

Elimination of Thermodynamically Infeasible Loops in Steady-State Metabolic Models

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ABSTRACT The constraint-based reconstruction and analysis (COBRA) framework has been widely used to study steady-state flux solutions in genome-scale metabolic networks. One shortcoming of current COBRA methods is the possible violation of the loop law in the computed steady-state flux solutions. The loop law is analogous to Kirchhoff's second law for electric circuits, and states that at steady state there can be no net flux around a closed network cycle. Although the consequences of the loop law have been known for years, it has been computationally difficult to work with. Therefore, the resulting loop-law constraints have been overlooked. Here, we present a general mixed integer programming approach called loopless COBRA (ll-COBRA), which can be used to eliminate all steady-state flux solutions that are incompatible with the loop law. We apply this approach to improve flux predictions on three common COBRA methods: flux balance analysis, flux variability analysis, and Monte Carlo sampling of the flux space. Moreover, we demonstrate that the imposition of loop-law constraints with ll-COBRA improves the consistency of simulation results with experimental data. This method provides an additional constraint for many COBRA methods, enabling the acquisition of more realistic simulation results.

INTRODUCTION

A primary aim of researchers in the field of systems biology is to understand the properties of large-scale biochemical networks through the construction and use of predictive *in silico* models. One common approach is the constraint-based reconstruction and analysis (COBRA) framework (1–4). Genome-scale metabolic models are built in a bottom-up fashion from various sources of biological knowledge, such as genome annotations, metabolic databases, and published biochemical information (5–7). This quality-controlled reconstruction process results in validated mathematical models that can make predictions about reaction fluxes inside a cell. These predictions have a wide variety of applications (8–10). Because these models are generally underdetermined, steady-state flux solutions are calculated by imposing constraints on the system and optimizing an objective function (2,11–13). Popular constraints include the steady-state assumption, reaction reversibility, and bounds on reaction capacity. The various methods developed under this framework have been described elsewhere (2,4–6,14).

COBRA models are defined primarily by their stoichiometric matrix (S) and reaction lower (lb) and upper (ub) bounds. The stoichiometric matrix encodes information about reactions (columns) and metabolites (rows), such that each entry, $S_{i,j}$, is the signed stoichiometric coefficient of metabolite i in reaction j . The stoichiometric matrix relates the reaction flux (v) to the change in metabolite concentrations (x):

$$\frac{dx}{dt} = S \cdot v.$$

At steady state, it is assumed that concentrations do not change. Thus, the equation reduces to $S \cdot v = 0$. Upper and lower bounds can be placed on each reaction flux. Many reactions are considered irreversible ($v_i > 0$), whereas others, such as uptake and secretion reactions, can be set to experimentally measured values ($v_i = v_{exp}$). If no information is available, arbitrarily large bounds are set (e.g., $-10,000 < v_i < 10,000$). Together, the flux bounds and the steady-state equation define a bounded space of possible flux states.

The constraint-based method known as flux balance analysis (FBA) is commonly used to compute the likely state of the network by optimizing a metabolic objective (15,16). Common objectives include biomass production (12), ATP production (17), and biomass production per unit input (13).

Many COBRA methods, including FBA, ignore the imposition of the loop law (18). The loop law is analogous to Kirchhoff's second law for electrical circuits, in that it states that the thermodynamic driving forces around a metabolic loop must add up to zero. As such, there cannot be a net flux around a closed cycle in a network at steady state. Methods for detecting loops have been developed (19); however, these methods are too computationally intensive and not flexible enough to be included within optimization computations (20).

An alternative approach for addressing the loop law is to include additional thermodynamic information. Such an approach relies on the relation $\Delta G_r = \Delta G^0 + RT \ln Q$, where Q is a ratio of metabolic concentrations and ΔG_r is the Gibbs energy of a reaction. ΔG_r directly relates to the sign of the flux through the associated reaction (i.e., if $\Delta G_r > 0$, then $v_{net} < 0$ and vice versa). This imposes additional constraints on reaction directionality, as well as on feasible concentrations. This approach has been used to

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compute potential regulatory sites (21), determine reaction directionality (22), and compute feasible concentration ranges (23). A slightly different formalism with decoupled forward and reverse reactions has been used to modify FBA (24,25). All of these methods require a priori knowledge of the standard free-energy change of reactions (ΔG_r) or the standard energies of formation (ΔG_f°) of all metabolites in the network. These values can be found in databases (e.g., the NIST Chemical Kinetics Database (26)) or estimated computationally with methods such as group contribution theory (27,28). However, the lack of accuracy and coverage in some cases can pose challenges.

Here, we present a simpler method to incorporate the loop-law constraints into many current COBRA methods. This method does not require additional inputs or data (e.g., metabolite concentrations and ΔG_f°), and turns any linear programming (LP), quadratic programming (QP), or mixed integer problem (MIP) into a modified MIP problem. The solution to the modified MIP problem solves the initial problem, with an additional constraint. This constraint does not allow the inclusion of network fluxes that contain loops. We demonstrate this technique on three popular COBRA methods: FBA, flux variability analysis (FVA), and Monte Carlo sampling, thereby producing loopless versions of each method (II-FBA, II-FVA, and II-sampling, respectively). Given the extensive application of COBRA methods, this simple method for imposing the loop-law constraint will likely find widespread use.

