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Cardiac Magnetic Resonance Fingerprinting: Technical Overview and Initial Results

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Abstract

Cardiovascular Magnetic Resonance (CMR) is a versatile tool that enables non-invasive characterization of cardiac tissue structure and function. Parametric mapping techniques have allowed unparalleled differentiation of pathophysiological differences in the myocardium such as the delineation of myocardial fibrosis, hemorrhage and edema. These methods are increasingly employed as part of a tool kit to better characterize disease states such as cardiomyopathies and coronary artery disease. Currently conventional mapping techniques require separate acquisitions for T_1 and T_2 mapping, the values of which may depend on specifics of the MRI system hardware, pulse sequence implementation and physiologic variables including blood pressure and heart rate. The cardiac Magnetic Resonance Fingerprinting (cMRF) technique has recently been introduced for simultaneous and reproducible measurement of T_1 and T_2 maps in a single scan. The potential for this technique to provide consistent tissue property values independent of variables including scanner, pulse sequence and physiology could allow an unbiased framework for the assessment of intrinsic properties of cardiac tissue including structure, perfusion and parameters such as extracellular volume (ECV) without the administration of exogenous contrast agent. This review seeks to introduce the basics of the cMRF technique, including pulse sequence design, dictionary generation, and pattern matching. The potential applications of cMRF in assessing diseases such as non-ischemic cardiomyopathy will also be briefly discussed, and ongoing areas of research described.

Keywords

MR fingerprinting; CMR; parametric mapping; T_1 mapping; T_2 mapping

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Introduction

Cardiovascular Magnetic Resonance (CMR) is a valuable and versatile tool to characterize myocardial tissue and assess cardiac function non-invasively. Anatomical images acquired using FLASH (fast low angle shot) or SSFP (steady-state free precession) sequences are widely used to measure the chamber size, myocardial mass, and ejection fraction. Quantitative imaging can also be performed to provide T_1 and T_2 relaxation times that may shed light on intrinsic tissue properties. Such parametric maps have been shown to be more sensitive to a variety of pathological tissue changes than anatomical images (1–6). Changes in native myocardial T_1 values for instance may reflect underlying pathological changes including infarction, inflammation and area at risk (4–6). Contrast-enhanced T_1 measurements combined with native T_1 mapping have been used to estimate extracellular volume fraction (ECV), which may change in the presence of diffuse fibrosis or deposition of amyloid fibrils that may be otherwise hard to detect or quantify (7–9). Myocardial T_2 maps may provide information on myocardial edema (10,11) which may occur in the context of injury, infarction or inflammation (12,13). Furthermore, changes in T_1 parameters in response to pharmacologic vasodilation without administration of contrast may allow non-contrast stress imaging (14).

In light of this unprecedented utility of T_1 and T_2 mapping for the non-invasive characterization of myocardial disease states, significant effort has been devoted to developing fast and accurate T_1 and T_2 mapping techniques. Most current techniques perform T_1 and T_2 mapping in separate scans, and the values in these maps may be dependent on field strength, pulse sequence and physiological parameters such as heart rate and blood pressure. Measuring T_1 and T_2 rapidly in an unbiased fashion during the same scan may provide distinct advantages compared to current approaches (15–18). Cardiac Magnetic Resonance Fingerprinting (cMRF) has recently been proposed to map multiple properties such as T_1 , T_2 , and proton density simultaneously in the heart (19). This technique is based on the general Magnetic Resonance Fingerprinting (MRF) framework, which was originally introduced to map tissue properties in the brain (20,21). cMRF has a number of features which make it advantageous over traditional T_1 and T_2 mapping techniques. For instance, many traditional mapping techniques require complete recovery or decay between imaging periods, and errors can arise when waiting periods are insufficient for complete relaxation (i.e. due to scan time or breath hold limitations). As cMRF does not rely on complete recovery of magnetization, it has the dual advantage of a shorter scan time as well as the potential to provide more accurate and reproducible T_1 and T_2 values. Second, cMRF is potentially immune to heart rate dependent bias which has been reported in cardiac T_1 mapping methods such as MOLLI (22), because variations in heart rate are taken into account when extracting tissue property maps from cMRF data. Most importantly, MRF may be useful in characterizing tissue properties beyond T_1 and T_2 , such as perfusion (23), diffusion (24), fat fraction (25), T_2^* (26,27), and ECV without the administration of exogenous contrast agents (28). Indeed, MRF can also be used to map system properties including B_1 (29) and off-resonance (20), and this ability can be harnessed to remove the confounding effect of these system parameters on tissue parametric maps. cMRF thus has

the potential to yield reproducible measurements of tissue properties independent of scanner, software and physiologic variables.

