

Determining the Time of Cancer Recurrence Using Claims or Electronic Medical Record Data

abstract **Purpose** Data from claims and electronic medical records (EMRs) are frequently used to identify clinical events (eg, cancer diagnosis, stroke). However, accurately determining the time of clinical events can be challenging, and the methods used to generate time estimates are underdeveloped. We sought to develop an approach to determine the time of a clinical event—cancer recurrence—using high-dimensional longitudinal structured data.

Methods Manual chart abstraction provided information regarding the actual time of cancer recurrence. These data were linked to claims from Medicare or structured EMR data from the Cancer Research Network, which were used to determine time of recurrence for patients with lung or colorectal cancer. We analyzed the longitudinal profile of codes that could help determine the time of recurrence, adjusted for systematic differences between code dates and recurrence dates, and integrated time estimates from different codes to empirically derive an optimal algorithm.

Results We identified twelve code groups that could help determine the time of recurrence. Using claims data for patients with lung cancer, the optimal algorithm consisted of three code groups and provided an average prediction error of 4.8 months. Using EMR data or applying this approach to patients with colorectal cancer yielded similar results.

Conclusion Time estimates were improved by selecting codes not necessarily the same as those used to identify recurrence, combining time estimates from multiple code groups, and adjusting for systematic bias between code dates and recurrence dates. Improving the accuracy of time estimates for clinical events can facilitate research, quality measurement, and process improvement.

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INTRODUCTION

Enormous quantities of data are collected by administrative systems and electronic medical records (EMRs) during the routine delivery of health care. Increasingly, these data are being used for reasons other than just delivering care (EMR systems) and requesting reimbursement (administrative systems), including population health management; epidemiologic, comparative effectiveness, and outcomes research; quality measurement; and operational improvement. For many of these secondary uses, an essential first step is to identify which patients have a specific condition or have experienced a clinical event. When trying to identify these events, diagnosis and procedure codes are particularly helpful, because they are based on structured data elements (eg, International Classification of Diseases, 10th revision [ICD-10], Healthcare Common Procedure Coding System, Systematized

Nomenclature of Medicine) and they are used widely by EMRs and administrative systems.

However, extracting accurate and reliable clinical information from structured EMR/claims data can be challenging, because many different codes are entered by many different users. To determine who had a clinical event and when that event occurred, one must decide which codes to trust and figure out how to synthesize all the available information when many different codes have been documented. Algorithms that systematically address these challenges have been developed.¹⁻¹¹ For example, a breast cancer–detection algorithm concludes that any patient who has a claim associated with the C50 code (ICD-10) has breast cancer, and that the date of the first C50-associated claim is the date of the breast cancer diagnosis.¹²

Although many investigators have described methods for detecting who had a clinical event,

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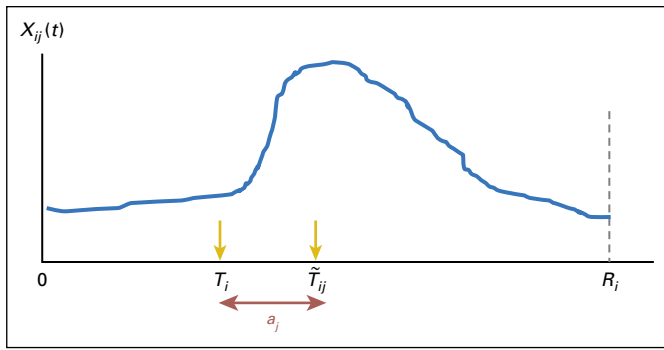


Fig 1. Illustration of a typical pattern of the trajectory of indicators. $X_{ij}(t)$ = longitudinal profile of a potential indicator j for subject i (eg, the trajectory of the count of diagnosis codes for secondary malignant neoplasm). 0 = start of the observation period (eg, initial cancer diagnosis). R_i = end of the observation period for subject i (eg, end of observation/follow-up time). T_i = time of the event occurrence for subject i (eg, cancer recurs). \tilde{T}_{ij} = time when a large gap in X_{ij} is observed (eg, the count of diagnosis codes for secondary malignant neoplasm per month increases more than a specified threshold compared with the previous months). a_j = an unknown parameter that takes account of the potential difference between the event occurrence time T_i and the time when the observed gap in X_{ij} is observed (\tilde{T}_{ij}).

