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Rigid, Complete Annuloplasty Rings Increase Anterior Mitral Leaflet Strains in the Normal Beating Ovine Heart

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Abstract

Background—Annuloplasty ring or band implantation during surgical mitral valve repair perturbs mitral annular dimensions, dynamics and shape, which have been associated with changes in anterior mitral leaflet (AML) strain patterns and suboptimal long-term repair durability. We hypothesized that rigid rings with non-physiological 3-D shapes, but not saddle-shaped rigid rings or flexible bands, increase AML strains.

Methods and Results—Sheep had 23 radiopaque markers inserted: 7 along the anterior mitral annulus and 16 equally spaced on the AML. True-sized Edwards Cosgrove flexible, partial band (COS, n=12), rigid, complete St. Jude saddle-shaped annuloplasty ring (RSAR, n=12), Carpentier-Edwards Physio (PHYSIO, n=12), Edwards IMR ETlogix (ETL, n=11) and Edwards GeoForm (GEO, n=12) annuloplasty rings were implanted in a releasable fashion. Under acute open-chest conditions, four-dimensional marker coordinates were obtained using biplane videofluoroscopy along with hemodynamic parameters with the ring inserted and after release. Marker coordinates were triangulated and the largest maximum principal AML strains were determined during isovolumetric relaxation (IVR). No relevant changes in hemodynamics occurred. Compared to the respective Control state, strains increased significantly with RSAR, PHYSIO, ETL and GEO ($0.14\pm0.05 vs. 0.16\pm0.05, p=0.024, 0.15\pm0.03 vs. 0.18\pm0.04, p=0.020, 0.11\pm0.05 vs. 0.14\pm0.05, p=0.042$ and $0.13\pm0.05 vs. 0.16\pm0.05, p=0.009$), but not with COS ($0.15\pm0.05 vs. 0.14\pm0.05 vs. 0.15\pm0.04, p=0.973$).

Conclusions—Regardless of 3-D shape, rigid, complete annuloplasty rings, but not a flexible, partial band, increased AML strains in the normal beating ovine heart. Clinical studies are needed

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to determine if annuloplasty rings affect AML strains in patients, and, if so, whether ring-induced perturbations in leaflet strain states are linked to repair failure.

Keywords

mitral valve; physiology; mitral regurgitation; surgery

INTRODUCTION

Surgical mitral valve repair most commonly includes the insertion of an annuloplasty band or ring. While bands are flexible devices that spare the anterior, fibrous portion of the mitral annulus, rings encircle the entire annulus and may be either flexible, semi-rigid or rigid. Rigid rings are available in various shapes. The most commonly used ring (Carpentier-Edwards Physio) is flat, semi-rigid and D-shaped. Recently, saddle shaped, rigid, complete annuloplasty rings have been introduced (e.g. Saint Jude Medical RSAR, Medtronic Profile 3-D or Carpentier-Edwards Physio II) in order to account for the physiological 3-D shape of the mitral annulus [1, 2]. Furthermore, rigid rings with non-physiological shapes and dimensions have been designed specifically for patients with functional/ischemic mitral regurgitation (e.g. Edwards GeoForm and IMR ETLogix). These rings aim to counteract the main determinants of functional/ischemic mitral regurgitation (i.e. mitral annular dilatation, left ventricular (LV) dilatation and papillary muscle displacement) on an annular level via their specific designs, all of which include disproportionate annular septal-lateral downsizing [3]. While some studies demonstrate that such rings may reduce mitral leaflet strains in the diseased heart [4], other studies suggest that, by perturbing the natural mitral annular saddle-shape, disease-specific or non-physiologically shaped rings may increase leaflet strains in the normal heart [5-7]. Due to these results from *in vitro* measurements the authors speculate that such perturbations in mitral leaflet strain patterns could be associated with impaired long-term results after mitral valve repair [5-7]. Our goal was, therefore, to assess the effects of one flexible partial band and four different, complete annuloplasty rings on anterior mitral leaflet strains in healthy, beating ovine hearts. We tested the hypothesis that rigid, complete rings with non-physiological 3-D shapes, but not saddle-shaped rigid rings or flexible partial bands, increase maximum principal strains across the anterior mitral leaflet.

METHODS

All animals received humane care in compliance with the Principles of Laboratory Animal Care formulated by the National Society for Medical Research and the Guide for Care and Use of Laboratory Animals prepared by the National Academy of Sciences and published by the National Institutes of Health (DHEW [NIH] Publication 85 to 23, revised 1985). This study was approved by the Stanford Medical Center Laboratory Research Animal Review Committee and conducted according to Stanford University policy.

Surgical Preparation

Fifty nine adult, Dorsett-hybrid, male sheep (49±5kg) were premedicated with ketamine (25mg/kg intramuscularly), anesthetized with sodium thiopental (6.8mg/kg intravenously), intubated and mechanically ventilated with inhalational isoflurane (1.0-2.5%). A left thoracotomy was performed and the heart was suspended in a pericardial cradle. Thirteen miniature radiopaque tantalum markers were surgically implanted into the sub-epicardium to silhouette the LV chamber at the intersections of two longitudinal and three crosswise meridians as shown in Figure 1A. Using cardiopulmonary bypass and cardioplegic arrest a total of 33 radiopaque tantalum markers were sewn to the following sites (Figure 1B): 16

around the mitral annulus (17-32, Fig 2A, B), 16 equally spaced on the atrial aspect of the anterior mitral leaflet (AML, 1-16, Fig 2B) and 1 on the central edge of the middle scallop of the posterior mitral leaflet (PML, 33, Fig 2B). A single tantalum loop (0.6mm ID, 1.1mm OD, 3.2 mg) was used for each leaflet marker.

After marker placement, five different annuloplasty ring models, the Cosgrove-Edwards band (COS, Edwards Lifesciences, Irvine, CA, USA, n=12), St. Jude Medical rigid saddle ring (RSAR, St. Jude Medical Inc, St. Paul, MN, USA, n=12), Carpentier-Edwards Physio (PHYSIO, n=12), Edwards IMR ETlogix (ETL, n=11) and Edwards GeoForm (GEO, n=12, all three Edwards Lifesciences, Irvine, CA, USA) were implanted in a releasable fashion as described earlier [8]. In brief, the annuloplasty devices were prepared before the operation in the following manner: The middle parts of eight double-armed polyester braided sutures were stitched evenly spaced around the ring or band from the bottom to the top side using a "spring eye" needle. The resulting loops were "locked" with two polypropylene sutures. The polyester sutures were stitched equidistantly in a perpendicular direction from the ventricular to the atrial side through the mitral annulus. The annuloplasty devices were secured to the mitral annulus by tying these sutures. The "locking sutures" (polypropylene) and the drawstrings were exteriorized before closing the atrium. Ring and band sizes were determined by assessing the entire area of the anterior mitral leaflet using a sizer from Edwards Lifesciences. All annuloplasty devices were true-sized (as all animals had similarly sized leaflets, each received size 28 rings or bands). The left atrium (LA) was closed and the left circumflex artery (LCx) was encircled with a vessel loop for a parallel study [9]. Data from mitral annular and leaflet geometry using this dataset have been published earlier [8-11]. The animals were then transferred to the experimental catheterization laboratory for data acquisition under acute open-chest conditions.

Data Acquisition

Videofluoroscopic images (60 frames/sec) of all radiopaque markers were acquired using biplane videofluoroscopy (Philips Medical Systems, North America, Pleasanton, CA, USA). First, images were acquired under baseline conditions with the ring inserted (COS, RSAR, PHYSIO, ETL, GEO). Following the data acquisition under baseline conditions, 90sec of ischemia were induced, for a parallel study, by tightening the encircling LCx vessel loop with a tourniquet. Thereafter, the "locking sutures" were pulled out and the ring was lifted away from the mitral annulus towards the left atrial roof using the drawstrings. After hemodynamic values returned to baseline, a third data acquisition was performed and images were acquired under baseline conditions with the ring released (COS-CTRL, RSAR-CTRL, PHYSIO-CTRL, ETL-CTRL, GEO-CTRL). Marker coordinates from two consecutive sinus rhythm heart beats from each of the biplane views were then digitized and merged to yield the 3-D coordinates of each marker centroid in each frame using semi-automated image processing and digitization software [12]. Simultaneously, analog left ventricular pressures (LVP) as well as electrocardiogram (ECG) signals were recorded in real-time on the video images during data acquisition.