This review introduces the basic idea behind cMRF, including pulse sequence design, dictionary generation, and pattern matching. Experiments and results demonstrating the potential power of cMRF in phantoms and *in vivo* are described, and emerging techniques for further improving the speed, accuracy, and mapping capabilities of cMRF discussed. Finally, potential clinical applications of cMRF are briefly reviewed.

Current Approaches to Cardiac Tissue Parametric Mapping

In the heart, fast T_1 mapping techniques commonly used in routine clinical exams such as MOLLI (22,30) and SASHA (31) generate T_1 maps in a single breath-hold by acquiring a series of images following either an inversion or a saturation pulse (the function of which is to sensitize the signal to T_1). ECG triggering is used to restrict the acquisition window to a short period, often in end diastole, to avoid artifacts due to cardiac motion. In the example of a commonly used variant of MOLLI, the so-called 5(3)3 version, an initial inversion pulse is applied, followed by the collection of five images in five separate heartbeats with different T_1 weightings. The magnetization is allowed to recover in the following three heartbeats, and then a second inversion pulse is played out with image acquisition in the next three heartbeats. The result is a total of eight T_1 -weighted images, each at a different inversion time. The signal for each pixel over time from the series of images is then fit to an exponential function to estimate the T_1 value. This fitting process is repeated for each pixel to generate a spatial map of estimated T_1 values. Common T_2 mapping techniques take a similar approach and use either a fast spin echo or gradient spin echo readout, or T_2 preparation pulses followed by a gradient echo (bSSFP or FLASH) readout to generate images with different T_2 -weightings along the T_2 decay curve. T_2 maps are calculated by fitting the decay time courses for each pixel to an exponential function (32–34). These standard cardiac T_1 and T_2 mapping techniques rely on the assumption that acquired signals follow an exponential recovery (T_1) or decay (T_2) curve; however, incomplete longitudinal magnetization recovery due to a rapid or variable heart rate may cause deviations from the assumed exponential curve, leading to inaccuracies in the measured T_1 or T_2 maps (22,32). One potential solution to obtain T_1 maps in the presence of heart rate variations is to model the deviation of the signal evolution from the expected exponential form using Bloch equation simulations (35); while this approach can provide improved T_1 maps, the similarity of different exponential curves to one another may result in residual errors in the T_1 maps. An additional drawback to conventional parametric mapping approaches is that it is challenging to generate images which are sensitive to only one tissue property a time. For instance, in T_1 mapping, confounding factors including T_2 , off-resonance effects, and magnetization transfer (MT) can lead to errors in the resulting tissue parametric maps. Interested readers are referred to the following excellent review articles regarding the technical details and clinical applications of these methods (5,6,36,37).

In addition to mapping T_1 or T_2 separately, joint T_1 and T_2 mapping techniques have also been explored (15–18). These methods play out T_1 preparation pulses (saturation or inversion) and T_2 preparation pulses in either interleaved R-R intervals (15,17,18) or the

same R-R interval (16) to sensitize signals to both T_1 and T_2 simultaneously. However, like MOLLI, most of these methods are still limited by the reliance on a simple signal model (such as an exponential form), which constrains the type of pulse sequences which can be used and introduces errors when the acquisition timing is variable (i.e. due to heart rate changes) (15,18).

MRF Basics

MRF takes a radically different approach to parametric mapping compared to the traditional methods discussed above. In MRF, a pulse sequence with variable sequence timings and/or RF strengths is used which sensitizes the signal to multiple tissue properties simultaneously. The goal of the MRF pulse sequence is to force tissues with different tissue properties, i.e. T_1 and T_2 values, to produce distinguishable signals. In other words, the signal time courses from different tissues should be unique due to differences in their T_1 and/or T_2 values.

