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The promise and perils of causal circuit manipulations

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Abstract

The development of increasingly sophisticated methods for recording and manipulating neural activity is revolutionizing neuroscience. By probing how activity patterns in different types of neurons and circuits contribute to behavior, these tools can help inform mechanistic models of brain function and explain the roles of distinct circuit elements. However, in systems where functions are distributed over large networks, interpreting causality experiments can be challenging. Here we review common assumptions underlying circuit manipulations in behaving animals and discuss the strengths and limitations of different approaches.

Introduction

A major goal of systems neuroscience is to explain the neural underpinnings of behavior. We believe a necessary first step is to describe experimentally tractable behaviors in terms of the algorithms and computations that underlie them [1,2]. The neural implementations of these processes can then be interrogated by recording and manipulating activity in targeted circuits and cell types, and by relating the experimental results to mechanistic models of how the probed functionality could be implemented in neural hardware [3].

Neural recordings play an important role in this endeavor by providing descriptions of brain dynamics that can reveal correlations with various aspects of behavior or sensory stimuli. The neural representations or coding schemes thus discovered can be evocative and inspire theories about the function of the probed circuits (e.g. 'place cells' in hippocampus [4], 'mirror neurons' in cortex [5]). However, the extent to which such correlations reflect *causal* contributions to the process under study is harder to gauge [6].

The concept of causality (i.e. cause and effect) in neuroscience is perhaps most intuitively grasped by thinking of the brain as a mechanistic system in which independent components with distinct functions interact to generate behavioral output [7] (Box 1). Besides offering tangible explanations, mechanistic models also speak to how a system can be controlled and

CONFLICTS OF INTEREST NONE

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manipulated [8] - an important aspect for many neuroscientists for whom the end game is to intervene in neurobiological processes gone awry [9,10].

BOX 1

The pained but consequential nomenclature of causality

The notion of causality and the interpretations of causality experiments can quickly become ambiguous and muddled by vague terminology. While superficially a semantic problem, imprecise or misconceived terms can interfere with our thinking, models, and experimental design.

The concept of *causality* itself has been the subject of intense debates in biology, physics, philosophy, and other fields [8]. In neuroscience, causality is most commonly described in terms of the relationship between neuronal activity and behavior: i.e. activity patterns in a distinct part of the brain (cells, circuits, brain areas) directly control an aspect of behavior. However, what is meant by such causal statements is often unclear. Is a neuron that merely relays commands to downstream circuits causal to the resulting behavior or not? More differentiated statements require additional classifications, like the distinction between *necessary* and *sufficient* which has been thoroughly explored in epidemiology, oncology, and genetics [134–136].

In genetics, *loss-* and *gain-of-function* experiments to identify *necessary* (function not possible without) and *sufficient* (can trigger function by itself) genes for a given function are commonplace. *Rescue experiments* are typically done to test for the specificity of destructive manipulations. In neuroscience, silencing and activating certain parts of the brain and determining the effects on behavior are often considered tests of necessity and sufficiency respectively, but rescue experiments are difficult and rarely done (e.g. activating axon terminals in a presumed target area while silencing the cell bodies). As discussed in the text, the interpretation of such experiments may not be straightforward, and will depend on the complexity of the studied system and the nature of the manipulation.

The distinction between *instructive* and *permissive* provides another perspective on causality [137,138]. Instructive neural elements are those whose activities contribute uniquely to computations crucial to the function of interest. Activity in a permissive part of the brain, on the other hand, is acutely necessary for a specific function, but does not contribute unique information or signal processing for it (i.e. the system can recover from loss of permissive activity without adding any new information to it).

In face of all these different aspects of causality, having clearly defined terminology is important to avoid misconceptions and ambiguities and to allow for meaningful discussions, interpretations, and conclusions of causality experiments in neuroscience.

Establishing and verifying mechanistic models requires demonstrating causal links between neural activity and behavior (Figure 1). Thankfully, optogenetics and other recently developed circuit manipulation tools are making it possible to control the activity of circuits and cell types with increasing specificity, something that has catalyzed an exciting new era

in systems neuroscience [11–14]. But in embracing these new methods, we must recognize that they are sharp tools that should be used with caution [15,16]. Indeed, how specific perturbations of neural activity affect the function of complex and interconnected neural networks, and how such experiments inform mechanistic models of brain function are often far from obvious. While there are no universal rules for designing and interpreting causality experiments in neuroscience, being cognizant of the complexities involved and explicit about the assumptions underlying particular experiments is likely to improve the utility of these remarkable technologies. The purpose of our review is to highlight some issues we believe are important and relevant for neural circuit manipulations in behaving animals.

