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Imaging Feedback of Histotripsy Treatments Using Ultrasound Shear Wave Elastography

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Abstract

Histotripsy is a cavitation-based ultrasound therapy that mechanically fractionates soft solid tissues into fluid-like homogenates. This paper investigates the feasibility of imaging the tissue elasticity change during the histotripsy process as a tool to provide feedback for the treatments. The treatments were performed on agar tissue phantoms and ex vivo kidneys using 3-cycle ultrasound pulses delivered by a 750-kHz therapeutic array at peak negative/positive pressure of 17/108 MPa and a repetition rate of 50 Hz. Lesions with different degrees of damage were created with increasing numbers of therapy pulses from 0 to 2000 pulses per treatment location. The elasticity of the lesions was measured with ultrasound shear wave elastography, in which a quasiplanar shear wave was induced by acoustic radiation force generated by the therapeutic array, and tracked with ultrasound imaging at 3000 frames per second. Based on the shear wave velocity calculated from the sequentially captured frames, the Young's modulus was reconstructed. Results showed that the lesions were more easily identified on the shear wave velocity images than on Bmode images. As the number of therapy pulses increased from 0 to 2000 pulses/location, the Young's modulus decreased exponentially from 22.1 ± 2.7 to 2.1 ± 1.1 kPa in the tissue phantoms $(R^2 = 0.99, N = 9 \text{ each})$, and from 33.0 ± 7.1 to 4.0 ± 2.5 kPa in the *ex vivo* kidneys ($R^2 = 0.99, N$ = 8 each). Correspondingly, the tissues transformed from completely intact to completely fractionated as examined via histology. A good correlation existed between the lesions' Young's modulus and the degree of tissue fractionation as examined with the percentage of remaining structurally intact cell nuclei ($R^2 = 0.91$, N = 8 each). These results indicate that lesions produced by histotripsy can be detected with high sensitivity using shear wave elastography. Because the decrease in the tissue elasticity corresponded well with the morphological and histological change, this study provides a basis for predicting the local treatment outcomes from tissue elasticity change.

I. Introduction

Histotripsy is a cavitation-based tissue ablation therapy that mechanically fractionates soft tissues using high-intensity, extremely short ultrasound pulses [1]–[4]. During the

treatments, the tissues progressively transform from soft solids to fluid-like homogenates. This technique has been shown to successfully fractionate target tissues with high precision in many *in vivo* models [3], [5]–[8], demonstrating its potential to become a useful therapy tool for noninvasive tissue removal.

Image-based feedback information about the treatment efficacy during and after the treatment is important for a non-invasive therapy such as histotripsy. Our previous study has shown that the quantitative measurement of the ultrasound backscatter intensity can be used to predict the degree of tissue fractionation as the scattering tissue structures are progressively fractionated to small debris that no longer scatters ultrasound effectively [9], [10]. The backscatter measurement, however, is not sensitive enough to detect the tissue damage at an early stage of the treatment. More sensitive measurement can be achieved with magnetic resonance (MR) T2-weighted imaging [11]. The major drawback of MR is the high cost and the requirement for MR-compatible ultrasound therapy systems so that feedback can be provided during the treatments.

Ultrasound elastography (or elasticity imaging) [12]–[18] may be a cost-effective alternative that can characterize the histotripsy lesions with high sensitivity. The general approach for elastography includes application of stress, estimation of stress-induced strain, and reconstruction of tissue elasticity from the stress-strain relations. The stress can be applied with static or sinusoidal mechanical compression directly exerted on the tissues with mechanical compressors (e.g., [12]–[14], [19], [20]). However, the mechanical compression limits the applicable imaging range to superficial tissues because of the difficulty of propagating the force to deep-lying tissues. Furthermore, artifacts may arise from incomplete knowledge of the boundary conditions [21]. As such, an alternative approach has been developed to remotely apply the stress in the deep-lying tissues using acoustic radiation force [16], [22]-[26]. The acoustic radiation force is generated in the tissues along the propagation path of ultrasound by the momentum transfer from the acoustic wave to the medium via absorption and/or reflection of ultrasound. A short duration (~milliseconds) of focused ultrasound can induce an impulsive push in the focal region, which subsequently launches transient shear waves propagating laterally away from the focal region. Because the velocity and attenuation of the shear waves are directly related to the elasticity and viscosity of the tissues [27], the elasticity can be derived from the spatial-temporal recording of the shear waves by direct inversion of the Helmhotz equation [16], [17], [28], or estimation of the local propagation velocity [29]–[32]. Elastography can provide higher specificity and sensitivity for disease diagnosis [20], [33], [34] as a result of the high elasticity contrast between diseased and normal tissues [35], [36]. Elastography has been successful in the detection of liver cirrhosis [19], [37], renal disease [33], [38], [39], myocardial ischemia [40], [41], prostate cancer and/or breast lesions [20], [21], [42]–[46], as well as thermal lesions produced by radio-frequency or ultrasonic ablation therapy [47]-[52]. In contrast to thermal therapy, which produces stiffened tissues, histotripsy results in soft homogenized tissues in the treated volume. Such tissue transformation may be detected with high sensitivity using elastography because of the potentially high contrast in elasticity between normal and treated tissues.

In this paper, we hypothesize that tissue elasticity decreases as the tissues are progressively fractionated with increasing numbers of therapy pulses. We first investigated the feasibility of imaging the elasticity change using shear wave elastography, in which shear waves were induced by an impulsive push generated by the therapeutic array transducer and tracked with high-frame-rate ultrasound imaging. Next, the quantitative correlation between the tissue elasticity (i.e., Young's modulus) and the degree of tissue fractionation was studied. This correlation, if established, could provide a basis for predicting the treatment outcomes with tissue elasticity change.

