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# **The role of the microenvironment in tumor growth and invasion**

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# **Abstract**

Mathematical modeling and computational analysis are essential for understanding the dynamics of the complex gene networks that control normal development and homeostasis, and can help to understand how circumvention of that control leads to abnormal outcomes such as cancer. Our objectives here are to discuss the different mechanisms by which the local biochemical and mechanical microenvironment, which is comprised of various signaling molecules, cell types and the extracellular matrix (ECM), affects the progression of potentially-cancerous cells, and to present new results on two aspects of these effects. We first deal with the major processes involved in the progression from a normal cell to a cancerous cell at a level accessible to a general scientific readership, and we then outline a number of mathematical and computational issues that arise in cancer modeling. In Section 2 we present results from a model that deals with the effects of the mechanical properties of the environment on tumor growth, and in Section 3 we report results from a model of the signaling pathways and the tumor microenvironment (TME), and how their interactions affect the development of breast cancer. The results emphasize anew the complexities of the interactions within the TME and their effect on tumor growth, and show that tumor progression is not solely determined by the presence of a clone of mutated immortal cells, but rather that it can be 'community-controlled'.

It Takes a Village – Hilary Clinton

#### **Keywords**

Tumor progression; mechanical effects; hybrid model; breast cancer

# **1 Introduction**

#### **1.1 What is cancer?**

Cells embedded in an *in vivo* tissue continuously sense the biochemical and mechanical state of their environment, transduce the extracellular signals into intracellular signals, integrate these signals, and respond accordingly. The response at the cell level may involve changes

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in metabolic state, gene expression, growth, differentiation, cell division, cell movement, or apoptosis1. Maintenance of homeostasis at the tissue level involves the tissue-wide integration of and response to signals from within the tissue and its surroundings, and disruption at any of the detection, transduction or response steps may lead to neoplastic growth, *i.e.,* abnormal, unchecked growth of the tissue, producing what is called a neoplasm or tumor. Tumors can be benign, pre-malignant or malignant, and when they become malignant they become a cancer. More precisely, cancer denotes diseases that give rise to abnormal cells that proliferate indefinitely, and that can invade nearby tissues and spread to other parts of the body through the blood and lymph systems. A decade ago Hanahan and Weinberg (2000) identified six essential characteristics of cancer that are summarized as follows.

- **•** Self-sufficiency in growth signals normally cells require a signal to enter the proliferative state, and many oncogenes mimic such growth signals.
- **•** Insensitivity to anti-growth signals where cells ignore the external and internal signals that regulate cell proliferation.
- **•** Evasion of apoptosis –where cells circumvent programmed cell death.
- Unlimited ability to divide in normal tissue cells typically double 50–80 times (the Hayfllick limit), but cancer cells can divide considerably more by, *e. g.,* suppressing  $p53$ .
- **•** Sustained angiogenesis tumor cells can induce production of capillary sprouts from nearby vessels, which then provide nutrients and a pathway to the circulatory system.
- **•** Tissue invasion and metastasis without this characteristic tumors remain benign, but with it they can spread to other tissues and organs, via the circulatory system or the lymph system.

The first four of these are also characteristic of a benign tumor, while the fifth is a necessary condition for unlimited growth at the location where the tumor is initiated. Thus the primary characteristic of cancer cells is their ability to invade and metastasize. A summary of the steps and processes involved in metastasis, which distinguishes cancer from benign tumors, is shown in Figure 1. In the figure metastasis occurs via the circulatory system, but it can also occur via the lymphatic system. In either case, an essential characteristic of cancer cells is their ability to spread from the point of initiation.

There are numerous environmental causes of cancer, which is initiated with either mutations or viral or bacterial agents. Most tissues in the body can give rise to cancer, some even yield several types, and each cancer has unique features. A carcinoma is a cancer that begins in the skin or in tissues that line or cover internal organs. A sarcoma is a cancer that begins in bone, cartilage, fat, muscle, blood vessels, or other connective or supportive tissue. Leukemia is a cancer that starts in blood-forming tissue such as the bone marrow, and causes large numbers of abnormal blood cells to be produced and enter the blood. Lymphoma and multiple myeloma are cancers that begin in the cells of the immune system. Central nervous system cancers are cancers that begin in the tissues of the brain and spinal cord.

Given the complexity of normal embryonic development and the multitude of steps and checkpoints involved, it is unsurprising that there are numerous steps at which the homeostatic balance in a tissue can be upset. While the hallmarks of cancer listed earlier

 $<sup>1</sup>A$  glossary of terminology is included at the end of this manuscript.</sup>

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focus on properties of the cancer cells, cancer development *in vivo* is context-dependent in that environmental factors play a major role in the transition from normal cell to benign tumor to cancer. Our focus in the remainder of this section will be on identifying some of the key processes involved, discussing the role of mathematical modeling and computational analysis in their understanding, and briefly reviewing previous work.

# **1.2 The processes involved in the progression from the normal to the invasive phenotype**

The four major steps in terms of cell mechanisms and processes that are involved in progression of a normal somatic cell to the metastasis-competent state are as follows.

**Transformation and initiation—**The first step in the progression involves multiple genetic changes that accumulate with successive cell divisions. This is facilitated by 'immortalization' of cells (the ability to divide indefinitely) via, *e. g.,* activation of telomerase, an enzyme that prevents shortening of chromosomes during cell division. This can lead to clones capable of neoplastic growth wherein genetic errors can arise and accumulate with each cell division. It can also involve activation of growth promoting oncogenes, inactivation of cancer suppressor genes, and changes in the expression of genes that regulate apoptosis. For example, cells can be transformed by over expression of the proto-oncogenes c-Myc and Ras (Silvera *et al.*, 2010), or alternatively, by down regulation of the tumor suppressor protein p53, which down regulates c-Myc and prevents the accumulation of telomerase (Sachdeva *et al.*, 2009). This step is certainly stochastic and hence it is difficult to predict the outcome in individual cases.

**Neoplastic growth—**This is characterized by a higher than normal density at which growth saturates, usually lower than normal nutritional requirements in the growth medium, and loss of contact inhibition of growth. Tumor cells may face hypoxia, acidity, and limited nutrient availability as they grow, and some types have developed adaptive responses to cope with metabolic and other types of stress. Under normal conditions cells utilize the Krebs cycle for generating ATP, but tumor cells shift their metabolism toward high levels of glucose consumption and lactate production (the Warburg Effect) (Warburg, 1956; Kim & Dang, 2006). One adaptive response to ensure an adequate glucose supply is to stimulate angiogenesis (discussed later) in nearby vessels and to migrate toward these vessels. In this phase tumor cells may also produce chemoattractants to attract stromal cells such as macrophages to the tumor, which provide more growth factors. Thus tumor cells can pursue strategies of metabolic adaptation to survive periods of metabolic stress and maintain viability as cells accumulate (Jones & Thompson, 2009).

Numerous signal transduction pathways are involved in the control of growth and proliferation, but we focus on two widely-studied pathways – the transforming growth factor- $\beta$  (TGF- $\beta$ ) pathway and the epidermal growth factor (EGF) pathway – that are sufficiently representative of how major pathways can interact in growth control. TGF-*β*s are polypeptide growth factors that regulate numerous processes, including cell division, differentiation, motility, adhesion, and death (Kretzschmar *et al.*, 1999; Massague & Gomis, 2006). In breast cancer, which is discussed in detail later, TGF-*β* acts as a tumor suppressor in early stages of the disease, but in later stages of the disease it can promote tumor progression, in part by enhancing tumor cell motility and invasiveness (Kretzschmar *et al.* (1999) and references therein).

TGF-*β* signals through complexes of type II and type I receptors. Upon ligand binding, TRII receptors phosphorylate and activate the TRI receptors, which then activate RSmads such as Smad2 and Smad3 via phosphorylation (Massague & Gomis, 2006). Phosphorylated Smads form complexes with regulatory Smads, translocate into the nucleus, and regulate the

transcription of TGF-*β* target genes (*cf.* Figure 2(a)). TGF-*β* signaling also activates signal transducers other than Smads, such as Erk MAP kinases, PI3 kinase and Rho-like GTPases (Derynck & Zhang, 2003; Luo *et al.*, 2007).

One of the pathways that exerts a regulatory effect on the TGF-*β* pathway by regulation of Smad signaling is the Erk MAP kinase pathway, which is activated by receptor tyrosine kinases (RTKs) such as EGFR, and by Ras, a small G-protein that is activated by RTKs (Luo *et al.*, 2007). As with the TGF-*β* pathway, signaling through the Ras-Raf-MEK-ERK pathway (*cf.* Figure 2(b)) affects many cellular processes, including growth, cell-cycle progression, differentiation, and apoptosis (Dhillon *et al.*, 2007). The SOS-Grb2 complex catalyzes exchange of GDP with GTP on Ras, and the active Ras-GTP binds the Raf-1 kinase, which induces the recruitment of Raf-1 from the cytosol to the cell membrane. Activated Raf-1 phosphorylates and activates mitogen-activated protein kinase (MEK), a kinase that in turn phosphorylates and activates mitogen-activated protein kinase (MAPK or ERK), which has numerous downstream effects (*cf.* Figure 2(b)). One of these is phosphorylation of the linker regions of Smad2 and Smad3, which can inhibit the TGF-*β*induced nuclear translocation of these Smads and the antiproliferative effect of TGF-*β* (Kretzschmar *et al.*, 1999). Activated ERK also feeds back to the pathway activation at several levels (Shin *et al.*, 2009). For example, it exerts a negative feedback effect by interfering with Ras activation through SOS phosphorylation (Bourhis *et al.*, 1997; Wang *et al.*, 2009a).

In addition to the multitude of biochemical signals to which cells within a tissue are exposed, they are also subject to external forces that arise from cell-cell or cell-substrate (fluid or ECM) interactions, and to internal forces generated in the cytoskeleton. These can be either contractile or tensile, and either tangential or normal to the cell boundary. Tangential or shear forces involve relative motion of adjacent regions of the cell and can thereby open mechanosensitive channels and deform the cytoskeleton. While biochemical signaling pathways still receive the most attention, it is widely recognized in molecular biology that forces within a cell and between a cell and its environment, whether the environment is other cells in an epithelial sheet, or the ECM in the tissue context, give rise to an additional mode of signaling that can influence cell growth, differentiation, and the morphology of a tissue or organ. Of course this has long been known in biophysics, and an early formulation of this effect appears in Pauwels (1960). Whether the forces act directly by suppressing growth or gene expression, or indirectly by activating intracellular biochemical pathways, depends on the context.

Folkman & Greenspan (1975) and Folkman & Moscona (1978) were amongst the first to study the effect of cell shape on proliferation. They showed that DNA synthesis increases when cells flatten on the substrate, while proliferation stops in cells that are allowed to round up. It is now known that the rigidity of the substrate affects the force that can be transmitted through a focal adhesion (FA) to the cytoskeleton, which in turn can affect the stresses exerted on the nucleus and thereby modulate mechanosensitive pores (see Wang *et al.* (2009b) for a discussion in the framework of the tensegrity model, which postulates that the forces that are transmitted through a tissue can feed back to regulate tissue shape and form). Recent work has shown that cell-cell, cell-substrate and cell-ECM contacts such as FAs involve a complex mechanotransduction system of transmembrane proteins such as integrins, which connect via adapter proteins to the cytoskeleton, and localized signaling molecules such as focal adhesion kinase (FAK) and Src family kinases, which connect to intracellular signaling pathways such as the MAPK pathway (*cf.* Fig. 3) (Butcher *et al.*, 2009). An increase in the force on a FA, whether internally-generated by contraction in the cytoskeleton, or externally applied, leads to activation of FAK via phosphorylation and to downstream signaling steps via the small G proteins Ras, Rac and Rho. FAK activation is

required for mechanically-induced ERK activation and proliferation, while suppression of ERK activation blocks this induction (Frisch *et al.*, 1996; Hebner *et al.*, 2008). Related work shows that nectins and NECL-5, as well as the integrin  $\alpha_5\beta_3$  and platelet-derived growth factor receptor, are involved in contact inhibition of cell movement and proliferation (Takai *et al.*, 2008). Other recent results directly related to the analysis in Sections 2 and 3 of this manuscript will be discussed there.