Are neural systems decomposable into functional modules?

The goal of most causality experiments is to attribute functions to specific neural components, be they circuits or cell types. The underlying assumption is that the brain is a modular system with localized functions [17,18]. If this is indeed a good approximation, we should be able to study individual components of the brain in isolation, determine their respective functions, and then explain how complex behaviors and processes are implemented in terms of how the components interact [19]. This widely adopted approach has been successful in explaining how relatively simple and specialized systems operate [20–22].

Take, for example, the frog's prey-capture behavior [23]. It relies on a fast and largely feedforward circuit, with sensory processing 'modules' (retina/tectum) extracting important features of the sensory environment (is there prey?). The brainstem receives the results of these computations and makes a decision whether to trigger a pattern generator for prey capture. The system is well approximated by a box and arrow model where each box relates to an anatomically confined circuit with a specific function, and the arrows denote the (unidirectional) causal interactions between the modules (Figure 2, left and middle).

Models of this kind are satisfying because they align with our mechanistic worldview and mirror the design of our own man-made systems, whether machines or electronic circuits. However, there is a growing recognition that more complex and less specialized neural systems may not be easily decomposed into discrete modules executing sequential and causally linked operations [24,25]. Indeed, in circuits characterized by recurrence, feedback, and dense interconnectivity, system components are often interdependent to a degree that makes localization of function and the notion of causality less intuitive and explanatory (Figure 2, right).

In complex systems, neural and otherwise, functional principles may reveal themselves not by studying parts of the system in isolation, but rather by considering the rules that govern their dynamic interactions [26–29]. These interactions can give rise to emergent properties that must be considered to avoid mereological fallacies, i.e. ascribing to a part what only applies to the whole [30]. While there is no easy prescription for how to deal with emergent phenomena in neuroscience, dynamical systems theory [31] offers a framework for relating neural activity patterns to behavior in a way that abstracts from individual nodes in the network and describes the time-varying behavior of the system as a whole [32,33]. Recently,

Churchland and colleagues described the control function of motor cortex from a dynamical systems perspective [34], resolving apparent contradictions in studies taking a more neuron-centric view. In limiting their analysis to motor cortex, the implication was that this control functionality is, in large part at least, anatomically localized. This allowed the large scale box-and-arrow model of the motor system to be preserved, with one of the boxes (here: motor cortex) described as a dynamical system (Figure 2, middle).

The above discussion reminds us that the brain can be interrogated, understood, and modeled at different levels [18], and that the explanatory or descriptive framework most appropriate for one level may not be the best approximation for another [35]. Note that mechanistic explanations and dynamical systems descriptions are neither exclusive nor incompatible [24]; they simply represent complementary ways of analyzing a system (as do other types of models, including statistical and network-based models). Which of the various formalisms serve as the most useful abstraction in any given case will depend on a variety of factors, including the nature of the explanation sought, the complexity of the system etc.

However, when it comes to circuit dissection experiments in which the function of a circuit or cell type is queried, there is really no substitute for having a plausible and concrete mechanistic model (or a set of models) of how the probed algorithm could be implemented. Such models allow us to hypothesize putative functions of the manipulated neural elements in ways that relate them to other parts of the circuit and ultimately to behavior. We can then test these hypotheses with causal manipulations, thus furthering our mechanistic understanding. If, for reasons discussed above, the system cannot be adequately reduced to a meaningful mechanistic model, experimental outcomes may remain phenomenological descriptions of what happens when a circuit is perturbed in a particular way, with the bridge to conceptual understanding awaiting further theoretical or experimental advances.

