Breast volumetric analysis for aesthetic planning in breast reconstruction: a literature review of techniques

Michael P. Chae^{1,2*}, Warren Matthew Rozen^{1,2*}, Robert T. Spychal^{2*}, David J. Hunter-Smith^{1,2*}

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Correspondence to: Michael P. Chae, MBBS, BMedSc. Department of Plastic and Reconstructive Surgery, Frankston Hospital, Peninsula Health, 2 Hastings Road, Frankston, Victoria 3199, Australia. Email: mpc25@me.com.

Background: Accurate volumetric analysis is an essential component of preoperative planning in both reconstructive and aesthetic breast procedures towards achieving symmetrization and patient-satisfactory outcome. Numerous comparative studies and reviews of individual techniques have been reported. However, a unifying review of all techniques comparing their accuracy, reliability, and practicality has been lacking.

Methods: A review of the published English literature dating from 1950 to 2015 using databases, such as PubMed, Medline, Web of Science, and EMBASE, was undertaken.

Results: Since Bouman's first description of water displacement method, a range of volumetric assessment techniques have been described: thermoplastic casting, direct anthropomorphic measurement, two-dimensional (2D) imaging, and computed tomography (CT)/magnetic resonance imaging (MRI) scans. However, most have been unreliable, difficult to execute and demonstrate limited practicability. Introduction of 3D surface imaging has revolutionized the field due to its ease of use, fast speed, accuracy, and reliability. However, its widespread use has been limited by its high cost and lack of high level of evidence. Recent developments have unveiled the first web-based 3D surface imaging program, 4D imaging, and 3D printing. **Conclusions:** Despite its importance, an accurate, reliable, and simple breast volumetric analysis tool has been elusive until the introduction of 3D surface imaging technology. However, its high cost has limited its wide usage. Novel adjunct technologies, such as web-based 3D surface imaging program, 4D imaging, and 3D printing, appear promising.

Keywords: Breast; volumetric analysis; water displacement; thermoplastic casting; anthropomorphic; mammography; two-dimensional photography (2D photography); ultrasonography; computed tomography (CT); magnetic resonance imaging (MRI); 3D surface imaging; 4D imaging; 3D printing

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Introduction

Accurate assessment of breast volume is an essential component of preoperative planning in both reconstructive and aesthetic breast operations for achieving breast symmetrization and satisfactory outcome (1-5). Breast

shape is dynamic and highly dependent on patient position, and is also highly variable between patients; therefore any objective method of volumetric analysis requires a high degree of versatility. However, an accurate and reliable method of objective breast volumetric analysis, that is also clinically useful, has been elusive (6). Currently, most

¹Monash University Plastic and Reconstructive Surgery Group (Peninsula Clinical School), Peninsula Health, Frankston, Victoria 3199, Australia; ²Department of Surgery, Frankston Hospital, Peninsula Health, Frankston, Victoria 3199, Australia

^{*}These authors contributed equally to this work.

surgeons rely on visual estimation and two-dimensional (2D) photographs to evaluate breast volume that is irreproducible and is subject to individual clinical experiences. An ideal breast volume assessment technique should be accurate, reliable, simple, and practical.

Since the earliest report of breast volume measurement by Bouman (7), various techniques have been described of varying accuracy and reliability: water displacement technique using Archimedean principle, negative molding using thermoplastic casts, direct anthropomorphic measurements, indirect anthropomorphic measurements using 2D imaging and standard (or 3D) imaging, and 3D surface scanning technology (2,8-23). Countless number of comparative studies (6,13,18,24-37) and reviews of individual techniques (38,39) have been described. However, a unifying, updated review of all techniques comparing their accuracy, reliability and practicality has been lacking (6,24,40).

In this review, we summarize all the currently available techniques calculating breast volume and compare their accuracy, reproducibility, and practicality.

Methods

We reviewed the published English literature from 1950 to 2015 from well-established databases, such as PubMed, Medline, Web of Science, and EMBASE, using various combination of search terms, such as "breast volumetric analysis", "breast reconstruction", "breast asymmetry", "aesthetic breast surgery", "anthropomorphic", "mammography", "Archimedean", "thermoplastic", "computed tomographic angiograph", "magnetic resonance imaging (MRI)", "3D surface scanning", and "3D printing".

