

Satellite retrieval of cloud condensation nuclei concentrations by using clouds as CCN chambers

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Quantifying the aerosol/cloud-mediated radiative effect at a global scale requires simultaneous satellite retrievals of cloud condensation nuclei (CCN) concentrations and cloud base updraft velocities (W_b). Hitherto, the inability to do so has been a major cause of high uncertainty regarding anthropogenic aerosol/cloud-mediated radiative forcing. This can be addressed by the emerging capability of estimating CCN and W_b of boundary layer convective clouds from an operational polar orbiting weather satellite. Our methodology uses such clouds as an effective analog for CCN chambers. The cloud base supersaturation (S) is determined by W_b and the satellite-retrieved cloud base drop concentrations (N_{db}), which is the same as $CCN(S)$. Validation against ground-based CCN instruments at Oklahoma, at Manaus, and onboard a ship in the north-east Pacific showed a retrieval accuracy of $\pm 25\%$ to $\pm 30\%$ for individual satellite overpasses. The methodology is presently limited to boundary layer not raining convective clouds of at least 1 km depth that are not obscured by upper layer clouds, including semi-transparent cirrus. The limitation for small solar backscattering angles of $< 25^\circ$ restricts the satellite coverage to $\sim 25\%$ of the world area in a single day.

CCN concentrations | satellite remote sensing | convective clouds | cloud–aerosol interactions

The Intergovernmental Panel on Climate Change (IPCC) report (1) states that the uncertainty in aerosol/cloud interactions dominates the uncertainty about the degree of influence that human activities have on climate. Because clouds form in ascending air currents, whereas cloud droplets nucleate on aerosols that serve as cloud condensation nuclei (CCN), we need accurate measurements of both updrafts and CCN supersaturation (S) spectra before we can disentangle aerosol effects on cloud radiative forcing (CRF) from dynamical effects.

Need for Global Measurements of Cloud Base Updrafts and $CCN(S)$

Tackling the global change problems as identified by the IPCC requires that these quantities be measured on a global scale. However, satellites have not been able to measure updraft speed of the air that forms the clouds or the concentrations of aerosols that are capable of forming cloud drops, which are ingested into the clouds as they grow. Lack of such fundamental quantities has greatly hindered our capability of disentangling the effects of meteorology and anthropogenic aerosol emissions on cloud properties (2). This situation is starting to change with our recently developed methodology to retrieve updrafts at cloud base (3, 4) using the Visible/Infrared Imager Radiometer Suite (VIIRS) instrument onboard the Suomi National Polar-orbiting Partnership (NPP) satellite. This satellite is sun-synchronous, with an overpass time near 13:30 solar time.

Missing such fundamental quantities as $CCN(S)$ and cloud base updraft W_b has been preventing us from disentangling the effects of aerosols from atmospheric dynamics (i.e., meteorology). Their absence also has limited our ability to validate the hypothesized impacts of added aerosols on a large range of phenomena, including (i) maintaining full cloud cover in marine stratocumulus, thus incurring a strong cooling effect on the climate system (5); (ii) suppressing precipitation from shallow clouds (6–8); (iii) invigorating the convection in deep tropical clouds (9); (iv) enhancing cloud electrification (10, 11); (v) intensifying severe convective storms to produce more large hail and tornadoes (12); and (vi) decreasing the intensity of tropical cyclones (13). In addition to their intrinsic importance, these aerosol effects could induce radiative effects that change Earth's energy budget in a significant way (1).

Previous satellite-based studies related cloud properties mostly to the aerosol optical depth (AOD) and the Ångström coefficient (14–18). However, AOD as a proxy for CCN is a rather crude tool that is fraught with problems (19) due to a large number of reasons, including (i) aerosol swelling with high relative humidity (20, 21); (ii) uncertainty in solubility and size distribution (18); (iii) lack of a discernible optical signal from small CCN; (iv) cloud contamination (22); (v) AOD not representing aerosol concentrations near cloud base; (vi) cloud obscuration of the aerosols in the boundary layer; (vii) cloud detrainment of aerosols aloft (23, 24) yielding an increase in AOD for deeper and more extensive clouds without corresponding increase in cloud base aerosol concentrations; and (viii) lack of accurate AOD signal for the pristine boundary layer, where accuracy is most critical because clouds respond to the relative change in CCN concentrations, which can be a very small absolute change at very low absolute concentrations (25). These factors often explain a substantial part of the indicated associations of AOD with cloud top properties (18, 26), which has been erroneously ascribed to aerosol effects.

