sides of metatarsals IV and V. They adduct digits II, IV and V towards the third ray and also cause metatarso-phalangeal flexion. In the juvenile gibbon, we found two additional mm. interossei, one at the medial side of the second digit, inserting distally onto the proximal phalanx I, and one at the lateroplantar side of the third metatarsal.

The organization of the mm. interossei in apes appears to be different from the typical human pattern and therefore we suggest that another nomenclature should be used for the description of the interosseus muscles of non-human primates. It might be beneficial

Fig. 7 Footprint of a gibbon (A) and bonobo (B), scaled to the same length.

to abandon the prevailing distinction into a plantar and dorsal interosseus muscle group and instead adopt a nomenclature in which the mm. interossei are grouped per digital unit (digits II–V; see also Sokoloff, 1972).

The planta pedis

The bonobo foot has a broad heel region compared with the slender gibbon foot, as can clearly be seen in Fig. 7. On these footprints you can also observe the deep cleft between the first and second toe in the gibbon foot and the apparent flatness of both ape feet, which is due to the absence of a longitudinal arch. Between the plantar epidermis and the plantar aponeurosis there is a layer of fat tissue. In the human foot this is a thick layer, which is particularly dense in the heel region, i.e. the so-called 'heel pad'. Both apes lack such a well-developed plantar fat layer but in gibbons regions of accumulated adipose tissue are observed at the heel, at the lateral foot border, at the base of the

hallux and at the metatarsal heads. In bonobos, fat tissue was only found in the heel region and lateral foot border. This is an interesting difference, because the distribution of fat tissue on the foot sole gives information on the position of the foot during locomotion. Bonobos strike the ground with the heel and lateral midfoot (Vereecke et al. 2003), whereas gibbons do not heel-strike but exert high impact forces at the middlemost metatarsal heads (Schmitt & Larson, 1995; Vereecke et al. in press). In line with the marked heelstrike in humans, there is a particularly thick heel pad in the human foot.

The human plantar aponeurosis is a tight network of collagen fibres, reaching from the calcaneus to the base of the phalanges of the five digits, which helps to maintain the longitudinal foot arch. It functions as a shock absorber (Jacob, 2001) and as an elastic recoil mechanism that saves up to 17% of energy during human bipedalism (Alexander, 1992). This plantar aponeurosis is also present in gibbons and bonobos but

Fig. 8 Relative distribution of the extrinsic muscles in the gibbon (*Nomascus* and *Hylobates* sp.), bonobo (*Pan paniscus*) and human (*Homo sapiens*) foot. M: male and F: female specimen.

is not as extensive and strong as in humans and a longitudinal foot arch is lacking. In gibbons and bonobos, the plantar aponeurosis originates from the calcaneal tuberosity and from the intermuscular septum between the hallucal and digital flexors. It runs over the foot sole towards the metatarso-phalangeal joints of digits II–IV, towards the navicular bone, to the lateral side of the first metatarsal head, and to the lateral tuberosity of metatarsal V. It consists of strong and parallel orientated fibres that are closely associated with the foot sole and that are connected with the fascia of the superficial plantar foot muscles. The plantar aponeurosis of both apes might assist in digital flexion (Sokoloff, 1972) but an energy-saving function is presumably absent, due to the lack of a longitudinal foot arch.

The relative importance of the foot and ankle muscles in gibbons, bonobos and humans

We compared the relative amount of extrinsic and intrinsic foot muscle mass in gibbons and bonobos and for both apes we have found that they account for, respectively, 3.0% and 0.6% of the total body mass.

Thus, gibbons do not have relatively larger intrinsic foot muscles and bonobos do not have relatively heavier extrinsic foot muscles.

The relative mass distribution of the extrinsic foot muscles is shown in Fig. 8 and the triceps are clearly the largest muscle group in humans, accounting for up to 60% of the extrinsic foot muscles. This is not too surprising given that plantar flexion is very important during bipedal walking. Large propulsive forces have to be generated prior to toe-off, which explains the need for large plantar flexors (Hof et al. 2002). But, the triceps are also the largest muscle group in both apes, accounting for more than 40% of the extrinsic muscle mass (Fig. 8). Although these are not yet comparable with the huge human triceps, it appears that plantar flexion is also important in gibbon and bonobo locomotion. Looking in more detail at the relative mass distribution and the scaled PCSA of the different triceps muscles we do find some differences between the two apes. The m. soleus is the largest and strongest plantar flexor in bonobos, whereas the m. gastrocnemius is the largest and most powerful plantar flexor in gibbons and an m. plantaris is frequently absent (Fig. 8; Tables A1 and A2).