Acute versus chronic manipulations

While the development of modern circuit dissection tools is revolutionizing neuroscience [9,12–14], the design and interpretation of these cutting-edge experiments are often informed by foundational studies using far 'cruder' perturbations – most notably lesions [36]. While it is expedient to think of acute and reversible neuronal silencing [37] (e.g. optogenetics, pharmacology) as a spatiotemporally precise version of lesions, there is a growing realization that acute perturbations and chronic silencing probe neural circuit function in fundamentally different ways [38–40]. Appreciating this distinction may clear up some confusion and allow meaningful comparisons across different manipulations, thus also building a better understanding of neural circuit function.

Acute perturbations

While treating a complex neural system as a collection of distinct functional modules can be a convenient and often necessary simplification (Figure 2), we must not lose sight of the fact that the brain is also a non-linear dynamical system defined by the interactions of its many components [41,42]. This is particularly important to remember when performing sudden activity perturbations since their effects, however targeted, are likely to ripple through the interconnected brain and influence activity patterns also in remote circuits [39,43,44]

(Figure 3). It is this difficulty in confining the effects of specific perturbations to the targeted circuit that makes it hard to probe circuit function based on behavioral effects alone. This is particularly true if the consequence of a perturbation is the non-specific cessation of ongoing behavior (i.e. loss of function).

An unexpected and sudden perturbation could, for example, switch the brain into a dynamical state distinct from the one associated with the probed behavior [45], thus 'activating' other neural systems that generate competing behaviors. For example, if you are in the middle of knitting a sweater when perceiving a tingling sensation in your leg, you may stop the knitting to investigate what caused the sudden sensation. If it was the consequence of artificially perturbing neural activity in the leg region of your somatosensory cortex, it doesn't follow that this part of your brain plays an essential role in knitting.

More generally, suddenly inhibiting (or exciting) a neural circuit or cell type can change how downstream circuits operate, including how they process inputs from other non-targeted areas [39,43,46] (Figure 3). In line with this, we recently found that inactivating sensorimotor nucleus Nif in songbirds disrupts vocal behavior by acutely suppressing activity in nucleus HVC, a premotor region downstream of Nif that controls the temporal progression of song [47,48]. However, after Nif was permanently inactivated, HVC spontaneously (i.e. without the bird practicing its song) recovered its pattern generator function and produced the same neural activity sequence (and song) as before the lesions. We concluded that normal activity in Nif is 'permissive' (Box 1), i.e. it is acutely required for HVC (and the song control system) to express its function but it is not necessary long-term [39]. Interestingly, the spontaneous recovery of HVC function after Nif lesions could be explained by homeostatic processes bringing HVC neurons back to their original firing rate set-point [39,49].

In contrast to the 'permissive' role we ascribe to Nif, neural activity in a circuit can be 'instructive' (Box 1) for a behavior if it contributes essential information or computation(s) [39]. Distinguishing whether activity in a circuit is permissive or instructive (or indeed irrelevant) is a prerequisite for a mechanistic understanding of how neural circuits implement algorithms and computations, yet this distinction can be difficult to make with acute activity perturbations alone (Figure 3, Box 1).

Chronic perturbations

In contrast to fast reversible manipulations, acute behavioral effects of lesions are rarely considered (though see, for example, [39,50]). Rather, subjects are typically evaluated once the 'non-specific' effects have subsided [46], which can be days, weeks or even months (as in the case of humans) after the lesion. A significant fraction of these transient 'non-specific' effects are likely due to changes in network dynamics caused by the sudden silencing of a part of the brain, i.e. the very same effects described and analyzed during fast reversible manipulations [39]. By allowing time for homeostatic and other processes to bring the brain back to dynamic equilibrium, lesion studies probe the steady-state contributions of a brain area (Figure 3). However, potential off-target effects must be considered also for lesions. For example, structural and functional reorganization (homeostatic and otherwise) that follow

But the major reason why conventional lesions have ceded to acute and reversible manipulations as the favored method for interrogating circuit function may be the difficulties in interpreting a lack of behavioral effects after lesions [38,51]. That a particular behavior can be implemented without a brain area days or weeks after it was lesioned does not necessarily mean that it was not acutely instructive. This is because the brain can have redundancies, degeneracies, and the capacity for plasticity (Figure 3). Redundancy assures that if an essential part of the system fails a back-up stands ready to prevent system failure. While there is redundancy *within* specific brain circuits that make their function robust to the fractional loss of neurons experienced in degenerative disease [52,53], the extent to which functionally distinct circuits can cover for each other (degeneracy, [54]) is less clear and should not be generally assumed [55–58].