MATERIALS AND METHODS

The loopless condition

First, consider the simpler problem of determining whether a given flux solution, v , contains a loop. For v to satisfy the loop law, the reaction energies around any cycle must add to zero. This condition can be written concisely as $v^T \times G = 0$, where G is a vector of energies for each reaction. Extreme pathway (29) and elementary mode analysis (30) can be used to identify all cycles. However, these methods have shown that the number of loops (type III pathways) grows rapidly with the network size, and that enumerating all loops is not possible for medium- to large-scale networks (31). Fortunately, it is not necessary to enumerate all loops. As shown in Fig. 1, all loops lie within the internal network, S_{int} . Any steady-state pathway in S_{int} is a loop, and all such paths can be expressed as a linear combination of the null basis of S_{int} (3). All loops can be expressed in the form $v = N_{int} \times \alpha_i$, where $N_{int} = \text{null}(S_{int})$, and α_i are weights. If it can be shown that if $N_{int}^T \times G = 0$, then $v^T \times G = 0$ for all loops v .

The loopless condition forms an LP problem. A vector of continuous variables (G_i) indicates the driving force of each reaction. This quantity can be thought of as being analogous to the ΔG_r of each reaction, in that $\text{sign}(G) = \text{sign}(\Delta G_r)$, although numerically they may be quite different. A loop is purely defined by the sign (direction) of the flux distribution (19). Therefore, if $N_{int} \times G_i = 0$, no loop is present.

To verify that a flux distribution does not contain loops, a solution to $N_{int} \times G = 0$ is found with the following constraints:

$$G_i < 0 \text{ for all } v_i > 0$$

$$G_i > 0 \text{ for all } v_i < 0$$

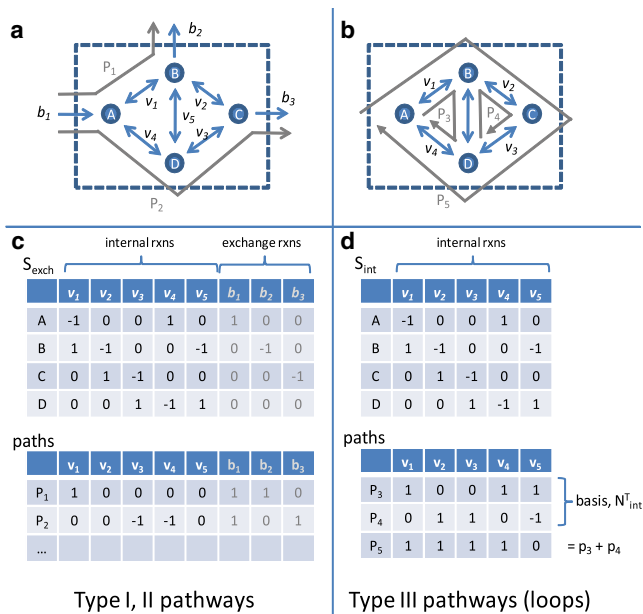


FIGURE 1 Loops in metabolic networks. (a and c) A small network illustrates pathways with and without loops, in which the network contains five internal reactions and three exchanges. (b and d) The internal part of the network. Steady-state pathways are superimposed (P_1 - P_5). EPA (29) indicates that Type I and II pathways use exchange reactions. A partial subset of these pathways is listed in c. Type III pathways do not contain exchange reactions and form a set of loops. In this example there are three type III pathways (d). P_3 and P_4 form the basis of the internal null space (N_{int}), and P_5 can be written as a linear combination of the other two type III pathways.

$$G_i \in R \text{ for all } v_i = 0$$

$$N_{int} G = 0.$$

In practice, it is necessary to restrict G_i to be strictly positive or strictly negative to avoid the degenerate solution $G_i = 0$ for all i . This requirement is another reason why G_i may not be interpreted directly as ΔG_r -values. The following correction restricts G_i to $[-1000, -1]$ or $[1, 1000]$, and G_i may never be exactly zero:

$$-1000 < G_i < -1 \text{ for all } v_i > 0$$

$$1 < G_i < 1000 \text{ for all } v_i < 0$$

$$G_i \in R \text{ for all } v_i = 0$$

$$N_{int} G = 0.$$

If a solution exists, then v contains no loops. Otherwise, v contains a loop. Unlike most LP problems, the objective ($\max c^T \times G$) is of no concern because only the feasibility is relevant.

Adding the loop-law constraints to COBRA problems: II-FBA

The linear loop-law constraints described above can be added to almost any COBRA LP, mixed integer linear programming (MILP), QP, or mixed integer quadratic programming (MIQP) problem, as long as this problem contains a variable, v_i , for each of the internal fluxes in the model. The

only necessary addition is the condition that ensures $\text{sign}(v) = -\text{sign}(G)$. This is achieved by adding a binary indicator variable (a_i) for each internal reaction.

