

On the analysis of protein–protein interactions via knowledge-based potentials for the prediction of protein–protein docking

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Abstract: Development of effective methods to screen binary interactions obtained by rigid-body protein–protein docking is key for structure prediction of complexes and for elucidating physicochemical principles of protein–protein binding. We have derived empirical knowledge-based potential functions for selecting rigid-body docking poses. These potentials include the energetic component that provides the residues with a particular secondary structure and surface accessibility. These scoring functions have been tested on a state-of-art benchmark dataset and on a decoy dataset of permanent interactions. Our results were compared with a residue-pair potential scoring function (RPScore) and an atomic-detailed scoring function (Zrank). We have combined knowledge-based potentials to score protein–protein poses of decoys of complexes classified either as transient or as permanent protein–protein interactions. Being defined from residue-pair statistical potentials and not requiring of an atomic level description, our method surpassed Zrank for scoring rigid-docking decoys where the unbound partners of an interaction have to endure conformational changes upon binding. However, when only moderate conformational changes are required (in rigid docking) or when the right conformational changes are ensured (in flexible docking), Zrank is the most successful scoring function. Finally, our study suggests that the physicochemical properties necessary for the binding are allocated on the proteins previous to its binding and with independence of the partner. This information is encoded at the residue level and could be easily incorporated in the initial grid scoring for Fast Fourier Transform rigid-body docking methods.

Keywords: protein–protein docking; rigid-body docking; docking scoring; statistical potentials; knowledge-based potentials; protein–protein interactions; docking-components of statistical potentials; transient interactions; permanent interactions; binding-site prediction

Additional Supporting Information may be found in the online version of this article.

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Introduction

Understanding the mechanisms of control, response, and regulation of the cell implies a deep knowledge on the relationships between the biochemical components of a biological network. With further interest on human health, protein interaction networks are a useful tool for characterizing diseases caused by malfunctions in genes or proteins¹ and identifying novel cancer gene candidates with differential expression between the metastatic cells and their parental cells.^{2–5} Protein interaction maps can be used to infer the function of proteins,⁶ to calculate the number of binding sites of a protein,⁷ and to identify them on the protein surface.^{8,9} Knowledge of the precise structures of macromolecules could provide insights about quantitative parameters or help to elucidate functional networks. Recent efforts to gain knowledge on the structure of protein–protein complexes have been tackled at high-throughput level.^{10,11} Mosca *et al.*¹⁰ provided models for over 3000 protein–protein interactions in the yeast interactome and assessed the use of homology models for computational docking experiments too.

Computational docking methods aim to elucidate the structure of a binary interaction of biomolecules (e.g., two proteins) when experimental data regarding the structure of the complex are lacking but is present for the interacting partners. Docking methods were introduced in 1978.¹² Since then, docking algorithms have substantially improved, with a breakthrough in algorithm speed given by the introduction of the fast Fourier transform (FFT)^{13,14} (e.g., FTDock,¹⁵ ZDock,¹⁶ and PIPER¹⁷) and by some other very successful geometry-based methods (e.g., FRODOCK,¹⁸ Hex,¹⁹ and MolFit¹³).

The general procedure for predicting the 3D structure of a protein–protein interaction using docking consists of an initial rigid-body exhaustive search. In this step, one performs a screening of a very large set of possible binary complex conformations obtained by rotating and translating one of the proteins around the other and by not allowing atom mobility. Next, a refinement step follows on some selected structures,²⁰ which accounts for changes in the conformation of the two proteins. The final goal is to provide a near-native structure, that is, a structure close to the native one.

Typically, a rigid-body docking algorithm returns a long list of possible structures, which includes many false interactions. Hence, a crucial point after this initial step is the selection of a few structures that will be further analyzed. A common strategy is to re-rank the docking poses by means of a scoring function. The accurate scoring of rigid-body docking orientations represents one of the major difficulties in protein–protein docking prediction. Overall, good discrimination of near-native docking poses from the very early stages of rigid-

body protein docking is an essential step before applying more costly interface refinement to the correct docking solutions. Some advances in this direction include the use of desolvation to predict the binding site area (e.g., pyDock²¹), the use of Monte Carlo simulations,^{22,23} the use of low-frequency normal modes, and side chain flexibility,^{24,25} or the use of energy evaluation during or after the docking generation phase, like Haddock,²⁶ ClusPro/SmoothDock,^{27,28} RosettaDock,²⁹ or ATTRACT.³⁰

Scoring functions are usually built upon different properties of protein–protein interactions observed in known binary complexes. These properties include physical and chemical characteristics of the binding site, at the level of residue or atomic contacts. Among these scoring functions, *statistical potential* is a term that refers to a knowledge-based scoring function that depends on specific properties of known protein–protein interactions stored in some database. Their common structure is the sum over all interacting pairs of a score given to each pair of interacting residues or suitable atom types. This score is usually based on chemical, physical, or biological properties. They have been used, with different degree of success, as ranking scoring functions.^{16,17,31} Initially, statistical potentials were derived in order to distinguish a correct protein fold (i.e., near-native) of a model from a plethora of generated solutions. A vast amount of statistical potentials have been described and tested.³² Specific potentials were derived for the interaction between macromolecules in order to assess protein–protein interactions (e.g., M-TASSER,³³ MULTIPROSPECTOR,³⁴ and InterPrets³⁵) or DNA–protein interactions.^{36–38}

In a recent work, we provided a decomposition of knowledge-based potentials for protein folds into different energy terms that reflected different levels of detail of the residue–residue interactions.³⁹ This decomposition allowed for a better characterization of the structural features that contribute to the greatest extend of highly discriminative potentials. We derive and split here empirical potential functions³⁹ for protein–protein interactions. The purpose is, in the first place, to elucidate the properties of the standard residue–pair potential that account for its success in ranking docking poses, and, in the second place, to obtain a new ranking of poses that improves current near-native selection success rate. We are eager to uncover the most important features that characterize the native binding interface in comparison to the other *a priori* possible binding modes.

We have obtained four new statistical potentials, depicting the geometry of the interaction and the energetic component of placing some residues in a particular secondary structure and surface accessibility. Their success has been evaluated in two different databases (the benchmark dataset and a set of permanent interactions) and from different points

of view. We have considered in the first place their ability to select near-native poses, that is, structures differing from the native one at most 2.5 Å [computed in terms of interface root mean square deviation (I-RMSD)]. Second, we have analyzed the number of top-ranked false interactions (by means of ROC curves), and, finally, we have studied their capacity to top-rank the best pose available in the set.

