

# Domain compliance and elastic power transmission in rotary $F_0F_1$ -ATPase

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The 2 nanomotors of rotary ATP synthase, ionmotive  $F_0$  and chemically active  $F_1$ , are mechanically coupled by a central rotor and an eccentric bearing. Both motors rotate, with 3 steps in  $F_1$  and 10–15 in  $F_0$ . Simulation by statistical mechanics has revealed that an elastic power transmission is required for a high rate of coupled turnover. Here, we investigate the distribution in the  $F_0F_1$  structure of compliant and stiff domains. The compliance of certain domains was restricted by engineered disulfide bridges between rotor and stator, and the torsional stiffness ( $\kappa$ ) of unrestricted domains was determined by analyzing their thermal rotary fluctuations. A fluorescent magnetic bead was attached to single molecules of  $F_1$  and a fluorescent actin filament to  $F_0F_1$ , respectively. They served to probe first the functional rotation and, after formation of the given disulfide bridge, the stochastic rotational motion. Most parts of the enzyme, in particular the central shaft in  $F_1$ , and the long eccentric bearing were rather stiff (torsional stiffness  $\kappa > 750$  pNm). One domain of the rotor, namely where the globular portions of subunits  $\gamma$  and  $\epsilon$  of  $F_1$  contact the c-ring of  $F_0$ , was more compliant ( $\kappa \cong 68$  pNm). This elastic buffer smoothes the cooperation of the 2 stepping motors. It is located where needed, between the 2 sites where the power strokes in  $F_0$  and  $F_1$  are generated and consumed.

elasticity | F-ATPase | nanomotor

Molecular motors abound in the cell. It is worth asking whether or not a discrete power stroke, usually caused by the hydrolysis of ATP or the transport of an ion, is fine-tuned to the detailed molecular events that are powered by the respective motor. In ATP synthase ( $F_0F_1$ -ATPase), for instance, the rotary electromotor,  $F_0$ , drives the rotary chemical generator,  $F_1$ , to synthesize ATP. Whereas  $F_0$ , depending on the organism, processes in 10–15 steps per turn,  $F_1$  processes in 3 steps. As an alternative to the fine-tuning of the underlying partial reactions, it has been proposed (refs. 1–4 and references therein) that an elastic power transmission might serve to smooth the coupled operation of the counteracting rotary motors. To substantiate this claim here, we determined the distribution of stiff and compliant domains over the molecular structure of this enzyme.

The ATP synthase from *Escherichia coli*,  $EF_0F_1$ , is composed of 8 different subunits attributable either to the “rotor,” namely, subunits  $\gamma$  and  $\epsilon$  of  $F_1$  plus the  $c_{10}$  ring of  $F_0$  (5), or to the “stator,” namely, subunits  $\delta$  and  $(\alpha\beta)_3$  of  $F_1$  plus subunits  $a$  and  $b_2$  of  $F_0$ . The rotor portion of  $F_1$  is linked to the rotor portion of the ion-motive  $F_0$  by interfacing subunits  $\gamma$  and  $\epsilon$  of  $F_1$  with the c-ring of  $F_0$ . The crystal structure of the bovine mitochondrial  $F_1$  ( $MF_1$ ) (6) has revealed the threefold pseudosymmetry of the hexagon formed by subunits  $\alpha$  and  $\beta$ , which are arranged as  $(\alpha\beta)_3$ . Under ATP hydrolysis, the structural symmetry of 3 is paralleled by the rotation of the  $\gamma$  subunit in 3 steps of  $120^\circ$  with substeps of  $40^\circ$  and  $80^\circ$  (7–9). The c-ring ion-driven motor,  $F_0$ , contains 10–15 identical monomers, depending on the organism and, supposedly, steps by  $24^\circ$ – $36^\circ$ . The symmetry does match in some organisms (3:15) but not in others (e.g., 3:14 in chloroplast  $CF_0F_1$  and 3:10 in yeast and *E. coli*) (see refs. 10–12 and references therein).

