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Wave attenuation as a measure of muscle quality as measured by magnetic resonance elastography: Initial results

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Abstract

Advances in imaging technologies such as magnetic resonance elastography (MRE) have allowed researchers to gain insights into muscle function in vivo. MRE has been used to examine healthy and diseased muscle by calculating shear modulus. However, additional information can be measured from visualizing a mechanical wave as it passes through a tissue. One such measurable quantity is wave attenuation. The purpose of this study was to determine if a simple measure of wave attenuation could be used to distinguish between healthy and diseased muscle. Twenty seven subjects (14 healthy controls, 7 hyperthyroid myopathy patients, 6 myositis patients) participated in this study. Wave amplitude was determined along a linear profile through the center of the muscle, and an exponential decay curve was fit to the data. This measure was able to find significant differences in attenuation between healthy and diseased muscle. Furthermore, four hyperthyroid myopathy subjects who were tested following treatment all showed improvement by this measure. A likely reason for patients with hyperthyroid myopathy and myositis behaving similarly is that this measurement may reflect similar changes in the muscle extracellular matrix. In addition to modulus, attenuation seems to be an important parameter to measure in skeletal muscle. Further research is needed to investigate other potential measures of attenuation as well as examining other potential measures that can be found from visualizing wave propagation. Future studies should also include muscle biopsies to confirm that the changes seen are as a result of changes in extracellular matrix structure.

Keywords

Biomechanics; MRE; Collagen; Extracellular matrix; Myositis; Hyperthyroid myopathy

1. Introduction

Advances in imaging technologies have allowed researchers to gain insights into muscle function in vivo. Examples include using T2 weighted MR imaging to examine muscle activity (Fisher et al., 1990) and using velocity-encoded (Finni et al., 2006) or displacement-encoded (Zhong et al., 2008) cine phase-contrast MR to measure strain distribution within an active muscle. Elastography is another technique that has shown promise for examining muscle in vivo. Early elastography studies used ultrasound imaging (Levinson et al., 1995). However, magnetic resonance elastography (MRE) has several advantages over ultrasound, including the ability to examine deeper tissue (Heers et al., 2003) and has been shown to be

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Conflict of interest statement

None of the authors have a conflict of interest.

able to measure muscle tissue shear stiffness (Kruse et al., 2000). For a review of applications of MRE to skeletal muscle see Ringleb et al. (2007).

MRE is based upon the idea of applying a small amplitude vibration to the tissue of interest and generating shear waves that propagate through the tissue, while at the same time applying a motion-sensitizing gradient that is synchronized to the tissue vibration. Phase-contrast MRI is then used to visualize the waves as they pass through the tissue (Muthupillai et al., 1995). Typically an inversion technique is applied to calculate shear modulus throughout the tissue based on the wave motion (Manduca et al., 2001).

Several studies have used MRE to measure the shear modulus of healthy muscle in vivo (e.g. Dresner et al., 2001; Uffmann et al., 2004; Papazoglou et al., 2005; Bensamoun et al., 2006). MRE has also been shown to be able to measure changes in muscle associated with treatment for hyperthyroidism (Bensamoun et al., 2007) and to be able to detect myofascial taut bands (Chen et al., 2007). These studies have focused on the calculation of shear modulus. However, additional information can be obtained from visualizing a mechanical wave as it passes through a tissue. Viscosity seems a likely candidate parameter to calculate, as MRE has been used to calculate viscosity in other soft tissues (e.g. Sinkus et al., 2005; Klatt et al., 2007). Assuming for example the viscoelastic Voigt model and an isotropic media, a viscoelastic characterizing parameter can be calculated by exciting the muscle at multiple frequencies, measuring the wave lengths and attenuation at each frequency, and curve fitting wavelength–frequency and attenuation–frequency equations (Manduca et al., 2001). However, attenuation is related to viscosity and can be calculated simply, therefore seems to be a good measure for initial testing.

The purpose of this study was to determine if a simple measure of wave attenuation could be used to distinguish between healthy and diseased muscle.

