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A Penalized Robust Method for Identifying Gene-Environment Interactions

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Abstract

In high-throughput studies, an important objective is to identify gene-environment interactions associated with disease outcomes and phenotypes. Many commonly adopted methods assume specific parametric or semiparametric models, which may be subject to model mis-specification. In addition, they usually use significance level as the criterion for selecting important interactions. In this study, we adopt the rank-based estimation, which is much less sensitive to model specification than some of the existing methods and includes several commonly encountered data and models as special cases. Penalization is adopted for the identification of gene-environment interactions. It achieves simultaneous estimation and identification and does not rely on significance level. For computation feasibility, a smoothed rank estimation is further proposed. Simulation shows that under certain scenarios, for example with contaminated or heavy-tailed data, the proposed method can significantly outperform the existing alternatives with more accurate identification. We analyze a lung cancer prognosis study with gene expression measurements under the AFT (accelerated failure time) model. The proposed method identifies interactions different from those using the alternatives. Some of the identified genes have important implications.

Keywords

Gene-environment interaction; robust rank estimation; penalization; marker identification

Introduction

High-throughput profiling has fundamentally changed the paradigm of research and practice of multiple diseases. Multiple types of genetic, epigenetic, genomic, and proteomic measurements have been generated. To avoid confusion, we use the generic terminology "gene", which matches the gene expression data analyzed in this article but note that the

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proposed method is also applicable to other types of genetic and genomic measurements. For complex diseases such as cancer and diabetes, the risk and progression are associated with the combined effects of genes, clinical and environmental risk factors, and their $G \times E$ (gene-environment) interactions. For the identification of important interactions, there are multiple families of approaches, including for example the joint approach and stratification approach. For comprehensive discussions, we refer to Hunter [2005], North and Martin [2008], Thomas [2010] and others. In this article, we focus on the statistical modeling approach, where interactions are described using the products of variables in statistical models. In general with high-dimensional measurements on genes, there are two types of analyses [Witten and Tibshirani 2010]. The first conducts marginal analysis and analyzes one gene at a time, and the other describes the joint effects of all genes in a single model. The proposed method conducts marginal analysis, which is still more popular than the joint analysis in $G \times E$ interaction studies.

Denote *Y* as a disease outcome or phenotype. It can be a continuous marker, categorical disease status, or survival time. Denote $Z = (Z_1, ..., Z_p)$ as the *p* genes and $X = (X_1, ..., X_q)$ as the *q* clinical/environmental risk factors. Assume *n* iid observations. The most popular statistical modeling approach proceeds as follows. (1) For k = 1, ..., p, fit a parametric or semiparametric model $Y \sim \phi(\sum_{l=1}^{q} \alpha_{kl}X_l + \gamma_k Z_k + \sum_{l=1}^{q} \beta_{kl}X_l Z_k)$. For example with a binary *Y*, φ can be the logistic model. α_{kl} 's, γ_k , and β_{kl} 's are the unknown regression coefficients. As usually $q \ll n$, for each *k*, this step can be carried out using standard techniques and software. Denote p_{kl} as the p-value of β_{kl} , the estimate of β_{kl} . (2) With $\{p_{kl}: k = 1, ..., p, l = 1, ..., q\}$, conduct multiple comparison adjustment. Approaches such as the FDR (false discovery rate) can be applied to identify significant interactions. Multiple existing approaches belong to this category [Hunter 2005; Thomas 2010]. Different approaches may have minor differences in terms of statistical models, hypothesis testing methods, and multiple comparison adjustment techniques.

The above approach has the following limitations. With p genes, it is likely that some of the p models are mis-specified. Although in principle it is possible to conduct model diagnostics, to the best of our knowledge, there is no study actually examining the validity of all p regression models. There are a few robust methods. A popular one is the multifactor dimensionality reduction (MDR) [Moore et al. 2006], which provides a powerful approach to detect nonlinear interactions among discrete attributes that are predictive for discrete outcomes. However, it cannot be directly adapted to continuous outcomes or discrete outcomes associated with continuous attributes. Other robust methods may share a similar limitation of restricted applicability. In addition, most of the existing methods use significance level to identify interactions. For some estimates, for example the rank estimate proposed in this study, computing the p-values can be computationally tedious. Moreover, as shown in our simulation study, the significance based methods may have less satisfactory performance.

In this article, we analyze high-throughput data and search for important gene-environment interactions. A statistical modeling approach is adopted, which detects interactions by conducting estimation with β_{kl} 's. A new method is developed to overcome some limitations

of the existing methods. Specifically, we assume a general semiparametric transformation model, which makes much weaker model assumptions and hence can be less sensitive to model mis-specification. Correspondingly, a rank-based estimation approach is proposed. This modeling and estimation framework can accommodate continuous, categorical, and censored survival data and includes many commonly adopted models as special cases. We propose using penalization for estimation. In general, for data with a small to moderate sample size, penalization can lead to more reliable estimates. More importantly, for the present problem, penalization can identify important interactions along with estimation, without relying on the significance level. Thus it provides an alternative strategy for identifying interactions. For computational feasibility, a smoothed penalized rank estimation is developed. Simulation study and data analysis are conducted to examine performance of the proposed method.

