

How minute sooglossid frogs hear without a middle ear

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Acoustic communication is widespread in animals. According to the sensory drive hypothesis [Ender JA (1993) *Philos Trans R Soc Lond B Biol Sci* 340(1292):215–225], communication signals and perceptual systems have coevolved. A clear illustration of this is the evolution of the tetrapod middle ear, adapted to life on land. Here we report the discovery of a bone conduction–mediated stimulation of the ear by wave propagation in *Sechellophryne gardineri*, one of the world's smallest terrestrial tetrapods, which lacks a middle ear yet produces acoustic signals. Based on X-ray synchrotron holotomography, we measured the biomechanical properties of the otic tissues and modeled the acoustic propagation. Our models show how bone conduction enhanced by the resonating role of the mouth allows these seemingly deaf frogs to communicate effectively without a middle ear.

earless frog | audition | extra-tympanic pathways | X-ray imaging

The middle ear evolved multiple times independently during the evolution of terrestrial life (1). Indeed, a tympanic middle ear is an adaptation to life on land (2, 3) and compensates for the mismatch in acoustic impedance between air and tissue. Without it, 99.9% of sound energy is reflected by the body wall (4, 5). *Sechellophryne gardineri* is one of the world's smallest terrestrial tetrapods (6). These sooglossid frogs have a Gondwanan origin and evolved in isolation on the Seychelles Archipelago over the last 47–65 My (7, 8). They lack a middle ear yet produce acoustic signals (9, 10). In fact, similar to many species of frogs lacking the tympanic middle ear, they are still capable of hearing in air. Nevertheless, the mechanisms for sound transfer to the inner ear are far less clear. Some extratympanic pathways (11) such as the lungs (12), the opercular system (13), and bone conduction (14) have been proposed but remain to be tested experimentally (11). X-ray synchrotron holotomography of a female *S. gardineri* reveals that the pulmonary system is poorly developed and cannot contribute significantly to a lung-based sound transmission pathway. We used finite-difference simulations to investigate possible pathways through the head itself. These simulations highlighted the role of the mouth. Finite-element simulations further showed that the oral cavity of the animals resonates at the dominant frequency of the advertisement call of the species. In addition, synchrotron holotomography performed on seven different species showed that earless frogs are specialized for sound transmission between the oral cavity and the ears in two ways: (i) by minimizing the tissue thickness between the mouth and the inner ear and (ii) by minimizing the number of layers of tissue. The combination of these extra-tympanic pathways allows the frog to perceive sound efficiently.

Results

Playback Experiments and Call Analysis. We recorded vocalization patterns of *S. gardineri* (Fig. 1A, Table S1, and Audio S1) in the field on Silhouette Island. The average call duration (note) is

185.14 ± 27.31 ms; call rate varied from one call every 3 min to one call every 30 min. Spectral analysis of the vocalization shows that the notes consist of a series of one to six harmonic frequencies, with a fundamental frequency of 1,830 Hz (number of calls, $n = 21$). The dominant frequency varies between 4,225 and 6,767 Hz, corresponding to the first and second harmonics, with an average frequency of 5,710 ± 420 Hz ($n = 52$). Peaks of higher frequency rarely exceed more than 10,105 Hz (Fig. 1A). Interestingly, we did not detect any frequency or amplitude modulation of the call. Each of the acoustic playback experiments with conspecific calls ($n = 15$) in the natural habitat of the frogs provoked vocalizations of several males, suggesting that these frogs are capable of hearing. Furthermore, males did not respond to nonspecific calls, suggesting good acoustic discrimination abilities.