Hemodynamic Parameters and Cardiac Cycle Timing

For each beat, the end-diastolic videofluoroscopic frame was defined as the frame that coincided with the peak of the R-wave on the ECG. In order to calculate leaflet strains, a reference configuration during diastole and a deformed configuration during peak systole were determined for each beat (t_0 and t_n , respectively, Figure 2). When defining these configurations the goal was to quantify strains with the mitral valve closed in both configurations and maximize the LVP difference between the two time points. To identify the reference configuration, the distance between AML central edge (#4, Figure 1B) and PML edge marker (#33, Figure 1B) was plotted throughout the cardiac cycle for each

animal. For each heartbeat the time point of leaflet opening was defined as the time point immediately before the AML and PML started to separate (Figure 2), thereby defining the reference state for beat 1 (t₀₁, Figure 2) and beat 2 (t₀₂, Figure 2). To identify the deformed configuration, LVP curves were plotted throughout the cardiac cycle. The time point of maximum LVP for each heartbeat was defined as the deformed state (t_{n1} and t_{n2}, respectively, Figure 2). The embedded period between these two states closely reflects the period of isovolumetric relaxation (IVR, Figure 2). Maximum systolic dP/dt (dP/dt_{max}) was calculated for each beat for each animal. LV volumes (LVV) were calculated from space-filling tetrahedral fit between all LV markers at each beat at end-diastole (LVEDV), t_{n1}, t_{n2}, t₀₁ and t₀₂ (See Ref [13] for details). Changes in LVP and LVV (Δ_{LVP} and Δ_{LVV} , respectively) from t₀₁ to t_{n1} and from t₀₂ to t_{n2} were calculated as LVPt_{n1} – LVPt₀₁, LVPt_{n2} – LVVt₀₂, respectively.

Mitral Annular Dimensions

At t_{n1} , t_{n2} , t_{01} and t_{02} distances between markers #20 and #28 and those between #32 and #24 (Figure 1B) were calculated to determine septal-lateral (S-L) and commissure-commissure (C-C) annular dimensions, respectively. Changes in mitral annular S-L and C-C dimensions (Δ_{S-L} and Δ_{C-C} , respectively) from t_{01} to t_{n1} and from t_{02} to t_{n2} were calculated as $t_{n1} - t_{01}$ and $t_{n2} - t_{02}$.

Global Maximum Principal (global ϵ_{max}), Radial (global ϵ_{rad}) and Circumferential (global ϵ_{cir}) Strains

In order to determine the largest (global) maximum principal, radial and circumferential strains across the entire leaflet, the 16 AML mitral leaflet markers (#1-#16, Figure 1B) and the seven mitral annular markers (#17-#23, Figure 1B) were triangulated and 30 triangular membrane elements were generated. For each triangle, the co- and contravariant base vectors at time points t₀₁, t_{n1}, t₀₂, and t_{n2}, were calculated to determine the corresponding metric tensors and the resulting Euler-Almansi strain tensors for beats 1 and 2. The direction defined by the belly markers #9 and 11# (Figure 1B) in the deformed configuration, i.e., at times t_{n1} and t_{n2} for beat 1 and beat 2, respectively, was interpreted as the circumferential direction. The radial direction was defined orthogonal to the circumferential axis, passing through belly marker #10 (see Fig 1B). The largest projections of the Euler-Almansi strain tensor onto the circumferential and radial directions were defined as global maximum circumferential strain (global ε_{cir}) and global maximum radial strain (global ε_{rad}), respectively. These values were determined for two beats in each animal, and each state (with and without annuloplasty device implanted). The animal global maximum principal strain (global ε_{max}) was calculated as the two-beat average for each animal and each state by solving the eigenvalue problem for the Euler-Almansi strain tensor.

Maximum Principal (ϵ_{max} ,), Radial (ϵ_{rad}) and Circumferential (ϵ_{cir}) Strains Across the Entire Anterior Mitral Leaflet

In order to provide a qualitative description of changes in strain patterns across the entire AML with and without annuloplasty device implanted, the two-beat averages of ε_{max} , ε_{rad} and ε_{cir} values of each triangular element were calculated for each animal in each state. These values were averaged for all animals (by extrapolating constant average element strains to the individual marker positions using super-convergent patch recovery to obtain smoothly varying strain profiles) and plotted onto color mapped schematics.

Statistical Analysis

Average values of all animals in the respective groups were reported as mean ± 1 SD. All data reported for individual animals and all data used for quantitative statistical comparisons

are two beat averages. Data with and without annuloplasty ring (or band) were compared using 1-way repeated-measures analysis of variance with a Holm–Sidak post hoc test (Sigmaplot 11.0, Systat Software Inc). To look at strain differences between the ring groups, maximum principal (ε_{max} ,), radial (ε_{rad}) and circumferential (ε_{cir}) strains with rings (COS, RSAR, PHYSIO, ETL and GEO) were compared using 1-way analysis of variance. A *P* value of less than .05 was considered statistically significant.

RESULTS

Heart rate, LVEDV and dP/dt_{max}

Group mean heart rates, LVEDVs and dP/dt_{max} are shown in Table 1. No significant differences were found between ring and Control states in all five groups (except for Cosgrove, where dP/dt_{max} was slightly higher compared to Control).

LV Pressures and Volumes at Reference State (t₀) and Deformed State (t_n)

Table 2 shows LVPs and LVVs at t_0 and t_n as well as Δ_{LVP} and Δ_{LVV} . Δ_{LVP} and Δ_{LVV} are also graphically depicted in Figure 3 (top row). A significant increase in LVPs by approximately 80mmHg (note that changes in LVP and LVV (Δ_{LVP} and Δ_{LVV}) are described from t_0 to t_n , i.e. backward in time) occurred in both ring and Control states from t_0 to t_n , while no relevant LVV changes were observed.

Mitral Annular Dimensions at Reference State (t₀) and Deformed State (t_n)

Table 3 shows the mitral annular S-L and C-C dimensions at t_n and t_0 as well as Δ_{S-L} and Δ_{C-C} . Δ_{S-L} and Δ_{C-C} are also graphically depicted in Figure 3 (middle row). Again, please note that Δ_{S-L} and Δ_{C-C} are described from t_0 to t_n , i.e. backward in time. Consequently, negative Δ_{S-L} and Δ_{C-C} represent an increase, whereas positive Δ_{S-L} and Δ_{C-C} represent a decrease in the respective dimension during the regular cardiac cycle. Relative to Control, implantation of either complete, rigid rings (RSAR, PHYSIO, ETL or GEO) or the flexible band (COS) resulted in significantly smaller mitral annular S-L and C-C dimensions. Decreases in S-L and C-C diameters from t_0 to t_n (negative Δ_{S-L} and Δ_{C-C} , Table 3) were observed for the Control cases (all groups). With the annuloplasty device implanted, the S-L dimension became slightly smaller from t_0 to t_n with COS (Δ_{S-L} : -0.9 ± 0.5 mm, Table 3 and Figure3, middle row) while no relevant decreases in S-L and C-C diameters from t_0 to t_n were found with RSAR, PHYSIO, ETL or GEO.

Global Maximum Principal (global ϵ_{max}), Radial (global ϵ_{rad}) and Circumferential (global ϵ_{cir}) Strains

Table 4 shows global ε_{max} , ε_{rad} and ε_{cir} for all five groups with and without annuloplasty devices implanted. Global ε_{max} , ε_{rad} and ε_{cir} (average from all animals) are also graphically displayed in Figure 3 (bottom row). Compared to the respective Control state, strains increased significantly with RSAR, PHYSIO, ETL and GEO (0.14±0.05 *vs.* 0.16±0.05, p=0.024, 0.15±0.03 *vs.* 0.18±0.04, p=0.020, 0.11±0.05 *vs.* 0.14±0.05, p=0.042 and 0.13±0.05 *vs.* 0.16±0.05, p=0.099, respectively, all p<0.05), but not with COS (0.15±0.05 vs. 0.15±0.04, n.s., p=0.973). Global ε_{rad} increased significantly compared to the Control state only with RSAR, while greater global ε_{cir} values were found with RSAR, PHYSIO, ETL and GEO (however, insignificant for GEO, Table 4). No significant changes in global ε_{rad} or ε_{cir} were found with COS compared to the Control state. With no annuloplasty device implanted, global ε_{rad} was greater than global ε_{cir} in all five groups (COS-CTRL, RSAR-CTRL, PHYSIO-CTRL, ETL-CTRL, GEO-CTRL, Table 4 and Figure 3, bottom row). With annuloplasty device implanted, global ε_{rad} values were either greater than global ε_{cir} (COS, RSAR), smaller (PHYSIO) or similar (ETL, GEO, Table 4 and Figure 3, bottom row). No

differences in ε_{max} (p=0.331, F=1.178), ε_{rad} (p=0.188, F=1.598) or ε_{cir} (p=0.160, F=1.716) with rings implanted were found between the groups (COS, RSAR, PHYSIO, ETL and GEO).

Maximum Principal (ϵ_{max}), Radial (ϵ_{rad}) and Circumferential (ϵ_{cir}) Strains Across the Entire Anterior Mitral Leaflet

Figure 4 shows ε_{max} , ε_{rad} and ε_{cir} across the entire AML for both states, with and without annuloplasty device implanted in all five groups. Increases in ε_{max} can be appreciated with RSAR, PHYSIO, ETL and GEO compared to the respective Control state and predominantly occur in the belly and edge region of the anterior mitral leaflet. No major changes in strain patterns (ε_{max} , ε_{rad} or ε_{cir}) were observed with COS. ε_{max} values across the AML of the respective Control states were slightly different between groups with COS-CTRL, RSAR-CTRL and PHYSIO-CTRL being more strained than GEO-CTRL and ETL-CTRL.

