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A Regional Bolus Tracking and Real-time B1 Calibration Method for Hyperpolarized 13C MRI

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Abstract

Purpose: Acquisition timing and B_1 calibration are two key factors that affect the quality and accuracy of hyperpolarized ${}^{13}C$ MRI. The goal of this project was to develop a new approach using regional bolus tracking to trigger Bloch-Siegert B_1 mapping and real-time B_1 calibration based on regional B₁ measurements, followed by dynamic imaging of hyperpolarized ¹³C metabolites in vivo.

Methods: The proposed approach was implemented on a system which allows real-time data processing and real-time control on the sequence. Real-time center frequency calibration upon the bolus arrival was also added. The feasibility of applying the proposed framework for in vivo hyperpolarized 13 C imaging was tested on healthy rats, tumor-bearing mice and a healthy volunteer on a clinical 3T scanner following hyperpolarized $[1 - {^{13}C}]$ pyruvate injection. Multichannel receive coils were used in the human study.

Results: Automatic acquisition timing based on either regional bolus peak or bolus arrival was achieved with the proposed framework. Reduced blurring artifacts in real-time reconstructed images were observed with real-time center frequency calibration. Real-time computed B_1 scaling factors agreed with real-time acquired B_1 maps. Flip angle correction using B_1 maps results in a more consistent quantification of metabolic activity (i.e, pyruvate-to-lactate conversion, k_{PL}). Experiment recordings are provided to demonstrate the real-time actions during the experiment.

Conclusion: The proposed method was successfully demonstrated on animals and a human volunteer, and is anticipated to improve the efficient use of the hyperpolarized signal as well as the accuracy and robustness of hyperpolarized 13 C imaging.

Keywords

Real-time; Bloch-Siegert; B_1 mapping; ¹³C; Hyperpolarized; MRI; metabolic imaging; Bolus tracking; Pyruvate

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Introduction

Magnetic resonance imaging with hyperpolarized 13 C-labeled compounds prepared via dynamic nuclear polarization (1) has been used to non-invasively study metabolic processes in vivo (2). In this method, the hyperpolarized state of the agent and any metabolic products will irreversibly decay to thermal equilibrium due to metabolic conversion, RF depletion and T_1 relaxation. Hyperpolarized $[1 - 13C]$ pyruvate has been widely used to monitor metabolic pathways (3–12) and its feasiblity for human study has been demonstrated (11,12). The T_1s of hyperpolarized [1-13C]pyruvate and its downstream metabolites (e.g. lactate) at clinical field strengths are estimated to be 25s to 45s (11, 13) in vivo. In light of the nonrenewable nature and fast decay of the hyperpolarized magnetization, acquisition timing and transmit power (B_1) calibration are two key factors that affect the quality and accuracy of hyperpolarized ${}^{13}C$ imaging.

Bolus tracking for triggering the acquisition has been used in clinical MRI for proton MR angiography (14). Appropriate acquisition timing for hyperpolarized 13 C imaging is useful in several aspects: a) Excitation before the bolus arrival may saturate the nonrecoverable hyperpolarized signal particularly near the coils conductive elements where the B_1 can be elevated. b) Many variable flip schemes (15–18) that optimize the hyperpolarized MRI signal sampling require knowledge of the bolus arrival. c) It is more straightforward for kinetic modeling to start signal sampling after the bolus maximum (19) to eliminate the need to account for the input function. d) Inconsistent acquisition timing leads to quantification errors when metabolite to substrate ratios are used as a quantitative metric (19, 20). Currently, in vivo hyperpoliarized 13 C imaging protocols typically start at a certain delay time after bolus injection. The delay time is determined based on prior knowledge, which can be unreliable due to the inherent physiological variability of each individual. This is particularly problematic in human subjects in which 12 s variations in bolus arrival have been observed (11). This variability can be further exacerbated in tumors where the vascularization and perfusion are highly inconsistent over subjects (21). Recently, a bolus tracking method using a slab FID as tracking signal was demonstrated (19) for automatic acquisition timing. However, this method didn't reflect the signal variation within the imaging slab. In this study, bolus tracking was improved by using the bolus signal from a region of interest (ROI) on a tracking image rather than from the entire excitation slab.

In the context of hyperpoliarized ¹³C MRI, B_1 calibration is crucial for variable flip angle schemes (15, 16, 18) and quantification of metabolic activities (22). Due to the virtually nonexistent endogenous ¹³C signal, ¹³C B₁ calibration is typically performed on external phantoms, but this approach does not account for the variability of subject loading. Bloch-Siegert B_1 mapping has been applied to hyperpolarized ¹³C imaging (23, 24) and is advantageous due to its short acquisition time and efficient use of the hyperpolarization signal. However, real-time power compensation has not yet been accomplished to calibrate the flip angle during the scan.