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Aerosol optical properties are useful for measuring aerosol type and particle size, which can be identified by active sensor backscatter intensity, color ratio, and polarimetry, or by passive multi-angle intensity measurements even without polarimetry. Adding polarimetry to passive, multiangle imaging should improve the precision and range of conditions under which particle size, shape, and refractive indices can be retrieved. However, this still leaves most of the issues unresolved, especially issues *iii* and *v–viii*, as listed above. To overcome this conundrum, a complete shift in approach is needed. Instead of addressing the limited information content in the optical signal of the aerosols, we extract $CCN(S)$ by using clouds as an analog for CCN counter (CCNC) chambers.

The structure of this paper is as follows: This section provides the importance and motivation for retrieving $CCN(S)$. *Methodology* provides a summary of the recent advancements which constitute a critical mass enabling satellite-only retrieval of $CCN(S)$ and applies it while describing the essence of the methodology. An extensive validation effort is described in *Validation of the Satellite-Retrieved CCN(S)*, and its results are given in *Results*, along with error calculations. The possibilities that open up with the emerging capabilities for coincident satellite retrieval of convective cloud base updrafts and $CCN(S)$ are discussed in *Applications of Satellite-Retrieved Updrafts*. Finally, the conclusions are given in *Conclusions*.

Methodology

Using Clouds as CCN Chambers. The commonly used CCNCs measure the number concentration of aerosol particles in a sample air stream (N_a), which at a given S can be activated into the same number of cloud droplets at its base (N_{db}) (27). Alternatively, retrieving N_{db} and S in clouds can provide $CCN(S)$. The peak vapor supersaturation at an adiabatic cloud base, S , is determined by $CCN(S)$ and W_b . Therefore, a good approximation of S can be calculated from the retrieved N_{db} and W_b according to

$$S = C(T_b, P_b) W_b^{3/4} N_{db}^{-1/2}, \quad [1]$$

where C is a coefficient that depends weakly on cloud base temperature (T_b) and pressure (P_b) (28). This is an analytical expression that was derived based on theoretical considerations. Recently, it has become possible to estimate N_{db} and W_b from satellite measurements, thus calculating also S . This constitutes the ability to calculate $CCN(S)$ from satellite measurements only. The following subsections describe the methodology of satellite estimation of N_{db} and W_b .

Estimation of Cloud Base Drop Concentrations. Retrieving T_b , P_b , W_b , and N_{db} became possible with the advent of the Suomi NPP satellite, which was launched in October 2011. The VIIRS onboard this satellite has a moderate spatial resolution of 750 m. The VIIRS has an Imager with a subset of five channels with double resolution of 375 m at 0.64 μm , 0.865 μm , 1.61 μm , 3.74 μm , and 11.45 μm . Although VIIRS Imager 375-m data were not designed for retrieving cloud properties, a methodology was developed for using it to retrieve cloud drop effective radius (r_e) and cloud-top temperatures (T). The retrieval of r_e was based on the methodology developed by Rosenfeld and Lensky (29) for the Advanced Very High Resolution Radiometer. It has been applied to VIIRS by Rosenfeld et al. (30). The ability to retrieve cloud properties at a resolution of 375 m is a breakthrough compared with the previous best available resolution of 1 km. This allows microphysical monitoring of cloud properties with unprecedented accuracy and makes it possible to obtain the microstructure of small clouds at the top of the boundary layer (30).