2. Methods

Twenty seven subjects participated in this study. Fourteen study subjects were healthy controls (4 male and 10 female; age: 35.9 ± 16.4 years; height: 1.65 ± 0.10 cm; body mass: 64.5 ± 10.2 kg). Six subjects had myositis (2 male and 4 female; age: 44.5 ± 24.3 years; height: 1.65 ± 0.12 m; body mass: 72.8 ± 22.8 kg). Myositis patients were diagnosed by proximal muscle weakness, elevated serum levels of muscle enzymes, and muscle biopsy evidence of inflammation. Five of the myositis patients had dermatomyositis and one had polymyositis. The remaining seven study subjects had hyperthyroid myopathy (1 male and 6 female; age: 40 ± 14.9 years; height: 1.67 ± 0.052 m; body mass: 66.0 ± 12.8 kg). Hyperthyroid myopathy patients showed suppressed serum thyrotropin (TSH) and elevated levels of free thyroxine (FT4) and triiodothyronine (T3). FT4 ranged from 1.8 to 8.2 ng/dL, while TSH levels were all below 0.010 mIU/L. Of the seven hyperthyroid subjects four subjects were retested after treatment with radioactive iodine and levothyroxine replacement. All subjects provided informed consent, and all procedures were approved by the institutional review board.

Scans were performed with a 1.5 T General Electric Signa MRI machine. A custom-made Helmholtz surface receive coil was placed around the thigh for data acquisition (Bensamoun et al., 2006). The subjects laid supine with a 30° knee angle and were instructed to relax all muscles during the scans. Vibration was applied by a small silicone tube wrapped around the subject's thigh $\frac{1}{3}$ of the distance from the patellar tendon to the greater trochanter. This tube was connected via a long hose to an acoustic speaker operating at 90 Hz. The resulting vibration produced shear waves with amplitudes on the order of microns. When the MRE images were collected, four phase offsets were obtained. The flip angle was 45° and the FOV was 24×24 cm². The acquisition matrix was 256×64 , which was interpolated to 256

× 256. The slice thickness was 5 mm. The TR was 350 ms and the TE corresponded to the minimum spin echo time that allowed for motion encoding.

A series of axial scout images of the thigh was acquired using gradient echo sequence. From these images an oblique slice was drawn tangent to the medial curvature of the vastus medialis. This slice was then translated so that it was approximately in the middle of the muscle in a central axial image. Axial images were scrolled through to verify the placement of this plane stayed within the muscle (Bensamoun et al., 2006). MRE scans were performed in this plane (Fig. 1). Phase data was unwrapped and filtered using a bandwidth Butterworth filter with wavelength cutoffs of 0.48 and 4.8 m. At each pixel a time-domain, discrete Fourier analysis was performed on the displacement data of the four phase offsets, and the amplitude of the first harmonic component at 90 Hz was extracted and reported as the wave amplitude at that pixel. A linear profile was drawn starting in the center of the muscle at the point of vibration application (Fig. 2). This profile continued proximally to the end of the muscle in a direction estimated to be perpendicular to the wave motion from the phase image.

The values for amplitude along the profile were then used to determine a decay constant for wave attenuation in each subject. For each profile, the maximum value for amplitude was determined and used to normalize the data. Any points distal to the maximum were assumed to be a result of attenuation in the distal direction and were discarded. An exponential decay curve was fit to the remaining data using a least squares fit to Eq. (1) (Fig. 3).

$$\frac{A}{A_{Max}} = e^{-\lambda x} \quad (1)$$

where A is the displacement amplitude, A_{Max} is the maximum displacement amplitude, λ is the spatial decay constant of displacement amplitude and x is the distance along the profile measured in meters

A Student t -test was used to compare means of the decay constants between diseased and healthy muscle. A value for significance was set at 0.05.

3. Results

All results are presented as mean±standard deviation. Healthy muscle was found to have a decay constant of $38.1 \pm 12.1 \text{ m}^{-1}$ and diseased muscle was found to have a decay constant of $60.7 \pm 25.6 \text{ m}^{-1}$. This difference was found to be statistically significant. Means for the different pathologies were $55.6 \pm 27.5 \text{ m}^{-1}$ for myositis and $65.1 \pm 25.1 \text{ m}^{-1}$ for hyperthyroid (Fig. 4).

The four hyperthyroid patients whom retest data were available had a mean decay constant of $59.6 \pm 19.6 \text{ m}^{-1}$ pre-treatment and a mean decay constant of $29.3 \pm 11.3 \text{ m}^{-1}$ post-treatment. Each of the four subjects showed a decrease in decay constant following treatment (Fig. 5).

4. Discussion

A decay constant fit to wave amplitude data was selected as a simple measure of wave attenuation. This measure was able to find significant differences in attenuation between healthy and diseased muscle. Furthermore, four subjects who were tested following treatment all showed improvement by this measure.