This work presents a new approach using regional bolus tracking to trigger Bloch-Siegert B 1 mapping and real-time RF power compensation based on regional B_1 measurements followed by dynamic imaging of hyperpolarized 13 C metabolites. Real-time center

frequency calibration upon bolus arrival was also implemented. Thermally polarized 13C phantom experiments were performed to validate Bloch-Siegert B_1 mapping. The feasibility of applying the proposed framework for in vivo hyperpolarized ^{13}C imaging was demonstrated on healthy rats, tumor-bearing mice and a healthy volunteer on a clinical 3T scanner. This proposed method was designed to improve the efficient use of the hyperpolarized signal as well as the accuracy and the robustness of hyperpolarized 13C imaging.

Methods

Real-time Hyperpolarized 13C MRI

The proposed scheme is illustrated in Fig. 1. ROIs for both bolus tracking and B_1 calibration are prescribed according to proton anatomical images before starting 13C sequences. The bolus tracking sequence starts before the hyperpolarized substrate is injected. Real-time center frequency calibration based on the acquired slab frequency spectrum can be triggered upon the bolus arrival. When the peak bolus signal in the prescribed ROI is detected, Bloch-Siegert B_1 mapping is triggered and the RF power for all sequences is then calibrated in real time based on the measured ROI B_1 . The sequence triggered upon the completion of B_1 calibration for most experiments in this study is alternate pyruvate/lactate dynamic imaging, which could be replaced by any hyperpolarized 13 C sequence for other studies. Our proposed scheme was implementedon a GE Signa MR 3T scanner (GE Healthcare, Waukesha, WI) using a commercial software (RTHawk, HeartVista, Los Altos, CA) which allows for real-time reconstruction of acquired data and feedback control of the pulse sequence. The software was installed on a workstation (2.4GHz, 16 proccessors, 64 GB RAM) running the Ubuntu operating system.

The bolus tracking sequence used a singleband spectral-spatial excitation pulse and a singleshot spiral readout, similar to Fig. 2 but without the Fermi pulse and associated delay. In these studies, this was used for selective imaging of $[1 - {^{13}C}]$ pyruvate, but could be adapted for other metabolites (e.g. 13 C-urea). The algorithm for tracking the maximum bolus signal was implemented based on prior works (14,19). The bolus signal is the mean value of a prescribed ROI on the tracking image. Our bolus tracking acquisition consists of two modules, i.e., noise calibration and bolus tracking, which can be performed independently. Noise calibration is used to determine the tracking threshold. If the tracking threshold has been previously computed, bolus tracking can be performed without running noise calibration. In the noise calibration module, the tracking threshold S_{thr} is determined as

 $S_{thr} = c_{thr} \sigma = c_{thr}$ *mnoise π* 2 , where σ is the standard deviation of Gaussian noise in the complex

image, m_{noise} is the mean value of magnitude images of noise and c_{thr} is a scaling factor. 100 calibration scans (TR = 200 ms) are performed to compute m_{noise} which is converted to σ (25). Given the noise distribution of the background in magnitude images follows a Rayleigh distribution (25), if a probability P_{thr} that a noise signal is above the tracking threshold is required, the proportional relationship between S_{thr} and σ can be derived using the cumulative distribution function of a Rayleigh distribution. For example, $c_{thr} = 3$ would result in a P_{thr} of 0.001%. In the bolus tracking module, the sequence is resumed

automatically if the bolus peak is not detected. When a cumulative number n_{cum} of signal increases is detected and all these signals are above the tracking threshold as well as greater than u_{peak} fraction of its previous signal, the program starts to update the peak value. When the bolus signal is lower than u_{peak} fraction of the current peak signal, detection of bolus peak will be reported. In our study, u_{peak} was determined based on estimated hypolarization loss due to T_1 . For example, under the assumptions of a T_1 of 30s, an excitation ip angle of 5°, no more pyruvate from the bolus coming into the ROI and neglecting metabolic conversion, the hyperpolarization loss over a TR of 1s for the bolus tracking sequence would

be 1 - cos($5^{\circ} \times \pi/180$) \times exp(-1/30) = ~0.04, and the remaining hyperpolarization (~0.96) was used as u_{peak} . The use of cumulative increase rather than successive increase as used in the previous work (19) aims to improve the robustness of the tracking algorithm to motion and injection with unstable rates. For some experiments, during the time that bolus signal was below the current signal peak but above u_{peak} threshold, a short repetition time was used to shorten the time interval between actual bolus peak and detected bolus peak.

