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High Sensitivity Gas Detection Using a Macroscopic Three-Dimensional Graphene Foam Network

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Nanostructures are known to be exquisitely sensitive to the chemical environment and offer ultra-high sensitivity for gas-sensing. However, the fabrication and operation of devices that use individual nanostructures for sensing is complex, expensive and suffers from poor reliability due to contamination and large variability from sample-to-sample. By contrast, conventional solid-state and conducting-polymer sensors offer excellent reliability but suffer from reduced sensitivity at room-temperature. Here we report a macro graphene foam-like three-dimensional network which combines the best of both worlds. The walls of the foam are comprised of few-layer graphene sheets resulting in high sensitivity; we demonstrate parts-per-million level detection of NH₃ and NO₂ in air at room-temperature. Further, the foam is a mechanically robust and flexible macro-scale network that is easy to contact (without Lithography) and can rival the durability and affordability of traditional sensors. Moreover, Joule-heating expels chemisorbed molecules from the foam's surface leading to fully-reversible and low-power operation.

anoscale structures such as carbon nanotubes^{1–3} and graphene^{4–5} have been considered as candidates for chemical sensing. Such sensors are attractive for "on-site" monitoring and can be used by emergency rescue crews o chemical sensing. Such sensors are attractive for ''on-site'' monitoring and can be used by emergency leaks. The Dai and Zettl groups first showed¹⁻² that the electrical conductance of semi-conducting single-walled carbon nanotubes (SWNTs) changes sensitively at room temperature on exposure to several gases due to charge transfer between adsorbed gas molecules and nanotubes. For example, SWNTs are found to exhibit large increase in conductivity on exposure to oxygen¹. Similarly hole doped (p-type) SWNTs exhibit three orders of magnitude increase in conductance² on exposure to 200 parts-per-million (ppm) of NO₂. On exposure to 1% (10,000 ppm) $\rm NH_3$ flow, the same nanotubes exhibited a two orders of magnitude decrease in conductance². Since $\rm O_2$ and $\rm NO_2$ are strong oxidizing agents, they attract electrons from the p-type SWNT, thereby increasing the number of conducting holes. This hole (or p-type doping) shifts the Fermi level closer to the valence band causing increase in conductance. On the other hand, reducing agents such as NH₃ that inject electrons into p-type SWNT reduce the number of holes, leading to reduced conductance.

Individual graphene sheets⁴⁻⁵ can also be used to construct ultra-sensitive gas sensor devices. Graphene exhibits an exceptional band structure which contains conduction and valence bands with quasi-linear dispersion that touch at the Brillouin zone corners to form a zero gap semiconductor. Due to these properties as well as ultra-high surface area provided by graphene, its electronic properties show strong dependence to surface absorbents, including gas molecules, that can alter the carrier density of graphene. It has been shown that graphene and reduced graphene oxide respond sensitively to the adsorption of trace amounts of different gases including NH3, $NO₂, H₂O, Cl₂$ and $CO⁶⁻¹²$. The very high sensitivity of graphene is also due in-part to its inherently low electrical noise4–5 at room temperature which arises from its unique two-dimensional crystal lattice. Despite the outstanding potential of graphene and carbon nanotubes as gas sensors, the path of these devices towards commercialization is hindered by the complexity and cost of the fabrication process, durability/robustness of the sensor devices and large variability from sample-to-sample. For example, devices utilizing individual SWNT or graphene require patterning and subsequent electrode attachment using lithography^{6-7, 12-16} which increases the cost. Since individual SWNT or graphene elements are exquisitely sensitive to the chemical environment, they are easily susceptible to extraneous factors. This can affect the repeatability and reliability of the device performance.

Besides, such devices can be fragile and difficult to repair and maintain in the field. Here we report a mechanically robust and flexible 3D macro graphene foam (GF) network that offers the durability and affordability of macro sensors coupled with the very high sensitivity of a nanosensor device. We recently reported¹⁷ the development of such a free-standing continuous graphene-based network structure for flexible electronics applications. Here we show that such an inexpensive and simple GF device can also be utilized for chemical sensing with high sensitivity and reversibility.