Data are first collected using a pulse sequence designed to impart unique signal time courses to tissues with different T_1 and T_2 values. Following data collection, the next step is to link the signal time courses for each pixel to the appropriate T_1 or T_2 values. In MRF, this step is often performed using a dictionary matching technique. First, a discrete set of possible T_1 and T_2 values is selected that covers the range of relaxation times that are typically found *in vivo*. For each pair of T_1 and T_2 values, the signal time course that would result from the application of the MRF pulse sequence is calculated using the Bloch equations (the equations which dictate the behavior of MRI signals as a function of the sequence parameters, timing, and tissue properties). Each time course is saved to make a dictionary of the possible signal evolutions that could have resulted from the applied pulse sequence. Finally, the measured signal time course for each pixel is compared to the dictionary; the T_1 and T_2 values used to make the dictionary entry that best fits the measured data are assigned as the T_1 and T_2 values for that pixel. When this process is repeated for each pixel, the results are quantitative maps showing the T_1 and T_2 values for each pixel (Figure 1).

MRF for Cardiac Tissue Characterization

Although previous work has demonstrated the accuracy and efficiency of MRF in stationary organs such as the brain and prostate (20,21,38), the use of MRF for parametric mapping in the heart is more challenging given cardiac and respiratory motion. In order to reduce motion artifacts, data are acquired during end-diastole with ECG triggering and during a single breath-hold. Thus, unlike in conventional MRF where the pulse sequence is played out continuously, signal encoding and data acquisition are interrupted in cMRF. As a consequence of this “dead time”, the time courses of tissues with similar T_1 and T_2 values may be more difficult to differentiate than when using a continuous pulse sequence. To address this challenge, more preparation modules are employed in cMRF to encode T_1 and T_2 information as compared to the original MRF techniques used in stationary organs. Another result of the interrupted pulse sequence is that the exact timing of each cMRF sequence will change, depending on the subject’s heart rate, and thus a new cMRF dictionary with the appropriate timings must be generated following each scan. Finally, the total data collection time in a cMRF scan is limited to the length of a breath-hold, and thus

the pulse sequence must enable the collection of as much signal as possible while also differentiating between different tissues.

Pulse sequence

In order to mitigate artifacts caused by respiratory and cardiac motion, the cMRF pulse sequence is designed to acquire data at end-diastole during a breath-hold. While several different cMRF variants have been employed, the longest sequence (and thus the longest breath-hold) has been limited to 16 heartbeats (19). The cMRF pulse sequences used to date employ a FISP (fast imaging with free precession) readout with no RF phase cycling, instead of the originally proposed bSSFP readout. Unlike the bSSFP readout, FISP uses an unbalanced spoiler gradient in the slice select direction, making this sequence relatively insensitive to off-resonance effects. In cMRF, data are collected in a specified window (between 120–250ms) during diastole to avoid artifacts due to cardiac motion. The number of data collection phases in a single heartbeat is designed such that the total acquisition time ($TR \times$ data collection phases) is less than this specified acquisition window. In each data collection phase, lasting one TR, one interleaf of a variable density spiral trajectory is used to acquire data. The spiral interleaf is rotated by the golden angle (111°) in each data collection phase to ensure that the aliasing artifacts from undersampling take on a noise-like appearance in the signal time course, facilitating the pattern matching step to find the correct T_1 and T_2 values.

The data collection for the original implementation of cMRF (19) is performed over 16 heartbeats, divided into four segments of four heartbeats each (Figure 2). In each segment, a specific pattern of magnetization preparation pulses is performed to improve the sensitivity of the sequence to T_1 and T_2 . A non-selective inversion pulse is applied in the first heartbeat, and T_2 -preparation pulses with echo times of 40 ms and 80 ms are employed in the third and fourth heartbeats. No magnetization preparation is used in the second heartbeat. This 4-heartbeat pattern is repeated four times, where the inversion times used in the first heartbeat of the segments vary from 21 to 400 ms. If the subject's heart rate is too fast for the longest inversion time to fit within one cardiac cycle, then the inversion times are shortened. Sinusoidally varying flip angles and variable TRs of 5.1 to 6.1 ms are used.