The Bloch-Siegert B_1 mapping sequence (23, 24, 26) (Fig. 2) shared the similar excitation and readout as bolus tracking, using a singleband spectral-spatial excitation pulse and a single-shot spiral readout, whereas an off-resonance Fermi pulse $(K_{BS} = 6.76 \text{ rad} = G^2)$ was inserted in between. The phase difference between two Bloch-Siegert B_1 mapping sequences with opposite ω_{RF} was used to calculate B_1 . Taking the phase difference removes receiver phase and minimizes the influence of B_0 off-resonance frequency (26). Parameters used in this study were designed to measure a maximum B_1 of 0.48G. The two phase maps were masked based on corresponding magnitude images in order to eliminate noisy phases due to low signal. The threshold is determined as $S_{B1} = c_{B1}\sigma$, where c_{B1} is a scaling factor and noise standard deviation σ was obtained from the bolus tracking sequence. The ratio of the desired B_1 to the measured ROI B_1 was passed to all sequences as a scaling factor to calibrate transmit power in real time.

The center frequency calibration sequence consists of a sinc excitation pulse with slab selection gradient and a 102 ms readout with a 5kHz bandwidth. The acquired spectrum is used to calibrate center frequency for all sequences in real time. Alternate pyruvate and lactate dynamic imaging shared the same excitation and readout as bolus tracking, using a single-band spectral-spatial excitation pulse and a single-shot spiral readout, but with alternating excitation frequencies and different flip angles to image pyruvate and lactate.

All methods described are available through the HeartVista research collaboration portal [\(https://www.heartvista.com/git/shuyu/hv_research_shuyu](https://www.heartvista.com/git/shuyu/hv_research_shuyu)).

Phantom and Animal Experiments

Validations of the Bloch-Siegert B_1 mapping sequence were performed on a ¹³C/¹H birdcage coil as well as on a ¹³C figure-8 transceiver coil. For experiments using the ¹³C/¹H birdcage coil, a cylindrical ethylene glycol phantom with a base of 3.6cm diameter was used. Axial $13C B₁$ maps at four transmit powers (50%, 75%, 100% and 150% of the calibrated power) were acquired (FA 90°, slice thickness 10mm, Fermi pulse duration T_{RF} 12ms, frequency offset ω_{RF} ±4.5kHz, FOV 10cm, in-plane resolution 2.5 \times 2.5mm, TR 2s, NEX 100). For experiments using the ¹³C figure-8 transceiver coil, a cup (cross-section diameter from 5.5 to

7.5cm, height7.5cm) filled with oil was placed on top of the coil. An axial ¹³C magnitude map with a nominal 180° excitation (FA 180°, slice thickness 100mm, FOV 20cm, in-plane resolution 5×5 mm, TR 1s, NEX 100) and its corresponding B_1 map (FA 60°, slice thickness 100mm, Fermi pulse duration T_{RF} 8ms, frequency offset $\omega_{RF} \pm 3kHz$, FOV 20cm, in-plane resolution 5×5 mm, TR 1s and NEX 200) were acquired. A 2D phase unwrapping algorithm (27) based on minimum spanning tree was implemented to correct phase images of B_1 mapping off line.

Hyperpolarized 13C animal experiments were performed to test our proposed scheme using normal Sprague-Dawley rats and transgenic adenocarcinoma of mouse prostate (TRAMP) mice with ${}^{13}C/{}^{1}H$ birdcage coils (8cm diameter for rats, 5cm diameter for mice). Two experiments were also performed on a rat with a ${}^{13}C$ figure-8 transceiver coil. A total of six rats and two TRAMP mice were used to test the proposed scheme.All animal studies were conducted under protocols approved by the University of California San Francisco Institutional Animal Care and Use Committee (IACUC). Both rats and mice were anesthetized with iso urane (1–2%) and placed in a supine position on a heated pad throughout the duration of the experiments. $[1 - {^{13}C}]$ pyruvic acid (Sigma Aldrich, St. Louis, MO) mixed with 15mM trityl radical (GE Healthcare, Waukesha, WI) and 1.5mM Gd-DOTA (Guerbet, Roissy, France) was polarized in a HyperSense dissolution DNP system (Oxford Instruments, Abingdon, UK) at 1.35K and 3.35T for ~1h. A 4.5mL volume of 80mM NaOH and 40mM Tris buffer was used as dissolution media, resulting in a 80mM $[1-13C]$ pyruvate solution, with final pH of 6–8. The hyperpolarized $[1-13C]$ pyruvate was injected into the animal via tail vein catheters, ~2.6mL for each rat and ~350μL for the mouse. Each animal received two injections.

All animal experiments were performed using the proposed scheme (Fig. 1). ^{13}C sequence parameters for animal experiments are shown in Table 1. Some experiments were performed with real-time center frequency calibration. The desired B_1 of the Fermi pulse in B_1 mapping sequence for all experiments was always set to 0.3G (344% of B_1 required for a 90° excitation of the spectral-spatial pulse used in this study). Using the measured transmit B_1 maps, all in vivo results were compensated for spatial B_1 variations and flip angles between sequences. RF power measurements are shown as relative B_1 maps which are the measured B_1 normalized by the desired B_1 . For some experiments, data from alternate pyruvate and lactate dynamic imaging was used to quantify pyruvate-to-lactate conversion rate (k_{PI}) based on a two-site exchange model (28) using non-linear least-squares fitting.