DISCUSSION

The principle finding of this study was that, with no relevant changes in hemodynamics, implantation of rigid, complete annuloplasty rings (RSAR, PHYSIO, ETL and GEO), but not of the flexible partial band (COS), increased global maximum principal strains of the AML. These changes predominantly occurred in the region of the AML belly and edge.

Several studies have determined mitral leaflet strains and stretches using a variety of different techniques [4-7, 14-19]. *In vitro* studies have been employed to characterize dynamic stretches on the anterior and posterior leaflet of excised porcine mitral valves using a left heart simulator [6, 14-17]. *In vivo* studies, using sonomicrometer technology, quantified AML strains in the beating ovine heart [16] and lastly, finite element studies investigated strain patterns across the AML [4, 5, 18, 19].

Salgo et al. demonstrated in a numerical simulation that the native mitral annular shape is important to minimize stresses acting on the leaflet [5]. In a previous analysis from the same dataset we demonstrated that implantation of the Physio, IMR ETLogix and GeoForm, but not RSAR, perturbed the physiological saddle-shape of the mitral annulus [11]. The increased maximum principal leaflet strains observed with these three rings are therefore consistent with engineering intuition quantified through the results of Salgo et al.. However, to our surprise, the supposedly physiologically shaped RSAR also led to an increase in maximum principal leaflet strains. Assuming that the shape of this ring is physiological it could be speculated that the dynamic motion of the mitral annulus rather than its 3-D shape is of major importance to preserve AML strain distribution. This hypothesis, however, is contrary to previous studies that suggested changes in the physiological mitral annular 3-D saddle shape lead to increases in leaflet strains [6]. It may therefore also be speculated that the shape of the RSAR does not fully represent the natural 3-D annular shape and that, as discussed earlier [6], increased strains are also a result of a non-physiological annular shape.

The partial, flexible band (COS) has been found to preserve the mitral annular saddle shape [11] and allow minimal mitral annular S-L dynamics (Figure 3, middle row) during the observed time period (from t_0 to t_n). However, COS significantly reduced mitral annular dimensions compared to the Controlstate (Table 3 and Ref [11]). Since COS did not affect AML strains (Figure 3, bottom row) we speculate that preserving physiologic mitral annular dynamics and shape rather than absolute mitral annular dimensions are the key components to maintaining a physiological strain distribution across the AML.

To our knowledge, Votta et al. were the only group that quantified the effects of annuloplasty rings (GeoForm and Physio) on mitral leaflet strains and stresses [4]. The group used a finite element model and demonstrated that the GeoForm, but not the Physio, reduced maximum principal mitral leaflet stresses during simulated functional mitral regurgitation [4]. In our study we found that all rigid rings (RSAR, PHYSIO, ETL and GEO) increased maximum principal AML strains, irrespective of their 3-D shape. However, unlike Votta et al., we used an *in vivo* model of the normal, beating heart. We therefore cannot comment on the potential effects of FMR/IMR rings in the diseased state and it is possible that these rings restore a physiological strain distribution in hearts with dilated LVs.

In our study we report the effect of different annuloplasty devices on radial and circumferential strains. While global ε_{rad} was only greater with RSAR, global ε_{cir} was greater with all rigid, complete rings (RSAR, PHYSIO, ETL and GEO, Table 4) compared to the Control state (however, insignificantly for GEO), suggesting that rigid, complete annuloplasty devices affect circumferential strains more than radial strains. The reason for the insignificant increase in global ε_{cir} observed with GEO could be a result of the larger commissure to commissure dimension of this ring compared to RSAR, PHYSIO or ETL [3], suggesting that the physiological circumferential AML strain distribution is sensitive to the amount of mitral annular C-C decrease.

Study Limitations

Several limitations should be addressed to allow a better interpretation of these data. First, the data were acquired from open-chest, anesthetized ovine hearts with normal preoperative anatomy. Considerable caution must therefore be exercised when extrapolating these findings to the human heart. This is especially true for the GeoForm and IMR ETLogix rings that have been designed for patients with IMR/FMR (with distorted annular, leaflet and ventricular geometry and function). As mentioned above, if these rings are implanted in the setting of FMR/IMR, it could well be that they reduce (or restore physiological) leaflet strains as demonstrated by Votta and colleagues in a computer simulation [4]. In future analyses we aim to use our experimental in vivo data to determine whether these two FMR/ IMR-specific rings (GEO and ETL) are more efficient than conventional rings in terms of reducing leaflet strains during acute myocardial ischemia. Second, AML strains were quantified for only the IVR phase of the cardiac cycle and it could be that the rings affect strain patterns differently in other phases of the cardiac cycle [20]. Third, although perturbed leaflet strains have been associated with impaired mitral valve repair durability [6, 7] currently no study exists that proves causation. Consequently, it remains to be determined whether perturbations in AML strains impair long-term function of the mitral valve after repair. Fourth, when radial and circumferential strains were plotted onto color mapped schematics (Figure 4), we did not only observe tensile, but also compressive strains in both Control states and with rings implanted (green and blue areas, Figure 4). Compressive strains do not occur, e.g., in purely computational models that use simplified AML shapes with the leaflet being entirely convex to the left ventricle [4] and, thus, may be a result of the complex AML shape [21] that was included in our analyses. The finding of compressive strains warrants further investigation; however, we focused on the tensile aspects of strain in this manuscript and did not perform detailed analyses of compressive strain patterns. Fifth, no statistically significant differences in strains were found between the different ring types. We therefore cannot draw any conclusions from these data whether one ring design is superior to another; however, this study was not adequately powered to demonstrate differences between the different ring types. Sixth, we only studied a partial, flexible band. Since no complete, flexible ring was examined in this experiment it is not possible to distinguish whether the observed lack of increase in AML strains with a partial band is due to its partial design, its flexibility, or due to a combination of the two. Lastly, strain patterns

Conclusions

In conclusion, regardless of their three-dimensional shape, rigid, complete annuloplasty rings (RSAR, PHYSIO, ETL, GEO), but not a partial flexible band (COS), increased maximum principal anterior mitral leaflet strains predominantly in the belly and edge regions in the normal beating ovine heart. Large, randomized, clinical trials are needed to answer the question whether the observed ring-induced alterations in mitral leaflet strain states exist in patients, and if so, whether they adversely affect long-term mitral valve repair durability.

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Fig 1.

A: Schematic illustrating ventricular and annular marker locations. Marker #20 represents the mitral annular saddle horn marker and markers #17 and #23 the anterior and posterior commissural markers, respectively. **B**: Schematic magnification of a top view of the mitral valve showing annular as well as leaflet markers. Sixteen markers were placed on the mitral annulus (#17-#32), 16 markers were placed on the anterior mitral leaflet (#1-#16) and one marker was placed on the free edge of the mid part of the posterior leaflet (#33). Inset shows the radial (rad) and circumferential (cir) directions used for strain definitions.



Fig 2.

Illustration of time point definitions. Time point t_n (strained state) was defined as maximum LV pressure for beat 1 (t_{n1}) and beat 2 (t_{n2}). Time point t_0 (reference state) was defined as last time frame before mitral leaflet separation (as represented by the rapid increase in plotted curve of distances (cm) between marker #33 and #4, see Fig 1) for beat 1 (t_{01}) and beat 2 (t_{02}).



Fig 3.

Changes in LV pressure and volumes (Δ LVP and Δ LVV, respectively (top row), mitral annular dimensions (middle row) from reference state (t₀) to strained state (t_n) as well as global maximum principal (ϵ_{max}), radial (ϵ_{rad}) and circumferential (ϵ_{cir}) (bottom row). Note that changes from t₀ to t_n include a calculation from a time point later in the cardiac cycle (t₀) to an earlier time point of the cardiac cycle (t_n). COS=Edwards Cosgrove band, RSAR=St Jude Medical rigid saddle-shaped annuloplasty ring, ETL=Edwards IMR ETlogix, GEO=Edwards GeoForm. Values are mean±1SD.



Fig 4.

Color-mapped schematics of maximum principal (ϵ_{max} , two top rows), radial (ϵ_{rad} , two middle rows) and circumferential (ϵ_{cir} , two bottom rows) strains across the entire anterior mitral leaflet for the Control state (CTRL) and with annuloplasty device implanted (RING). Markers #17 and #23 depict anterior and posterior commissures, respectively, marker #20 represents the mid-septal mitral annulus (saddle horn, see Figure 1). COS=Edwards Cosgrove band, RSAR=St Jude Medical rigid saddle-shaped annuloplasty ring, ETL=Edwards IMR ETlogix, GEO=Edwards GeoForm.