First evidence for an elastic coupling element in  $F_0F_1$  has been provided by simulations of its kinetic properties both under rate limitation by proton transfer in  $F_0$  (13) and by catalysis in  $F_1$  (14). A first estimate for the torsional stiffness of the elastic element in  $EF_0F_1$  has been obtained from recordings of the torque as a function of the angular reaction coordinate (4). A single molecule of  $F_0F_1$  has been immobilized with  $F_1$  down on a solid support with a fluorescent actin filament attached to the c-ring of  $F_0$  to monitor the rotation as driven by the hydrolysis of ATP. Because of the viscous drag on the long filament (length  $>3 \mu\text{m}$ ) the turnover rate is reduced by  $>2$  orders of magnitude compared with the rate without filament. The viscous drag counteracts the enzyme-generated torque, and this bends the filament. As with a spring balance, its curvature was used to determine the torque as a function of the angular position of the c-ring. Although the driving motor,  $F_1$ , progressed in steps (of  $120^\circ$ ), the torque profile, as sensed by  $F_0$ , was smooth, and this was attributed to an elastic coupling element with a torsional stiffness of  $\approx 60$  pNm (4). The theoretical treatment of this nanomachine in terms of the Smoluchowski equation of statistical mechanics has revealed the benefit of an elastic buffer, which is required for a high turnover rate under load (see figure 8 in ref. 4 and also ref. 15). Although the existence of an elastic power transmission between  $F_0$  and  $F_1$  has been established by the above-cited work (4), the magnitude and the distribution of compliant versus stiff elements over the enzyme structure, in particular between central rotor and eccentric stator, has not been determined before. Here, we investigated the torsional stiffness of several enzyme domains by fluctuation analysis, and localized the elastic buffer in the structure of  $EF_0F_1$ . The domain compliance was investigated by monitoring either via a magnetic bead (diameter typically  $1 \mu\text{m}$ ) or by a short actin filament (length  $<0.5 \mu\text{m}$ ) the thermal rotational fluctuations of an attached fluorescent probe in immobilized single molecules. To attribute the observed overall compliance to specific enzyme domains we stiffened selected portions by disulfide cross-linking through engineered cysteines. The properties of the respective cysteine pairs, their position in the crystal structure and the correlation between the functional halt positions of the active enzyme, the disulfide-locked conformations, and the published crystal structures have been presented elsewhere (46).

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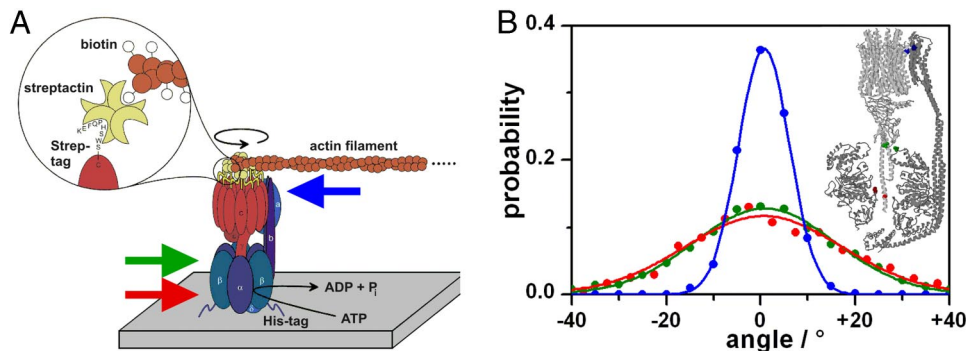
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**Fig. 2.** Immobilized  $EF_oF_1$  with attached actin filament of short length, typically  $0.5 \mu\text{m}$  (A), and histograms of thermally driven rotational fluctuations after the formation of a disulfide cross-link between the rotor and the stator (B). The positions of 3 different disulfide cross-links are indicated in colors in A and in the *Inset* in B, with matching colors of the respective histograms. For details, see *Results*.

$$\sigma_{\text{comp}}^2 = k_B T \cdot (\kappa_1^{-1} + \kappa_2^{-1}) = k_B T \cdot \kappa_{\text{result}}^{-1} \quad [3]$$

If, instead of the standard deviation,  $\sigma$ , in radians, the FWHM of the distribution in degrees is read out, the stiffness,  $\kappa$ , reads as follows:

$$\kappa = 8 \cdot \ln 2 \cdot \left(\frac{180}{\pi}\right)^2 \cdot k_B T \cdot (\text{FWHM})^{-2} \cong 73,700 \text{ pNm} \cdot (\text{FWHM})^{-2} \quad [4]$$

In summary: (i) The width of rotational fluctuations yields the torsional stiffness calibrated in terms of  $k_B T$ . (ii) In composite rods, the reciprocal stiffnesses are additive. (iii) The most compliant element stores the major portion of the elastic deformation energy, and it contributes most to the deformation angle.

