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Force Plate Gait Analysis in Doberman Pinschers with and without Cervical Spondylomyelopathy

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Abstract

Background—The most accepted means of evaluating the response of a patient with cervical spondylomyelopathy (CSM) to treatment is subjective and based on the owner and clinician's perception of the gait.

Objective—To establish and compare kinetic parameters based on force plate gait analysis between normal and CSM-affected Dobermans.

Animals—Nineteen Doberman Pinschers: 10 clinically normal and 9 with CSM.

Methods—Force plate analysis was prospectively performed in all dogs. At least 4 runs of ipsilateral limbs were collected from each dog. Eight force platform parameters were evaluated, including peak vertical force (PVF) and peak vertical impulse (PVI), peak mediolateral force (PMLF) and peak mediolateral impulse, peak braking force and peak braking impulse, and peak propulsive force (PPF) and peak propulsive impulse. In addition, the coefficient of variation (CV) for each limb was calculated for each parameter. Data analysis was performed by a repeated measures approach.

Results—PMLF ($P = .0062$), PVI ($P = .0225$), and PPF ($P = .0408$) were found to be lower in CSM-affected dogs compared with normal dogs. Analysis by CV as the outcome indicated more variability in PVF in CSM-affected dogs ($P = 0.0045$). The largest difference in the CV of PVF was seen in the thoracic limbs of affected dogs when compared with the thoracic limbs of normal dogs ($P = 0.0019$).

Conclusions and Clinical Importance—The CV of PVF in all 4 limbs, especially the thoracic limbs, distinguished clinically normal Dobermans from those with CSM. Other kinetic parameters less reliably distinguished CSM-affected from clinically normal Dobermans.

Keywords

Cervical vertebral instability; Dog; Kinetic; Wobbler

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Cervical spondylomyelopathy (CSM) is the most common cervical spinal disease of large and giant breed dogs, with Doberman Pinschers and Great Danes being overrepresented.¹⁻⁷ This term collectively refers to several disorders of the caudal cervical vertebrae and intervertebral disks that result in static and dynamic compression of the spinal cord.^{5,8} Gait abnormalities are the hallmark of dogs suffering from CSM. Clinical signs often involve varying degrees of ataxia, paresis, or both affecting the pelvic limbs,^{5,9-11} with the most common initial presentation being a slowly progressive pelvic limb ataxia and paresis with less severe changes in the thoracic limbs.^{1,5,9,10} The diagnosis of CSM is not always straightforward and requires advanced imaging or myelography. In addition, the treatment for CSM is controversial, with several surgical techniques available to treat the disease.

Determining a CSM patient's response to treatment currently is highly subjective and based on client interpretation and gait examination in which patients are determined to be "improved, worse, or unchanged." This assessment is very subjective because, in principle, there is no difference in the degree of improvement between a dog that demonstrated improvement after treatment, but still is severely ataxic and disabled, and a dog that returns to normal or almost normal function. Development of a more objective means of assessing an affected dog's neurologic status is essential to allow objective comparisons of treatment methods and outcome.

Force plate analysis is a noninvasive, objective measurement to evaluate limb loading in humans and animals,^{12,13} and it has been used to study normal gait as well as experimentally induced or naturally occurring lameness in dogs.¹⁴⁻²⁷ In addition, ground reaction forces using force plate analysis have been evaluated as an assessment of recovery in dogs treated for lumbosacral stenosis.^{28,29} Force plate analysis also has been proven to be useful in differentiating between orthopedic and neurologic causes of gait abnormalities in horses.³⁰ There have been no studies investigating the force plate characteristics of dogs with cervical spinal cord diseases causing weakness and ataxia.

The purpose of this study was to prospectively identify force plate parameter differences between Doberman Pinschers with CSM and normal Doberman Pinschers. We hypothesized that a subset of the force plate parameters, namely peak vertical force (PVF) and peak mediolateral force (PMLF), would be significantly altered in Doberman Pinschers with CSM because of ataxia, paresis, or a combination of both. Identification of consistent differences in kinetic parameters between normal and CSM-affected dogs will serve as an initial step in the development of objective outcome measures for monitoring response to medical or surgical treatment in dogs with CSM.