Results

To fabricate the GF, a scaffold of porous nickel foam is used as a template for the deposition of graphene.17 Using chemical vapor depositon (CVD)¹⁸, carbon atoms are deposited on the nickel foam using CH4 decomposition at \sim 1000 $^{\circ}$ C under ambient pressure. The nickel scaffold is then removed using chemical etching by a hot HCl (or $FeCl₃$) solution. To maintain the integrity of the foam during the etching of the Ni and to prevent it from collapsing, a thin layer of poly(methyl methacrylate) (PMMA) is also deposited on the surface of the graphene formed on the nickel foam. In the final step the PMMA layer is dissolved by hot acetone. What remains is a continuous 3D network of graphene formed as a free-standing macroscopic structure with extremely thin interconnected sheets of graphene (Figure 1a–b). More details of the fabrication process of GF can be found in our previous work.17 The GF resembles the interconnected 3D scaffold structure of the initial nickel foam template. The graphene films in GF grow on the entire surface of the nickel foam scaffold and hence they are interconnected into each other and there is no interface or physical breaks in the network. Importantly, graphene films formed on the different surfaces of the nickel foam are well separated from each other, providing more adsorption sites for gas molecules. The GF is also very porous, flexible and light-weight and has a very high specific surface area of ${\sim}850\,$ m $^{2}/{\rm g}$ determined by standard BET nitrogen cryosorption characterization. The GF fabricated using a CH4 concentration of 0.7 vol% which was used in the present study has an extremely low density of \sim 5 mg/cm⁻³, corresponding to a very high porosity of \sim 99.7%.¹⁷ The thickness of the GF

sample used in our study was \sim 0.5 mm. Raman spectroscopy analysis of the foam (Figure 1c) indicates that the walls of the GF are comprised of monolayer to few-layer graphene sheets. This is consistent with the specific surface area of \sim 850 m²/g measured for the GF. The Raman spectra (Figure 1c) also show a strongly-suppressed defect-related D band, which confirms the overall high quality of the graphene in the foam.

In GF charge carriers can move rapidly with a small resistance through the continuous and interconnected network of high quality CVD-grown graphene building blocks, resulting in high electrical conductivity (\sim 10 S/cm). The operational mechanism of the GF sensors presented in this work is based on changes in their electrical conductivity, due to charge transfer induced by the adsorption of gas molecules acting as donors or acceptors $4-5$ on to the foam's surface. To measure the change in conductivity of GF by adsorption of gases, a four-probe resistance measurement technique was used (see Methods). Note that no lithographic patterning or manipulation of the sample is necessary; the flexible and robust macro-scale GF can be used directly in the as-produced condition. Proof-of-concept gas sensing experiments are performed using trace amounts of NH₃ and NO2 in mixtures with air at room temperature and atmospheric pressure. The temperature dependence of desorption of gas species is also studied using a hot plate with a temperature sensor. Heating increases the reversibility of the device and also accelerates the response rates. Another advantage of the robust GF device is that Joule heating can be conveniently used to locally heat the foam thereby achieving excellent reversibility of the sensor response. All of the data presented in this paper are obtained using one device, but similar response was reproduced in three other devices.

Discussion

To demonstrate the proof-of-concept, we chose ammonia (NH_3) as a test gas. Ammonium nitrate present in explosives is known to gradually decompose and release trace amounts of NH₃ which if detected would indicate presence of an explosive. NH_{3,} a toxic gas, is also used in a variety of industrial and medical processes and therefore it becomes important to monitor for NH₃ leaks. The GF device was

Figure 1 | Characterization of the GF structure. (a) Photograph and (b) scanning electron micrograph of the microporous GF structure showing a continuous network of 3D interconnected graphene sheets that comprise the walls of the foam-like structure. The robust and flexible GF strips can be easily handled and manipulated. Electrical contacts to the macro-scale GF can be established without the need for lithography. (c) Typical Raman spectra obtained at various locations on the GF indicating that the foam walls are comprised of mono to few-layer graphene.

placed in an environmental chamber with electrical feed-through, and air was pumped out of the chamber to establish a high vacuum $(-10^{-6}$ torr). Next NH₃ gas pre-mixed with air at the appropriate concentration was released into the chamber. We exposed the GF device for \sim 800 seconds to \sim 1000 parts-per-million (ppm) of NH₃ diluted in air at atmospheric pressure and room temperature $(\sim$ 300 K). The time evolution of the change in resistance due to adsorption of gas molecules is shown in Figure 2a. NH₃ appears to cause a decrease in the number of charge carriers in the foam resulting in an increase in resistance. Graphene under ambient conditions has been observed to display p-type behavior¹⁹ due to the electron withdrawing nature of adsorbed water or oxygen containing moeties which induce a holelike carrier concentration. $NH₃$ is a reducing agent with a lone electron pair that can be donated to the p-type GF thereby reducing the conductance. This change in resistance normalized by the initial resistance $(\Delta R/R)$ is defined as the sensitivity of the GF and it is \sim 30% for the case of \sim 1000 ppm of ammonia. The resistance of the GF reaches \sim 90% of its steady state value after \sim 500 seconds. Steady state is defined as the condition when the resistance value shows <1% change over a \sim 60 second time interval. To study the reversibility of the device, the gas input is closed and the NH3-dosed device was exposed to vacuum desorption conditions for another \sim 800 seconds. As Figure 2a shows the resistance of the sample does not return to the initial value even after prolonged exposure to vacuum and \sim 13.8% of the response is not recoverable. This shows that the desorption process is much slower than the adsorption process, likely due to chemisorption of $NH₃$ to the graphene surface. Purging the chamber with pure air for \sim 800 seconds also did not lead to full reversibility of the sensor response.