A VIIRS-retrieved $T-r_e$ relationship, which is obtained from a convective cloud ensemble within an area of $\sim 30 \times 30$ km (28), serves as the basis for retrieving T_b , P_b , and N_{db} . This satellite method is based on extensive aircraft measurements of $T-r_e$ relationships. It was demonstrated that r_e varies with altitude nearly as in an adiabatic cloud, and therefore adiabatic cloud drop number concentrations (N_{da}) can be calculated at different altitudes in the cloud using the calculated adiabatic water content LWC_a and r_{ea} , which is assumed to vary adiabatically with altitude, thus marked as r_{ea} (31). Then, N_{da} approximates N_{db} , because the cloud can be assumed to be adiabatic at its base. The retrieved r_e is assumed to be r_{ea} based on the assumption that the measured r_e is adiabatic, which is the case for clouds with extreme inhomogeneous mixing and with all cloud drops nucleated at their base.

Deviations from the extreme inhomogeneous assumption lead to a reduction of the aircraft-based calculation of N_{da} by an average factor of 1.3 with respect to the value calculated under this assumption (31). The cloud base drop concentration is approximated by the adiabatic cloud drop concentration as calculated by Eq. 2 (32),

$$N_{da} = \alpha^3 LWC_a / r_{ea}^3, \quad [2]$$

$$\alpha = 62.03 r_e / r_v, \quad [3]$$

where r_v is the cloud drop mean volume radius, as calculated by equally distributing cloud water content between the cloud droplets. We used the value of $r_e = 1.08 r_v$ (31). The adiabatic water is obtained from the VIIRS-measured T_b , which is simply the warmest cloudy pixel, based on a specially developed cloud mask (33). The LWC_a is calculated based on an adiabatic parcel that rises from cloud base at T_b and P_b to the isotherm T , where multiple pairs of T and r_{ea} are retrieved for different cloudy pixels of the same cloud cluster at different heights above cloud base. Here, P_b is obtained from the pressure at the isotherm of satellite-retrieved cloud base height (H_b), which was computed from the European Center for Medium-range Weather Forecasting reanalysis data. H_b was calculated as the difference between reanalysis surface air temperature and T_b divided by the dry adiabatic lapse rate. T_b was validated at a root-mean-square (RMS) error of 1.1 K, as shown in Fig. 1 (33). H_b and T_b were calculated for conditions of convective clouds that developed from well-mixed boundary layer at the early afternoon satellite overpass time (33), before the peak of the convective rain and the resultant cooling and moistening of the boundary layer by evaporating precipitation.

Estimation of Cloud Base Updrafts. Until now, only lidar and radar measurements of W_b were used. This is expanded here to satellite-retrieved W_b . According to Eq. 1, knowing W_b and N_{db} at cloud base yields S . Then, N_{db} is numerically identical to $CCN(S)$. Rosenfeld et al. (32) used this method to retrieve $CCN(S)$ over the Atmospheric Radiation Measurement (ARM) site of the Southern Great Plains (SGP), using N_{db} retrieved from a satellite and W_b measured by ARM's vertically pointing K_a -band radar. The W_b was calculated from all full Doppler statistics during a 2-h window centered at the satellite overpass time, where the W_b of each point in time was weighted by W_b itself, thus representing its relative contribution to building the cloud volume. More specifically, equation 5 in Rosenfeld et al. (32) (replicated as Eq. 4 here) shows that the radar or lidar updraft W was constructed from all of the N realizations W_i of single data points within the time window as follows:

$$W = \frac{\sum N_i W_i^2}{\sum N_i W_i} \Bigg|_{W_i > 0}. \quad [4]$$

According to Eq. 4, W is the cloud volume-weighted updraft. Good agreement was achieved by Rosenfeld et al. (32) between $CCN(S)$ as

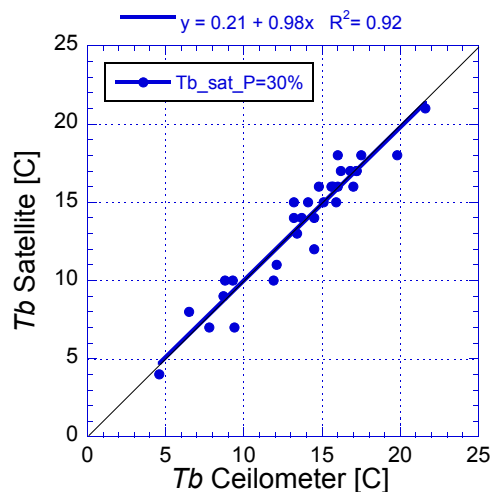


Fig. 1. The relationship between satellite-measured cloud base temperature and validation measurements by a combination of a ceilometer and soundings at the Department of Energy (DOE)/Atmospheric System Research (ASR) sites on the SGP in Oklahoma. Reproduced from ref. 33.