Results/discussion

Various techniques for breast volumetric analysis have been reported in the literature, such as Archimedean principle, thermoplastic casting, anthropomorphic measurement, 2D imaging, 3D imaging, and 3D surface imaging (*Tables 1,2*).

Archimedean principle

First reported by Bouman in 1970 (7), water displacement technique works on the Archimedean principle where the volume of water displaced equals the volume of breast submerged in water (*Table 1*) (8,61). Discouragingly, the earlier method described by Schultz *et al.* (8) are wet and

messy, require complete patient cooperation, and cannot be performed intraoperatively. To this effect, investigators have devised various forms of calibrated measurement cylinders containing liquid with a flexible diaphragm at the base (9.44,62-65). In contrast to commercial devices (63,65), Tezel and Numanoglu describe a free, easy-to-assemble device that can be assembled from equipments that can be readily found on a sterile operating table (9). In comparison to the gold standard mastectomy specimens, water displacement technique shows only ~2% difference (36). However, against mammography-derived volume estimation, it correlates less favorably (regression coefficient =0.608) (6). Major disadvantages of the Archimedean techniques are that the breast tissue lateral to pectoral fold is often missed leading to underestimation in hypertrophic breasts.

Thermoplastic casting

Thermoplastic cast method uses a fast-setting plaster or a thermoplastic sheet that is applied on to the thoracic wall and creates a negative mold of the breasts, from which volume can be measured with either sand or water (Table 1) (6,10,37). Despite its advantages, such as it can be performed with patient sitting upright and the breast shape can be visualized additionally, it has numerous failings that prevent it from being used routinely. It is a subjective technique and during the process of manually pressing the thermoplastic material to the thorax, the breast becomes compressed and its boundaries become arbitrary, making it difficult to determine the breast footprint reliably. Moreover, if the material is relatively inflexible, it cannot mold perfectly around the breast form. It incurs high material cost (\$150 per breast) and has a relatively poor accuracy (coefficient variable =6%) (10).

Anthropomorphic measurement

Anthropomorphic measurement is one of the earliest methods of calculating breast volume that is still used by physicians (*Table 1*). A volume is derived from a mathematical formula using predefined end-to-end measurements that are obtained either directly from the patient or indirectly via imaging modalities. In order to define a set of "ideal" measurement values for comparison, Penn has derived parameters from "aesthetically perfect" breasts, which, however, did not correlate well clinically (66). Smith *et al.* have studied 55 consecutive women to

Table 1 Summary of all reported breast volumetric analysis techniques except 3D surface imaging

| Tachnisusa | A | Practicality | | | | |
|------------------------------|------------------------|-------------------|-------------|-------------------|--|--|
| Techniques | Accuracy & reliability | Time | Portability | Cost/USD (Ref.) | | |
| Archimedian principle | | | | | | |
| Schultz method (8) | MD 5.6% (27) | N/A | Yes | 0 | | |
| Tezel device (9) | N/A | 10 min (41) | Yes | 1 (41) | | |
| Thermoplastic casting | | | | | | |
| Conventional (10) | MD 7.97% (33) | 25 min (41) | Yes | 20-150 (10,35) | | |
| Anthropomorphic measurement | | | | | | |
| Grossman-Roudner device (11) | MD 3.61% (11) | 3-10 min (35,41) | Yes | 1 (35) | | |
| Qiao formula (42) | MD 3.89% (42) | N/A | Yes | 0 | | |
| Brown formula (43) | MD 5.54% (33) | N/A | Yes | 0 | | |
| Sigurdson formula (44) | $R^2 = 0.89 (44)$ | N/A | Yes | 0 | | |
| BREAST-V formula (12) | $R^2 = 0.73 (12)$ | N/A | Yes | 0 | | |
| 2D Imaging | | | | | | |
| Mammogram (13) | 1.09-3.15% (45) | 20 min (41) | No | N/A | | |
| 3D Imaging | | | | | | |
| CT (15) | CC 0.782-0.873 (16) | 90 min (46) | No | 390 (47) | | |
| MRI (16) | MD 1.1% (32) | 13-30 min (35,48) | No | 280-1,400 (35,49) | | |

MD, mean deviation; N/A, not available; CT, computed tomography; CC, correlation coefficient; MRI, magnetic resonance imaging.