Robust Modeling and Rank Estimation

Semiparametric transformation model

We use notations similar to those in the above section. For gene k(=1, ..., p), consider the model

$$E(g_{k}(Y)) = \sum_{l=1}^{q} X_{l} \alpha_{kl} + Z_{k} \gamma_{k} + \sum_{l=1}^{q} X_{l} Z_{k} \beta_{kl} = \theta'_{k} W_{k}, \quad (1)$$

where $W_k = (X, Z_k, Z_kX)'$, $a_k = (a_{k1}, ..., a_{kq})'$ is the unknown coefficient vector for clinical and environmental factors, γ_k is the main gene effect, $\beta_k = (\beta_{k1}, ..., \beta_{kq})'$ corresponds to $G \times$

E interactions, and $\theta_k = (\alpha'_k, \gamma_k, \beta'_k)'$. Model (1) is a semiparametric transformation model where the form of the transformation function g_k is left *unspecified*, making the model assumptions much weaker than the existing ones. For identifiability, it is assumed that g_k is monotone (without loss of generality, monotone increasing). Under the approach described in the Introduction section, different genes usually have the same φ . Here different genes are allowed to have different transformation functions, making this model much more flexible.

For a continuous outcome, model (1) includes $g_k(Y) = \theta'_k W_k + \varepsilon_k$ as a special case. When $g_k(t) = t$ and $g_k(t) = log(t)$, this model reduces to the additive and multiplicative error models, respectively. When $g_k(t)$ takes the form of a power function and ε_k follows a normal distribution, we obtain the Box-Cox transformation model. For categorical data, model (1) includes many commonly adopted generalized linear models, for example the logistic model and probit model for binary data and Poisson model for count data. For survival data, model (1) accommodates transformation models (which include the Cox model, accelerated failure time (AFT) model, exponential and other parametric models, etc) and the additive risk model. Thus model (1) indeed has broad applications.

Rank estimation

In principle, it is possible to build estimating equations and simultaneously estimate g_k and θ_k . However, nonparametric estimation of g_k can be computationally expensive. A small

scale simulation to be presented below also shows that it may lead to inferior results. For the identification of important interactions, only θ_k is of interest. In this study, we adopt the rank-based estimation [Han 1987; Khan and Tamer 2007], which can avoid estimating g_k .

With *n* iid subjects, use the subscripts *i* and *j* to denote the *i*th and *j*th subjects, respectively. For gene k(=1, ..., p), consider the estimate $\hat{\theta_k} = argmax_{\theta_k} O(\theta_k)$, with the objective function $O(\cdot)$ defined as follows. (a) When *Y* is continuous,

$$O(\theta_k) = \frac{1}{n(n-1)} \sum_{i \neq j} I(Y_i \ge Y_j) I(\theta'_k W_{ik} \ge \theta'_k W_{jk}), \quad (2)$$

where $I(\cdot)$ is the indicator function. (b) When Y is categorical, first consider a binary outcome. Denote D and H as the index sets for diseased (Y = 1) and healthy (Y = 0) subjects with sizes n_D and n_H , respectively. Then

$$O(\theta_k) = \frac{1}{n_D n_H} \sum_{i \in D, j \in H} I(\theta'_k W_{ik} \ge \theta'_k W_{jk}) = \frac{1}{n_D n_H} \sum_{i \neq j} I(Y_i > Y_j) I(\theta'_k W_{ik} \ge \theta'_k W_{jk}).$$
(3)

 $O(\theta_k)$ is the empirical AUC (area under curve) under the ROC (receiver operating characteristics) framework [Pepe 2004]. With multi-category data, the construction of rank estimates may follow Pepe [2004] and followup studies. (c) When *Y* is a right-censored survival outcome, denote *C* as the censoring time. One observes ($V = \min(Y, C)$, = I(Y C)), where is the event indicator. Here

$$O(\theta_k) = \frac{1}{n(n-1)} \sum_{i \neq j} \Delta_j I(Y_i \ge Y_j) I(\theta'_k W_{ik} \ge \theta'_k W_{jk}), \quad (4)$$

which is closely connected with the integrated time-dependent AUC [Li and Ma 2011]. Under more complex censoring patterns (for example interval censoring), it is also possible to develop rank estimation [Li and Ma 2011]. However, such data are rarely encountered in genomic data analysis and hence not further discussed.

In the above rank-based objective functions, θ_k is only identifiable up to a constant. Without loss of generality, we assume that $|a_{k1}| = 1$, k = 1, ..., p. With a slight abuse of notations, we still use θ_k to denote the remaining coefficients $(a_{k2}, ..., a_{kq}, \gamma_k, \beta_{k1}, ..., \beta_{kq})'$. Although there are some minor differences, the objective functions in (2), (3), and (4) all belong to the MRC (maximum rank correlation) framework. Their asymptotic behaviors can be established following Han [1987] and Sherman [1993], and computationally they can be solved using similar algorithms.

Penalized Identification of G × E Interactions

For the identification of important $G \times E$ interactions, we propose the following penalization method. For gene k = 1, ..., p, compute

$$\hat{\theta}_k = argmax\{O(\theta_k) - \rho(\theta_k)\},$$
 (5)

where $\rho(\cdot)$ is the penalty function. Interactions (and main effects) corresponding to the nonzero components of $\theta_k^{\hat{\gamma}}$'s will be identified as associated with response. In this study, we

consider the MCP penalty [Zhang 2010], where $\rho(\theta_k) = \sum_{l=1}^{2q} \rho(\theta_{kl}; \lambda_l)$ and

 $\rho(t;\lambda) = \lambda \int_0^{|t|} (1 - \frac{x}{\lambda \gamma})_+ dx$. $\lambda > 0$ is the tuning parameter, and $\gamma > 1$ is the regularization parameter. Many other penalties can be used to replace MCP, including for example the Lasso family, bridge, SCAD, and others. Studies under simpler data and model settings suggest that MCP can outperform Lasso and several other penalties and have similar performance as bridge, SCAD, and others. As the main goal is not to compare different penalties, we focus on the MCP and will not further discuss the other penalties.