approaches to characterize the timing of clinical events are underdeveloped. We hypothesized that existing event-detection algorithms could yield biased or inaccurate estimates of an event's timing for several reasons. First, there could be systematic differences between the date associated with a code used to detect an event and the date on which the event actually occurred. Second, the codes best suited to detect an event may differ from the codes best suited to determine the timing of that event. Third, if a patient does not have the code being used to characterize timing, then no timing estimate can be generated. If timing estimates are missing or inaccurate, then efforts to analyze the quality of care delivered to, outcomes experienced by, and costs associated with a condition could be biased.

Recurrence—the return of cancer in a patient who completed therapy for localized disease and was believed to have been disease free—is a critically important outcome for patients with cancer. Not surprisingly, recurrence has been the focus of many epidemiologic, comparative-effectiveness, and outcomes research studies.¹³⁻¹⁶ Although tumor registries reliably capture cancer diagnoses, they do not typically capture recurrence status. In previous articles, we described highly accurate algorithms that use claims or EMR data to detect recurrence for patients with lung, colorectal, and breast cancer.^{17,18} In this article, we build on that work by describing a systematic and reproducible method for determining the timing of cancer recurrence using structured data and developing tools that can be used to compare the performance of different timing estimation algorithms.

METHODS

Data Sources and Patient Sample

To develop and validate an algorithm that determines the timing of cancer recurrence, we used

two data sets that contained codes that could suggest when recurrence occurred linked to information describing when recurrence actually occurred. The Cancer Care Outcomes Research and Surveillance (CanCORS) Consortium was a large, prospective study of the care provided to and outcomes experienced by patients with lung or colorectal cancer diagnosed in 2003 to 2005 and followed through 2011.¹⁹ Medical record abstract data from CanCORS (used to identify gold-standard recurrence status) were linked to Medicare fee-for-service claims from 2002 to 2011 (used to estimate the timing of recurrence).²⁰ The Cancer Research Network (CRN) is a consortium of health maintenance organizations (HMOs) affiliated with the HMO Research Network. Two CRN sites have certified tumor registrars collect recurrence status data: Kaiser Permanente Colorado, Denver, Colorado, and Kaiser Permanente Northwest, Portland, Oregon. The CRN also maintains a Virtual Data Warehouse (VDW)¹ that links tumor registry data (used to identify gold-standard recurrence status) with diagnosis and procedure codes documented in an EPIC-based EMR and with claims for services delivered by contract providers (used to estimate the timing of recurrence).

Gold-standard recurrence status was ascertained through manual abstraction of the medical record by study personnel (for CanCORS) or the tumor registry (for the CRN) and recorded using the North American Association of Central Cancer Registry's cancer status variable. To estimate the timing of recurrence, we used diagnosis and procedure codes associated with the following events: secondary malignant neoplasm involving a solid organ site, secondary malignant neoplasm involving either a solid organ or lymph node site, chemotherapy, radiotherapy, hospice, high-cost imaging, cancer symptoms, narcotic/pain medications, inpatient encounters, observation encounters, emergency department encounters, and any procedure. The codes represented commonly used data standards: ICD-9th Revision—Clinical Modification, Current Procedural Terminology 4th Edition, Healthcare Common Procedure Coding System, National Drug Codes, Diagnosis-Related Groups, Berenson-Eggers Type of Service, and facility revenue centers (Data Supplement).^{1,3,21} Codes were extracted from all available Medicare files and from procedure, diagnosis, encounter, pharmacy, and infusion files from the VDW.^{22,23} The

Table 1. Estimates of Offset Parameters and Average Absolute Prediction Errors for Each Indicator Variable Using Cancer Care Outcomes Research and Surveillance/ Medicare Data for Patients With Recurrent Lung Cancer

Indicator	Offset Parameter Estimate (months)	Average Absolute Prediction Error* (months)
Secondary malignant neoplasm (solid organ and lymph node sites)	0.2	5.4
Secondary malignant neoplasm (solid organ sites only)	0.2	5.2
Receipt of chemotherapy	1.2	5.9
Radiotherapy events	1.3	6.7
Hospice encounters	3.8	7.1
High-cost imaging	-0.9	5.6
Diagnosis codes for cancer symptoms	0.3	7.5
Dispenses of narcotic/pain medications	-0.7	6.3
Inpatient stays	-0.8	6.4
Observation stays	7.4	7.1
Emergency department encounters	-2.2	8.4
Any procedure	-0.20	8.1
Naive prediction	NA	6.7