Table 2 Summary of all 3D surface imaging techniques

| | Accuracy | Reliability | Practicality | | | | |
|---------------------------|------------------|------------------|--------------|-----------|------------|-------------|----------------|
| Devices | | | Time | | | Portability | Coot (LISD) |
| | | | Calibration | Capture | Processing | Portability | Cost (USD) |
| Konica Minolta Vivid (17) | 0.1-0.22 mm (50) | MD 1.24% (51) | None | 0.3-2.5 s | 1-1.5 s | Yes | 20,000-100,000 |
| Axis Three (18) | <0.05 mm (38) | CC >0.8 (18) | <5 min | <2 s | <30 s | No | 30,000 |
| JRCB-D (19) | ≤0.1 mm (19) | ICC 0.9999 (52) | N/A | <5 s | N/A | Yes | N/A |
| VECTRA XT (20) | <1 mm (20) | EE <1.2% (53) | None | 3.5 ms | 80 s | No | 40,000 |
| Di3D (21) | ≤0.2 mm (54) | ICC 0.999 (21) | 5 min | 1 ms | 60 s | Yes | 30,000 |
| 3dMD Torso System (22) | <0.2 mm (55) | CR < 0.92 (36) | 45 s | 1.5 ms | <12 s | Yes | 130,000 |
| Crisalix (23) | 2-4 mm (23) | None | None | N/A | 10-15 min | Yes | 4,790 per yr |
| Di4D (56) | 0.17 mm (56) | ME 0.4 mm (57) | 5 min | 60 fps | N/A | Yes | 105,000 |
| 3dMD Dynamic (58) | ≤0.5 mm (59) | ME ≤1.32 mm (60) | 100 s | 60 fps | N/A | Yes | N/A |

MD, mean deviation; s, second; CC, correlation coefficient; ICC, interclass coefficient; N/A, not available; EE, estimate of error; ms, millisecond; CR, coefficient of reproducibility; ME, mean error; fps, frames per second; yr, year.

determine a set of "average" measurements, but they utilized soft tissue parameters that are difficult to reproduce (67). Later, Westreich *et al.* has described a standardized protocol for assessing female breasts using a measuring tape and a Grossman-Roudner device, achieving a mean measurement

deviation of only 3.61% (11). Grossman-Roudner device is an adjustable cone made out of flat envelope that changes to the size of the breast and volume can be read off a scale (68). Similarly, Palin *et al.* have used a set of graduated discs to calculate volume (40). However, the Palin discs only

work for volumes up to 450 mL and overestimates in firm breasts. More lately, Sigurdson and Kirkland have introduced an equation to predict volume based on two anthropomorphic variables that significantly correlated with the volumes measured by the water displacement method, demonstrating high accuracy (R^2 =0.89) in 101 normal female volunteers (44).

In contrast to the conventional formulae that have been standardized against water displacement techniques, Qiao et al. report a modified method where a breast is equated to a half-ellipse and the parameters of the mathematical formula of half-ellipse are applied to estimate volume (42). The authors have applied the formula to 125 Chinese women and reported a mean measurement deviation of 3.89% (42). This is reproduced by Bulstrode et al., demonstrating its high correlation with mammogramderived volume measurements (R² =0.830) (6). However, the Qiao formula is more appropriate for smaller conicalshaped breasts and its accuracy is significantly reduced in hypertrophic cylindrical breasts (44). In 2013, Longo et al. have introduced the BREAST-V formula that has been derived by correlating anthropomorphic measurements against mastectomy specimen weight in 88 women undergoing modified radical mastectomy (12). It is a relatively simple and objective method only requiring three parameters. The authors demonstrate that the formula is significantly superior to the Sigurdson formula from their own experience ($R^2 = 0.73 \text{ vs. } 0.55$). However, it remains to be validated in a larger trial.

Major advantages of direct anthropomorphic measurements are that they are relatively easy to perform, cheap, require minimal apparatus, and can be measured with patient standing up. However, since most mathematical formulae used rely on imposing certain geometrical shapes on to breasts, they ignore the wide variability and individuality in breast shapes. Furthermore, most anatomical landmarks chosen as parameters can be subjective and arbitrary. Where anatomical landmarks and submammary regions are not well-defined, accuracy can be significantly compromised (17).