II. Materials and Methods

A. Sample Preparation

Experiments were performed on agar-graphite tissue mimicking phantoms and *ex vivo* kidneys. To prepare the agar-graphite tissue mimicking phantoms, agar powder (AG-SP, Lab Scientific, Livingston, NJ) was mixed in deionized water at 0.8% w/v concentration. The mixture was heated in a microwave oven until the agar completely melted in the solution. Next, the graphite powder (extra-fine graphite powder, Mr. Zip, Muskegon, MI) was mixed into the agar solution at 3% w/v concentration. To ensure homogeneous distribution of graphite in the phantom, the agar-graphite solution was stirred with a magnetic stirrer (Cimarec, Thermo Scientific, Asheville, NC) until it was fully solidified. The agar-graphite aggregates under microscopic examination. These aggregates can be fractionated into very fine (<30 μ m) debris after the histotripsy treatments. Morphologically, the treated volume transformed into paste-like homogenate that never re-solidifies to gel (a sign of mechanical rather than thermal damage).

Freshly excised porcine kidneys were obtained from a local abattoir. The kidneys were placed in normal saline at 4°C with the capsule removed. All samples were used within 48 h of harvest. Prior to experimentation, the kidneys were submerged in degassed (20 to 30% of normal saturation determined by pO_2) saline at room temperature for ~1 h. The kidneys were then dissected across the long axis, resulting in two ~6-cm-thick sections with ~6 × ~5 cm cut surface. The kidney sections were embedded in 0.8% agar gel prepared with normal saline in a polycarbonate holder.

B. Experimental Setup

A 750-kHz therapeutic array transducer (Imasonic, Voray sur l'Ognon, France) was used to generate both the therapy pulses for histotripsy and the push pulses for shear wave imaging. The transducer has a geometric focal length of 12 cm, with an aperture size of 15 cm and a center hole of 5.9 cm diameter. The array consists of nine 5-mm-wide concentric rings, each dissected into two half-ring elements. The driving signal of each element can be individually adjusted by a custom-built array control system, allowing for electronic steering in the axial direction and f-number control. A 5-MHz 128-element linear-array imaging probe (L7-4, Philips Healthcare, Andover, MA) connected to a research ultrasound imaging system (V1, Verasonics, Redmond, WA) was used to collect the image data.

The experimental apparatus is shown in Fig. 1. The therapeutic transducer was mounted to a manual 3-axis positioning system. The imaging probe was mounted in the experimental tank opposite the therapeutic array. The beam axis of the therapeutic transducer was aligned to the imaging plane by the following approach. A bubble cloud was induced in the water with brief excitation of the therapeutic transducer. The therapeutic transducer was placed so that the bubble cloud appeared with highest backscatter amplitude and largest spatial extent on the ultrasound images. After the alignment, the phantom or tissue was mounted to a motorized 3-axis positioning system and submerged in the tank approximately at the geometric focus of the therapeutic transducer. For the tissue experiments, the kidney-gel blocks were positioned with the long axis of the kidney approximately parallel to the imaging plane. In this orientation, exposures were made through the renal cortex without obstruction from the renal pelvis.

C. Histotripsy Treatments

Histotripsy therapy pulses of 3 cycles in duration were delivered at 50 Hz pulse repetition frequency (PRF) by the therapeutic array transducer. All elements on the array were driven

in-phase with equal amplitude, resulting in an f-number 0.8 focal configuration. The pressure field was calibrated with a custom-built fiber-optic probe hydrophone (FOPH) with an active element of 100 μ m diameter [53]. The peak negative (P–) and peak positive (P+) pressures were measured to be –17 and 108 MPa, respectively. Because of attenuation of ultrasound in the agar-graphite phantoms (0.1 dB/cm/MHz [54]) and in the kidneys (1 dB/cm/MHz [55]), the P– pressures at the treatment location were likely ~16.5 MPa in the phantoms, and ~13 MPa in the kidneys. The P+ pressures were likely diminished more significantly as a result of nonlinear absorption. The –6-dB beamwidths were measured at a reduced P–/P+ pressure of –11/58 MPa. The lateral/axial –6-dB beamwidths were 2.6/17 mm on the P– pressure profile, and 1.2/7 mm on the P+ pressure profile. The beamwidths at higher pressures could not be successfully measured because the cavitation easily occurred and damaged the fiber tip during the pressure profile scan.

Lesions of approximately $7 \times 7 \times 14$ mm were produced by mechanically scanning the therapy focus in a 5×5 grid with 1-mm spacing on the focal plane (Fig. 1). To produce different degrees of tissue fractionation, lesions were produced with 0, 100, 200, 300, 500, 1000, 1500, or 2000 therapy pulses per treatment location on the grid. A total of 72 treatments, 9 for each, were performed on the agar-graphite tissue phantoms. A total of 64 treatments, 8 for each, were performed on the *ex vivo* kidneys. After the treatments, the samples were moved 15 mm laterally on the imaging plane so that the shear wave elastography was performed with the shear waves excited from outside and propagating across the lesions.

D. Shear Wave Elastography

The shear wave elastography approach used in this study is similar to those described in the literature [23], [44]. To generate a quasi-planar shear wave, three ultrasound pushing beams were successively fired by the therapeutic array transducer focused at z = +5, 0, and -5 mm with respect to the geometric focus (i.e., z = 120 mm). The outer 5 rings were shut off, resulting in f-number focal configurations of 1.25, 1.2, and 1.15 for the three beams. A 2- μ s delay was inserted between subsequent beams, allowing the update of the new focal delay pattern. The pulse parameters and the measured pressure fields of the three beams were summarized in Table I.