Results

Split statistical potentials

The interaction between two residues can be statistically described by means of a potential of mean force.^{40,41} Given two interacting proteins, several statistical potentials are defined by considering potentials of mean force reflecting different characteristics of the residue–residue interaction. These statistical potentials are obtained by summing the potential of mean force PMF for each pair of interacting residues a , b of the two proteins A and B:

$$E = \sum_{a,b} PMF(a,b) \quad (1)$$

Let k_B denote the Boltzmann constant and let T be the standard temperature (300 K).

A residue *condition* is a triplet of the form

$$\theta = (\textit{Secondary structure}, \textit{polar character}, \textit{degree of exposure}).$$

In this text, we consider the following potentials of mean force:

$$PMF_{pair}(a,b) = -k_B T \log \left(\frac{P(a,b|d_{ab})}{P(a)P(b)P(d_{ab})} \right)$$

$$PMF_{local}(a,b) = k_B T \log \left(\frac{P(a|\theta_a)P(\theta_a)}{P(a)} \right) + k_B T \log \left(\frac{P(b|\theta_b)P(\theta_b)}{P(b)} \right)$$

$$PMF_{3D}(a,b) = k_B T \log(P(d_{ab}))$$

$$PMF_{3DC}(a,b) = k_B T \log \left(\frac{P(\theta_a, \theta_b|d_{ab})}{P(\theta_a, \theta_b)} \right)$$

$$PMF_{S3DC}(a,b) = -k_B T \log \left(\frac{P(a,b|d_{ab}, \theta_a, \theta_b)P(\theta_a, \theta_b)}{P(a,b|\theta_a, \theta_b)P(\theta_a, \theta_b|d_{ab})} \right)$$

(see the Supplementary Material for details). Here, d_{ab} is the distance between the residues a and b (defined as the minimum of the distances between all pairs of atoms of the residues) and θ_a is the condition of residue a . The terms $P(\cdot)$ denote the probabilities of observing interacting pairs with some given characteristics. For instance, $P(a,b|d_{ab})$ is the conditional probability that residues a , b interact at distance smaller than or equal to d_{ab} , and $P(d_{ab})$ is the probability of finding any pair of residues interacting at distance smaller than or equal to d_{ab} . The

other probabilities are defined similarly, and the details are given in the Supplementary Material. All probabilities $P(\cdot)$ are obtained from the relative frequencies in the selected database [3D interacting domains (3DID) in our case, see Methods].

The statistical potentials \mathbf{E}_{pair} , \mathbf{E}_{local} , \mathbf{E}_{3D} , \mathbf{E}_{3DC} , and \mathbf{E}_{S3DC} are defined using formula (1), with corresponding subindexes between \mathbf{E}_- and \mathbf{PMF}_- . It was shown³⁹ that \mathbf{E}_{pair} admits a decomposition of the form

$$E_{pair} = E_{S3DC} - E_{3DC} + E_{3D} - E_{Local} + E_{emp},$$

where \mathbf{E}_{emp} is a residual energy term depending only on the conditions of the interacting residues that accounts for the reference state. This equation was initially derived for the scoring of protein folds, but it remains valid when applied to the residues in the interface between two interacting proteins.

Note that the statistical potential \mathbf{E}_{S3DC} is a refinement of the residue-pair statistical potential \mathbf{E}_{pair} , in the sense that it takes into account not only the residues that interact but also the condition in which each of them sits. On the contrary, the statistical potential \mathbf{E}_{3DC} depends on the occurrence of interacting conditions, disregarding the specific interacting residues. The score \mathbf{E}_{local} is distance independent and it reflects the probability of placing a residue on a specific condition. Moreover, it splits into two terms, each of them depending only on the probability of placing a certain residue in some condition, for each chain separately. The energy term \mathbf{E}_{3D} concerns only the distance at which pairs of residues interact. Note that this score increases together with the number of interacting residue-pairs.

For our computations, we have considered that two residues interact if its minimum distance is below 5 Å. The reference state considered here is the one called *mole-fraction*,³¹ and its equivalent extensions for the condition-specific potentials of mean force.

The statistical potentials and native structure prediction on the 3DID dataset

We have undertaken a preliminary analysis of the statistical potentials by determining their capacity to correctly discriminate native structures from non-native structures on the dataset of binary interactions 3DID. For each native structure in the dataset, 1000 nonnative structures were constructed by shuffling the residues of each protein sequence while fixing the structure.

The five potentials \mathbf{E}_{pair} , \mathbf{E}_{local} , \mathbf{E}_{3D} , \mathbf{E}_{3DC} , and \mathbf{E}_{S3DC} were analyzed using a five-fold approach. The dataset 3DID was split into five groups. The native structures in four of the groups were used to define the potentials (i.e., for the computation of the probabilities above), while the remaining group, together with the corresponding generated nonnative

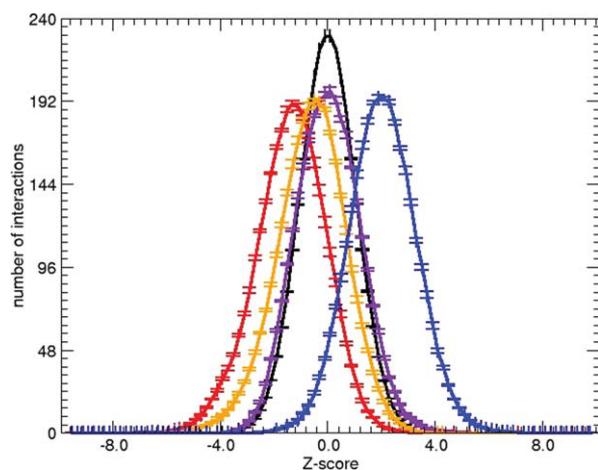


Figure 1. Average of the distribution of Z-scores using a five-fold approach plus the ranges of error. Z-scores are obtained with the statistical potentials E_{pair} (red), E_{S3DC} (orange), E_{local} (blue), and E_{3DC} (purple). Also the distribution of the Z-score of a random distribution, simulated by shuffling the sequences of the unbound proteins along the interface is shown in black.

structures, was used for testing. This process was repeated for five times, so that each group was used as test group once. Additionally, in order to provide a better comparison of native and nonnative scores as well as of the different scores, each score was normalized with respect to the random distribution obtained by shuffling the residues in each sequence. That is, for each potential, a new score called Z-score was defined by subtraction of the mean score and division by the standard deviation among the randomized sequences.³⁹

In Figure 1, the distribution of the Z-scores of native structures is shown. The distribution of Z-scores for nonnative structures is also given and is centered at zero (by construction). The deviation from the centered distribution of the Z-scores corresponding to native structures indicates that our statistical potentials discriminate to different extent native from nonnative structures and prove the validity to further use them for binary interactions structure prediction or validation. In this sense, Figure 1 shows that the most relevant scoring functions are E_{pair} , E_{local} , and E_{S3DC} , while E_{3DC} is probably the less useful potential for this task. Note that the Z-score of E_{3D} vanishes because this score depends only on the coordinates of the interface residues that are fixed in the randomized sequences.