Imaging

2D imaging

Various 2D imaging modalities have been utilized, from which anthropomorphic variables can be derived and estimate breast volume, mainly mammography (13), 2D photography (69,70), and 2D ultrasound (14) (*Table 1*). A

major advantage of utilizing imaging is that measurements and calculations can be conducted away from the patient, which can lead to objective assessment and standardization. Furthermore, imagings like mammograms are already being performed routinely for breast cancer screening (71). Applying parameters of the mathematical formula of cone on mammograms, volumes can be estimated to the accuracy of 1.09-3.15% (45). Unsurprisingly, due to radiation exposure, it is the least acceptable volumetric analysis tool by the patients (6) and is not indicated for utility in benign breast conditions, such as Poland syndrome. Brown et al. have utilized 2D photographs, to which they have applied the Qiao formula and calculated volume (43). However, 2D photographs fail to adequately demonstrate depth and shape, which significantly limits its accuracy (72). Similarly, an ultrasound probe has been used to scan a breast on either sagittal or transverse slices, from which an "area" of the breast is calculated and summed to yield a volume (14). However, it has a mean measurement deviation of 8% (14).

3D imaging

In contrast to other breast volumetric analysis techniques, the conventional 3D imaging modalities, such as computed tomography (CT) and MRI, enable visualization of internal structures leading to potentially more accurate estimation of the breast parenchymal volume (Table 1) (6,10,15,16,32,33,35,40,49,73-76). Furthermore, CT and MRI data are usually readily available since they are routinely performed as preoperative planning tool in autologous breast reconstructions and for diagnosis of breast cancers, respectively. Using a computer software either manually by an operator or automatically by an underlying mathematical algorithm, a region of interest encompassing the breast tissue can be segmented on individual axial slices. Given that all slices have equal thickness, the sum of all segmented volumes indicate the total parenchymal volume. Kim et al. have compared the modalities and demonstrated that MRI is more accurate than CT in determining the volume of the resected breast tissue (0.928 vs. 0.782; P=0.001) and the final autologous flap (0.959 vs. 0.873; P=0.001) (16). Moreover, MRI has a reported mean measurement deviation of only 4.3% (75). This is most likely related to the superior soft tissue resolution in MRI. Furthermore, CT scans involve radiation exposure, making them an unattractive option. In contrast, MRI does not involve radiation or require the use of intravenous contrast, and it can be performed in prone position facilitating accurate definition of the breast boundaries and its shape.

Major disadvantages of MRI are its cost (\$1,400 per scan) (35), it is time-consuming, and is contraindicated in patients with claustrophobia. Moreover, segmentation on imaging software is still mostly conducted manually, which is laborintensive, and evidences supporting commercially available automatic segmentation tools are scarce (76,77).

3D surface imaging

3D surface imaging is the latest and the most extensively studied technique of breast volumetric analysis (Table 2). It describes a technology where the light reflected off a surface is captured to build a virtual 3D model, from which both quantitative and qualitative analysis of volume and shape can be deduced. 3D surface scanning has been utilized in the automotive and aerospace industry for decades where accuracy is paramount. One of the first uses of this technology in medical application has been evaluation of facial asymmetry in orthograthic conditions (78-84). In breast evaluation, Galdino et al. have first used 3D surface scanners to quantitate parameters, such as volume and shape, to assess symmetry (2). Interestingly, a follow-up study by the same authors fail to show any clinical improvement in achieving volumetric symmetry after autologous breast reconstructions despite using 3D scanners during preoperative planning (85). However, the authors note that the approach was not standardized and the anatomical landmarks were inconsistent (85).

Early 3D surface imaging techniques utilized by clinicians have been cumbersome and unreliable, such as image-subtraction technique (86), liquid-crystal scanning (87), light-luminance scanning (88), basic laser scanning (89-91), stereolithography (92), video system (93-96), and moiré topography (31,97,98). Recent advances in optical imaging systems and software developments facilitated by growing databases of anatomical profiles, 3D surface scanning has become more accurate and reliable, and the patient protocols have become simplified (38,99,100). For clinical application, laser imaging, structured light and stereophotogrammetry 3D scanning techniques have been most commonly studied (*Table 2*).