To track the propagation of the shear waves at a high frame rate, ultrasound plane wave imaging [17] was performed. The imaging system generated a plane wave to illuminate the entire imaging field by simultaneously exciting all elements on the array. The system then started recording the backscatter signals after the plane wave was transmitted. Because the system can only receive signals from 64 channels a time, 2 successive transmit-receive sequences, each lasting for 77 μ s, were conducted to collect the backscatter signals from the 38 × 38 mm field of view. A total of 72 frames were acquired from 1 ms after the pushing beams at a rate of 3000 frames per second. The total imaging duration lasted for 24 ms.

The channel data were collected and processed off-line. Conventional delay-and-sum beamforming with a f-number 1.5 dynamic receive focusing was applied to produce the beamformed RF images. The 1-D correlation-based speckle tracking algorithm [56] was then applied on the beamformed RF data to estimate the local tissue displacement. The RF data were transformed into analytical signals, and segmented into 1.5-mm regions with 75% overlap along the axial direction. The cross-correlation function of the segments from consecutive frames was calculated. The position of the maximum of the cross-correlation function was obtained by locating the phase zero-crossing around the maximum magnitude of the function. This position determined the tissue displacement between the consecutive frames.

This processing produced a series of spatial-temporal displacement images (e.g., Fig. 2) which allowed the estimation of the shear wave propagation velocity in each local area, (*x*, *z*). The propagation velocity was estimated using a time-of-flight algorithm [29], [44]. For each location (*x*, *z*), the temporal displacement profiles at two points across the location, $u(x - \Delta x, z, t)$ and $u(x + \Delta x, z, t)$, were extracted from the spatial-temporal displacement images. The propagation time, Δt , between the two points was obtained from the location of the maximum of the cross-correlation function of the two displacement profiles, $u(x - \Delta x, z, t)$ and $u(x + \Delta x, z, t)$. The propagation velocity was calculated as $v_s = 2 \cdot \Delta x / \Delta t$. To improve the quality of measurement, an average propagation velocity was calculated from multiple estimates with different spacing, Δx . In this study, the average velocity was calculated from 3 pairs of points with $\Delta x = 0.6$ to 0.9 mm. This set the resolution of the final elasticity map to be approximately 1.8 mm. The imaging process was repeated 3 times for the lesions created in the agar-graphite phantoms, and 9 times for those created in the kidneys. The average shear wave velocities were color-coded and overlaid on the B-mode images (e.g., Fig. 3).

The Young's modulus of the lesions was estimated from the measured shear wave velocities. It is assumed that the medium is isotropic, purely elastic (non-dispersive), incompressible, and locally homogeneous in each interrogated location. The Young's modulus was then calculated using

$$E=3\mu=3\rho v_s^2 \quad (1)$$

where *E* is the Young's modulus, μ is shear modulus, and ρ is the density of the medium (assumed to be 1000 kg/m³). A median Young's modulus was calculated for each lesion in an 8 × 6 mm region approximately in the center of the lesions. As a comparison, the backscatter intensity in the same region was calculated and normalized to the backscatter intensity before the treatment using a method described in our previous publication [10].

To compare the lesion detectability with the elastography and the B-mode, the contrast-tonoise ratio (CNR) was calculated. The CNR was defined as

$$CNR = \frac{S_{lesion} - S_{background}}{\sqrt{\sigma_{lesion}^2 + \sigma_{background}^2}}, \quad (2)$$

where S and σ are the spatial mean and standard deviation of the shear wave velocities on the elastography or the image magnitude on the B-mode.

To validate the elasticity measured with shear wave elastography, the elasticity of the untreated samples was also measured with a custom-built elastometer [57]. The phantoms or the kidney cortex were cut into 1-cm cubes and placed on an electronic balance. An aluminum rod with 8-mm diameter flat end was brought in contact with the samples. The rod was pressed into the samples step by step with a known step size. The scale reading was recorded to estimate the applied force for each step. A linear fit was applied to the stress-strain curves in the low-strain (<10%) regime. The slope of the linear fit was determined as the Young's modulus of the samples.

E. Histological Examination

The treated tissues were fixed in 10% neutral buffered formalin and prepared for hematoxylin and eosin (H&E) staining. Histological sections of 4 µm thickness were made

To evaluate the degree of tissue fractionation, the percentage of structurally intact cell nuclei remaining in the treated area was calculated. The cell nuclei were selected because they are a common indicator of cell or tissue damage. Moreover, they appeared more resistant to histotripsy damage than other cellular components, thus serving as a good indication of histotripsy-induced fractionation [10], [58]. The calculation followed the process described in our previous publication [10]. In brief, images of five $320 \times 240 \,\mu\text{m}$ regions in the lesion area were captured. The locations of the five regions formed a cross pattern with 1.5-mm span in 4 directions centered approximately at the lesion center. The numbers of the structurally intact cell nuclei were counted for the five images. An average of the five counts was obtained and normalized to the average count from an untreated area (control), producing a percentage of remaining structurally intact cell nuclei. This percentage may represent the degree of tissue fractionation caused by histotripsy.

III. Results

A. Experiments on Agar-Graphite Phantoms

Fig. 2 shows the spatial-temporal displacement images induced by the shear waves in the phantoms. Displacement of several tens of micrometers was detected in the push region. Quasi-planar shear waves were launched from the push region and propagated outward in the lateral direction [Fig. 2(a)]. The shear waves propagated at a slower speed in the treated area, leading to a bent wavefront [e.g., Figs. 2(b) and 2(c)]. The propagation speed decreased with increasing numbers of therapy pulses. When more than 1000 pulses/location were applied, the shear waves could not propagate very far into the treated area within the 24-ms observation period.