Materials and Methods

Animals

Nineteen client-owned mature Doberman Pinscher dogs were prospectively enrolled in this investigation. The study was conducted in accordance with the guidelines and with approval of the Clinical Research Advisory Committee and the Institutional Animal Care and Use Committee. Written owner consent was obtained before study enrollment.

Normal Dogs

Dogs were considered normal and eligible for study enrollment if they were 1 year of age and had no abnormalities identified on physical, orthopedic, and neurologic examinations. In addition, they could not have any previous orthopedic or neurologic disease.

Affected Dogs

Inclusion criteria for affected dogs included a history of pelvic limb ataxia, paraparesis, tetraparesis with or without neck pain in a mature Doberman Pinscher dog in addition to neurologic examination findings consistent with cervical myelopathy. All affected dogs had physical and neurologic examinations, CBC, serum biochemistry profile, cervical spinal radiographs, and magnetic resonance imaging (MRI) examination of the cervical spine. Neurologic status at the time of 1st examination was graded on a scale from 1 to 5 on the basis of a previously published grading scale.^{31,32} Dogs classified as Grade 1 had cervical hyperesthesia only. These patients were excluded from participation. Grade 2 dogs had mild pelvic limb ataxia or paresis with mild thoracic limb involvement. Thoracic limb involvement was defined as either short-strided or spastic gait with a floating appearance. Grade 3 dogs had moderate pelvic limb ataxia or paresis with thoracic limb involvement as described in Grade 2. Grade 4 was defined as marked pelvic limb ataxia or paresis with thoracic limb involvement, and Grade 5 was defined as nonambulatory tetraparesis. Any dog with Grade 5 neurologic status also was excluded from the study. The diagnosis of CSM was confirmed in all dogs by MRI, utilizing a modified standard protocol³² to support evidence of spinal cord compression with or without spinal cord signal change. Thoracic radiographs were performed in all dogs >7 years of age (n = 5). Neurologic examinations of all dogs (normal and affected) were performed by 2 of the investigators (K.F. and R.d.C.).

Gait Analysis

Force plate analysis was performed in all 4 limbs of all dogs by a stationary force plate^a and computer analysis system.^b The force plate was 40 × 60 cm and mounted flush with the surface and in the center of a 6-m walkway (Fig 1). All dogs were weighed on the same digital scale before data collection and force plate data forces in Newton (N) were normalized to body weight (BW). Each dog was walked across the walkway for 5–10 minutes to acclimate the animal to the laboratory before data collection. Valid repetitions were recorded from the left and right sides of the body (minimum of 2 and maximum of 8 repetitions). A valid repetition was defined as a passage over the force plate by the dog in which the ipsilateral thoracic and pelvic limb fully contacted the surface of the plate and the gait velocity was within the range of 0.8–1.5 m/s. Dogs were walked in both directions, and starting position was standardized in each direction. Gait velocity was measured by the use of 3 photoelectric switches (spaced 1 m apart) connected to the computer system.

Three force-to-time curves were generated by the computer analysis system to compute 8 kinetic parameters in each limb. These parameters included PVF, peak vertical impulse (PVI), peak braking force (PBF), peak braking impulse (PBI), peak propulsive force (PPF),

^aKistler Model 9687A force platform, Kistler Instrumente AG, Winterhur, Switzerland

^bAcquire 7.35, Sharon Software, Inc, Dewitt, MI

peak propulsive impulse (PPI), PMLF, and peak mediolateral impulse (PMLI). Force peaks and impulses were expressed as percentage of body weight and percentage of body weight per second by normalizing a dog's weight and multiplying it by time. Descriptive statistics (mean, standard deviation, range) were calculated for each force plate parameter. In addition, the CV for PVF and PMLF were calculated for each limb.

Data Analysis

A repeated measures analysis by commercial statistical software^c was performed and the significance level was set at $P < .05$. First, all 8 parameters were compared between normal and CSM-affected dogs. Then, left and right side and thoracic and pelvic limbs were compared using all data as well as data from normal and CSM-affected dogs separately. To account for the nonindependent observations and measurements within limbs and limbs nested within dogs, compound symmetry covariance structure was used. Similarly, variability in PVF and PMLF between normal and CSM-affected dogs, as well as between left and right side, and thoracic and pelvic limbs was compared by the coefficient of variation (CV) as the outcome variable as follows:

$$CV (\%) = [(SD \text{ of valid repetitions}) / (\text{mean of valid repetitions})] \times 100.$$

Results

A total of 19 dogs were enrolled and placed into 1 of 2 groups. The 1st group consisted of 10 clinically normal Doberman Pinschers, of which 9 were male and 1 was female between 1 and 7 years old (mean, 4.2 years; SD, 1.8; median, 4 years) with body weights ranging from 31.3 to 43.6 kg (mean, 37.9; SD, 4.5; median, 39.3 kg). The affected group consisted of 9 Doberman Pinschers dogs that included 6 males and 3 females between 3 and 12 years old (mean, 7.7 years; SD, 3.5; median, 9 years). Clinical signs included mild pelvic limb ataxia or paresis with mild thoracic limb involvement (Grade 2; $n = 4$), moderate pelvic limb ataxia or paresis with thoracic limb involvement (Grade 3; $n = 2$), and marked pelvic limb ataxia or paresis with thoracic limb involvement (Grade 4; $n = 3$). The body weights of the dogs ranged from 27.2 to 55.8 kg (mean, 37.4 kg; SD, 6.7; median, 35.6 kg). All CSM-affected dogs had spinal cord compression in the caudal cervical spine. The main compression was at C5-6 in 3 dogs, and at C6-7 in 6 dogs. Kinetic gait analysis was performed in all dogs without any complications. The entire procedure required no more than 2 personnel to complete. Data collection time, including warm-up, ranged from 20 minutes to 2 hours (mean, 45 minutes) to acquire all valid passes. The collection time was approximately 1 hour for normal dogs and 1 hour for affected dogs. Time required for data collection did not appear to be associated with neurologic status. The mean number of valid passes collected during this process was 4.9 for the normal dogs (range, 3–8) and 4.5 (range, 2–6) for the CSM-affected dogs.

Descriptive statistics (mean \pm SD) of all kinetic parameters are presented in Table 1. Based on the repeated measures analysis when adjusting for the correlated data structure, PVF was

^cSAS 9.2, SAS Institute, Cary, NC

not significantly different between normal and affected dogs ($P = .3031$). However, PVF was significantly higher in the thoracic limbs than in the pelvic limbs ($P < .0001$) of all dogs. PMLF, using data from all 4 limbs, on the other hand, was significantly lower in CSM-affected dogs versus normal dogs ($P = .0062$) as were PVI ($P = .0225$) and PPF ($P = .0408$). No significant differences were detected in PPI, PBF, PBI, or PMLI when comparing normal and affected dogs.

A summary of the data using CV as an outcome is presented in Table 2. When comparing CV of PVF between normal and affected dogs, the values were significantly higher in CSM-affected than normal dogs ($P = .0045$). When stratifying the data to compare the thoracic limbs of normal and affected dogs, the CV of PVF in the thoracic limbs of affected dogs also was much higher than that of normal dogs ($P = .0019$, Fig 2). However, no significant differences were found in the pelvic limbs between normal and affected dogs. The CV values of PMLF were not different between normal and affected dogs ($P = .4926$), or between thoracic and pelvic limbs (Fig 3).