**Torsional Compliance of the Rotor Portion in  $EF_1$ .** The evaluation of the original data shown in Fig. 1C according to Eq. 2 yielded a stiffness of  $\approx 1,500$  pNm for the mutant  $\beta D380C/\gamma A87C$ , where the disulfide link was placed close to the bead (green) and 500 pNm for the mutant  $\alpha E284C/\gamma A270C$  (magenta), where it was farther down. The greater figure in the former mutant comprised compliance from all elements of the surface-to-enzyme-to-bead construct, in particular the rotational compliance of the His tags, and of the bead's attachment to the central shaft. All these "background compliances" were small, and the enzyme body and its attachment to the surface were stiff. The great stiffness was partially relieved in the mutant where the rotor/stator lock was placed farther down toward the C terminus of subunit  $\gamma$  (Fig. 1C, magenta). The increase of the compliance was thus attributable to the portion of subunit  $\gamma$  lying between the 2 sites chosen for blocking the rotation. We calculated a stiffness of  $\kappa = 750$  pNm for the particular portion of the central stalk lying between the green- and magenta-encircled sites as shown in Fig. 1C.

**Torsional Compliance of the Rotor Portion in the Holoenzyme  $EF_oF_1$ .** The torsional compliance of the rotor-portion in the holoenzyme,  $EF_oF_1$ , was determined by a similar procedure as for  $EF_1$  except for 2 modifications, (i) ATP-driven ( $0.05\text{--}5$  mM Mg-ATP) instead of magnetically driven rotation served to select relevant single molecules, and (ii) a fluorescent actin filament attached to the c-ring of  $F_o$  served as a probe. This construct is illustrated in Fig. 2A. Detergent-solubilized  $EF_oF_1$  was immobilized by His tags. A fluorescent actin filament was attached to  $EF_o\text{-}c_{10}$  by biotin/streptactin linkage to engineered Strep-tags at the C termini of  $EF_o\text{-}c$  (16). The rotation of the  $c_{10}$ -ring, driven by ATP hydrolysis, was recorded by microvideography. Short filaments (typically  $0.5 \mu\text{m}$ ) were used to avoid viscous overdamping of the stepped rotation (4, 17). Oxidizing conditions promoted the formation of a disulfide bridge between appropriately engineered cysteines on the stator and the rotor (see Fig. 2B), and this blocked the rotation.

Keeping a given rotating enzyme molecule in focus and changing

the solution from reducing to oxidizing stopped the rotation. The rotational fluctuations persisted and were attributable to fluctuations within the enzyme. The actin filament itself contributed negligibly because of its short length (see ref. 17).

The *Inset* in Fig. 2B shows the location of the disulfide bridge in 3 mutants, namely (i)  $\alpha I223C/\gamma L72C$  (blue), (ii)  $\beta D380C/\gamma A87C$  (green), and (iii)  $\alpha E284C/\gamma A270C$  (red). The probability distributions of the respective rotational fluctuations are shown in matching colors in Fig. 2B. The respective FWHM translated into the following figures for the torsional stiffness in pNm: (i) 450 (blue), (ii) 59 (green), and (iii) 47 (red). It implied a stiffness of  $<68$  pNm for the rotor segment lying between the blue and the green disulfide bridges. The stiffness of the segment between the green and the red disulfide bridges was not to be determined precisely here because of the great compliance of the segment farther up toward  $F_o$ .

The largest stiffness resulted if the c-ring was locked to subunit a (blue in Fig. 2B). The stiffening effect of this particular cross-link showed that the respective detergent-solubilized and surface-attached  $EF_oF_1$  construct was intact and, in particular, that the attachment of the stator to the rotor was present. This qualifies the previous notion of a dangling stator in this  $EF_oF_1$  construct (18). The smaller stiffness (450 pNm) compared with the one observed with magnetic beads for  $F_1$  (1,500 pNm) was attributable to the compliance of the c-ring/ $F$ -actin construct. It was not caused by the attachment of  $F_1$  to the solid support (see data in Fig. 1C).