Fig. 9 Relative distribution of the intrinsic muscles in the gibbon (*Nomascus* and *Hylobates* sp.) and bonobo (*Pan paniscus*) foot. M: male and F: female specimen.

Other differences are found in the relative amount of invertor/evertors and deep hind flexors. We have observed that bonobos have a relatively larger and stronger m. tibialis posterior, acting as a powerful invertor of the foot (see the scaled PCSAs of Tables A1 and A2). By contrast, gibbons have a relatively stronger m. peroneus brevis, which is an important foot evertor (see the scaled PCSAs of Tables A1 and A2). Gibbons also have slightly heavier and stronger deep hind flexors than bonobos (see the scaled PCSAs of Tables A1 and A2), pointing to more powerful digital flexion in the gibbon foot.

A last difference is found in the relative strength of the dorsiflexors. The m. tibialis anterior and the EDL muscle of bonobos have a relatively larger PCSA than observed in the adult gibbon, although no difference was found in the relative mass of these dorsiflexors (Fig. 8; Tables A1 and A2). Apparently, these muscles are more elongated, and hence less forceful, in gibbons. There is, however, considerable individual variation in the PCSA of the extrinsic muscles, especially between the adult and juvenile gibbon, so we should be cautious when looking at these data.

If we compare the extrinsic foot muscles of humans with those of both apes, we find that the sizes of the human dorsiflexor and invertor/evertor muscle group are similar to these of both apes (Fig. 8). However, the human

deep hind flexors are very small, which can be related to the absence of a prehensile function in the human foot.

The mass distribution of the intrinsic foot muscles of gibbons and bonobos is depicted in Fig. 9 and is very similar in both apes. The hallucal abductors and adductors are clearly the largest intrinsic foot muscle group in gibbons and bonobos, accounting for more than 60% of the intrinsic foot muscles. This points to a powerful hallux and is related to the prehensile ape foot. Gibbons have a relatively larger m. hallucal adductor and a smaller abductor than bonobos but apart from this no significant size differences are observed. In both apes, the short flexors are somewhat larger than the short extensors, which is in accordance with the importance of digital flexion during arboreal locomotion. Unfortunately, comparison with the human foot was not possible because we could not obtain data from the intrinsic foot muscles of humans. When we compare the scaled PCSA of the intrinsic foot muscles of both apes we find that gibbons have somewhat stronger hallucal extensors and flexors than bonobos. This might point to a stronger hallucal grasp in gibbons compared with bonobos. However, we have to be cautious when interpreting these, and the other, muscle mass data, as they only come from two gibbon specimens and one bonobo specimen.

The importance of tendon in the locomotion of nonhuman apes can be estimated by calculating the ratio of muscle belly length to total muscle–tendon unit length (see Table 5). We found some differences between the relative muscle belly lengths of gibbons and bonobos, but again, we have to be aware that there might be some intraspecific variation as well. The most apparent difference is found in the relative length of the Achilles tendon. The Achilles tendon comprised a greater proportion of the muscle–tendon unit of the triceps in gibbons (28–38%) than in bonobos (4–8%) and other non-human apes (Payne, 2001). As a consequence the m. gastrocnemius and m. soleus have shorter muscle bellies and the mass of the triceps is more proximally distributed in gibbons than in bonobos and other great apes. The importance of the Achilles tendon as an energysaving mechanism during high-speed locomotion has been well documented in human and non-human animals (Alexander & Vernon, 1975; Alexander et al. 1982; Ker et al. 1988; Alexander, 1991; Biewener, 1998; Payne, 2001; Hof et al. 2002). As gibbons have a well-developed Achilles tendon and their bipedal locomotion is often very fast and bouncing (our personal observations; Tuttle, 1972), it is very likely that a similar energy-saving mechanism is also active during high-speed locomotion of gibbons. As a consequence, gibbon locomotion might be more (energetically) efficient than the locomotion of other non-human apes. However, this still needs to be confirmed by a detailed analysis of the energetic costs of hylobatid locomotion.

