

HHS Public Access

Author manuscript *Phys Med Biol.* Author manuscript; available in PMC 2017 January 21.

Published in final edited form as:

Phys Med Biol. 2016 January 21; 61(2): 923-936. doi:10.1088/0031-9155/61/2/923.

Analytical estimation of ultrasound properties, thermal diffusivity, and perfusion using magnetic resonance-guided focused ultrasound temperature data

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Abstract

For thermal modeling to play a significant role in treatment planning, monitoring, and control of magnetic resonance-guided focused ultrasound (MRgFUS) thermal therapies, accurate knowledge of ultrasound and thermal properties is essential. This study develops a new analytical solution for the temperature change observed in MRgFUS which can be used with experimental MR temperature data to provide estimates of the ultrasound initial heating rate, Gaussian beam variance, tissue thermal diffusivity, and Pennes perfusion parameter. Simulations demonstrate that this technique provides accurate and robust property estimates that are independent of the beam size, thermal diffusivity, and perfusion levels in the presence of realistic MR noise. The technique is also demonstrated in vivo using MRgFUS heating data in rabbit back muscle. Errors in property estimates are kept less than 5% by applying a third order Taylor series approximation of the perfusion term and ensuring the ratio of the fitting time (the duration of experimental data utilized for optimization) to the perfusion time constant remains less than one.

Keywords

MR thermometry; high-intensity focused ultrasound; SAR; thermal diffusivity; perfusion

1. Introduction

Thermal modeling plays an important role in ongoing efforts to improve magnetic resonance-guided focused ultrasound (MRgFUS) thermal therapies. While current treatment strategies use magnetic resonance temperature imaging (MRTI) during the therapy alone for

PACS

87.50.yt	Therapeutic applications
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- 87.19.Pp Biothermics and thermal processes in biology
- 87.80.Lg Biophysical techniques (magnetic resonance techniques)
- 87.85.jc Physical properties of biomaterials

treatment guidance, effective use of thermal modeling can improve safety and streamline and shorten the overall treatment time, a known treatment limiting factor (Wu et al 2003, Kim et al 2011, 2012). For example, thermal modeling can be used to preemptively adjust treatments to prevent violation of tissue safety constraints and mitigate risks to healthy tissues and critical structures. Thermal modeling can also be used during treatment planning to make therapies more time efficient by tailoring power and duration settings to balance healthy tissue constraints with a desire for fast target treatment without excessive overdosing (Burtnyk et al 2010, Jenne et al 2012, Salgaonkar et al 2014, Schwenke et al 2015). During the treatment, thermal models can provide information to increase the spatial and temporal resolution or volumetric coverage of temperature monitoring (Todd et al 2010, Roujol et al 2012, de Senneville et al 2013, Odéen et al 2015). In addition to improved safety monitoring, these additional data can provide model-predictive controllers with treatment feedback guiding impromptu adjustments for optimized thermal therapies (Salomir et al 2000, Vanne and Hynynen 2003, Arora et al 2006, de Bever et al 2014). In each of these cases, however, the value of thermal models and the treatment predictions they provide depends upon the accuracy of the ultrasound and thermal properties used in those models.

With the development of accurate and robust MRTI capabilities comes the opportunity to develop or improve patient-specific property estimation procedures that are less invasive and less susceptible to positional uncertainties and noise errors than previous methods. In recent years, MRTI has been used in estimation techniques for determining a variety of ultrasound (Salomir *et al* 2000, Dragonu *et al* 2009, Dillon *et al* 2012, 2013, Appanaboyina *et al* 2013, Alon *et al* 2013), thermal (Cline *et al* 1994, Salomir *et al* 2000, Cheng and Plewes 2002, Huttunen *et al* 2006, Sumi and Yanagimura 2007, Dragonu *et al* 2009, Cornelis *et al* 2011, Zhang *et al* 2013, Appanaboyina *et al* 2013, Alon *et al* 2013, Dillon *et al* 2013, 2014, Zhang *et al* 2013, 2015), and perfusion properties (Cheng and Plewes 2002, Huttunen *et al* 2009, Cornelis *et al* 2011, Appanaboyina *et al* 2013, Alon *et al* 2013, Alon *et al* 2013, Dillon *et al* 2013, Dillon *et al* 2015).