Laser imaging technique

The latest laser imaging technology projects a certain pattern of laser (i.e., spot and stripe) to a surface, which is captured by a calibrated camera placed at a known triangulation distance from the laser source (50). Triangulation is a mathematical calculation used to derive at 3D coordinate (i.e., x, y, and z) of a point on the object surface where the laser has hit (100). In contrast to the

optical techniques, laser scanning technology can produce a more regular grid of points (50). However, it is less sensitive to edge effect, occlusion, and sharp transition in depth (50). One of the limitations of laser scanners is their inability to differentiate the posterior surface of the breasts from the chest wall and image 360 degrees. To this effect, proprietary software have been standardized to recognize breast boundaries according to the "mammometric" parameters defined by Tepper et al. (101), and subsequently accurately estimate the posterior surface (51). In addition, rotating subjects on a turntable to image 360 degrees, as seen with inanimate objects in industrial practice, is not feasible in clinical application without creating significant motion artifacts. To this effect, Tepper et al. have demonstrated that standing patients with arms by their side in anatomical position and introducing fluorescent illumination that reduces shadowing effect improve visualization (102).

Currently, numerous commercial 3D laser scanners are available, such as Cyberware Whole Body Color 3D Scanner (Cyberware, Monterey, CA, USA) (27,28). However, Konica Minolta 3D scanners (Konica Minolta Inc., Tokyo, Japan) are the most extensively investigated one in the literature (1,17,32,33,51,101-108).

(I) Konica Minolta 3D scanner

Konica Minolta Vivid 910 3D scanners contain a linear laser scanner with a reported accuracy of 0.1-0.22 mm (50) and high reproducibility (51,109) (Table 2). Kovacs et al. report that the technique most reliably measures breast volumes between 300 and 1,600 mL (51) and it has a high correlation with MRI (33). In addition, its reliability can be improved by connecting two or more scanners together reducing motion artifacts, however, multiplying costs (17). For ptotic and hypertrophic breasts, obtaining multiple views and manually merging them together on the accompanying free computer software facilitates accurate volumetric analysis (17). Major advantages of the Konica Minolta scanners are that they are simple to operate, require no calibration, have a fast capture and processing speed, and are portable (11 kg). However, its price (USD 20,000-100,000) is a significant drawback, especially where more than one device are necessary. To date, Konica Minolta scanners have been used to facilitate preoperative planning and postoperative monitoring in implant breast reconstruction (1), reduction mammoplasty (107), and breast augmentation (108).

Structured light technique

When an organized pattern of light (i.e., stripe, grid, and dots) is projected on to an object, it becomes distorted in a predictable manner. Structured light technology utilizes

a camera system calibrated to the predicted distortion of the light patterns to capture and generate a 3D surface data (99,110). Placing cameras at two separate viewpoints further eliminates pattern interference (99). Numerous noncommercial devices, such as MTV camera (Mintron, New Taipei City, Taiwan, China) (111), Daly Shape Measurement System (112), Malata Bodymap System (113), and Precision Light Imaging System (114-116), and commercial units, such as CAM3D (3D-Shape, Erlangen, Germany) (29), C3D (C3D, Beirut, Lebanon), Voxelan (Hamano Engineering, Kanagawa, Japan) (34), and Rainbow 3D Camera (Genex Technologies Inc., Kensington, MD, USA) (2), have been described. However, the most frequently studied structured light device is Axis Three scanner (Axis Three, Miami, FL, USA).

(I) Axis Three scanner

Axis Three Torso System extrapolates 3D data using colorcoded triangulation (CCTTM) technique conceived from collaboration between Axis Three and Siemens (Siemens Technology Accelerator, Munich, Germany) (Table 2). CCTTM consists of sequential firing of images from three separate cameras and has a reported accuracy of 0.05 mm. The system requires calibration (less than 5 min) every time it is physically relocated and has a relatively slow capture (2 sec) and processing speed (30 sec). Interestingly, Axis Three has developed a physics-driven tissue behavior simulation (TBS) software program using its database of real patients. Furthermore, a physician can individualize the tissue elasticity to the patient in real-time while navigating the program in a consulting room. An initial report suggests that the software quality may be compromised due to the relatively slow image acquisition speed of the hardware (100). Studying 22 patients undergoing breast augmentation, Mailey et al. demonstrate that mean difference between the simulation and the actual outcome is 12% (range, 0.4-30%), but the system still has high reproducibility (correlation coefficient of >0.8). To date, more studies are required to validate this technology.