Near-native decoy selection by the statistical potentials on the benchmark dataset

Each binary-complex conformation obtained by means of rigid-body docking from its two individual protein-chains will be referred as *decoy*. We denote by I-RMSD the interface C $_{\alpha}$ -RMSD⁴² from the native

structure. A decoy is called *near-native* if I-RMSD < 2.5 Å.^{31,43}

We consider here the suitability of our scoring functions to single out near-native decoys from a pool of decoys. For that, we consider the benchmark dataset.⁴⁴ It consists of a collection of binary complexes (124) with known structure (named *targets*) and a set of decoys for each of them (named *target set*). Note that there are 97 of the target sets in the dataset that contain at least one near-native decoy.

Each scoring function provides a ranking of the decoys in a target set. We call a target set a *hit* of a scoring function for a fixed number of allowed predictions m if the scoring function ranks at the top m at least one near-native decoy of the set. We build success curves of each scoring function by considering the percentage of hits in the dataset while varying the number of allowed predictions. We consider the success only up to 1000 predictions because for this number, the probability of finding at least one near-native decoy is around 0.9 for most target sets (see Methods). Therefore, it is essentially meaningful to analyze the behavior of scoring functions for small number of predictions. Moreover, the usual number of predictions provided by the uploaders in the CAPRI scoring function experiment (<http://www.ebi.ac.uk/msd-srv/capri/>) is 1000.

Figure 2(A) shows the success curves of the five statistical potentials. It can be seen that each of the potentials in which E_{pair} was split (E_{local} , E_{3D} , E_{3DC} , and E_{S3DC}) has a lower near-native prediction capability than that of E_{pair} . Surprisingly, the two statistical potentials that account for the most sophisticated conditions to take part in an interaction, E_{S3DC} and E_{3DC} , have less successful rate than E_{local} and E_{3D} potentials. With the exception of E_{pair} , all other potentials show success curves below the random for more than 150 predictions [Fig. 2(A)].

When the number of allowed predictions is lowered to 200, most P -values of the target sets in the benchmark dataset are small (Table SI). This indicates that near-native predictions are not likely to be solely due to random. The success curves of the scoring functions in Figure 2(A) are over the random curve for up to 200 predictions. In this case, 53 targets are hits for at least one scoring function and four of them are exclusive of E_{pair} . We have observed that all but two of the hits of E_{local} and E_{3D} are also detected by E_{pair} . On one hand, this indicates that E_{local} and E_{3D} do not incorporate new information to E_{pair} , and, on the other, that most of the success of E_{pair} is encoded in these two scoring functions. That is, the frequency of pairs of interacting residues observed in known binary interactions (measured by E_{pair}) is essentially due to (a) the intrinsic geometry of the binding interface (E_{3D}) and (b) the presence of some residues at certain locations, independently of the interacting partner (E_{local}).

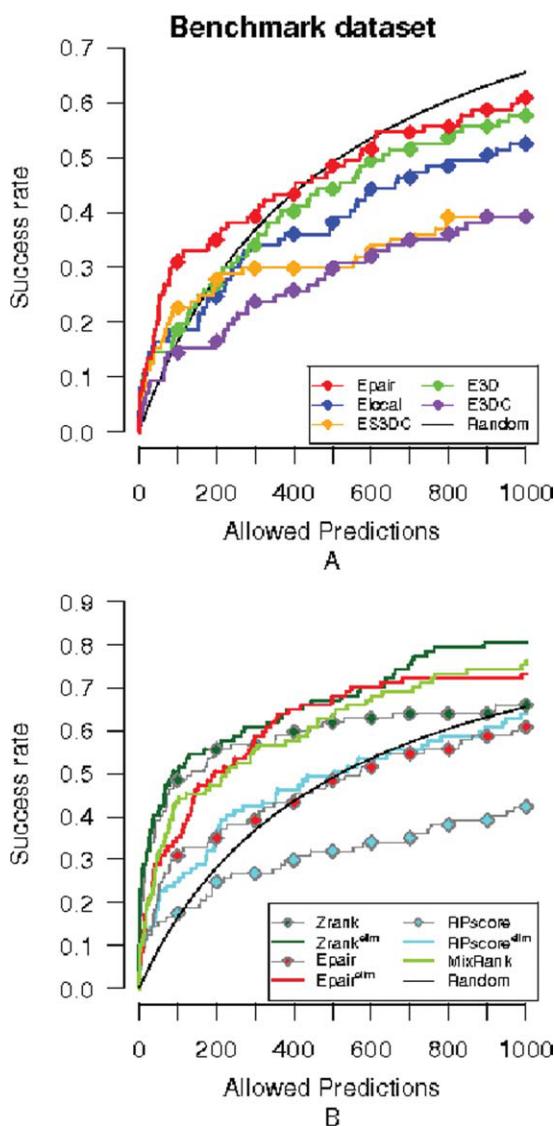


Figure 2. Success curves for the benchmark dataset. Success curves for the near-native criterion I-RMSD < 2.5 Å are plotted. (A) Success curves for the five statistical potentials: E_{pair} (red), E_{S3DC} (orange), E_{local} (blue), E_{3D} (green), and E_{3DC} (purple), plus the success curve expected by random (black). (B) Success curve of the MixRank strategy ranking and ranks with E_{pair} , Zrank, RPScore scoring functions before and after application of the redundancy filter (superindex “elim” indicates the application of the filter).

Although the scoring function E_{S3DC} is less successful than E_{pair} , it detects 14 hits (out of 27) where E_{pair} failed, for 200 predictions. Also, the scoring function E_{S3DC} predicts six hits that were not found by E_{pair} and four of them were also predicted by E_{S3DC} . To emphasize the nonoverlap of the hits of E_{pair} and E_{S3DC} , we show in Figure S1 their success curves together with the percentage of common hits. We conclude that a relevant number of hits are different between E_{S3DC} and E_{pair} , independently of the number of allowed predictions.

For comparison, we have also plotted in Figure 2(B), the success curves of the scoring functions E_{pair} , Zrank, and RPScore. RPScore is a pair potential scoring function, while Zrank encodes atomistic energy terms. We see that Zrank provides the best success curve in the benchmark dataset for the current near-native criterion. The differences between the scoring functions will be addressed later in the text.

Finally, to see the dependence of the results on the near-native decoy criterion, we show in the supplementary material (Figure S2), the success curves of our scoring functions obtained by considering a decoy to be near-native if I-RMSD < 5 Å.