This paper introduces a new analytical temperature solution that can be used with MRgFUS temperature data to provide estimates of four parameters of interest in patient-specific modeling: the ultrasound initial heating rate (*IHR*) and Gaussian beam variance (β), the tissue thermal diffusivity (*a*), and the Pennes perfusion parameter (*w*). This is the first analytical solution for estimating all of these parameters that incorporates finite duration ultrasound heating and the effects of perfusion. The solution is made possible by replacing the exponential perfusion term in a commonly applied focused ultrasound integral equation with its Taylor series approximation. A parametric simulation study assesses how the order of the Taylor series approximation, optimization fitting parameters, random Gaussian noise, and various ultrasound and thermal properties affect the estimation results. The technique is then demonstrated with in vivo MRTI data from focused ultrasound heating in rabbit back muscle. By applying the extensive dynamic and spatial MRgFUS data to the simultaneous estimation of these important parameters, this technique has unique potential to provide accurate properties for improved thermal modeling of MRgFUS thermal therapies.

2. Theory

2.1. Heating solution

The transverse plane (figure 1) temperature change profile during focused ultrasound heating, T_{heat} (°C), as a function of radial position r (mm) from the beam axis and time t (s) since the onset of heating, assuming a Gaussian power distribution with no axial conduction, uniform thermal properties, and perfusion modeled as a scalar thermal energy sink (Pennes 1948), is expressed by (Cline *et al* 1994)

$$T_{\text{heat}}(r,t) = \int_{0}^{t} \left[\frac{IHR \cdot \exp\left(-t'/\tau_{\text{bl}}\right) \exp\left(\frac{-r^{2}/\beta}{1+t'/\tau_{\text{c}}}\right)}{1+t'/\tau_{\text{c}}} \right] dt' \quad (1)$$

where *IHR* is the initial heating rate (°C/s) and β is the Gaussian variance (mm²) of the ultrasound beam. The perfusion time constant τ_{bl} (s) is related to the Pennes perfusion parameter w (kg/m³/s), tissue density ρ (kg/m³), and specific heats of tissue c_p and blood c_{bl} (J/kg/°C) by the equation $\tau_{bl} = \rho c_p / (w c_{bl})$. The conduction time constant τ_c (s) depends upon tissue thermal diffusivity α (mm²/s) and β according to $\tau_c = \beta / (4\alpha)$.

In the past, applying (1) for analytical estimation of ultrasound and thermal properties has required eliminating the time integral through the assumption of instantaneous heating (Parker 1983, Cheng and Plewes 2002, Anand and Kaczkowski 2008, 2009, Dragonu *et al* 2009, Cornelis *et al* 2011, Zhang *et al* 2013, 2015) or simplifying the integrand for evaluation by neglecting perfusion (Cline *et al* 1994, Dillon *et al* 2012, 2013, 2014) and/or utilizing only the center-line, on-axis solution (Parker 1985, Kress and Roemer 1987, Cline *et al* 1994, Dillon *et al* 2012). To our knowledge, the full analytical solution of (1) cannot be directly evaluated.

2.2. Taylor series expansion of perfusion

However, by approximating the exponential perfusion term with a low-order Taylor series expansion, obtaining a closed-form analytical solution to (1) is possible. In this study, we evaluate the 1st, 2nd, and 3rd order Taylor series perfusion term approximations (i.e. 3rd order approximation: $\exp(-t/\tau_{bl}) \approx 1 - (t/\tau_{bl}) + (t/\tau_{bl})^2/2 - (t/\tau_{bl})^3/6$). Figure 2 shows the exponential perfusion term $\exp(-t/\tau_{bl})$ and the proposed Taylor series approximations as a function of the exponential argument t/τ_{bl} . It is clear that the higher order approximations will remain valid for longer times, with approximation errors greater than 5% occurring at $t/\tau_{bl} > 0.29$, 0.58, and 0.88 for the 1st, 2nd, and 3rd order approximations, respectively.

2.3. Taylor series-approximated analytical heating solutions

After substituting the appropriate Taylor series approximation into (1), the time integral can be evaluated for a closed-form analytical solution. These solutions are given in table 1, where Ei refers to the exponential integral function (Abramowitz and Stegun 1964). While the higher order approximations should remain valid for longer times, they also increase the complexity of the analytical solution and may increase the computation time required for identifying the parameters of interest.