 $O(\theta_k)$ is not differentiable. Straightforwardly maximizing $O(\theta_k)$ is an NP-hard problem. A few computationally effective methods have been proposed including the tree-based method and the more recent forward selection method in Li et al. [2011]. However, the high dimensionality of genes and more importantly MCP penalization make computation in this study nontrivial. To tackle the computation problem, we adopt the approximation proposed in Ma and Huang [2005]. Specifically, $I(\theta'_k W_{ik} \ge \theta'_k W_{jk})$ in $O(\theta_k)$ is approximated with

 $S_n(\theta'_k W_{ik} - \theta'_k W_{jk})$, where $S_n(u) = \frac{1}{1 + \exp(-u/\sigma_n)}$ is the sigmoid function. We denote the smoothed approximation of $O(\theta_k)$ as $O_s(\theta_k)$. The smoothed counterpart of (5) is proposed as

$$\hat{\theta}_k = argmax \{O_s(\theta_k) - \rho(\theta_k)\}$$
 (6)

and referred to as the smoothed penalized rank estimate (SPRE). Performance of the approximation and hence the estimate depend on σ_n . The asymptotic behavior of σ_n has been studied in Ma and Huang [2005]. Numerical studies in Ma and Huang [2005] and followup studies show that, as long as σ_n is small, the smoothed rank estimate is not very sensitive to its value. In our numerical study, we set $\sigma_n=2/\sqrt{n}$ and find satisfactory results. In practice, one may need to experiment with a sequence of σ_n values and find one that is small enough (so that the estimate does not change significantly when it gets smaller) but not too small (so that the approximation is still stable).

Penalization is imposed. Here it serves two purposes. First, it achieves the identification of important interactions along with estimation. There is no need to further compute the significance level. Using the results in Sherman [1993], we can establish the asymptotic behaviors of θ_k . In our numerical study, we demonstrate that it is possible to compute a p-value for the rank estimate. However, it can be computationally expensive especially when the number of genes or environmental factors is large or the sample size is moderate to low (so that the asymptotic results are not sensible, and computationally expensive methods such as bootstrap have to be adopted). Second, in general, with a small to moderate sample size, penalization can lead to more stable estimates. In the proposed penalized estimation, the tuning parameter λ_l 's do not depend on k. Thus, the same degree of penalization is imposed

on all genes, leading to a fair comparison. For a gene, the first $q - 1 \lambda_l$'s correspond to the effects of clinical/environmental risk factors. Our main goal is to select important interactions and gene effects. As the clinical/environmental risk factors are usually preselected as important and have a low dimensionality, in this study, the first q - 1 effects are not subject to penalization, and we set $\lambda_l = 0$ for l = 1, ..., q - 1. In practice, when it is suspected that there may be "noisy" clinical/environmental factors, prescreening or penalization can be conducted. All interactions and main effect will be subject to the same amount of penalty, that is, $\lambda_q = ... = \lambda_{2q}$. Following Liu et al. [2013], the penalty can be revised to respect the "main effect, interaction" hierarchy. Such an extension is of less interest under the present setup and will not be pursued.

Under low-dimensional settings, Song and Ma [2010] studies penalized rank estimation. The present data settings are much more complicated, and the MCP penalty is adopted, which may outperform the Lasso penalties in Song and Ma [2010]. Liu et al. [2013] identifies important interactions using penalization. However, that study assumes specific data generating models, which are subject to mis-specification.

Computation

With fixed λ_l and γ , optimization in (6) can be solved using the coordinate descent algorithm, which proceeds as follows. For each *k*: (a) Initialize θ_k . Sensible initial values include component wise zero and the unpenalized estimate. (b) For l = 1, ..., 2q, optimize (6) with respect to θ_{kl} (the *l*th component of θ_k), with $\theta_{km}(m - l)$ fixed at its current value θ_{km} . (c) Repeat Step (b) until convergence. In our numerical study, we use the ℓ_2 -norm of the difference between two consecutive estimates less than 0.001 as the convergence criterion. Convergence is achieved for all simulated and real data, usually within 20 iterations.

Consider optimization with respect to θ_{kl} in Step (b). Denote $R(\theta_{kl})$ as the terms in (6) that involve θ_{kl} . Denote $\theta_k = (\theta_{k1}, \dots, \theta_{k,2q})$. To simplify the optimization in (6), we propose using a local linear approximation of the penalty. More specifically, we approximate $\rho(\theta_{kl})$.