Heart rate (HR), LV end-diastolic volume (LVEDV) and dP/dt_{max}

Animal no

TABLE 1

P vs. CTRL LVEDV P vs. CTRL dP/df _{max} P vs		120±15	1360±317	.914	121±16 .392	1527±386		121±22	1283±409	.853		121±20 .714	121±20 .714 1226±297	121±20 .714 1226±297 .	121±20 .714 1226±297 . 124±21	121±20 .714 1226±297 . 124±21 1307±333	121+20 .714 1226±297 . 124±21 1307±333 .517 .	121+20 .714 121+20 .714 1226+297 . 1226+297 . 1226+297 . 1307+333 1307+333 1307+333	121+20 .714 121+20 .714 126+297 . 124+21 .126+297 . 1207+333 .517
HR ain ⁻¹) P v	8±14			8±13			9±17			9±15				2±12	2±12	2±12	2±12	2±12	2±12
12 (n	94 9	22	128	94 9	19	240	77 8	38	125	74 8		40	40	40 212 90 9	40 212 90 9 28	40 212 90 9 28	40 212 90 9 560 88 9	40 212 28 560 88 9 28 88 9	40 212 28 28 88 9 28 28 560 560 560
11	85 9	49 1	346 1	86	49 1	70 12	87	23 1	08 1	85		23 1	23 1 582 1:	23 1 882 11 87 4	23 1. 82 1. 87 <u>5</u>	23 1 82 12 87 <u>5</u> 20 1 888 1:	23 1 88 1 88 1	23 1 82 12 88 1 20 1 21 20 22 1 20 1 23 1 23 1 23 1	23 1 82 11 87 9 20 1 23 1 23 1 23 1 23 1 23 1 23 1 23 1 23 1
10	113	122	564 8	111	122 1	636 5		136 1	232 7	67		133 1	111 6	111 (100	.33 1 111 6 100 126 1	33 1 111 6 111 6 111 6 126 1 126 1	33 1 111 6 100 1 126 1 126 1 129 8	33 1 33 1 111 6 111 6 111 6 111 6 111 6 111 6 111 6 111 6 111 6 111 6 111 6 111 6 111 6	33 1 111 € 111 € 111 € 111 € 128 1 128 1 362 5
6	100	113 1	478 1	97 1	111	739 1	901	113 1	039 1	104		1 11	111 1 087 1	111 1 087 1 88 1	1 11 087 1 88 1 89 1	111 1 087 1 88 1 89 1 948 1	11 1 087 1 88 1 99 1 91 1	11 1 087 1 88 1 99 1 91 1	11 1 087 1 99 1 948 1 91 - 91 - 91 - 91 - 126 1
×	90 1	00 1	238 1	06	00 1	294 10	86 1	56 1	381 1(85 1		49 1	49 1 011 10	49 1 011 10 82 8	49 1 011 10 82 8 19 9	49 1 011 10 82 8 19 9 19 9 116 19	49 1 011 10 82 8 19 9 19 9 10 19 116 19 82 5	49 1 011 10 011 10 10 19 10 19 11 19 12 19 13 19 14 19 15 19 16 19 17 19	49 1 011 10 10 10 10 10 10 10 116 19 116 19 116 19 118 9 118 9 126 14
٢	14	32 1	742 12	14	32 1	196 12	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	40 1	382 13	3 68		38 1	38 1 131 1(38 1 131 1(88 {	38 1. 131 1(88 8 24 1	38 1 131 10 131 10 24 1 24 1 014 1	38 1 131 10 133 10 24 1 014 1 88 1 88 1	38 1 131 10 131 10 38 8 14 1 14 1 14 1 15 1 25 1	38 1 131 10 131 10 24 1 214 1 88 8 88 5 106 10
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S	87	36 1	853 15	87	37 1	018 16	71 \$	22 1	055 17	73 5		24 1	24 1 145 1(24 1 145 16 99 {	24 1 145 16 99 8 26 8	24 1 145 16 99 8 26 8 343 1:	24 1 145 16 99 8 99 8 26 8 343 1; 03 8	24 1 145 16 99 8 26 8 343 15 16 1 16 1	24 1 145 16 99 8 99 8 343 15 333 15 16 8 16 8 683 1
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-	89 1	09 1	16 16	97 1	09 1	280 15	74 1	3 16	309 22	77 1	3 96		202 15	202 18 84 1	202 18 84 1 74 1	202 18 84 1 74 1 694 1	202 18 34 1 74 1 694 1 84 1	202 18 34 1 74 1 694 1: 84 1 78 1	202 18 34 1 74 1 694 1 78 1 78 1 896 1
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	HR (min ⁻¹)	LVEDV (ml)	dP/dt _{max} (mmH	HR (min ⁻¹)	LVEDV (ml)	dP/dt _{max} (mmH	HR (min ⁻¹)	LVEDV (ml)	dP/dt _{max} (mmH	HR (min ⁻¹)	LVEDV (ml)		dP/dt _{max} (mmH	dP/dt _{max} (mmH HR (min ⁻¹)	dP/dt _{max} (mmH HR (min ⁻¹) LVEDV (ml)	dP/dr _{max} (mmH HR (min ⁻¹) LVEDV (ml) dP/dr _{max} (mmF	dP/df _{max} (mmH HR (min ⁻¹) LVEDV (ml) dP/df _{max} (mmH HR (min ⁻¹)	dP/df _{max} (mmH HR (min ⁻¹) LVEDV (ml) dP/df _{max} (mmH HR (min ⁻¹) LVEDV (ml)	dP/df _{max} (mmH HR (min ⁻¹) LVEDV (ml) dP/df _{max} (mmH HR (min ⁻¹) LVEDV (ml) dP/df _{max} (mmF
		COS-			SOS			RSAR- CTRL			SAR				DHYSIO- CTRL	HYSIO-	HYSIO-	HYSIO- TRL	HYSIO- TRL HYSIO-

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Mean±1SD

							ł	Animal 1	10								Mean±1SD		
		1	2	3	4	ß	6	7	8	6	10	11	12	HR (min ⁻¹)	P vs. CTRL	LVEDV (ml)	P vs. CTRL	dP/dt _{max} (mmHg)	P vs. CTRL
	LVEDV (ml)	145	105	96	147	115	94	120	140	125	148	139				125±20			
	dP/dt _{max} (mmHg)	1879	681	1630	1064	1091	1348	1085	821	728	1322	1207						1169±368	
	HR (min ⁻¹)	09	<i>6L</i>	83	81	75	80	78	83	91	96	74		80±9	.531				
ETL	LVEDV (ml)	150	104	96	147	120	98	117	139	123	145	137				125±20	.833		
	dP/dt _{max} (mmHg)	1860	686	1591	1053	1098	1399	1073	874	772	1492	1188						1190±363	.259
	HR (min^{-1})	80	82	94	100	96	106	106	86	85	106	84	82	$92{\pm}10$					
GEO- CTRL	LVEDV (ml)	89	113	120	114	122	131	131	107	113	95	109	130			114±13			
	dP/dt _{max} (mmHg)	1030	1238	1298	1248	1469	1043	1163	1392	1138	1342	2221	1180					1313±315	
	HR (min ⁻¹)	83	<i>6L</i>	95	103	97	104	109	91	66	96	84	79	9 3±10	.492				
GEO	LVEDV (ml)	89	116	119	105	119	130	129	101	107	104	106	129			113±13	.223		
	dP/dt _{max} (mmHg)	1070	1259	1398	1144	1569	1181	1372	1509	1110	1321	2586	1131					1388±41	.070
All values fro	m individual animals	are two l	beat ave	rages, C(DS=Edw	'ards Cos	grove bé	und, RSA	∧R=St Ju	de Medi	cal rigid	saddle-s	shaped a	nnuloplasty	v ring, ETL= Ed	wards IMR	ETlogix, GEO=	Edwards Geo	Form, SD=stane