The full set of constraints can be expressed as follows:

$$a_i = \begin{cases} 1 & \text{if } v_i > 0 \\ 0 & \text{if } v_i < 0 \end{cases}$$

$$G_i > 0 \text{ if } a_i < 0$$

$$G_i < 0 \text{ if } a_i > 0$$

$$N_{\text{int}}G = 0.$$

This is converted to the following MILP problem:

$$-1000a_i + 1(1 - a_i) \leq G_i \leq -1a_i + 1000(1 - a_i)$$

$$-1000(1 - a_i) \leq v_i \leq 1000a_i$$

$$N_{\text{int}}G = 0$$

$$a_i \in \{0, 1\}$$

$$G_i \in R.$$

As before, to avoid degenerate solutions, G_i is not allowed to be zero.

These constraints may be added to almost any LP COBRA method. For example, the full formulation for loopless FBA (ll-FBA) is as follows:

$$\max c_j v_j$$

subject to

$$\sum_k S_{kj} v_k = 0$$

$$lb_j \leq v_j \leq ub_j$$

$$-1000(1 - a_i) \leq v_i \leq 1000a_i$$

$$-1000a_i + 1(1 - a_i) \leq G_i \leq -1a_i + 1000(1 - a_i)$$

$$N_{\text{int}}G = 0$$

$$a_i \in \{0, 1\}$$

$$G_i \in R$$

$$i \in \text{internal},$$

where S_{kj} is the stoichiometric matrix; j iterates over all reactions; i iterates over internal reactions; lb_j and ub_j are the lower and upper bounds, respectively, for each reaction; and c_j are the coefficients of optimization. See the [Supporting Material](#) for additional performance enhancements that can be added to speed up the computation.

Models

Several COBRA models were used to validate the ll-COBRA methods. All models (except the toy network) have been published elsewhere (see Table 1). Models were exported from the BiGG knowledgebase (32) as

TABLE 1 Five models of increasing size used in this work

Network	Reactions	Metabolites	Genes	Citation
Toy network	5	3	—	—
Core <i>E. coli</i>	95	72	137	(49)
<i>H. pylori</i> iIT341	554	485	339	(50)
<i>S. aureus</i> iSB619	743	655	619	(51)
<i>E. coli</i> iAF1260	2382	1668	1261	(52)
Human Recon 1	3742	2776	1905	(53)

SBML files and subsequently imported in the COBRA toolbox, using default parameters. Only the *Staphylococcus aureus* model was modified. This model contains several potential biomass objective functions, so only the default objective, biomass_SA_8a, was retained. In addition, this model had unrealistic uptake rates of carbon substrates, so these rates were reduced to 10 mmol glucose gDW⁻¹ h⁻¹ (similar to uptake rates in other prokaryotic models). These changes do not affect the occurrence of loops, but aided in the comparison of loop fluxes before and after the imposition of loop law constraints.

Loopless FVA

Loopless FVA (ll-FVA) was performed with the use of the ll-FBA method described above, followed by the sequential maximization and minimization of each reaction in the model. This computation was performed both with and without the loop-law constraints. Reactions in which the range (max v_i - min v_i) differed by $>10^{-6}$ mmol gDW⁻¹ h⁻¹ between FVA and ll-FVA were classified as loop reactions, affected by the loop-law constraints.

Sampling of the steady-state solution space

Monte Carlo sampling was used to generate a set of flux distributions that uniformly sample the space of all feasible fluxes (possibly including loops). The method is based on the artificially centered hit and run algorithm with slight modifications (33,34). Initially, a set of 2000 nonuniform pseudo-random points, called warm-up points, was generated. In a series of iterations, we randomly moved each point while keeping it within the feasible flux space. We accomplished this by 1), choosing a random direction; 2), computing the limits on how far a point could travel in that direction (positive or negative); and 3), choosing a new point randomly along that line. After numerous iterations, the set of points was mixed and approached a uniform sample of the solution space. We used a mixed fraction, as described previously (34), to determine when the solution space was uniformly sampled. For this work, 2000 points were generated and mixed for 1 h, at which time the space was determined to be uniformly sampled with a mixed fraction of 0.495.

Removing loops: ll sampling

Sampling the loopless solution space can be implemented as a postprocessing step in Monte Carlo sampling. Once a set of flux distributions has been generated, the loops can be removed. To do this, we find a loopless flux, w_i , that is nearest to a given flux distribution, v_i :

$$\min_w |w_j - v_j|$$

subject to:

$$\sum_k S_{kj} w_k = 0$$

$$lb_j \leq w_j \leq ub_j$$

$$-1000(1 - a_i) \leq w_i \leq 1000a_i$$

$$-1000a_i + 1(1 - a_i) \leq G_i \leq -1a_i + 1000(1 - a_i)$$

$$N_{\text{int}}G = 0$$

$$a_i \in \{0, 1\}$$

$$G_i \in \mathbb{R},$$

where $|w_i - v_i|$ is the distance to be minimized. If the Euclidian norm (2-norm) is used as the distance metric, this becomes an MIQP problem in which $(w_j - v_j)^2$ is minimized. The Manhattan norm (1-norm) may be implemented as an MILP problem by introducing a helper variable v_j^+ , such that $|v - w| = v^+$.