ROC curves on the benchmark dataset

Success curves tell us about the number of hits of a scoring function in a dataset but provide no insight about the number of near-native decoys selected for each target set. This feature can be globally analyzed in the dataset by considering ROC curves. ROC curves are constructed here from the ratio of near-native decoys selected while varying the number of allowed predictions (see Methods). Our approach is equivalent to first compute the ROC curve for each target set and then average the curves over the target sets.

Figure 3 shows the ROC curves of the five statistical potentials (E_{pair} , E_{local} , E_{3D} , E_{3DC} , and E_{S3DC}) together with those of the scoring functions Zrank and RPScore. The ROC curves of the five

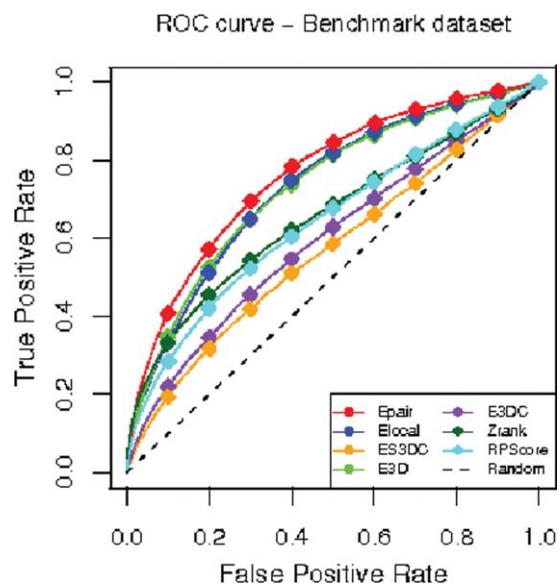


Figure 3. ROC curves for the benchmark dataset. We plot the ROC curves for each of the five statistical potentials E_{pair} (red), E_{S3DC} (orange), E_{local} (blue), E_{3D} (light green), E_{3DC} (purple), the scoring functions Zrank (dark green) and RPScore (light blue), and the random classification ROC curve (dashed black).

Table I. Hits by different ranking methods on the benchmark dataset

Zrank and RPScore	Zrank	Zrank and MixRank
1AY7, 1EWY, 1N8O, 1RLB, 2QFW, 2SIC, 2UUY	1AY7, 1B6C, 1E96, 1HE1, 1I9R, 1IJK, 1IQD, 1JPS, 1KAC, 1KTZ, 1QFW, 1AZS, 1GLA, 2MTA, 2SNI, 2VIS, 2FD6	1AKJ, 1E6J, 1F34, 1F51, 1KXQ, 1ML0, 1MLC, 1NCA, 1GPW, 1K74, 1R0R, 1YVB, Z5Y, 1ZHI, 2HLE
	Common for all	
	1AHW, 1AVX, 1BJ1, 1BUH, 1BVN, 1DFJ, 1E6E, 1EAW, 1FSK, 1IQD, 1K4C, 1KXP, 1MAH, 1PPE, 1WEJ, 1T6B, 1XD3, 1Z0K, 2JEL, 2B42, 2CFH, 7CEI	
RPScore	RPScore & MixRank	MixRank
1FC2, 1J2J	1CGI, 2BTF, 2I25	1EZU, 1I4D, 1TMQ, 1UDI, 2PCC, 2H7V

We show the targets of the benchmark dataset that provide a near-native decoy among the first 200 predictions, for the rankings provided by the MixRank strategy, Zrank and RPScore, after applying the redundancy filter. Common hits are grouped. Total of structures: 71 (out of 97 possible).

statistical potentials relate similarly to the relation among their success curves explained above.

Although the success curve of Zrank surpassed the curve of \mathbf{E}_{pair} (and hence of the other statistical potentials), it is remarkable that the statistical potentials \mathbf{E}_{pair} , $\mathbf{E}_{\text{local}}$, and $\mathbf{E}_{3\text{D}}$ provide a bigger area under the ROC curve (AUC) than Zrank. This observation implies that these three statistical potentials tend to group near-native decoys together, providing a better separation of the two classes (near-native and non-near-native) than Zrank.

MixRank: A new strategy to rank the decoys of a target set

Based on the fact that \mathbf{E}_{S3DC} and \mathbf{E}_{pair} provide a fairly amount of nonoverlapping hits, we consider a new strategy to rank the decoys of a target set, called *MixRank*. It consists of first considering the lists of decoys ranked by the scoring functions \mathbf{E}_{S3DC} and \mathbf{E}_{pair} separately, and then alternatively selecting one decoy from each list. Additionally, in order to avoid repetitions, we apply a removal of redundant predictions.⁴⁵ That is, we do not include decoys that are less than 5 Å of ligand-RMSD⁴⁶ from an already selected decoy. This way of removal of redundancies was analyzed⁴⁵ and was proved to provide better selection of near-native decoys. We wish to note that MixRank is not a scoring function but a method of ranking.

We have applied the same filter for redundant predictions to the scoring functions \mathbf{E}_{pair} , Zrank, and RPScore. Figure 2(B) shows the success curves of these scoring functions, with or without the redundancy filter, together with that of the MixRank.

It is noteworthy that the elimination of redundancy improves near-native prediction success for all scoring functions.⁴⁵ Also, the MixRank strategy provides better hit-prediction in comparison with \mathbf{E}_{pair} when the number of selected predictions is small. This is due to the fact that this strategy adds hit-predictions of \mathbf{E}_{S3DC} without losing hit-predictions

of \mathbf{E}_{pair} . Note that even with the improvement of MixRank over \mathbf{E}_{pair} , Zrank (with elimination of redundancies) is the best ranking method for near-native selection on the benchmark dataset.

In order to understand the ratio of hits shared between decoys ranked with the MixRank strategy, Zrank and RPScore (after removal of redundancies), we show in Table I the name of the targets in the benchmark dataset for which each of the rankings include at least one near-native among the first 200 selected decoys. Zrank clearly provides the highest number of nonshared hits (17), but we observe that MixRank obtains a hit for nine of the targets where Zrank fails and RPScore for five (see Fig. 4 for the scores of target 1UDI, for which there is a near-native decoy ranked 1 with the MixRank).