*For patients in whom an indicator did not generate a predicted time of cancer recurrence, the missing predicted time was imputed using the naive prediction rule ($R_i/2$ = the half time of the given time window) before calculating the average absolute prediction error for that indicator variable. Abbreviation: NA, not applicable.

claim through date or the discharge date was used to assign a date to each code. The primary sample included 308 patients with stage I to IIIa lung cancer from CanCORS/Medicare, of whom 89 (29%) developed recurrence. In secondary analyses, we determined the timing of recurrence using CanCORS/Medicare data for 600 patients with colorectal cancer (14% developed recurrence), CRN/VDW data for 792 patients with lung cancer (27% developed recurrence), and CRN/VDW data for 2,827 patients with colorectal cancer (13% developed recurrence).¹⁷ The institutional review boards from Dana-Farber and the participating Kaiser Permanente sites provided project oversight.

General Approach

Month was chosen as the unit of analysis, because it was the most granular level for which we could ascertain changes in claims over time. Let $[0, R_i]$ be a time window for subject i ($i = 1, \dots, n$). We assumed that each subject experienced a clinical event within this time window. Let $T_i \in [0, R_i]$ denote the actual recurrence time. Consider J kinds of indicators, let $X_{ij}(t)$, ($i = 1, \dots, n; j = 1, \dots, J$) be a nonnegative function

defined on the domain $[0, R_i]$. We consider the case that there exists such that $X_{ij}(t)$ takes a large change around or after T_i . For example, suppose we are interested in detecting the time of cancer recurrence. The trajectory of the count of codes for secondary malignant neoplasm between time 0 and R_i would be an example of $X_{ij}(t)$, because the incidence of such codes would increase around recurrence. For additional explanation of the identification problem, let $X_{ij}^*(t)$ be the perfect identifier in the sense that $X_{ij}^*(t) = I(T_i = t)$ or $I(T_i \leq t)$ for all i , where $I(\cdot)$ is the indicator function. With $X_{ij}^*(t)$, we could accurately identify T_i for each subject by finding the smallest t when $X_{ij}^*(t) = 1$. Of course, a perfect identifier $X_{ij}^*(t)$ does not exist, but we assume there exist several $X_{ij}(t)$'s that behave as such. Specifically, in our notation, we consider J kinds of indicators, $X_{ij}(t)$, $j = 1, \dots, J$, for each subject ($i = 1, \dots, n$). Here we are interested in deriving an algorithm to identify the timing of the event T_i for each subject, integrating information from the $X_{ij}(t)$'s.

Figure 1 illustrates a typical pattern of $X_{ij}(t)$ we use to identify T_i . In this example, we see a large increase in $X_{ij}(t)$ at $\tilde{T}_{ij} = T_i + a_j$, where a_j is an unknown offset parameter that takes account of the potential difference between the event occurrence time T_i and the time, \tilde{T}_{ij} , when we observe a large change in $X_{ij}(t)$. In this example, a_j denotes the delay between when the event occurred and when it was reflected in $X_{ij}(t)$. Note that a_j can be positive or negative, depending on the temporal relationship between the event and the indicator. After deriving a best estimate for T_i from the trajectory of $X_{ij}(t)$, $i = 1, \dots, n$ for each j ($j = 1, \dots, J$), the proposed method integrates the $\{\hat{T}_{i1}, \hat{T}_{i2}, \dots, \hat{T}_{iJ}\}$ (where $\{\hat{T}_{i1}, \hat{T}_{i2}, \dots, \hat{T}_{iJ}\}$ denotes a set of estimators for T_i for subject i ($i = 1, \dots, n$)) to derive an algorithm that gives a single T_i estimate for each subject