$$\min \sum v_j^+$$

subject to:

$$v_j^+ \geq v_j - w_j$$

$$v_j^+ \geq -(v_j - w_j)$$

$$\sum_k S_{kj} v_k = 0$$

$$lb_j \leq v_j \leq ub_j$$

$$-1000(1 - a_i) \leq v_i \leq 1000a_i$$

$$-1000a_i + 1(1 - a_i) \leq G_i \leq -1a_i + 1000(1 - a_i)$$

$$N_{\text{int}}G = 0$$

$$a_i \in \{0, 1\}$$

$$G_i \in \mathbb{R}$$

$$v_j^+ > 0.$$

Computer configuration and availability

Computations were performed in the MATLAB (The MathWorks, Natick, MA) version 2009b environment with the COBRA toolbox (35) and SBML toolbox version 3.0 (36). Linear and mixed integer linear programming were performed with the TOMLAB/CPLEX package version 7.4 (Tomlab Research, Pullman, WA). All computations were run on a Dell Studio XPS workstation (core i7 920 processor, 12GB ram, Windows 2003 R2, 64 bit). The MATLAB parallel toolbox was used for both the ll-FVA and ll-sampling applications to take advantage of its multicore architecture.

The methods presented here can be added to any implementation of FBA or similar methods. However, to facilitate their use, the code used for the computations in this publication are available in the COBRA toolbox 2.0 (35), in which the optimizeCbModel (FBA) and fluxVariability functions have an optional flag to exclude loops. Monte Carlo sampling is called through the nearest loopless flux function, which returns the nearest loopless flux distribution using the MILP or MIQP methods. Internally, these three methods call an addLoopLawConstraints function, which adds

loop-law constraints to any COBRA LP, MILP, QP, or MIQP problem and turns it into an ll-COBRA problem.

Microarray analysis

Previously published (37) Affymetrix *E. coli* antisense genome arrays were obtained and subjected to GC robust multiarray average (gcrma) normalization using the bioconductor package in R. This data set includes 213 expression profiles, representing ~70 variations in experimental conditions and genetic perturbation of *E. coli* K-12 MG1655. We used these data to assess loop flux before and after imposition of the loop-law constraints, and to compare these fluxes with gene expression levels. To that end, we first identified the genes associated with loop and nonloop reactions. We then selected 2500 random pairs, containing one loop- and one nonloop-associated gene, and computed the ratios between the expression levels for each pair. In like manner, we randomly selected pairs of loop and nonloop reactions, and computed the ratios of the maximum fluxes through these reactions before and after adding the loop law constraints.

RESULTS

FBA with a toy network

A toy network is used to illustrate FBA in Fig. 2, *a* and *b*. The S matrix defines the topology of this network mathematically. Upper and lower bounds are imposed on the reaction rates. In this case, the internal reactions (v_1 , v_2 , and v_3) are reversible and bounded in the range $[-10, 10]$. Metabolites A and C can be exchanged with the environment at lower rates $[0, 1]$. This setup is commonly used because uptake and secretion rates may be constrained to

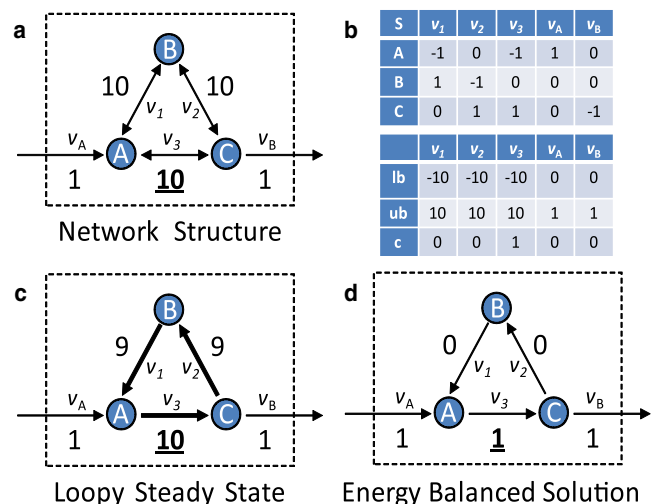


FIGURE 2 Toy network with loops. A five-reaction toy network is used to illustrate the effects of the loop law. (a) The structure of the network and the reaction bounds are represented graphically. Reactions v_1 , v_2 , and v_3 form a loop. (b) The stoichiometric matrix, lower bounds and upper bounds (S, lb, and ub, respectively) mathematically describe the network. The objective coefficient, c, indicates which reaction should be maximized (in this case, reaction v_3). (c) Classical FBA returns a solution that contains a loop and an objective value of 10. (d) By eliminating the loop, we obtain a lower, thermodynamically consistent objective of 1 unit of flux, with flux passing through reaction v_3 and not around the center loop.

experimentally measured values, whereas internal reaction bounds are often unknown. Maximizing reaction v_3 by conventional FBA yields the flux distribution shown in Fig. 2 c. This solution is not unique. However, all of the solutions have a flux of 10 through v_3 and at least 9 units through reactions v_1 , v_2 , and v_3 forming a loop around $A \rightarrow B \rightarrow C \rightarrow A$. This scenario violates the second law of thermodynamics because there can be no chemical driving force for all three reactions at the same time. However, the II-FBA solution that maximizes flux through v_3 effectively removes the loop by allowing only 1 unit of flux through v_3 while deactivating v_2 and v_1 (Fig. 2 d).