The results for the other extrinsic foot muscles are less definite. Some muscles are more tendinous in gibbons, such as the EHL, the Pbrev and the TP muscle, whereas other muscles are more tendinous in bonobos, such as the TA muscle (Table 5). Previously obtained data on the hind limb muscles of hominoids (Thorpe et al. 1999; Payne, 2001) have emphasized the remarkable slender and tendinous thigh muscles of gibbons, but apparently this is less pronounced in the more distal muscle groups.

The sesamoid bones

We have observed a markedly higher occurrence of sesamoid bones in the gibbon foot compared with the bonobo and human foot. Most sesamoid bones are embedded in the tendons, near the attachment site, but some are found proximally, e.g. in the gastrocnemius muscle. The two sesamoid bones of the hallux are

present in gibbons, bonobos and humans but gibbons (and common chimpanzees; Deloison, 1993) also have sesamoid bones at the other metatarso-phalangeal joints. Nearly all sesamoid bones that we have observed in gibbons have also been described for humans, but most of them are very uncommon (Pfitzner, 1896; Gray, 1918). Probably, a similar number of sesamoid bones are present as cartilaginous nodules in ape and human fetuses but different physical demands may determine which sesamoid bones persist in the adult (Gray, 1918; Sarin et al. 1999). Apparently, gibbon locomotion selects for the retention of many sesamoid bones, which offers several benefits to the musculoskeletal system:

(1) First, they can improve the joint mechanics, by increasing the lever arm of the muscle and, hence, increasing the flexion torque. They can also change the direction of pull and can diminish friction, which also enhances the joint mechanics. (2) Secondly, the reduction of friction also enhances tendon sliding, which prevents wear and tear in tendon. Thus, sesamoid bones can also provide mechanical protection to the tendon. (3) Finally, they can disperse forces and modify pressure, by acting as a shock absorber and in transferring loads from the substrate to the bones (David et al. 1989; Perlman, 1994).

But why have most sesamoid bones not been retained in bonobos and humans, if they are indeed so advantageous? This might be related to the more tendinous muscles of gibbons compared with other apes and humans (Payne, 2001), as it is probably more crucial for longer tendons to reduce friction and to obtain mechanical protection. This might also be the reason why horses, which have extremely long tendons, have numerous sesamoid bones (Nickel et al. 1986).

Conclusion

The foot and ankle musculature follows the same general 'bauplan' in gibbons, bonobos and humans, which is not so surprising in view of their close phylogenetic relationship. The human foot is most deviant, owing to its bipedal specializations, but the foot–ankle complex of gibbons and bonobos is remarkably similar. Both apes have strong plantar flexors and large hallucal muscles, which are related to a propulsive and prehensile foot function. Thus, although gibbons and bonobos have a clearly different ecological niche and locomotor behaviour, the myology of their foot–ankle complex is largely similar. Both apes have a very adaptable

foot–ankle complex with a generalized structure, which enables them to use a wide variety of locomotor modes and substrates. Whether the similarities in the foot myology of gibbons and bonobos are homoplasies or synapomorphies remains unresolved but we hope that additional research on primate foot myology might help to clarify this question in the (near) future.

This study gives a clear and detailed description of the functional morphology of the foot–ankle complex of two extant ape species and provides viable form– function relationships. This can be used in studies on primate locomotion but might also be helpful for the reconstruction of the locomotor behaviour of (pre)hominid fossils.

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 $partheses$).

AddHo 0.54 (0.15) 3.20 (2.55) 3.20 (2.10) 1.20 (1.50) –(0.40) –(0.35) –(0.17) –(1.60) –(0.40) ^v EHB 0.54 (0.24) 8.80 (6.00) 3.20 (3.25) 0.60 (0.50) 0.30 (–) 1.70 (–) 0.50 (–) 6.20 (3.69) –(3.19) – EDB 1.20 (0.58) 9.60 (8.35) 4.10 (3.73) 5.70 (0.35) 1.80 (1.50) 0.63 (0.36) 0.19 (0.18) 7.60 (5.70) –(4.20) – FHB 1.20 (0.32) 4.20 (3.25) 4.20 (3.25) 0.90 (0.90) 1.00 (–) 1.13 (–) 0.33 (–) ^v FDB I 0.54 (0.15) 11.90 (6.85) 6.70 (3.00) 0.55 (0.30) 2.00 (–) 0.25 (–) 0.08 (–) 8.10 (4.65) 7.80 (–) – FDB II 0.60 (0.31) 7.00 (5.53) – AbdV 0.40 (0.24) 7.90 (6.80) 4.10 (4.35) 0.40 (0.45) –(0.81) –(0.28) –(0.14) 7.90 (5.80) –(2.80) – FlexV 0.20 (0.07) 4.80 (2.70) 2.90 (1.70) 0.30 (0.30) –(1.00) –(0.07) –(0.03) 3.60 (1.00) –(0.50) – ODM 0.06 (–) 2.60 (–) 1.80 (–) 1.50 (–) –