2.4. Taylor series-approximated analytical cooling solutions

It may be beneficial to include the analytical cooling solution in the estimation process, especially when short ultrasound heating durations, t_h (s), limit the number of MRTI acquisitions during heating. The desired cooling solutions are obtained by the superposition of heating solutions according to (Cline *et al* 1994, Dillon *et al* 2014)

 $T_{\text{cool}}(r,t>t_{\text{h}})=T_{\text{heat}}(r,t)-T_{\text{heat}}(r,t-t_{\text{h}})$ (5)

These solutions are presented in table S1 of the supplementary material.

2.5. Estimation of ultrasound, thermal, and blood flow properties

Even though the complexity of the analytical solutions varies for the different order Taylor series approximations, the same parameters are required in each variant. With known times *t* and t_h and radial positions *r* for the MRTI data, the heating [(2), (3), or (4)] and/or cooling [(S1), (S2), or (S3)] solutions can be optimized in a least-squares minimization utilizing four parameters: *IHR*, β , τ_c , and τ_{bl} . The tissue thermal diffusivity (*a*) can be calculated from fitting parameters β and τ_c and the Pennes perfusion parameter (*w*) from τ_{bl} . While many previous methods have employed only single position data or required multi-step estimation procedures, this method can estimate each of these four important parameters using temperature data from multiple locations and times simultaneously.

3. Methods

3.1. Numerical simulations of temperature data

The ultrasound power deposition pattern was simulated as a radial Gaussian in a 2D plane perpendicular to the beam axis at a spatial resolution of 0.1 mm isotropic. As part of the parametric study, the full width at half maximum (FWHM) of the ultrasound varied between 1, 1.5, 3, and 5 mm, with a nominal value of 3 mm. The magnitude of the power deposition was adjusted to yield 10 °C temperature rise during thermal simulations. Temperatures were calculated with a 2D finite-difference time-domain solver at a spatial and temporal resolution of 0.1 mm isotropic and 0.01 s, respectively. The ultrasound heating time $t_{\rm h}$ was 24 s (approximately the duration of current clinical sonications) and cooling temperatures were simulated for an additional 24 s. Adiabatic boundary conditions were assumed at the edges of the model and the blood temperature was assumed equal to the uniform, initial tissue temperature. Tissue density was set at 1000 kg/m³ and tissue and blood specific heats were assumed equal at a value of 4000 J/kg/°C. The parameter study adjusted the tissue thermal diffusivity a between values of 0.075, 0.1, 0.125, 0.15, and 0.175 mm²/s (nominal a $= 0.125 \text{ mm}^2/\text{s}$), and the Pennes perfusion parameter w was simulated at 1, 5, 10, 20, 30, 40, and 50 kg/m³/s (nominal w = 5 kg/m³/s). To more realistically represent MRTI data, the temperatures were subsampled to 0.5 mm isotropic spatial resolution and 4 s temporal resolution. In high signal regions, MRI noise distributions can be approximated by a Gaussian function (Anand and Sahambi 2010); therefore, random Gaussian noise was added to the temperatures with a standard deviation (SD) of 0.1, 0.2, 0.5, 1, and 2 °C (nominal

noise = 0.2 °C). The study included 250 independent noise trials for each parameterized case. In a few cases, no noise was added to the data to identify errors under ideal conditions.

3.2. Optimization of parameters to estimate properties

The properties of interest were estimated as described in section 2.5 on an Intel Core 2 Duo T6500 Processor (2.10 GHz, 4.00 GB RAM) using MATLAB function fminsearchbnd. This function places constraints on each of the four fitting parameters (*IHR*: 0–10, β : 0–10, τ_c :0– 25, and $\tau_{\rm bl}$:10– ∞), but still allows for a range of values larger than would be anticipated clinically. For reference, values of τ_{bl} calculated using a tissue property database compiled from many studies are presented in table 2 (Hasgall et al 2015). Fitting parameters for each trial started from a random initial guess. The study assessed the order of the Taylor series approximation in the analytical solutions, and the 3rd order approximation was used in the nominal case. Two parameters related to the selection of data in the optimization process were also considered in the parametric study. First, the fitting time included the first 8, 16, 24, 32, 40, or 48 s of simulated data (nominal fitting time= 48 s). Second, the fitting radius (0, 2, 4, or 6 mm) incorporated all data within that distance of the beam axis (see portrayal in figure 1) in the optimization process (nominal fitting radius= 4 mm). A fitting radius of 0 mm indicates that only the data from the point at the center of the focal zone (r=0) are included, requiring use of the on-axis analytical solution provided by Kress and Roemer (1987) and its corresponding cooling solution evaluated using (5).