**Angiogenesis—**Initially, solid tumors are avascular *i.e.,* they do not have their own blood supply, and rely on diffusion from the surrounding vasculature to supply oxygen and nutrients and to remove waste products. As the tumor grows, nutrient demand increases until the flux of nutrients through the surface of the tumor is too small to supply the entire mass of cells. A necrotic core of dead cells may develop at the center and eventually the tumor stops growing and reaches a steady state size of  $\sim$ 1–3 mm, in which the number of dying cells counterbalances the number of proliferating cells. Growth can resume only if the tumor becomes vascularized *i.e.,* if it becomes permeated with a network of capillaries. An early response of tumor cells to hypoxia (oxygen deprivation) is the expression of genes that code for tumor angiogenic factors (TAFs), primarily vascular endothelial growth factor (VEGF) and basic fibroblast growth factor (bFGF; also called FGF-2), that are used to induce a nearby vessel to grow new capillaries to vascularize the tumor through a process called angiogenesis. These growth factors diffuse from tumor cells to the nearby primary vessels, and initiate activation of endothelial cells that line the blood vessel walls, inducing them to proliferate and migrate chemotactically towards the tumor. This results in the creation of a new capillary network that extends from a primary vessel into the growth-factor-secreting tumor, thereby bringing essential nutrients to the tumor and providing a shorter route for the spread of cancer cells to other parts of the body (Folkman, 1971). A number of comprehensive reviews of the biological background and mathematical models of angiogenesis are available (Mantzaris *et al.*, 2004; Roose *et al.*, 2007; Lowengrub *et al.*, 2010).

**Invasion—Cell-cell interactions modulated by cadherins, a family of**  $Ca^{++}$ **- binding** transmembrane glycoproteins that interact with members of the same type on adjacent cells, are critical for tissue formation and homeostasis. As with integrins, cadherins interact with the cytoskeleton via adapter proteins, and are an integral part of what are called adheren junctions between cells. These junctions encircle each cell in a belt-like structure that contains myosin II and tropomyosin. The tension created by these belts stabilizes tissues, and maintains their integrity. The first stage of single-cell invasion involves detachment of epithelial cells from the primary tumor by loss of expression or function of the adhesion molecule E-cadherin, which leads to loss of connections with neighboring cells and reorganization of the actin cytoskeleton into actin stress fibers anchored to the focal adhesion complexes that are essential for traction during cell migration. The downregulation of E-cadherin leads to release of soluble *β*-catenin, which in turn activates the expression of c-Myc, the oncogenic transcription factor. These cells, which are called mesenchymal cells, also secrete ECM proteases and exhibit increased expression of extracellular matrix proteins and their receptors, which characterizes the migratory phenotype. Ultimately expression of epithelial genes is lost and there is new or elevated expression of mesenchymal markers such as vimentin, N-cadherin and fibronectin. Collectively the genetic and epigenetic changes involved constitute the epithelialmesenchymal transition (EMT), and clearly not all cells in a migrating mass have to undergo the EMT. In some contexts the cells differentiate further into the specialized contractile myofibroblast cell type that expresses *α*-smooth muscle actin and secretes various proteases and cytokines.

Cancer cells invade the surrounding tissue either as individuals or as small groups of cells, and may secrete enzymes that degrade the ECM to facilitate passage of cells. Migration is to nearby vessels (if the tumor is vascularized cells may enter the circulatory system directly) or to the lymph system. In the former case it may involve chemotaxis to attractants released by nearby stromal cells in response to stimuli from the tumor. For example, it has been shown that invasion and metastasis involve a paracrine signaling loop between tumor cells and host macrophages using colony-stimulating factor (CSF-1) produced by the former and epidermal growth factor produced by the latter. Tumor cells secrete CSF-1 and sense EGF, whereas the macrophages secrete EGF and sense CSF-1 (Green *et al.*, 2009). (*cf.* Figure 4.) Similarly, in breast cancer macrophages are recruited to the tumor by expression of tumorderived chemotactic signals, where they stimulate tumor cell migration and invasion by secretion of chemotactic signals such as EGF.

Movement is a very complex process that involves the spatiotemporal control and integration of a number of sub-processes, including the transduction of chemical or mechanical signals from the environment, intracellular biochemical responses, and translation of the intra- and extracellular signals into a mechanical response (Mitchison & Cramer, 1996; Sheetz *et al.*, 1999). Four major stages are involved in the mechanical response. **(1)** Extension of directed protrusions (lamellipodia, filopodia, or pseudopodia) at the leading edge. The force for this results from localized polymerization of monomeric actin (G-actin) into cross-linked networks of actin filaments (F-actin) in lamellipodia or bundles of filaments in filopodia or pseudopodia. **(2)** Anchoring of protrusions to the substrate or the ECM via adhesive complexes, which serve as sites for force transmission to the substrate (Soll, 1995; Small *et al.*, 2002). In cells such as fibroblasts, these complexes, which are called focal complexes (FCs), can mature into larger FAs that serve as 'traction pads' over which the cell body moves (Small, 1989; Friedl & Wolf, 2003). **(3)** Next, depending on the cell type, actomyosin filaments (complexes of F-actin and the motor protein myosin II) contract at the front, in the perinuclear region, or at the rear, to move the cell body forward. **(4)** Finally, cells release attachments at the rear (Pollard *et al.*, 2000).

Force transmission to the ECM via FCs and FAs involves integrin binding to extracellular ligands, force-modulated receptor clustering, and interactions with cytoskeletal structural and signaling proteins (Hynes, 2002; Bershadsky *et al.*, 2003; Bershadsky *et al.*, 2006). On solid substrates FCs appear beneath the leading edge of the cell (Smilenov *et al.*, 1999) and may or may not mature into oriented FAs, depending on the cell type and the substrate. The standard model for the development of FAs involves integrin-ligand binding followed by strengthening of the attachment (Lotz *et al.*, 1989). The strengthening arises from increases in cell-substrate contact area due to spreading, from receptor recruitment and clustering at FAs, and from interactions with the cytoskeleton to distribute the forces across bound receptors. Growth of FAs involves positive feedback, since FA size is proportional to the force applied to it by the cell (Balaban *et al.*, 2001), and FAs grow in the direction of the applied force, even in the absence of stress fibers. *In vivo* these adhesions act as mechanotransducers that adjust their size in proportion to the stiffness of the ECM and the force applied to them. Moreover, stress is necessary for the development of FAs, because inhibition of myosin II via over-expression of a myosin ATPase inhibitor blocks the maturation of FCs into mature FAs (Helfman *et al.*, 1999; Bershadsky *et al.*, 2003). FAs are stationary in motile cells but slip centripetally in stationary cells (Smilenov *et al.*, 1999), and thus the integrated mechanical system of networks and adhesion sites may have multiple stable states corresponding to macroscopic motile or stationary states of a cell.

Cells are quite adaptable to their environment, and other modes of locomotion are possible. It is known *e. g.,* that leukocytes can move up to 100 times faster than mesenchymal and epithelial cell types, probably by using frequent shape changes characteristic of amoeboid

cells (Pittet & Mempel, 2008). Recently it has been shown that integrin-mediated adhesion is only needed to pass through barriers like the endothelial layer, and that migration through the ECM can be adhesion-independent (Lämmermann *et al.*, 2008). After a quadruple knockout of all the integrins expressed by dendritic cells, it was found that these cells move in 3D collagen gels and *in vivo* by extension of the anterior actin network of the cell, in concert with actomyosin contractions of the trailing edge, to move the rigid nucleus through narrow spaces. In essence it appears that these cells 'swim' by a controlled sequence of shape changes, but it remains to be seen if some minor adhesion molecules were involved (Friedl, 2010).

#### **1.3 An overview of the modeling and computational issues**

The sequence of steps in the progression from normal cell to cancer cell involves a hierarchy of time and space scales, and the complexity of the processes involved precludes a unified model that incorporates all the sub-processes. We describe some of the modeling and computational issues raised and the main types of models for the sub-processes.

- **•** Models of progression from a single mutation to a 'viable' neoplasm. The early stages of cancer development are certainly stochastic, whether at the level of mutations in normal cells or at the level of survival of transformed cells. At present we have no information on the survival of individual transformed cells *in vivo*, and thus we cannot predict the probability of generating a successful neoplasm. Moreover, while population means are relevant at that level, they are of little value at the level of individual realizations without further knowledge of the distribution. A review of many of the models formulated in the past 50 years appears in Little (2010).
- **•** Integration of signaling networks As described earlier, there is cross-talk between signal transduction networks for growth factors and other cytokines, and for mechanical influences. Kinetic data is sparse in all these systems, and thus it is important to understand the qualitative effects of these interactions and the sensitivities of the outcome to changes in the signal levels, the strength of interactions, and the kinetic parameters. In particular, a major unknown factor is the effect of force on gene expression and how to model transduction through the focal adhesions and the cytoskeleton. Again one can expect a diversity of effects, as exemplified by just two cases, one in which stress affects apoptosis via the mitochondria (Cheng *et al.*, 2009) and the other in which stress affects the balance between two antagonistic transcription factors that govern the expression of the VEGF receptor (Mammoto *et al.*, 2009).
- **•** Another aspect of signaling concerns the indirect interactions between signaling networks in different, spatially-separated cell types in the local environment. This 'action-at-a-distance' brings in the role of transport through the intervening tissue and the effects of inhomogeneity and anisotropy on transport. For example, tumors frequently recruit macrophages (TAMs) and interact with TAFBs via growth factor signaling networks. Tumors may also induce stiffening of the surrounding tissue, but this could potentially impede transport and thus reduce interaction with macrophages and fibroblasts. In the brain, anisotropy of the surrounding ECM and astrocyte networks plays an important role in the growth of tumors.
- **•** Many existing models of tumor growth have focused on the transport of nutrients and mechanical properties, but little has been done to incorporate both signaling networks and cell-cell interactions into the continuum models. One aspect of this is discussed in Section 3, where a hybrid model is used. As noted earlier, after tumor spheroids reach a certain size dependent on local conditions, growth occurs

primarily in a shell at the outer boundary of the tumor. This makes it feasible to use a hybrid model, in which proliferating cells at the boundary retain their identity, whereas cells in the interior are effectively homogenized and treated as a continuum. This allows for changes in adhesive properties, metabolic state and other characteristics at the individual cell level in regions where it is likely to be most important, while retaining the computational advantage of a continuum description for both the interior of the tumor and the exterior tissue. What is lacking to date is a detailed analysis of the algorithms used heretofore (Kim *et al.*, 2007) and improvements in the computational implementation of the algorithms. Furthermore, more work is needed on continuum models of tissues and on methods for homogenizing a multiphase description that embeds cell-level properties into the constitutive relations for the continuum (Macklin *et al.*, 2009; Preziosi & Tosin, 2009; Lowengrub *et al.*, 2010).

- **•** The early stage of invasion that involves the EMT has not been modeled in detail, but this is a critical step. Here a hybrid model of the type described in Section 3 is useful because the effects of changes in cell-cell adhesion and intracellular mechanics can be incorporated. Cellular automata models can also be useful, but there is difficulty in properly incorporating mechanics into such models, and as we have seen above, mechanics plays a major role at this stage.
- **•** Modeling of movement of single cells and small groups of cells through the ECM, both of tumor cells and the fibroblasts and macrophages in the stroma surrounding a tumor, is still in its infancy. However, understanding how to do this is important for predicting how to subvert metastasis. A great deal of attention has focused on the movement of cells on well-defined 2D substrates, but the cell morphology and the interaction with the environment can be very different in 3D. In fact, as we noted previously, cells in the ECM can move even in the absence of integrins, *i.e.,* in the absence of the primary modulator of cell-ECM interactions. We suggested that cells swim under these circumstances, but there is little known about the efficiency of movement or even what signals induce the sequence of shape changes that produces translocation. Inhomogeneity and anisotropy of the surrounding tissue play an important role in determining how cells move and tumors grow and spread, especially in the brain. Detailed models of single cell motility have been used to predict the effects of substrate properties on cell speed (DiMilla *et al.*, 1991; Gracheva & Othmer, 2004; Stolarska *et al.*, 2009) in 2D, and less detailed cell-based models of tissues have been used to predict movement of cellular aggregates such as the *Dictyostelium discoidium* slug (Palsson & Othmer, 2000; Palsson, 2008) and to understand how forces are transmitted through a 3D moving aggregate (Dallon & Othmer, 2004). However there are as yet no satisfactory models of movement in 3D that account for local mechanical interactions of the ECM and remodeling of it, via either stress effects or secreted proteases. Continuum models based on kinetic equations have been developed ((Painter, 2009) and references therein), but much remains to be done to embed cell-level behavior into the continuum equations.
- **•** Integration of molecular and cell-level behavior into population- and continuumlevel descriptions. To date most models evade this issue by simply postulating constitutive equations for material behavior, but more quantitative predictions from models will only be possible if they reflect the molecular, cell and tissue properties with greater fidelity. When constitutive relations that better reflect these lowerlevel properties and behaviors become available, one can envision detailed models of a growing tumor and the surrounding microenvironment, including the various embedded cells in the stroma, so as to quantitatively study the role of mechanics,

transport of nutrients, feedback loops between tumor cells and stromal cells, and cell movement (Preziosi & Tosin, 2009).

# **1.4 An overview of the paper**

It is clear from the foregoing that the interactions between a tumor and its microenvironment plays a critical role in the transition from benign or pre-malignant tumor to cancer. In the remaining sections we treat two aspects of these interactions. In the following section we develop a continuum model for mechanics and nutrients that we use to quantify the effects of the material properties of the surroundings on the growth of tumors, and we compare our predictions with experimental observations. In Section 3 we introduce a hybrid model for breast cancer that incorporates signaling from stromal cells to tumor cells in addition to the mechanical effects of the environment. There we model tumor cells using a cell-based model and the surrounding tissue as a continuum.