Ear Anatomy. *S. gardineri* possesses no tympanum, middle ear cavity, or a columella as can be seen on the X-ray holotomographic images (Fig. 1). The inner ear is covered by a strongly ossified operculum (76% of the volume; Fig. 1D) at the large oval window (area: 0.677 mm²; Fig. 1E). This ossicle connects to the ventral surface of the posterior suprascapula through the opercular muscle (Fig. 1F). The latter inserts on the operculum postero-dorsally on a narrow ridge with an asymmetrical cone-shaped aspect in profile (Fig. 1D). The inner ear is fully surrounded by the ossified otic capsule (Figs. 1B, F, and G and 2A and B), which contains six foramina including four in the medial wall (communicating with the endocranial cavity) and two on the posterior wall (Fig. 1C, E, and G). Three points are notable

Significance

Gardiner's Seychelle frog, one of the smallest terrestrial tetrapods, resolves an apparent paradox as these seemingly deaf frogs communicate effectively without a middle ear. Acoustic playback experiments conducted using conspecific calls in the natural habitat of the frogs provoked vocalizations of several males, suggesting that these frogs are indeed capable of hearing. This species thus uses extra-tympanic pathways for sound propagation to the inner ear. Our models show how bone conduction is enhanced by the resonating role of the mouth and may help these frogs hear.

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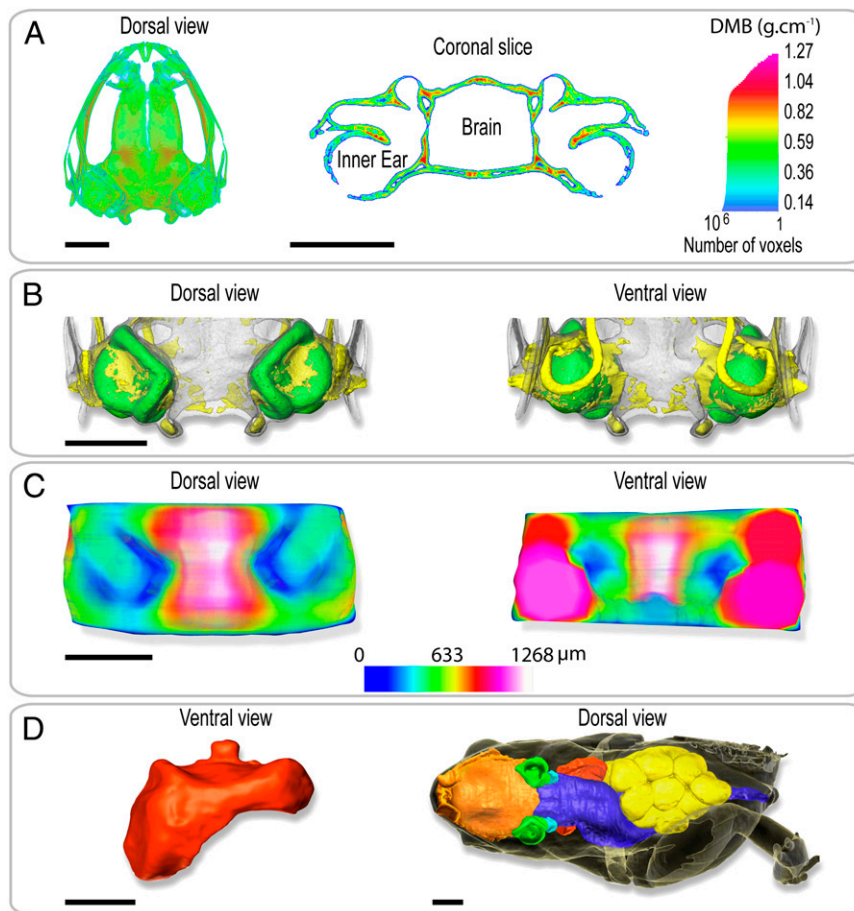


Fig. 2. Volume rendering of holotomography of the body and the tissues surrounding the ear of *S. gardineri*. (A) 3D map (Left) and virtual sagittal section (Right) illustrating the degree of mineralization of the skull as determined by absorption tomography. (B) Visualization of the degree of ossification of the otic region of the skull in dorsal (Left) and ventral (Right) views. The skull is transparent, cartilage is shown in yellow, and the inner ears in green. (C) 3D map of the thickness of the tissues separating the inner ears and the gaseous medium. (Left) Dorsal view and (Right) ventral view of the oral region. The thinnest parts are shown in dark blue. (D) 3D visualization of the pulmonary system of a gravid female (SVL = 11.65 mm). Red, pulmonary and laryngeal cavity in ventral view. To right, dorsal view of female in transparency visualizing the anatomy and the volume occupied by the nasal and oral cavities (orange), the inner ears (green), the digestive system (blue), the ovarian masses (yellow), and the pulmonary system. Note the left forelimb was removed for molecular analysis. (Scale bar, 1 mm.)