 λ_l) with $\lambda_l (1 - \frac{|\hat{\theta}_{kl}|}{\lambda_l \gamma})_+ |\theta_{kl}|$. Let $\dot{O}_s(\theta_{kl}|\theta_{k,-l})$ and $\ddot{O}_s(\theta_{kl}|\theta_{k,-l})$ be the first and second partial derivatives of O_s at θ_{kl} . Here $\theta_{k,-l}$ is θ_k with the *l*th element removed. Overall, we approximate $R(\theta_{kl})$ at θ_{kl} by the following function

$$R(\theta_{kl}) = O_s(\tilde{\theta}_k) + \dot{O}_s(\tilde{\theta}_{kl}|\tilde{\theta}_{k,-l})(\theta_{kl} - \tilde{\theta}_{kl}) + \frac{\ddot{O}_s(\tilde{\theta}_{kl}|\tilde{\theta}_{k,-l})}{2}(\theta_{kl} - \tilde{\theta}_{kl})^2 - w_{kl}|\theta_{kl}|.$$
(7)

Below we show the derivatives of O_s for right censored survival data. Results for other types

of data can be derived in a very similar manner. Let $u_{ij}^k = \frac{\theta'_k W_{ik} - \theta'_k W_{jk}}{\sigma_n}$ and

$$v_{ij}^{kl} = \frac{W_{ik}^i - W_{jk}^i}{\sigma_n}$$
. Simple calculation shows that for each θ_{kl} $(l = 1, ..., 2q)$

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 $\dot{O}_{s}(\theta_{kl}|\theta_{k,-l}) = \frac{1}{n(n-1)} \sum_{i \neq j} \Delta_{j} I(Y_{i} \ge Y_{j}) \frac{\exp\left(-u_{ij}^{k}\right)}{\left[1 + \exp\left(-u_{ij}^{k}\right)\right]^{2}} v_{ij}^{kl}$

and

$$\ddot{O}_{s}(\theta_{kl}|\theta_{k,-l}) = -\frac{1}{n(n-1)} \sum_{i \neq j} \Delta_{j} I(Y_{i} \ge Y_{j}) \frac{\exp\left(-u_{ij}^{k}\right) - \exp\left(-2u_{ij}^{k}\right)}{\left[1 + \exp\left(-u_{ij}^{k}\right)\right]^{3}} (v_{ij}^{kl})^{2}.$$

Since $\frac{\exp\left(-u_{ij}^{k}\right) - \exp\left(-2u_{ij}^{k}\right)}{\left[1 + \exp\left(-u_{ij}^{k}\right)\right]^{3}}$ is upper-bounded by $\xi = 0.1$, maximizing $R(\theta_{kl})$ is equivalent to maximizing its minorization

$$\frac{1}{2}a_{kl}(\theta_{kl}-\tilde{\theta}_{kl})^2+\dot{O}_s(\tilde{\theta}_{kl}|\tilde{\theta}_{k,-l})(\theta_{kl}-\tilde{\theta}_{kl})-w_{kl}|\theta_{kl}|,$$

and the solution is

$$\hat{\theta}_{kl} = \frac{\operatorname{sgn}(b_{kl})}{a_{kl}} (|b_{kl}| - w_{kl})_+,$$

where
$$a_{kl} = -\frac{\xi}{n(n-1)} \sum_{i \neq j} \Delta_j I(Y_i \ge Y_j) (v_{ij}^{kl})^2$$
, $b_{kl} = a_k \theta_{kl} - \dot{O}_s(\theta_k | \theta_{k,-l})$, and $w_{kl} = \lambda_l (1 - \frac{|\tilde{\theta}_{kl}|}{\lambda_l \gamma})_+$.

In the overall objective function, O_s is continuously differentiable and regular in the sense of Tseng [2001]. The MCP penalty is separable. Thus, the above algorithm converges to a coordinate-wise maximum of O_s , which is also a stationary point.

Parameter path—Parameter path provides a way of visualizing the estimates as a function of tuning. We analyze one simulated dataset with a continuous response under the linear regression model with Error 2. The number of genes is p = 1000, and the correlation structure is AR(0.8). More detailed settings are described in the next section. When the number of clinical/environmental risk factors is not too large and the sample size is not too small, as in our simulation, we recommend using the unpenalized estimates as the initial values. This type of "warm starts" allows for more stable estimates and faster convergence. In Figure 1 (Appendix), we show the parameter paths for a gene with a nonzero main effect and two important interactions. In Figure 2 (Appendix), we show those for a gene with no important main effect or interaction. The parameter paths overall look "similar" to other penalized estimates. A nonzero effect may enter the model earlier under a larger λ_l , and

more important effects (with larger coefficients) may enter earlier. The intuition is that many penalization methods including the proposed one are closely related to thresholding. This can be partly seen from the above coordinate descent algorithm. With a high level of thresholding (large penalty), important effects may enter the model, while less important ones may not. Thus by examining the parameter paths (whether an effect, main or interaction, enters early or late), we may draw conclusions on the relative importance of effects. More definitive conclusions on performance of the proposed method will be drawn based on larger scale simulations in the next section.