One advantage of the MRF framework is the extreme flexibility in pulse sequence design. As long as a pulse sequence causes different tissues to exhibit signal time courses that are distinguishable, it can be used for MRF; given the same sensitivity to confounding factors, the T_1 and T_2 measurements made with one sequence should be reproducible with other embodiments of MRF. Ideally, MRF signal time courses are only governed by tissue properties such as T_1 and T_2 in a given pulse sequence. However, changes in physiological properties which the user may not anticipate, such as heart rate or blood pressure, may influence the signal time course and act as confounding factors. Ideally, the pulse sequence should be designed to avoid sensitivity to these confounding factors or enhance it, such that it can be mapped along with the desired tissue properties. Additionally, other system errors such as imperfect slice profile and B_1^+ inhomogeneity, may cause the acquired signal time courses to deviate from the ideal case.

Since the original implementation of cMRF was proposed, other pulse sequence designs have been considered to accelerate the measurement of T_1 and T_2 in the myocardium and reduce errors due to confounding factors. Based on this work (39), it has been found that minor alterations to the timing and number of preparation pulses do not significantly impact the measurements made with cMRF. However, these pulse sequences, when used in phantom and *in vivo* experiments, may result in inaccurate T_1 and T_2 maps if the appropriate confounding factors are not taken into account (see Dictionary Generation, below). Importantly, many pulse sequences offer equivalent encoding power and insensitivity to confounding factors, and some offer supplementary benefits. For instance, in addition to the 16 heartbeat, 4-segment scheme described in the original cMRF sequence, a 15-heartbeat, 5-segment scheme has also been tested; this 5-segment schedule may be advantageous because it can be easily shortened to a 5-heartbeat scan (see below). In this 15-heartbeat, 5-segment scheme, T_2 -preparation pulses were employed in the third, fourth, and fifth heartbeats in each segment with echo times of 30 ms, 50 ms, and 80 ms. Data are collected with a constant TR of 5.1 ms and ramped flip angles between 4° to 25° are used. Both the 16-heartbeat sequence and the 15-heartbeat sequence show good agreement *in vivo* with conventional cardiac T_1 and T_2 measurements; however, it should be noted that there are numerous options for possible sequences besides these two examples. The optimal implementation may not be limited to a certain sequence type, and may depend on the specific application (i.e. sequences optimal for patients with arrhythmias may differ dramatically from those optimal for bradycardia).

Dictionary generation

The dictionary is a lookup table that contains a representative set of the possible signal time courses that could result from the specific pulse sequence applied. It is generated by specifying ranges for the T_1 and T_2 values which could appear in the tissue and using the Bloch equations to calculate the signal time course for each combination of T_1 and T_2 .

The spacing of T_1 and T_2 values for which time courses are calculated determines the size of the MRF dictionary, which can grow to be quite large if the dictionary resolution is fine. Resolutions of 5~10 ms for T_1 (in the range between 50 and 5000 ms) and 2~5 ms for T_2 in the range between 6 and 500 ms, are used to ensure that the dictionary can be stored and accessed (19). Values of T_2 longer than T_1 are excluded from the dictionary because they are physically unrealistic; further exclusion of other unlikely combinations could also be performed to reduce the dictionary size, but such exclusion is not generally performed in practice. Another method to reduce the dictionary size is to compress the dictionary either along the time dimension or across the tissue property space. Low rank approximation methods such as randomized singular value decomposition and dictionary fitting methods also may significantly reduce the memory requirement for dictionary storage (40), and may be used to improve the dictionary resolution.

In previous MRF work in stationary organs, the dictionary is calculated once, and applied to all subsequent scans because the timing of the sequence is fixed for all subjects. However, cMRF requires a different dictionary for every scan because the timing between heartbeats can and will change for each subject and during the course of the cMRF scan. Even slight

changes in heart rate, and thus slightly different pulse sequence timings, may cause the same tissue to exhibit a different signal time course. Thus, for each scan, the precise sequence timing is recorded and employed when calculating the signal time courses in the dictionary. While this calculation requires additional time and computation power after each scan, it is advantageous as cMRF may not suffer from heart rate dependence in the measurement of relaxation times, and could be used even for patients with arrhythmias. Figure 3 shows examples of signal time courses affected by heart rate, and other factors including tissue composition, fat fraction, and sequence variant.