Discussion

This study is the first to use force plate analysis to investigate changes in gait pattern in dogs suffering from a cervical myelopathy. Of 26 different parameters evaluated, only 5 were found to be of significance, including PMLF, PVI, PPF, CV PVF, and the thoracic limb CV PVF. We found that dogs with CSM have much more variability in their PVF, in particular the PVF of the thoracic limbs, but not in the pelvic limbs. Previous force plate studies have shown that dogs have a different weight distribution between the thoracic limbs and the pelvic limbs. The thoracic limbs carry about 60% of the body weight, whereas the pelvic limbs carry 40% of the body weight during a walk.^{12,33} In addition, it has been observed that ataxic dogs have a tendency to shift their weight even more onto their thoracic limbs as a result of hind limb ataxia.³⁴ These dogs also show some degree of ataxia in the thoracic limbs, which may play a role in the larger variability in PVF in affected dogs. For example, an ataxic dog may not be able to recognize its limb position and therefore cannot adjust the timing of foot landing based on visual perception. This then may lead to footfalls that occur early or late, leading to random weight distribution during each pass across the force plate, and greater variation in PVF with each step. Studies in humans have shown increased vertical forces when walking on an unbalanced surface with blocking of the lower visual field.^{13,35} When a patient has an unexpected footfall, the next step may be more hesitant, leading to a decrease in PVF of that limb in the subsequent foot placement.³⁶ The combination of bearing more weight in the thoracic limbs and the incoordination associated with ataxia may lead not only to a larger PVF in the thoracic limbs but also to a greater variability in PVF in the affected dogs. Despite this finding, there was a great deal of overlap in the CV of the PVF in both CSM-affected dogs and normal dogs, suggesting that force plate analysis may be able to distinguish severely affected dogs from normal dogs, but may not be as clinically useful for discriminating between normal dogs and mildly affected dogs.

Dogs with CSM have upper motor neuron paresis (which typically is associated with increased muscle tone) and proprioceptive ataxia, versus a musculoskeletal weakness, which

may explain why there were no differences detected in mean PVF between normal and affected dogs in either the thoracic or pelvic limbs. The mean PVI from all 4 limbs also was significantly lower in CSM-affected dogs compared with normal dogs. Normal dogs may have a longer stance phase to account for this difference, because the average velocity was not different between normal and affected dogs (1.08 and 1.07 m/s, respectively). PPF also was higher in all limbs of normal dogs. One explanation could be related possibly to a longer stance phase, because this phase of the gait often is broken into 2 parts: the braking forces, which are the impulses required to decrease momentum in the early stance phase; and the propulsion forces, which are the impulses required to increase momentum during the late stance phase.^{12,33} The thoracic limbs spend approximately 50% of the stance phase in braking and 50% in propulsion, whereas the pelvic limbs spend approximately 35% in braking and 65% in propulsion.^{12,33} Dogs with CSM can present with varying degrees of ataxia and weakness in the thoracic and pelvic limbs, which may alter the distribution of braking and propulsive forces, leading to decreased propulsion.

We expected that CSM-affected dogs also would show increased mediolateral forces as well as more variability in these forces. However, the mean peak MLF was not different between groups, nor was there a difference in the variability in the peak MLF. In fact, the peak MLF was found to be higher in all limbs of normal dogs, but not statistically different from the CSM dogs. This may be related to the fact that this force is based on measuring the estimate of mediolateral movement and not assessing stability of the patient. However, a study assessing force plate analysis in ataxic horses concluded that they had significantly larger mediolateral force peaks in the pelvic limbs than did normal or horses with musculoskeletal lameness.³⁰ This may be explained by the observation that ataxic horses may have an elongated swaying motion resulting in exaggerated sideways movement, allowing detection of magnitude of force. This theory of exaggerated sideways movement most likely is true in dogs as well. However, horses are larger and theoretically may supply a larger amount of force, whereas mediolateral forces have been reported to be difficult to determine in dogs.¹⁵ This may be attributed to the fact that mediolateral forces are considered to be <6% of a dog's body weight.¹⁵ Perhaps a more reliable assessment of instability in ataxic dogs would be to assess the patient's center of pressure by means of stabilography. This method has been used widely in human medicine as a means of diagnosing a variety of neurologic disorders, including cervical spinal disorders.³⁷⁻⁴⁰ This method also has been applied in measuring postural sway in horses, but has not yet been evaluated in dogs.^{41,42} Another possible way to eliminate variability would be to calculate a symmetry index for the PVF and PMLF. This index has been used previously in studies on lameness in dogs to remove interdog variations because this calculation requires every dog to serve as its own control.¹⁹ In addition, the CV PMLF was quite large. Valid passes were collected from the ipsilateral limbs. A possible cause for the high CV may be attributed to using only 1 force plate to measure this value. For example, if an ataxic dog were to stumble when crossing the force plate, it may off-load the ataxic limbs during that pass and, during the next pass, bear more weight on the affected limbs. One possible way to address this issue would be to utilize 2 force plates to measure limbs simultaneously.