# **2 A continuum approach to the effect of stress on tumor growth**

As was described earlier, extracellular mechanical stresses can be transmitted to the cytoskeleton via integrins and thereby affect growth and gene expression. In particular, Helmlinger *et al.* (1997) were amongst the first to show experimentally that compressive stress in a tumor reduces its growth rate. When a tumor spheroid was grown in a sufficiently large agarose gel environment, the spheroid grew isotropically and reached an equilibrium size that scales inversely with the stiffness of the agarose. When an initially spherical tumor was embedded in a glass capillary tube 1 mm in diameter and 1 cm long, the mechanical properties of the surrounding medium determined whether or not growth was isotropic. When grown in a free suspension in the capillary, growth was isotropic up to a diameter of  $\sim$ 500  $\mu$ m, when the experiment was terminated. In contrast, when the capillary contained 0.7% agarose gel the tumors were oval-shaped with an aspect ratio of approximately 2:1 when the major axis was less than about  $450 \mu m$ . That this anisotropic growth is due to the anisotropic stress distribution in the gel was established by showing that tumors removed from the tube subsequently grew isotropically.

More recent work has confirmed these results and has also begun to elucidate the effects of mechanical stress on intracellular kinetics and gene expression involved in the transformation of normal cells, and on the proliferation and apoptosis of tumor cells. Koike *et al.* (2002) showed that highly invasive AT3.1 carcinoma cells do not form spheroids when grown in free suspension, but do when grown in agarose. They also showed that the size of the spheroids is inversely proportional to the agarose stiffness. These cells do not express Ecadherin, which may account for the fact that they do not form spheroids in free suspension. However, when grown in a gel the reactive stress induces the production of hyaluronan, an adhesion molecule found in connective tissue and believed to aid progression of malignant tumors (Park *et al.*, 2008; Gotte & Yip, 2006), which may facilitate growth of tumors as spheroids when under stress. Concerning apoptosis, Cheng *et al.* (2009) showed that it is the compressive mechanical stress, not nutrient availability, that leads to an increased rate of apoptosis in mammary 67NR carcinoma cells. These results are opposite those of Helmlinger *et al.* (1997), who showed that increased mechanical stress decreases the apoptotic rate. The difference may stem from different packing arrangements of cells in different cell lines, and if confirmed in other experiments it precludes the possibility of assigning unique effects of stress on tumor growth.

In this section we describe a continuum framework for modeling the mechanics of a growing tumor so as to investigate the combined effects of nutrient supply, mechanical stresses, and geometric constraints on tumor growth in three dimensions. There are numerous mathematical models describing tumor growth, all of which are reviewed in one

of Araujo & McElwain (2004); Rejniak & McCawley (2010); Kim *et al.* (2007) or Lowengrub *et al.* (2010). We discuss four of these that pertain to the experiments of Helmlinger *et al.* (1997) and Cheng *et al.* (2009). Chen *et al.* (2001) treat the tumor as a two phase mixture, wherein one phase represents the cellular material and the other represents the extracellular fluid. The agarose is treated as a hyperelastic solid and growth is incorporated by specifying a nutrient dependent growth rate of the tumor/agarose interface. Ambrosi & Mollica (2004) treat the tumor and surrounding agarose as an elastic material and incorporate tumor growth using a multiplicative decomposition of the deformation gradient. Roose *et al.* (2003) describe the tumor and agarose as a two-phase poroelastic material wherein fluid movement is governed by Darcy's law, while the solid phase is treated as a hypoelastic material. The residual stress due to the growth of the tumor is incorporated via an effective prestress in the hypoelastic constitutive equation. The radial component of displacement predicted by this model compares qualitatively with their experimentally-measured radii for MU89 melanoma tumor spheroids. All of these mathematical models assume spherical symmetry, which reduces them to one dimension and thus precludes analysis of anisotropic growth.

Kim *et al.* (2007) describe a two-dimensional hybrid discrete-continuum model in which cells in the proliferating layer of the tumor spheroid are modeled by discrete deformable ellipses, each of which can grow and divide. The mechanical properties of each axis of the ellipse are described by viscoelastic spring-dashpot systems, and the deformation of the cellular layer is coupled to the deformation of two continuum regions, one that represents the quiescent and necrotic regions in the tumor interior, and one external to the proliferating zone that represents the surrounding agarose. These authors predict the dependence of the size of the necrotic core, the quiescent region, and tumor on agarose stiffness and nutrient supply.

Here we develop and solve a three-dimensional continuum model of tumor growth and use it to investigate the effects of agarose gel inhomogeneities and other factors on tumor growth. We treat the tumor and surrounding agarose as a single-phase hypoelastic material, which for small strains, is equivalent to linear elasticity. While a variety of constitutive models for the material properties of tumor have been used, most soft biological tissues, including tumors, exhibit viscoelastic material properties (Fung, 1993; Sinkus *et al.*, 2005), and for large strains hypoelastic materials dissipate energy, which reflects a viscoelastic response (Olsen & Bernstein, 1984; Mihailescu-Suliciu & Suliciu, 1979). Agarose has been shown to exhibit a fairly complicated rheology and has been generally treated as an elastic material (Normand *et al.*, 2000). Therefore, modeling the tumor as a hypoelastic material is a reasonable assumption, and we do this here. Because the tumor and agarose deformations can be quite large, hypoelastic constitutive equations lead to computational algorithms with better numerical properties, because it is not necessary to relate the current configuration to a fixed reference configuration.

#### **2.1 The mathematical model**

**2.1.1 The evolution equations for nutrients—**We assume that transport of nutrients occurs via diffusion and advection due to growth. Thus one can in general describe the evolution of nutrient profiles with a system of reaction-diffusion equations containing an advective term. The coupling of nutrient evolution to the momentum equation given later is via the advective velocity, whereas the reverse coupling enters through the growth term and its effect on the deformations. The general form the *i*<sup>th</sup> component of this reaction-diffusion system is

$$
\frac{\partial c_i}{\partial t} + \nabla \cdot (c_i \mathbf{v}) = D_i \nabla^2 c_i + R_i(\mathbf{c}).
$$
\n(1)

Here  $c_i$  is the concentration of the *i*th nutrient,  $v = du/dt$  is the velocity (where *u* is the displacement), and  $D_i$  is the diffusion coefficient. The function  $R_i$ (c) describes the net rate of production of the nutrient, which is fixed by the reactions for its production, uptake and utilization.  $R_i$  depends on the vector of nutrient concentrations  $\mathbf{c} = [c_1, c_2 \dots]$  since in general it is possible that reactions of the nutrients with one another affects the uptake or production rates. We assume that these species occur in small enough quantities so that their interconversion does not affect the momentum balance of the bulk material.

In most experimental systems involving the growth of multicell tumor spheroids the primary nutrients are oxygen and glucose. It has been shown experimentally that an increase in the glucose concentration decreases oxygen uptake (the Crabtree effect), and converesly, an increase in the oxygen concnetration decreases the glucose uptake (the Pasteur effect) (Mueller-Klieser *et al.*, 1986; Casciari *et al.*, 1992b). However, in both cases an increase in the concentration of one nutrient has only a small effect on the uptake of the second, and to simplify the model for the numerical experiments done here we consider oxygen as the only nutrient. For some of the experiments described earlier it is known that the nutrient levels do not limit the tumor growth, and thus we do not expect to find necrotic cores in the tumor.

Previous results due to Casciari *et al.* (1992b) and to Freyer & Sutherland (1985) lead to a Michaelis-Menten form for the consumption of oxygen, and thus the evolution of the oxygen concentration is described by

$$
\frac{\partial c}{\partial t} + \nabla \cdot (cv) = D_{a/t} \nabla c - \varphi(\mathbf{x}) \frac{Ac}{c+k}.
$$
\n(2)

Here *c* is the concentration of oxygen, and *A* and *k* are empirically determined paramters (Casciari *et al.*, 1992b).  $\varphi(\mathbf{x})$  is the characteristic function of the tumor:  $\varphi(\mathbf{x}) = 1$  inside the tumor and  $\varphi(x) = 0$  in the agarose, and the subscripts on  $D_{a/t}$  reflect the fact that the diffusion coefficient is different in the tumor than in the surrounding agarose. The oxygen evolution is coupled to the mechanics through the velocity *v*, which is found from the momentum balance equations developed in the following sections.

**2.1.2 Deformation and growth—**Various models of growing biological tissues incorporate growth by postulating a multiplicative decomposition of the deformation gradient

$$
F = I + \frac{\partial u}{\partial X}
$$

where *X* represents a material coordinate point, into a part that describes growth and a part that describes deformations due to incompatible local growth and any externally applied tractions or body forces. Thus the deformation gradient is written as  $\mathbf{F} = \mathbf{F}^P \mathbf{F}^G$ , where  $\mathbf{F}^G$  is the growth component and *FP* is the passive component (Skalak, 1981; Rodriguez *et al.*, 1998; Taber & Perucchio, 2000). In models of hypoelasticity the material is effectively incrementally elastic in that the configuration at time *t* is the reference configuration for the material at time  $t + \delta t$ , where  $\delta t$  is suitably small. Because deformations are small in each

time increment,  $F - I$  is small. From this it follows, by neglecting nonlinear terms and differentiating the result with respect to time, that the multiplicative decomposition of *F* leads to an additive decomposition of the symmetric part of the rate of deformation tensor

$$
D = \frac{1}{2} \left( \frac{\partial v}{\partial x} + \left( \frac{\partial v}{\partial x} \right)^T \right),
$$

where  $v(x, t)$  is the veloctity and x represents a spatial coordinate point. Thus

$$
D=D^P+D^G,\tag{3}
$$

where  $D<sup>P</sup>$  is the passive component of the rate of deformation gradient that is incorporated into the constitutive equation, and  $D^G$  is the growth component of *D* that depends on the local nutrient concentration and local stresses.

The experimentally-observed dependence of the volumetric growth rate on the local oxygen concentration has the form

$$
\overline{G}(c) = \frac{G_1 c}{c + G_2},\tag{4}
$$

where  $G_1$  and  $G_2$  are constant parameters (Casciari *et al.*, 1992b). We assume that tumor growth is isotropic, and thus the growth component of the rate of deformation tensor has the form

$$
D^G = G I. \tag{5}
$$

Here *G* is the overall growth rate (which will be related to  $\bar{G}$  later); it takes into account both nutrient concentrations and stress feedback. Anisotropic growth can be incorporated by appropriately modifying one or more diagonal and/or off-diagonal entries in *DG*.

**2.1.3 Momentum balance and constitutive equations—**We assume that the tumor and agarose are slightly compressible materials (Roose *et al.*, 2003) on which no body forces are acting. Since the tumor grows very slowly (approximately 1 *mm* in diameter over the course of one month), we also neglect all inertial effects. The momentum balance equation can therefore be expressed as

$$
\nabla \cdot \sigma = 0 \tag{6}
$$

where  $\sigma$  is the Cauchy stress tensor. We assume conservation of angular momentum, and thus  $\sigma$  is symmetric. The constitutive equation used to describe the agarose and tumor is given by

$$
\frac{d\sigma}{dt} - (\nabla v)^T \sigma - \sigma (\nabla v) = \mathbf{C} (\mathbf{D} - \mathbf{D}^G). \tag{7}
$$

The left-hand side of (7) is the Oldroyd time derivative, which ensures frame invariance of (7), *C* is a constant, fourth-rank Hooke tensor that depends on *E*, the Young's modulus of the material, and *ν*, the Poisson ratio. When the stress and rate of deformation tensors are written in Voigt form, *i.e.*,  $\sigma = [\sigma_{xx} \sigma_{yy} \sigma_{zz} \sigma_{yz} \sigma_{xz} \sigma_{xy}]^T$ , the Hooke tensor can be written as

$$
\boldsymbol{C} = \left[ \begin{array}{cccccc} C_1 & C_2 & C_2 & 0 & 0 & 0 \\ C_2 & C_1 & C_2 & 0 & 0 & 0 \\ C_2 & C_2 & C_1 & 0 & 0 & 0 \\ 0 & 0 & 0 & C_3 & 0 & 0 \\ 0 & 0 & 0 & 0 & C_3 & 0 \\ 0 & 0 & 0 & 0 & 0 & C_3 \end{array} \right],
$$
\n
$$
(4)
$$

where

$$
C_1 = \frac{E(1-\nu)}{(1+\nu)(1-2\nu)} \qquad C_2 = \frac{E\nu}{(1+\nu)(1-2\nu)} \qquad C_3 = \frac{E}{1+\nu}.
$$
\n(9)

We note that the stress depends only on the passive component of the rate of deformation, *i.e.,*  $\mathbf{D} - \mathbf{D}^G = \mathbf{D}^P$ , which allows for development of residual stresses if local growth rates are incompatible. If growth is uniform throughout a growing body on which there are no additional applied forces, then all stresses should be identically zero, but if local growth rates vary between adjacent material elements, residual stresses must develop for a body to remain continuous. The assumption that the stress depends only on  $D<sup>P</sup>$  allows for the formation of these stresses.