**Torsional Compliance of the Unrestricted, Active Enzyme.** The torsional compliance of the unrestricted, active enzyme, e.g., during 1 ATP-waiting dwell before jumping by  $120^\circ$  into the next dwell, was inferred from long trajectories of rotation. Fig. 3A shows a short segment of a stepped rotary trajectory of 2-s duration, and Fig. 3B shows the respective angular probability distribution. The stiffness of the ADP-saturated and thereby intrinsically locked state (orange in Fig. 3B) was 66 pNm, very much the same as when the DELSEED lever was cross-linked with the rotor (68 pNm, green data in Fig. 2B). During the ATP-waiting dwells (typically of 100-ms duration, blue in Fig. 3B) the stiffness was  $\kappa = 30$  pNm. It implied that the lever motion (occurring during the ATP wait) contributed a stiffness of 50 pNm.

**Torsional Compliance of the Eccentric Bearing.** The torsional compliance of the eccentric bearing was investigated in a construct illustrated in Fig. 4A. A cysteine was added to the C terminus of subunit b (bold letters in NCMNLN... ). Two cysteines, one on each copy of the more or less parallel helices of subunit b (19–21), served as attachment sites for a Q-dot-doped magnetic bead via the maleimide-biotin link. Fig. 4B shows the probability distribution of the bead without magnetic field (*Upper*) and with the magnetic field turning steadily at 0.125 revolutions per second either clockwise (blue) or counterclockwise (red) when viewed from the  $F_o$  side (*Lower*). The sign of the displacement was chosen positive when moving in the counterclockwise direction. As expected, the rota-



mechanical engineering would have placed it; and (v) if the DELSEED lever is free to undergo hinge motion, as during the ATP-waiting dwell, it contributes another rotary torsional compliance with a stiffness of  $\approx 50$  pNnm.

Hydrolysis of ATP by  $EF_0F_1$  produces an average torque of 50 pNnm as determined from the curvature of a  $F_0$ -attached actin filament by the same single-molecule setup illustrated in Fig. 2A (4). If the holoenzyme operates in its native coupling membrane, and if it reaches thermodynamic equilibrium, then the forward torque generated by ionmotive force (by  $F_0$ ) counterbalances the backward torque by ATP hydrolysis (by  $F_1$ ), and the elastic element between them is maximally wound up. Taking the above-determined stiffness of the most-compliant domain of  $EF_0F_1$  as 68 pNnm, it implies that the rotor is twisted by an angle of  $\phi = M/\kappa = \frac{50}{68}$  or  $42^\circ$ , whereas the eccentric bearing is only negligibly twisted by  $< 2^\circ$ . This amounts to the storage of elastic energy of  $U = M^2/2\kappa = 18$  pNnm or 11.1 kJ/mol.

How do these figures compare with those that have been hypothesized or indirectly inferred in previous studies? Simulations of the kinetic behavior of the enzyme taking the transient storage of elastic energy have led to gross estimates for the torsional stiffness of the elastic buffer, 60 pNnm (13) and 30 pNnm (14), respectively. A stored elastic energy ( $6 k_B T \rightarrow 24.7$  pNnm  $\rightarrow 14.9$  kJ/mol) has been calculated for the elastic hinge motion in subunit  $\beta$  (15). The former figures resulted from rather indirect kinetic or theoretical approaches. The experimentally observed smoothing of the discrete power strokes of  $F_1$  after being transmitted to  $F_0$  has led to an estimate for stiffness in the order of 60 pNnm (4). The figures for the stiffness of the major elastic element between  $F_0$  and  $F_1$  resulting from the present work,  $\kappa \approx 68$  pNnm, and for the buffered elastic energy,  $U \approx 11$  kJ/mol, are of the same magnitude as the former ones. However, the elastic buffer has now been experimentally attributed to a given domain, namely the bulky segment including the large, globular domains of subunits  $\gamma$  and  $\epsilon$  plus the loops of the ring of subunit  $c$  to which they are attached.