constructed by satellite-retrieved N_b and radar-retrieved W_b with the SGP ground base-measured $CCN(S)$, but the number of cases with useful clouds and data were rather small and served mainly to verify the methodology. The need for ground-based measurements of W_b limited severely the occasions where CCN could be retrieved to sites where cloud Doppler lidars or radars measurements are available. The present study is the first one, to our knowledge, to retrieve $CCN(S)$ from satellite estimates of both N_{db} and W_b , thus becoming potentially very widely applicable, despite some limitations in the retrievals of N_{db} and W_b .

Retrieval of CCN solely from satellite data requires W_b to be retrieved from satellite. This was done by using satellite-retrieved components of the energy that propels the convection (3). Subsequently, Zheng and Rosenfeld (4) showed that W_b can be simply calculated by

$$W_b = AH_b, \quad [5]$$

where W_b is cloud base updraft in meters per second, A is a coefficient (0.0009 s^{-1}) obtained in a previous study (4), and H_b is the cloud base height above the ground in meters, which is determined by the difference between the surface air and cloud base temperatures, as explained at the end of *Estimation of Cloud Base Drop Concentrations*. This relationship was developed based on synchronous satellite and lidar measurements from the ARM SGP site and at the ARM Mobile Facility onboard a ship on a line between Los Angeles and Honolulu [Marine ARM GPCI Investigations of Clouds (MAGIC)]. The satellite-retrieved W_b was validated against the Doppler measurements, resulting in an RMS error of $0.41 \text{ m}\cdot\text{s}^{-1}$ and a mean absolute percentage error (MAPE) of 24% and 21% by Zheng et al. (3) and Zheng and Rosenfeld (4), respectively. When forcing the relationships through zero (Eq. 5 and Fig. 2), the error becomes 27%. These results are consistent with the physical considerations of Williams and Stanfill (10). This means that the methodology is very likely to be universally applicable to boundary layer convective clouds.

Table 1 summarizes the methodology. It shows the satellite measurements, their combination with reanalysis data, and their propagation into the eventual W_b and $CCN(S)$, and the associated errors.

Validation of the Satellite-Retrieved $CCN(S)$

Cloud base S was obtained from Eq. 1, with N_{db} calculated by Eq. 2 and W_b calculated using Eq. 5. The calculated N_{db} is by definition equal to $CCN(S)$ at cloud base. To compare with surface-based measurements, the concentration is corrected for the difference between air density at cloud base and at the ground, and then validated against the $CCN(S)$ as measured by the ground-based instrument. This assumes that the thermals bring the surface air to cloud base without much change in the mixing ratio and properties of aerosol particles. This is a widely accepted assumption for vapor mixing ratio at thermally driven cloud bases in a well-mixed

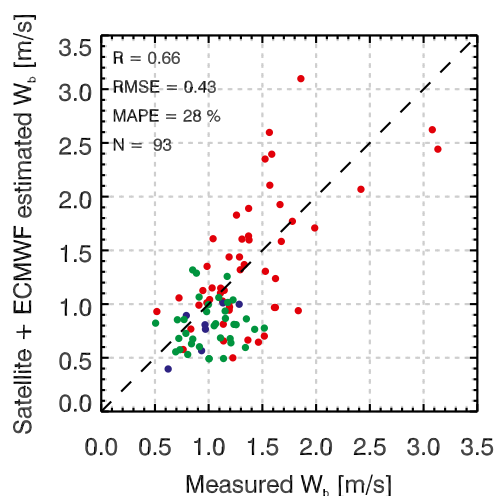


Fig. 2. Relationship between satellite-estimated $W_b = 0.0009H_b$ and directly measured W_b by Doppler lidars at the SGP (red dots), Green Ocean Amazon (GOAmazon) (green), and MAGIC (blue). After Zheng and Rosenfeld (4). The satellite-retrieved T_b was converted to height using the European Centre for Medium-Range Weather Forecasts reanalysis data. RMSE is the estimation root mean square error.

boundary layer, where the lifting condensation level is usually very similar to the actual cloud base height.