3.3 Experimental protocol

To demonstrate the technique in vivo, MRgFUS was performed on a female New Zealand white rabbit under IACUC approval. The rabbit was placed supine on the MRgFUS system under general anesthesia, and the back muscle was sonicated with an acoustic power of 8 W for 24 s (see figure 3 for setup). MR temperature images (Siemens 3T Trio, 3D segmented echo planar imaging (EPI), repetition time = 36 ms, echo time = 11 ms, flip angle = 20° , bandwidth = 744 Hz/pixel, EPI factor = 9, spatial resolution = $1 \times 1 \times 3$ mm, field of view = 192×114 mm, 8 slices with 25% oversampling, temporal resolution = 4.7 s) were acquired with a single-loop coil positioned under the rabbit and a two-channel surface coil placed on the rabbit's abdomen. The coil signals were weighted and combined by the inverse covariance matrix (Roemer et al 1990), data were zero-filled interpolated to 0.5 mm isotropic resolution (Todd et al 2011, Dillon et al 2013), and temperatures were calculated with the proton resonance frequency method (De Poorter et al 1995, Ishihara et al 1995) using a 2D referenceless technique with fifth order polynomial (Rieke et al 2004). Tissue properties were estimated with the 3rd order Taylor series approximation using a fitting time of 80 s and fitting radius of 10 mm in the transverse plane where the maximum temperature rise occurred. After the animal was euthanized, invasive thermal diffusivity measurements were made in the back muscle with a commercial thermal property analyzer (KD2 Pro, Decagon Devices, Pullman, WA, USA).

4. Results

Noise-free simulation results are shown in figure 4, in which the fitting time (x-axis), Taylor series approximation order (rows), and Pennes perfusion parameter *w* are varied (color

gradation). Results are normalized on the y-axis as the ratio of the estimated to true property values. These plots show that, in the absence of noise, results are most accurate for low perfusion levels and short fitting times. In addition, the 3rd order Taylor series approximation is consistently the most accurate. As perfusion and fitting times increase, property estimates using the 2nd order Taylor series approximation degrade significantly.

Figure 5 combines all the results of figure 4, and its x-axis (t_{fit} = fitting time) is nondimensionalized by the perfusion time constant τ_{bl} . For each Taylor series approximation order, results for different perfusion levels overlap. Thus, regardless of perfusion level, accurate estimates of *IHR*, β , and α (< 7% error) can be made using any of the Taylor series approximations with the condition that $t_{fit}/\tau_{bl} < 1$. However, accurate estimates of *w* require a 3rd order Taylor series approximation and that $t_{fit}/\tau_{bl} < 1$ for < 5% error or $t_{fit}/\tau_{bl} < 1.5$ for < 10% error.

As fitting times increased from 8 to 48 s, average computation times for estimating properties ranged from 42–61 s for the 1st order Taylor series approximation, 42–65 s for the 2nd order approximation, and 52–78 s for the 3rd order approximation.

Figure 6 uses box-and-whisker plots of the 250 trials at each noise level to show that increased noise in temperature data leads to more variability in property estimates, as expected. The Pennes perfusion parameter *w* is the property most sensitive to noise.

Increasing the fitting radius reduces variability in property estimates as seen in figure 7. The number of voxels included in the optimization process was 1, 45, 193, and 437 for the 0, 2, 4, and 6 mm fitting radius, respectively. The greater computational burden of using more voxels' data for a larger fitting radius results in longer computation times (rightmost plot of figure 7).

The size of the ultrasound beam has minimal effect upon property estimates, with <5% reduction in the interquartile range (IQR) for all estimates when increasing the beam FWHM from 1 to 5 mm (see supplemental data). In all cases, the median value was within 1% of the true property value.

Variation in the tissue thermal diffusivity α does not produce any observable differences in property estimates (see supplemental data). The entire IQR was contained within $\pm 2\%$, $\pm 3\%$, $\pm 3\%$, and $\pm 6\%$ of the true values for *IHR*, β , α , and w, respectively.