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		vs. CTRL												.323						
		Atn-t0 F						.3±2.5						.7±2.9						.7±3.0
		TRL						ŝ					8	3						4
		VV (ml) P vs. (.70							
		th L					96±13						96±14						97±17	
		s CTRL										.940								
	0	P ve				14						15						17		
	lean±1SI	L t0				92±						92±						92±		
	N	vs. CTR									.132									
		tn-t0 P			0±16						5±7						4±12			
) FRL A			×					~	~						õ			
		' (mmHg								.218										
		LVF tn		96±8						97±6						101±9				
		CTRL							188											
		P vs.							•••											
		t0	16±11						12 ± 6						16 ± 9					
		12	L	103	96	66	102	3.0	9	67	91	97	66	2.2	14	96	82	101	106	4.6
		11	18	88	69	108	112	4.0	12	92	81	109	116	7.3	17	95	78	103	106	2.9
(tn)		10	9	94	88	102	101	-0.6	2	76	95	101	101	-0.1	٢	98	91	102	108	6.2
l state		6	7	103	96	91	92	0.9	S	100	94	87	88	0.9	14	95	80	90	94	4.3
rainec		×	6	87	78	72	80	7.6	10	91	81	72	80	7.6	19	107	87	113	117	3.7
and st	on le	٢	15	95	79	86	92	6.1	15	98	83	80	88	8.0	25	107	82	109	113	3.5
e (t0)	Anima	9	12	100	88	81	82	1.8	17	107	90	81	85	3.9	15	125	109	81	89	8.4
e stat		w	24	109	85	94	76	3.7	24	109	85	89	94	4.4	11	76	86	83	93	10.3
ferenc		4	17	105	89	122	124	1.6	17	100	84	126	126	0.6	21	91	71	LL	79	1.7
s at re		3	45	82	37	88	89	1.1	18	90	71	101	102	0.8	12	101	89	113	120	6.6
lume		7	10	76	88	78	85	6.7	10	66	89	76	81	5.6	4	96	92	63	68	5.7
and vc		1	20	87	68	87	91	4.1	13	90	LL	90	93	3.6	39	100	61	75	74	-1.1
ssures			to	ţ,	$\Delta_{\mathrm{tn-t0}}$	to	f.	$\Delta_{\mathrm{tn-t0}}$	t ₀	t.	$\Delta_{\mathrm{tn-t0}}$	t_0	t,	$\Delta_{\rm tn-t0}$	t ₀	tn	$\Delta_{\mathrm{tn-t0}}$	t_0	t,	$\Delta_{\mathrm{tn-t0}}$
ular pre				LVP mmHg)			(ml)			LVP mmHg)			(ml) (ml)			LVP mmHg)			(ml)	
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TABLE 2

	vs. CTRL						.639												.657		
	Δtn-t0 P						5.0±2.9						1.6±3.3						1.8 ± 2.6		
	7 (ml) P vs. CTRL					.022												.236			
	LVV tn]					99±17						97±16						98±18			
	P vs. CTRL				.027												.285				
n±1SD	t0				94±17						95±16						97±17				
Mear	P vs. CTRL			.752												.221					
	Δtn-t0			83±10						76±15						78±15					
	nmHg) ' vs. CTRL		.144												.949						
	LVP (r tn P		9 8±5)5±8)5±6)5±5
	vs. CTRL	.040	5						5.					.124	5						
	t0 P	[4±7						$8{\pm}14$						7±15						[4 <u>+</u> 4	
	12	11	98	87	103	107	3.5	12 1	76	85	76	102	4.4	8	76	89	66	103	3.8	-	
	11	×	94	86	102	107	5.4	10	95	85	93	95	2.2	11	66	89	76	101	3.4	21	103
	10	7	97	90	102	107	4.8	37	101	64	105	100	-4.5	33	66	65	105	102	-2.8	11	98
	6	13	95	83	88	92	4.0	7	101	66	99	70	4.1	7	95	92	71	75	4.1	14	91
	8	18	101	82	115	121	6.0	5	96	91	95	100	5.6	3	96	93	98	100	1.9	11	91
l no	٢	18	95	LT	110	114	3.5	33	95	62	88	88	-0.1	29	76	67	87	87	0.4	15	105
Anima	9	13	109	96	81	89	7.5	41	76	56	72	69	-2.2	46	98	52	62	61	-1.6	13	89
	S	10	102	92	85	95	10.7	13	108	95	96	98	1.5	٢	103	96	95	95	0.4	17	06
	4	21	95	75	81	83	2.4	9	83	LL	113	116	2.7	4	87	83	119	122	3.4	15	92
	3	10	102	92	120	124	4.1	24	85	61	94	94	-0.1	26	86	60	76	100	3.4	10	98
	7	7	91	83	67	75	7.9	7	81	79	102	109	6.4	7	83	81	107	112	5.8	19	93
	1	33	92	59	75	75	-0.2	32	95	63	123	122	-1.1	28	97	69	123	123	-0.6	10	95
		t0	r,	$\Delta_{ m tn-t0}$	\mathbf{t}_0	t,	$\Delta_{\rm tn-t0}$	\mathbf{t}_0	t.	$\Delta_{\rm tn-t0}$	\mathbf{t}_0	4-	$\Delta_{\rm tn-t0}$	to	t,	$\Delta_{\rm tn-t0}$	\mathbf{t}_0	r,	$\Delta_{\rm tn-t0}$	t ₀	t
			LVP (mmHg)			(ml)			LVP (mmHg)			(ml)			LVP (mmHg)			(ml)		UV1	LVF (mmHg)
					KSAK					-OISYH9	CTRL					CIDINIC	PH YSIO			L'II	CTRL