For rat experiments using the ${}^{13}C/{}^{1}H$ birdcage coil, an anatomical localizer was acquired using proton 3D bSSFP sequence (FOV $16 \times 8 \times 4.8$ cm, Matrix size $256 \times 256 \times 76$). A total number of five injections were performed on three rats using the proposed scheme with different combinations of injection times (8s, 12s) and transmit gains (100%, 120% of prescan power calibration). Real-time center frequency calibration were not performed in these studies. A ¹³C urea phantom was used for frequency and pre-scan power calibrations. ¹³C images were acquired on the axial kidney plane. ROIs for bolus tracking and B_1 calibration were both placed on the left kidney.

For rat experiments using the 13 C transceiver coil, an anatomical localizer was acquired using proton T2-weighted fast spin echo sequence (FOV 6×6 cm, Matrix size 256×256) with the scanner body coil. The rat was positioned in a way that right kidney was about 1 cm further than left kidney from the bottom 13 C transceiver coil. This set up was designed to produce a distinct B_1 variation between two kidneys. Two injections were performed using the proposed scheme with the same parameters but with different tracking/ B_1 calibrating ROIs, one on right kidney and the other on left kidney. A 13 C urea phantom embedded on the coil was used for pre-scan frequency calibration. Real-time center frequency calibration was performed at the bolus arrival. ${}^{13}C$ images were acquired on the axial kidney planes with an injection time of 10s and transmit gain set based on pre-scan with the ¹³C-urea phantom.

For the TRAMP experiment, an anatomical localizer was acquired using proton T2-weighted fast spin echo sequence (FOV 6×6 cm, Matrix size 256 \times 256). Real-time center frequency calibration was performed at the bolus arrival. ${}^{13}C$ images were acquired on the axial tumor plane with an injection time of 12s and transmit gain the same as the calibrated power in pre-scan. A 13 C urea phantom was used for pre-scan frequency and power calibration. ROIs for bolus tracking and B_1 calibration were both in the tumor.

Volunteer Study

One human study was performed to test the proposed scheme (Fig. 1). A healthy volunteer was recruited with institutional review board approval and provided with written informed consent for participation in the study. The volunteer was a 37-year-old male. An Investigational New Drug approval was obtained from the U.S. Food and Drug Administration for generating the agent and implementing the clinical protocol. 1.47g of Good Manufacturing Practices (GMP) [1-13C]pyruvate (Sigma Aldrich, St. Louis, MO) mixed with 15mM electron paramagnetic agent (EPA) (AH111501, GE Healthcare, Oslo, Norway) was polarized using a 5T SPINlab polarizer (General Electric, Niskayuna, NY) for 3h before being rapidly dissolved with 130°C water and forced through a filter that removed EPA. The solution was then collected in a receiver vessel and neutralized with NaOH and Tris buffer. The receive assembly that accommodates quality-control processes provided rapid measurements of pH, pyruvate and EPA concentrations, polarization, and temperature. In parallel, the hyperpolarized solution was pulled into a syringe (Medrad Inc, Warrendale, PA) through a 0.5μm sterile lter (ZenPure, Manassas, VA) and transported into the scanner for injection. The integrity of this filter was tested in agreement with manufacturer specifications prior to injection. A 0.43mL/kg dose of ~250mM pyruvate was injected at a rate of 5mL/s via an intra-venous catheter placed in the antecubital vein, followed by a 20mL saline flush.

In this study, ${}^{13}C$ axial brain images were acquired with in-house built birdcage transmit coil and 32-channel receive array (29). Different from animal experiments, excitation pulses for bolus tracking, B_1 mapping and metabolic-specific dynamic imaging were replaced with a different singleband spectral-spatial RF pulse (130Hz FWHM passband, 870Hz stopband) (30). Single-slice real-time B_1 calibration was triggered right after real-time center frequency calibration rather than on bolus peak. The ROI for both bolus tracking and B_1

calibration was on the brain tissue near the superior sagittal sinus. Following B_1 calibration, multi-slice 2D acquisitions were performed to cover the entire brain, and $[1 - {^{13}C}]$ pyruvate, $[1¹³C]$ lactate and $[1¹³C]$ bicarbonate signals were acquired alternately. A ¹³C urea phantom embedded on the coil was used for pre-scan frequency calibration. Pre-scan power calibration was performed on a ${}^{13}C$ ethylene glycol head phantom. Proton anatomical reference was acquired with body coil built in the scanner, using 3D T1-weighted spoiled gradient echo with FOV 26.6×26.6×16cm, matrix size 256×256×160. 13C sequence parameters for this study are presented in Table 2.