**2.1.4 Stress feedback—**To incorporate the effects of stress on the growth of the tumor, we include a stress feedback function in the overall volumetric growth rate. Following Roose *et al.* (2003) and Kim *et al.* (2007), we assume that the stress feedback is isotropic and depends linearly on the average bulk stress. This stress feedback is represented by

$$
f(\sigma) = \begin{cases} 1 - \beta(|\sigma_{xx} + \sigma_{yy} + \sigma_{zz}|)/3 & \text{for } \beta(|\sigma_{xx} + \sigma_{yy} + \sigma_{zz}|)/3 < 1\\ 0 & \text{for } \beta(|\sigma_{xx} + \sigma_{yy} + \sigma_{zz}|)/3 \ge 1, \end{cases}
$$
(10)

where  $\beta$  is a constant parameter representing the strength of the stress feedback. Furthermore, we assume that the overall volumetric growth rate depends multiplicatively on the nutrient-dependent and stress-feedback components, and therefore

$$
G(c,\sigma)=G(c)\cdot f(\sigma). \tag{11}
$$

In this formulation it is only the magnitude, not the sign, of the isotropic stress that affects growth. Said otherwise, compressive and tensile stresses contribute equally to the decrease of the growth rate. While it has not been established experimentally, it is plausible that only compressive stresses reduce the growth while tensile stresses do not, and it may be that

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(8)

shear stresses are also important, as in blood flow; both effects are easily incorporated, but even in the isotropic case the functional form of the dependence of growth on stress is not known. Moreover, it can be shown experimentally and mathematically that the bulk stresses inside an agarose-embedded, isotropically-growing tumor of convex shape are exclusively compressive.

#### **2.2 Computational results**

#### **2.2.1 The effect of stress on growth under spherically symmetric conditions—**

Experiments on spherical tumor growth involve seeding liquid agarose gels with single tumor cells at a seed density at which there is no interaction between the growing spheroids over the course of an experiment. Once the agarose solidifies, nutrient-rich culture medium is added to compartments above and below the disk-shaped, solidified suspension. The geometry of our numerical simulations is based on this experimental configuration.

We consider a single tumor spheroid growing in a solidified medium, which is significantly larger in the experimental setup than our computational domain, and we impose zero normal displacements on the exterior faces (*cf.* Figure 5). This reflects our assumption that the normal displacement decay occurs on a sufficiently small length scale to vanish at the boundaries of the computational domain, despite the fact that it is smaller than the experimental domain. For spherical growth we invoke reflective symmetry conditions to only simulate one-eighth of a tumor, and to retain the symmetry zero normal displacements are imposed on the three symmetry planes. We assume that the initial tumor radius is 0.1 *mm* and the length of one edge of the cubic domain is 0.4 *mm*. In the experiments each cell has a diameter of ≈ 20 *μm*, and thus there are approximately 5 cells along a radius of 0.1 *mm* of the tumor. In the Helmlinger *et al.* (1997) experiments, tumor growth starts at the single cell level, but it is computationally prohibitive to start at this level in the numerical experiments. Furthermore, begining with one cell would preclude treating the tumor as a single-phase continuum; a hybrid model of the type described later would be required. For this reason we start with a larger tumor and assume that all initial velocities and stresses are zero.

In addition to the conditions at the boundary of the domain, additional conditions must be satisfied at the tumor-agarose interface. Specifically, the displacements and surface tractions at this interface must satisfy the continuity conditions

$$
[[u]]=0, \qquad [[\sigma \cdot \mathbf{n}_t]]=0,\tag{12}
$$

where  $\left[ \cdot \right]$  represents the jump across the interface, and  $\mathbf{n}_t$  is the outer unit normal to the tumor at the tumor-agarose interface. The finite element implementation employed to solve the model equations automatically satisfies these and other interface conditions specified later.

Figure 5 also illustrates boundary conditions for oxygen diffusion and uptake. To retain symmetry, we assume that there is no flux of oxygen across the three faces of the domain that intersect the tumor. We impose no-flux boundary conditions on the lateral boundaries at  $x = 0.4$  *mm* and  $y = 0.4$  *mm*, and the boundary at  $z = 0.4$  *mm* corresponds to the nutrient medium, where we impose a fixed oxygen concentration of 0.2 *mol*/*m*<sup>2</sup> . In addition, the concentrations and normal diffusion fluxes across the tumor-agarose interface must be continuous. This is represented by the conditions

 $[|c|] = 0$ ,  $[|D_{a/t} \nabla c \cdot \mathbf{n}_t]| = 0$ .

We allow the oxygen profile, which evolves according to (2), to reach a steady state in the initial domain shown in Figure 5 before initiating tumor growth, since this occurs on a time scale that is short compared with that of tumor growth.

All parameter values used for the numerical simulations are given in Table 1. Whenever possible, we based our parameter values on experimental data or previous models. We chose our oxygen-dependent growth rate so that the tumor would reach size of approximately 1 *mm* in the course of 30 days if grown in free suspension. We chose the stress feedback parameter so that equilibrium radius of the tumor growing in 0.5% agarose is twice the original radius and so that the tumor approaches the equilibrium size at approximately 25 days of growth. All simulations were done using the finite element method with remeshing on Comsol Multiphysics®. All simulations were run until the rate of tumor growth decreased signficantly from its initial rate, which is approximately 0.13 *day*−<sup>1</sup> .

The evolution of the radius of the growing tumor is shown in Figure 6. As expected, the tumor reaches a smaller equilibrium size at an earlier time in the 1% agarose, as seen in Figure 6(c). In 1% agarose the tumor stops growing after about 10 days, but in 0.5% agarose it continues to grow, but with a decreasing rate.

The average bulk stress profiles (*i.e.*,  $(\sigma_{xx} + \sigma_{yy} + \sigma_{zz})/3$ ) in the 1% and 0.5% agarose gels at  $t = 25$  days are shown in Figure 7(a) and (b), respectively. The growth rate reaches a value of approximately 0.01 *day*−<sup>1</sup> when the bulk stresses internal to the tumor are approximately 0.08 *kPa*. While the computed radii compare well to experimental results, these stresses are approximately one order of magnitude smaller than those predicted by Roose *et al.* (2003), and two orders of magnitude smaller than those measured by Helmlinger *et al.* (1997). However, we expect the stresses computed here to be somewhat smaller than in experiments, because there tumor growth begins with a single cell, which results in larger relative deformations, and therefore larger stresses. Specifically, in the experiments described in Roose *et al.* (2003) tumor growth starts with a single cell, which is approximately 10 *μm* in radius, and equilibrium tumor size for 0.5% agarose is approximately 180 *μm*. Therefore, throughout the course of the experiment and their numerical simulation the tumor radius increases approximately 18-fold. In our computations for 0.5% agarose, the initial tumor has a radius of 100 *μm* and reaches an equilibrium size of approximately 200 *μm*. Hence the increase in radius is approximately 1/10 that in the experiment, and therefore it is to be expected that our computed stresses are approximately 10 times smaller than in the experiment. To circumvent using a large initial radius one could use a three-dimensional version of the hybrid model discussed later for the simuations presented here. This would allow us to begin with a single cell and then convert the growing tumor into a continuum when it reached the appropriate size. This would likely provide a more accurate stress approximation, and is part of our future work.

#### **2.2.2 The effect of stress on growth under spatially inhomogeneous**

**conditions—**Surprisingly, our attempt to replicate the capillary tube experiment of Helmlinger *et al.* (1997) does not result in tumor growth similar to that observed experimentally. We ran simulations, using the parameters and stress feedback described here in both 0.5% and 1% agarose, beginning with a tumor of initial radius 100 *μm* placed in the center of a capillary-shaped domain with a 300 *μm* radius and a total length of 1200 *μm*. In these simulations the tumor retains its spherical symmetry (data not shown). The radial growth profiles of the tumor in the capillary tube were similar to those illustrated in Figure

6(c), and we observed that level surfaces of constant non-zero bulk stresses remained concentrated in spherical shells surrounding the growing tumor. To illustrate this stress profile in a domain comparable to the domain used in our simulations of spherical tumor growth, we simulate a growing tumor in the domain depicted in Figure 5, but with the boundary condition  $\sigma \cdot \mathbf{n} = 0$  at  $z = 0.4$  *mm*. In other words, to represent conditions similar to those found in the capillary tube, rather than fixing the normal displacement at this boundary as before, we assume that the boundary can move but is traction free.

Figure 8 shows the displacement magnitudes and bulk stress profile in the domain at  $t = 25$ *days*, at which point the growth rate of a tumor growing in 1% agarose is approximately 5<sup>−4</sup> *days*−<sup>1</sup> . In simulations in which the top boundary is fixed, the magnitude of the displacement field is non-zero only in a small portion of the agarose surrounding the tumor (data not shown). However with a free top domain boundary, the displacements are larger at this boundary (Figure 8(a)), but the stress field is clearly concentrated near the tumor-agarose interface (Figure 8(b)). Helmlinger *et al.* (1997) and Cheng *et al.* (2009) also note that experiments show that non-zero stresses are concentrated in a small shell surrounding the growing tumor and then decay quickly to zero away from the tumor, and our numerical investigation confirms this. This indicates that the stress feedback is likely non-linear and/or non-isotropic, as is assumed by us and in other mathematical models (*e. g.,* Roose *et al.* (2003); Kim *et al.* (2007)). Nonlinear stress feedback may be such that small stress gradients are amplified interior to the tumor resulting in a much more inhomogeneous growth rate than occurs with a linear stress feedback. In addition, it is possible that the growth rate is not affected by bulk stresses, but rather the tumor tends to grow in the direction of least resistance, resulting in anisotropic growth. We also neglect the effects of the formation of a necrotic core or any other local modulations in material properties that may occur due to stresses, and these local modulations may have an affect on tumor growth rates (Paszek & Weaver, 2004). However, our simulations using a Poisson ratio of  $v = 0.42$  exhibited results similar to those shown in Figure 8, and therefore it is unlikely that the compressibility of the material causes the stress distribution to be localized to the periphery of the tumor (data not shown).

Helmlinger *et al.* (1997) note that it is not known how local modulation of the material properties of the surrounding tissue will affect the tumor growth, and here we investigate this computationally. We assume that the tumor is embedded in a very pliable agarose gel (with  $E = 0.1$  *kPa*) and directly adjacent to one side of the tumor is a rigid agarose gel with a elastic modulus of  $E = 1.0$  *kPa*. The setup of the simulation is as illustrated in Figure 5 with normal displacements at the top boundary fixed. However, the overall elastic modulus of the agarose is defined by the function

$$
E = \begin{cases} 0.1 \, kPa & \text{for } x \le 0.1 \, mm \\ 1 \, kPa & \text{for } x > 0.1 \, mm. \end{cases} \tag{14}
$$

While elasticity parameter values for agarose used in tumor experiments typically fall in the range of 0.15 *kPa* – 0.4 *kPa*, here we choose the values in (14) for agarose elasticity because they are still within a reasonable range and simultaneously illustrate the model's ability to capture experimentally-observed inhomogeneity in tumor growth. We note that the numerical setup here effectively resembles the experimental setup of Cheng *et al.* (2009) in which tumor growth leads to a crack in the surrounding agarose, which in turn results in the tumor growing primarily into the stress-free void generated by the crack (see Figure 5(b)).

A comparison of the radial component of the tumor in the  $y - z$  plane at  $x = 0$  to the radial component along the *x* axis is illustrated in Figure 9. Since the elastic modulus of the agarose increases as x increases, the tumor grows in the  $y -$  and  $z$ –directions at a faster rate than in the *x*-direction. The dependence of the length of the tumor radius in the  $y - z$  plane on the radial length of the tumor in the *x* direction can be described by the line  $y = 1.81x -$ 83.9. The ratio of the two lengths described by this line is similar to the ratio of the major and minor diameters of the tumor in the capillary tube experiment from Helmlinger *et al.* (1997).

Therefore, the model described here is able to capture the inhomogeneous deformations that have been observed experimentally, despite the fact that here the deformations are caused by inhomogeneity of material properties, while in Helmlinger *et al.* (1997) inhomogeneous growth is induced by the shape of the capillary. The bulk stress distribution at  $t = 7.5$  days is illustrated in Figure 7(c). We note here that due to the variable material properties, the bulk stresses are inhomogeneous in the tumor interior, which leads to variable growth rates within the tumor. Furthermore, this leads to the presence of shear stresses inside the tumor. Figure 10 shows the  $\sigma_{r\theta}$  shear stress component at the plane defined by  $z = 0$ . In this stress

component  $r = \sqrt{x^2 + y^2 + z^2}$  and  $\theta$  is the angle between the positive *x* axis and the ray defined by *r*. In the case of spherically symmetric tumor growth,  $\sigma_{r\theta}$  inside the tumor is zero to numerical accuracy. Therefore, inhomogeneous growth rates inside the tumor lead to nonnegligible shear stresses, which may impact local tumor growth rates. Endothelial cells that line blood vessels typically respond to shear stresses by increasing proliferation (see *e.g.,* (Shyu, 2009; Hudlicka & Brown, 2009)), and it is not clear whether shear stresses have a similar effect on tumor growth.