The B-mode and the shear wave velocity images of a representative lesion treated with increasing numbers of therapy pulses are shown in Fig. 3. As the number of therapy pulses increased, the treated area became increasingly hypoechoic on the B-mode images. Correspondingly, the shear wave velocities decreased in the treated area, indicating a softer area produced by histotripsy. The treated area was more easily identified on the shear wave velocity images than on the B-mode images, particularly when small numbers of therapy pulses were applied (e.g., 100 pulses per treatment location). The shear wave velocities in the majority of the treated area were successfully measured except for some regions in the far end, opposite the region of shear wave generation. Unsuccessful or noisy measurements were obtained in these regions, likely because the shear waves were unable to propagate far into a sufficiently fractionated volume.

The Young's modulus of the treated area decreased exponentially with increasing numbers of therapy pulses ($R^2 = 0.99$, Fig. 4). This decrease leveled off when more than 500 pulses/ location were applied. The Young's modulus of the untreated agarose phantoms measured with shear wave elastography was comparable with that measured with the elastometer, i.e., 26.6 ± 2.6 kPa (N = 7). In comparison, the normalized backscatter intensity also decreased exponentially with increasing numbers of therapy pulses ($R^2 = 0.99$, Fig. 4). However, it decreased at a much slower rate. For example, although the elasticity of the lesions produced with 100 pulses/location dropped by 63%, the backscatter intensity only decreased by 36%.

The CNRs of the lesion images on the elastography and on the B-mode imaging are shown in Table II. The CNR was significantly higher on the elastography than on the B-mode imaging in all experiments (p < 0.001; *t*-test). This indicates that the elastography provides

higher lesion detectability than the B-mode does. It was observed that the CNR on the elastography first increased and then decreased with increasing numbers of therapy pulses. The initial increase resulted from increased contrast between the lesion and the background. The following decrease occurred because noisy measurements were obtained in the lesion produced with a large number of therapy pulses.

B. Experiments on Ex Vivo Kidneys

Fig. 5 shows the spatial-temporal displacement images induced by the shear waves in the kidney tissues. Similar to the phenomena observed in the phantom study (Fig. 2), quasiplanar shear waves were launched from the push region. The shear waves propagated at a lower speed in the treated area, and could not propagate very far into lesions created with large numbers of therapy pulses (>1000 pulses/location). The shear waves appeared to disperse and attenuate faster in the tissues (Fig. 5) compared with those in the phantoms (Fig. 2). It is worth noting that cavitation bubbles could have been generated by the pushing beams, as indicated by the bright spots in the push region (Fig. 5).

The B-mode and the shear wave velocity images of a representative lesion treated with increasing numbers of pulses are shown in Fig. 6. The treated volume was identified as an increasing hypoechoic area on the B-mode images, or a softer area with reduced shear wave velocity on the shear wave velocity images. The treated area was more easily identified on the shear wave velocity images than on the B-mode images, particularly at a small number of pulses (<500 pulses per treatment location). Unsuccessful or noisy measurements were obtained in the far end of the lesion opposite the region of shear wave generation because the shear waves could not propagate very far into the fractionated volume. Despite these limitations, the lesions depicted on the B-mode and shear wave velocity images corresponded well with their morphological appearance (Fig. 7).

The Young's modulus decreased exponentially with increasing numbers of therapy pulses, and leveled off after more than 1000 pulses/location were applied ($R^2 = 0.99$, Fig. 8). The Young's modulus of the untreated kidney tissues measured with the shear wave elastography was comparable with that measured with the elastometer, i.e., 30.2 ± 4.5 kPa (N=8). The normalized backscatter intensity also decreased exponentially with increasing numbers of therapy pulses. For lesions produced with the same number of therapy pulses, the decrease in the elasticity was more significant than that in the normalized backscatter intensity. In addition, the CNRs on the lesion shear wave velocity images were significantly higher than those on the B-mode images in all experiments (p < 0.001, *t*-test; see Table II). These results indicate that the lesions may be detected with higher sensitivity using elastography.

C. Histological Examinations

Representative histological sections of the lesions produced with increasing numbers of pulses are shown in Fig. 9. In the control, all tissue structures and cell nuclei appeared structurally intact. In the treated area, damages to the tissue structures (e.g., disintegrated tubules) and the cellular components (e.g., pyknotic or fragmented cell nuclei) were observed. Increasingly more damage was observed with increasing numbers of therapy pulses. With small numbers of therapy pulses, small portions of the treated volume were damaged but most parts remained structurally intact. As the numbers of pulses increased, larger portions of the tissues were damaged and more damaged cell nuclei were found. With large numbers of therapy pulses (>1000 pulses/location), the treated volume appeared to be completely homogenized, with no recognizable tissue structures.

The degree of tissue fractionation was examined using the percentage of the remaining structurally intact cell nuclei and plotted against the number of therapy pulses in Fig. 10(a). The percentage of the remaining intact nuclei decreased exponentially with increasing numbers of therapy pulses ($R^2 = 0.99$). This percentage was further correlated to the Young's modulus of the treated tissues [Fig. 10(b)]. A good linear correlation was found between the percentage of the remaining intact nuclei and the lesion's Young's modulus ($R^2 = 0.91$). A good linear correlation was also found between the percentage of the remaining intact cell nuclei and the normalized backscatter intensity [$R^2 = 0.99$, Fig. 10(c)]. This trend is consistent with our previous study [10].

IV. Discussion

Elastography appears to be a more sensitive measurement for detecting tissue fractionation in the early stage of the histotripsy treatment compared with another imaging feedback metric, backscatter reduction [9], [10]. This is supported by results from visual inspection (Fig. 3 and Fig. 6) and CNR measurements (Table II). The capability of detecting minor damage at the beginning of the treatment is extremely helpful for histotripsy because it allows for precise targeting, analysis, and optimization of the treatment parameters.