An initial comparison of the satellite-retrieved CCN to the SGP instrumental validation data (assuming no error in the instrument measured CCN) showed a slope of 0.74 for the regression line. A retrieval bias could be caused by a large number of factors, which are quantified in *Error Analysis*, but the largest potential source of error is inaccuracy in r_e . The observed 26% underestimate in CCN could have been caused by a 10% systematic overestimate in the retrieved r_e . This is quite probable, because MODIS-retrieved r_e was found to be larger by 10–15% than aircraft in situ measurements (34–36). An underestimate of satellite- versus surface-measured CCN can be also caused by a systematic decrease of CCN number concentration (N_{CCN}) between the surface and cloud base heights. This bias has to be corrected before calculating S by Eq. 1, because, otherwise, S would be overestimated. To stay on the conservative side, we applied only half of the bias correction and used here a reduction factor of 1.15 instead of 1.3, as proposed by Freud et al. (31), and applied it to all of the validation sites.

Validation cases were selected over the sites of the ARM sites of the SGP in Oklahoma, at Manacapuru near Manaus in the Amazon, and over the northeastern Pacific onboard the MAGIC ship. In addition, CCN measurements were obtained from the Amazon Tall Tower Observatory (ATTO) site 150 km to the northeast of Manaus (37). Data were obtained from the start of availability of VIIRS data in 2012 until early 2015. The case selection criteria were as follows: (i) Satellite overpass has to occur at a zenith angle between 0° and 45° to the east of the ground track, which is the sunny side of the clouds. For a specific location, these satellite views occur once or twice every 6 d. (ii) Convective clouds must occur and possess a vertical development that spans at least 6 K of cloud temperature from base to top, limiting to clouds with thickness >1 km. (iii) The clouds must not precipitate significantly (i.e., without a radar or lidar detectable rain shaft that reaches the ground). The precipitation causes cold pools that disconnect the continuity of the air between the surface and the cloud base. (iv) Cloud elements with indicated $r_e > 18 \mu\text{m}$ are rejected automatically from the analysis that is likely to rain/drizzle heavily. (v) No obscuration from high clouds is allowed. An automatic detection of semitransparent clouds screens them from the selected area for analysis. (vi) Ground-based CCN data must be available.

The availability of CCN data from the ARM program at all of its three sites was severely limited due to data quality issues. Insufficient available time for stabilization of temperatures at low S caused the CCN readings at $S \leq 0.25\%$ to be grossly underestimated or zero, and therefore they could not be used. The points with $S > 0.25\%$ were fit with a second-order polynomial that was forced through the origin, because CCN must be zero for $S = 0$. By extrapolation with this polynomial, we could extend the use of the data down to $S = 0.2\%$. Cases with cloud base $S < 0.2\%$ were rejected. The operation of the ARM CCN s was changed after August 2014 to allow sufficient time for stabilization at low S . This correction was applied to Manacapuru only by April 2015, however. These limitations did not apply to ATTO, and valid data from this site were available from May 2014 until January 2015.

The results are shown in Fig. 3. Each point in the figure represents one satellite overpass over one ground-based CCN . The CCN data from a time window of ± 1 h around the overpass are taken to include several $CCN(S)$ spectra at all measured supersaturations. Because of the much slower scanning rate of S at ATTO, a larger time window of ± 1.5 h was taken there to include at least one full spectrum of $CCN(S)$. The satellite analyzes clouds over an area of about 30×30 km around the ground measurement site, with some adjustments to incorporate the convective clouds in the vicinity. The satellite-retrieved CCN and S are compared with the instrument measurements as follows:

Table 1. Propagation of the calculations from the satellite retrievals to the resultant $CCM(S)$