FVA

The above analysis provides a simple example of how the loop-law constraints eliminate thermodynamically infeasible loops from FBA simulations. Of importance, imposing loop-law constraints has a similar effect on genome-scale metabolic networks. FVA is a common technique for evaluating the scope of metabolic states a network can achieve (Fig. 3 a). In FVA, each reaction is sequentially minimized and maximized, thereby providing the range of feasible steady-state fluxes for each reaction. Here, six models of increasing size were tested with FVA (Table 1). The scale of these models ranges from the toy network (five reactions) to the human metabolic network (3742 reactions). The results of the six networks are shown in Table 2. Although each network has a different number of loop reactions, the fraction of reactions that participate in the loops is roughly 0.4–4% (except for the toy model).

Flux through loops in constraint-based models is limited only by the reaction directionality and the arbitrary upper limits in flux imposed by the user. Thus, the predicted maximum flux values through loop reactions are expected to be significantly higher than fluxes through nonloop reactions. If the loopless methods effectively remove loops, then the maximum flux values for loop reactions should be comparable to nonloop reactions. To demonstrate this, we used II-FVA to compute the range of feasible flux values for all reactions. Using II-FVA on the *E. coli* iAF1260 model, all loop reaction flux ranges decrease, and most decrease to levels within the range of nonloop reactions (Fig. 3 b). This reduction of all loop reaction flux spans occurs in the other models tested here (see Table 2 and Fig. S1). In addition, the larger models exhibit cases in which a few reactions are completely deactivated, suggesting that these reactions can only carry a flux in the growth conditions tested here if they participate in a loop. Thus, II-FVA reduces the flux span for all loop reactions and provides flux ranges that are more consistent with the ranges seen in nonloop reactions.

II-FVA and expression levels of loop reactions

Although II-FVA effectively reduces the range of feasible flux values for all loop reactions, it remains to be shown that this is consistent with biological reality. Previous studies reported a moderate correlation between model-predicted flux and gene expression levels (13,38,39). However, when comparisons are made between flux and gene expression, loop reactions are regularly removed from the

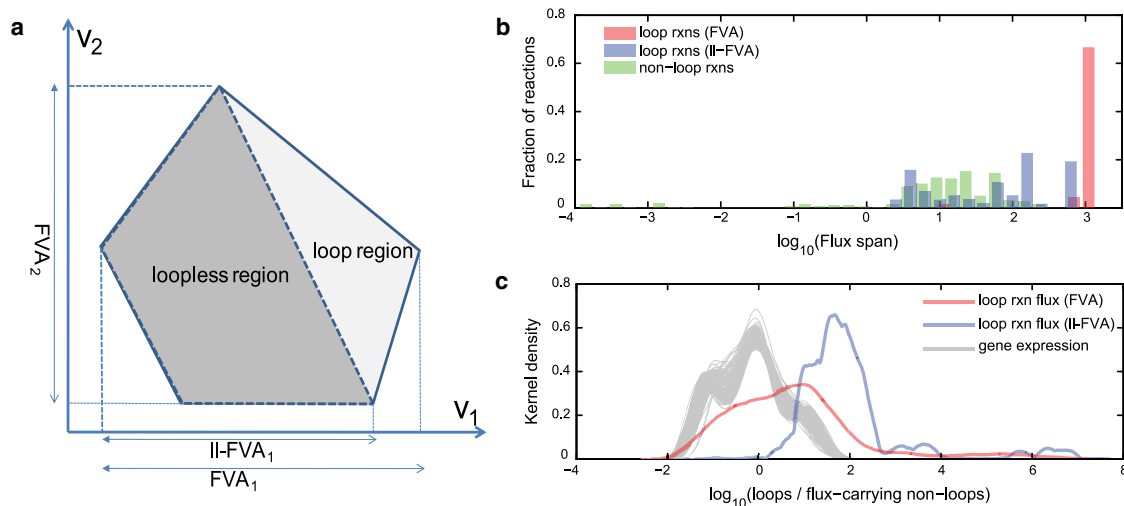


FIGURE 3 FVA computes the range of each reaction in a network. (a) An example of the loop and loopless regions in the flux solution space shows that removing loops (II-FVA) reduces the range of reaction 1 but not that of reaction 2. In all cases, II-FVA is as or more constraining than classical FVA. (b) After the use of II-FVA on the iAF1260 model of *E. coli* metabolism, the flux spans for most loop reactions are comparable to the ranges of nonloop reactions. (c) The use of II-FVA on the iAF1260 model also brings the ratio of loop to nonloop reaction flux to a level that is more consistent with the loop to nonloop gene expression ratios, as determined from 213 different microarray experiments (each gray line represents gene expression level ratios from one microarray). Thus, II-FVA reduces the range of feasible reaction flux to values that are more consistent with nonloop flux and gene expression.