# **3 A model for ductal carcinoma** *in situ*

As in other tissues, the TGF-*β* family of growth factors regulates many cellular processes during both normal mammary gland development and during the initiation and progression of breast tumors. As described earlier, TGF-*β* inhibits cell cycle progression of epithelial cells, probably by down-regulation of factors such as c-Myc, that lead to arrest of the cell cycle in G1 and thereby control epithelial cell proliferation during gland development. Moreover, it also has a biphasic role in tumor progression: in early development of ductal carcinoma *in situ* (DCIS) it inhibits the outgrowth of tumors, but in later stages it can promote tumor progression by increasing tumor cell motility and altering the microenvironment. However, mutations in the TGF-*β* signaling pathways are relatively rare in breast cancers – instead there are more subtle changes in the balance between the growthinhibiting effect of TGF-*β* and the growth-promoting effects of other factors. These include regulation of the levels of transcriptional co-repressors or co-activators involved in the Smad pathway, and epigenetic regulation of critical steps in the progression to cancer (Hinshelwood *et al.*, 2007). Some of these are changes in stromal cells such as fibroblasts and macrophages that are induced by TGF-*β*, which suggests that the effects of TGF-*β* in the microenvironment, together with its roles in EMT and metastasis, stimulate cancer progression and overwhelm its effects as a tumor suppressor. The effect of the microenvironment on tumor growth via nutrient levels and other passive factors such as the tissue properties has long been recognized, but the active role of the microenvironment has gained attention recently (Gatenby & Gillies, 2008), as exemplified by the characterization of stromal fibroblasts as 'contracted farmers' used by tumors to prepare the microenvironment (Cheng & Weiner, 2003). This highlights the necessity of incorporating interactions between signaling networks within the local microenvironment into mathematical models of tumor growth and invasion, and in this section we develop one that enables us to study some of these interactions and their effects.

#### **3.1 Biological background**

Breast ducts are made of a layer of epithelial cells (ECs), a layer of myo-epithelial cells, and a layer of basal membrane, all surrounded by connective tissue that contains stromal cells such as fibroblasts and the extracellular matrix. The ducts have diameters of 80–90 *μm* in mice and 0.2–0.4 mm in humans (Franks *et al.*, 2003). In mice the ECs are roughly 10 *μm* in diameter, and thus 8–9 layers of ECs suffice to completely block a duct.

Under homeostatic conditions breast duct ECs secrete various growth factors, including TGF-*β*, and stromal fibroblasts secrete EGF, but the rates are balanced and growth is controlled. When a sufficient number of ECs inside a duct are transformed (which we designate as TECs), they proliferate in the duct and increase their secretion of TGF-*β* (Massague, 1998). The increased level of TGF-*β* in the stroma induces differentiation of fibroblasts into myofibroblasts and upregulates their secretion of EGF. This closes the paracrine positive feedback loop and can strengthen the feedback, since the increased EGF level can induce upregulation of Her2/Neu, a member of the EGFR family, which in turn strengthens signaling via the EGF pathway (Cheng & Weiner, 2003). This increase in EGF signaling disrupts the balance with the TGF-*β*-pathway that controls proliferation (see Figures 12 and 2(c)). Patients with breast cancer often show upregulated Her2/Neu, making Her2/Neu a common target for treatment (Bhowmick *et al.*, 2004).

There are also other effects of stromal fibroblasts on tumor growth. When ECs are transformed to TECs and a carcinoma develops, the number of fibroblasts may increase more than five-fold and these stromal fibroblasts secrete large amounts of the ECM in addition to EGF (Bissell & Radisky, 2001). Fibroblasts from normal tissue may even have an inhibitory effect on growth while those cultured from tumors stimulate cell growth as described above (Adams *et al.*, 1988; Bhowmick *et al.*, 2004), particularly in breast tissue (Samoszuk *et al.*, 2005). Recently Yashiro *et al.* (2005) demonstrated that tumor size is significantly increased in mice when breast cancer cells are co-inoculated with breast fibroblasts. In addition, before TECs begin to degrade the duct wall and migrate into the surrounding tissue, they first fill in the duct by proliferating. A sufficient tumor mass induces a response in inflammatory cells such as macrophages, which appear to detect TECs as a wound (Matrisian, 1999). Thus fibroblasts, myofibroblasts and macrophages in the microenvironment surrounding a tumor play an important role in tumor growth and metastasis by enhancing local signaling and by modifying the ECM locally.

Franks *et al.* (2005) developed a continuum model of comedo ductal carcinoma *in situ* of the breast. Tumor cells are subject to mechanical and nutritional stresses by high pressures and oxygen deprivation, and experience expansion when the duct wall deforms. They postulate such stresses may stimulate the cells to produce proteolytic enzymes to degrade the duct wall, therefore making it more compliant and prone to penetration by the tumour cells. They found that mechanical stress is likely the dominant mechanism, with the wall deforming most at the centre of the duct. These authors do not treat the interactions between stromal cells and tumor cells.

In the following sections we introduce a 2D hybrid model describing the interactions amongst TECs, fibroblasts and myofibroblasts via EGF and TGF-*β*. Rather than treating the entire domain as either a continuum or using only a cell-based model, we adapt a hybrid approach in which a cell-based model is used to describe the dynamics of TECs in the duct and ECs on the interface between stroma and the duct, and to describe the dynamics of the sinks and sources that arise from the fibroblasts and myofibroblasts in the stromal tissue. The surrounding stroma is modeled as a viscoelastic continuum. We begin with a simplified model for the dynamics of EGF and TGF-*β* in a single cell to illustrate some of the major factors involved in the interaction between a TEC and the stroma.

# **3.2 The intracellular dynamics of the EGF-TGF-***β* **signaling pathways**

The intracellular signaling model is based on the following assumptions: (i) TGF-*β*-occupied receptors phosphorylate Smads, (ii) EGF-occupied receptors activate a molecule that binds to either form of the Smads, (iii) the proliferation rate is a monotone decreasing function of the concentration of phophorylated Smad. The symbols and their definitions are given in Table 2. The reactions involved in the model are as follows.

**•** Ligand binding:

$$
T + R_1 \frac{\sum_{k_1^-}^{k_1^+} \overline{R_1 T}}{\sum_{k_1^-}^{k_1^+} \overline{R_1 T}} \quad E + R_2 \frac{\sum_{k_2^+}^{k_2^+} \overline{R_2 E}}{\sum_{k_2^-}^{k_2^+} \overline{R_2 E}}
$$

**•** Smad reactions and activator reactions

$$
S + \overline{R_1 T} \overset{k_T^+}{\underset{k_T^-}{\rightleftharpoons}} \frac{R_T^0}{S R_1 T} \overset{k_P^0}{\longrightarrow} \overline{R_1 T} + S_p
$$
\n
$$
A + \overline{R_2 E} \overset{k_E^+}{\underset{k_E^-}{\rightleftharpoons}} \overline{R_2 E} \overset{k_P^0}{\underset{k_E^-}{\rightleftharpoons}} \overline{R_2 E} + A^*
$$
\n
$$
A^* + \left\{ \begin{array}{c} S \\ S_p \end{array} \right\} \overset{k_B^+}{\underset{k_B^-}{\rightleftharpoons}} \left\{ \begin{array}{c} \overline{A^* S} \\ \overline{A^* S_p} \end{array} \right\}
$$
\n
$$
A^* \overset{k_A}{\longrightarrow} A \quad S_p \overset{k_S}{\longrightarrow} S.
$$

Here overlines denote complexes.

#### **Evolution Equations—**

$$
\frac{d}{dt}\overline{R_1T} = k_1^+T \cdot R_1 - k_1^-\overline{R_1T} - k_r^+S \cdot \overline{R_1T} + (k_r^- + k_\tau^0)\overline{SR_1T}
$$
\n
$$
\tag{15}
$$

$$
\frac{d}{dt}\overline{R_2E} = k_2^+E \cdot R_2 - k_2^-\overline{R_2E} - k_E^+A \cdot \overline{R_2E} + (k_E^- + k_E^0)\overline{AR_2E}
$$
\n(16)

$$
\frac{dS}{dt} = -k_r^+ S \cdot \overline{R_1 T} + k_r^- \overline{S} \overline{R_1 T} - k_\beta^+ A^* \cdot S + k_\beta^- \overline{A^* S} + k_s \cdot S_p \tag{17}
$$

$$
\frac{d\overline{SR_1T}}{dt} = k_T^+ S \cdot \overline{R_1T} - k_T^-\overline{SR_1T} - k_T^0\overline{SR_1T}
$$
\n(18)

$$
\frac{dA}{dt} = -k_E^+ A \cdot \overline{R_2E} + k_E^- \cdot \overline{AR_2E} + k_A A^*
$$
\n(19)

$$
\frac{d\overline{AR_2E}}{dt} = k_E^+ A \cdot \overline{R_2E} - (k_E^- + k_E^0) \overline{AR_2E}
$$
\n(20)

$$
\frac{dA^*}{dt} = k_E^0 \overline{AR_2E} - k_B^+ A^*(S + S_p) + k_B^-(\overline{A^*S} + \overline{A^*S_p}) - k_A A^*
$$
\n(21)

$$
\frac{dS_p}{dt} = k_p^0 \overline{SR_1T} - k_s S_p - k_p^+ A^* \cdot S_p + k_p^- \overline{A^* S_p}
$$
\n(22)

$$
\frac{d\overline{A^*S}}{dt} = k_B^+ A^* \cdot S - k_B^- \overline{A^*S}
$$
\n(23)

$$
\frac{d\overline{A^*S_p}}{dt} = k_B^+ A^* \cdot S_p - k_B^- \overline{A^*S_p}
$$
\n(24)

with conservation relations

$$
\frac{R_1 + \overline{R_1T}}{R_2 + \overline{R_2E} + \overline{AR_2E}} = R_{10}
$$

$$
S+S_{p}+\overline{S}\overline{R_{1}T}+\overline{A^{*}S}+\overline{A^{*}S_{p}}=S_{0}
$$
  

$$
A+A^{*}+\overline{AR_{2}E}+\overline{A^{*}S}+\overline{A^{*}S_{p}}=A_{0}.
$$

and initial condition (6.3, 1.1, 3.2, 0.4, 0.16, 2.7, 0.1, 6.7, 5.8, 25.5).

The rate constants and other parameters that appear in these equations are given in Table 3.

Figure 13 shows experimental and numerical results for EGF-TGF-*β* control over TEC growth. Kretzschmar *et al.* (1999) found that the Ras pathway inhibits the TGF-*β*-controlled anti-proliferation effect, as shown in Figure 13(A). Receptor-activated Smad2 or Smad3 translocates to the nucleus and forms a transcriptional complex on the activin/TGFb response element (ARE). Strong (up to 14-fold) activation of an ARE reporter construct (A3-Luc) by TGF-*β* was observed in nontumorigenic EpH4 cells (squares in Figure 13(a)), but only weak activation (2-fold) of A3-Luc by TGF-*β* was found in the v-Ha-Rastransformed derivative, EpRas cells (triangles in Figure 13(a)), suggesting impaired Smad signaling. We did not model the detailed steps in the process, but rather, we assumed that pSmad represents a measure of activity similar to that of the ARE reporter construct (A3- Luc). Our model for the intracellular dynamics predicts that the EGF-Ras pathway can block the TGF-*β*-Smad pathway and lead to a reduced pSmad concentration and increased proliferation (Figure 13(B)). To compare the results, we assume that the EGF level is low under normal conditions, and that a high EGF level represents hyperactive Ras mutant cells (EpRas).

#### **3.3 Mechanical effects on tumor growth**

It is believed that mechanics plays a large role in ductal breast tumors. Healthy breast ducts and their surrounding stroma respond very sensitively to changes in compressive and tensile

stresses to facilitate lactation. Paszek & Weaver (2004) note that mammary epithelial cells that have undergone a cancerous transformation also respond to stresses intracellularly by possibly increasing FGF and VEGF signalling to promote their proliferation and by increasing production of MMPs to promote invasion. They also note that a generally stiff breast tumor is interspersed with small regions that are significantly more compliant, and it may be that such material inhomogeneities contribute to breast cancer progression.