Derivation of Estimates

From here on, we assume $X_{ij}(t)$ is a nonnegative, discrete function of time. We also assume that t is discrete and takes on the values 0, 1, 2, ... Let $K_{ij}(t) = \sum_{k=0}^t X_{ij}(k)$ be the cumulative function of $X_{ij}(\cdot)$ at t . We then standardize $K_{ij}(t)$ by t and calculate:

$$L_{ij}(t) = \frac{K_{ij}(t)}{t},$$

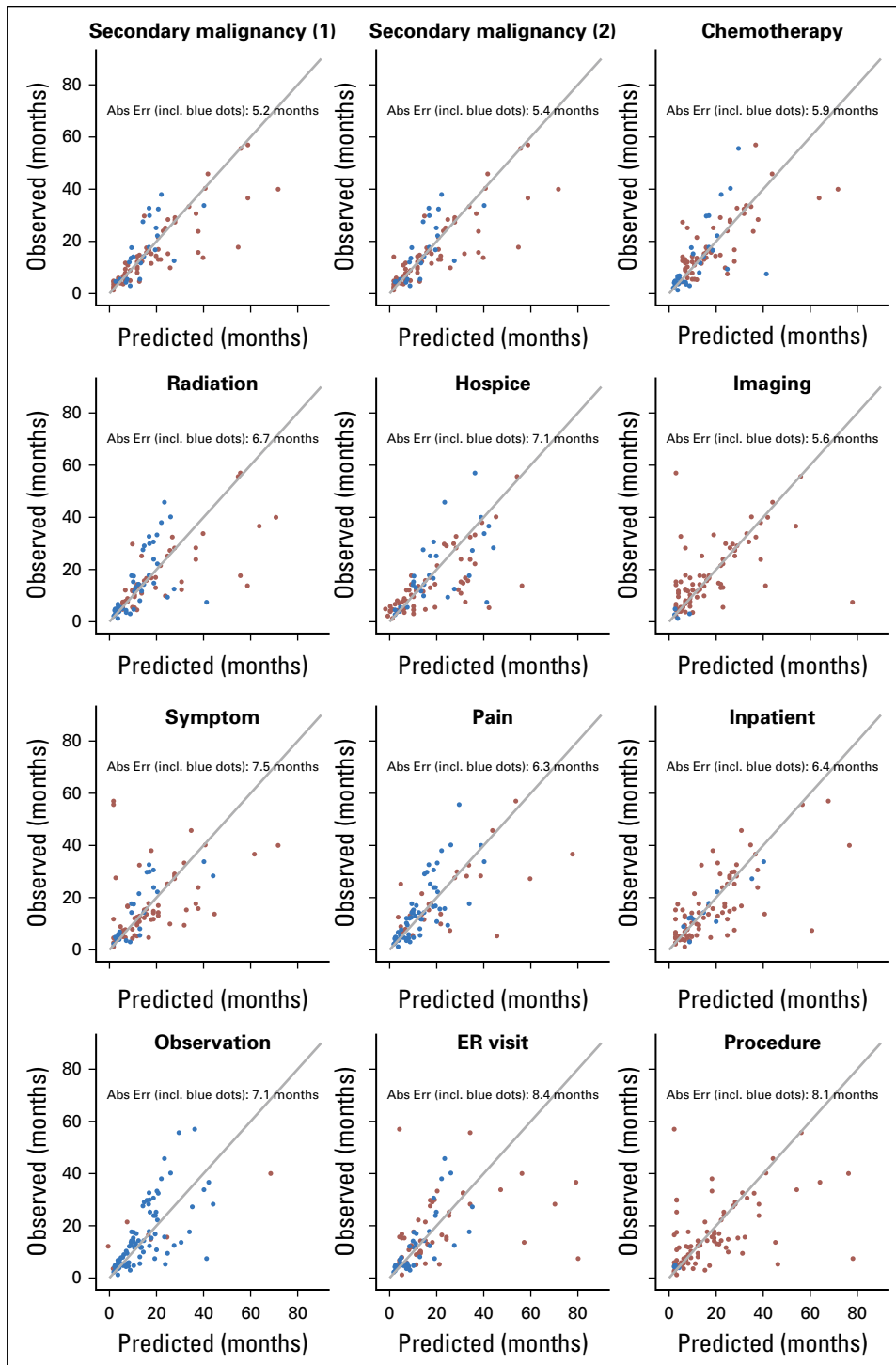


Fig 2. Scatter plots of the predicted time of recurrence and the observed time of recurrence, in months after definitive local therapy, for each indicator variable using Cancer Care Outcomes Research and Surveillance/Medicare data for patients with lung cancer. Secondary malignancy (1): secondary malignant neoplasm codes without lymph node sites of disease. Secondary malignancy (2): secondary malignant neoplasm codes including lymph node sites of disease. Red dots indicate subjects for whom the indicator variable produced a predicted time of recurrence. Blue dots indicate the subjects for whom the indicator variable produced no predicted time of recurrence, so the predicted time of recurrence displayed in the figure was estimated by the naïve prediction rule (ie, $R/2$; the half time of the given time window). Abs Err, absolute error; ER, emergency room; incl, including.

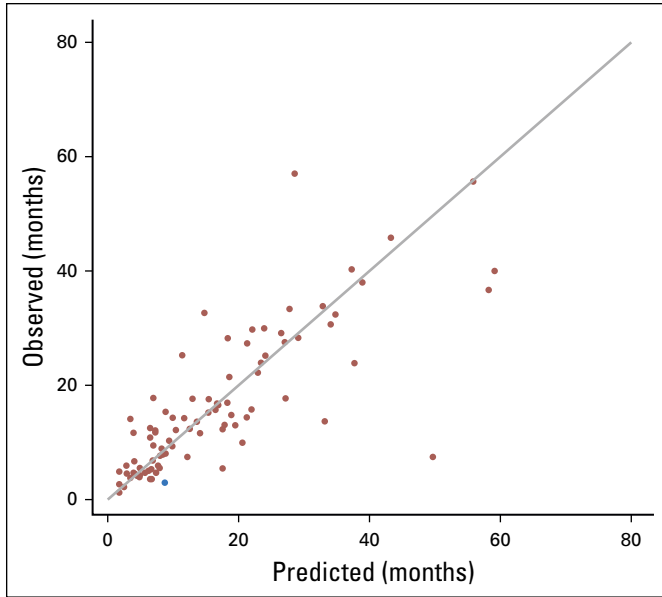


Fig 3. Scatter plot between the predicted time of recurrence and the observed time of recurrence for the final model using Cancer Care Outcomes Research and Surveillance/Medicare data for patients with lung cancer, in months after definitive local therapy. Red dots indicate subjects for whom the indicator variable produced a predicted time of recurrence. The blue dot indicates the subject whose predicted time of recurrence was estimated by the naive prediction rule (ie, $R/2$; the half time of the given time window).