Stereophotogrammetry

Stereophotogrammetry is an imaging method similar to the human eye physiology where a stereo pair of cameras shoots a single object from multiple angles and their points of intersections are recorded (100,117,118). 3D surface data is rendered using triangulation technique where 3D coordinates are calculated for each 2D surface point. Depending on the presence of an additional light source being projected on to the object, stereophotogrammetry technology can be classified into active, passive, and

hybrid (38).

(I) Active stereophotogrammetry

In active stereophotogrammetry, the surface information is gathered from two sources: random, unstructured light being projected on to the object and natural reflections from the innate patterns on the object's surface. The inclusion of projected light makes it easier for the software to compute triangulation and resists interference from ambient lighting. The most frequently studied commercial device using active stereophotogrammetry is JRCB-D 3D scanner (Jirui, Beijing, China) (19,52,119,120).

(i) JRCB-D scanner

JRCB-D system consists of two paired cameras that capture light illuminated by a grating projector (*Table 2*) (19). The standard protocol requires patients to stand leaning against a flat wall and their hands on the anterior superior iliac spine, also known as akimbo. The wall is also captured and analyzed to help generate the *x-y* Cartesian plane. Using ideal models from virtual breast augmentation, Liu *et al.* demonstrate that a JRCB-D scanner calculate volume to 1 mL accuracy and its analysis is reliable (interclass coefficient of 0.9999) (52). Interestingly, the same group reports that maintaining patients in the same respiratory state during image capture is also critical (119). To date, the technology has been used for preoperative assessment (19) and postoperative monitoring in breast augmentation (120).

(I) Passive stereophotogrammetry

A 3D imaging system using passive stereophotogrammetry lacks the projected light source and relies alone on the natural reflections from the innate patterns on an object's surface. As a result, a requirement for high-quality cameras is crucial to achieving adequate detail. Similarly, choosing an object to visualize that has sufficient surface textures (e.g., pores, freckles, scars, and rhytids) is essential. Furthermore, ambient lighting must be carefully controlled and identifying 3D coordinates for triangulation by the software is comparably more difficult. The most commonly used commercial passive stereophotogrammetry devices are VECTRA scanners (Canfield Scientific, Fairfield, NJ, USA) (20,53,121) and Di3D scanners (Dimensional Imaging, Glasgow, Scotland) (21,30,54,122,123).

(i) VECTRA scanner

VECTRA XT scanners are modular 3D imaging systems equipped with three stereo pods containing two color single-lens reflex (SLR) cameras each. These are capable of capturing high-resolution photos at a fast speed (3.5 milliseconds) (*Table 2*). VECTRA systems are accompanied by two types of software. Mirror® medical

imaging (Canfield Scientific, Fairfield, NJ, USA) is a well-respected patented program that simulates surgical procedures on 2D photographs. Canfield Sculptor® is the latest suite of programs that enables tissue simulation on 3D reconstructed surface images. Namely, the Breast Sculptor® software is capable of performing automatic measurements and simulates outcomes of virtual breast augmentation procedures. Using faces of normal adult subjects, de Menezes et al. report that VECTRA scanners are accurate with low mean measurement error (<1 mm) and are reliable, as demonstrated by negligible intra- and inter-observer variability (P>0.05) (20). Similarly, Rosati et al. show that using VECTRA scanners to compare measurements on virtual dental models to in vivo, the estimate of error is less than 1.2% and there are also no significant differences between repeated measurements (53). In a single-blinded study, Roostaeian et al. have compared the software simulation to the actual patient measurements after primary breast augmentation procedure and demonstrate a mean accuracy of 90.8% (26). Moreover, VECTRA scanners have been used to illustrate the "bottoming out" phenomenon after breast reduction (121). Major limitations of VECTRA systems are its high cost, relatively slow image processing speed, and lack of portability (Table 2).