Since inertial effects are negligible for the slow movements involved in growth and division, there is no net force on ECs, and as long as the duct is not occluded there will be little mechanical feedback from the surrounding tissue. However, if proliferation of TECs leads to complete occlusion of the duct the tumor cells will begin to experience a reactive force from the surrounding tissue, which has been called the 'reciprocal tissue resistance force' (Paszek & Weaver, 2004). This reactive force can alter the cytoskeleton, open mechanosensitive channels, and lead to altered gene expression (Helmke & Davies, 2002; Chen *et al.*, 2004). The stiffness of the surrounding tissue is increased after EC transformation (Krouskop *et al.*, 1998) in an inhomogeneous manner, and differentiated and highly contractile myofibroblasts also contribute to stiffening by reorganizing collagen fibrils (Paszek & Weaver, 2004). The effects of these forces interact with those of many soluble factors in the ECM, leading to homeostasis in normal tissue, but it is not clear at present what type of perturbations are necessary to initiate malignant transformation (Paszek & Weaver, 2004). In the remainder of this section, communication between fibroblasts/myofibroblasts and TECs is mediated by soluble growth factors (EGF and TGF-*β*), and mechanical interaction between stroma and growing TECs inside the duct is incorporated in the model. Mechanical stresses influence growth in a phenomenologically-specified manner in the current model, but future work will address the effects of mechanical stresses on intracellular kinetics and other modes of interaction. We begin in the next section with a description of the cell-based component of the hybrid model.

**3.3.1 The cell-based component—**There are four different kinds of cells involved – ECs, TECs, fibroblasts, and myofibroblasts. ECs and TECs are modeled as in the KSO model (Kim *et al.*, 2007) and a fibroblast or myofibroblast is considered as a point sink/ source. The KSO model, which is based on an earlier model for the mechanical behavior of cells and tissues under stress (Dallon & Othmer, 2004), addresses three major aspects (i) how an individual cell reacts to forces on it, (ii) how cells interact mechanically with their surroundings, and (iii) how growth and division are described, and how stress affects growth. The cells are treated as oriented ellipsoids whose cytoplasm is an incompressible, viscoelastic solid. In the absence of growth their volume is constant under all deformations, and growth is included in series with the active response and the passive forces.

In the KSO model a cell can grow and divide into two daughter cells according to the algorithm given there, which incorporates an intrinsic cell volume  $V_0$  that cells attain immediately after division, an intrinsic cell-cycle time *τ<sup>c</sup>* , and rules for how a cell divides under a given stress. Since the effect of stress is isotropic, all cells relax to a spherical shape, whatever their initial shape, in the absence of external forces. In the absence of nutrient or stress limitations cells grow to the volume  $2V_0$  and then instantly divide into equal two daughter cells. Under external forces the orientation of cell division is determined by the direction of the net force exerted on the cell, as others have assumed.

Cells experience growth delay or inhibition as a result of several control mechanisms. The growth inhibition has two components. First, the growth along each axis is zero when the force acting on the cell in that direction is too compressive or tensile. The second, which is specific to the model used here, is a pSmad-dependent, switch-like component described

shortly. Throughout we assume that there is an adequate supply of nutrients and we do not treat them explicitly.

Changes in the length of an axis  $a$  of a cell consist of the change due to the length of the spring-dashpot component ( $u_{\alpha}^{(0)}$ ) and the change due to the growth ( $u_{\alpha}^{g}$ ). This leads to two equations for the lengths of the axes that have to be solved subject to the volume constraint. We assume that the growth rate of TECs depends on the stress acting on the cells and the level of the phosphorylated Smad (*Sp*) independently, and thus we use the multiplicative form of the growth rate function for the *i th* axis given by

$$
\dot{u}_i^g = f(\sigma)P(S_p),\tag{25}
$$

where  $\sigma$  is the stress acting on the cell and *P* is a function of  $S_p$ . The growth function  $f(\sigma)$  is defined so that cells grow under sufficiently small tensile and compressive stress, but do not if stresses are too large. As in Section 2, the growth rate due to stress decays linearly with increasing tensile or compressive stress (see Fig 4 in KSO for the explicit form of the stress dependence of growth). The function  $P(S_p)$  is defined as

$$
P(S_p) = \begin{cases} P_0 & \text{if } S_p < S_p^{\,th} \\ 0 & \text{otherwise} \end{cases} \tag{26}
$$

and as a result growth is either on or off, the latter if either the stress or  $S_p$  is too large. The force balance equations for each cell are derived in KSO, taking into consideration all the forces acting on the cell: the adhesion forces, internal pressure, and other forces, and these are not repeated here. The solution of these equations provide the time-dependent track of each cell.

Here we restrict attention to two space dimensions, and therefore the cells are treated as oriented ellipses. In the context of the DCIS model, TEC growth is a passive process and active motion of the TECs is not incorporated. ECs are a key structural element for maintaining the integrity of a breast duct and do not proliferate unless it is necessary in order to maintain the integrity of the duct, and we assume that only TECs proliferate. Some cells on the ECM-cell interface are involved in active motion to invade into the stroma, and these types of motions are important in the later invasive stage or in certain types of brain tumor growth, but we do not include such active cell movement here.

**3.3.2 The continuum components for mechanics and growth factors—**As was indicated earlier, we use a continuum description for the mechanical response of the stroma outside the breast duct. The stromal region, denoted Ω*<sup>s</sup>* , is treated as a linear viscoelastic material as in KSO, where details of the constitutive equations and boundary conditions are given. Forces acting on the boundary between the stroma and the duct are calculated from the cell-based component, as shown in Figure 3 in KSO. These equations are solved using the finite element method based on the triangular mesh shown in Figure 14.

Myofibroblasts in the stromal tissue can exist in two states, an inactive one and an active one, and the latter as well as the fibroblasts are treated as point sources of EGF. Furthermore, we assume that the fibroblasts and myofibroblasts are randomly distributed initially, and we ignore the possible chemotaxis-driven migration of myofibroblasts toward tumor sites. These assumptions allow us to model cells as fixed sites, thereby avoiding the development of a realistic model for cell migration through the complex ECM. An inactive

myofibroblast is activated in response to a sufficiently high level of TGF-*β* at the location of that cell, and both fibroblasts and myofibroblasts secrete EGF at a constant rate – higher for the latter than for the former. The spatial distributions of EGF and TGF-*β* evolve according to reaction-diffusion equations that include the effects of the point sources due to cell secretion. We let  $E(x, t)$  and  $T(x, t)$  be the concentration of EGF and TGF- $\beta$  respectively, and we assume that there is no flux of EGF or TGF-*β* at the outer boundaries of the domain shown in Figure 14. We also assume that (i) there are fixed a total number of fibroblasts and myofibroblast near the duct, (ii) initially all myofibroblasts are inactive, and (iii) cells in the duct (ECs and TECs) produce TGF-*β*, and these cells are moving sources for TGF-*β*. The governing equations for  $E(x, t)$  and  $T(x, t)$  are as follows.

$$
\frac{\partial E}{\partial t} = \nabla \cdot (D_E \nabla E) + \sum_{i=1}^{N_f} \frac{k_{i,f}^E V_c^f}{V_*} \delta(x - x_i^f) + \varphi(T) \sum_{i=1}^{N_m} \frac{k_{i,m}^E V_c^m}{V_*} \delta(x - x_i^m) - \underbrace{d_E E}_{\text{decay}}, \quad \text{in } \Omega
$$
\n
$$
\frac{\partial T}{\partial t} = \nabla \cdot (D_T \nabla T) + \sum_{i}^{N_f} \frac{k_{i,n}^T V_c^i(t)}{V_*} \delta(x - x_i^t) - d_T T, \qquad \text{in } \Omega
$$
\n
$$
\frac{\partial E}{\partial v} = 0, \quad \frac{\partial T}{\partial v} = 0 \qquad \text{on } \partial \Omega. \qquad (27)
$$

Here  $D_F$  and  $D_T$  are space-dependent diffusion coefficients of EGF and TGF- $\beta$  respectively,

and  $x_i^t=(x_i^t, y_i^t), x_i^t=(x_i^t, y_i^t), x_i^m=(x_i^m, y_i^m)$  are the locations of TECs, fibroblasts, and myofibroblasts at time *t*, respectively.  $N_t$ ,  $N_f$ , and  $N_m$  are the total number of TECs, fibroblasts, and myofibroblasts, respectively, *V*\* is the volume of the extracellular medium,

 $V_c^f$ ,  $V_c^m$ ,  $V_c^t$  are the volumes of a fibroblast, myofibroblast, and epithelial cell, respectively, and *ν* is the outer unit normal of the boundary of the region containing the duct and the ECM. The volumes of fibroblasts, and myofibroblasts are constant, but the volume of TECs is variable, since they grow and divide. The threshold function for activation of myofibroblasts is

$$
\varphi(T) = \begin{cases} 1 & \text{if } T > th_T \\ 0 & \text{otherwise.} \end{cases} \tag{28}
$$

We have assumed that ECs and TECs secrete TGF-*β* at the same rate, and thus the only difference between ECs and TECs is that the latter proliferate when the pSmad level drops below the threshold  $S_p^{th}$ .

The reaction-diffusion equations (27) are solved on the regular grid using the alternatingdirection implicit (ADI) method and the nonlinear solver *nksol* for algebraic systems. A typical spatial grid size used is  $hx = hy = 0.01$  on a square domain of 1 mm side length. An initial time step of 0.001, which corresponds to 3.6 seconds, was used, but adaptive time stepping based on the number of iterations is used to control this step. After convergence of the solution step for the growth factors, the level of  $pS$  at all EC locations is checked in order to determine whether the cells on the duct wall have to be transformed to TECs and DCIS has to be initiated. We also have to transfer the EGF flux from the fibroblast/myofibroblast locations to grid points in order to update the reaction-diffusion equations. For this purpose the EGF level at the center of the cell is used, and interpolation to and from grid to cell is done as described in Dallon & Othmer (1997). We also use the level of TGF-*β* at a site to determine if a myofibroblast is to be activated. Details concerning

the numerical algorithm for this mixed on-lattice, off-lattice scheme can be found in Dallon & Othmer (1997).

# **3.4 Computational results**

Figure 15 shows the tumor patterns that result from one, two, or three TECs initiated at different EC locations on the breast duct. These histological patterns of ductal carcinomas have been observed experimentally and are called micropapillary (a), tufting (b) (Bostwick *et al.*, 1993), cribriform (c), and solid (Winchester *et al.*, 2000), respectively. Rejniak & Dillon (2007) investigated this patterning in the absence of the surrounding tissue and concluded that two key parameters, variability in cell orientation and cell replication, may determine those four patterns. What is lacking in their model is mechanical feedback from the surrounding stroma via the reciprocal tissue resistance force. In fact, in our simulations, we observe that the cribriform pattern at the initial stage (days 5–7) later turns into the solid pattern (after day 10). Even though the patterns in the three cases appear different at intermediate stages of development, all tumors eventually merge to a solid pattern and continue to grow outward against the resistance of the stroma. Thus the distinct patterns may simply be transient patterns enroute to complete occlusion of the duct in DCIS, after which the stresses from the surrounding stroma play a large part in the further growth of the tumor. We also observe different patterns when we change certain mechanical or biochemical properties, such as the adhesion strength between cells or between cells and breast duct (data not shown).

Since these simulations were done in a two-dimensional cross section, the effects of growth only in the radial direction are considered in Figures 15–20 but the growth effects in longitudinal direction are shown in Figure 21. 3D hybrid simulations will reveal more realistic patterns of intraductal microarchitectures. As noted in Rejniak & Dillon (2007), the direction of cell division plays a significant role in determining the variable tumor growth patterns, and our preliminary study shows quite different patterns might be generated when different division rules are applied (data not shown). This would be important for maintaining homeostasis of normal ductal structure in particular. It is also not clear how the original location(s) of TECs is determined, but it is likely that these locations reflect the location of the first viable clones of transformed cells. Here we simply specify TECs at random locations, but as shown in Figure 12, the transition from ECs to TECs is controlled in part by interactions between fibroblasts and established TECs via EGF and TGF-*β*. A more detailed investigation of the role of the microenvironment in the initial development of TECs remains to be done.

