## Calculating the error in refractive error

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**Correction to:** *Eye* (2011) **25**, 1333–1336; doi:10.1038/eye.2011.169; published online 22 July 2011

Since the publication of the above article, the authors have noticed that further testing of the spreadsheet calculations in the article has revealed, in a predictable and limited set of special circumstances, that the spreadsheet calculations return a recognisable error. No candidates have been incorrectly scored as a result. The error is rectified in the following code, which also simplifies the number of calculation steps required. RH Taylor, RB Ellingham, S Subramaniam and LA Wakely

If, at this stage, a dioptric power of the error is desired, as previously described, this correcting refraction can be converted as follows:

| S   | Calculated induced spherical equivalent | = P + (Q/2) |
|-----|---|-------------|
| Т   | Calculates absolute SE                  | = SQRT(S*S) |
| * * | ~                                       | 0000000000  |

U Calculated absolute cylinder power = SQRT(Q\*Q)

V Calculates the defocus equivalent =(T+U/2)

Unconventional results still occur with special scenarios, such as a one axis being entered as zero and the other as 180 (results in zero cylinder power at 135), and one axis 10, the other (minus) -170 (result zero cylinder power at 90). The calculated dioptric defocus equivalent would still be calculated correctly.

The authors would like to apologise for this mistake.

| A<br>B<br>C<br>D<br>E<br>F | Candidate name/number<br>Correct sphere<br>Correct cylinder<br>Correct axis<br>Correct spherical equivalent $= B + (C/2)$<br>Candidate sphere |   |
|----------------------------|---|---|
| G                          | Candidate cylinder  |   |
| Н                          | Candidate axis  |   |
| Ι                          | Spherical equivalent from refraction  | =F+(G/2)  |
| J                          | X1 calculated X vector from G and H   | $= G^{*}COS(RADIANS(2^{*}H))$                         |
| Κ                          | Y1 calculated Y vector from G and H   | = G*SIN(RADIANS(2*H))                                 |
| L                          | X3 calculated X vector from C and D   | $= C^{*}COS(RADIANS(2^{*}D))$                         |
| М                          | Y3 calculated Y vector from C and D   | = C*SIN(RADIANS(2*D))                                 |
| Ν                          | Resulting induced cyl axis  | = IF(K = M,90, DEGREES((ATAN2((L-J), (M-K)))/2))      |
| 0                          | Correction for minus cyl axis result  | = IF(N < 0,N + 180,N)                                 |
| Р                          | Calculated induced sphere   | =(B-F)-0.5*(G+Q-C)                                    |
| Q                          | Calculated induced cyl power  | = (C*COS(RADIANS(2*(D-O)))-(G*COS(RADIANS(2*(H-O))))) |
| R                          | Correction for induced zero cyl axis  | = IF(Q = 0,0,O)                                       |

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