For the online reconstruction, multichannel k-space data were combined using sum of squares. In the offline processing, coil combination was performed by using pyruvate signals as coil sensivitiy maps (31).

Results

Axial thermal ¹³C B maps of the ¹³C/¹H birdcarge coil at 50%, 75%, 100% and 150% of the calibrated transmit power are shown in Fig. 3a. The mean B_1 value of the phantom region versus the relative transmit power is plotted (Fig. 3b) to demonstrate the quadratic relationship between Bloch-Siegert phase difference and transmit power. A comparison between the magnitude image of nominal 180 $^{\circ}$ excitation and its corresponding B_1 map of a thermal ¹³C phantom on the ¹³C transceiver coil is shown in Fig. 3c and Fig. 3d. The B_1 value along the dark band in Fig. 3c and its corresponding theoretical excitation flip angle(0.3 G) is plotted in Fig. 3e, demonstrating the accuracy of Bloch-Siegert B_1 mapping.

Results of a representative hyperpolarized [1-13C]pyruvate experiment using the proposed scheme to image the kidneys of a healthy rat with ${}^{13}C/{}^{1}H$ birdcage coil are shown in Fig.4. Real-time center frequency calibration was not performed in this study. Fig. 4d displays every other timeframe of the real-time reconstructed data where magnitude images are normalized by the peak value of the corresponding metabolic series. The full set of images can be found in Sup. Fig. S1. The acquired B_1 map (Fig. 4b) was homogenous, as expected for this coil. The initial transmit power was purposely set to 120% of the power calibrated on a thermal ¹³C phantom and resulted in a nominal B_1 scaling factor of 0.83 (1/1.2), which was in reasonable agreement with the real-time computed B_1 scaling factor of ~0.87. Normalized pyruvate signal curves combining the data of bolus tracking and pyruvate/lactate dynamic imaging are shown in Fig. 4c for different ROIs. These pyruvate signal curves demonstrate that the ROI (left kidney) bolus peak was successfully detected, and acquisition timing would be different if the tracking ROI was on the major vessels.

Results of a hyperpolarized [1-13C]pyruvate experiment using the proposed scheme to image the tumor of a TRAMP mouse with $13C¹H$ birdcage coil are shown in Fig. 5. Fig. 5e displays every other timeframe of the real-time reconstructed data where magnitude images are normalized by the peak value of the corresponding metabolic series. The full set of images can be found in Sup. Fig. S2. The frequency spectrum (Fig. 5d) acquired from the imaging slab at the bolus arrival shows that the measured pyruvate frequency was 20Hz downfield from the frequency calibrated based on a thermal 13C phantom. Bolus tracking images right before and after real-time center frequency calibration in Fig. 5e demonstrate

that real-time center frequency calibration reduced blurring caused by off resonance reconstruction in real-time reconstructed images. Fig. 5b depicts the normalized B_1 map which is homogenous as expected for the coil. The real-time B_1 scaling factor (Fig. 5b) was 1.05, indicating a 5% difference from the power calibrated on a thermal 13 C phantom. Tumor k_{PL} (Fig. 5c) fitted using pyruvate and lactate signals was ~ 0.09 s⁻¹, agreeing with prior works (32) which showed a k_{PL} range of 0.03 to 0.08 s⁻¹ for high grade TRAMP tumor.

Results of two hyperpolarized $[1 - {^{13}C}]$ pyruvate experiments using the proposed scheme to image the kidneys of healthy rats with one-sided 13 C surface transceiver coil are shown in Fig. 6. Two experiments were performed with the same parameters but with the different tracking/calibrating ROIs, one on the right and the other on the left kidney, where the left kidney was closer to the coil. B_1 maps (Fig. 6b) acquired in two experiments are consistent and show that the left kidney experienced a 40% higher B_1 than the right kidney did. This agreed with the real-time B_1 scaling factors, 1.49 and 1.07 for the tracking experiments on the left and right kidney, respectively. k_{PL} maps fitted with and without flip angle correction for the two experiments are shown in Fig. 6c, where k_{PI} values of right kidney, left kidney and intestine are labeled. Root mean squared errors of k_{PL} values in the three labeled ROIs between two experiments are 0.0033 with flip angle correction and 0.0045 without flip angle correction, demonstrating that using acquired B_1 maps to correct flip angle results in more consistent k_{PL} estimations.