Tuning parameter—The MCP penalty involves two tunings, λ and γ . For γ , Zhang [2010] and Breheny and Huang [2011] suggest examining a small number of values (in particular including 1.8, 3, 6, and 10) or fixing its value. In our numerical study, we find that the performance is not very sensitive to γ and set $\gamma = 6$. In practice, one may need to experiment with multiple γ values, examine the sensitivity of estimate, and select using data-dependent methods. The value of λ plays a more important role: with a smaller λ , more interactions will be identified. Following Tibshirani [2009] and others, it is possible to determine the value of λ data-dependently, using for example cross validation. In Figure 1 and 2 (Appendix), we also plot the λ values selected using 2-fold cross validation. However, it should be noted that with high-dimensional data, the selection of optimal tuning is still an ongoing effort especially in marginal analysis, and it can be more sensible and "safer" to examine performance under a sequence of tunings as opposed to one fixed value [Meinshausen and Buhlmann 2010; Liu 2013b]. In our simulation and data analysis, we start with the smallest λ value under which all gene effects (main and interaction) are zero. We then gradually reduce λ . At each λ value, we examine the set of identified interactions. In simulation, as the set of true positives is known, we are able to compute the true/false positive rates. With a sequence of λ values, as a comprehensive measure, we are able to compute the AUC (area under curve) under the ROC (receiver operating characteristics) framework for binary data and time-integrated AUC for censored survival data. The same discussions and evaluation approach are applicable to penalty functions other than MCP. In addition, for the alternative methods described in the next section (and many of the existing $G \times E$ interaction analysis methods), we can vary the cutoffs and compute (time-integrated) AUC in a similar manner.

Simulation

As specific examples, we consider continuous and right censored survival responses. In particular, we consider the following three scenarios: (a) a continuous response under a linear regression model; (b) a survival response under the accelerated failure time (AFT)

model, where $g_k(Y) = \log(Y) = \theta'_k W_k + \varepsilon$; and (c) a survival response under the transformation model with the transformation function other than log. Here

 $g_k(Y) = \theta'_k W_k + \varepsilon$, with $g(t) = t^3$, t^5 , t, and $t^{1/3}$. For all three models, we consider three different error distributions: (a) Error 1 has a standard normal distribution. (b) Error 2 has a 0.7N(0, 1) + 0.3Cauchy(0, 1) distribution. That is, it is partly contaminated. And (c) Error 3 has a t-distribution with one degree of freedom. This distribution has a long tail. For each subject, we simulate five normally distributed clinical and environmental risk factors. The

expressions of p = 500 or 1000 genes are simulated from a multivariate normal distribution. Two correlation structures are considered here. The first is the auto-regressive correlation where the correlation between genes j and k is $\rho_{jk} = \rho^{|j-k|}$ with $\rho = 0.2$ and 0.8, corresponding to weak and strong correlations, respectively. We also consider two banded correlation scenarios. Under the first scenario, $\rho_{jk} = 0.33$ if |j - k| = 1, and $\rho_{jk} = 0$ otherwise. Under the second scenario, $\rho_{jk} = 0.6$ if |j - k| = 1, $\rho_{jk} = 0.33$ if |j - k| = 2, and $\rho_{jk} = 0$ otherwise. There are a total of 2500 or 5000 G×E interactions. Seven main effects, three from environmental risk factors and four from genes, and twenty interactions have nonzero coefficients and are associated with the response. The coefficient of the first main effect is set as 1, and the rest nonzero coefficients are generated from Unif[0.2, 0.8]. For the two survival scenarios, we generate the censoring times independently. The censoring distributions are adjusted so that the censoring rates are about 20%.

We analyze the simulated data using the proposed SPRE. In addition, we also conduct benchmark analyses. In the first set of analysis, we take the commonly-adopted model-based goodness-of-fit measures and employ the same penalization as with SPRE. Specifically, for the continuous response, we consider penalized least squares (PeLS, Table 1). For the survival response under the AFT model, we consider penalized AFT (PeAFT, Table 2). For more details on penalized estimation under the AFT model, we refer to Huang and Ma [2010]. For the survival response under the transformation model, we consider penalized Cox (PeCOX, Table 3), where the goodness-of-fit measure is the log partial likelihood function. In the second set of analysis, we adopt the rank estimation. The marginal p-value, which is the most popular ranking statistic, is used to rank and select important interactions. This approach is referred to as "Sig" (for significance) in Table 1–3.

Simulation first suggests that the proposed method is computationally feasible. Under fixed tunings, for one gene, the analysis takes 0.46 seconds on a regular desktop computer. For the continuous response (Table 1), when the errors have a normal distribution, the significance based method has the best performance. For example when p = 500 under the AR(0.2) correlation structure, the AUC values are 0.911 (PeLS), 0.928 (Sig) and 0.826 (SPRE). This result is as expected. Using classic likelihood theories, one can prove that the least squares estimation with normal error and so the significance based method are the most efficient. The PeLS is slightly worse because of the shrinkage caused by penalization. The proposed method is robust. As with other robust methods, it can be less efficient. The loss of efficiency can be clearly seen from Table 1 under Error 1. However, when the errors are contaminated or have a long tail, the proposed method can significantly outperform the alternatives. For example when p = 500 under the second banded correlation structure and Error 3, the AUC values are 0.632 (PeLS), 0.650 (Sig), and 0.793 (SPRE). Under the second simulation scenario, although the model has a similar form as the linear regression model for continuous data, right censoring leads to significantly different estimation and inference procedures [Huang and Ma 2010]. Observations made in Table 2 are similar to those in Table 1. In Table 3, we observe that SPRE has the largest AUC under all simulation scenarios. For example with p = 500, $g(t) = t^3$, and Error 1, the AUC values are 0.647 (PeCOX), 0.566 (Sig), and 0.721 (SPRE), respectively. In addition, PeCOX outperforms Sig, which may also justify the use of penalization.