As described above, the ideal cMRF sequence is sensitive only to the tissue properties to be mapped, and insensitive to all other physiological or system properties. However, this may not be the case for all pulse sequences, and the signal time courses may be affected by additional confounding factors. In order to improve the accuracy of the maps generated using cMRF, these confounding factors can be taken into account in dictionary generation. In particular, slice profile imperfection, preparation pulse efficiency, and B_1^+ errors have been found to affect cMRF pulse sequences. Corrections to the dictionary which model these effects have been examined using the ISMRM/NIST MRI system phantom for several possible versions of cMRF pulse sequences (39). Measured T_1 and T_2 values in the phantom with the above corrections show a better agreement with the true values compared to those without corrections (Figure 4). More importantly, the consistency between different cMRF sequences in T_1 and T_2 measurements (especially T_2) are significantly improved after applying these corrections; this result is expected and reassuring, as the T_1 and T_2 measured in this phantom should not depend on the specific pulse sequence used. However, the use of more accurate dictionaries comes with a price: computation time. The time required to generate the dictionary without any confounding factor corrections is approximately 12s on a standalone PC using optimized MATLAB code. The dictionary that incorporates all three corrections took approximately 60 minutes to generate on a high-performance cluster with 168 nodes. Given the fact that of the many sequences appropriate for cMRF, some are less sensitive to these confounding factors, it is recommended that a cMRF implementation which requires the fewest corrections be employed. In cases where system properties must be taken into account for accurate tissue parametric mapping, the full dictionary calculation including confounding factors can be performed.

Pattern matching

Once the data have been collected and an appropriate dictionary calculated, the next step is to compare the acquired signal to the dictionary entries to find the best match. Several matching algorithms have been employed for cMRF. In the original cMRF work, a simple correlation calculation was used for matching, but recent developments have suggested that the use of sparse iterative (41,42) or low rank reconstructions (43,44) may provide better accuracy and precision or allow for shorter scan times.

In the simplest matching approach, the best match is selected by calculating the similarity between the acquired signal time course for a pixel and all the dictionary entries (calculating the correlation mathematically). Because the dictionary time courses and measured signals may be scaled differently, they are both normalized to have the same scale before computing

the correlation. The dictionary entry with the highest correlation value is selected as the best match, and the T_1 and T_2 values used to make that dictionary entry are assigned as the T_1 and T_2 values for that pixel. Proton density is calculated as the scaling factor between the measured signal time course and the selected dictionary entry. Quantitative maps are generated by applying the above procedures to all pixels in the images. Direct correlation-based matching is straightforward, rapid, and relatively easy to implement (20). However, pattern matching with large dictionaries can be time-consuming. Some dictionary compression methods have been developed recently to reduce the dictionary size and speed up pattern matching process without compromising image quality (40,45). While this direct approach is easy to understand and implement, more advanced methods including low rank reconstruction algorithms, are becoming more prevalent due to their ability to provide improved maps (43,44).

cMRF in Healthy Subjects

As part of the initial cMRF validation experiments in healthy subjects, T_1 and T_2 maps were acquired in eleven volunteers at 3T (Siemens MAGNETOM Skyra, Erlangen, Germany) using cMRF (the 16-beat variant), MOLLI, and T_2 -prepared bSSFP. Figure 5 shows three examples of T_1 and T_2 maps acquired using cMRF compared with the MOLLI and bSSFP measurements (note that all T_1 and T_2 maps acquired using cMRF shown in this article have a spatial resolution of $1.6 \times 1.6 \text{ mm}^2$ and a slice thickness of 8 mm, and do not include corrections for confounding factors such as slice profile). The mean T_1 value in the myocardium obtained by cMRF over all volunteers (1235 ms) agrees well with that measured using MOLLI (1247 ms) in this study, although both average values are slightly higher than literature MOLLI T_1 measurements (1050~1150 ms) (22,46) and lower than SASHA T_1 measurements reported in the literature (1487 ms) (31,47). The mean myocardial T_2 value measured with cMRF (38 ms) also matched bSSFP measurements (38ms) and was comparable to previously reported values in the literature (17,48). It is important to note that the T_1 and T_2 maps generated in this study did not include slice profile or inversion or T_2 preparation efficiency corrections, which were introduced only after the initial cMRF technique was reported, and thus the T_1 values measured with cMRF in this study were likely underestimated. Additionally, relaxation times for the blood pool measured by cMRF may not be reliable, given that blood flow entering or leaving the imaging slice may result in a signal evolution different from simulations in the dictionary.