Results of the hyperpolarized [1-13C]pyruvate human experiment using the proposed scheme to image the brain are shown in Fig. 7 and Fig. 8. The polarization of the injected dose, back-calculated to the time of dissolution, was 41.9%. The ROI for both bolus tracking and B1 calibration was on the brain tissue near the superior sagittal sinus of slice 5. The frequency spectrum (Fig. 7c) acquired from slice 5 upon the bolus arrival shows that the measured pyruvate frequency was the same as the frequency calibrated in pre-scan. Fig. 7b depicts the normalized B_1 map which is homogenous as expected for the birdcage transmit coil. The real-time B_1 scaling factor (Fig. 7b) was \sim 1.04, 4% difference from the power calibrated in pre-scan. Pyruvate, lactate and bicarbonate sum-over-time images are displayed in Fig. 8, where maximum SNRs for pyruvate, lactate and bicarbonate are 627, 60 and 20, respectively. Dynamic images can be found in Sup. Fig. S3.

Experiment recordings are provided on YouTube (see links in the figure) to demonstrate real-time actions during the experiments.

Discussion

As discussed in the Introduction section, automatic acquisition timing via bolus tracking improves efficient use of hyperpolarization as well as consistency and accuracy of hyperpolarized 13C imaging. Furthermore, accurate timing is critical for some optimal variable fiip angle schemes and metabolic quantification (15–18). The implementation of regional bolus tracking in this work improves the flexibility and accuracy of acquisition timing, and it would be especially useful for imaging tissue with low perfusion rate where injected metabolites would arrive at the target region later relative to major vessels or other

tissues. The resolution of the bolus tracking image should be chosen as coarse as possible to improve image SNR but fine enough to separate the desired tracking region (e.g. major vessels from other tissues). An alternative approach is to use 2D spatially selective excitation pulses, but this approach is less robust to signals from off-resonance metabolites. In this study, bolus tracking triggered its following sequences either upon bolus arrival or following peak detection. This could easily be modified to use other schemes, such as starting metabolic imaging during the bolus or adding an additional delay from the peak. Manually triggering sequences during bolus tracking is also allowed in the designed framework and is useful if the automatic tracking algorithm fails. The bolus tracking used a flip angle of 5° and a TR of 1 s. Assuming an injection time of 10s, the expected total hyperpolarized signal loss due to bolus tracking RF pulses would be less than 2%.

The naturally low-abundance ${}^{13}C$ signal requires real-time B_1 mapping for accurate in vivo measurements of RF power in hyperpolarized ¹³C imaging. The acquired B_1 map is useful for flip angle correction of images and is crucial for quantification of metabolism (e.g. k_{PL}) (22)) as demonstrated in in vivo results (Fig. 6). Real-time B_1 calibration could achieve accurate flip angle during the scan, which is critical for variable flip angle schemes (15 18) and large flip angle pulses (33), and avoiding unnecessary use of hyperpolarization. The upper limit of the B_1 measurement depends on the K_{BS} value of the Bloch-Siegert pulse while the lower limit depends on the SNR. 2D phase unwrapping could be implemented in real time to extend the upper limit of B_1 measurement. Real-time masking of the acquired B_1 map based on signal intensity made the real-time B_1 calibration robust when the B_1 calibration ROI contained regions with low hyperpolarized signal. The two TRs required for the B1 mapping sequence used a pyruvate flip angle of 10°, using only 3% of the hyperpolarization magnetization.

Center frequency calibration is crucial for metabolite specific imaging. For singleband spetral-spatial pulses, frequency calibration errors will reduce the flip angle and may also excite undesired resonances. For spiral or echo-planar imaging (EPI) readouts, frequency calibration errors will lead to off-resonance blurring and shift artifacts. Both of these factors can undermine the accuracy of Bloch-Siegert B1 mapping and quantification of metabolism. Using a thermal 13 C phantom, which must be placed external to the subject, center frequency calibration doesn't capture B_0 within the subject. Although B_0 maps can be obtained via proton imaging, in vivo shimming could still be challenging, particularly in the presence of motion. In this study, real-time center frequency was triggered upon bolus arrival, which improved the quality of all the following real-time reconstructed images (Fig. 5e). The 102ms readout duration of the center frequency measurement sequence resulted in a \sim 10Hz frequency resolution which could be improved with a longer readout duration. A 3 \degree flip angle cost less than 0.2% hyperpolarization.

The transition time between acquisitions is mainly attributed to real-time image reconstruction and loading sequence waveforms. For animal experiments using singlechannel acquisition, the transition times of a bolus tracking acquisition, real-time center frequency calibration, real-time B_1 calibration and their following sequences were about 60ms, 60ms and 400ms, respectively. For the human experiment using 32-channel acquisition, a longer transition time (~800ms) was observed for real-time B_1 calibration,

whereas transition times for bolus tracking acquisition and real-time center frequency calibration remained similar. The longer transition time found in B_1 calibration could be caused by its more complicated reconstruction compared to frequency calibration, and its shorter TR compared to a bolus tracking acquisition which typically used a TR of 1s and allowed real-time reconstruction to be completed during the dead time of a TR.