The proposed method avoids estimating g_k 's. We conduct a small scale simulation and compare the proposed method against the following alternative. For gene k, g_k is estimated using the nonparametric method for single index models provided in R package np. Specifically, the functions *npindexbw* and *npindex* are used. The same penalty as with the proposed method is imposed for selection. We consider the scenario with a continuous response under the transformation model and Error 1. The nonparametric method is computationally expensive. For each gene, its computer time is about 7.72 times that of the proposed method. To reduce computational burden, we consider only five environmental factors and ten genes. Summary statistics in Table 5 (Appendix) clearly shows the superiority of the proposed method.

Analysis of a Lung Cancer Prognosis Study

Lung cancer is the leading causes of cancer death for both men and women in the United States. Gene profiling studies have been extensively conducted, searching for markers associated with prognosis. The progression of lung cancer is a complex process, involving the contributions of multiple clinical and environmental risk factors, genetic mutations and defects, and their interactions. Individual lung cancer profiling studies have small sample sizes and may lead to unreliable results. To increase sample size, following Xie et al. [2011], we collect and analyze three independent datasets. The UM (University of Michigan Cancer Center) dataset has a total of 175 patients, among whom 102 died during follow-up. The median follow-up was 53 months. The HLM (Moffitt Cancer Center) dataset had a total of 79 patients, among whom 60 died during follow-up. The median follow-up was 39 months. The CAN/DF (Dana-Farber Cancer Institute) dataset has a total of 82 patients, among whom 35 died during follow-up. The median follow-up was 51 months. We refer to Xie et al. [2011] and references therein for more detailed information.

A total of 22,283 probe sets were profiled in all three datasets. Gene expression normalization is first conducted for each dataset separately. To improve comparability, across-datasets normalization is also conducted. To reduce computational cost, and as genes with higher variations are often of more interest, the probe sets are ranked using their variations, and the top 2,500 are screened out for downstream analysis. For the expression of each gene in each dataset, the mean is normalized to zero, and the variance is normalized to one. The following demographic and clinical factors are analyzed: age (centered to mean zero and rescaled to variance one), gender (male is used as reference), smoke (current/ former or never; never is used as reference), chemo (chemotherapy treatment), and stage. They include the most commonly measured prognostic factors.

We apply the proposed SPRE and provide the results in Table 4. For each gene, the regression coefficient of age's main effect is set as -1.0 (we have experimented with 1 and found that -1 leads to an overall larger objective function). As described above, with the proposed method, the number of identified important main effects and interactions depends on the tuning parameter. The results in Table 4 correspond to one specific tuning value which leads to 30 identified genetic effects (main and interaction combined). Results under other tunings are available from the authors.

Most of the identified interactions are between genes and smoking status. There are also a few interactions with age and stage. There is one interaction with gender, but no interaction with chemotherapy. In our literature search, we find very few lung cancer studies on $G \times E$ interactions. Thus we cannot definitively say whether the identified interactions are meaningful or not. However there are more results on the functionalities of genes, which may provide some insights into the identified effects. The most interesting finding is perhaps SFRP1 (Secreted frizzled related protein 1). SFRP1 is an antagonist of the transmembrane frizzled receptor, a component of the Wnt signaling pathway, and has been suggested to be a candidate tumor suppressor in several human malignancies including lung cancer. Fukui et al. [2005] demonstrates that the SFRP1 gene is frequently downregulated by promoter hypermethylation and suppresses tumor growth activity of lung cancer cells. Other interesting findings include genes that play important roles in the regulation of cell growth, differentiation, and migration. Gene IGFBP1 encodes a protein which is a member of the insulin-like growth factor binding protein family, and binds both insulin-like growth factors and circulates in the plasma, which promotes cell migration. Its important role in lung cancer has been suggested by Chang et al. [2002] and Lee et al. [2002]. Gene AHSG has several important functionalities, including endocytosis, brain development, and formation of bone tissue. It encodes the serum glycoprotein AHSG blocks, whose levels are significantly altered in serum from patients with squamous cell carcinoma of the lung [Dowling et al. 2012]. Swallow et al. [2004] also suggests that AHSG may play an important role in tumor progression. AGR2 is a proto-oncogene that may play a role in cell migration, cell differentiation, and cell growth. Pizzi et al. [2012] shows its overexpression in lung adenocarcinoma. IL 8 acts as a promoter of human non-small cell lung cancer (NSCLC) tumor growth through its angiogenic properties [Kunkel et al. 1991]. We have also identified several genes that have been implicated in the development and progression of several other cancers. For example, it has been reported that low ANXA10 expression is associated with disease aggressiveness in bladder cancer [Munksgaard et al. 2011]. The protein encodes by CXCL5 belongs to the CXC chemokine family, which plays a paramount role in tumor progression [Raman et al. 2007; Speetjens et al. 2008]. FAM134B has been associated with Wilms tumor. Considering the interconnections among different cancer types, it may be of interest to study their functions in lung cancer.

We have also applied the alternative methods. Results using PeAFT (Table 6), PeCOX (Table 7), and Sig (Table 8) are provided in Appendix. For these three methods, the number and set of identified interactions also depend on tunings. We only provide results for a specific tuning value, and more extensive results are available from the authors. We can see that different methods identify significantly different sets of main effects and interactions. We have also examined "longer lists" of identified effects and reached the same conclusion. With our limited knowledge on the genetic effects, it is hard to say whether the SPRE identified interactions are more sensible. The simulation results and biological implications described above may partly support SPRE.