Our results qualified the role of 3 enzyme domains that were tentatively discussed in this role: (i) The eccentric bearing was rather stiff (see Fig. 4B) [for the large binding strength of subunits  $\delta$  and  $b_2$  to the hexagon of  $(\alpha\beta)_3$  see refs. 22–24, and for a comprehensive review on  $b_2$  see ref. 21]. (ii) The elasticity of the hinge motion of the DELSEED region of subunit  $\beta$  has been previously emphasized in theoretical studies (15, 25). We have found that it matters during the turnover of the active enzyme, but it is not the main determinant of the elastic power transmission. (iii) When discussing the inner elasticity of  $F_0F_1$ , several groups (e.g., ref. 26) including our own have emphasized a role of the coiled coil plus the extended C terminus of subunit  $\gamma$ . Deletion studies (27, 28) have shown that this portion of the enzyme, extending from the counterpart on subunit  $\gamma$  of the DELSEED domain toward the supposed “hydrophobic bearing” (6), is dispensable for torque generation by  $F_1$ , although it is helpful for enzyme assembly and stability (27). Because it is (i) much less compliant than the main elastic buffer associated with the globular portions of  $\gamma$  and  $\epsilon$  and (ii) mobile in its bearing (29, 30), the coiled-coil region of subunit  $\gamma$  cannot be claimed as the main elastic buffer.

That the main compliance is associated with the globular portions of  $\gamma$  and  $\epsilon$  in contact with the  $c$ -ring is in line with the observation that these enzyme domains are not well-resolved in crystals of both  $F_1$  (6) and  $F_0F_1$  (11). Our data provide a basis for testing the predictive power of normal mode analysis (31) and molecular-dynamics simulations (31–36) of this particularly agile enzyme.

Because of the existence of an elastic buffer between the 2 stepping rotary motors in ATP synthase, any fine-tuning between the partial ion-transport events occurring in  $F_0$  and the partial chemical reactions (e.g., cleavage of certain hydrogen bonds) in  $F_1$  is dispensable. The elastic power transmission explains why the enzyme can work by the same principles with different gears (3:10–15) in different organisms and why it operates robustly even

in structurally modified (27, 28, 37–39) and in chimeric constructs with  $F_0$  and  $F_1$  taken from different sources (40). The essential function of the elastic buffer is to provide this stepping rotary enzyme with high kinetic efficiency, in other words, with a high rate of turnover under load (3, 4).

## Materials and Methods

**Molecular Genetics.** This work was carried out with 3 plasmids, namely pKH4, pSE1, and pKH7, and their derivatives. pKH4, the starting plasmid, had all wild-type cysteines substituted by alanines and carried a His<sub>6</sub> tag at the N terminus of subunit  $\beta$  (41). The plasmid pSE1, based on pKH4, carried a Strep-tagged C terminus in subunit  $c$  (16). The plasmid pKH7, based on pKH4, carried 1 extra cysteine,  $\gamma$ K108C. The plasmid pSW3, based on pKH7, carried the cysteine pair  $\beta$ D380C/ $\gamma$ A87C and is described in ref. 42. The pKH7-based plasmid pMM25, carrying the cysteine pair  $\alpha$ E284C/ $\gamma$ A270C, was a kind gift of M. Müller (University of Osnabrück, Osnabrück, Germany).