Besides redundancies and degeneracies, the brain can also compensate for lost functionality through experience-dependent plasticity [59] (Figure 3). Spared neural circuits could plausibly assume some of the functions of the lesioned one(s) or alternative solutions to a behavioral task could be learned. For example, after partial motor cortex lesions, other parts of motor cortex can rewire to 'cover' for the lost area [60]. Further, if most or all of motor cortex is gone, tasks that depended on it, such as skilled reaching, can be solved in new, albeit slower and less dexterous, ways [61], likely by engaging subcortical control circuits to a larger degree [62]. Importantly, such experience-dependent plasticity requires renewed engagement with the task [63]. One way to rule it out as an explanation for post-lesion recovery is to prevent lesioned animals from 'practicing' the probed behavior [39,64], though this may not always be possible, especially for innate and habitually expressed behaviors.

The above discussion highlights the strengths and weaknesses of both acute perturbations and chronic lesions (Figure 3). Lesion studies ask how a brain that has reached post-lesion equilibrium performs with a piece missing. But gleaning the functionality of the missing piece by studying the behavioral deficit is complicated by the fact that other parts of the brain could have compensated for functions initially carried by the lesioned area. While acute perturbations leave little time for such compensation, their interpretive difficulty lies in the brain being in an altered and unusual dynamical state with unknown consequences on overall network function.

Thus, rather than relying exclusively on one method, our quest to understand brain function may benefit from combining both acute and chronic manipulations with careful behavioral monitoring and electrophysiological recordings of network-wide consequences. The ultimate goal should be to explain the often disparate experimental outcomes [38–40] within a unifying mechanistic model. With the recent development of targeted chronic manipulations (e.g. by genetically- or anatomically-defined expression of Tetanus or Diphtheria toxin [65,66]), it is now possible to manipulate the very same neural circuit elements both acutely and chronically, making comparisons across the different types of perturbations more meaningful.

Interestingly, issues relating to the peculiarities of acute and chronic manipulations have cropped up in other fields of biology. In genetics, for example, there is an ongoing discussion about the use of mutants (chronic genetic manipulations) versus morpholinos (acute manipulations: transient antisense gene knockdown) in zebrafish, Xenopus, and other organisms [67–70]. While both approaches probe the role of targeted genes, interpreting the outcomes of such experiments is complicated by possible compensation and off-target effects. However, the field has seemingly embraced the strengths and weaknesses of each approach and acknowledged that they can be used in complementary ways to dissect the roles of specific genes and gene networks [67,71].

Every so often acute and chronic perturbations alter (without completely disrupting) a behavior in similar ways, and these cases may be particularly informative. An illustrative example comes from songbirds, where silencing the outflow nucleus of the song-specialized basal ganglia (LMAN) with lesions [72] and acute inactivations [73] produces the same outcome: a reduction in song variability. Given our discussion above, one might ask why the sudden silencing of LMAN does not cause larger and more disruptive effects on both network function and behavior. We believe this is because the system is tuned to expect - and function in - a scenario where LMAN activity is suddenly suppressed, which happens when the male sings to a female [74]. LMAN neurons provide excitatory drive to the downstream song-control region RA, which also receives excitatory input from HVC, the temporal pattern generator. However, balanced feed-forward excitation and feed-forward inhibition from LMAN to RA ensures that the overall excitability of RA projection neurons is robust to acute changes in LMAN activity, thus allowing the motor pathway (HVC-RA) to produce song both with and without LMAN active [75].

Disruptive vs physiological perturbations

The above example emphasizes the power of using physiologically realistic and behaviorally relevant manipulations to probe neural circuit function. While sudden and unnatural perturbations of complex non-linear systems are often difficult to interpret (Figure 3), coaxing the system into dynamic regimes it naturally visits is likely to be less disruptive and more informative (Figure 4). Also, manipulation experiments are meant to probe 'what-happens-if' scenarios, and the most useful ones to explore are those that occur under normal conditions [44]. This is where modern manipulation techniques have the potential to change the game. Spatiotemporally precise, bi-directional manipulations of neuronal activity allow us, in principle at least, to reproduce behaviorally relevant activity patterns in specific circuits [76,77]. Exploring the brain's natural dynamic regimes in controlled ways could allow for real gain-of-function experiments.