In figure 16 we show the results of computations that illustrate how the interaction between TECs and stromal cells (fibroblasts and myofibroblasts) can regulate both the conversion of ECs into TECs and the growth of TECs. The process is initiated by a higher level of TGF-*β* signaling by ECs, which in turn triggers fibroblasts to proliferate more rapidly, followed by differentiation of some fibroblasts into myofibroblasts when the TGF-*β* level exceeds the threshold  $th_T$  = 0.757 *nM* in the stromal tissue at about 76 h. The increased level of EGF leads to the activation of ECs into TECs when the pSmad level at the EC site drops below

the threshold  $S_p^{th} = 5.8 \, nM$  at about 90 h, and these new TECs grow inward in the duct. This positive feedback between the fibroblasts and TECs continues, and the expanding tumor exerts force on the breast duct wall which generates a reactive force from the viscoelastic stroma. Despite the fact that we do not consider longitudinal growth in this simulation, our model shows the importance of the TEC-stroma interaction in the initiation and early enhancement of TEC growth inside the duct. In the simulation we simply activate myofibroblasts at the pre-determined locations near the duct, rather than including another set of equations to describe the transition from fibroblasts to myofibroblasts. The locations

of fibroblasts/myofibroblasts are indicated in Figure 16(g). Figure 16(h) shows the time evolution of the TEC population within the duct. The time evolution of the pSmad level for the 1<sup>st</sup> cell, which is indicated by an arrow in 16(a), is shown in Figure 16(i). The pSmad level for this cell decreases quickly due to the emergence of myofibrobasts, which have a higher EGF production rate ( $k_m^E$ ), around t=76 h, and reaches the threshold value for transformation of that EC into a TEC around t=90 h. The effect of myofibroblasts is discussed in more detail in the Figure 18. Even though we made a simple but reasonable assumption that pSmad acts as a switch for proliferation, it is not clear whether this rule can be applied to the entire EC population along the duct, since it may be that only a few activated ECs are necessary to ensure the survival of the tumor.

Figure 17(a–c) and Figure 17(d–f) show the concentrations of EGF and TGF-*β* at t = 2 h, 80 h, and 478 h, respectively. The early high level of EGF at three cells (figure 17(a);  $t=2$  h) later evolves into many localized peaks at the sites of fibroblasts/myofibroblasts at  $t = 80$  h and 478 h (figure 17(b–c)), as myofibroblasts become activated at about 76 h. This occurs in response to elevated values of TGF-*β* at these sites that has diffused outward from TGF-*β*secreting ECs and TECs in the duct. The EGF released diffuses toward the duct and activates ECs. In the early stages of the simulations, when ECs are not yet activated, TGF-*β* is localized at the duct periphery (figure 17(d)) and diffuses into the surrounding stroma. Later the highest levels of TGF-*β* are concentrated in the duct interior following transformation of ECs to TECs (after t= 96 h) and increased TGF-*β* secretion within the duct (figure  $17(f)$ ). Examples of pSmad values inside three representative cells (cell index=1, 20, 30) at the corresponding times (t = 2 h, 80 h, 478 h) are shown in Figure 17(g-i). These figures show that initially high pSmad values  $(t=2 h)$  at these selected EC sites decrease as time progresses, eventually leading to pSmad values below the threshold for transformation.

Figure 18 shows the effect of myofibroblasts on TEC growth and the evolution of other components. In the presence of myofibroblasts the ECs are activated and TECs proliferate (Figure 18a) due to the high level of EGF secreted by myofibroblasts (Figure 18(b)). In the absence of myofibroblasts TEC growth is inhibited (Figure 18(c)) due to the low level of EGF (Figure 18(d)). This dramatic difference is due to the large difference in pSmad and EGF concentrations between the two cases (shown for one cell in Figures 18(e) and (g)). These results show that the myofibroblasts are required to achieve the elevated EGF production necessary to lower pSmad levels to the threshold level for TEC activation. As shown in figures 18(b) and 18(d), the difference in EGF concentrations in the presence and absence of myofibroblasts is dramatic, which results from the fact that EGF secretion rates from myofibroblasts are typically 2–10 times larger than fibroblast secretion rates. In addition, the fibroblast population is smaller than the myofibroblast population. As shown above in Figure 16(i), most ECs are activated by 96 h, which implies that the presence of fibroblasts is not sufficient to activate TECs and secretion of EGF by myofibroblasts is crucial for TEC activation and growth in the duct. While pSmad concentration slowly decreases as a function of time due to an increased EGF concentration from fibroblasts alone, the pSmad level decreases much more rapidly when activated myofibroblasts are present in the stroma, which in turn leads to TEC activation. (see figure 18(e)).

The trajectories of a moving epithelial cell (given by its center of mass) are shown in figure 18(f). This movement of the cell is due to passive growth, not active migration, and its location is bounded by four computational cells  $(Q_i, i = 1, ..., 9)$  shown. In the absence of myofibroblasts, none of the ECs were activated by 20 days and the trajectory of the same cell in (f) is bounded by a computational grid  $(Q_1, Q_2, Q_5, Q_4)$  (data not shown). Figure 18(g) shows the time evolution of the EGF concentration at this cell site. The EGF level increases much more rapidly when myofibroblasts are activated around 76 h, which corresponds to the sudden drop of pSmad shown in (e), as compared to the slow increase in

EGF from fibroblasts alone. The TGF-*β* concentration in the presence of both fibroblasts and myofibroblasts is also significantly different as compared to that when only fibroblasts are the source, since many more ECs become transformed to TECs, thereby increasing the source of TGF-*β* in the duct. Figure 18(h) illustrates the TGF-*β* concentration at a myofibroblast site (0.358, 0.126). The TGF-*β* concentration increases slowly with time when only fibroblasts are present, but it increases much more rapidly when a significant number of myofibroblasts are present. To simulate the absence of myofibroblasts we assumed that myofibroblasts are not activated even when TGF-*β* concentration is above the threshold th*T*, and the results indicate that activation of myofibroblasts in the stroma plays a significant role in communicating with the ECs in the duct. In early breast cancer development, myofibroblasts are abundant near a breast duct in the stromal tissue and our results indicate that they play a significant role in the activation of TECs and enhancement of tumor growth.

In Figure 19 we investigate the effect of myofibroblast location on activation of both TECs and myofibroblasts. Since the interaction between TECs and these stromal cells results from counter-diffusion of EGF and TGF-*β*, these interactions are strong and both cell types are activated earlier when myofibroblasts are located close to TECs in the duct. It is clear from this that if myofibroblasts are also chemotactic to TGF-*β* the strength of the positive feedback would be further enhanced. This figure also confirms the important role of myofibroblasts in enhancing TEC growth by activating TECs at the earlier stages of cancer development.

We also tested the effect of TGF-*β* secretion rates on TEC growth and the activation of TECs and myofibroblasts. When TGF-*β* secretion rates are increased, both TECs and myofibroblasts are activated at an earlier time (Figure 20(a)), and the TEC population at day 10 is also increased (Figure 20(b)). A qualitatively similar result can be achieved by increasing the diffusion rates of EGF and TGF-*β* (data not shown). As we saw earlier, it can be difficult for fibroblasts alone to generate a sufficiently high level of EGF for activating TECs and increasing TEC growth. This figure and Figure 22 below imply that it is important to block secretion of both TGF-*β* and EGF (or to lower the diffusion rates of the signals) in order to achieve slower TEC growth.

As observed earlier, a variety of stromal components can contribute to the stiffening of stromal tissue, including reorganization of collagen fibrils by myofibroblasts (Paszek & Weaver, 2004) and local stiffening after TEC transformation (Krouskop *et al.*, 1998). Furthermore, an increase of the reactive force due to the growth of TECs then may lead to tumor invasion in later stages (Paszek & Weaver, 2004). In Figure 21 we show the effect of stress on TEC growth in a longitudinal cross-section of a duct. Two activated TECs grow in the longitudinal direction in the face of resistence from stromal tissue above (stiffer) and below (more compliant). Due to the stiffer stromal tissue above the growth is confined to the longitudinal direction, whereas when the stroma is more compliant the growing tumor forms a bulge. In any case the TECs grow inward first to fill up the duct, as in the case of growth patterns in the radial direction in Figure 15. Once the space is filled near the origin of TECs, TECs begin to feel a reciprocal tissue resistance force from the surrounding stromal tissue and tend to grow in the longitudinal direction, *i.e.,* in the direction of less stress. This is qualitatively consistent with experimental results described earlier on anisotropic growth (Helmlinger *et al.* (1997); Cheng *et al.* (2009)).

It has been suggested that attacking the active players that facilitate the interaction between the TECs and the stroma, such as fibroblasts, may result in better clinical outcomes in breast cancer patients. In Figure 22, we display results of tests to determine the effect of blocking EGF secretion from both fibroblasts and myofibroblasts. We consider EGF secretion rates that are decreased by factors of 2, 3, and 5, from the control case, which simulates the effect

that a hypothetical drug may have. The TEC population at the final simulation time  $(t=10$ days) is reduced by 49%, 33%, and 10% for a 5-,3-, and 2-fold rate decrease, respectively, when compared to the control (see Figure 22(b)). This reduction is due to delays of TEC activation due to the decreased rate of EGF secretion by fibroblasts and myofibroblasts. This is seen in Figure 22(d), where it is clear that slower EGF secretion rates result in slower increases in EGF concentration that in turn lead to slower decrease in the pSmad level at the TEC site. To illustrate this point, we chose an epithelial cell near (0.42, 0.5) and displayed the time evolution of pSmad in this cell in Figure 22(c), and the EGF concentration at this location (see Figure 22(d)).

# **4 Conclusions and open problems**

It is now well established that the TME, which comprises cell types such as epithelial and endothelial cells, inflammatory cells, fibroblasts, and myofibroblasts, as well as the surrounding ECM, affects tumor growth and metastasis (Samoszuk *et al.*, 2005). Cells in the TME communicate via secreted cytokines and growth factors, and are subject to the mechanical forces transmitted through the TME that arise from tumor expansion. Fibroblasts and macrophages are of particular interest because both *in vitro* and *in vivo* studies have shown that they contribute to the formation and growth of tumors (van den Hooff, 1988).

In Section 2 we presented a mathematical model of a tumor growing in an agarose gel. Both the tumor and the gel are treated as single-phase hypoelastic continua, and the model equations are solved in a three-dimensional domain using the finite element method. The results here constitute the first set of numerical simulations in three-dimensions that investigate the effects of inhomogeneous material properties on *non*-spherical tumor growth. Nonetheless, there are several limitations of the continuum model described here. The first, as discussed earlier, is that it is necessary to start with a larger tumor than in experiments. However, as also noted, a hybrid model such as the one described in Section 3 can remedy this and allow us to start growth with a single cell. Second, we assume homogeneous material properties of the tumor and agarose and do not consider local modulations in stiffness due to formation of the necrotic core and compression of the tumor, nor do we consider the effects of stress on the stiffness of the surrounding agarose gel. These effects can be incorporated in the model as more experimental evidence regarding them becomes available. In spite of these limitations, the numerical investigations here have enabled us to gain some insight into the effects of mechanical stresses on tumor growth. In particular, we show that the effect of stress on tumor growth is very complicated, and it is likely that these effects are nonlinear and/or anisotropic.

There remain various unanswered questions regarding the stress affects on tumor growth, and the mathematical model presented here provides a framework to address several of these questions mathematically. Some of these questions include what is the form of a nonlinear stress feedback function that would appropriately amplify local variations in the stress gradient. Ambrosi and Mollica use an exponential stress feedback that depends on the bulk stresses and apply this function to spherically-symmetric tumor growth (Ambrosi & Mollica, 2004). They obtain results that compare to experiments qualitatively, but the use of their exponential stress feedback has not been attempted in the three-dimensional context. Another question that arises is whether or not the stress feedback should depend on average bulk stresses or does tumor growth depend on the maximum bulk stress. Also, it is not clear whether tensile and compressive stresses affect tumor growth differently, and how shear stresses should be incorporated into an anisotropic stress feedback. These are all open problems that will be addressed in future work.

The questions that arise here also call for further experimental investigation. It would be beneficial to know whether shear stresses affect tumor growth rates positively or negatively, as bulk stresses do. Spatial dependence of stresses in an experimental setting in which tumor growth rates are spherically inhomogeneous (such as in the capillary tube experiment of Helmlinger *et al.* (1997)) may shed light on the type of stress feedback that tumors experience. Knowledge of material properties of necrotic tumor regions would also benefit further mathematical, and in turn experimental, investigation.

The hybrid model for DCIS has the potential for many other computational experiments not done here to understand the interaction between the tumor and the microenvironment. Easy extensions of the current model include (i) the role of myofibroblast motility, (ii) a sensitivity study for certain important parameters such as TGF-*β* secretion rate, the transition rate from fibroblasts to myofibroblasts, diffusion coefficients of growth factors, and pSmad production rate, (iii) ECM stiffening to account for changes observed after EC transformation (Krouskop et al., 1998), and (iv) inclusion of proteinase secretion by fibroblasts.

The last of these illustrates the need for a more detailed treatment of the early steps of cancer invasion into the surrounding tissue, and the later migration of cells through the ECM. Both the myoepithelial cells and the basement membrane in normal breast tissue or DCIS define a clear boundary between stromal tissue and the epithelial cell layer in the breast duct. This layer forms a continuous sheet connected by intermediate or gap junctions and intercellular adhesion molecules for mechanical support of the duct structure. Due to the tight connections, it only allows passage of small molecules in normal duct, acting like a semipermeable membrane in the two-chamber system in Kim *et al.* (2010). It was found that myoepithelial cell layer breakdown is an early indicator of the formation of an aggressive cell clone and may be associated with tumor invasion in breast cancer (Man *et al.*, 2003).