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0 10 </th <th>1 2 3 4 5 6</th> <th>1 2 3 4 5 6</th> <th>2 3 4 5 6</th> <th>3 4 5 6</th> <th>4 5 6</th> <th>5 6</th> <th>Ŷ</th> <th></th> <th>٢</th> <th>x0</th> <th>9 1</th> <th>0 11</th> <th> 12</th> <th>t0</th> <th>Ρv</th> <th>s. CTRL</th> <th>th LVI</th> <th>P (mmHg) P vs. CTRI</th> <th>L Attr-</th> <th>t0 P vs. CTF</th> <th>KL t</th> <th>0 P vs. CTRL</th> <th>Ē</th> <th>LVV (ml) P vs. CTRl</th> <th>L Atn-t0</th> <th>P vs. CTI</th>	1 2 3 4 5 6	1 2 3 4 5 6	2 3 4 5 6	3 4 5 6	4 5 6	5 6	Ŷ		٢	x 0	9 1	0 11	12	t0	Ρv	s. CTRL	th LVI	P (mmHg) P vs. CTRI	L Attr-	t0 P vs. CTF	KL t	0 P vs. CTRL	Ē	LVV (ml) P vs. CTRl	L Atn-t0	P vs. CTI
0 104 107 104	$\Delta_{\rm In-t0}$ 85 74 88 77 73 75	85 74 88 77 73 75	74 88 77 73 75	88 77 73 75	77 73 75	73 75	75		68	80 7	17 8	6 8]							81±	9						
1 10 10 10 10 10 2 1 2 <th>t₀ 96 87 64 110 87 68</th> <td>96 87 64 110 87 68</td> <td>87 64 110 87 68</td> <td>64 110 87 68</td> <td>110 87 68</td> <td>87 68</td> <td>68</td> <td></td> <td>90 1</td> <td>04 10</td> <td>04 10</td> <td>11 11</td> <td>0</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>93:</td> <td>=16</td> <td></td> <td></td> <td></td> <td></td>	t ₀ 96 87 64 110 87 68	96 87 64 110 87 68	87 64 110 87 68	64 110 87 68	110 87 68	87 68	68		90 1	04 10	04 10	11 11	0								93:	=16				
3 10 1 9 3 10 10 112 00 4 10 112 00 30 112 114 114 8 10 10 11 114	t _n 123 89 77 115 95 70	123 89 77 115 95 70	89 77 115 95 70	77 115 95 70	115 95 70	95 70	70		91 1	12 10	05 11	5 12	0										101 ± 1	8		
3 10 12 142 142 00 8 8 8 8 3 30 8 8 13 5 94 30 1 14 13 5 95 95 95 1 14 13 3 3 13 34 36 1 1 3 3 3 14 30 35 35 35 35 35 36 <th>$\Delta_{\rm in-t0}$ 26.9 2.1 12.3 5.6 8.0 2.9</th> <td>) 26.9 2.1 12.3 5.6 8.0 2.9</td> <td>2.1 12.3 5.6 8.0 2.9</td> <td>12.3 5.6 8.0 2.9</td> <td>5.6 8.0 2.9</td> <td>8.0 2.9</td> <td>2.9</td> <td></td> <td>0.9</td> <td>7.5 0</td> <td>.7 7.</td> <td>1 9.</td> <td>5</td> <td></td> <td>7.6±7.4</td> <td></td>	$\Delta_{\rm in-t0}$ 26.9 2.1 12.3 5.6 8.0 2.9) 26.9 2.1 12.3 5.6 8.0 2.9	2.1 12.3 5.6 8.0 2.9	12.3 5.6 8.0 2.9	5.6 8.0 2.9	8.0 2.9	2.9		0.9	7.5 0	.7 7.	1 9.	5												7.6±7.4	
10 36 36 364 306 8 8 8 8 8 8 9 13 9 10 10 11 9 96±16 015 96±16 015 1 10 11 12 12 13 13 13 03±17 03±17 03±17 03±17 1 1 1 1 1 12 12 103±17 03±17 03±17 03±17 03±17 03±17 15 1 1 1 1 1 1 1 1 1 1 10 10 15	t ₀ 11 11 8 9 13 12	11 11 8 9 13 12	11 8 9 13 12	8 9 13 12	9 13 12	13 12	12		13	10 1	2 1	2 15	10	11	5	.010										
8 8 9 8 9 8 9	t) t _n 98 93 103 90 93 94 1	98 93 103 90 93 94 1	93 103 90 93 94 1	103 90 93 94 1	90 93 94 1	93 94 1	94 1	-	01	95 5	9 9	8 98	~				96±4	.306								
0 10 11 10 11 10 10 10 10 8 1 10 1 2 1 10	$\overline{\Delta}_{\text{in-t0}}$ 87 82 95 80 79 82 8) 87 82 95 80 79 82 8	82 95 80 79 82 8	95 80 79 82 8	80 79 82 8	79 82 8	82		88	85 8	3 8	7 83	~						85±	4 .080						
1 10 13 12 103±1	t ₀ 97 91 66 114 93 72 8	97 91 66 114 93 72 8	91 66 114 93 72 8	66 114 93 72 8	114 93 72 8	93 72 8	72 8	∞	9	06 1	07 10	11 11	5								96	-16 .015				
8 1 1 0 68±73 186 1 3 3 15 12-4 68±73 186 1 1 3 3 15 12-4 186 186 2 96 88 93 89 96 89±14 1 1 3 92 90 7 85±10 89±14 1 1 1 92 90 7 89±14 89±14 1	t _n 123 94 77 115 101 74 9	123 94 77 115 101 74 9	94 77 115 101 74 9	77 115 101 74 9	115 101 74 9	101 74 9	74 9	6		14 10	06 11	3 12	2										103±1	7 .034		
1 1 3 3 15 124 6 96 88 93 88 96:8 6 96 87 96 88 96:8 7 7 96:8 90 72 85:10 8 14 80 90 72 94:14 9 14 80 90 7 94:14 1 2 14 89:14 89:14 2 14 80 90 14:14 3 15 90 91 94:14 1 2 14 89:14 89:14 1 2 1 91 91 2 91 91 91 91:14 1 2 1 91:15 89:14 1 2 91 89 91 3 91 91 91 91	$\Delta_{\rm meto}$ 25.2 2.7 11.0 1.6 7.7 2.2 1.) 25.2 2.7 11.0 1.6 7.7 2.2 1.	2.7 11.0 1.6 7.7 2.2 1.	11.0 1.6 7.7 2.2 1.	1.6 7.7 2.2 1.	7.7 2.2 1.	2.2 1.		~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~		1.2 9.	1 6.	~												6.8±7.2	.186
96 88 93 88 94 92 92 73 85±10 85±10 14 83 15 81 90 74 15 81 90 78 89±14 89±14 16 81 90 74 89±14 89±14 17 80 90 74 89±14 89±14 18 90 74 89±14 89±14 89±14 19 90 78 90 89±14 89±14 89±14 10 90 90 90 90 91 91 91 91 10 10 10 10 10 10 10 11	t ₀ 18 13 33 16 17 8 11	- 18 13 33 16 17 8 11 	13 33 16 17 8 11	33 16 17 8 11	16 17 8 11	17 8 11	8 11	11		1	3 3	3	15	12±	6											
1 1	the construction of the co	98 91 100 111 105 105 80	91 100 111 105 105 80	100 111 105 105 80	111 105 105 8	105 105 80	105 80	ž	2	6 96	96 8	8 93	3 88				96±8									
0 84 85 90 1 92 74 53 9414 2 14 36 9414 3414 3 7.8 34 9414 3414 3 7.8 10 36 90 3 7.8 10 36 90 1 2 7 9 9414 3 14 36 90 1 2 10 36 90 1 2 9 9 9 9 1 2 9 9 9 9 9 1 2 9 9 9 9 9 9 1 2 9 9 9 9 9 9 1 9 9 9 9 9 9 9 9 1 9 9 9 9 9 9 13	$\Delta_{\rm In-10}$ 81 77 67 95 88 98 7:	, 81 77 67 95 88 98 7:	77 67 95 88 98 7:	67 95 88 98 7:	7: 86 88 75	5L 86 88	5L 86	1	10	95 5	3 8	5 9() 72						85±1	10						
1 24 74 54±14 7.8 2.4 -1.0 3.6 9.0 1 2 7 6 8 10± 5.1±4.8 1 2 7 6 8 10± .175 5.1±4.8 1 2 7 6 8 10±6 .175 5.1±4.8 1 2 9 9 9 9 8 10±6 .175 5.1±4.8 1 2 9 9 9 8 10±6 .175 5.1±4.8 1 2 9 9 9 .08 .175 .5.1±4.8 1 9 9 9 .06 .175 .589 .5.1±4.8 .5.1±4.8 1 9 9 9 .08 .5.89 .5.89 .5.89 .5.89 .5.85 .5.85 .5.85 .5.1±4.8 .5.1±4.8 .5.1±4.8 .5.1±4.8 .5.1±4.8 .5.1±4.8 .5.1±4.8 .5.1±4.8	t ₀ 70 74 99 86 102 118 99	70 74 99 86 102 118 99	74 99 86 102 118 99	99 86 102 118 99	86 102 118 99	102 118 99	118 99	66	_	84 8	88 7	5 8]	90								-68	-14				
7.8 1.4 -1.0 3.6 9.0 1 2 7 6 8 10±6 175 2 9 92 96 88 97±7 589 3 97 87±9 088 131 131 3 83 91 92 83 91 91 131	t_n 77 88 103 93 99 125 10	77 88 103 93 99 125 10	88 103 93 99 125 10	103 93 99 125 10	93 99 125 10	99 125 10	125 10	10	Ţ	92 5	00 2	4 85	66 5										94±14	-		
3 1 2 7 6 8 10±6 .175 2 96 92 96 88 97±7 .589 3 95 97 83 87±9 .088 8 83 91 92 81 .03	$\Delta_{\text{In-10}}$ 7.0 14.0 4.1 7.7 -3.9 7.8 2.	7.0 14.0 4.1 7.7 -3.9 7.8 2	14.0 4.1 7.7 -3.9 7.8 2.	4.1 7.7 -3.9 7.8 2.	7.7 -3.9 7.8 2.	-3.9 7.8 2.	7.8 2.	6	ε.	7.8 2	.4 –1	.0 3.	6 9.0												5.1 ± 4.8	
2 96 92 96 88 97±7 .589 3 95 97 85 90 81 87±9 .088 3 83 91 92 82 91 92 91 91±13 .131	t ₀ 17 10 24 15 14 8 8	17 10 24 15 14 8 8	10 24 15 14 8 8	24 15 14 8 8	15 14 8 8	14 8 8	8	×		-	5	9	×	$10\pm$	9	.175										
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	the	93 90 96 110 101 111 92	90 96 110 101 111 92	96 110 101 111 92	110 101 111 92	101 111 92	111 92	92		96 5	6 6	2 96	5 88				97±7	.589								
8 83 91 92 82 91 91 131 91±13 131	Δ_{tn-t0} 76 81 73 95 87 103	76 81 73 95 87 103	81 73 95 87 103	73 95 87 103	95 87 103	87 103	103		83	95 9	97 8	5 9() 81						87±	980. 6						
	t ₀ 74 77 102 86 98 122	74 77 102 86 98 122	77 102 86 98 122	102 86 98 122	86 98 122	98 122	122		98	83 5	1 9	2 82	2 91								91:	-13 .131				

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						Animal	00											Mean±	ISD					
															LVP	(mmHg)					ΓΛ	VV (ml)		
	1	7	e	4	w	9	٢	×	6	10	11	12	1 0	P vs. CTRL	ħ	P vs. CTRL	Atn-t0 P	vs. CTRL	t0	P vs. CTRL	tn	P vs. CTRL	Δtn-t0	P vs. CTRI
ťn	78	92	105	92	97	130	101	90	91	78	82 1	102									95±14	.289		
$\Delta_{\mathrm{tn-t0}}$	4.0	14.6	2.6	6.1	-1.6	7.9	2.5	7.0	0.6 –	-14.7	0.7 1	0.6											3.4±7.3	.175

All values from individual animals are two beat averages, t_n=strained state (time point of maximum LVP), t₀=reference strain state (time point before mitral valve opening, see METHODS), COS=Edwards Cosgrove band, RSAR=St Jude Medical rigid saddle-shaped annuloplasty ring, ETL= Edwards IMR ETlogix, GEO=Edwards GeoForm, SD=standard deviation

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TABLE 3

Mitral annular septal-lateral (S-L) and commissure-commissure (C-C) dimensions at reference state (t0) and strained state (tn)