To stimulate the desorption process in GF, a heater was placed under the GF device and a temperature sensor was used to measure the foam temperature. Figure 2b shows the change in resistance as a function of time when a heater is used. The GF temperature is also measured and illustrated in the graph as a function of time. As seen in this graph, the heating significantly accelerates the desorption process, by exciting the molecules vibrationally so that they enter a repulsive state²⁰. After the heater is turned off, the Δ R/R of the GF equilibriates close to the original value, showing good reversibility. Even though the use of an external heater helps to achieve complete desorption in a shorter time, it will make the device bulky and complicated. A much more elegant approach is to use the Joule heating effect to generate the heat locally within the sample. For calibration purpose, the GF sample was heated in the 300–450 K temperature range using the external heater under vacuum (\sim 10⁻⁶ torr) and the reduction in resistance was measured as a function of temperature (see Supplementary Fig. S1). The GF displays a semi-conducting behavior with a negative coefficient of thermal resistivity of about \sim 0.00125 Ω /K. Next, a controlled Joule heating current (I) was applied to resistively heat the GF sample. Increasing the current also decreases the values of resistance (Supplementary Fig. S2), confirming that there is a Joule heating effect. From Figures S1 and S2 (Supplementary Section), one can associate each value of current (I) to a temperature (T), for example, to achieve \sim 400 K in the GF, a current of \sim 125 mA is required. In figure 2c, we show the results of an experiment performed with Joule heating $(I=125 \text{ mA})$ used to accelerate the desorption process. As seen in this graph, the adsorption process is fully reversible and the desorption time is almost as short as the adsorption time. Note that the electrical current range for sensing signals is \sim 1 mA, while the Joule heating current as previously discussed is of the order of \sim 100 mA.

Figure 3a shows the reversibility of the sensor over several cycles with Joule heating during the desorption step. Figure 3b shows the normalized change in GF resistance $(\Delta R/R)$ as function of time for different concentrations of NH₃ ranging from 1000 ppm (0.1%) to 20 ppm (0.002%). All tests are performed at atmospheric pressure and room temperature with Joule heating used during desorption.

 (a) 35

30

> Ω $\overline{0}$

 (b)

40 35

30

25 $\sqrt{6}$

5

 \approx 20

 \overline{AR} 15 10 $NH₃$ ON

Figure 2 [|] GF sensor response. Change in the normalized resistance of the GF as a function of time during adsorption of \sim 1000 ppm of NH₃ and desorption using (a) room temperature degassing and (b) high temperature degassing. The color bar at the top of the graph in (b) shows the change in temperature as a function of time. (c) Corresponding adsorption and desorption response obtained by using Joule heating of the sample during the desorption step. The control current supplied to the GF to heat it to \sim 400 K is \sim 125 mA.

The Δ R/R of the GF device decreases from \sim 30% for 1000 ppm to \sim 5% for 20 ppm of NH₃ which is well above the background noise level. Typical NH₃ gas sensors operate in the 1 to 0.1% range of NH₃ concentrations in air. For example in Ref. 2, the individual SWNT device was used to detect \sim 0.1% (i.e. 1000 ppm) of NH₃ in air. Here

Figure 3 | Reversibility and sensitivity of the GF sensor for detection of NH₃ and NO₂. (a) Normalized change in electrical resistance of the GF as a function of time for detection of \sim 1000 ppm of NH₃ in three cycles. With Joule heating during the desorption step, the GF sensor exhibits a fully reversible response. (b) Normalized resistance change vs. time for different concentrations of $NH₃$ in air. The adsorption step is performed at room temperature, while Joule heating to \sim 400 K is used during desorption. (c) Corresponding normalized resistance change vs. time for different concentrations of $NO₂$ in air.

we detect $NH₃$ concentrations that are nearly two orders of magnitude lower (\sim 20 ppm) using a robust and inexpensive GF device that is also very easy to handle and use. Commercially available conducting polymer sensors²¹ undergo \sim 30% resistance change in 5–10 minutes when exposed to \sim 1% (10,000 ppm) of NH₃ at room

temperature. By contrast, the GF sensor undergoes \sim 30% resistance change at room temperature at an order of magnitude lower NH₃ concentration of \sim 1000 ppm (Fig. 3b). Other viable NH₃ sensor technologies such as metal oxide sensors require high temperature operation (between 300–500 $^{\circ}$ C) for adequate sensitivity²². These devices suffer from high power consumption due to their high working temperatures. Therefore the ability to detect gas species at room temperatures with high sensitivity and low production cost is of great practical relevance.