Muscle	Mass (g)	Length (cm)	BL (cm)	BW (cm)	FL (cm)	PA $(^\circ)$	$PCSA$ (cm ²)	Scaled PCSA	LT (cm)	LET (cm)	Oss
Galat	105.17 (36.00)	31.20 (33.00)	$28.60(-)$	$-(3.50)$	9.50(7.00)		10.44 (4.85)	0.68(0.44)			
Gamed	141.45 (64.00)	32.50 (31.00)	$29.80(-)$	$-(3.00)$	9.67(7.50)		13.80 (8.05)	0.90(0.73)			
Soleus	220.21 (140.00)	29.30 (28.00)	$28.00(-)$	$-(5.00)$	6.20(7.10)		33.51 (18.60)	2.19(1.69)			
Plant	8.66(6.00)	32.80 (32.00)	14.50 (12.00)	$-(1.60)$	5.40(8.50)		1.51(0.67)	0.10(0.06)	$-(20.00)$		
EHL.	12.05 (10.00)	32.00 (25.00)	21.00 (17.50)	$-(1.50)$	8.30(8.00)		1.37(1.18)	0.09(0.11)	$-(7.50)$		
EDL	43.23 (34.00)	46.00 (37.00)	28.00 (26.50)	$-(2.00)$	9.00(10.50)		4.53 (3.05)	0.30(0.28)	$-(10.50)$		
TA	101.20 (74.00)	34.00 (29.00)	23.80 (25.00)	$-(2.00)$	9.50 (19.00)		10.05 (4.99)	0.66(0.45)	$-(4.00)$		
FF.	121.34 (32.00)	45.30 (41.00)	$25.30(-)$		$8.00(-)$		$14.31(-)$	$0.94(-)$			
FT.	41.52 (80.00)	41.90 (38.50)	20.40 (25.00)		$6.30(-)$		$6.22(-)$	$0.41(-)$	$-(13.50)$		
lumbr	$-(7.70)$	$13.80(-)$	$7.00(-)$	$0.65(-)$	$7.80(-)$				$6.47(-)$		
Plong	70.58 (52.00)	33.00 (32.50)	21.50 (23.50)		5.40(6.00)		12.33 (8.18)	0.81(0.74)	$-(9.50)$		
Pbrev	31.44 (30.00)	23.00 (31.00)	19.00 (27.00)	$-(2.50)$	5.30(6.50)		5.60(4.35)	0.37(0.40)	$-(4.00)$		
TP	79.25 (56.00)	27.20 (31.00)	21.00 (23.00)	$-(2.50)$	4.40(4.00)		16.99 (13.21)	1.11(1.20)			
AbdH	21.80	12.61	9.72	2.41	4.80		4.29	0.28	2.94		v
AddHt	24.38	5.76	5.76	4.64	4.50		5.34	0.35			v
AddHo		5.53	5.53	2.78	3.10		5.02	0.33			v
EHB		16.30	7.49	1.77	4.20		3.05	0.20	12.79		
EDB	13.60	17.80	8.20	0.55	5.10		2.51	0.16	9.77		
FHBm	4.71	5.52	5.52	2.02	1.80		2.47	0.16			v
FHBI	1.12	4.86	3.87	1.70	1.80		0.59	0.04	1.76		v
FDB I	7.17	19.08	8.20	1.62	5.30		1.28	0.08	14.38		
FDB II	1.69	13.59	5.20	1.02	2.00		0.80	0.05	9.59		
AbdV	7.79	12.66	7.55	1.85	4.30		1.71	0.11	7.56		
FlexV			5.03						5.00		
iPlant	17.56	5.34	5.34	1.51							
CH	0.17	5.09	5.09								

Table A2 Muscle data of the male and female bonobo (female data in parentheses). Abbreviations as in Table A1.