where $L_{ij}(t)$ can be viewed as the average speed of the increment in $X_{ij}(t)$ per unit time. We derive the difference of $L_{ij}(t)$ with respect to time, to capture the time corresponding to the largest increase in the average speed. Specifically, at each t , we calculate

$$b_{ij}(t) = \frac{\{L_{ij}(t) + \varepsilon\} - \{L_{ij}(t-1) + \varepsilon\}}{\{L_{ij}(t-1) + \varepsilon\}},$$

For $(t = 1, 2, \dots)$, where $\varepsilon = 1$, which is added to avoid division by 0. Note that $b_{ij}(t)$ is a change in the average speed of rising codes per unit time, which can be viewed as an acceleration rate of $X_{ij}(t)$. We then extract the time point when $b_{ij}(t)$ takes the maximum for the first time within the given time window

$$\tilde{T}_{ij} = \min\{\operatorname{argmax}_t b_{ij}(t)\}.$$

As illustrated in Figure 1, because we model $\tilde{T}_{ij} = T_i + a_j$, we then estimate the unknown parameter a_j for each j , from the observed data (T_i, \tilde{T}_{ij}) . In our empirical example, we used the median, rather than the mean, because of its robustness to extreme values. Let \hat{a}_j be the empirical counterpart for a_j . The estimated event time, T_i , from the trajectory of the j -th indicator is then given by

$$\hat{T}_{ij} = \tilde{T}_{ij} - \hat{a}_j.$$

We perform this procedure for each of the J indicators. Note that when $b_{ij}(t)$ is 0 for all t , we replace \tilde{T}_{ij} and \hat{T}_{ij} by missing values.