In figure 8, the Pennes perfusion parameter *w* is varied, and fitting times are adjusted for perfusions greater than 20 kg/m³/s to ensure that $t_{fit}/\tau_{bl} < 1$. When estimating *IHR*, β , and α , changes in perfusion do not result in observable changes in estimation. The variability of *w* estimates decreases with increasing perfusion values. When fitting times are reduced to ensure $t_{fit}/\tau_{bl} < 1$, a slight increase in the variability of results is seen.

Several locations and times from the least-squares fit (blue line) of (4) to the *in vivo* MRgFUS data (× markers) are shown in figure 9. The left plot includes data from the heating period at times t = 2, 12, and 21 s. The middle plot shows cooling temperatures at times t = 26, 35, and 78 s. The right plot shows the experimental temperature versus time

curve and fit at the location of maximum temperature change (13.9 °C). The properties estimated for these data are *IHR* = 2.3 °C/s, β = 1.5 mm², α = 0.146 mm²/s, and w = 1.3 kg/m³/s. Invasive measurements of thermal diffusivity (N=5) have a mean and standard deviation value of 0.155± 0.008 mm²/s.

5. Discussion

The primary finding of this study is that by utilizing a 3rd order Taylor series expansion of the exponential perfusion term, a closed-form analytical temperature solution is attainable that can be used with MRTI data for accurate property estimation independent of beam size, tissue thermal diffusivity and perfusion levels, provided that the data for fitting is selected such that $t_{fit}/\tau_{bl} < 1$.

5.1. Effects of solution properties

The 3rd order Taylor series approximation consistently provided the most accurate property estimates and maintained <5% error under the condition $t_{\text{fit}}/\tau_{\text{bl}}$ < 1. Somewhat surprisingly, results with the 2nd order Taylor series approximation were generally worse than those of the 1st order approximation. This most likely occurs because the 2nd order expression overpredicts perfusion when the approximation is invalid (see figure 2), thus overemphasizing its contribution in the analytical expression, while the 1st order expression underpredicts perfusion, which reduces the impact of its error in the estimation process.

5.2. Effects of fitting properties

In the noise-free case, better estimates of all properties are obtained when using a short fitting time. With the addition of noise, which is always present in reality, utilizing additional data from more fitting points is desirable. Because the analytical solution becomes invalid for long times, it is recommended that the choice of fitting time be constrained by $t_{\text{fit}}/\tau_{\text{bl}} < 1$. This constraint should only be consequential when high perfusion values are anticipated in the tissue of interest, i.e. in the kidneys (see table 2).

Using a single voxel (fitting radius = 0 mm) eliminates information about the spatial distribution of temperatures and explains why estimates of spatial parameters β and a could not be made for that case (figure 6). While estimates of *IHR* and w can be made with the center-point solution, increasing the fitting radius led to a dramatic reduction in the variability of results and demonstrates the value of the extensive data available from MRTI. However, there may be diminishing returns with increased fitting radius as temperature changes relative to the noise decrease with increasing distance from the ultrasound beam axis and computation times increase.

5.3. Effects of noise and ultrasound properties

The Pennes perfusion parameter *w* was found to be the property most sensitive to noise in the temperature data, because it has the smallest effect of all estimated properties upon the temporal and spatial distribution of temperatures. It is noteworthy that in the absence of noise, 9% of the 250 trials failed to converge to within $\pm 5\%$ of the true property values because MATLAB exits the optimization algorithm if the solution has not converged within

800 iterations. This occurs because the search space is shallow, particularly in the perfusion dimension, and errors in one parameter are compensated by offsets in other parameters, slowing convergence to the global minimum, i.e. the true property values. With more advanced optimization algorithms, it is likely that the solution would converge more quickly and these outliers would be eliminated.

Increasing the size of the ultrasound beam led to minor improvements in estimation results. While the effect of *IHR* was not assessed, a greater *IHR* will increase the magnitude of temperature changes and should lead to improved estimation results.

5.4. Effects of tissue properties

Accurate property estimates were made for all thermal diffusivity and perfusion values tested. Changes to thermal diffusivity had limited effect upon the variability of property estimates and greater perfusion values led to less variability in property estimates. However, under the constraint $t_{\text{fit}}/\tau_{\text{bl}} < 1$, the shorter fitting times required by high perfusion values led to increased variability in estimates.