Discussion

Frogs without middle ears lack specializations to make hearing more efficient (25) and may need to compensate for the lack of the middle ear.

The ability of earless frogs to hear has been debated even though Loftus-Hills (26), Jaslow and Lombard (27), and Lindquist et al. (28) already demonstrated that some earless frogs actually have a hearing capacity comparable, in both range and sensitivity, to species with tympanic ears. To explain this observation, extra-tympanic pathways for sound transmission have been proposed involving the opercularis system (13), a lung-based pathway (28, 29), and a bone-based pathway (14). *S. gardineri* is an example of frog without a tympanic middle ear. It produces an advertisement call around 5,710 Hz and responds noticeably to playbacks of these calls. Our holotomography analysis shows that the opercularis system of this species is well developed, but the hearing function of this structure has still not been conclusively resolved (11, 30) and would be limited to frequencies <1 kHz (13).

The lung-based hearing hypothesis was originally proposed for eared species by Narins and coworkers (29) and later was extended to earless frogs (28). The suggestion that this system could work for earless frogs was based on data showing that the

lateral body wall overlying the lung vibrates in response to air-borne sounds with a frequency corresponding to the dominant frequency of the advertisement call in an earless frog (*Atelopus*) (28). A lung-based hearing system for *S. gardineri* is not supported by our holotomography and finite-element analyses. In fact, the lack of lateral body pathway and a weak development of the lung, with a volume 40% lower than that of the oral cavity, lead to resonant frequencies in the ultrasound domain, incompatible with the frequencies perceived by the species.

Bone conduction could thus constitute an alternative pathway, specifically in small animals. In the initial phase of our study, 3D finite-difference simulations were conducted to test this hypothesis. Nevertheless, in our species, bone conduction appeared to be insufficient to explain significant sound transfer to the inner ear: a drastic sound attenuation (−29 dB) was observed in our model, independent of the size and degree of mineralization of the skull. Interestingly, in the same simulations, the acoustic pressure appeared to pop up in the mouth cavity (Fig. 3C). Consequently, the role of the oral cavity as a resonator was investigated and shown to resonate at 5,738 Hz, a value close to the dominant frequency present in the call of this species. Thus, the oral cavity appears as the ideal frequency-tuned candidate to amplify the acoustic signal (20). Finally, the tissues separating

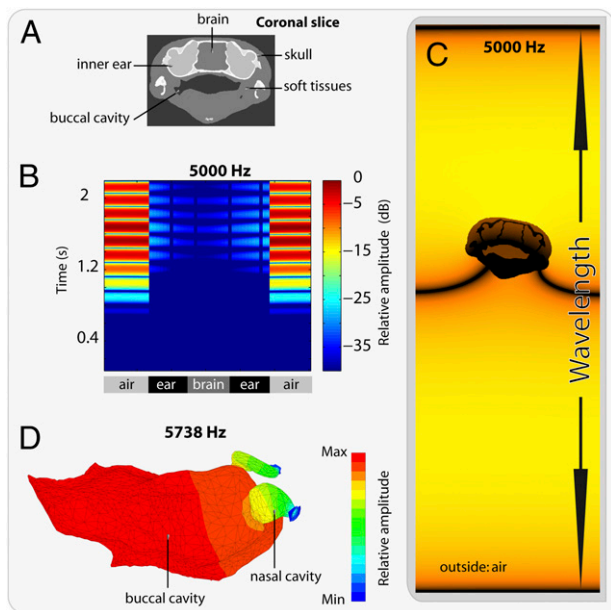


Fig. 3. Bone conduction in *S. gardineri*. (A) Image segmentation at the level of the inner ears used for bone conduction simulations. (B) Graphic representation of the acoustic pressure as a function of time (ms) along a line crossing the two inner ears; color bar shows the relative pressure amplitude in decibels. (C) Snapshot of the simulated field: visualization of the propagation of a pressure wave (at 5 kHz) on a coronal section of the skull. (D) Finite-element acoustic mode of the oral cavity and the nasal cavities with open nostrils in a 3/4 dorsal view. Color scale represents the acoustic pressure in Pascals.