A significant challenge to clinical myocardial T_1 and T_2 mapping has been the lack of reproducibility in these measurements across MRI scanners. Indeed, experts agree that T_1 values must be interpreted in the context of normative T_1 values for the specific MRI scanner; different sequence versions, vendors, and software platforms can lead to the measurement of different T_1 values (8). Because cMRF has the potential to take heart rate variations and any variable system properties into account, it is hypothesized that cMRF will allow more reproducible measurements of T_1 and T_2 in the heart. In order to determine the reproducibility of cMRF and potentially establish normative T_1 and T_2 values in the myocardium, 49 healthy subjects were recruited in an IRB-approved study at University Hospitals Cleveland Medical Center (UHCCMC). The protocol involved collecting cMRF scans as well as scans from conventional T_1 and T_2 mapping methods (MOLLI and T_2 -

prepared bSSFP) in three short axis slices at 1.5T (Siemens MAGNETOM Aera, Erlangen, Germany) (49). All cMRF scans were performed using the 15-heartbeat sequence within a breath-hold as described in the pulse sequence section. Figure 6 shows representative T_1 and T_2 maps in three healthy subjects obtained by cMRF and conventional methods. A Bland-Altman analysis shows systematic differences between cMRF and MOLLI T_1 measurements as well as cMRF and T_2 -prepared bSSFP T_2 measurements. In both cases, the cMRF measurements were lower than those derived from the standard techniques (on average ~ 20 ms for T_1 and ~ 5 ms for T_2) and the differences were statistically significant. All methods demonstrated fair to excellent repeatability in the measurements on mid-slice that was acquired twice during the scan, as well as comparable intra-reader agreement and inter-reader agreement between two independent readers. For each parametric map, image quality was evaluated on a 5-point Likert scale (1: worst visualization and most artifacts, 5: excellent). Oneway ANOVA analysis shows that cMRF maps were scored better than conventional T_1 and T_2 maps in all metrics by both raters, and this difference was statistically significant ($p < 0.05$, with the exception of visibility of the RV in T_2 maps). Two-alternative forced choice results also show that cMRF maps were preferred ($p < 0.05$ in all cases). Work is underway to assess if T_1 and T_2 maps generated using cMRF are reproducible across MRI scanners. Research along these lines has been performed for brain and prostate MRF implementations, and excellent agreement has been found in both intra-scanner (50) and inter-scanner measurements on different continents (51).

Initial and Potential Applications of cMRF

The first cMRF pilot patient study is currently ongoing and focuses on the use of cMRF for the assessment of non-ischemic cardiomyopathy. cMRF experiments were performed after written informed consent in this IRB-approved study on a 1.5T clinical scanner (Siemens MAGNETOM Aera, Erlangen, Germany) at UHCMC. Figure 7 shows an example of native T_1 , post-contrast T_1 , and native T_2 maps acquired using the 15-heartbeat cMRF sequence compared with conventional T_1 and T_2 maps in a patient with non-ischemic dilated cardiomyopathy. Both image quality and measured relaxation times were comparable between cMRF and conventional approaches. Figure 8 shows an example of pre- and post-contrast cMRF T_1 and T_2 maps, and MOLLI T_1 maps in a patient with asymmetrical septal hypertrophic cardiomyopathy, collected on a 3T scanner (Siemens MAGNETOM Skyra, Erlangen, Germany) at Toronto General Hospital. T_1 values in the anteroseptal myocardial wall obtained by cMRF agreed well with MOLLI measurements both before (cMRF 1385 ± 69 ms vs. MOLLI 1339 ± 43 ms) and after (cMRF 403 ± 34 ms vs. MOLLI 406 ± 28 ms) contrast injection. Since T_1 and T_2 maps are acquired in a single breath-hold and generated from the same dataset, cMRF not only saves scan time, but also provides precise co-registration between the parametric maps, which may facilitate the diagnosis process and further evaluation using advanced processing techniques such as machine learning.