In addition to higher sensitivity, elastography can compensate for some discrepancy of the feedback with backscatter reduction *in vivo*. Our experience in the *in vivo* studies has shown that the backscatter reduction is apparent during and within several minutes after the treatments. The backscatter intensity may increase again several minutes later, possibly because the blood coagulated in the treated volume. In this situation, the lesions may still be detectable with elastography because the newly formed blood clot is likely much softer (Young's modulus ~2 kPa [59]) than normal tissues.

The Young's moduli measured with shear wave elastography corresponded well with those measured with the elastometer. These measurements are also comparable to several results reported in the literature. For instance, the Young's modulus of the tissue phantoms measured in this study is comparable to that reported in [60] (20 to 30 kPa). The Young's modulus of the *ex vivo* kidney cortex is comparable to results from [61]–[63] (20 to 40 kPa), although higher than results from [64], [65] (7 to 15 kPa). Measurement errors in the Young's modulus reported here may occur because of violations of assumptions in (1), i.e., the medium being isotropic, non-dispersive, and locally homogeneous. The tissues are generally dispersive, which causes higher frequencies to travel faster. The present work estimated the elasticity based on the group velocity of the shear waves, which contain a wide band of frequencies (center frequency = 130 to 220 Hz, -15-dB frequency band = 30 to 500Hz). Therefore, the estimated elasticity could be higher than that estimated at a single lower frequency (e.g., 90 Hz in [65]). This effect has also been discussed by other researchers [44]. In addition to dispersion, the anisotropic nature of the renal cortex could cause directiondependent measurements [64]. Furthermore, heterogeneities introduced at the lesion boundaries could also cause measurement errors. Despite these influences, the decreasing trend of the elasticity should hold during histotripsy treatments, serving as a good indicator of the tissue softening process.

The mechanism of acoustic radiation force generation in the current work may be different from that in most elastography setups for diagnostic purposes (e.g., [16], [23], [44], [66]). The acoustic radiation force could be generated via absorption and/or reflection of ultrasound. In diagnostic setups, the radiation force is generated primarily through absorption. To enhance the absorption within the safety regulations, the radiation force is commonly generated by ultrasound with a higher frequency (5 to 10 MHz), limited pressure (<5 MPa), and long duration (300 to 600 μ s). In the current work, the radiation force is

generated by ultrasound with similar duration (450 to $600 \,\mu s$) but a lower frequency (750 kHz) and a slightly higher pressure (5 to 6 MPa). The radiation force caused by the absorption could be weaker because the absorption decreases with decreasing frequencies. However, the combination of low frequency, high pressure, and long pulse duration increased the likelihood of cavitation (as evidenced in Fig. 5). The strong reflection from the cavitation bubbles could have significantly enhanced the radiation force. The effect of cavitation on the radiation force generation is under investigation. On the other hand, the cavitation bubbles indeed produced noticeable damage on the histological sections of the tissues (not shown here). Therefore, we envision this setup to be applied within the target volume where the push region is to be ablated eventually. Such an approach can be very helpful for optimization of the therapeutic parameters before the treatment. For posttreatment lesion evaluation, because the push region must be outside the target volume, the push pulse parameters must be adjusted to meet the safety regulations for diagnostic ultrasound. A higher-frequency transducer should be used to generate sufficient radiation force at a lower intensity. Other elastography-based approaches may also be applied. For example, the same push pulses used in this study can be delivered to the target volume. The tissue response in the target volume (e.g., how fast the tissue rebounds) can be measured to provide important information on the tissue fractionation process. These approaches are currently under investigation.

It is well known that shear waves only travel in solids, because fluids cannot support the shear stress. The fact that the shear waves were unable to propagate very far into a sufficiently fractionated volume indicates that the tissue was transformed from a soft solid into a fluid-like medium. This is consistent with our morphological examinations (e.g., [2], [4]).

Because the tissue is fractionated into a fluid-like homogenate, shear wave propagation is increasingly restricted. Moreover, as the treatment volume approaches complete fractionation, the decreased backscatter can reduce image signals needed in the detection of the shear waves. Thus, as the treatment reaches these advanced stages, the accuracy of the elasticity measurement may decrease. Fortunately, complete fractionation of all cellular and tissue structures is far beyond what is necessary for most clinical applications. To improve the images as the treatment volume approaches complete fractionation, we propose use of an image compounding technique as shown in Fig. 11. Two shear wave velocity images were obtained separately with shear waves excited from the left or right side of the lesion. Using a simple image registration algorithm applied on the B-mode images, the two shear wave velocity images can be combined to provide a full map of the entire lesion.

V. Conclusions

Tissues treated with histotripsy become increasingly softer as they are fractionated by increasing numbers of therapy pulses. This tissue transformation process can be detected with high sensitivity using shear wave elastography. The created lesions depicted on the shear wave velocity images correspond well with their morphological appearance. Strong correlation exists between the lesion elasticity and the degree of tissue fractionation as examined by the percentage of remaining structurally intact cell nuclei. Because damage to the cell nuclei is directly related to cell death, tissue injury, and many other clinical outcomes, this correlation provides a basis for predicting histotripsy treatment outcomes from tissue elasticity change, allowing for a clinician to determine when sufficient treatment has occurred.

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Biographies



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Jeffery Brian Fowlkes (M'94–A'94) is a professor in the Departments of Radiology and Biomedical Engineering at the University of Michigan, Ann Arbor, MI. He is currently directing and conducting research in medical ultrasound, including the use of gas bubbles for diagnostic and therapeutic applications. His work includes studies of ultrasound contrast agents for monitoring tissue perfusion, acoustic droplet vaporization for bubble production

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Charles A. Cain (S'65–M'71–SM'80–F'89) was born in Tampa, FL, on March 3, 1943. He received the B.E.E. (highest honors) degree in 1965 from the University of Florida, Gainesville, FL; the M.S.E.E. degree in 1966 from the Massachusetts Institute of Technology, Cambridge, MA; and the Ph.D. degree in electrical engineering in 1972 from the University of Michigan, Ann Arbor, MI. From 1965 through 1968, he was a member of the Technical Staff at Bell Laboratories, Naperville, IL, where he worked in the electronic switching systems development area.