the inner ear from the air cavity in the mouth are extremely thin ($\sim 80 \mu\text{m}$) in these frogs, both dorsally above the semicircular canals and ventrally toward the mouth under the sacculle (Fig. 2C), thus facilitating transmission from the resonator to the inner ear. This hypothesis was further investigated by measuring the distance between the mouth resonator and the inner ear for four earless frogs and three eared frogs of comparable size and for which holotomographic data were available (Table S2). Earless frogs have lower total tissue thickness between the oral cavity and the inner ear and a reduced number of interfaces, which both optimize transmission between the ear and the mouth. The role of the oral cavity as resonator, in association with bone conduction from the mouth to the inner ear is an original solution to hearing without a middle ear derived from preexisting anatomical structures and constitutes an interesting example of an exaptation (31). Aertsen and coworkers (20) and Palmer and Pinder (21), demonstrated the role of the oral cavity in rendering the coupling of eardrums asymmetric to account for the directionality of sound for hearing in frogs. We show here the enhancing role of the resonating mouth cavity in earless frogs, but the mouth could additionally play a role in detecting the directionality of sound for such earless frogs.

Our results contribute to an understanding of the evolution of the auditory system in tetrapods. It is commonly accepted that the evolution of the middle ear is associated with the transition from an aquatic to a terrestrial lifestyle. However, recent work on the earliest tetrapods has shown that these animals (32) possessed a specialized ossicle in the middle ear despite their largely aquatic lifestyle (33, 34). Furthermore, the tetrapod middle ear, with a tympanum, evolved independently at least four times in terrestrial tetrapods (35–37). We show that the presence of a middle ear is not a necessary condition for terrestrial hearing, despite being the most versatile solution for life on land (12, 24).

Methods

Study Site. Seychelles frogs were studied in the field at two locations in the Seychelles Islands: between April 9 and 29, 2002, at Jardin Marron and Anse Mondon on Silhouette Island ($4^{\circ}51'N$; $53^{\circ}3'W$, 300- to 500-m elevation; $4^{\circ}28'15''S$, $55^{\circ}13'40''E$, 300-m elevation). Recording and playback experiments were undertaken during the active phonation period of males (i.e., between 6.00:00 AM and 9.30:00 PM).

Electro-Acoustic Material. Calls were recorded at 1-m distance using an omnidirectional Brüel and Kjær serial 4053 microphone mounted on a 2.5-m boom and a Sony TCD-D100 digital audio tape (DAT) recorder (sampling rate = 48 kHz, frequency response flat within the range 20–20,000 Hz). Calls were analyzed with the Syntana signal processing software (38). Frequency measurements were performed on power spectra with the following fast Fourier transform (FFT) values: Hamming window, window size = 4,096 points, filter bandwidth = 120 Hz ($T = 1/F = 8.3$ ms). Sound pressure level (SPL in dB) measurements were taken by a Bioblock Scientific Sound Level Meter type 5017 (linear frequency scale, fast setting). For playback tests, signals were played back by a Sony WM6 recorder (frequency range, $30\text{--}20,000$ Hz ± 1 dB) connected to a Sony SRS-Z500 loudspeaker (frequency response, $100\text{--}16,000$ Hz ± 1.5 dB).

Call Analysis. Patterns of interindividual variability of advertisement calls were assessed by analyzing 52 signals of 10 calling males. Call duration (Cd), the fundamental frequency (f_0), and the dominant frequency (Df) were extracted. For each call parameter, we determined the mean, SD, minimum, and maximum.

Playback Design. Before a test, a speaker was placed at a distance of 1.5 m from the subject. To test the species-specific recognition, males were stimulated by a loudspeaker emitting two series of signals separated by a 2-min silent period. One series (the control series) consisted of conspecific calls and the other one (the experimental series) with *Eleutherodactylus martinicensis* calls. Each series consisted of 15 consecutive advertisement calls separated by artificial intercall silences (mean duration: 2.5 s). The order of presentation of both control and experimental series was randomized. In natural conditions, the response to an advertisement call was characterized by an obvious behavioral change in the male's attitude: calling in reply. On the basis of these observations, the intensity of responses of tested males to playback signals was evaluated.