Additionally, cMRF has been applied in a small patient population of cardiac transplant recipients to characterize cardiac graft rejection non-invasively (52). Thirteen heart transplant recipients were recruited in an IRB-approved study at Lausanne University Hospital (CHUV) / University of Lausanne (UNIL). The 15-heartbeat cMRF sequence was used to acquire T_1 , T_2 and proton density maps in addition to MOLLI T_1 measurements on a

3T scanner (Siemens MAGNETOM Prisma, Erlangen, Germany). Figure 9 shows representative T_1 , T_2 , and proton density maps acquired using cMRF compared with MOLLI T_1 maps in a heart transplant recipient both before and after contrast injection. Bland-Altman analysis shows good agreement between cMRF T_1 measurements and T_1 values obtained by MOLLI (52). This pilot study suggests the potential of cMRF for monitoring of cardiac health in a patient population such as heart transplant recipients.

cMRF has a number of features which may enable its application in a variety of additional clinical contexts. Since a unique dictionary incorporating variations in heart rate is generated for each individual subject, cMRF may be suitable for evaluation of patients with arrhythmias or in generating reproducible measurements that reflect a change in intrinsic tissue properties that may occur with heart rate alterations. A distinct advantage of cMRF is the reliable measurement of tissue property values over a large range that may enable a more accurate reflection of the true spread of values in health and disease. This feature may allow depiction of subtle alterations associated with physiologic adaptations such as changes in heart rate and hemodynamics resulting from exercise or pharmacologic vasodilation, but also permit registration of changes seen with aging or early disease states such as diabetes, hypertension and heart failure (1,53,54).

Future Directions for cMRF

The ultimate goal of cMRF is to enable comprehensive and reproducible whole heart tissue parametric mapping with a rapid 3D free-breathing sequence. A number of technical advances are being explored to reach this goal.

First, work is underway to increase the anatomical coverage and reduce the scan time required for cMRF. The current cMRF pulse sequence requires a 15-heartbeat breath-hold and employs an acquisition window of approximately 250ms at end-diastole to collect a single set of 2D parametric maps. The duration of breath-hold and acquisition window are appropriate for healthy volunteers but may be problematic for patients. Preliminary results have shown that it may be possible to reduce the cMRF scan time to 5 heartbeats (Figure 10) (55). Furthermore, a new version of cMRF sequence with shortened acquisition window (~150ms) is also under investigation to reduce artifacts due to cardiac motion; this approach may be especially useful when scanning patients with a high heart rate. Simultaneous multi-slice (SMS) cMRF has been developed to provide greater coverage within a single breath hold. Figure 11 shows representative T_1 , T_2 , and proton density maps from three slices collected simultaneously in a single 15-heartbeat breathhold from a healthy volunteer at 3T (Siemens MAGNETOM Skyra, Erlangen, Germany) using SMS cMRF. While SMS enables the collection of more slices, true 3D coverage is still preferable; such a 3D approach is currently being explored and may be invaluable in the assessment of T_1/T_2 changes over the whole heart in response to stress (vasodilator or exercise) that may allow evaluation of ischemia (14).

Secondly, the inclusion of additional tissue properties into the cMRF framework would enable complete tissue characterization in a single MRI scan and thus offer a full array of diagnostic information. In addition to T_1 and T_2 , T_2^* and fat deposition are also valuable

biomarkers for myocardial diseases. Recently, MRF pulse sequences have been developed to provide T_2^* maps and fat measurements in the brain (26,27) and in the heart (56). Such a cMRF pulse sequence could enable estimation of myocardial iron content and lipid deposition in addition to T_1 and T_2 . cMRF thus has the potential to provide a diagnosis in a single scan instead of using separate scans to investigate specific disease states such as cardiomyopathies and hemochromatosis/iron overload. The inclusion of diffusion (24) and perfusion (23) may allow further disease stratification in a single simple MRI scan.