From 1972 through 1989, he was in the Department of Electrical and Computer Engineering at the University of Illinois at Urbana-Champaign, where he was a professor of electrical engineering and bioengineering. Since 1989, he has been in the College of Engineering at the University of Michigan, Ann Arbor, as a professor of biomedical engineering and electrical engineering. He was the chair of the Biomedical Engineering Program from 1989 to 1996; the founding chair of the Biomedical Engineering Department from 1996 to 1999; and the Richard A. Auhll Professor of Engineering in 2002.

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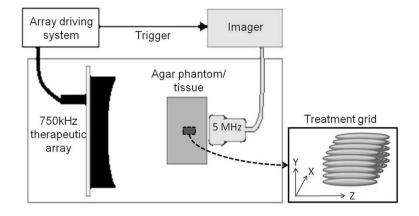


Fig. 1.

Experimental setup. The 5-MHz linear array imaging probe and the 750-kHz therapeutic array transducer were mounted on opposite sides of the agar phantoms/tissues in a tank of degassed water (25 to 35% of normal saturation determined by pO_2). The imager was synchronized with the therapeutic array driving system. Lesions were produced by mechanically scanning the therapy focus in a 5 × 5 grid with 1-mm spacing.

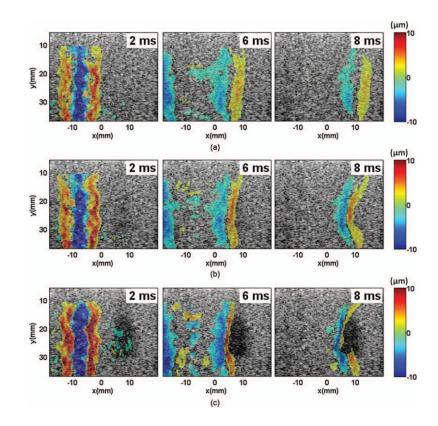


Fig. 2.

Spatial-temporal displacement images acquired at different times after the shear wave generation in the phantoms: (a) control, (b) 100 pulses, and (c) 1000 pulses. The positive and negative displacements indicate directions of motions toward and away from the imaging probe, respectively. The shear waves were generated in the left part of the field of view, centered at around x = -8 mm, and propagated away from the push region in opposite directions. The shear waves propagated at a lower speed in the lesion area, resulting in a bent wavefront as shown in panels (b) and (c). The curvature increased with increasing numbers of therapy pulses. The shear waves could not propagate far into the lesions created with more than 1000 pulses/location.

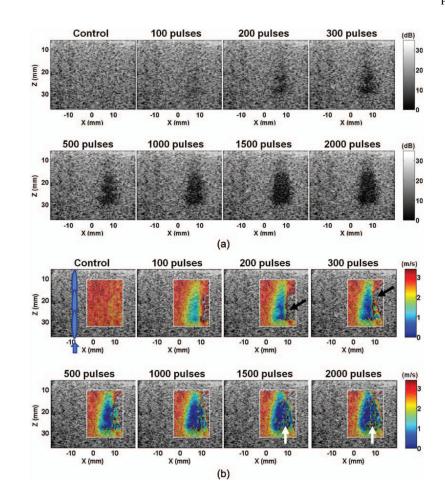


Fig. 3.

(a) B-mode and (b) shear wave velocity images of a representative lesion produced in the agar-graphite phantoms with increasing numbers of therapy pulses per treatment location. The treated volume became increasingly hypoechoic. Correspondingly, the shear wave velocity decreased in the treated volume. The lesions were more easily detected on the elastography than on the B-mode when small numbers of therapy pulses were applied (e.g., 100 pulses/location). The shear wave velocity in some areas opposite the push region (e.g., the areas indicated by black arrows) could not be measured. Noticeable noise was also present in the far end of the lesion (e.g., the areas indicated with the white arrows). These likely occurred because the shear waves were unable to propagate far into a significantly fractionated volume.

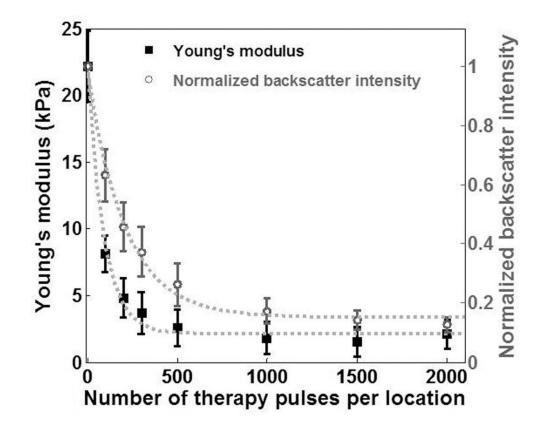


Fig. 4.

The Young's modulus and the normalized backscatter plotted against the numbers of therapy pulses for lesions produced in the phantoms. Each data point represents the mean \pm standard deviation from 9 independent treatments. The dashed line represents the exponential fit with the number of pulses centered at zero mean and scaled to unit standard deviation (i.e., Young's modulus: $y = 0.01 \cdot e^{-8.1 \cdot ((x - 700)/729)} + 2.18$, R² = 0.99; normalized backscatter intensity: $y = 0.03 \cdot e^{-3.5 \cdot ((x - 700)/729)} + 0.15$, R² = 0.99).