Holotomography. One male and one female adult *S. gardineri*, one *Sechelophryne pipilodryas*, *Sooglossus sechellensis*, and *Sooglossus thomasseti* from Silhouette Island (Seychelles), and *Eleutherodactylus barlagnei*, *Eleutherodactylus johnstonei*, *E. martinicensis*, and *Eleutherodactylus pinchoni* from Guadeloupe Island were euthanized by an overdose of anesthetic (ketamine), fixed in 3.7% (wt/vol) formaldehyde solution, and placed in a small polypropylene tube for holotomographic imaging on return from the field. Protocols were approved by the ethics committee at the University of Paris XI. Animals were collected under collecting permits from the Seychelles Bureau of Standards and National Park of Guadeloupe. The quantitative X-ray phase contrast imaging [holotomography (39)] used the experimental station ID19 of the European Synchrotron Radiation Facility (Grenoble, France), on a long (150 m) imaging beamline with large spatial coherence of the beam. The X-ray photon energy was set to 20.5 keV with an exposure time of 0.5 s per image. Twelve hundred radiographic images with a $2,048 \times 2,048$ pixel resolution were acquired by a FReLoN CCD Camera (40). The effective pixel size at the converter screen position was $7.5 \mu\text{m}$, resulting in a field of view of $15 \times 15 \text{mm}^2$. The data set for a single sample comprised four angular scans, recorded at different sample detector distances (40, 300, and 995 m) and chosen to avoid consistently low values of the optical transfer function for some spatial frequencies. The retrieved phase maps (Fig. S2) were used as input to a filtered backprojection tomography reconstruction algorithm yielding the distribution of the electron density and a good approximation of the mass density. Volume renderings were obtained after segmentation by using isosurface representations and volume texture renderings with Avizo from VSG.

Geometrical and Quantitative Measurements. Geometrical and quantitative measurements of the sample were performed with ImageJ. The computation of 3D direct head thickness between inner ear and air was based on the calculation of the local thickness map and was implemented using the 3D Chamfer discrete distance (16). The mean degree of mineralization of bone (DMB, g/cm^3) was derived from the distribution of the X-ray attenuation coefficient in the absorption tomography scans corresponding to the first sample detector distance. Attenuation coefficients were converted

to volumetric tissue mineralization expressed as grams per centimeter cubed of hydroxyapatite crystals, as detailed in ref. 15. Quantitative measurements on the image datasets were performed with ImageJ. 3D regions of interest are selected on the skull (angulosplenic, otic capsule, columella, squamosal, operculum, parasphenoid, and pterygoid) and soft tissues (muscles: *depressor mandibulae*, opercular, *levator mandibulae posterior longus*, and *depressor mandibulae*; cartilage: menckelien, hyale, opercular, pectoral, omosternum, *crista paraotica*, and diploe; brain; skin; and tongue).

Numerical Simulation. Simulations were performed with a finite-differences program developed at the Institut Langevin (Paris, France). It solves the 3D linear wave equation in heterogeneous and absorbing media

$$\left\{ \rho_0(\vec{r}) \nabla \cdot \left[\frac{1}{\rho_0(\vec{r})} \nabla p(\vec{r}, t) \right] \right\} - \frac{1}{c_0(\vec{r})^2} \frac{\partial^2 p(\vec{r}, t)}{\partial t^2} = S_0(\vec{r}, t),$$

where $c_0(\vec{r})$ is the speed of sound, and $\rho_0(\vec{r})$ is the density. Simulations were conducted for frequencies ranging from 5 to 40 kHz. The simulation grid was set to 1/10th of a wavelength. To meet the stability criteria, the temporal step is given by

$$\Delta t < \frac{\Delta x}{\max_{\vec{r}} [c_0(\vec{r})] \sqrt{3}},$$

where Δx is the spatial step of the grid. For example, for a 5-kHz simulation, the temporal step was set to $\Delta t = 0.0054 \mu\text{s}$. Speed of sound and density maps were extracted from the high-resolution tomography images. The mean computation time was 18 h.

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