pSE1 was used as the starting plasmid for the mutations  $\alpha$ E284C/ $\gamma$ L276C,  $\alpha$ I223C/ $\epsilon$ L72C, and  $\beta$ D380C/ $\gamma$ A87C, resulting in the plasmids pGH14, pGH33, and pGH47, respectively. pBluescript II SK (+/–) subclones were generated by insertion of the following fragments of pSE1: KpnI/XhoI and KpnI/SacI for pGH14, BamHI/HindIII and BsrGI/PpuMI for pGH33, and KpnI/SacI for  $\gamma$ A87C in pGH47. Site-directed mutagenesis was carried out by PCR using the oligonucleotide 5'-CGCCAGGACGTTGTGCATCCCGG-3' and its complement 5'-CCGGAATGCAACAGTCCTGGCG-3' for  $\alpha$ E284C, 5'-GCATTACTCAGGAATGCACCGAGATCGTCTCG-3' and its complement 5'-CGAGACGATCTCGGTGCATTCGAGATGCG-3' for  $\gamma$ L276C, 5'-CCGGTGAGCTGATTTCTGTCTGATTGCTGCTGTTCG-3' and its complement 5'-GCAACAGACCAGCAATCAGACAGAAAATCAGCTCACCGG-3' for  $\alpha$ I223C, 5'-CGCTGTAGGTCTGGTTGCTACGTGATGTTGCTGTG-3' and its complement 5'-GACAGCGAACATCAGTAGCAACCCAGACCTACACGCG-3' for  $\epsilon$ L72C, and 5'-CGACCGACCGTGGTTGTGTGGTGGTTTGAAC-3' and its complement 5'-GTTCAAACACCACACAAACCCAGCGTCGGTCG-3' for  $\gamma$ A87C (43). KpnI/XhoI, BsrGI/PpuMI, and KpnI/SacI fragments of pSE1 were substituted with the corresponding fragments carrying the  $\alpha$ E284C,  $\epsilon$ L72C, and  $\gamma$ A87C mutations by standard restriction and ligation, resulting in plasmids pKG7, pGH39, and pGH46, respectively. The double mutants  $\alpha$ E284C/ $\gamma$ L276C, and  $\alpha$ I223C/ $\epsilon$ L72C were then generated by exchanging the KpnI/SacI and BamHI/HindIII fragments of pKG7 and pGH39 with the corresponding mutated fragments of the pBluescript II SK (+/–) subclones by standard restriction and ligation, resulting in the plasmids pGH14, and pGH33, respectively. The plasmid pGH47 was obtained by exchanging XbaI/SacI fragment of pGH46 with the respective fragment of pSW3, carrying the mutation  $\beta$ D380C, by standard restriction and ligation. Successful cloning was checked by nucleotide sequencing.

A cysteine residue was added to the N terminus of the  $b$  subunit by site-directed mutagenesis by the following procedures. A 756-bp BsaHI fragment of pKH4 including the gene for subunit  $c$  and most of the gene for subunit  $b$  was cloned into pUC8 that had been cut with *AccI* to produce pSD300, with the insert in the reverse orientation relative to expression. Site-directed mutagenesis was carried out by PCR using pSD300 as the template with the mutagenic oligonucleotide 5'-CAGAACGTTAACTAAATAGAGGCATTGTGCTGTAATTGTATGAATCTTAACGCAACAATC-3' and the M13 reverse primer. The mutagenic oligonucleotide included the *HpaI* site (italics) located upstream of the *uncF* start codon, and a 3-codon insertion (bold) at the start of *uncF*, retaining the natural GUG start codon. This insertion changed the N-terminal amino acid sequence encoded from MNLN to MNCMNLN. The PCR product was cut with *HpaI* and *EcoRI* and inserted into pSD300 that had been cut with the same enzymes to produce plasmid pSD303. After DNA sequencing, this plasmid was cut with *PpuMI* and *BsrGI*, and the 431-bp fragment was inserted into pKH4 that had been cut at unique sites with the same enzymes to produce plasmid pSD308.

**Preparation of  $EF_1$  and  $EF_0F_1$ .** The preparation of  $EF_1$ , derived from the plasmids pSW3 and pMM25, followed the same procedures published previously (27, 42).

$EF_0F_1$ , derived from the plasmids pGH14, pGH33, and pGH47, was prepared and purified via its Strep-tags as described in ref. 16.

$EF_0F_1$  based on pSD308, lacking the Strep-tag in  $c$ , was purified via its His tags as follows: Membrane protein was obtained as above, followed by centrifugation at  $100,000 \times g$  for 90 min. The supernatant was diluted with buffer A [20 mM Tris-HCl (pH 7.5), 50 mM KCl, 5 mM MgCl<sub>2</sub>, 10% (vol/vol) glycerol, 20 mM imidazole] to 1% (wt/vol) *N*-octyl-L-D-glucopyranoside final concentration and applied (3 times) to an empty NAP5 column packed with 1 ml of Ni-NTA-Superflow. Wash was done with 5 ml of buffer A and then with the same buffer containing 150 mM imidazole. Glycerol (70%) was added to eluates before they were quick-frozen in liquid nitrogen and stored at  $-80^\circ\text{C}$  before use.