Now we integrate the multiple estimated times $\{\hat{T}_{i1}, \hat{T}_{i2}, \dots, \hat{T}_{iJ}\}$ and derive a single value for each subject. Let ξ_{ij} be the indicator variable for i -th subject and j -th indicator, which takes 1 if \hat{T}_{ij} is not missing and 0 otherwise. We derive the integrated estimated time for T_i through

$$\hat{T}_i = \frac{\sum_{j=1}^J \hat{T}_{ij} \xi_{ij} W_j}{\sum_{j=1}^J \xi_{ij} W_j},$$

where W_j indicates a weight for the j -th indicator. Because the estimated time with smaller deviation from the observed recurrence time is more reliable, we determine W_j by the reciprocal of the variance of \hat{T}_{ij} across n subjects. From a practical perspective, we used a trimmed variance instead to reduce the impact of a small number of extreme values in \hat{T}_{ij} on the weight W_j . Specifically, we empirically determined to exclude the top and bottom 3% when calculating the variance. When \hat{T}_{ij} is missing for all j , we substitute the naive prediction $R/2$ to \hat{T}_i .

Variable Selection and Algorithm Assessment

Several standard measures quantify the performance of prediction models for continuous variables. For example, the average absolute prediction error is given by

$$\hat{D}_1 = n^{-1} \sum_{i=1}^n |T_i - \hat{T}_i|,$$

and the average squared error is given by

$$\hat{D}_2 = n^{-1} \sum_{i=1}^n (T_i - \hat{T}_i)^2$$

One may standardize these measures by taking the width of the time window into account. The standardized versions of these measures are given by $\bar{D}_1 = n^{-1} \sum_{i=1}^n |T_i - \hat{T}_i| / R_i$ and $\bar{D}_2 = n^{-1} \sum_{i=1}^n \{(T_i - \hat{T}_i) / R_i\}^2$, respectively. Also, for a given cutoff value, we can estimate a correct classification rate by:

$$\hat{D}_{CCR}(c) = n^{-1} \sum_{i=1}^n I\{|T_i - \hat{T}_i| < c\}.$$

To adjust for the optimistic bias that is generally included in these substitution performance estimates, we use a Monte Carlo cross-validation procedure to estimate performance metrics for each of the 4,095 (ie, $2^{12} - 1$) candidate algorithms. Specifically, we randomly split the data into two equally sized groups, use one to determine the unknown parameters included in T_i , and

Table 2. Comparative Algorithm Performance for Lung Cancer Recurrence Timing Using Cancer Care Outcomes Research and Surveillance/Medicare Data

Measure of Performance	Our Final Algorithm	Secondary Malignancy Codes		Chemotherapy Only		High-Cost Imaging Only	
	Result	Result	Difference v Ours	Result	Difference v Ours	Result	Difference v Ours
Performance*							
\hat{D}_1 (months)	4.8	6.3	1.5	6.2	1.4	5.6	0.9
\tilde{D}_1 (%)	16.2	21.8	5.6	20.9	4.7	20.6	4.4
Correct classification, cumulative %							
± 1 month	34.8	29.2	-5.6	20.2	-14.6	29.2	-5.6
± 2 months	42.7	41.6	-1.1	32.6	-10.1	43.8	1.1
± 3 months	57.3	56.2	-1.1	50.6	-6.7	55.1	-2.2
± 4 months	61.8	62.9	1.1	60.7	-1.1	61.8	0.0
± 5 months	70.8	66.3	-4.5	61.8	-9.0	64.0	-6.7
± 6 months	75.3	68.5	-6.7	68.5	-6.7	69.7	-5.6

* \hat{D}_1 is the average absolute error, and \tilde{D}_1 is the standardized version of \hat{D}_1 where the absolute prediction error is divided by the width of the observed time window (see Methods).

use the other to estimate the performance metric. We then repeated this process M times and took the average. For example, the cross-validation estimate for the average absolute prediction error is given by

$$\hat{D}_1^* = M^{-1} \sum_{m=1}^M \left\{ n_m^{-1} \sum_{i \in \Theta_m} \left| T_i - \hat{T}_i^{(\Theta_m)} \right| \right\},$$

where $\bar{\Theta}_m$ and Θ_m are the disjoint subsets created by the m -th random split—the former is used to estimate the unknown parameters of the algorithm, and the latter is used to calculate the performance. Here, $\hat{T}_i^{(\Theta_m)}$ denotes the estimate for T_i when it is derived without using the data elements in Θ_m . Such a cross-validation estimate for selected performance metrics can be used to choose a final algorithm from the several candidate algorithms. Confidence intervals for performance metrics are calculated via a standard bootstrap method.