Limitations of this study include its small sample size. However, it is not uncommon for studies utilizing force plates to assess gait in veterinary medicine with small samples

sizes,^{15,21,29,30,43,44} and our sample size actually was larger than some previous force plate studies.^{17,24,26,29,44} We also used a wide range for our velocity (0.8–1.5 m/s) to be able to obtain valid passes, especially in the more severely affected dogs. The standard speed for a walking dog is about 1.0 ± 0.3 m/s,^{29,43} but some studies have included a velocity of 2 m/s within the range of walking speeds.¹⁵ However, this large range of velocity may have led to more variability in the value of the PVF in our cases.^{14,25} In addition, the data collection time was widely variable. Although we did not observe any difference in collection time between the 2 groups, we did observe that some dogs took longer than others, regardless of status, based solely on their behavior when being led on a leash. Furthermore, we attempted to collect data from ipsilateral limbs for a valid pass, which to our knowledge, has not been attempted previously. Most force plate studies, especially those assessing lameness, have focused on collecting data from 1 limb at a time, which may lead to more rapid collection times. Lastly, our sample size was small, which may have led to the study being underpowered. Before data collection, a power analysis was performed to estimate the number of dogs necessary to detect a 20% difference between the groups to give a power of 0.8, which gave a number of 20 dogs (10 in each group). A post hoc power analysis was also performed and indicated that it would be necessary to enroll between 76 and 270 dogs in each group to have a power of 0.8 with a significance of 0.05 for PVF. To have a power of at least 0.8 and significance of 0.05 for PMLF between 29 and 87 dogs would be needed per group. Based on these results, it would have been impossible to enroll enough dogs of 1 breed to complete the study in a timely manner.

In conclusion, we found significantly more variability in the PVF of CSM-affected dogs compared with normal dogs, but we also observed substantial overlap between normal and affected dogs. In addition, several other parameters, including PMLF, were not found to be significantly different between Doberman Pinschers with and without CSM. The limited information provided by force plate analysis to detect differences between normal and affected dogs, coupled with the prolonged acquisition time, makes force plate analysis a method with limited applicability for use in the clinical setting for dogs with CSM. However, although there were not marked differences in variability between normal and affected dogs, there may be more substantial differences in variability detected within the same affected dog, which then may be used as a measure of outcome.

Acknowledgments

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Abbreviations

CSM	cervical spondylomyelopathy
CV	coefficient of variation
MRI	magnetic resonance imaging
PBF	peak braking force

PBI	peak braking impulse
PMLF	peak mediolateral force
PMLI	peak mediolateral impulse
PPF	peak propulsive force
PPI	peak propulsive impulse
PVF	peak vertical force
PVI	peak vertical impulse

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Fig 1.
Force plate gait analysis in a clinically normal Doberman Pinscher.