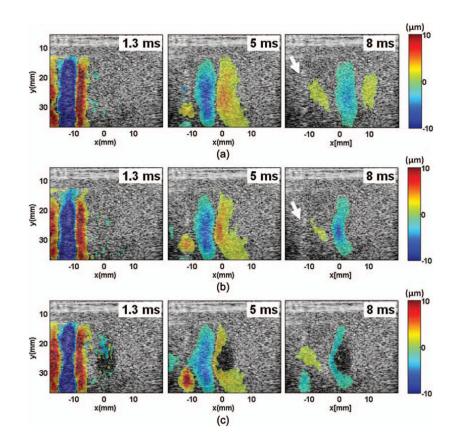


Fig. 5.

Spatial-temporal displacement images acquired at different times after the shear wave generation in the *ex vivo* kidneys: (a) control, (b) 100 pulses, and (c) 1000 pulses. The positive and negative displacements indicate directions of motions toward and away from the imaging probe, respectively. Compared with the shear waves generated in the phantoms, the shear waves generated in the kidneys appeared to be more dispersive and attenuated faster. The shear waves slowed down in the lesion area, resulting in a bent wavefront as shown in panels (b) and (c). The curvature increased with increasing numbers of therapy pulses. The shear waves could not propagate very far into the lesion created with more than 1000 pulses/location. Bright spots, likely cavitation bubbles, were observed in the push region after the pushing beams were delivered (examples indicated by the white arrows).

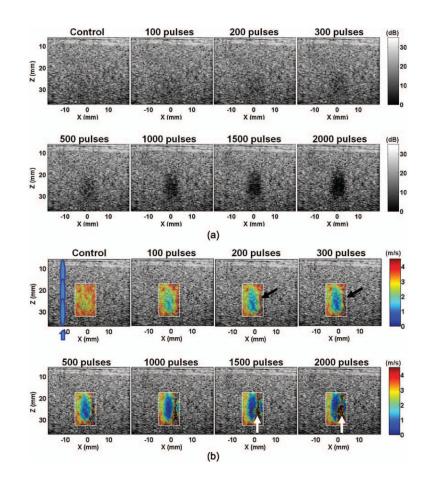


Fig. 6.

(a) B-mode and (b) shear wave velocity images of a representative lesion produced in the *ex vivo* kidneys with increasing numbers of pulses per treatment location. Both the backscatter and the shear wave velocity decreased with increasing numbers of pulses. The lesions were more easily detected on the shear wave velocity images than on the B-mode when small numbers of therapy pulses were applied (e.g., 500 pulses/location). The shear wave velocity in some areas opposite to the push region (e.g., the areas indicated by black arrows) could not be measured. Noticeable noise was present in the far end of the lesion (e.g., the areas indicated with the white arrows). These likely occurred because the shear waves were unable to propagate far into a sufficiently fractionated volume.

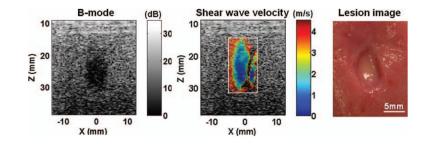


Fig. 7.

The B-mode image, shear wave velocity image, and gross morphology of a representative lesion produced in the kidneys. The size and shape of the lesion depicted on the B-mode and shear wave velocity images corresponded well with those observed from the morphological appearance.

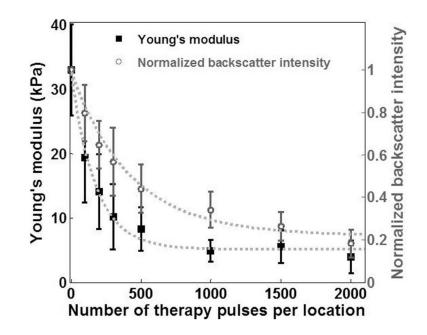


Fig. 8.

The Young's modulus and the normalized backscatter plotted against the numbers of therapy pulses for lesions produced in the *ex vivo* kidney tissues. Each data point represents the mean \pm standard deviation from 8 independent treatments. The dashed line represents the exponential fit with the number of therapy pulses centered at zero mean and scaled to unit standard deviation (i.e., Young's modulus: $y = 0.47 \cdot e^{-4.23 \cdot ((x - 700)/729)} + 5.20$, $R^2 = 0.99$; normalized backscatter intensity: $y = 0.15 \cdot e^{-1.7 \cdot ((x - 700)/729)} + 0.22$, $R^2 = 0.99$).

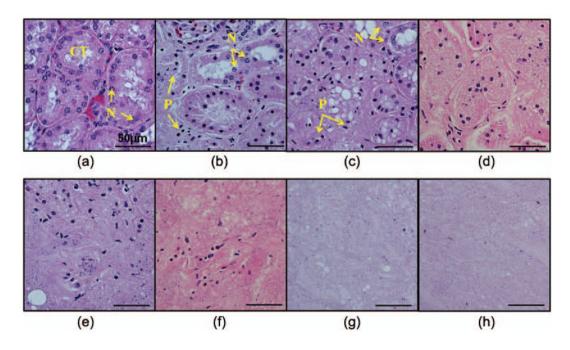


Fig. 9.

Hematoxylin and eosin (H&E)-stained histological sections of the lesions produced in the *ex vivo* kidneys with increasing numbers of pulses per treatment location: (a) control, (b) 100 pulses, (c) 200 pulses, (d) 300 pulses, (e) 500 pulses, (f) 1000 pulses, (g) 1500 pulses, and (h) 2000 pulses. In the control, the tissue structures [e.g., convoluted tubules (CT)] appeared structurally intact. Normal-appearing cell nuclei (N) were observed in all regions. In the treated area, damages to the tissue structures (e.g., disintegrated tubules) and cellular components (pyknotic or fragmented cell nuclei) were observed. The degrees of damage increased with increasing numbers of therapy pulses. When small numbers of therapy pulses were applied, small portions of the tissues were damaged [e.g., the left part in panel (b)] but most parts remained structurally intact. Some damaged (pyknotic or fragmented) cell nuclei (P) were observed. As the numbers of pulses increased, more damage occurred to both the tissue structures and the cell nuclei. With therapy pulses higher than 1000 pulses/location, the treated volume appeared to be completely homogenized with no recognizable tissue structures.