Symbol	Parameter and unit	Source of calculation	Error
r_e	cloud drop effective radius, μm	satellite retrieval	8%
T	cloud surface temperature, $^{\circ}\text{C}$	satellite retrieval	0.2 $^{\circ}\text{C}$
T_b	cloud base temperature, $^{\circ}\text{C}$	satellite retrieval	1.1 $^{\circ}\text{C}$
P_b	cloud base pressure, hPa	T_b + reanalysis	15 hPa
r_v	drop mean volume radius, μm	r_e (Eq. 3)	8%
LWC_a	cloud adiabatic water, $\text{g}\cdot\text{kg}^{-1}$	$T + T_b + P_b$ (parcel)	15%
N_d	cloud base drop concentrations, cm^{-3}	$r_v(T) + LWC_a(T)$ (Eq. 2)	30%
H_b	cloud base height above surface, m	T_b + reanalysis	150 m
W_b	cloud base updraft, $\text{m}\cdot\text{s}^{-1}$	H_b (Eq. 5)	27%
S	cloud base max supersaturation, %	T_b, P_b, W_b, N_d (Eq. 1)	25% of S in percent
$N_{CCM(S)}$	CCN at cloud base, cm^{-3}	N_d, S by definition	30%

(i) A scatter plot of the individual ground-based measurements of CCN concentrations (N_{CCN}) is plotted as a function of S . (ii) A second-order polynomial curve is fit to the points. The function is forced through the origin, because zero S must correspond to zero N_{CCN} . (iii) The N_{CCN} is taken from the polynomial fit at the same S that is retrieved from satellite at cloud base. The $\pm 95\%$ confidence interval of N_{CCN} at the value of satellite-retrieved S is calculated. (iv) The satellite-retrieved N_{CCN} is the satellite-retrieved N_{db} , corrected for the air density difference between cloud base and the surface.

Results

Fig. 3 shows the relationships between the satellite retrievals of N_{CCN} and S at cloud base, and the ground-based measurements

of N_{CCN} at the same S . There are several points worth noting. (i) The figure covers a large dynamic range of S for both low and high values N_{CCN} . (ii) The value of $R^2 = 0.76$ shows that the fit explains more than 3/4 of the variability between the satellite and ground-based measurements of $CCN(S)$. (iii) There is a systematic underestimate bias of 14% in the satellite-retrieved CCN. It follows that the estimation errors decrease almost linearly with smaller N_{CCN} . (iv) The variation of the satellite with respect to the ground-based measurements is within 20–25% of the ground-based measurements. This includes the 14% bias error. (v) The SD of the fit is similar to the expected magnitude from the error sources of the satellite uncertainties in $W_b, T_b,$ and r_e .

The methodology was converted into a procedure that can be applied to any specified rectangle in the VIIRS imagery, which