A ¹³C-pyruvate and ¹³C-urea co-polarized injection (34) would benefit substantially from the proposed methods. 13C-urea could be used to perform bolus tracking, real-time center frequency and B_1 calibration. This strategy would fully reserve hyperpolarized signal of pyruvate (19) and provide higher SNR for B_1 mapping by using a larger flip angle. Cardiac and respiratory motion could detrimentally affect bolus tracking and Bloch-Siegert B¹ mapping. Cardiac gating could be used (23). In terms of respiratory motion, breathholding is often used in clinical studies. Respiratory gating is not suitable for bolus tracking due to large potential delays but can be applied to perform B_1 mapping at the end of exhalation (23), in which case, a short TR (200ms) as used in this study is recommended. A more challenging but robust approach to handle motion is to perform real-time image registration. To extend the proposed scheme for volumetric calibration, real-time center frequency and B_1 calibration can be integrated with a multislice imaging framework (23). More than one ROI for tracking or B_1 calibration could be useful when B_1 (e.g. Fig. 6b) or acquisition timing (e.g. Fig. 4c) shows variation within the imaging subject.

Conclusion

This work demonstrated an approach that integrates automatic acquisition timing using the regional bolus signal with real-time center frequency calibration, Bloch-Siegert B_1 mapping and real-time RF power compensation based on regional B_1 measurements as well as dynamic hyperpolarized 13 C imaging. This scheme allows for timing the acquisition based on bolus information of a local region within the imaging plane. Acquiring in vivo B_1 maps, performing real-time center frequency calibration and B_1 calibration, ensures accurate center frequency and flip angles which are used in the following hyperpolarized ^{13}C sequences. The proposed scheme was successfully demonstrated for in vivo hyperpolarized $[1¹³C]$ pyruvate imaging on a clinical 3T scanner. Future work will focus on incoporating pyruvate-urea co-polarized injections, volumetric calibration and motion-compensation methods into the proposed scheme to improve efficiency, accuracy, and robustness of hyperpolarized 13 C studies.

Supplementary Material

Refer to Web version on PubMed Central for supplementary material.

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 $B₁$ Cal calibrates $B₁$, triggers *Pyruvate/Lactate Imaging*

Figure 1:

Overview of the proposed scheme. Bolus tracking starts before the bolus injection. Realtime center frequency calibration ('CF Cal') based on a slab FID is triggered upon ROI bolus arrival, while Bloch-Siegert B_1 mapping and real-time ROI B_1 calibration (' B_1 Cal') are triggered at the ROI bolus peak. The sequence triggered after B_1 calibration for most experiments in this study is alternate pyruvate/lactate dynamic imaging, and could be replaced by any hyperpolarized 13 C sequence for other studies.

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Figure 2:

Metabolite-specific imaging sequence used in this study, where all instances included a singleband spectral-spatial excitation pulse (passband 120 Hz, stopband 600 Hz) and a single-shot spiral readout. The sequence shown also includes an off-resonance Fermi pulse $(T_{RF} = 12 \text{ ms}, \omega_{RF} = \pm 4.5 \text{ kHz})$ for Bloch-Siegert B1 mapping, while bolus tracking and pyruvate/lactate dynamic imaging also used this sequence but without Fermi pulse and its associated delay. Other key parameters for bolus tracking were FA 5° (pyruvate), TR 1s; and for Bloch-Siegert B1 mapping were FA 10° (pyruvate), TR 200ms.

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Figure 3:

Validation of Bloch-Siegert B mapping on the ${}^{13}C/{}^{1}H$ birdcage coil using a cylindrical ethylene glycol phantom (a-b) and on the ${}^{13}C$ figure-8 transceiver coil using a cup filled with oil (c-e). For the latter experiment, the oil cup was placed on the top of the ^{13}C coil. In both experiments, the desired B_1 of the Bloch-Siegert pulse was 0.3G, at which the excitation pulse would produce the theoretically accurate flip angle. (a) Axial $^{13}C B_1$ maps of birdcarge coil with 50%, 75%, 100% and 150% relative to the calibrated transmit power in pre-scan. (b) A plot of Bloch-Siegert phase difference versus relative transmit power. Each data point corresponds to the mean value of the phantom area of each B_1 image in(a). The data point at the relative power of zero is estimated to be zero. The quadratic curve is computed by a least-squares fitting. (c) Axial 13 C image of transceiver coil with a nominal 180° flip angle. The dark band in the image corresponds to a 180° signal null. (d) Corresponding axial B_1 map of (c), where the dark band corresponds to ~ 0.3 G as expected. (e) A plot of B_1 value across the dark band and corresponding flip angles calculated based on the B_1 value.