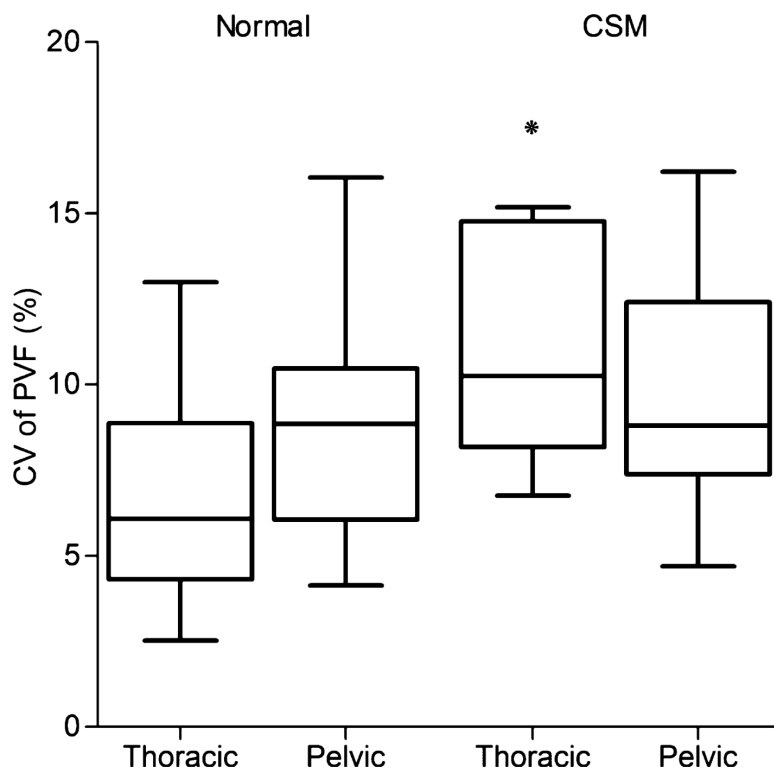


Fig 2. Boxplot of the coefficient of variation in the PVF in normal and CSM-affected dogs. The box represents the interquartile range (25–75%), and the line in each box delineates the median value. Overall, CSM-affected dogs had a significantly higher variability in PVF versus normal dogs, but more specifically, in the thoracic limbs. * $P = .0045$; PVF, peak vertical force; CV, coefficient of variation; CSM, cervical spondylomyelopathy.

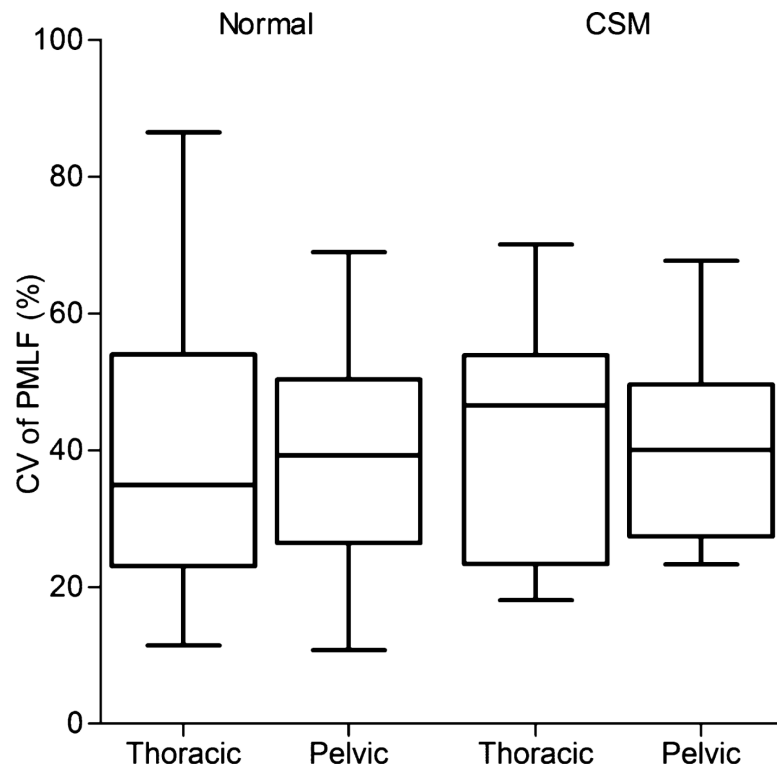


Fig 3. Boxplot of the coefficient of variation in the PMLF in normal and affected dogs. There was no significant difference in the CV of the PMLF between the normal and affected dogs. CV, coefficient of variation; PMLF, peak mediolateral force. See Figure 1 for remainder of key.