(ii) Di3D scanner

Di3D scanners utilize four high-quality digital SLR (DSLR) cameras, Canon EOS 550D (Canon Inc., Tokyo, Japan), to generate ultra-high quality 3D images (Table 2). The system has been used extensively in the entertainment industry by video game producers. Unique features of Di3D include the optional capability in the proprietary software that combines CT scan data with the 3D surface images, and the revolutionary 4D imaging technology by Di4D (Dimensional Imaging, Glasgow, Scotland) that captures dynamically changing anatomical structures. Earlier studies using Di3D scanners on facial models have shown that its accuracy is clinical acceptable and reliable (repeatability error of 0.0016 mm) (54,122). In a comparative study using cadaver heads, Fourie et al. demonstrate that Di3D system is as accurate and reliable as Konica Minolta laser 3D scanners and CT scans (123). Catherwood et al. are the first to report its use on breasts demonstrating that it is reliable (interclass coefficient of 0.999) and the linear measurements derived from the 3D surface data are accurate (<0.5 mm) (21). To date, no clinical application of this technology in breast surgery has been reported.

(I) Hybrid stereophotogrammetry

Hybrid stereophotogrammetry combines active and

passive stereophotogrammetry to achieve higher accuracy and image quality. Currently, the most well-studied hybrid scanner is 3dMD scanner (3dMD, Atlanta, GA, USA) (22,30,36,55,124-129).

(i) 3dMD scanner

3dMDtorso system consists of four modular units of 12 synchronized machine vision quality cameras that are of engineering and industrial standards and are superior to the regular SLR cameras (Table 2). The accompanying software has novel functions, such as the ability to track patient history and simulate soft tissue behaviors using biomechanical mass-spring method (125). Furthermore, there are optional additional software, such as 3dMDvultus that allows 3D image fusion with CT data and 3dMDdynamic that facilitates 4D imaging. 3dMDtorso system has a reported accuracy of 0.2 mm (range, 0.1-0.5 mm) (55,127) and high reliability as depicted by low intra- and inter-observer errors (1.2 and 1.0 mm, respectively) (126). Moreover, its high capture speed (1.5 milliseconds) makes it resistant to motion artifacts. In breast volumetric analysis, Losken et al. have applied 3dMD system in the preoperative work-up for skin-sparing mastectomy and demonstrate that the mean difference between the calculated and the actual volume is only ~2% and the coefficient of reproducibility is less than 0.92 (36). In addition, Henseler et al. report that the 3D imaging system is superior to the traditional water displacement technique in accuracy (P≤0.017) and reproducibility (36 vs. 62.6 units/cc) (30). To date, clinicians have utilized 3dMD scanners to demonstrate baseline breast asymmetry in 87 normal women (124) and study the compressive effect of implants on breast volume after augmentation (22). Significantly, in the latter study, the authors report no difference between the imaging-derived expected breast volume and the actual augmented volume (P=0.3483) (22). Despite its fast processing speed and mobility, a major limitation of the imaging system is related to its high cost.

Novel 3D imaging technologies

Crisalix

Crisalix (Crisalix, Lausanne, Switzerland) is the first, web-based 3D imaging technology that generates 3D surface data from three 2D photographs (front, left, and right) taken by patients on their own consumer cameras (*Table 2*). In addition, a user needs to upload the physical distance from which the photo was taken and a set of anatomical landmarks. Calculation and simulation is performed via a

cloud computing storage database based in Switzerland. The program contains two simulation engines, 3D FACE Simulator (130) and 3D MAMMO Simulator (23). The latter enables a patient to examine and choose their preferred choice of breast implant size and brands prior to attending an aesthetic plastic surgeon's consultation. In 11 cases of women planning for breast augmentation, de Heras Ciechomski *et al.* compared Crisalix program and a consumer handheld 3D laser scanner, EScan 3D (3D Digital Corp, New Town, CT, USA) (23). The program performs comparably to the laser scanner and reports a mean error of 2-4 mm (23). Despite its ease of access and a reasonable price, more robust evidence is required to validate this novel technology.

4D imaging

In contrast to static 3D imaging techniques, 4D imaging adds temporal resolution facilitating dynamic analysis of 3D structures, such as breasts (Table 2). In the literature, numerous 4D imaging systems have been used to study mainly facial animation and asymmetry (38,59,131). The most commonly investigated commercial 4D system has been Di4D (Dimensional Imaging, Glasgow, Scotland) (56,57,132) and 3dMDdynamic (3dMD, Atlanta, GA, USA) (58,60). Di4D scanners consist of two pods with two greyscales and a color digital video camera each. Main advantages of the system are that it requires only the standard video lighting and has an inbuilt optical flow tracking capability with automatized digitization of facial landmarks to track every pixel in every image being shot. However, it remains expensive and is yet to be validated in breast surgery. The latest 3dMDdynamic body system consists of 9-22 modular units of 27-66 machine vision quality cameras and an LED-based lighting system that minimizes interference and yields smooth sequential playback. In addition, the accompanying 3dMDtempus surface tracking software helps analyze skin dynamics reliably from different positions. To date, 3dMDdynamic system has been studied in facial anatomy showing high accuracy and reliability (60). However, it has yet to be applied in breast volumetric assessment.