RESULTS

First, we applied this method to patients with recurrent lung cancer from the CanCORS/Medicare data set. Table 1 shows the offset parameters and absolute prediction errors for 12 indicators. A negative offset parameter indicates

that the peak in the code count was observed before the event occurrence. For example, the offset parameter for the imaging codes was -0.9 months. This is expected, because imaging is often performed to evaluate symptoms before a biopsy is done and recurrence is confirmed. On the other hand, the offset parameter for chemotherapy was positive (0.2 months), which is also reasonable, because chemotherapy is a consequence of having recurrent cancer.

Figure 2 shows scatter plots between the predicted and the observed time of recurrence for 89 patients with recurrent disease across all 12 indicators. The blue dots indicate patients in whom the naive prediction was used because the predicted time was not determined by the corresponding code group. The estimated absolute prediction error analysis shows that secondary malignant neoplasm involving solid organ sites was the strongest indicator among the 12; the corresponding absolute prediction error was 5.2 months. As a reference, the absolute prediction error on the basis of the naive prediction was 6.7 months (Table 1).

To select the final algorithm, we examined all possible combinations of the 12 indicators $\{\hat{T}_{11}, \hat{T}_{12}, \dots, \hat{T}_{112}\}$ and calculated the average

Table 3. Components and Performance Characteristics of Timing Estimation Algorithms for Two Cancers Using Two Data Sets

Data Source	CanCORS/Medicare		CRN/VDW	
	Lung Cancer	Colorectal Cancer	Lung Cancer	Colorectal Cancer
No. of patients with recurrence	89	84	216	355
Variables included in timing algorithm, offset in months* (weight)†				
Secondary malignancy‡	0.2 (0.279)	−0.1 (0.387)	0.9 (0.264)	1.8 (0.297)
Chemotherapy	1.2 (0.296)	3.7 (0.500)	1.6 (0.379)	2.6 (0.460)
Imaging	−0.9 (0.425)	−1.1 (0.113)	−0.5 (0.357)	−0.6 (0.243)
Average absolute error, months	4.8	4.8	4.9	5.4
Standard error, %§	16.2	13.4	15.2	13.7
Correct classification, cumulative No. (%)				
≤ 1 month	31 (34.8)	18 (21.4)	81 (37.5)	80 (22.5)
≤ 2 months	38 (42.7)	34 (40.5)	110 (50.9)	149 (42.0)
≤ 3 months	51 (57.3)	44 (52.4)	127 (58.8)	188 (53.0)
≤ 4 months	55 (61.8)	57 (67.9)	142 (65.7)	211 (59.4)
≤ 5 months	63 (70.8)	62 (73.8)	155 (71.8)	236 (66.5)
≤ 6 months	67 (75.3)	68 (81.0)	160 (74.1)	254 (71.5)
6 months	22 (24.7)	16 (19.0)	56 (25.9)	101 (28.5)

Abbreviations: CanCORS, Cancer Care Outcomes Research and Surveillance; CRN, Cancer Research Network; VDW, Virtual Data Warehouse.

*The offset represents the average of the difference between the time when the component variable count peaked and the time of the gold-standard recurrence. Negative values indicate that the peak in the component variable was before the gold-standard recurrence date.

†The weight is the amount a component variable's estimated recurrence date contributed to estimated date of recurrence.

‡For the CanCORS/Medicare population, this variable included secondary malignancy codes for both solid organ and lymph node sites, whereas for the CRN/VDW sample, this variable included secondary malignancy codes only for solid organ sites (ie, excluding lymph node sites).