A likely reason for patients with hyperthyroid myopathy and myositis behaving similarly is that this measurement may reflect changes in the muscle extracellular matrix. It is known that thyroid hormone induces matrix degradation by activating matrix metalloproteinase-1 (Ghose Roy et al., 2007) and as well as having a role in regulating collagen synthesis (Klein et al., 1996) in cardiac muscle. Increased activity of matrix metalloproteinases have also been seen in patients with myositis (Kieseier et al., 2001).

In addition to modulus, attenuation seems to be an important parameter to measure in skeletal muscle. However, the standard deviation of this measure was large. The large standard deviation in patients may be related to disease severity, but even in healthy subjects there was a relatively large standard deviation. Viscoelastic behavior of muscle is complex and depends on fiber orientation (van Loocke et al., 2008). Therefore, variation in the placement of the profile with respect to fiber orientation seems a likely cause for the large standard deviations found. Future studies should consider anisotropic models. Other issues such as nonlinearity and muscle inhomogeneity may also contribute to large standard deviations. Given that viscoelastic behavior of muscle is also rate dependent (van Loocke et al., 2008), future studies should consider collecting wavelength and attenuation data at multiple frequencies. Thus, allowing parameters which characterize the viscous and elastic properties related to shear deformation to be calculated by curve fitting different viscoelastic models.

Even though a simple measure of attenuation had large variation, statistically significant differences were observed between healthy and diseased muscle. The use of viscosity and incorporation of anisotropy will likely decrease variation and enhance the usefulness of this measure. Future studies should also include muscle biopsies to confirm that the changes seen are as a result of changes in extracellular matrix structure.

Acknowledgments

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Fig. 1. T2* weighted, gradient echo, axial image of the right thigh, showing the location of the scan plane through the vastus medialis.

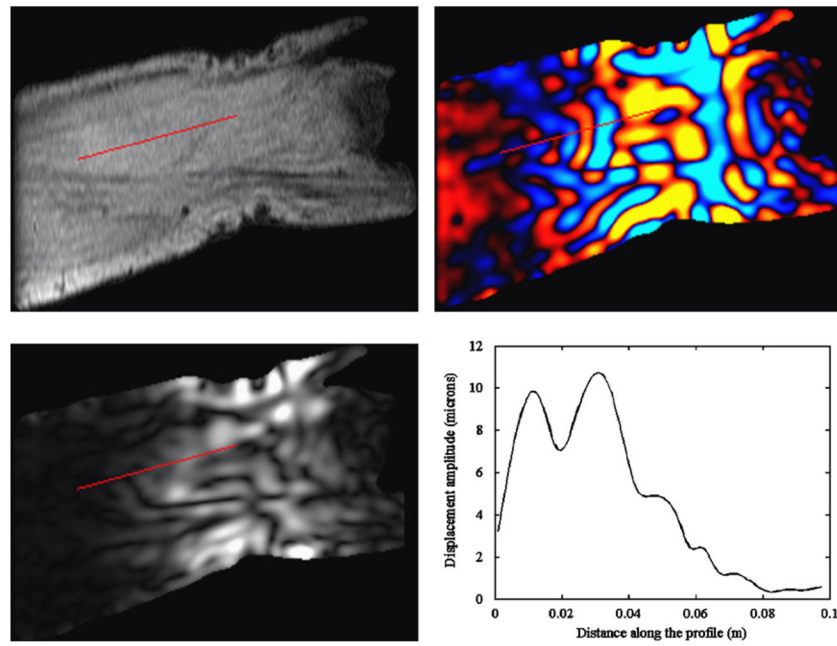


Fig. 2. Typical output from a MRE scan. Top left: magnitude image. Top right: phase image displaying wave displacements. Bottom left: displacement amplitude image. Bottom right: amplitude plot along the selected profile. The red line indicates the location of the linear profile. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