TABLE 2 Comparison of FVA and II-FVA, performed on models spanning a wide range of sizes

Model	Number of reactions	FVA time (s)	II-FVA time (s)	Time per iteration (s)	Number of changed reactions	% of model changed	Number of deactivated reactions	Changed reactions
Toy network	5	0.08	0.19	0.04	3	60.00%	0	v1 v2 v3
Core <i>E. coli</i>	95	1.1	7.35*	0.08	2	2.11%	0	FRD7 SUCDi
<i>H. pylori</i> iTT341	554	7.8	123	0.22	22	3.97%	6	4HGLSD ACKr AHSERL2 H2CO3D H2CO3D2 HCO3E HPROa HPROx HSERTA HSK METB1r NA13_1 PHCD PHCHGS PRO12r PRO4r PTAr SHSL1r SHSL2r SHSL4r THRD_L THRS
<i>S. aureus</i> iSB619	730	12.1	604	0.83	6	0.82%	1	FLDO FMNRx GLU12 GLU12r NADTRHD NA13
<i>E. coli</i> iAF1260	2382	58.8	18222**	7.6	68	2.85%	7	ABUT12pp AACT1r ACCOAL ACKr ACS ACT2rpp ACT4pp ADK1 ADK3 ADN12pp ADN12rpp ALATA_L CA213pp Cat6pp CRND12rpp CRN12rpp CRN18pp CYTD12pp CYTD12rpp GLBRAN2 GLCP GLCP2 GLCS1 GLCtex GLCtexi GLDBRAN2 GLGC GLUABUT17pp GLU12rpp GLU14pp GLYCLT12rpp GLYCLT14pp HPYRI HPYRRx ICHORS ICHORSi INDOLE12pp INDOLE12rpp INST12pp INST12rpp KAT1 NA13pp NDPK1 PPAKr PPCSCT PPKr PPM PRO12rpp PRO14pp PRPPS PTA2 PTAr R15BPK R1PK SER12rpp SER14pp SUCOAS THMD12pp THMD12rpp THR12rpp THR14pp TRSARr URAT12pp URAT12rpp UR112pp UR12rpp VALTA VPAMT
Human Recon 1	3742	199.95	111163	29.7	34	0.91%	10	10FTHFtm 25HVITD1t 25HVITD2tm 4HGLSDm ACCOAtn ACHtn CHAT CHATn CHOLtn COAtn CYTK1n CYTK2n DCK1n DCK2n GALT H2CO3D2m H2CO3Dm HCO3Em NADH1pu NAD1pu NDPK1n NDPK2n NDPK3n NDPK5n NDPK7n NDPK8n NNATr P5CRx PHCDm PHCHGSm PPDOx UMPKn VITD3t VITD3tm

*Standard deviation of 0.3 s across four different growth conditions and two different objective functions.

**Standard deviation of 6358 s across four different growth conditions and two different objective functions.

analysis. Thus, if II-FVA effectively improves the prediction of loop-reaction fluxes, one would expect the loop reaction fluxes to be more consistent with the gene expression levels. Here, we tested this by comparing the ratios between loop and nonloop reaction fluxes with the ratios between gene expression levels for loop and nonloop genes. First, we removed all reactions that could not carry flux in the given growth conditions from the *E. coli* iAF1260 model. Second, we selected 2500 randomly chosen pairs of gene-associated loop and nonloop reactions, and used FVA to compute the maximum flux for the reactions. The ratio of loop reaction flux to nonloop flux was subsequently computed. Third, we identified genes associated with loop and nonloop reactions. We then selected 2500 random pairs of loop and nonloop genes, and computed the ratios of their expression values using 213 different microarrays (37).

The ratios of loop reaction fluxes to nonloop fluxes are beyond the ranges of the loop to nonloop gene expression ratios computed from the expression data. However, when we repeated this process using II-FVA, we found that the loop/nonloop ratios were more similar to the distribution of loop/nonloop gene expression ratios (Fig. 3 c). Thus,

for most reactions, II-FVA effectively reduces the range of feasible flux values to ranges that are more consistent with gene expression differences between sets of loop- and nonloop-associated genes.

Performance considerations

II-FVA reduces flux spans of loop reactions to levels that are more consistent with nonloop reactions and with real gene expression levels. However, II-FVA is more computationally intensive than FVA. MILP is known to be NP complete, and the running time is highly problem- and solver-specific. Average running times for the Tomlab/CPLEX solver are shown in Table 2. For a medium-sized problem such as the *H. pylori* model, the addition of the loop-law constraints increases the computation time by a factor of 12. A different solver, GLPK, was unable to solve this problem after several hours. Thus, the solver choice and network size significantly affect the running time of II-FVA. However, variations in model growth media and objective function choice only have a small effect on running time and thus do not

significantly affect the feasibility of II-FVA calculations (see Table 2 and Supporting Material).

Monte Carlo sampling of networks

Monte Carlo sampling of the steady-state solution space allows one to study the set of feasible flux distributions that a network is capable of supporting. For this study, we chose the *H. pylori* iIT431 model, and sampled the model using a modified ACHR method. We then postprocessed the 2000 uniformly sampled points to remove the loops using either the MILP or MIQP method as shown in Fig. 4 a (see Materials and Methods). All 2000 points contain loop fluxes (Fig. 4 b). The MILP and MIQP methods show different properties in removing looping reactions. On average, the MILP method altered 22.6 reactions in the flux distribution, which is very close to the number of reactions with altered FVA range (22 reactions). The MIQP method on average shifted 252.6 reactions by 0.01 units or more. This difference results because the MIQP method is able to find nearer loopless flux distributions by adding small modifications to nonloop reactions. However, these modifications are orders of magnitude smaller than the changes in the loop reaction fluxes (Fig. S2). Thus, for both methods, loop reactions are primarily changed.