5.5. Experimental demonstration of technique

The demonstration of the technique with MRTI data in rabbit back muscle shows that property estimates with *in vivo* data are possible. The initial slope of the temperature versus time curve and the width of the temperatures over time were well matched by the fitting parameters of *IHR* and β . The thermal diffusivity estimate was within 6% of the mean measured thermal diffusivity. Differences between the estimated perfusion value (1.3 kg/m³/s) and published values for muscle perfusion (0.6 kg/m³/s) are negligible when considering the minimal impact such low perfusion values have on temperature curves. Ultimately, the ability of the technique to accurately fit the heating and cooling MRTI data both spatially and temporally increases confidence that this technique has potential for property estimation in MRgFUS applications.

5.6. General observations

The accuracy of this property estimation technique depends upon the accuracy of the temperature measurements as well as the appropriateness of the analytical solution's approximations. Any magnetic field drift, systematic artifacts, or other measurement errors in the temperature data may introduce errors in property estimates. Additionally, assumptions of constant, uniform thermal, acoustic, and perfusion properties will lead to errors if such properties change dynamically or vary spatially. In heterogeneous tissues such as malignant tumors, this technique would likely provide average properties that, while not indicative of true tissue anatomy, would also be useful for thermal modeling and treatment planning purposes. However, in areas of severe property variation, such as in close proximity to large blood vessels, this technique is not likely to converge to meaningful property values. Further studies are needed to more extensively investigate the accuracy and usefulness of property estimates from applying this technique in heterogeneous tissues.

The magnitude of the noise used for much this study (SD = 0.2 °C) may be lower than that encountered clinically, particularly when hardware limitations require the use of the MRI

body coil for temperature measurements. However, the effects of greater noise in clinical data upon property estimates would likely be counteracted by the greater temperature rise induced by clinical treatments (20–40 °C instead of 10 °C). Future work will apply retrospective analysis of clinical treatment data to further validate this technique. Also, application-specific coils have the potential to greatly reduce the noise magnitude (Minalga *et al* 2013) and would make possible pretreatment clinical evaluation of these properties without requiring ablative sonications.

This new approach increases the amount of data utilized for property estimation, both temporally and spatially, when compared with previous analytical solutions. It is the first technique to simultaneously account for and estimate ultrasound properties (*IHR* and β), tissue thermal diffusivity, and the Pennes perfusion parameter. As such, it has unique potential for improving property estimation for thermal modeling applications in MRgFUS thermal therapies.

6. Conclusion

The new analytical solution has been shown to accurately and robustly estimate ultrasound, thermal, and perfusion properties independent of the ultrasound beam size, thermal diffusivity, and Pennes perfusion parameter. Where possible, longer fitting times and a larger fitting radius should be used to include more MRTI data in the optimization process and mitigate the effects of noise. To obtain estimation results with less than 5% error, it is recommended that the 3rd order Taylor series expansion solution be used with the fitting time constrained such that $t_{fit}/\tau_{bl} < 1$.

Supplementary Material

Refer to Web version on PubMed Central for supplementary material.

Acknowledgments

The authors gratefully acknowledge support from NIH grants R01 CA172787 and R01 EB013433.

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Figure 1.

Orientation of coordinate axes for property estimation with respect to the ultrasound transducer.



Figure 2.

The exponential perfusion term $\exp(-t/\tau_{bl})$ and its Taylor series approximations as a function of the argument t/τ_{bl} .



Figure 3.

Experimental setup for in vivo estimation of properties in rabbit back muscle. The ultrasound transducer sonicates vertically through a coupling water bath to focus in the center of the back muscle. The MR temperature imaging volume is identified with a dashed box.

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Figure 4.

Noise-free estimation results with variation of fitting time (x-axis), order of Taylor series approximation (rows), and perfusion levels (color gradations). Property estimates are normalized by their true values.



Figure 5.

Combination of all figure 4 results with the x-axis non-dimensionalized by the perfusion time constant τ_{bl} . When estimating *IHR*, β , and a < 7% error is possible using any of the Taylor series approximations if $t_{fit}/\tau_{bl} < 1$. When estimating *w*, a 3rd order Taylor series approximation and $t_{fit}/\tau_{bl} < 1$ results in errors <5%. See figure 4 for color legends.



Figure 6.

Property estimation as a function of noise in the temperature measurements. The Pennes perfusion parameter *w* is the property most sensitive to noise.



Figure 7.

Property estimation as a function of the fitting radius. As the fitting radius increases, variability in estimates decreases and the computation time increases.



Figure 8.