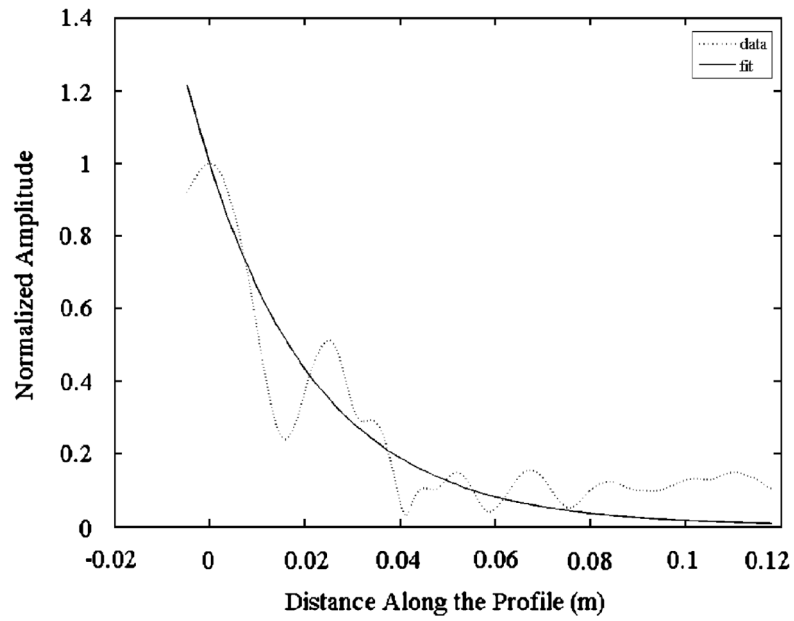


Fig. 3. Typical normalized amplitude data along the profile and the curve fit. Zero distance corresponds to the location of maximum amplitude along the profile. Data to the left of zero is disregarded.

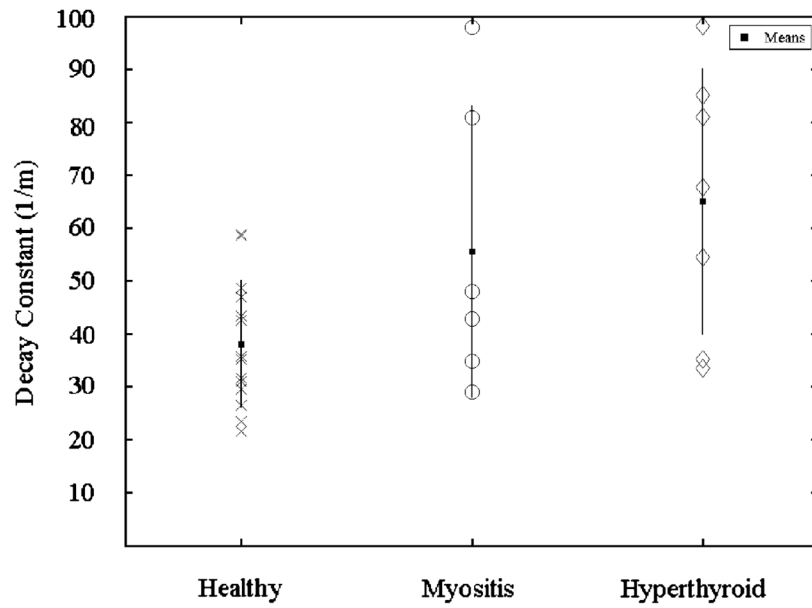


Fig. 4. Decay constants for each subject separated by group. The squares indicate group means. The lines indicate standard deviations.

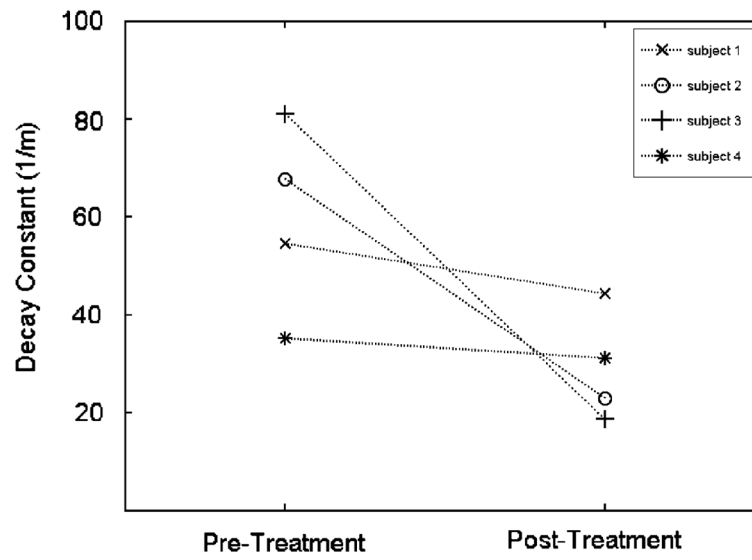


Fig. 5.
Decay constants for each hyperthyroid patient with pre- and post-treatment data.