Table 1

Median (\pm SD) of force plate parameters from all 4 limbs in normal and CSM-affected dogs.

Force Plate Parameter	Normal Dogs (n = 10)			Affected Dogs (n = 9)		
	All Limbs	Thoracic Limbs	Pelvic Limbs	All Limbs	Thoracic Limbs	Pelvic Limbs
PVF (100 \times N/N)	57.72 \pm 11.0	65.21 \pm 6.02	47.08 \pm 6.31	60.19 \pm 15.9	65.52 \pm 14.3	47.07 \pm 11.05
PVI (100 \times Ns/N)	20.04 \pm 12.5	25.05 \pm 13.4	15.855 \pm 9.44	16.74 \pm 5.9	21.3 \pm 6.343	15.835 \pm 3.63
PPF (100 \times N/N)	7.2 \pm 3.3	8.465 \pm 3.3	6.375 \pm 3.03	6.325 \pm 3.8	6.88 \pm 3.77	6.185 \pm 3.74
PPI (100 \times Ns/N)	1.075 \pm 1.1	1.005 \pm 1.03	1.15 \pm 1.2	0.765 \pm 1.1	0.52 \pm 0.84	1.175 \pm 1.25
PBF (100 \times N/N)	-8.57 \pm 5.0	-10.685 \pm 4.97	-6.7 \pm 4.7	-8.405 \pm 4.6	-9.24 \pm 4.4	-7.215 \pm 4.55
PBI (100 \times Ns/N)	-1.015 \pm 1.4	-1.68 \pm 1.14	-0.64 \pm 1.62	-0.975 \pm 1.1	-1.205 \pm 1.1	-0.625 \pm 0.97
PMLF (100 \times N/N)	-3.015 \pm 7.3	-3.015 \pm 7.03	-3.015 \pm 7.53	-2.73 \pm 5.16	-2.805 \pm 5.24	-2.71 \pm 5.12
PMLI (100 \times Ns/N)	-0.46 \pm 2.7	-0.495 \pm 2.65	-0.39 \pm 2.7	-0.31 \pm 1.4	-0.31 \pm 1.46	-0.32 \pm 1.52

PVF, peak vertical force; PVI, peak vertical force; PPF, peak propulsive force; PPI, peak propulsive impulse; PBF, peak braking force; PBI, peak braking impulse; PMLF, peak mediolateral force; PMLI, peak mediolateral impulse; SD, standard deviation.

Table 2

Standard deviation, mean, and coefficient of variation for PVF and PMLF from all 4 limbs of normal and CSM-affected Doberman Pinschers.

Force Plate Parameter	Normal Dogs (n = 10)			Affected Dogs (n = 9)		
	All Limbs	Thoracic Limbs	Pelvic Limbs	All Limbs	Thoracic Limbs	Pelvic Limbs
PVF SD (100 × N/N)	11.00562845	5.354030205	46.93352928	15.87375	14.26288648	10.70708963
Mean PVF (100 × N/N)	56.23964709	65.54576491	63.05106915	59.48801	69.1505131	49.82551286
PVF CV (%)	19.56916343	8.168384659	13.43412058	26.68395	20.62585777	21.48917094
PMLF SD (100 × N/N)	3.100395	3.028367	3.148396	2.499764	2.639914	2.123727
Mean PMLF (100 × N/N)	5.927	5.665176	6.188824	4.719936	4.946154	4.60141
PMLF CV (%)	52.30969	53.45583	50.87229	52.96182	53.37307	46.15383

PVF, peak vertical force; PMLF, peak mediolateral force; SD, standard deviation; CV, coefficient of variation.