		Anir	nal no																Me	an±1SD					
		T	6	6	4	o،	و	٢	œ	6	10	Π	12	60 F	P vs. CTRL	E	S-L P vs. CTRL	Δtn-t0	P vs. CTRL	8	P vs. CTRL	е	-C P vs. CTRL	Atm-t0 P	vs. CTRL
	t0	29.3	29.9	27.2	33.2	27.2	24.6	32.7	28.8	27.1	25.9	35.7	29.8	29.3±3.3											
	i-L t _n	27.9	27.4	26.3	28.7	23.0	22.7	30.5	27.5	24.9	26.1	34.6	26.9			27.2±3.2									
COS- CTRL	∆ tn-t0 t0) –1.4 36.2	-2.4 36.9	-1.0 34.6	-4.5 37.2	-4.2 36.9	-1.9 33.8	-2.2 40.4	-1.3 41.6	-2.2 42.4	0.2 36.5	-1.1 38.9	-2.9 39.0					-2.1±1.3		37.8±2.7					
J	C t _n	35.7	36.2	34.1	36.3	34.1	33.1	39.8	40.6	40.8	35.7	38.0	37.9								m	6.8±2.6			
	∆ tn-t0 t0) -0.4 23.5	-0.7 26.1	-0.5 26.0	-1.0 29.7	-2.8 23.9	-0.7 24.2	-0.6 30.6	-1.0 25.9	-1.6 24.5	-0.8 26.1	-0.9 32.2	-1.1 27.5	26.7±2.8	<.001									9.0±0.1	
	i-L t _n	22.9	25.5	25.2	29.1	22.5	22.9	28.9	25.7	23.7	25.5	31.8	26.2			25.8±2.8	800.								
COS	Δ tn-t0 t0) -0.6 30.6	-0.6 32.7	-0.9 32.0	-0.6 34.6	-1.5 32.6	-1.3 33.6	-1.7 38.3	-0.2 38.8	-0.7 38.0	-0.6 35.9	-0.4 35.2	-1.3 37.9					-0.9±0.5	900.	35.0±2.8	.004				
Ŭ	C t _n	30.4	32.6	31.7	34.4	32.3	33.4	38.1	38.3	38.1	35.2	34.8	37.6								(7)	4.7±2.8	.001		1
	∆ tn-t0 t0	0 -0.3 30.5	23.3	-0.3 27.5	-0.1 27.3	-0.3 27.6	-0.2 29.7	-0.2 29.1	-0.5 30.8	0.0 27.5	-0.7 33.9	-0.4 28.5	-0.3 30.4	28.8±2.6									Т	0.3±0.2	.002
	i-L t _n	30.0	22.9	26.4	27.3	25.9	28.3	27.7	27.1	25.3	30.5	26.6	28.7			27.2±2.1									
RSAR- CTRL	Δ tn-t0 t0) -0.5 37.6	-0.3 32.7	-1.1 32.9	0.0 35.2	-1.7 37.7	-1.4 35.6	-1.4 36.4	-3.8 40.1	-2.2 36.7	-3.5 42.1	-1.9 38.6	-1.7 40.4					-1.6±1.1		37.2±2.9					
J	tn th	36.6	32.5	32.5	34.7	36.3	34.1	35.5	38.0	36.7	41.1	37.3	40.0								(7)	6.3±2.7			
	∆ tn-t0 t0) –1.1 25.4	-0.2 23.7	-0.5 24.9	-0.5 24.1	-1.4 24.6	-1.6 25.8	-0.9 24.8	-2.2 25.0	0.0 23.5	-1.0 26.5	-1.3 24.7	-0.5 24.6	24.8±0.8	<.001								Т	9.0∓0.6	
RSAR	s-L t _n	25.2	24.0	24.6	23.9	24.5	25.7	24.6	24.9	22.9	26.4	24.8	24.4			24.6±0.9	<.001								

		Anima	ul no																Me	an±1SD					
		1	7	3	4	<u>م</u>	9	٢	×	6	1	1 12	-	t0 P	vs. CTRL	Ę	S-L P vs. CTRL	, Δtn-t0	P vs. CTRL	9	P vs. CTRL	E	C P vs. CTRL	Δtn-t0	P vs. CTRL
	Δ tn-t0	-0.2	0.3	-0.3	-0.3	-0.1	-0.1	-0.2	-0.2	- 9.0-	-0.1)- 1.	J.2					-0.2±0.2	.001						
	t0	34.5	33.4	33.7	33.8	33.8	34.6	34.3	33.1	31.1	33.0 5	31.8 35	3.8							33.4±1.	600. (
C	Ċ fa	34.3	33.6	33.7	33.8	33.8	34.5	34.5	33.4	31.3	33.1 3	11.8 32	6.8									33.5±1.0	.002		
	∆ tn-t6) -0.2	0.2	0.0	0.0	0.0	-0.1	0.2	0.3	0.1	- 1.0	-0.1 0.	0											0.1 ± 0.1	<.001
	t0	30.1	26.9	26.5	30.5	27.7	25.3	30.5	35.6	27.7	31.2 5	33.1 30).2 29.(6±3.0											
S	Ľ th	28.6	26.1	24.0	27.6	25.7	24.5	28.4	33.5	25.2	29.6 3	81.4 27	7.3			27.7±2.	6								
PHYSIO- CTRL	∆ tn-t() –1.5 42.6	-0.9 37.7	-2. 4 39.0	-2.9 42.0	-2.0 40.5	-0.8 36.7	-2.1 40.0	-2.1 43.6	-2.5 .	-1.7 - 37.9 4	-1.7 -< .0.5 39	3.0).6					-2.0±0.7		<u>39.9</u> ±2.					
C	Ċ Ĺ	41.2	39.1	37.5	41.4	39.9	35.7	39.4	43.2	37.1	37.9 3	9.3 38	3.4									39.1±2.1			
	Δ tn-t() -1.4 24.2	1.4 24.2	-1.6 24.6	-0.6 24.1	-0.6 23.5	-1.1 23.3	-0.6 25.0	-0.4 28.1	-1.9 (0.0 - 26.1 2	-1.2 -	1.3	9±1.4	<.001									−0.8±0.9	
S	Ĺ ħ	23.9	24.0	24.2	23.8	22.8	23.1	24.6	28.2	23.8	25.9 2	5.9 25	6.5			24.7±1.	5 <.001								
OISYHA	∆ tn-t() -0.2 33.0	-0.2 33.1	-0. 4 32.7	-0.2 34.9	-0.7 32.8	-0.2 32.7	-0. 4 32.7	0.1 33.7	-0.4 ·	-0.2 (32.6 3	0.0 –(1.5 32	0.3 2.6					-0.3±0.2	<.001	32.9±0.	<.001				
C	Ċ fa	33.1	33.1	32.7	34.8	32.8	32.6	32.8	33.9	32.9	32.9 3	11.7 32	6.9									33.0±0.8	<.001		
	∆ tn-t(0.0	0.0 32.1	0.0 28.0	-0.1 27.5	0.1 29.8	-0.1 26.2	0.2 33.3	0.1 32.6	0.1 (0.2 (30.6 2	.2 0.	3 30.1	1±2.4										0.1±0.1	.007
S	.L t _n	27.9	31.4	24.8	25.8	27.9	27.1	31.1	30.5	31.1 2	27.5 2	0.7.0				28.4±2.	3								
ETL- CTRL	∆ tn-t() –1.3 34.0	-0.7 39.8	-3.3 35.6	-1.7 39.6	-1.9 40.4	0.9 43.6	-2.3 36.8	-2.1 38.8	-1.6 -	-3.1 - 40.7 4	-1.7 .1.5						-1.7±1.1		39.2±2.	~				
C	Ċ.	34.0	39.0	35.4	38.3	39.5	43.0	36.6	38.3	40.8	39.7 3	8.61										38.6±2.5			
ETL S	L to) 0.0 23.1	-0.7 25.5	-0.2 20.7	-1.3 24.5	-1.0 24.3	-0.7 21.0	-0.2 22.9	-0.5 24.2	-0.2	-1.0 - 24.2 2	-1.7 3.5	23.4	4±1.5	<.001									-0.7±0.5	