Similar success in near-native decoy prediction was obtained by considering a MixRank strategy with the combination of \mathbf{E}_{S3DC} , $\mathbf{E}_{\text{local}}$, and $\mathbf{E}_{3\text{D}}$, or $\mathbf{E}_{3\text{DC}}$ and \mathbf{E}_{pair} , or $\mathbf{E}_{3\text{DC}}$, $\mathbf{E}_{\text{local}}$, and $\mathbf{E}_{3\text{D}}$ as above. Alternatively, we also tried to find a new scoring function by combining the five statistical potentials \mathbf{E}_{pair} , $\mathbf{E}_{\text{local}}$, $\mathbf{E}_{3\text{D}}$, $\mathbf{E}_{3\text{DC}}$, and \mathbf{E}_{S3DC} . This was attempted by using artificial intelligence methods (support vector machine and neural networks among others) without success. Failure was mainly due to the fact that all artificial intelligence methods tended to ignore success cases of \mathbf{E}_{S3DC} and $\mathbf{E}_{3\text{DC}}$ in favor of the three most successful scoring functions \mathbf{E}_{pair} , $\mathbf{E}_{\text{local}}$, and $\mathbf{E}_{3\text{D}}$. As already observed, the last three scoring functions share most of the hits, and therefore, there is no gain in their combination.

Selection of the best decoy in a target set

We have been concerned with the selection of near-native decoys in a target set. However, only 97 of the target sets of the benchmark dataset contain decoys satisfying our criterion of near-native. We analyze here the capacity of the scoring functions and MixRank ranking to top-rank the best available decoy. To introduce some flexibility, we consider a

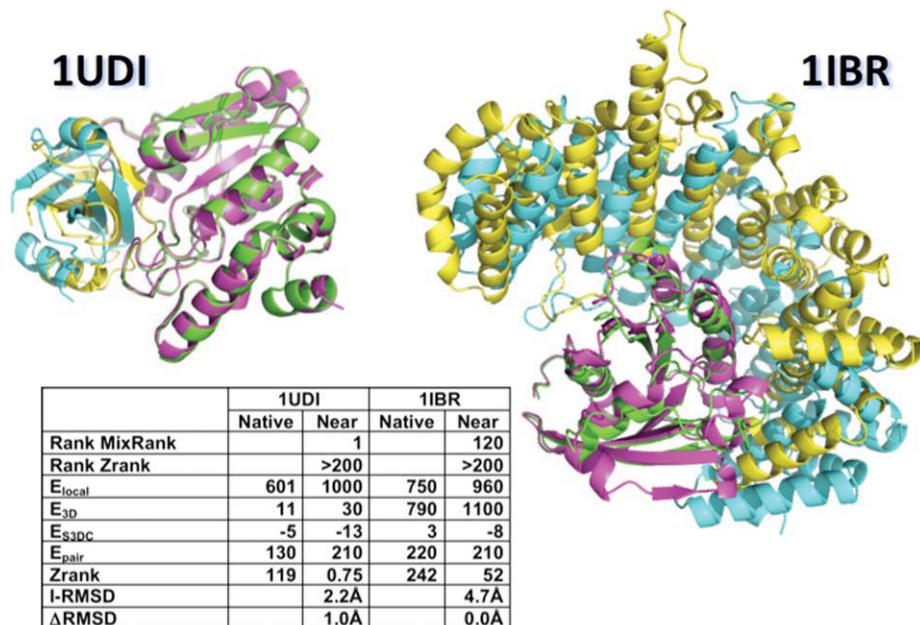


Figure 4. Comparison of the native conformation and one decoy for easy and difficult targets. The native conformation and a near-native decoy of 1UDI (easy case) and of a good decoy of 1IBR (difficult case) are plotted in ribbons. Decoy conformations obtained by rigid-body docking of the unbound proteins are shown in pink and yellow. Their respective chains in the native conformation of the binary complex are shown in green and cyan. Additional information of the scores (Zrank, E_{local} , E_{pair} , E_{S3DC} , and E_{3D}) calculated with the native and selected decoys are shown in the inner table. Also, for the decoys of both targets, the table includes the I-RMSD and the ranking by Zrank scores and the MixRank strategy.

decoy *good* if its I-RMSD differs less than 0.5 Å from the lowest I-RMSD among all the decoys in the target set. Note that this concept depends on the other decoys in the target set, and it is not a property of the decoy conformation in comparison to the native structure.

We have constructed new success curves [Fig. 5(A)] by considering the percentage of target sets in the benchmark dataset for which a good decoy is top-ranked, while varying the number of allowed predictions. Note that this definition of success allows us to test all 124 target sets. We observe that the relation between our five statistical potentials is analogous to that depicted in Figure 2(A). However, in this case, the most successful scores are better than random.

Determination of the best (or good) decoys in the target set allows us to take a closer look to the behavior of the scoring functions on the medium and difficult cases of the benchmark dataset (see Methods). For most targets in these two classes, there is no decoy in their target set satisfying our near-native criterion. The goal for the docking community is to obtain the best pose, but our purpose here concerns only the evaluation of scoring functions that are aimed to select the decoys that will be further processed, and we do not allow conformational changes at this step. Therefore, the success in these types of targets is to select the best decoy available.

Figures 5(B) and 5(C) provide the analysis of success when restricted to medium and difficult

cases. Figure 5(B) depicts the success curves related to good decoys for medium and difficult cases, for the scoring functions E_{pair} , E_{local} , E_{3D} , E_{S3DC} , and E_{S3DC} and Zrank and RPScore. We observe that the statistical potentials E_{pair} , E_{3D} , and E_{local} have a similar success in the selection of the best decoy [compare to Fig. 5(A)]. Additionally, these three statistical potentials surpass Zrank for these cases. Figure 5(C) provides the success curves for the MixRank strategy together with the ranks provided after the application of the redundancy filter to E_{pair} , Zrank, and RPScore. The MixRank strategy and the rank provided by E_{pair} are better than Zrank at predicting the best decoy in the dataset of medium and difficult cases.

We attribute the differences to the fact that Zrank takes into account detailed atomic features (*fine-grain*) and hence it is likely to fail in predicting decoys that are not close enough to the native structure. On the contrary to Zrank, our statistical potentials are less dependent on small variations of the conformation of the binding interface (*coarse-grain*). This observation was also pointed out in a previous work.⁴⁵

Figure 4 shows the scores and ranks for the best near-native decoy of target 1IBR predicted as solution at rank 120 according to MixRank and at rank 3722 according to Zrank (applying the redundancy filter). The value of I-RMSD of this decoy is 4.71 Å. In this example, it is shown that the Zrank score of the native conformation of the binary

complex of target 1IBR is significantly different to the Zrank score of this near-native decoy, while the differences using E_{pair} scores are not that significant. Using the scoring functions E_{local} or E_{3D} alone, we also mistake the ranking. Therefore, Zrank can only be used if the structure of the binary complex after rigid-docking is optimized and correctly modified, while this example shows how E_{pair} ,

E_{local} , and E_{3D} can be combined to obtain a good ranking of rigid-docking poses.

Near-native decoy selection by the statistical potentials on the permanent interactions dataset

Next, we analyze the success of our statistical potentials E_{pair} , E_{local} , E_{3D} , E_{3DC} , and E_{S3DC} in the detection of near-native decoys on the permanent dataset. We observe that the success curves in this case (Fig. 6) are similar to the success curves obtained for the benchmark set (Fig. 2). It has to be noted that most scoring functions are over the random curve in the permanent interactions dataset and that E_{pair} overcomes the rest of the potentials [Fig. 6(A)].