§The average absolute error in months divided by the average duration of follow-up in months.

absolute prediction error for each one, selecting the combination of indicators, weights, and offset parameters that offered the best performance. The indicators in the final selected algorithm and their relative weights were: secondary malignant neoplasm involving solid organ or lymph node sites (0.279), chemotherapy (0.296), and high-cost imaging (0.425). [Figure 3](#) shows a scatter plot of the 89 patients with recurrent disease, with the predicted time of recurrence on the basis of the final model plotted against the observed time of recurrence. The estimated absolute prediction error was 4.8 months (0.95 CI, 3.5 to 6.3). The correct classification rate (\pm 3-month time window) was 57.3% (0.95 CI, 47.2% to 67.4%). Model performance was compared with three alternatives: secondary malignancy involving either solid organ or lymph node sites only, chemotherapy only, and high-cost imaging only. The absolute prediction error of

our algorithm was better (ie, smaller) than any of the single indicator-based alternatives ([Table 2](#)).

To evaluate this technique in other cancers using data from other sources, we applied the same method to colorectal cancer cases from CanCORS/Medicare and to lung and colorectal cancer cases from the CRN/VDW. Whether using claims data from CanCORS/Medicare or EMR data from the CRN/VDW, and whether detecting recurrence after a colorectal or lung cancer diagnosis, the same three code groups were part of the final algorithm ([Table 3](#)). Although the directionality of the offsets was similar, the weights for the codes varied somewhat across the four algorithms.

DISCUSSION

Compared with the methods used to detect which patients experience an event, the methods used

to determine the timing of an event have been underdeveloped. Historically, timing estimation algorithms have relied on only one code (eg, secondary malignancy) or a small set of homogeneous codes (eg, chemotherapy). We found that using just one code yielded estimates that tended to be less accurate and meant that many patients had no timing estimate. A key strength of our approach is the use of multiple complementary code sets. Of 89 patients with recurrent lung cancer in CanCORS/Medicare, our algorithm provided a timing estimate for all but one subject. Also, in situations where the algorithm does not derive a timing estimate, we describe a straightforward imputation method on the basis of the time half way between the original cancer diagnosis and the end of follow-up.

Timing estimation algorithms often assume that the dates of the codes used to detect events can also be used to determine the timing of events. We found that the codes best suited to determine the timing of an event were not necessarily the same as the codes best suited to detect who had an event. For example, hospice was part of the model that determined who had recurrence but not part of the model that determined when recurrence occurred.¹⁷ Also, imaging was a relatively weak predictor of developing recurrence but a strong factor when estimating the timing of recurrence. The date associated with the code in claims/EMR-based systems often differed systematically from the actual recurrence date, and the directionality of this difference made intuitive sense.

Limitations of our approach include that it is more complex than previous techniques.¹² Also, the accuracy of timing estimates still remains suboptimal for a meaningful subset of patients. Although estimates were within a few months for most patients, one quarter had estimates with an average absolute error > 6 months, and model performance was only 2 months better

than the naïve estimate. We are not aware of methods that derive more accurate estimates. No standard threshold for optimal accuracy has been defined, but we believe better timing estimates are needed. Caution should be taken when using most existing timing estimation algorithms. An inaccurate timing estimate could lead to the inappropriate inclusion of expenditures in an episode of care or a biased estimate of an outcome (ie, recurrence-free survival) in a comparative effectiveness research study.

The tools that we developed to determine the timing of recurrence for patients with lung and colorectal cancer can be applied to other data sources (eg, SEER-Medicare, CancerLinQ), and the methodology that we described can be used to determine the timing of other cancers or other events. In fact, we have already used this technique to estimate the timing of recurrence for patients with breast cancer.¹⁸ Although our approach relied on claims- and EMR-based data sources, it could easily incorporate other data types too. For example, natural language processing could be used to convert unstructured text into structured format, and then our methodology could be used to combine natural language processing- and claims-based information to generate a refined timing estimate. Having consistent methods for assessing the performance of timing-estimation algorithms offers important advantages to those who develop and use these tools. Regardless, efforts to develop better timing estimation algorithms are still warranted. The need for accurate timing estimates will continue to grow as the use of clinical and administrative data for quality measurement, clinical research, and reimbursement expands.

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The following represents disclosure information provided by authors of this manuscript. All relationships are considered compensated. Relationships are self-held unless noted. I = Immediate Family Member, Inst = My

Institution. Relationships may not relate to the subject matter of this manuscript. For more information about ASCO's conflict of interest policy, please refer to www.asco.org/rwc or ascopubs.org/jco/site/ifc.

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