These samples allow visualization of the solution space within which the cell operates. By plotting the samples on a histogram, one can obtain the projection across the solution space for any reaction. This projection shows the distribution of feasible flux values for each reaction, given the model topology and constraints. The projections of three reactions are shown in Fig. 4 c. The MILP loop removal does not shift points for nonloop reactions, such as ACONT. However, when loops are removed by MIQP, small modifications are introduced in these nonloop reactions because the modifications lead to slightly closer loopless flux distributions. However, for loop reactions, both methods shift the bulk of points toward fluxes of lower magnitude (e.g., ACKr and THRS).

Performance considerations

Removing loops in the iIT431 model with 554 reactions requires ~4.5 s of postprocessing per point using the MILP method. The MIQP method requires ~16.9 s. It is possible to sample larger networks. The iJR904 *E. coli* model with 1075 reactions is the largest successfully sampled model (results not shown). However, the larger *E. coli* model, iAF1260, and the human reconstruction could not be sampled as described in the Materials and Methods

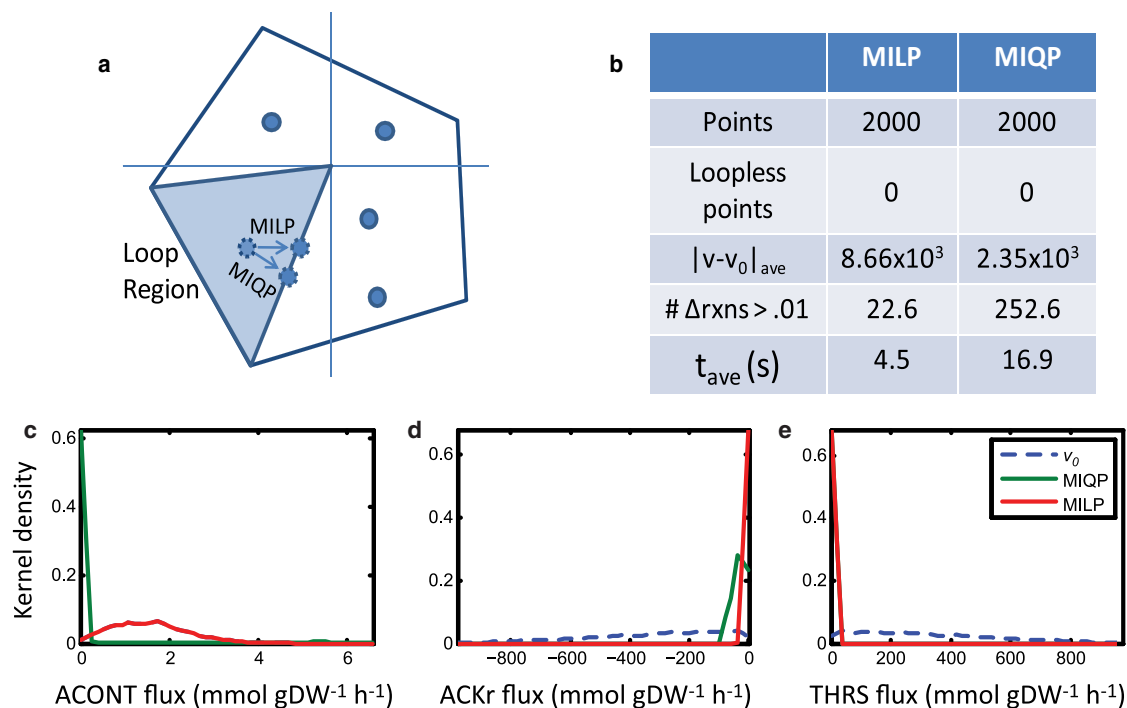


FIGURE 4 Monte Carlo sampling. A random Monte Carlo sample of 2000 points was generated for the *H. pylori* model (50). (a) Points are initially sampled from the complete steady-state solution space. Points within the infeasible region (shaded) are moved to the nearest feasible loopless point using either a Euclidian distance (MIQP) or a Manhattan distance (MILP). (b) Differences between the two samples are quantified, including the average distance moved ($|v-v_0|$) and the average number of reactions that change their flux values as the point is corrected ($\#\Delta rxns > 0.01$). (c) Histograms show the distributions of sample flux values for three reactions (ACONT, ACKr, and THRS) of initial points (v_0), and MILP/MIQP loopless points.

section, due to scaling issues. The MILP/MIQP solver was not able to find the nearest solution in a reasonable time.

DISCUSSION

We have presented an enhancement of COBRA methods that incorporates the constraints associated with the loop law by disallowing steady-state flux solutions containing closed loops. We applied this method to FBA, FVA, and Monte Carlo sampling to demonstrate how it refines the solutions to various COBRA methods. In these cases, we showed that the traditional method, which allows loops, predicted flux distributions that are known to be infeasible, whereas ll-COBRA provided better solutions. The success of ll-COBRA in this respect has three broader implications for the modeling community, as discussed below.

First, our results demonstrate that for certain applications, detailed quantitative parameterization of thermodynamic constants can be bypassed through the use of more global governing constraints. The COBRA framework has developed rapidly in part because the associated models do not demand the rigorous parameterization required by kinetic models. Thus, many COBRA methods can be used even on large FBA models, since model predictions are subject to more global physicochemical constraints such as mass balance and the delineation of possible chemical transformations in the cell. The successes and, in part, the limitations of these models have motivated the development of hybrid methods that integrate additional elements of thermodynamics with the FBA approach. The different modeling approaches that can be used to address thermodynamics are summarized in Table 3.