Figure 4:

Results of a hyperpolarized $[1 - 13C]$ pyruvate study in a normal rat using the proposed method (Fig. 1) with a birdcage coil. Real-time center frequency calibration was not performed in this study. The ROI for both bolus tracking and B_1 calibration was on the left kidney. Injection time was 8 s and initial power was purposely set to 120% of the calibrated power in pre-scan. Sequence parameters are presented in Table 1. (a) Proton localizer. (b) Normalized ¹³C B₁ map. Real-time B₁ scaling factor (~0.87) matched up with the initial transmit power (120%). (c) Normalized pyruvate signal curves in different ROIs. The ROI (left kidney) bolus peak was successfully detected. (d) 13 C results displayed in the order of time. Every other timeframe is shown. The full set of images can be found in Sup. Fig. S1. Experiment recording: <https://youtu.be/CN3mIrzmBT8>.

cf calibration reduced image blurring caused by off resonance reconstruction

Figure 5:

Results of a hyperpolarized $[1 - 13C]$ pyruvate study in a TRAMP mouse using the proposed method (Fig. 1) with a birdcage coil. The ROI for both bolus tracking and B_1 calibration was the tumor. Injection time was 12 s and initial power was the same as the calibrated power in pre-scan. Sequence parameters are presented in Table 1. (a) Proton localizer. (b) Normalized ¹³C B₁ map. (c) Pyruvate-to-lactate conversion rate(k_{PL}) map with corrected flip angle. (d) Acquired frequency spectrum for center frequency calibration. "Center frequency" is abbreviated as "cf" in the gure. (e) 13 C results displayed in the order of time. Every other timeframe is shown. The full set of images can be found in Sup. Fig. S2. Bolus tracking images before and after real-time center frequency calibration demonstrate that real-time center frequency calibration reduced off-resonance artifacts in real-time reconstructed images. Experiment recording: [https://youtu.be/ViTDb3PzK3U.](https://youtu.be/ViTDb3PzK3U)

Figure 6:

Results of two hyperpolarized $[1 - 13C]$ pyruvate studies in a normal rat using the proposed method (Fig. 1) with a ${}^{13}C$ surface transceiver coil. The two experiments were performed with the same parameters except for different tracking/calibrating ROIs: experiment #1 on right kidney and #2 was on left kidney, where the left kidney is closer to the coil. Injection time was 10 s and initial power was the same as the calibrated power in pre-scan. Sequence parameters are presented in Table 1. (a) Proton localizer. (b) Normalized ¹³C B₁ maps. B₁ maps acquired in two experiments are consistent. (c) Estimated k_{PL} with and without flip angle correction based on measured B_1 map. k_{PL} values for left kidney, right kidney and intestine are labeled in the maps. Using acquired B_1 maps to correct flip angle results in more consistent k_{PL} estimations of those ROIs between the two experiments, demonstrating the importance of flip angle correction for k_{PL} measurements. Experiment recordings: [https://youtu.be/Mu3NW7Kog9M,](https://youtu.be/Mu3NW7Kog9M) [https://youtu.be/fL5gVkPDw2o.](https://youtu.be/fL5gVkPDw2o)

time

Figure 7:

Results of hyperpolarized $[1 - 13C]$ pyruvate studies on a healthy human volunteer using the proposed method (Fig. 1) with in-house built birdcage transmit coil and 32-channel receive array. In this study, single-slice real-time B_1 calibration was triggered right after real-time center frequency calibration. The ROI for both bolus tracking and B_1 calibration was on the brain tissue near the superior sagittal sinus of slice 5 (see Fig. 8 for slice 1–8). A multi-slice 2D acquisition was used for pyruvate/lactate/bicarbonate dynamic imaging. Initial power was the same as the calibrated power in pre-scan. Sequence parameters are presented in Table 2. (a) Proton image of slice 5. (b) Normalized ${}^{13}C B_1$ maps. (c) Acquired frequency spectrum for center frequency calibration. (d) ¹³C results of slice 5 displayed in the order of time. Multi-slice dynamic images can be found in Sup. Fig. S3. Sum-over-time images can be found in Fig. 8. Experiment recordings:<https://youtu.be/Oq36Z7ayQ0g>.

Figure 8:

Sum of first twenty time points of multi-slice pyruvate/lactate/bicarbonate dynamic images as described in Fig. 7 and Sup. Fig. S3. Anatomical images are provided as coarse anatomical landmarks. Maximum SNRs of sum-over-time images for pyruvate, lactate and bicarbonate are 600, 58 and 19, respectively.

Table 1:

¹³C sequence parameters for animal experiments shown in Fig. 4 ('Rat/Birdcage'), Fig. 5 ('TRAMP') and Fig. 6 ('Rat/Surface').

¹³C sequence parameters for the human study shown in Fig. 7 and Fig. 8

Table 2: