BASIC RESEARCH

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Cylindrical Axis, Not Epicondyles, Approximates Perpendicular to Knee Axes

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Abstract

Background The transepicondylar axis (TEA) is often used as a surrogate for the flexion-extension axis, ie, the axis around which the tibia moves in space, because of a belief that both axes lie perpendicular to the mechanical axis. However, studies suggest the cylindrical axis (CA), defined as a line equidistant from contact points on the medial and lateral condylar surfaces from 10° to 120° flexion, more closely approximates the axis around which the tibia moves in space.

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Questions/purposes We examined the TEA and CA angles relative to mechanical axes to determine whether one more consistently and closely approximates the surgical goal of orthogonality to the mechanical axis.

Methods Three-dimensional (3-D) models were reconstructed from CT scans of five cadaver limbs. Three observers repeated three measurement sets to locate the TEA, CA, and femoral mechanical and tibial mechanical axes. Angles of the TEA and CA relative to the mechanical axes were calculated in two-dimensions (2-D) and as 3-D projections and compared for differences in magnitude and variance.

Results Angles between CA and the mechanical axes were closer to 90 \degree than the TEA in 2-D (92 \degree versus 94 \degree for the femur, 93° versus 94° for the tibia) and 3-D (88° versus 87° for the femur, 88° versus 86° for the tibia). Variance of the TEA was higher than the CA in 2-D.

Conclusions The CA forms angles more orthogonal to the mechanical axes of the thigh and leg than the TEA.

Clinical Relevance Although we found a consistently greater deviation of the TEA from the mechanical axis than the CA with small differences, future studies will need to determine whether these differences are biomechanically or clinically important.

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Introduction

Although the concept of a single flexion axis for the knee is becoming more widely recognized $[1, 6, 9-12, 17, 21, 26, 28]$ $[1, 6, 9-12, 17, 21, 26, 28]$ $[1, 6, 9-12, 17, 21, 26, 28]$ $[1, 6, 9-12, 17, 21, 26, 28]$ $[1, 6, 9-12, 17, 21, 26, 28]$ $[1, 6, 9-12, 17, 21, 26, 28]$ $[1, 6, 9-12, 17, 21, 26, 28]$ $[1, 6, 9-12, 17, 21, 26, 28]$ $[1, 6, 9-12, 17, 21, 26, 28]$ $[1, 6, 9-12, 17, 21, 26, 28]$ $[1, 6, 9-12, 17, 21, 26, 28]$ $[1, 6, 9-12, 17, 21, 26, 28]$, how best to find this axis intraoperatively has become a matter of dispute among orthopaedic surgeons. This single axis around which the tibia rotates in space is not captured in any of the traditional coronal, sagittal, or transverse planes and attempts to project it onto these planes gives rise to an artifact. Therefore the use of a surrogate axis passing through identifiable landmarks has been proposed as a solution $[1, 2, 4-7, 30]$ $[1, 2, 4-7, 30]$ $[1, 2, 4-7, 30]$ $[1, 2, 4-7, 30]$ $[1, 2, 4-7, 30]$ $[1, 2, 4-7, 30]$. Churchill et al. $[6]$ $[6]$ $[6]$ suggested a line passing through the most medial and lateral portions of the epicondyles, the transepicondylar axis (TEA), best approximates the actual flexion-extension axis (FEA) of the knee. Using this TEA as a surrogate for the actual axis of flexion is attractive because these landmarks can be palpated by a surgeon intraoperatively and are not altered by joint surface degeneration $[1, 4, 23, 24, 27]$ $[1, 4, 23, 24, 27]$ $[1, 4, 23, 24, 27]$ $[1, 4, 23, 24, 27]$ $[1, 4, 23, 24, 27]$ $[1, 4, 23, 24, 27]$ $[1, 4, 23, 24, 27]$ $[1, 4, 23, 24, 27]$ $[1, 4, 23, 24, 27]$. With their two-dimensional (2-D) analysis, Churchill et al. [[6\]](#page-4-0) concluded there was a statistically insignificant difference of $3^{\circ} \pm 1^{\circ}$ between the TEA and the true FEA. However, recent work by Eckhoff et al. [[9\]](#page-4-0) suggested the TEA may be an unsatisfactory surrogate of the FEA because the TEA lies anterior and superior to the actual FEA (Fig. 1). Using three-dimensional (3-D) CT, Eckhoff et al. reported an angle considered statistically insignificant by Churchill et al. in 2-D can be statistically significant when measured in 3-D using the dot product to assign an angle between nonintersecting lines projected onto a plane. Eckhoff et al. found 2-D angles were small, with an average 2° difference and a range of 0.1° to 4 $^{\circ}$ in the coronal plane and 2° with a range of 0.2° to 5° in the transverse plane, but they doubled to an average 5° difference with a range of 2° to 11° measured in 3-D with the TEA more superior and anterior.

This 5° average difference appeared important in a biomechanical and clinical study by Hsu et al. [[19\]](#page-4-0), where a 5° variation in either varus or valgus produced a 7% change in the distribution of load under the tibial component. Further, a 10° misalignment, consistent with the 11° maximum varus outlier reported by Eckhoff, et al. [\[9](#page-4-0)], showed a 62% change in load distribution in the biomechanical study by Hsu et al. [[19\]](#page-4-0). Although it is difficult to say what is clinically significant based on a biomechanical study, in a concurrent clinical radiographic review published in the same paper, Hsu, et al. [[19\]](#page-4-0) found a disturbing clinical correlation between increased implant malalignment and increasing lucent lines around the tibial components of otherwise successful implants at average 6 years followup. Other studies [[15,](#page-4-0) [20](#page-5-0)] confirm this clinical relationship between orthogonal positioning of an implant and implant longevity, and there have been no

Fig. 1 The TEA is anterior and superior to the FEA [\[9\]](#page-4-0).

papers challenging this concept of orthogonal positioning, biomechanical or clinical, for two decades.

Although previous work suggests the cylindrical axis (CA) is a better surrogate for the FEA $[2, 3, 8-12]$ $[2, 3, 8-12]$ $[2, 3, 8-12]$ $[2, 3, 8-12]$ $[2, 3, 8-12]$, there is no documentation in the literature regarding the relationship of either the TEA or CA to the femoral mechanical axis or the tibial mechanical axis. Because the goal of a contemporary TKA is to position the tibial component at a right angle to the tibial axis and the femoral component at a right angle to the femoral mechanical axis [\[15](#page-4-0), [19](#page-4-0), [20](#page-5-0)], it may be useful to know whether either axis being used as a surrogate is perpendicular to these longitudinal axes.

Therefore, we addressed the following two questions: (1) does the CA angle relative to the mechanical axes of the femur and tibia consistently differ from the TEA angle relative to these mechanical axes in either 2-D or 3-D, and (2) does the CA angle relative to the mechanical axis better approximate perpendicular than the TEA angle relative to the mechanical axis, ie, closer to orthogonal?

Materials and Methods

We imaged five cadaver limbs using a nonhelical CT scanner. CT scans were obtained for each of these limbs from the pelvis to the ankle in 0.5-mm increments. All knees were determined to be normal anatomically and nonpathologic; ie, they showed no observable or radiographic sign of varus, valgus, or rotational malalignment of congenital, developmental, or traumatic origin and there was no demonstrable arthritis or other articular abnormality. The ages of the cadaveric specimens used for this study

ranged from 61 to 87 years. Three of the limbs were obtained from white male cadavers and two from white female cadavers.

CT images were reconstructed into 3-D models using Mimics[®] software (Materialise, Leuven, Belgium). This program automatically assigns weights to the radiodensity of each voxel (3-D equivalent of 2-D pixel) in each plane of the study, which then is compared with the weight of an observer-selected pixel lying within bone. The voxel thickness corresponds to the 0.5-mm thickness of the CT cuts through the limb. The program constructs a 3-D image of the bone in the absence of soft tissue attachments but remaining within proper 3-D alignment and relation to the other bones of the limb. In most of the reconstructions, the bone near the articular surface of the femur and tibia was less radiopaque than the dense cortical bone of the diaphysis. Occasionally, this caused the articular surface of the bone in 3-D reconstruction to be rough or caused some soft tissue artifact to be included on the articular surface of the 3-D model. In such cases, an observer reviewed the frames of the CT that included the joint surface and manually selected voxels that corresponded to the bone surface to produce smoothing of the articular surface.

Once completed and reviewed, the 3-D models were imported and viewed with Rapidform[®] 2006 software (Inus Technology, Inc, Seoul, South Korea). Using this software, axes were generated for the TEA, CA, femoral mechanical axis, and tibial mechanical axis consistent with previous studies [[5–14,](#page-4-0) [16,](#page-4-0) [18](#page-4-0), [21,](#page-5-0) [23–25,](#page-5-0) [31](#page-5-0)]. The femoral mechanical axis was defined as a line connecting the center of the hip to the middle of the knee. This line runs medial to the shaft of the femur and then between the condyles of the distal femur through the posterior aspect of the femoral sulcus meeting with the tibial mechanical axis between the tibial intercondylar tubercles. To generate this axis, a sphere was fit to the surface of the femoral head and the geometric center point of this sphere was extrapolated. A point judged by the observer to be equidistant between the tibial intercondylar tubercles was chosen to represent the distal pole of the femoral mechanical axis and a line was generated connecting the center at the hip to the middle of the knee. The tibial mechanical axis was defined as a line starting at the midpoint between the tibial intercondylar tubercles and extending to the midpoint between the cortical surface of the medial and lateral malleoli of the ankle. The CA was generated by selecting points on the articular surface of each posterior condyle and using leastsquares regression to fit a cone to the posterior condyles. The center axis of this cone lying equidistant from all points on the condyle was extrapolated to be the CA. The TEA was defined by selecting the most prominent points of the medial and lateral epicondyles, according to the method of Churchill et al. [[6\]](#page-4-0). These medial and lateral points were connected to create the TEA. Three separate observers (CWH, MJW, HCE) repeated each of these described measurements in triplicate, resulting in nine serial measurements for each limb.

Four angles in 2-D and 3-D were generated from these measurements for analysis: TEA relative to tibial mechanical axis, CA relative to tibial mechanical axis, CA relative to femoral mechanical axis, and TEA relative to femoral mechanical axis. The lines and the 2-D angles between them were calculated by Rapidform $^{(8)}$. Dot products, the angle between the lines that do not intersect in a plane, were used to generate the 3-D angle [\[29\]](#page-5-0). Angles calculated from each of the three replications for each angle were averaged to obtain one dependent variable from each rater for each angle. Consistency of location of the TEA and CA was examined with Levene's test for equality of variance, which is not susceptible to conditions of nonnormality. Interobserver reliability of the measurements was assessed using an intraclass correlation coefficient model (2,k). Differences between the TEA and CA were examined with a paired t-test and compared with the goal of orthogonality to the mechanical axes.

Results

We found the angles formed by the TEA consistently further from perpendicular than angles formed by the CA relative to the mechanical axes of the femur and tibia in 2-D and 3-D measurements. In 2-D, all angles were greater than 90° for the TEA and CA (Fig. 2). The CA was

Fig. 2A–B The 95% CIs of the CA and TEA relative to the mechanical axis of the (A) femur and (B) tibia calculated in 2-D and 3-D projections are shown.

Table 1. TEA and CA angles relative to femoral and tibial mechanical axes

Axis	Two-dimensional angles $(°)$			Three-dimensional angles $(°)$		
	TEA	СA	p value	TEA	CА	value
Femoral mechanical axis	93.6 ± 2.0	92.3 ± 1.3	0.04	86.8 ± 2.4	88.2 ± 1.9	0.04
Tibial mechanical axis	94.2 ± 2.5	92.8 ± 1.6	0.04	86.5 ± 3.1	87.6 ± 1.9	0.24

Values are expressed as mean \pm SD; * paired t-tests used to compare axes; TEA = transepicondylar axis; CA = cylindrical axis.

Table 2. Variance of axis location and interobserver reliability

Axis	Mean absolute difference from mean measurement (°)							
	Two-dimensional angles			Three-dimensional angles				
	TEA	CA	p value*	TEA	CA	p value*		
Femoral mechanical axis	1.6 $ICC = 0.83$	1.0 $ICC = 0.56$	0.07	2.4 $ICC = 0.83$	1.9 $ICC = 0.56$	0.23		
Tibial mechanical axis	2.1 $ICC = 0.86$	1.1 $ICC = 0.70$	0.05	2.4 $ICC = 0.83$	1.5 $ICC = 0.72$	0.15		

* Levene's tests used to compare variances; TEA = transepicondylar axis; CA = cylindrical axis; ICC = intraclass correlation coefficient.

1.3° (95% CI, 0.0°, 2.6°; $p = 0.04$) closer to orthogonal than the TEA relative to the femoral mechanical axis and 1.4° (95% CI, 0.1°, 3.0°; $p = 0.04$) closer to orthogonal than the TEA relative to the tibial mechanical axis (Table 1). In 3-D projections, all angles to the mechanical axes were less than 90° for the TEA and CA. The CA was 1.4° (95% CI, 0.1°, 3.1°; $p = 0.04$) closer to orthogonal than the TEA relative to the femoral mechanical axis and 1.1° (95% CI, 0.7°, 3.2.8°; p = 0.24) closer to orthogonal than the TEA relative to the tibial mechanical axis (Table 1).

The positions of the 95% CIs suggest the measured CA more closely approximates an orthogonal angle than the TEA (Fig. [2\)](#page-2-0). For the TEA, the 95% CIs showed the mean angle could range from 85.4° to 94.6° and 84.8° to 95.8° across 2-D and 3-D measurements relative to the femoral and tibial mechanical axes, respectively (Fig. [2\)](#page-2-0). For the CA, the 95% CIs showed the mean angle could range from 87.2 $^{\circ}$ to 93.0 $^{\circ}$ and 87.6 $^{\circ}$ to 93.8 $^{\circ}$ across 2-D and 3-D measurements relative to the femoral and tibial mechanical axes, respectively (Fig. [2\)](#page-2-0).

Corresponding with the differing widths of CIs between the axes (Fig. [2](#page-2-0)), the measured variances of the TEA generally were larger than measured variances of the CA. For 2-D, the variance of the TEA trended 60% greater $(p = 0.07)$ than the CA relative to the femoral mechanical axis and the variance was 91% greater ($p = 0.05$) than the CA relative to the tibial mechanical axis (Table 2; compare widths of 95% CIs in Fig. [2](#page-2-0)). For 3-D, the variances of the TEA and CA were similar ($p > 0.05$) relative to the femoral and tibial mechanical axes.

Interobserver reliability ranged from 0.56 to 0.86 for the CA and TEA measurements (Table 2).

Discussion

The common practice of using the TEA as a surrogate for the FEA when implanting artificial joints in TKA may not be ideal, as the CA more closely corresponds to the actual FEA of the knee. We therefore addressed the following two questions: (1) Is the CA angle relative to the mechanical axes of the femur and tibia consistently different from the TEA angle relative to these mechanical axes in either 2-D or 3-D? (2) Does the CA angle relative to the mechanical axis better approximate perpendicular than the TEA angle relative to the mechanical axis, ie, closer to orthogonal?

The limitations of this study are (1) sampling from a single population, (2) modeling with a truncated cone, and (3) small relative/absolute differences. First, the observations are confined to a single population of white cadavers. A survey of the literature suggests there is morphologic variation in the femur and tibia between subpopulations based on race. For example, there appears to be a difference between white, black, and Asian populations in the degree of femoral anteversion [\[12\]](#page-4-0). Although our data show a difference between the CA and TEA for whites, we do not suggest the observation of a difference between the CA and TEA, or their relative orientation to mechanical axes, extends across all populations. Such an assertion is left for future investigation.

Second, we used a truncated cone as a model for the distal femur. Eckhoff et al. [9] used cylinder centers and Churchill et al. [6] used the center of spheres fit to the condyles to find the axis equidistant from the condylar surface. Cone axis and cylinder axis are the same, ie, collinear, by virtue of the fact that both lie equidistant from the condylar surface of the femur, but the cone is a better geometry to describe the distal femur. The cone model used here allows for the use of a single-fitting over double-fitting algorithm, ie, a single cone versus two cylinders or two spheres, which simplifies the algorithm to extrapolate an axis. The validity of this simplified algorithm is borne out in the consistency of our repeated observations by single and multiple observers (Table [2\)](#page-3-0). This analysis, however, does not confirm the axis of the cone is the exact match of the true FEA. Confirmation of the proximity of the cone axis to the FEA is left to future biomechanical studies.

Third, the measured differences between the two angles averaging 1° are small. The absolute difference of each line from the perpendicular is greater with 2° deviation of the CA versus 3° deviation of the TEA from the femoral mechanical axis and 3° deviation of the CA versus 4° deviation of the TEA from the tibial mechanical axis, but is this small deviation clinically important? Although there is no literature establishing the absolute limit of tolerable malalignment in contemporary TKA, there is a long tradition in TKA to minimize the potential for malalignment, and this tradition extends back to the work of Lotke and Ecker [\[22](#page-5-0)] who ''… noted that there is a statistically significant positive correlation between a good clinical result and a wellpositioned prosthesis. In addition, it was appreciated [in their study] that perfect positioning of the device was difficult to obtain. [They] believe that the long-term clinical results, wear resistance, and resistance to prosthetic failure depend on correct positioning of the devices.'' Despite studies [15, [20\]](#page-5-0) published since that of Lotke and Ecker, what constitutes ''correct component positioning'' remains elusive, but subsequent work [19] does show the small tolerance, biomechanically and clinically, for off-axis alignment in TKA.

Our study documents the previously unreported relationship between two reference axes, FEA and CA, and their relationship to the mechanical axes of the femur and tibia. It is not within the scope of this paper to say the 1° average difference, 2° to 3° paired difference, or the even larger difference between outliers, are biomechanically or clinically important. We further do not assert that one axis is superior, but rather to show there is a consistent difference between the two axes and a consistently greater deviation of the TEA from the mechanical axis than the CA. It is left to future biomechanical testing and long-term outcome studies to validate if this difference between axes is clinically relevant.

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