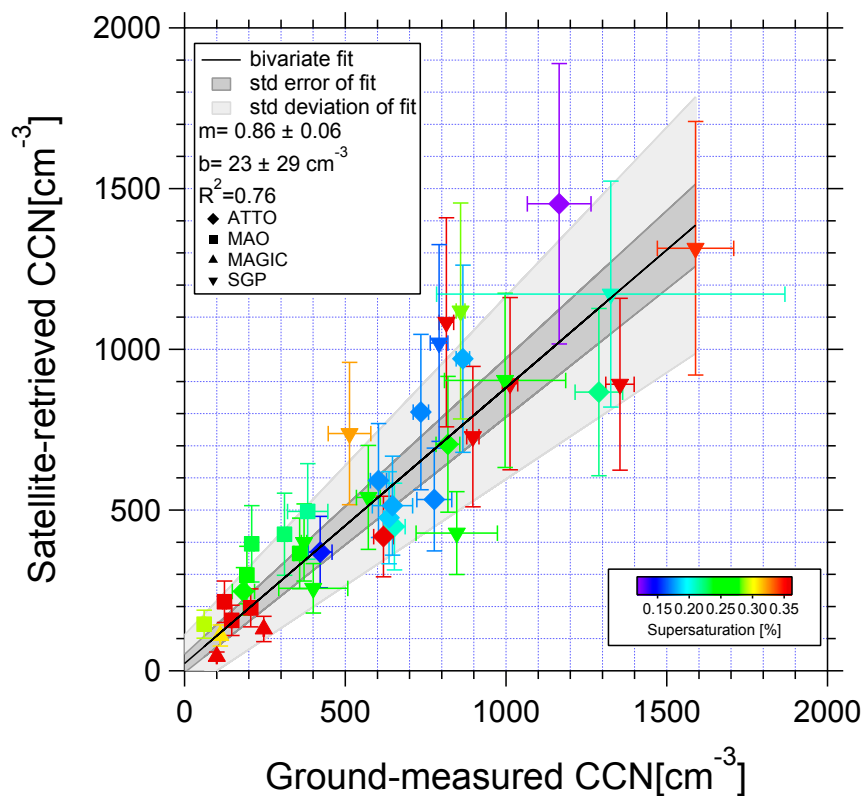


Fig. 3. The relationship between satellite-retrieved N_{CCN} and S at cloud base, and the ground-based instrument measurements of N_{CCN} at the same S . The slope and intercept of the best fit line are given in the key by m and b , respectively. The validation data are collected from the DOE/ASR sites on the SGP in Oklahoma and GOAmazon near Manaus, and over the northeast Pacific (MAGIC). In addition, data are obtained from the ATTO. The location is denoted by the marker shape, and S is shown by the color.

concentrations that affect growing clouds, the AOD approach allows only an order-of-magnitude estimate of N_{CCN} . On the other hand, combining W_b with N_{db} can provide $CCN(S)$ with an uncertainty that can be quantified and is far better than the AOD approach. Having both W_b and $CCN(S)$ will allow disentangling of the roles of these two factors in determining N_d and in the attribution of the related changes in CRE to aerosols.

Having satellite retrievals of both W_b and N_{CCN} will allow disentangling of their respective roles on determining N_d and the related precipitation-forming processes, rainfall amounts, and distribution of vertical latent heating. $CCN(S)$ ingested by deep convective clouds can be estimated by using adjacent shallower nonprecipitating convective clouds in their upwind side. Adding CCN to deep convective clouds can invigorate them and incur more extensive anvils and respective positive radiative forcing (41–43). This can be quantified observationally using long-term surface aerosol, cloud, and meteorological measurements made at a single location in the SGP (41, 42), and also using global A-Train satellite products (44). These estimates of CRF (the change in CRE due to anthropogenic causes) are associated with aerosol-induced changes in cloud properties that do not differentiate the respective roles of aerosol and dynamics or meteorology but their joint effects.

Having global coverage of $CCN(S)$ where we need them most—in conjunction with the clouds that ingest them—will provide input for regional and global simulations. The coincident retrieved cloud properties will constrain these models and provide us with realistic assessments of the CRE. The retrieved $CCN(S)$ can be used for constraining aerosol production and transport models. This will allow separating the aerosols into natural and anthropogenic components more accurately. The application of such classified $CCN(S)$ will facilitate calculating the anthropogenic aerosol-induced CRF, which will constitute a major reduction of the uncertainty in anthropogenic climate forcing. Developing methodologies for retrieving updrafts at clouds with elevated bases will further enhance these possibilities.

Conclusions

The feasibility of estimating $CCN(S)$ and W_b of boundary layer clouds from the Suomi NPP polar-orbiting operational weather satellite was demonstrated with an accuracy of $\pm 25\%$ to $\pm 30\%$, which is limited mostly by the accuracy in the retrieval of r_e . The validation was done in Oklahoma, the Amazon Basin, and the northeast Pacific Ocean. Our methodology is presently limited to boundary layer convective clouds of at least 1 km depth, which are not obscured by upper layer clouds, including semitransparent cirrus. This might limit its application in some regions of the world. Moreover, the limitation for small solar backscattering angles of $< 25^\circ$ restricts the satellite coverage to 1/4 of the satellite swath width, or a view once every 4 d, on average. On the other hand, even for a regional coverage, it would be much more valuable to study the process of aerosol–cloud interactions rather than using single-point data as provided by ground-based observations.

A major advantage of using clouds as analog for CCN chambers relative to relying on the optical signal of the aerosols themselves is the fact that the optical signals (e.g., AOD and Ångström coefficient) vanish at very small aerosol concentrations, which is exactly where the relative changes in CCN concentrations matter most, or, in other words, where very small absolute changes in concentrations have very large impacts on clouds (16, 25). This is where the traditional remote sensing methods of aerosols break down, whereas the applicability of using clouds as CCN chambers remains intact, as evident by the lower left corner of Fig. 3. This has particular importance in the context of the quest for the significance of changes from the preindustrial era to the present background aerosols (25).