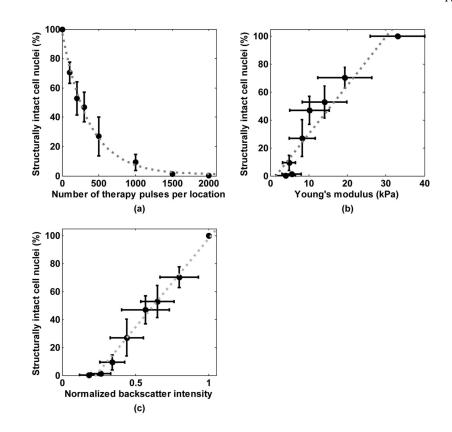


Fig. 10.

(a) Percentage of structurally intact cell nuclei remaining in the treated area decreased exponentially with increasing numbers of pulses. Each data point represents the mean \pm standard deviation from 8 independent treatments. The dashed line represents the exponential fit with the number of therapy pulses centered at zero mean and scaled to unit standard deviation, i.e., $y = 0.14 \cdot e^{-1.98 \cdot ((x - 700)/729)} + 0.01$, $R^2 = 0.99$. (b) Correlation between the percentage of the remaining structurally intact cell nuclei and the Young's modulus. The dashed line represents the linear fit, $y = 0.03 \cdot x - 0.05$, $R^2 = 0.91$. (c) Correlation between the percentage of the remaining structurally intact cell nuclei and the normalized backscatter intensity. The dashed line represents the linear fit, $y = 1.27 \cdot x - 0.29$, $R^2 = 0.99$.

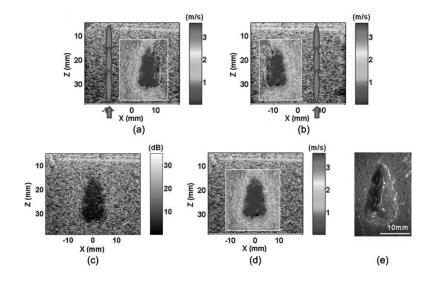


Fig. 11.

Image compounding applied on a lesion produced in the tissue phantoms: (a) push in the left, (b) push in the right, (c) compounded B-mode image, (d) compounded shear wave velocity image, and (e) lesion. Panels (a) and (b) show the shear wave velocity images produced with shear waves generated on the left and right sides of the lesions, respectively. Using a simple image registration algorithm, the two images were compounded to form the full lesion images [panels (c) and (d)]. The compounded image better outlined the entire lesion, as confirmed with the lesion morphology [panel (e)].

Pulse Parameters for Acoustic Radiation Force Generation Under Free-Field Conditions.

	Push beam 1	Push beam 2	Push beam 3
Focal location (z, mm)	125	120	115
Lateral/axial (–6 db) beamwidth * on P– pressure profile (mm)	3.5/38	3.2/36	3.0/35
Lateral/axial (-6 db) beamwidth $*$ on P+ pressure profile	2.3/34	2.1/32	2.0/28
P–/P+ Pressure *** (MPa)			
Phantom	-5/14	-5/15	-5/16
Ex vivo tissue	-6/30	-6/34	-7/36
Pulse duration (µs)			
Phantom	133	133	133
Ex vivo tissue	200	200	200
$I_{SPPA}^{***}(kW/cm^2)$			
Phantom	1.3	1.5	1.6
Ex vivo tissue	2.3	2.5	2.8

Note that the beamwidth was narrower for shorter focal length (or smaller f-number).

** The pressures at the treatment locations were expected to be lower than these measurements because of sound attenuation. Given a mean propagation distance of 3 cm and attenuation coefficients of 0.1 dB/cm/MHz in the agar-graphite phantoms [54], and 1 dB/cm/MHz in the kidneys [55], the P– pressures were estimated to be ~5 MPa both in the phantom and the *ex vivo* experiments.

*** ISPPA = spatial peak pulse average intensity.

TABLE II

Contrast-To-Noise Ratio (CNR) of the Lesions on Shear Velocity Images and B-Mode Images.

	CNR in agar phantoms		CNR in ex vivo kidneys	
Treatment parameters (pulses/location)	Shear wave velocity image	B-mode image	Shear wave velocity image	B-mode image
0 (control)	0.1 ± 0.1	0.1 ± 0.1	0.1 ± 0.1	0.1 ± 0.1
100	6.0 ± 1.1	0.5 ± 0.1	1.2 ± 0.6	0.2 ± 0.2
200	6.8 ± 1.2	0.7 ± 0.1	1.8 ± 0.8	0.3 ± 0.2
300	7.3 ± 1.4	0.9 ± 0.1	2.4 ± 0.8	0.4 ± 0.2
500	8.1 ± 1.0	1.1 ± 0.1	2.6 ± 0.9	0.6 ± 0.2
1000	8.9 ± 2.8	1.3 ± 0.1	3.2 ± 0.9	0.8 ± 0.2
1500	8.2 ± 3.3	1.3 ± 0.1	3.1 ± 1.2	0.9 ± 0.2
2000	5.3 ± 2.8	1.4 ± 0.1	3.0 ± 1.2	1.0 ± 0.3

The mean \pm standard deviation is listed (N = 9 for phantom studies; N = 8 for *ex vivo* tissue studies).