Several recent studies have shown the power of this approach to reveal causal relationships and inform mechanistic models. Given technical limitations, most successful examples thus far have involved neural systems in which behavioral variables are encoded by the overall firing rate of more-or-less homogenous neuronal populations (Figure 4). Perhaps the best understood examples of such systems are 'command neurons', classically identified in invertebrates and small vertebrates [78–80].

Bidirectional manipulations, now possible with optogenetics and chemogenetics, can dial up or down the activity of such neurons and explore the consequences on behavior. Studies in nematodes [81], flies [82–84], and zebrafish [85,86] have established the value of such experiments. A prominent example in rodents is the manipulation of the MLR, a brainstem nucleus controlling locomotion. Building on classic electrical stimulation experiments [87], recent optogenetic manipulations of MLR activity could increase and decrease the speed of locomotion in predictable ways [88,89]. Besides demonstrating a causal relationship between MLR activity and locomotion, the authors also identified the involved neuronal MLR subpopulation. Finally, they performed electrophysiological recordings from optogenetically identified neurons, showing that the effects of their manipulations matched the physiological activity of these neurons under normal conditions [89] (Figure 4). Other systems in which similar experiments have been performed include the freeze and flight systems of the central amygdala [90–92] and periaqueductal gray [93], amygdala-centered anxiety networks [94–96], and the hypothalamic circuits controlling aggression [97] and feeding [98,99]. There have also been encouraging developments in systems where the activity of specific neural populations contributes to computations without triggering immediate behavioral output. Examples include dissecting the role of interneuron subtypes in gating plasticity during fear learning [100,101], revealing the arithmetic of the dopamine prediction error circuit [102], and identifying VTA GABA projection neurons as key in communicating saliency during associative learning [103].

Acute circuit manipulations have also contributed to elucidating how memories are formed and stored [104–107]. Combining activity-dependent expression techniques with optogenetic and chemogenetic manipulations has allowed neuronal populations 'active' during a previous learning experience to be reactivated [108–113] or inhibited [114,115]. Such manipulation can trigger or suppress learned sensorimotor associations, indicating that the manipulated neurons are part of a memory network, or 'engram' [104–106]. However, because these manipulations do not mimic physiological activity patterns, interpretations of how the behavioral responses relate to the memory being probed remain debated [104–107].

More generally, simply increasing or decreasing the firing rate of neurons may not adequately probe circuits whose functions rely on precise spike-timing and complex network dynamics [77,116] (Figure 4). Such manipulations will generate non-physiological dynamics and likely lead to disrupted processing (i.e. loss of function), limiting the insights that can be gained (see discussion above). Performing behaviorally relevant perturbations in such systems has to start with describing, through neural recordings, the natural dynamical regimes of the system. Modern manipulation techniques could then be used to coax the system into making transitions between states by replaying physiological activity patterns at the right times. Due to uncertainties in each individual experiment, e.g. the number of neurons to manipulate, side-, off-target- and network-effects etc. [15,44], online monitoring of the induced effects will be crucial for interpreting these experiments. The promises and perils of manipulating neural systems within their natural regimes have been explored in a recent review [44] which gives some pointers on how to move forward.

Changing activity patterns in complex neural systems within their natural regimes can, in certain cases, be effectively accomplished with more 'low-tech' methods. Manipulating

temperature, for example, is a powerful way to probe how small changes in the speed of signal propagation in a network affect behavior – something not easily done with other manipulation techniques. It has been successfully used in songbirds to reveal the relationships between the tempo of neural activity sequences and behavior [117,118], and could be relevant also for a variety of other systems [119,120].