Property estimation as a function of the Pennes perfusion parameter *w*. By adjusting the fitting time such that $t_{fit}/\tau_{bl} < 1$ (*: $t_{fit}=32$ s, †: $t_{fit}=24$ s, ‡: $t_{fit}=16$ s), accurate property estimates are made regardless of perfusion levels. The variability of *w* estimates first decreases with increasing perfusion but then increases when the fitting times are reduced.



Figure 9.

Experimental MRgFUS temperature data in rabbit back muscle with optimized least-squares fit. The left plot shows temperatures and fit during heating, while the middle plot includes data during the cooling period. The right plot shows the experimental temperature versus time curve and fit at the location of maximum temperature change.

Table 1

Closed-form analytical temperature solutions during ultrasound heating.

Order of Approximation	Temperature solution	
1		$T_{\text{heat, 1}}(r, t) = \frac{IHR \cdot \tau_{c}}{\tau_{\text{bl}}} \left\{ \tau_{c} \exp\left(\frac{-r^{2}}{\beta}\right) - (t + \tau_{c}) \exp\left(\frac{-r^{2}/\beta}{1 + t/\tau_{c}}\right) + \left(\frac{r^{2}\tau_{c}}{\beta} + \tau_{c} + \tau_{\text{bl}}\right) \left[\operatorname{Ei}\left(\frac{-r^{2}}{\beta}\right) - \operatorname{Ei}\left(\frac{-r^{2}/\beta}{1 + t/\tau_{c}}\right) \right] \right\} $ (2)
2		$T_{\text{heat, 2}}(r, t) = T_{\text{heat, 1}}$ $+ \frac{IHR \cdot \tau_{c}}{\tau_{bl}^{2}} \Biggl[\Biggl[\frac{r^{2}\tau_{c}}{4\beta} + \frac{3\tau_{c}}{4} \Biggr] \tau_{c} \exp\left(\frac{-r^{2}}{\beta}\right) + \Biggl[\frac{t}{4} - \frac{r^{2}\tau_{c}}{4\beta} - \frac{3\tau_{c}}{4} \Biggr] (t + \tau_{c}) \exp\left(\frac{-r^{2}/\beta}{1 + t/\tau_{c}}\right) $ $+ \Biggl[\frac{(r^{4} + 4r^{2}\beta + 2\beta^{2})\tau_{c}^{2}}{4\beta^{2}} \Biggr] \Biggl[\operatorname{Ei}\left(\frac{-r^{2}}{\beta}\right) - \operatorname{Ei}\left(\frac{-r^{2}/\beta}{1 + t/\tau_{c}}\right) \Biggr] \Biggr] $ (3)
3		$T_{\text{heat, 3}}(r, t) = T_{\text{heat, 2}}$ $+ \frac{IHR \cdot \tau_{c}}{\tau_{bl}^{3}} \Biggl\{ \Biggl[\frac{(r^{4} + 8r^{2}\beta + 11\beta^{2})\tau_{c}^{2}}{36\beta^{2}} \Biggr] \tau_{c} \exp\left(\frac{-r^{2}}{\beta}\right)$ $- \Biggl[\frac{t^{2}}{18} - \frac{(r^{2} + 5\beta)\tau_{c}t}{36\beta} + \frac{(r^{4} + 8r^{2}\beta + 11\beta^{2})\tau_{c}^{2}}{36\beta^{2}} \Biggr] (t + \tau_{c}) \exp\left(\frac{-r^{2}/\beta}{1 + t/\tau_{c}}\right) $ $+ \Biggl\{ \frac{(r^{6} + 9r^{4}\beta + 18r^{2}\beta^{2} + 6\beta^{3})\tau_{c}^{3}}{36\beta^{3}} \Biggr] \Biggl[\operatorname{Ei}\left(\frac{-r^{2}}{\beta}\right) - \operatorname{Ei}\left(\frac{-r^{2}/\beta}{1 + t/\tau_{c}}\right) \Biggr] \Biggr\}$ (4)

Table 2

Pennes perfusion parameter w and perfusion time constants τ_{bl} for various tissues (Hasgall *et al* 2015).

Tissue	w (kg/m ³ /s)	$\tau_{bl}(s)$
Kidney	63	18
Heart Muscle	17	64
Liver	14	74
Brain	9	113
Uterus	8	147
Fat	0.6	1075
Muscle	0.6	1672
Nonperfused tissue	0	∞