Experiments and modeling work in Kim *et al.* (2010) confirmed the role of fibroblasts on promotion of TEC growth *in vitro*. Kim & Friedman (2009) extended the model to investigate how fibroblasts and myofibroblasts in the stroma affect tumor cell invasion in a Boyden Invasion Chamber. The semi-permeable membrane between two chambers mimics the layers of basal membrane and myoepithelial cells between the duct and the stroma, but the detailed intracellular dynamics of the EGF-TGF-*β* pathways, a realistic geometric representation of the duct structure, and the mechanical interaction between stroma and duct are not included.

The hybrid model developed herein is a first step toward incorporating these factors, and can be used both for *in vitro* experiments and *in vivo* studies. A hybrid model has numerous advantages which stem from the fact that changes in biochemical pathways or mechanical properties can be made in selected cells, which the majority of the tissue is treated as a continuum. For instance, one can easily alter individual properties such as adhesion, or study the effect of therapeutic drugs on individual cells in a heterogeneous population. An important further step not treated here is to extend the model to three space dimensions to understand, *e. g.,* the growth patterns in a geometrically-realistic duct, to investigate the role of fibroblasts/myofibroblasts distributed in 3D, and to study the dependence of direction of division on growth rates and tissue properties. One can test and reproduce the experimental results by Cheng *et al.* (2009), in which an oval shaped spheroid is observed when anisotropic compression is applied in one direction. As discussed in the background section, ECs and TECs show different sensitivities to external mechanical stimuli, and the individual cell model is well suited to investigate this effect. Another direction concerns the extension of the model to include invasion of individual cells through the ECM. Cell migration is a complex process since the microenvironment is a heterogeneous material including proteins,

cells, and extracellular fibril structures. More detailed and realistic quantitative data may be derived from a model that includes continuous mechanical feedback between a cell and the collagen network, which in turn may lead to a better understanding of cell motility through the ECM.

Understanding the relationship between a tumor and its microenvironment may lead to important new therapeutic approaches in controlling the growth and metastasis of cancer. Indeed, instead of targeting the tumor cells, one may target stromal elements in order to manipulate the host-tumor interaction in a way that will inhibit growth and metastasis of the tumor (Chen *et al.*, 2008). For instance, remodeling of the microenvironment can create an elevated interstitial fluid pressure and increased resistance to movement. Several drugs in current use target tumor associated fibroblasts or tumor associated macrophages (Chen *et al.*, 2008), and studies such as reported here can shed light on unforeseen effects of these agents.

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# **A Glossary of selected terms and abbreviations**









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#### **Figure 2.**

(Left) The TGF-*β* pathway. (From (Massague & Gomis, 2006) with permission.) (Center) The Ras-Raf-MEK-ERK pathway. (From (Shin *et al.*, 2009) with permission.) (Right) A schematic of the combined pathways. (From (Guo & Wang, 2009), with permission.)





A schematic of the structures involved in cell-ECM contacts. From (Butcher *et al.*, 2009), with permission.



# **Figure 4.**

A schematic of a model for the role of tumor associated macrophages (TAMs) in cancer progression. Macrophages in the stroma surrounding a tumor are attracted by CSF-1 released by the tumor cells, and they in turn release chemokines that stimulate further production of CSF-1. This stimulates tumor cell migration, and both tumor cells and macrophages are stimulated to release VEGF and TGF*β*. (From Green *et al.* (2009), with permission.)



# **Figure 5.**

(a) The geometry and boundary conditions of numerical experiments. **n** is the outer normal to the boundary of the domain. (b) Experimental tumor growth. Tumor growth induces a crack in the surrounding agarose (red arrows on top figure) and the tumor grows into the void caused by the crack (bottom). From Cheng *et al.* (2009), with permission.



#### **Figure 6.**

(a) Final configuration at time t=25 days for tumor growth in 1% agarose and (b) 0.5% agarose. Original tumor position is outlined in black. (c) Evolution of the tumor radius. Dashed line corresponds to evolution in 0.5% agarose and solid line corresponds to growth in 1% agarose.



#### **Figure 7.**

Average bulk stress  $((\sigma_{xx} + \sigma_{yy} + \sigma_{zz})/3)$  distribution near or upon approaching equilibrium size. (a) In 1% agarose at 25 days. (b) In 0.5% agarose at 25 days. (c) Inhomogeneous agarose concentration at 7.5 days (discussed later).



#### **Figure 8.**

(a) Magnitude of the displacement field at  $t = 25$  days for tumor growth in a domain with a free top boundary. (b)  $(\sigma_{xx} + \sigma_{yy} + \sigma_{zz})/3$  at  $t = 25$  days.



#### **Figure 9.**

(a) Evolution of the tumor radius along the *x*-axis (solid) and radius in  $y - z$  plane at  $x = 0$ (dashed). (b) The length of the radius along *x* axis relative to radius in  $y - z$  plane. Line of best fit *y* = 1.81*x* − 83.9



**Figure 10.** Shear stress  $\sigma_{r\theta}$  distributions on the plane defined by  $z = 0$  for agarose with variable material defined by (14). Here  $r = \sqrt{x^2 + y^2 + z^2}$  and  $\theta$  is the azimuthal angle.



# **Figure 11.**

(Left) A normal breast duct, showing one layer of epithelial cells (purple rectangles) enclosed by a layer of myo-epithelial cells (brown triangles) followed by the basement membrane and the stroma (from Paszek & Weaver (2004), with permission). Fibroblasts (white diamonds) are sparsely distributed in stromal tissue. (Center) DCIS: A necrotic core does not develop because the tumor is small and the nutrient can permeate throughout it (from Ma *et al.* (2003) with permission.) (Right) A high-grade (comedo) DCIS. The larger size leads to a necrotic core at the center due to hypoxia. The arrows (a–d) indicate the necrotic core (a), the proliferating zone (b), the duct wall (c), and the healthy stroma (d), respectively (from Franks *et al.* (2005) with permission.)



# **Figure 12.**

The interaction of the EGF and TGF-*β* pathways in the control of proliferation in breast cancer (see also Figure 2(c)). In normal ECs these pathways are balanced so as to control growth, but in TECs increased secretion of TGF-*β* induces fibroblasts and myofibroblasts to secrete more EGF. This disrupts the proliferation-inhibition mechanism by partially blocking the TGF-*β*-Smad pathway and triggers proliferation.



#### **Figure 13.**

(A) Activation of the A3-Luciferase reporter construct at the indicated concentration of TGF-*β* analyzed in EpH4 (squares) and EpRas, a Ras-transformed derivative, (triangles) of mammary epithelial cells. (Modified from (Kretzschmar *et al.*, 1999) with permission.) (B) Model predictions: inhibition of pSmad level when ECs are exposed to a higher concentration of EGF. For comparison of the model predictions with normal (EpH4) and mutant (EpRas) cell responses in (A), we assume that increased signaling due to increased EGF is equivalent to the Ras-mutant response.



# **Figure 14.**

(Left) Model domain: fibroblasts, myofibroblasts, and TECs interact via EGF and TGF-*β*. In the figure, the annular domain outside the duct is treated as a viscoelastic continuum region which consists of myo-epithelial cells and stroma. (Right) Changes in the length of the aaxis of a cell (the ellipsoid) under a given stress (*fa*; arrow) consist of the passive change in the first component, which comprises a Maxwell element in parallel with a nonlinear spring, and the change due to the growth ( $u^g$ ). The mechanical and growth elements are the same along all axes.



# **Figure 15.**

The patterns of growth of activated TECs at different locations. One (Figures (a)–(d)), two (Figures (e)–(h)), and three (Figures (i)–(l)) TECs initially grow to occlude the duct after 10 days.



#### **Figure 16.**

(a–f) The temporal evolution of TEC growth inside a duct. The panels show the configuration of TECs and the stromal mesh at  $2 h$  (a),  $90 h$  (b),  $200 h$  (c),  $300 h$  (d),  $400 h$ (e), 478 h (f). ECs are activated into TECs and begin to grow ( $\sim t = 90h$ ), when pSmad

values drops below the threshold value ( $S_p^n = 5.8nM$ ). Activated TECs and their progeny are gray in (b–f) while unactivated ECs are green in (a). (g) The location of fibroblasts (blue) and myofibroblasts (red). These cells are fixed sources of EGF in the simulation. Initially only three fibroblasts were located in the computational domain and myofibroblasts are activated when the TGF-*β* level exceeds  $th_T$  = 0.7567 *nM* ( $\sim t$  = 76*h*). (h) The temporal evolution of number of TECs. (i) The temporal evolution of the pSmad concentration at one TEC site (marked by an arrow in (a)). Similar profiles of pSmad are observed for all TECs.



#### **Figure 17.**

The concentrations (in *nM*) of EGF (a–c) and TGF-*β* (d–f), on the dimensionless domain [0,1]<sup>2</sup> at time t = 2 h (a,d), 80 h (b,e), 478 h (c,f). Initial conditions for EGF and TGF- $\beta$  were 3.0d-10, 3.0d-10 respectively. (g–i) pSmad concentration (*nM*) at the selected cell sites (1st, 20-th, 30-th cell site) at time  $t = 2 h(g)$ , 80 h (h), 478 h (i). Intial high values ( $\sim 20.5 nM$ ) of pSmad at the cell sites significantly decreased (~ 5.1 *nM*) below the threshold value

( $S_p^{\text{th}} = 5.8 \text{ }\text{nM}$ ) for higher levels of EGF and TGF- $\beta$  in (c) and (f).



#### **Figure 18.**

The effect of myofibroblasts on tumor growth. (a,c) The configurations of cells within a duct and of the stroma surrounding the duct at  $t=378$  h in the presence (a) and absence (c) of myofibroblasts. (b,d) EGF concentration profile at t=378h in the presence (b) and absence (d) of myofibroblasts. (e) pSmad concentration of a selected cell  $c_i$  with cell location in (f).

In the absence of myofibroblasts, the pSmad level has not reached the threshold value ( $S_p^{th}$ ) and ECs are not activated (dotted line). However, in the presence of myofibroblasts the pSmad level drops below the threshold (arrow) and ECs become TECs. (f) Trajectories of the moving cell  $(c_i)$  in the presence of and absence of the myofibroblasts in the stromal tissue respectively. The site was the center of cell mass. The dotted lines indicate the regular computational grid  $(h_x=0.01$  on  $[0, 1]^2$ ). (g) The time evolution of the EGF concentration at the cell site selected in (f) above. (h) TGF*β* concentration at a myofibroblast site with approximate location (0.358, 0.126).



# **Figure 19.**

The effect of myofibroblast location on activation of TECs and myofibroblasts. Thirteen myofibroblasts were located on a circular track as in Figure 16(g), but at various distances (20, 120, 220, 320 *μm*) from the duct periphery. When TECs and myofibroblasts are located close to each other, both cell types are activated at earlier times due to the relatively short diffusion distance.



#### **Figure 20.**

The effect of blocking TGF-*β* secretion from ECs. (a) The activation time of TECs and myofibroblasts as a function of TGF-*β* secretion rate. Larger TGF-*β* secretion rates lead to earlier activation of both TECs and myofibroblasts. (b) The TEC population at day 10 as a function of the TGF-*β* secretion rate. TEC population at day 10 were reduced compared to the control.



#### **Figure 21.**

The effect of stiffer stromal tissue on tumor growth. Upper stromal tissue has larger stiffness than lower stromal tissue. In general, TECs grow in longitudinal direction but generate bulb shape in less stiff (lower) stromal directional.



#### **Figure 22.**

Simulated therapy – the effect of blocking EGF secretion from fibroblasts. (a) Activation time of TECs and myofibroblasts as a function of EGF secretion rate ( $k_f^E, k_m^E$ ). The secretion rate of EGF from both fibroblasts ( $k_f^2$ ) and myofibroblasts ( $k_m^E$ ) were reduced by 2-, 3-, and 5-fold compared to the control case. There are delays in activation of TECs when EGF secretion rates are reduced, while the activation time for myofibroblasts remains the same, the latter a reflection of the fact that ECs and TECs secrete at the same rate. (b) The TEC population at day 10 compared to the control (arrow). (c) Time evolution of pSmad concentration at one epithelial cell near (0.4, 0.5) for the four cases of decreased EGF secretion rate considered. Myofibroblasts are activated for all four cases around 76 h when TGF-*β* reaches the threshold, while the pSmad level decreases slowly for smaller values of the EGF secretion rate, leading to a delay of the TEC activation time. (d) Initially slow increase of EGF concentration at (0.42, 0.5) near breast duct membrane begins to accelerate when myofibroblasts are activated at 76 h for all four EGF secretion rates considered.

Parameter values for the continuum tumor model.



Definition of variables in EGF-TGF-*β* signaling pathways



Parameters in the model of the intracellular dynamics. Some parameters were estimated to fit the experimental data in (Kretzschmar et al., 1999).



#### Parameters that are used in the ECM model.