3D printing

3D printing, also known as additive manufacturing or rapid prototyping, is the latest novel technology to aid clinicians, in combination with 3D imaging, for assessing breast volume (39,76,77,133-135). 3D printing describes a process where a computer-aided design (CAD) is

fabricated into an end product in a layer-by-layer fashion (77,133,136-140). The resultant haptic biomodel provides a 360-degree visualization and tactile feedback, enabling a superior visuospatial appreciation of the anatomy (141). In medical application, CAD files can be derived from any conventional imaging source, such as CT and MRI, or 3D surface imaging. Chae *et al.* have reported a case where routine preoperative CT scan is used to calculate the breast volume differential (*Figure 1*) and a model of the anterior chest wall is 3D printed to enhance visualization of the asymmetry (*Figure 2*) (76). As 3D printing becomes more affordable and intuitive to use by physicians, combining 3D printing and 3D imaging may revolutionize preoperative planning in breast reconstruction and the manufacturing of customized breast implants (39,77,134,142).

Recently, the concept of 4D printing has been described, in which the fourth dimension, time, is incorporated into the conventional 3D printing by utilizing 4D CT scan data (143). The technique of 4D CT has been initially developed to minimize motion artifacts and enhance the image quality of lungs for accurate assess of lung tumor volume and planning precise delivery of radiotherapy (144). Moreover, using the previously described "single volume acquisition" scanning method, overexposure to radiation is prevented and the overall dose is reduced to 1.78 mSv, equivalent of three plain abdominal X-rays (145). In addition to respiratory medicine, 4D CT has been used in breast cancers, renal tumors, and pancreatic cancers (146-148). In plastic surgery, clinicians have used 4D CT mainly to study perforator vascular dynamics (149-151). In 2015, Chae et al. have used 4D CT for 4D printing the bones of the thumb ray to depict the translation of metacarpal bones during various thumb movements and validated their technique (143). To date, 4D printing has not been applied in breast volumetric analysis. However, studies are currently underway to investigate dynamic changes in breast volume by 3D printing breasts during movement of the arm and torso.

Conclusions

Accurate volume measurement is an integral part of preoperative planning in both reconstructive and aesthetic breast procedures. Before the introduction of 3D scanning, most previous methods have been unreliable, difficult to execute, and had limited practicability. 3D surface imaging has revolutionized the field with its ease of use, reliability, fast speed, and improving portability. However, it is not yet

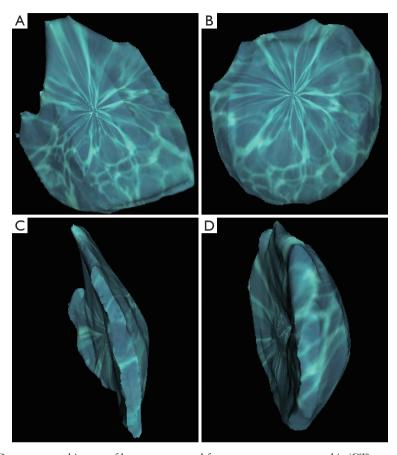


Figure 1 Volume-rendered 3D reconstructed images of breasts segmented from a computer tomographic (CT) scan using Osirix software (Pixmeo, Geneva, Switzerland), from which volume differential can be calculated. (A) Anterior view of the right breast; (B) anterior view of the left breast; (C) lateral view of the right breast; (D) lateral view of the left breast. Reproduced with permission from Chae *et al.* (76).



Figure 2 3D printed haptic model of the breasts in *Figure 1* using Cube 2 printer (3D Systems, Rock Hill, SC, USA) and polylactic acid (PLA) filaments. Reproduced with permission from Chae *et al.* (76).

being used widely due to its high cost and lack of published high level of evidence. Recently, interesting advancements and adjuncts to 3D scanning have been introduced, mainly the first web-based 3D surface imaging program, 4D imaging, and 3D printing.

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Footnote

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