As we did with the benchmark dataset, we have analyzed the overlap among the hits of the different statistical potentials when allowing 200 predictions. We observe that all hits of E_{local} and all but one hit of E_{3D} are hits of E_{pair} , while seven hits of E_{S3DC} are not found by the rest of scoring potentials. This suggests that the MixRank strategy can improve the rank given by E_{pair} for permanent interactions. For the analysis of the statistical significance of the hits, we show in Table SII the probability of finding at least one near-native decoy among the 200 top-ranked decoys of each target set. P values in the table show similar difficulties to guess a near-native decoy by chance to those found for the benchmark dataset (Table SI).

Based on the previous observation, we have further compared the near-native prediction success of MixRank strategy to that of the rank given by E_{pair} , Zrank, and RPScore after applying the redundancy filter. The corresponding success curves are given in Figure 6(B). We note that, contrary to the scenario shown in Figure 2(B) for the benchmark dataset, Zrank has lower success rate than the MixRank and E_{pair} rankings (both with the redundancy filter). We are apparently reflecting some property of the permanent dataset not present in the benchmark dataset. Zrank is a scoring function that is a linear

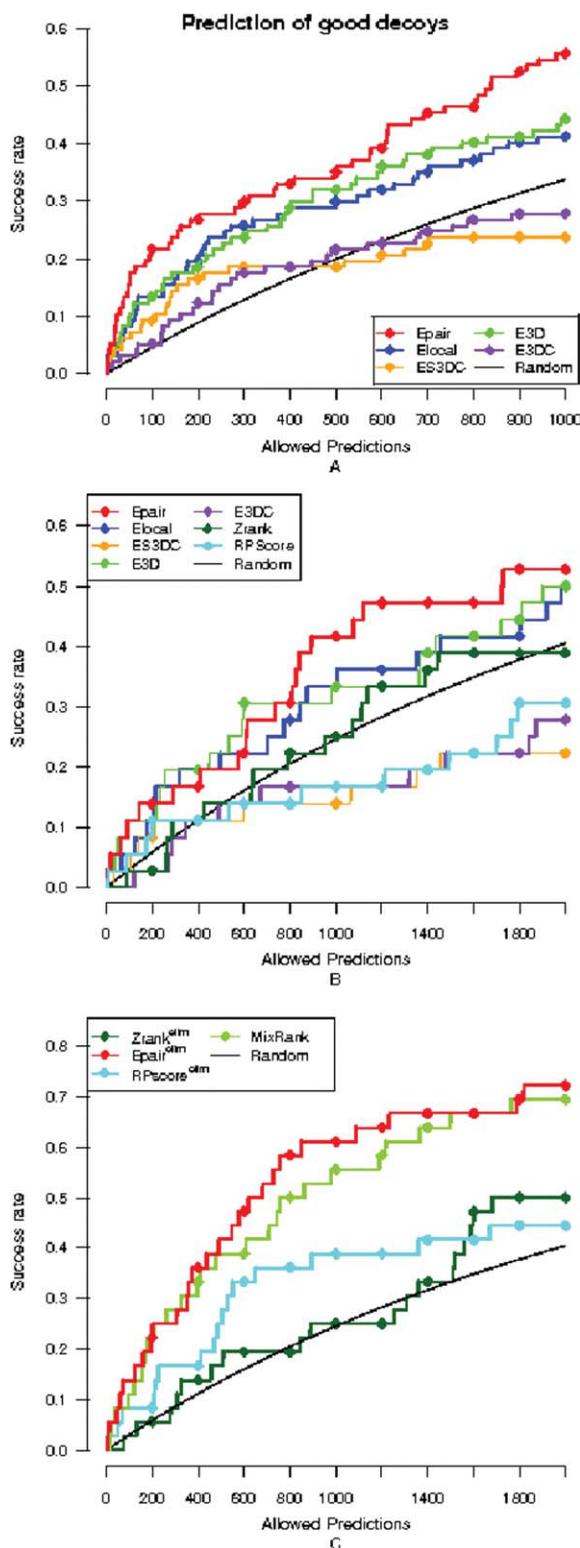


Figure 5. Success curves for good decoys in the benchmark dataset. (A) Success curves on the whole benchmark dataset are plotted for the five statistical potentials E_{pair} (red), E_{S3DC} (orange), E_{local} (blue), E_{3D} (light green), and E_{3DC} (purple). (B) Success curves for good decoys for the five statistical potentials together with Zrank (dark green) and RPScore (cyan), only with the medium and difficult cases of the benchmark dataset (no redundancy filter applied). (C) Success curves are plotted after removal of redundant solutions for the MixRank strategy, E_{pair} , Zrank and RPScore scoring functions, and also compared with the success curve expected by random (black), only with the medium and difficult cases of the benchmark dataset.

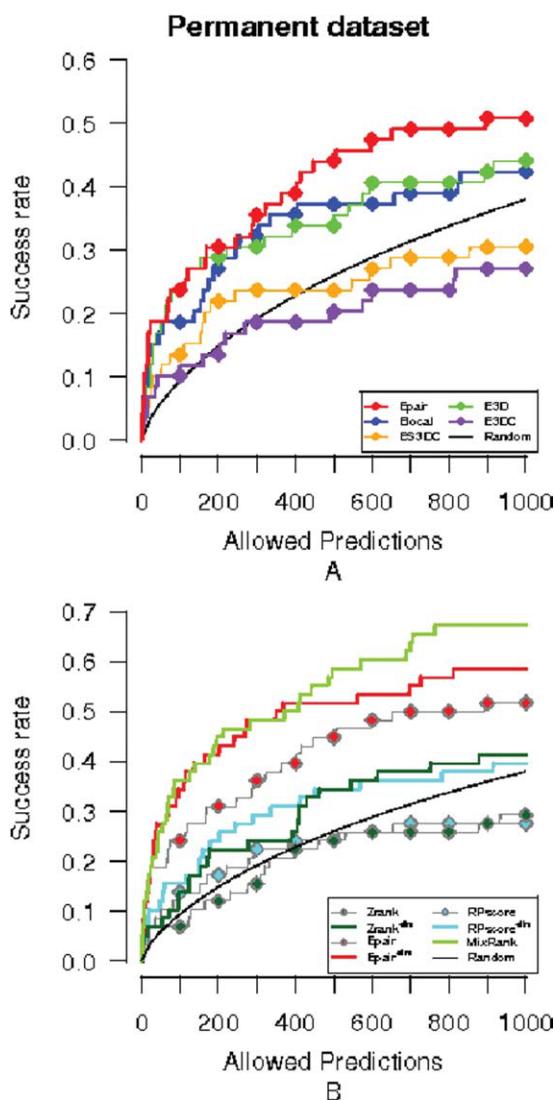


Figure 6. Success curves for the permanent dataset. Legend colors of potentials as in Figure 2. (A) Success curves for the five statistical potentials: E_{pair} , E_{S3DC} , E_{local} , E_{3D} , and E_{3DC} , plus the success curve expected by random. (B) Success curve of the MixRank strategy ranking and ranks with E_{pair} , Zrank, RPScore scoring functions before and after application of the redundancy filter.