Discussion

In the literature, there are a large number of statistical methods for detecting geneenvironment interactions. However, most of them assume specific models and rely on the

notion of significance level for ranking the relative importance of effects. Advancing from the existing studies, we adopt a robust approach which does not assume a specific model form. The proposed modeling framework and rank estimation include quite a few commonly encountered data and model settings as special cases. To facilitate computation, a smooth approximation is introduced. Different from the existing methods, the proposed SPRE uses penalization as a way of estimation and, more importantly, for identifying important interactions. The proposed method has roots in the MRC estimation and penalized marker selection. However, this study is among the first to apply such techniques in high-throughput $G \times E$ interaction studies. In simulation, we show that under certain scenarios, the proposed method can significance-level based method. In the analysis of a lung cancer prognosis study, the proposed method identifies interactions (and main effects) different from the alternatives. Some of the identified genes have been shown to have important implications.

The proposed method has limitations. Computationally, it is more expensive than the existing methods. This is the price paid for robustness and penalization. However, as the analysis can be conducted in a highly parallel manner, the computational cost is in fact acceptable. The significance level based methods can be coupled with multiple comparison adjustment methods such as the FDR and Bonferroni. With the proposed method, the notion of significance is not directly relevant. Most of the existing penalization methods examine results under a specific tuning parameter value. In principle, we can follow Tibshirani [2009] and use, for example, cross validation to determine such a tuning value, as shown in Figure 1 and 2. However, we believe it is more sensible to examine a sequence of tuning parameter values. Under such an approach, effects entering earlier (under larger tunings) are deemed as more important. In simulation, we have examined a total of 72 different settings. The proposed method is potentially applicable to a large number of data and model settings, but it is impossible to examine all of them in one study. In Table 1 under Error 1, the proposed SPRE is less competitive. This is not surprising. Under such a simulation setting, we can prove that the model-based method is more efficient than the robust method. Under other settings, the superiority of the proposed method is obvious. In data analysis, the proposed method identifies a different set of important interactions. More bioinformatics and biological analyses are needed to fully comprehend the identified interactions.

Supplementary Material

Refer to Web version on PubMed Central for supplementary material.

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Figure 1.

Parameter paths for a gene *with* important interactions. The vertical line corresponds to λ selected using 2-fold cross validation.

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Figure 2.

Parameter paths for a gene *without* important interaction. The vertical line corresponds to λ selected using 2-fold cross validation.

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Simulation for a continuous response under the linear regression model. PeLS: penalized least squares. Sig: significance based analysis. In each cell, AUC based on 100 replicates (mean in the first row, standard deviation in the second row).

d			AR(0.2)			AR(0.8)			Band1			Band2	
		PeLS	Sig	SPRE	PeLS	Sig	SPRE	PeLS	Sig	SPRE	PeLS	Sig	SPRE
	Error 1	0.911	0.928	0.826	0.945	0.995	0.954	0.917	0.936	0.838	0.928	0.962	0.885
		0.034	0.029	0.056	0.046	0.004	0.036	0.034	0.027	0.056	0.038	0.024	0.048
002	Error 2	0.739	0.755	0.791	0.806	0.889	0.936	0.750	0.769	0.800	0.778	0.824	0.849
nnc		0.126	0.126	0.058	0.127	0.137	0.055	0.127	0.133	0.060	0.124	0.135	0.053
	Error 3	0.595	0.614	0.710	0.613	0.742	0.897	0.601	0.624	0.722	0.632	0.650	0.793
		0.089	0.077	0.067	0.107	0.147	0.076	0.098	0.088	0.064	0.114	0.127	0.074
	Error 1	0.929	0.942	0.815	0.945	0.998	0.956	0.934	0.950	0.825	0.934	0.971	0.876
		0.029	0.027	0.037	0.047	0.002	0.034	0.029	0.024	0.034	0.037	0.015	0.035
0001	Error 2	0.659	0.667	0.776	0.751	0.798	0.949	0.667	0.679	0.796	0.707	0.731	0.850
		0.128	0.130	0.045	0.146	0.175	0.029	0.130	0.137	0.048	0.132	0.153	0.042
	Error 3	0.601	0.616	0.691	0.683	0.763	0.869	0.601	0.612	0.706	0.644	0.673	0.767
		0.073	0.055	0.067	0.132	0.147	0.074	0.074	0.075	0.061	0.095	0.105	0.070

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Table 2

Simulation for a right censored survival response under the AFT model. PeAFT: penalized AFT. Sig: significance based analysis. In each cell, timeintegrated AUC based on 100 replicates (mean in the first row, standard deviation in the second row).