Conclusion

New tools for manipulating neural activity in behaving animals have enabled researchers to control nervous system activity with unprecedented specificity and ease, transforming systems neuroscience in the process. Fulfilling the promise of these techniques requires us to tread carefully and mold our experiments and interpretations to the realities of the complex systems we are studying. While there are no fool-proof prescriptions for how to move forward, we believe that success will be contingent on carefully describing the behaviors we study in terms of the algorithms and computations that underlie them (Figure 1). Our current understanding of the system can then inform mechanistic models of how these algorithms are implemented in neural circuitry, models that can then be tested by manipulating activity patterns in different parts of the brain (Figure 2). Though these reductionist models often assume localization of function and independence of its various modules, in interpreting experimental outcomes of circuit manipulations we must be cognizant of the interconnected nature of the brain and the fact that its components interact over multiple temporal and spatial scales [39,40] (Figure 3). For this and other reasons, the most effective and informative manipulations may be those that mimic behaviorally relevant neural dynamics (Figure 4). While this is now being achieved in relatively simple systems, where our ability to control the overall firing rates of neurons comes close to replicating behaviorally relevant scenarios, as we venture into systems with more complex dynamics and coding schemes, there will be a need for more sophisticated monitoring and manipulation tools. Ongoing research to achieve more selective expression of effectors like opsins and DREADDs [14,121,122], to clarify their mechanisms [37,123], to engineer opsins with non-overlapping spectra [37,124,125], to miniaturize light guides or LEDs with integrated recording sites [126–128], and to develop patterned and holographic illumination [129–133]), will bring us closer to mimicking 'normal' neural activity in complex systems. Concurrently, there must also be an emphasis on developing analytic tools, theoretical frameworks, and mechanistic models to help us make sense of the emerging data and extract principles of function. Combining these efforts and approaches will allow us to probe our systems from disparate but complementary angles, thus advancing our understanding of how the brain generates behavior.

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Mechanistic understanding of the brain requires assigning functions to neural modules

New sophisticated tools for manipulating neural activity advance this quest

Localizing functions to brain areas can be difficult in distributed neural systems

Acute and chronic activity manipulations probe circuit function in different ways

Future developments should focus on manipulations that mimic physiological activity



Figure 1.

Addressing the neural basis of behavior requires defining the behavioral processes to be understood in terms of the underlying algorithms and computations (left). The implementations can then be probed by recording and manipulating activity in targeted neural circuits during behavior. Typical intermediate goals are: first, to identify the elements in the brain 'essential' for a given process (red squares – 'the causal network'), second, to describe the functions of the different parts, and third, to elucidate the logic by which these functions are implemented. The ultimate goal is to account for the behavioral 'process' in terms of how the various 'parts' (neurons and brain areas) interact, and to extract general rules that govern these interactions. This review discusses how different types of circuit manipulations can help us achieve this grander goal, and some of their pitfalls.



Figure 2.

The conceptual and practical utility of mechanistic descriptions depend on the complexity, dynamics, and topology of the underlying network. Certain systems (e.g. simple reflex arcs), can be represented as sequentially connected modules with distinct localized functions (left). In more distributed and complex information processing systems with recurrent connectivity and feedback loops, localization of function and causality are not as well defined, making mechanistic models less intuitive and explanatory. Certain approximations aim to localize functions to specific recurrent circuits (middle), while others treat the system as a complex interconnected dynamical system (right).



Figure 3.

Acute and chronic manipulations of neural activity can lead to different behavioral effects and conclusions regarding the role of the targeted circuit elements. When probing a permissive part of the system using acute perturbations (top row, see Box 1), sudden changes to the dynamics of downstream brain areas (blue) could plausibly disrupt their function, leading to behavioral deficits that do not reflect the computations of the targeted circuit element (top middle). Importantly, the outcome would be similar to targeting an essential, or instructive, part of the system (bottom middle). In contrast, after chronic removal of a permissive part of the targeted circuit, the system could spontaneously (i.e. without adding new information through practice) settle into a new dynamical equilibrium and resume its normal function (top right). This same outcome can be had if targeting an essential part of the system as long as there are experience-dependent mechanisms that allow other elements to compensate for lost function (bottom right, see text). Thus behavioral effects of acute manipulations could overestimate the role of a circuit element, while chronic perturbation could under-estimate it.



Figure 4.

The activity of neuronal populations and the states of a behavioral variable can be related in different ways. Homogeneous bidirectional activity manipulations in neurons using similar rate codes (left) is more likely to mimic behaviorally relevant scenarios than the same manipulations in circuits with more complex population codes (right). Perturbing a system along a behaviorally relevant axis (red lines) allows for more direct tests of causality.