combination of energy terms, whose weights are obtained by training on the cases of the benchmark dataset of the first version,⁴⁷ which is not included in the later versions of the dataset that were used for testing. We believe that this makes Zrank more specific to transient interactions, because the ratio of targets being transient interactions in the benchmark dataset is higher than in the permanent dataset, and this is why it has a reduced success rate when scoring permanent interactions.

Table II provides the name of the targets of the permanent interaction dataset for which the ranks given by the MixRank strategy, Zrank, and RPScore produced at least one near-native decoy in the first 200 predictions.

We have also analyzed the prediction of good decoys using the split statistical potentials (Fig. S3). We obtained similar success curves for E_{pair} , E_{local} , and E_{3D} . We further checked the consistency of our approach if decoys of permanent interactions were obtained using the unbound structures. We found only one case in 3DID (RibosomalS2#RibosomalS8) with the unbound structures of both partners (see Table SIII for the ranks of the first good decoy in this case).

Discussion

Statistical potentials have often been used to study protein folding and protein–protein interactions. Since they were first defined in the 1970s, they have been the focus of several studies. Their accuracy has improved substantially thanks to the increase of information available in the databases and the newly developed machine learning algorithms. When studying protein–protein interactions, it has been pointed out by several works^{14,16,17} that the integration of statistical potentials into the FFT framework increases the number of detected near-native structures during a rigid-body docking search.

In this study, we have tested a series of novel residue-pair statistical potentials for scoring protein–protein interactions, following the methodology of our previous work in protein folds.³⁹ The main focus of study has been the ability to discriminate near-native decoys from a collection of decoys obtained by rigid-body docking experiments. Four new statistical potentials have been considered: E_{S3DC} and E_{3DC} , concerning the frequency of interacting residues, including the specific conditions (secondary structure, exposure and polar character) in which they sit; E_{local} , measuring the probability of placing the residues involved in the binding interface within a specific condition; and E_{3D} , based exclusively on the geometry of the binding interface.

We have noticed that the information carried by the standard residue-pair statistical potential E_{pair} is mainly a mixture of two facts: first, the tendency of some residues that are at some specific conditions to be at the binding interface (encoded by E_{local}), and, second, some geometric constraints (encoded by E_{3D}). The fact that the scoring function E_{local} contains the largest part of the information required to predict an interaction implies that the physico-chemical properties necessary for the binding are allocated on the proteins previous to its binding and with independence of the partner. This is the first main conclusion of this work, however, given previous results in the literature, it is not entirely unexpected. The usage of desolvation and optimal docking area to predict binding sites has been described in the literature^{21,48} and has already been used to predict protein–protein interactions. In our case, we have proved the relevance of certain regions, formed

Table II. Hits by different ranking methods on the permanent dataset

RPScore & MixRank	MixRank	Zrank & MixRank
Dehydratase_LU#Dehydratase_SU	ATP-synt#ATP-synt_DE_N	ATP-synt_DE#ATP-synt_Eps
Fumarate_red_C#Fumarate_red_D	Cloacin#Cloacin_immun	MCR_beta#MCR_gamma
NHase_alpha#NHase_beta	COX4#COX7B	
Ribosomal_L11_N#Ribosomal_L12	MCR_alpha#MCR_gamma	
RNA_pol_A_bac#RNA_pol_Rpb1_3	MHC_II_alpha#MHC_II_beta	
RNA_pol_Rpb1_4#RNA_pol_Rpb2_3	PA28_alpha#PA28_beta	
TFIIF_alpha#TFIIF_beta	Ribosomal_S10#Ribosomal_S3_N	
	RuBisCO_large#RuBisCO_small	
	TP_methylase#TP_methylase	
	tRNA-synt_2e#tRNA-synt_2e	
	Urease_alpha#Urease_beta	
RPScore	Common for all	Zrank
RNA_pol_L#RNA_pol_Rpb1_3	Como_LCP#Como_SCP	COX1#COX3
	COX6C#COX7B	DNA_pol3_beta#DNA_pol3_beta_3
	LigA#LigB	Glyco_hydro_11#Glyco_hydro_18
	Me-amine-dh_H#Me-amine-dh_L	Ribosomal_S18#Ribosomal_S6
	Ribosomal_S2#Ribosomal_S5	SRP14#SRP9
	Trp_syntA#Trp_syntA	

We show the targets of the permanent interactions dataset that provide a near-native decoy among the first 200 predictions with rankings provided by the MixRank strategy and the scoring functions Zrank and RPScore, after applying the redundancy filter. All hits that are shared between Zrank and RPScore are also hits for the MixRank.

by residues located near the surface of the protein and within a specific secondary structure, to later interact with a protein and to become buried in the protein–protein interface. We have to note that E_{local} is computed as a sum of two terms, each of them obtained as the sum of statistical energies of the residues of the binding interface in one of the chains. This suggests that it might be worth introducing E_{local} into the FFT procedure, as initial grid scores, in order to improve the docking surface search.

When studying the rest of statistical potentials, we found that E_{S3DC} correctly detected some targets that escaped residue-pair statistical potential selection. E_{S3DC} is a refinement of E_{pair} that takes into account the frequency by which two residues interact and the local features in which the residues sit. Based on this observation, we elucidated a ranking strategy of rigid-docking poses, *MixRank*, that combined the selection power of the statistical potentials E_{pair} and E_{S3DC} in a way that its success curve was better than that of the standard residue-pair potential for a small number of predictions. This improvement was noticed with the benchmark dataset and the permanent interactions dataset, and also when searching near-native decoys or the best decoys available in the dataset. Our strategy to combine both scores seems plausible to follow if: (i) the hits given by independent scores are different; and (ii) we do not know *a priori* the most successful scoring function. We wish to note that we do not obtain a new scoring function but a strategy to rank the decoys.

Similarly, in ClusPro,²⁸ the authors follow the strategy to select 2000 decoys by picking the top-ranked decoys according to two different scores (desolvation free energy and electrostatics energy). They

proceed with the clustering of the selected decoys and the centers of the biggest clusters are further refined. Our approach here is slightly different, because the selection of decoys is not based on the size of the cluster but keeps the initial order of the individual scores.