In addition to NH₃ we also explored the effectiveness of the GF sensor for $NO₂$ detection at room temperature and atmospheric pressure. Explosives such as nitrocellulose gradually degrade and a byproduct is known to be $NO₂$ gas, which provides a fingerprint for its detection. Monitoring environmental pollution effects related to combustion or automotive emissions also requires $NO₂$ detection in real-time. Figure 3c shows the normalized change in the GF resistance ($\Delta R/R$) as a function of time for different concentrations of NO₂ ranging from 200 ppm down to 20 ppm. $NO₂$ appears to act as a p-type dopant for the GF resulting in a decrease in the resistance. The Δ R/R of the GF device decreases from \sim 16% for 200 ppm to \sim 4% for 20 ppm of NO₂. As before Joule heating of the sample to \sim 400 K using 125 mA control current was effective in achieving full reversibility of the sensor response. Compared to this commercial polypyrole conducting polymer sensors can detect $\sim 0.1\%$ (1000 ppm) of NO₂ by an \sim 10% resistance change in \sim 5–10 minutes at room temperature²¹. The GF sensor shows a comparable resistance change at room temperature at an order of magnitude lower $NO₂$ concentration (Fig. 3c). Other commercial $NO₂$ detectors (e.g. metal oxide sensors such as Cd -doped $SnO₂$) are limited by high power consumption requirements since they require elevated temperature operation ($>$ 200 $^{\circ}$ C) for adequate sensitivity^{22–23}.

We have demonstrated the effectiveness of macroscopic and continuous graphene foam-like 3D networks for the high sensitivity detection of $NH₃$ and $NO₂$ at room temperature and atmospheric pressure. Large sheets (several tens of inches in dimensions) of GF can be synthesized using thermal CVD and then cut into tens or even hundreds of smaller foams which can be directly used in the asproduced state. The cost and complexity of sensor fabrication, maintenance and operation are therefore likely to be lower as compared to individually deposited or cleaved graphene sheets that must be patterned lithographically to establish electrical contacts. By contrast, the GF device is mechanically robust, flexible and can be handled easily. Contacts to the macroscale foams can be established by simply attaching wires using silver epoxy. Importantly, the GF structures also offer high sensitivity of gas detection in the ppm range. Since the walls of the foam are comprised on average of only few-layer graphene films, charge carrier transport through the foam is highly sensitive to the adsorption/desorption of gas species. The very large porosity of the foam also makes it possible for gas molecules to infiltrate uniformly into the entire structure resulting in high sensitivity and stable operation of the device. Moreover, Joule-heating can be used to expel chemisorbed gas molecules on the GF leading to fully reversible operation. The simple, low-cost sensors described here could be deployed for a variety of applications, such as environmental monitoring, sensing in chemical processing plants, and gas detection for counter-terrorism.

Methods

Graphene Foam (GF) Synthesis: To fabricate the GF, a scaffold of porous nickel foam is used as a template for the deposition of graphene. Chemical vapor deposition (CVD) is used to deposit carbon atoms on the nickel foam using $CH₄$ decomposition at \sim 1000 $^{\circ}$ C under ambient pressure. The nickel scaffold is then removed using chemical etching by a hot HCl (or FeCl₃) solution. To maintain the integrity of the foam during the etching of the Ni and to prevent it from collapsing, a thin layer of poly(methyl methacrylate) (PMMA) is also deposited on the surface of the graphene formed on the nickel foam. In the final step the PMMA layer is dissolved by hot acetone resulting in a free-standing three-dimensional graphene network structure. Additional details regarding the process are provided in Reference 17.

Electrical Conductivity Measurements: The foam is cut into small pieces of \sim 2 mm in width and \sim 10 mm in length and then connected to a chip carrier using thin copper wires at four different points. The contacts to the wires are simply made using conductive silver epoxy (EJ-2189 two part kit from EPOXY Technology) on the foam side, and wire bonding on the chip carrier side. The four leads of the chip carrier are then connected to a current source and voltmeter to conduct the four-probe measurement test using LabView. The four-probe method is important in that it eliminates the effect of contact resistances. In such a configuration, the sensor response depends only on the changes in resistance of the graphene sheet and spurious effects related to the role of the electrical contacts are removed.

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Author contributions

NK and HMC planned the experiments. ZC and WR fabricated the graphene foam. FY, AVT and NK performed the gas sensing experiments and processing of the data. All authors contributed to the discussion of the results. HMC and NK wrote the paper.

Additional information

Supplementary information accompanies this paper at [http://www.nature.com/](http://www.nature.com/scientificreports) [scientificreports](http://www.nature.com/scientificreports)

Competing financial interests: The authors declare no competing financial interests.

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