**Preparation of F-Actin.** The preparation of F-actin followed the same procedures published previously (16).

**Preparation of Magnetic Beads.** Streptavidin-coated hyperparamagnetic beads (stock solution 10 mg/ml, diameter 1  $\mu$ m; Roche) for experiments with EF<sub>1</sub> or EFOF<sub>1</sub> were diluted 10-fold with 50 mM Mops/KOH (pH 7.5), 50 mM KCl, and 5 mM MgCl<sub>2</sub> (buffer B) or 50 mM Mops/KOH (pH 7.5), 50 mM KCl, 5 mM MgCl<sub>2</sub>, 0.5% (wt/vol) N-octyl-D-glucopyranoside, and 10% (vol/vol) glycerol (buffer C), respectively. The dilute suspension was centrifuged (16,000  $\times$  g, 4  $^{\circ}$ C, 3 min), and the pellet was resuspended in buffer B or buffer C. This washing procedure was repeated 3 times.

**Immobilization of EF<sub>1</sub> and EFOF<sub>1</sub>.** Similar procedures were used for immobilizing EF<sub>1</sub> and EFOF<sub>1</sub>. Samples were filled into flow cells consisting of 2 coverslips (bottom 26  $\times$  76 mm<sup>2</sup>; top 24  $\times$  24 mm<sup>2</sup>) separated by double-adhesive tape (Tesa). EFOF<sub>1</sub> protein solutions were stepwise infused as described previously (16) by using buffer C in all steps. 50  $\mu$ M–5 mM ATP was used in the last step. For ADP inhibition, 50  $\mu$ l of 20 mM glucose, 0.2 mg/ml glucose oxidase, 50  $\mu$ g/ml catalase (oxygen scavenger system, OSS), 0.5% 2-mercaptoethanol (2-me), 1 unit/ $\mu$ l hexokinase, and 5 mM ADP in buffer C were added after washing with 50  $\mu$ l of buffer C.

The infusion order for EF<sub>1</sub> was as follows (50  $\mu$ l per step, 4-min incubation, wash with buffer B before each step): (i) 0.8  $\mu$ M Ni-NTA-horseradish peroxidase conjugate in buffer B; (ii) 10 mg/ml bovine serum albumin in buffer B; (iii) 5  $\mu$ M EF<sub>1</sub> in buffer B; (iv) 0.2 mg/ml magnetic beads in buffer B (7-min incubation); (v) 2 pM Q-dots (stock 2  $\mu$ M, dilution factor 1:1,000,000; Quantum Dot) in buffer B (7-min incubation); (vi) OSS, 0.5% 2-me, 20 mM DTT, and 5 mM ATP in buffer B.

For PSD308-based EFOF<sub>1</sub>, the infusion followed the same instructions as for EF<sub>1</sub> (without 20 mM DTT in step vi), but replacing buffer B with buffer C.

For oxidation of both EFOF<sub>1</sub> and EF<sub>1</sub>, 50  $\mu$ l of OSS, 0.2 mg/ml creatine kinase, 2.5 mM creatine phosphate, 1–2 mM Ellman's reagent, and 5 mM ATP in buffer C or buffer B were added after washing with 50  $\mu$ l of buffer C or buffer B, respectively. For reducing of EF<sub>1</sub> after oxidation, 50  $\mu$ l of OSS, 0.5% 2-me, 20 mM DTT, 10 mM Na<sub>2</sub>S<sub>2</sub>O<sub>4</sub>, and 5 mM ATP in buffer B were added after washing with 50  $\mu$ l of buffer B.

**Video Microscopy.** EF<sub>1</sub> and EFOF<sub>1</sub> constructs were observed, and single-molecule rotation was recorded with an inverted fluorescence microscope as published (16). Fast bleaching of the fluorescently labeled actin filaments in the oxidized state was overcome by reducing the excitation intensity. Video data were captured with a Pinnacle DV500 Plus video card, and digitized with Adobe Premiere 6.0. A software program for evaluation of the obtained video sequences was written with Matlab 7.

**Homology Modeling.** Our model of EFOF<sub>1</sub> was based on the structure as determined by Abrahams *et al.* [PDB ID Code 1bmf, (6)]. Modeling was carried out with the programs Whatif (44) and O (45). The model coordinates are available from [www.biologie.uni-osnabrueck.de/Biophysik/Engelbrecht/se/data/ef1/](http://www.biologie.uni-osnabrueck.de/Biophysik/Engelbrecht/se/data/ef1/).

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