ROC curves for E_{pair} , E_{local} , E_{S3D} , and Zrank on the benchmark dataset suggested that predictions derived from the first three scoring functions included less non near-native decoys than Zrank. This was valid for a large ratio of false-positives (non near-native decoys being considered near-native), and it depends on the total number of allowed predictions. This was particularly relevant for medium and difficult cases, there were success curves for E_{pair} , E_{local} , and E_{S3D} surpassed Zrank and RPScore functions, and stressed when removing redundant solutions and using the MixRank strategy. This drives us to the second main conclusion of this work, that is, we have generated a ranking based on statistical potentials able to compete with the best available methods (i.e., Zrank) in successful rates, unless there is evidence that only small conformational changes occur upon binding. Besides, because this method is defined from residue-pair statistical potentials and does not require an atomic level description, it can also surpass Zrank when scoring rigid-docking decoys in cases where the unbound partners of an interaction have to endure conformational changes upon binding.

We have tested our methods in two different datasets: the standard benchmark set and a more specific set of permanent interactions. First, the benchmark decoy dataset⁴⁴ was used to analyze the success of our scoring functions. However, this dataset contains many transient interactions. Therefore,

in order to test whether different features would appear in other types of interactions, we constructed a new dataset consisting of only permanent interactions. We wish to note that for the permanent interactions dataset, the MixRank strategy and E_{pair} scoring function surpassed the success rate of Zrank and RPScore when filtering out redundant poses. Therefore, the third main conclusion from this work is that we have obtained a good methodology to rank protein–protein interactions of permanent complexes. This is particularly relevant to tackle the next challenge in protein docking, which is to ensemble higher-order structures (i.e., multiprotein complexes) from their individual components.^{49,50} These molecular machines are often constituted by a central core of interactions, which are permanent and confer the main function to the complex, decorated by some others with regulatory roles.⁵¹ Thus, a good set of potentials that predict the conformation of stable complex cores will be paramount.⁵² Besides, although it can be argued that the statistical potentials derived from domain–domain interactions are more suitable to the task of detecting permanent interactions, the fact that our methods predicted medium and difficult cases of rigid-docking with better or similar rate of success than other methods validates its generalized use for rigid-docking.

Methods

Databases

We have considered three databases, one to calculate the knowledge based pair potentials (3DID) and two to test the scoring functions (a benchmark decoy set and the permanent interactions set).

3D Interacting Domains (3DID). We have considered a nonredundant set of interacting domains extracted from the database 3DID.⁵³ The database 3DID consists of a nonredundant collection of domain–domain interactions in proteins for which high-resolution three-dimensional structures are known. Interactions in this database are labeled by the PFAM code of each of the interacting domains. This database has been used for the computation of the frequencies required in the statistical potentials definition.

Benchmark decoy dataset. We have considered the benchmark decoy dataset of Weng and coworkers.⁴⁴ This dataset is based on a set of nonredundant real interactions for which both the complex 3D structure and the individual chain structures are available. We consider the 54,000 decoys generated using the rigid-body docking algorithm ZDock3.0¹⁶ from the individual chain structures. The set of binary-complex conformations of a rigid-body prediction are classified according to the expected difficulties to obtain a near-native solu-

tion of the target. They deal with three types named: easy, medium, and difficult cases. This classification scheme is based on the degree of conformation changes as measured by I-RMSD and the fraction of non-native residue contacts.⁴⁴ In Figure 4, we compare the native conformations of targets 1UDI (easy case) and 1IBR (difficult case) to selected decoys (with I-RMSD 2.23 and 4.71 Å, respectively).

In total, the dataset consists of 124 cases, 88 of which are straight forward for rigid-body docking, 19 are medium and 17 are difficult cases for which further conformational changes are required upon binding. Only 97 of them (88 rigid-body and nine medium) fit into our near-native decoy criterion.

Permanent interactions dataset. We have collected a subset of permanent interactions and its accompanying docking decoys, by selecting from 3DID one representative structure of all those interactions whose interacting partner components can only function in their complex form, and thus are unlikely to exist in isolation. Each binary complex has been decomposed in two unbound domains and used to generate a set of decoys of binary interactions. The procedure to obtain the unbound structure of the interacting domains is as follows: First, for each binary complex, we searched in the PDB⁵⁴ for the structures containing the same domains without its interacting partner. Second, if the unbound domain was not found in the PDB, we searched for homologous proteins with solved structures in the PDB containing the unbound domain and we used them as templates to model the desired unbound domain with MODELLER.⁵⁵ And third, we constructed the rest of unbound domains of the permanent dataset by extracting the backbone of each unbound domain and remodeling the side-chains with MODELLER. In this way, the dataset contains 143 targets of binary complexes and its unbound structures.

Finally, a total of 54,000 decoys for each target were created using ZDock 3.0 with a 6° sampling. After the sampling, 59 of the targets produced at least one decoy satisfying the I-RMSD < 2.5Å.

Scoring functions

We have compared the performance of our five scoring functions (E_{pair} , E_{local} , E_{3D} , E_{3DC} , and E_{S3DC}) with Zrank⁴³ and RPScore.³¹ Zrank is the scoring function included in ZDock, obtained as a linear weighted sum of van der Waals and electrostatic energies and desolvation. RPScore is a knowledge-based pair potential scoring function included in FTDock.

Statistical assessment of hits

For the assessment of the statistical significance of predictions, we have used the *P*-value computation and the random expected curve.⁴⁵

I-RMSD and Ligand-RMSD

I-RMSD (interface root mean square deviation)^{31,43} of a decoy refers to the pairwise RMSD of corresponding C_{α} -atoms of the residues in the interface of the native conformation.

Ligand-RMSD⁴⁶ between two decoys (obtained from rigid-body docking) is computed as the RMSD between corresponding C_{α} -atoms of all the residues in the ligand. In rigid-body docking, the protein that is rotated and translated around the other protein is called the ligand.

Measures for correct predictions

Depending on the approach taken, we consider correct predictions those being either near-native decoys or good decoys. A decoy is called *near-native* if I-RMSD < 2.5 Å and *good* if its I-RMSD differs less than 0.5 Å from the lowest I-RMSD among all the decoys in the target set.

ROC curves

The ROC curve is the plot of the false positive rate (FPR) versus the true positive rate (TPR) calculated while varying the selection threshold of a scoring function:

$$TPR = \frac{TP}{Pos}, \quad FPR = \frac{FP}{Neg}.$$

Here, Pos and Neg are the total number of positive and negative objects, respectively, *TP* is the number of correctly predicted positive objects, and *FP* is the number of objects incorrectly predicted to be positive.

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