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		••••		3	4	ιo.	Q	٢	œ	٩	10	Ξ	12	£	P vs.	CTRL	E	S-L P vs. CTRL	Δtn-t0	P vs. CTRL	2	P vs. CTRL	E	C-C P vs. CTRL	Δtn-t0	P vs. CTRL
		t _n	23.6	25.3 2	0.5 23	3.1 23	3.9 20	.8 22.	7 23.	.9 24.0) 24.0	23.1				2	3.2±1.4	<.001								
		Δ tn-t0 (0.5	-0.1 - 32.3 2	-0.2 - 9.9 30	1.3 –().6 33	0.4 –(3.3 33).1 –0 .9 32.	.2 –0. 3 33.	4 –0. 2 32.8	1 -0.2 3 32.7	2 –0.4 32.7							-0.3±0.4	.002	32.1±1.5	<.001				
	C-C	Ŀ.	29.3	32.2 3	0.1 30).8 33	3.0 33	.9 32.	5 33.	1 32.7	7 32.7	32.7										(1)	32.1±1.4	<.001		
		Δ tn-t0 (0.3	-0.1 C 29.8 2	.2 0. 6.0 29	2 –1	0.2 0.(7.5 27	0 0.2 .2 31.	1 29.	.1 –0 6 30.5	2 0.1	0.0 24.8	30.1	28.6±2.(0										0.0±0.2	100.
	S-L	fi I	25.8	28.5 2	5.2 27	7.9 23	3.5 23	.2 29.	0 26.	6 27.0) 27.6	22.8	28.1			0	6.3±2.2									
GEO- CTRL		Δ tn-t0 .	-1.8 36.6	-1.3 - 34.8 3	-0.9 – . 4.2 35	1.9 – 5.7 36	4.1 -4	4:0 –2 .8 38.	.2 –2 3 38.	.9 –3. 5 42.5	9 -0.7 5 41.0	7 –2.C 37.4) -2.0 43.0						-2.3±1.2		37.9±2.9					
	СС	f.	35.1	35.2 3	3.2 34	4.9 32	3.9 36	.2 37.	9 37.	8 40.4	4 40.0	36.4	41.7									(1	36.9±2.7			
		Δ tn-t0 ·	-1.5 (0.4 - 19.6 1	-1.0 ⊣ 9.6 20	0.8 -:	2.6 –().7 19).6 –0 .1 21.	.4 -0 0 20.	i7 −2. 7 21.6	1 –0.5 5 18.7	9 –1.(18.7) –1.3 19.7	19.9±0.5	6 	100									−1.0±0.8	
	S-L	tn	19.8	19.8 1	9.5 20	0.7 19	9.5 18	.9 21.	1 20.	5 21.1	1 18.7	18.9	19.7			1	9.8 ± 0.8	<.001								
GEO		Δ tm-t0 .	-0.1 (33.4 3	0.2 - 33.4 3	-0.1 0. 1.5 34	.2 ⊣ 1.9 34	0.3 –C 4.8 33	2 0.1 .7 35.	-0 8 36.	.2 –0. 5 35.7	5 –0.1 7 35.4	1 0.2 35.7	-0.1 36.2						−0.1±0.2	<.001	34.7±1.5	.001				
	C-C	tn .	33.2	33.7 3	1.4 34	4.7 34	4.1 33	.3 36.	1 36.	4 35.7	7 35.3	35.6	36.1										34.6±1.5	<.001		
		Δ tn-t0 -	-0.2 (0.3 -	·0.1 –(0.2 –(0.7 –C).4 0.3	-0-	.1 0.0	0.0	-0.1	-0.1												-0.1±0.3	<.001
All values fi	rom indiv	vidual an	uimals an	re in mn	1 and tw	o beat i	averages	s, t _{n=str}	ained st	tate (tim	e point e	of maxi	mum LV	VP), t0=rc	eference	strain stat	e (time	point before n	uitral valve	opening, see l	VIETHO	DS), COS=Edwi	ards Cos	grove band, R	SAR=St Ju	ide Medical

rigid saddle-shaped â 5 5 P annuloplasty ring, ETL= Edwards IMR ETlogix, GEO=Edwards GeoForm, SD=standard deviation

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TABLE 4

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global ε _{max}).
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	Animal no															Mean	±1SD		
		1	2	3	4	5	9	7	8	6	10	11	12	global ɛ _{max}	P vs. CTRL	global $\epsilon_{\rm rad}$	P vs. CTRL	global ɛ _{cir}	P vs. CTRL
	global ɛ _{max}	0.08	0.20	0.06	0.12	0.14	0.22	0.19	0.15	0.11 (0.23 (0.11	0.16	0.15 ± 0.05					
COS- CTRL	global ϵ_{rad}	0.03	0.12	0.04	0.08	0.08	0.17	0.10	0.09	0.08 (0.10	0.05	0.12			$0.09{\pm}0.04$			
	global ɛ _{cir}	0.04	0.11	0.04	0.05	0.07	0.08	0.07	0.09	0.04 (0.07	0.03	0.10					0.07 ± 0.03	
	global ε _{max}	0.19	0.19	0.07	0.13	0.14	0.14	0.15	0.14	0.12 (0.16	0.12	0.21	0.15 ± 0.04	.973				
COS	global ϵ_{rad}	0.08	0.15	0.05	0.10	0.11	0.11	0.06	0.09	0.09	0.13	0.07	0.12			$0.10{\pm}0.03$.425		
	global ɛ _{cir}	0.08	0.08	0.04	0.05	0.07	0.04	0.08	0.06	0.05 (0.10	0.03	0.13					0.07 ± 0.03	.858
	global ɛ _{max}	0.08	0.19	0.24	0.08	0.18	0.09	0.17	0.16	0.08 (0.14	0.07	0.14	$0.14{\pm}0.05$					
RSAR- CTRL	global ϵ_{rad}	0.04	0.15	0.20	0.05	0.10	0.03	0.10	0.16	0.04 (0.09	0.05	0.07			$0.09{\pm}0.05$			
	global ɛ _{cir}	0.03	0.13	0.07	0.02	0.06	0.04	0.04	0.05	0.03 (0.06	0.02	0.07					0.05 ± 0.03	
	global ɛ _{max}	0.15	0.17	0.24	0.09	0.21	0.09	0.18	0.18	0.10 (0.15 (0.09	0.23	0.16 ± 0.05	.024				
RSAR	global ϵ_{rad}	0.12	0.15	0.20	0.06	0.12	0.06	0.15	0.17	0.03 (0.10	0.06	0.16			0.11 ± 0.05	.010		
	global ε _{cir}	0.06	0.09	0.09	0.05	0.11	0.05	0.07	0.04	0.06 (0.06	0.05	0.11					0.07 ± 0.02	.022
	global ɛ _{max}	0.17	0.15	0.19	0.20	0.17	0.12	0.16	0.14	0.18 (0.09	0.11	0.17	$0.15{\pm}0.03$					
PHYSIO- CTRL	global ϵ_{rad}	0.11	0.04	0.08	0.09	0.14	0.04	0.12	0.08	0.10 (0.03	0.07	0.13			0.08 ± 0.04			
	global ɛ _{cir}	0.05	0.11	0.11	0.09	0.07	0.08	0.06	0.07	0.03 (0.03	0.05	0.07					0.07 ± 0.03	
	global ɛ _{max}	0.21	0.18	0.21	0.19	0.20	0.12	0.20	0.20	0.14 (0.14	0.11	0.24	0.18 ± 0.04	.020				
OISYHY	global $\epsilon_{\rm rad}$	0.14	0.03	0.10	0.13	0.14	0.04	0.14	0.11	0.09	0.04	0.05	0.13			0.09 ± 0.05	.102		
	global ɛ _{cir}	0.10	0.13	0.10	0.10	0.10	0.05	0.11	0.13	0.04 (0.08	0.06	0.15					0.10 ± 0.03	.010
ETL- CTRL	global ɛ _{max}	0.21	0.08	0.09	0.12	0.07	0.10	0.07	0.08) 60.0	0.20	0.06		0.11 ± 0.05					

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		1	7	3	4	5	9	7	×	6	10	11	12	global ɛ _{max}	P vs. CTRL	global ɛ _{rad}	P vs. CTRL	global s _{cir}	P vs. CTRL
	global $\epsilon_{\rm rad}$	0.15	0.07	0.06	0.11	0.02	0.04	0.04	0.07	0.03	0.15	0.03				0.07 ± 0.05			
	global ε _{cir} global ε _{max}	0.13 0.19	0.02 0.11	0.03	0.05 0.24	0.05 0.06	0.06 0.11	0.04 0.15	0.03 0.11	0.02 0.12	0.12 0.17	0.03 0.09		$0.14{\pm}0.05$.042			0.05±0.04	
ETL	global $\epsilon_{\rm rad}$	0.10	0.08	0.08	0.17	0.03	0.03	0.05	0.10	0.07	0.11	0.06				0.08 ± 0.04	.349		
	global ε _{cir} global ε _{max}	$0.14 \\ 0.13$	0.05 0.15	0.11 0.04	0.12 0.17	0.04 0.06	0.08 0.08	0.07 0.19	0.04 0.17	0.05 0.11	0.09 0.13	0.06 0.16	0.13	0.13±0.05				0.08±0.03	.017
GEO- CTRL	global $\epsilon_{\rm rad}$	0.08	0.10	0.02	0.12	0.02	0.03	0.08	0.11	0.06	0.09	0.06	0.07			0.07±0.03			
	global ε _{cir} global ε _{max}	0.07 0.14	0.10 0.21	0.01 0.05	0.07	0.02 0.16	0.02 0.07	0.11 0.17	0.03 0.20	0.07 0.16	0.05 0.16	0.05 0.18	0.06 0.19	0.16±0.05	600.			0.06±0.03	
GEO	global $\epsilon_{\rm rad}$	0.07	0.15	0.01	0.12	0.09	0.04	0.05	0.14	0.07	0.05	0.00	0.11			0.07 ± 0.05	.581		
	global ε _{cir}	0.09	0.11	0.02	0.13	0.02	0.02	0.08	0.04	0.10	0.07	0.07	0.07					0.07 ± 0.04	.065
All values fi	om individual	animals	are two	beat av(erages, (COS=Ec	dwards (Cosgrov	'e band,	RSAR=	=St Jude	Medica	l rigid s	saddle-shaped	annuloplasty rin	g, ETL= Edwa	urds IMR ETlog	ix, GEO=Edwa	rds

GeoForm, SD=standard deviation

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