Many methods that incorporate thermodynamics rely on a priori knowledge of the ΔG_f for the metabolites in the model (21,23). These quantities can be obtained from the literature or estimated computationally (27). In theory, only these parameters and metabolite concentrations are needed to compute the reaction directionality. An advantage of this formalism is that no flux distributions with loops are allowed. However, these methods are hindered by the requirement for accurate ΔG_f -values. When these values are not available, many of the thermodynamic constraints can no longer be evaluated. Moreover, as shown in Table 3,

these methods significantly vary in their descriptive power, computational difficulty, and number of required parameters.

The loop-law method proposed here incorporates thermodynamic constraints while also addressing concerns about computational difficulty and missing thermodynamic constants. Its primary advantage over classical FBA is that it excludes loop-containing fluxes without requiring additional parameters. The additional constraints come free as a direct consequence of imposing the second law of thermodynamics on the model. It also has an advantage over other hybrid approaches in that it reduces the need for rigorous parameterization by including a ΔG_f for each metabolite. Also, as an MIP, it is computationally more tractable. Thus, detailed parameterization can be minimized and the models can be more easily and rapidly scaled up.

Second, this approach affects model construction. The ll-COBRA formulation provides an alternative to the laborious and potentially incorrect manual removal of loops in the reconstruction process. The process of reconstructing COBRA models has been described in detail elsewhere (5–7). When reconstructing a metabolic network, one must manually evaluate each reaction and assess the reaction directionality. An important step in network reconstruction is to verify that the model produces accurate results when optimizing for physiological functions such as ATP or biomass production. Unfortunately, if the models are not adequately constrained, unbounded internal reaction rates can result from loops. To remedy these unrealistic and problematic loops, one can change the directionality of a reaction, thereby eliminating the loop. Although this approach solves the problem of unbounded solutions, it may inadvertently introduce an artificial constraint on the system. For example, studies have indicated (40,41) that most reactions in the *iJR904* model of *E. coli* metabolism (42) are estimated to be near equilibrium. Thus, in this model, few reactions witness additional constraints from ll-FVA, because *iJR904* has been constructed to avoid loops. This is only a concern because all reactions are inherently reversible, and marking them as irreversible may restrict the accuracy of the model under extreme conditions. Therefore, the use of ll-COBRA instead of classical COBRA methods may lead to better models in the future because it

TABLE 3 Assumptions, required parameters, and computational complexity of different metabolic modeling formalisms

Formalism	FBA	ll-FBA	FBA + thermodynamics	Kinetics
Assumptions and constraints	Steady state, well mixed	Steady state, well mixed, loop law	Steady state, well mixed, $\Delta G = \Delta G^0 + RT \ln(Q)$	Well mixed, mass action**
Parameters	Enzyme capacities, uptake rates	Enzyme capacities, uptake rates	Enzyme capacities, uptake rates, metabolite concentrations, ΔG^0	Kinetic parameters, metabolite concentrations, initial conditions, mechanisms**
Computation type	Linear	Mixed integer	Nonlinear	Nonlinear
Computational difficulty	Easy	Medium	Hard*	Hard
Example studies	(16)	This study	(21–23)	

*Depends on the implementation (can be MILP, convex optimization, or generalized NLP).

**One has to either assume mass action kinetics or know the mechanism of reaction.

will not be necessary to add many of these artificial reversibility constraints to the models. Condition-specific loop elimination can instead be done with II-COBRA.

Third, the II-COBRA formulism is broadly applicable to COBRA methods. In this study we have provided examples of how the loop-law constraints can be added, and how the loop law affects COBRA solutions. Many other COBRA methods may benefit from this addition. The only requirements are that 1), the method must involve an LP, MILP, or QP problem; and 2), the method must include a variable for each internal reaction. Example candidate methods include minimization of metabolic adjustment (43), regulatory on/off minimization (44), gene deletion analysis (45), regulatory FBA (46), flux coupling analysis (47), Parsimonious enzyme usage FBA (38), and geometric FBA (48). By integrating the loop law constraints with these established methods, loop reactions can be corrected. Thus, beyond the five genome-scale models used in this study (49–53), additional insight may be obtained from additional metabolic models of prokaryotic function (8,9,54), host-pathogen responses (34), off-target drug effects (55), and multicellular tissues (56), using a host of additional COBRA methods.

CONCLUSIONS

Solutions to the classical FBA problem formulation regularly violate thermodynamic constraints. Although other thermodynamic methods can provide more insight into network functions than the II-COBRA methods, the II-COBRA method presented here successfully removes thermodynamically infeasible loops, is more scalable, and does not require additional parameters for implementation in a COBRA model. The code used to implement the II-COBRA methods here is freely available in COBRA toolbox 2.0 (35).

SUPPORTING MATERIAL

Descriptions of additional performance enhancements for the methods in this work, additional analysis, and Figs. S1 and S2 are available at [http://www.biophysj.org/biophysj/supplemental/S0006-3495\(10\)05225-2](http://www.biophysj.org/biophysj/supplemental/S0006-3495(10)05225-2).

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