d		7	AR(0.2)		Ŧ	AR(0.8)			Band1			Band2	
		PeAFT	Sig	SPRE	PeAFT	Sig	SPRE	PeAFT	Sig	SPRE	PeAFT	Sig	SPRE
	Error 1	0.736	0.818	0.768	0.834	0.976	0.898	0.739	0.816	0.775	0.739	0.867	0.820
		0.064	0.047	0.050	0.067	0.020	0.065	0.060	0.051	0.065	0.081	0.061	0.053
	Error 2	0.613	0.668	0.732	0.716	0.861	0.881	0.635	0.689	0.741	0.658	0.739	0.799
000		0.107	0.099	0.056	0.156	0.151	0.064	0.115	0.120	0.053	0.122	0.138	0.067
	Error 3	0.531	0.575	0.676	0.602	0.703	0.824	0.539	0.586	0.705	0.565	0.609	0.741
		0.077	0.080	0.050	0.114	0.143	060.0	0.080	0.057	0.064	0.093	0.106	0.098
	Error 1	0.732	0.800	0.770	0.816	0.978	0.898	0.753	0.822	0.786	0.788	0.896	0.810
		0.060	0.057	0.055	0.080	0.029	0.086	0.075	0.060	0.045	0.070	0.043	0.063
000	Error 2	0.651	0.721	0.745	0.715	0.875	0.889	0.653	0.736	0.766	0.673	0.778	0.843
0001		0.096	0.088	0.056	0.119	0.150	0.072	0.089	0.094	0.066	0.111	0.130	0.049
	Error 3	0.543	0.555	0.707	0.616	0.735	0.856	0.542	0.582	0.727	0.579	0.640	0.776
		0.064	0.081	0.056	0.084	0.139	0.070	0.068	0.072	0.055	0.058	0.084	0.084

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Table 3

Simulation for a right censored survival response under the transformation model. PeCOX: penalized Cox. Sig: significance based analysis. In each cell, time-integrated AUC based on 100 replicates (mean in the first row, standard deviation in the second row).

d			r ³			ŀz			t			t ^{1/3}	
		PeCOX	Sig	SPRE	PeCOX	Sig	SPRE	PeCOX	Sig	SPRE	PeCOX	Sig	SPRE
	Error 1	0.647	0.566	0.721	0.652	0.571	0.730	0.642	0.565	0.717	0.652	0.570	0.721
		0.048	0.052	0.077	0.059	0.058	0.076	0.043	0.056	0.076	0.054	0.055	0.076
2002	Error 2	0.594	0.556	0.742	0.597	0.550	0.747	0.586	0.536	0.748	0.572	0.548	0.743
000		0.062	0.041	0.061	0.056	0.046	0.055	0.059	0.051	0.060	0.056	0.044	0.060
	Error 3	0.548	0.544	0.713	0.548	0.542	0.715	0.544	0.547	0.716	0.545	0.552	0.719
		0.050	0.044	0.074	0.052	0.048	0.070	0.052	0.051	0.071	0.051	0.051	0.071
	Error 1	0.662	0.580	0.740	0.666	0.571	0.746	0.647	0.582	0.739	0.654	0.576	0.738
		0.059	0.048	0.065	0.063	0.058	0.063	0.057	0.049	0.064	0.049	0.043	0.065
0001	Error 2	0.575	0.552	0.733	0.574	0.548	0.735	0.578	0.548	0.728	0.581	0.564	0.737
10001		0.070	0.044	0.061	0.075	0.045	0.058	0.074	0.051	0.063	0.078	0.044	0.063
	Error 3	0.540	0.519	0.677	0.540	0.513	0.675	0.536	0.517	0.676	0.529	0.520	0.679
		0.061	0.037	0.083	0.059	0.039	0.083	0.061	0.040	0.086	0.053	0.038	0.089

Table 4

Analysis of the lung cancer data using SPRE: identified main effects and interactions.

			main e	ffects				'n	nteractions		
Gene name	age	gender	smoke	chemo	stage	gene	age	gender	smoke	chemo	stage
XIST	-1.00	-1.21	-0.56	-0.29	-3.89	2.43					
ALB	-1.00	0.60	0.05	-0.28	-3.41	3.57	2.49				
APOA2	-1.00	0.47	0.01	-0.36	-3.11	4.02					
ANXA10	-1.00	0.32	0.16	-0.49	-3.70	-2.93					-2.99
AHSG	-1.00	0.54	0.46	-0.51	-3.27	2.46	3.14				
EIFIAY	-1.00	2.33	2.46	-0.35	-2.34	3.45			2.53		
CXCL5	-1.00	0.52	2.25	-0.13	-3.56				3.51		
TF	-1.00	0.31	-0.24	-0.62	-3.33						-2.58
AGR2	-1.00	1.30	-0.71	-0.62	-3.09				3.08		
1128	-1.00	0.54	0.83	-0.35	-3.01				2.42		
HBG1	-1.00	1.06	-0.07	-0.30	-2.51				-2.91		
CXCL5	-1.00	0.66	1.06	-0.35	-3.46				3.30		
CALBI	-1.00	0.31	0.23	-0.30	-2.73		-4.09				
IGFBP1	-1.00	0.27	-0.11	-0.34	-3.18			-2.60			
MGP	-1.00	0.93	1.61	-0.32	-2.65				-2.72		
KDM5D	-1.00	-0.42	3.24	-1.00	-3.75				2.87		
CALBI	-1.00	0.79	0.44	-0.39	-3.45				3.63		-2.63
SLC6A10P	-1.00	0.65	0.42	-0.21	-2.58		2.60				
FAM134B	-1.00	1.14	0.97	-0.86	-4.29				2.57		
ZICI	-1.00	0.85	1.36	-0.42	-2.92				2.95		
FOXGI	-1.00	0.35	0.05	-0.46	-3.02						-2.58
CEL	-1.00	0.55	-0.15	0.01	-3.31						-2.87
FABPI	-1.00	0.68	0.47	-0.34	-2.14		2.84				
SFRP1	-1.00	0.74	1.71	-1.12	-4.25				5.50		
FOSLI	-1.00	0.75	1.41	-0.28	-2.44				2.45		