The retrieval of both $CCN(S)$ and W_b allows, for the first time to our knowledge, disentangling of the roles of updrafts and

CCN on cloud microphysical, precipitation, and radiative properties over climatically meaningful areas. Previously, the inability to separate these factors has been a major impediment to our ability to quantify the aerosol/cloud-mediated effects on Earth's energy budget, thus keeping high the uncertainty of this effect (1). Application of the new capabilities offered by our methodology is expected to allow a breakthrough in quantifying these effects and to substantially reduce the uncertainty in anthropogenic aerosol climate forcing, at least for boundary layer convective clouds.

Error Analysis

A direct comparison of the satellite- to ground-based CCN, assuming no errors in the CCNC measurements, shows a correlation coefficient of 0.88 and a slope of 0.9 (i.e., underestimate of 10%). The MAPE is $\pm 30\%$. However, both satellite retrievals and CCNC measurements are subject to errors. Therefore, a bivariate regression has to be used for fitting two parameters with associated errors for both (45). The associated error for the satellite-retrieved CCN for a given S was taken as $\pm 30\%$. The CCN instrument errors were taken as the $\pm 95\%$ confidence interval (i.e., ± 2 SDs) of N_{CCN} for the individual cases, as described at the end of *Estimation of Cloud Base Drop Concentrations*. Both sets of errors are shown as error bars in Fig. 3.

The largest sensitivity is to errors in r_e , because, according to Eq. 2, the error in N_a is the cube of the error in r_e . The accuracy of MODIS-retrieved r_e is best when the 3.7- μm waveband is used (MODIS r_e is also available for 2.1- μm and 1.6- μm wavebands) in nondrizzling clouds; under these conditions, it showed the best agreement with aircraft measurements, with an uncertainty of 1 μm (46). The 3.7- μm -based r_e is also minimally affected by cloud inhomogeneities (47) because this band absorbs solar radiation much more strongly (48, 49). The VIIRS footprint area, which is sevenfold smaller than that of MODIS, further reduces the possibility of errors caused by cloud inhomogeneities. Our implementation to VIIRS is even more accurate than MODIS in the best of circumstances, because we use only pixels with visible reflectance > 0.4 at backscattering angles (satellite zenith angle of 0–50 degrees). To avoid significant distortion of r_e by coalescence, we avoided heavily precipitating clouds at their tops ($r_e > 18 \mu\text{m}$). MODIS r_e is larger than aircraft in situ measurements by 10–15% (34–36). This is probably not a problem for retrieved r_e based on the VIIRS Imager (30), because it is lower by a similar amount with respect to MODIS r_e . The retrieval uncertainty of r_e itself is roughly $\pm 10\%$ (36). This translates to uncertainty of a factor of $\pm 33\%$ in N_a . This error alone is larger than the measured validation error of $\pm 30\%$ when assuming no errors in the ground-measured CCN, which includes many other error sources, as described next. This might serve as an indication that the error in the retrieved r_e from VIIRS is smaller than for MODIS, probably due to the much finer resolution.

The MAPE in cloud base temperature of $\pm 1.1^\circ\text{C}$ propagates to a 5% error in N_a due to changing $C(T_b, P_b)$ in Eq. 1. The error in W_b (Fig. 2) can be propagated to an error in N_a according to Twomey's approximation of

$$N_a = CCN(S = 1\%)^{2/(k+2)} W_b^{3k/(2k+4)}, \quad [6]$$

where k is the slope of the $CCN(S)$ spectrum on a log–log scale (50). Accordingly, a W_b MAPE of $\pm 27\%$ propagates to an error in N_a of only 7–13% for $k = 0.5$ and 1, respectively. The overall combined error is $\pm 36\%$, as obtained by the calculation $(0.33^2 + 0.05^2 + 0.13^2)^{0.5} = 0.36$. This overall calculated error of $\pm 35\%$, even before adding the CCN instrument uncertainty, is larger than the measured validation error of $\pm 30\%$ when assuming no errors in the ground-measured CCN. This discrepancy could be explained, for example, by reducing the r_e error from 10% to 8%.

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