MRF may also offer a novel and fast approach to measure additional non-standard tissue properties, such as changes in water content and ECV without exogenous contrast agents. ECV is the fraction of extracellular space within a voxel of myocardium, and this measurement can be derived from native T_1 and post-contrast T_1 values (5). ECV has been shown to serve as a marker of diffuse myocardial fibrosis and may provide important information on the degree of interstitial expansion (36). Most conventional parametric mapping techniques, including cMRF to date, treat each voxel as homogeneous and generate one set of T_1 and T_2 values for each voxel. However, biological tissues contain multiple compartments, such as intracellular and extracellular space, with their own relaxation times, within one MRI voxel. A novel approach called MRF with Exchange (MRF-X) has been developed to quantify subvoxel relaxation times and relative volume fractions (similar to ECV) in a single scan (28). By incorporating the two-compartment exchange model into the Bloch equations (i.e. using the Bloch-McConnell equations instead of the Bloch equations), MRF-X may be used to measure T_1 and T_2 values within each compartment, the water exchange rate between the two compartments, and the volume fractions of each compartment. While early explorations of MRF-X have focused on brain specific applications, one of the most attractive applications of MRF-X is the estimation of ECV without administration of contrast agents. The large number of tissue properties that must be modeled and differentiated have slowed the progress of MRF-X in the heart for ECV mapping, but the basic ability of cMRF to capture multi-compartment information makes this a promising application for this technology.

The third goal is for cMRF to provide unbiased MRF measurements that are reproducible on all MRI scanners, regardless of institutions, vendors, and installations. Since system properties including B_1 and off-resonance can also be mapped using MRF, the confounding effects of these system properties on tissue characterization could be potentially removed, leading to tissue property maps that do not differ when collected on a different MRI scanner. One open question is how to reduce the effect of MT on cMRF measurements. MT is an important factor that introduces bias in relaxation time measurements if it is not taken into account in sequence design. In inversion recovery T_1 measurement methods, the MT effect is known to shorten the apparent T_1 (36,57). MRF measurements of T_1 and T_2 values have been shown to be influenced by MT effects, and this bias caused by MT could be mitigated by incorporating a two-pool MT model into the dictionary and employing variable RF pulse durations in the acquisition (58). Note that MT effects are not accounted for in current cMRF sequences; therefore, a cMRF implementation which incorporates MT effects would be highly desirable and may yield more accurate and reproducible relaxation time measurements.

Once the appropriate confounding factors have been addressed, quantitative measurements acquired with cMRF in different places on different scanners would be comparable, and standard values of the quantitative parameters could be established across all institutions and hospitals. This aspect of cMRF is especially appealing in conjunction with the measurement of multiple tissue properties. Ideally, a database linking abnormal tissue property ranges to various disease states could be generated such that the make-up of the myocardial tissue for each patient could be characterized. In this way cMRF could fulfill the ultimate goal of quantitative MRI—complete tissue characterization in a non-invasive and cost-effective manner.

Conclusions

cMRF is a powerful tool to measure multiple tissue properties in the myocardium simultaneously and may allow seamless investigation of an array of myocardial diseases in a single scan. Optimization and improvements in pulse sequence design, confounding factor corrections, and pattern matching will enable precise unbiased measurements of T_1 and T_2 that are independent of current limitations in hardware and software which plague current parametric mapping approaches. Furthermore, mapping properties such as ECV, T_2^* and fat fraction could potentially be achieved in a single cMRF scan. Advanced techniques such as SMS cMRF, 5-heartbeat cMRF, or eventually whole-heart free-breathing 3D cMRF may significantly improve ability of physicians to evaluate the whole heart, moving closer to the ultimate goal of providing quantitative information to diagnose a variety of disease states and stratify disease severity.

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List of Abbreviations

bSSFP	balanced steady-state free precession
CMR	cardiovascular magnetic resonance
cMRF	cardiac magnetic resonance fingerprinting
ECV	extracellular volume fraction
FISP	fast imaging with free precession
FLASH	fast low angle shot
MOLLI	modified Look-Locker inversion recovery
MRF	magnetic resonance fingerprinting
MT	magnetization transfer

SASHA	saturation recovery single-shot acquisition
SMS	simultaneous multi-slice
SSFP	steady-state free precession

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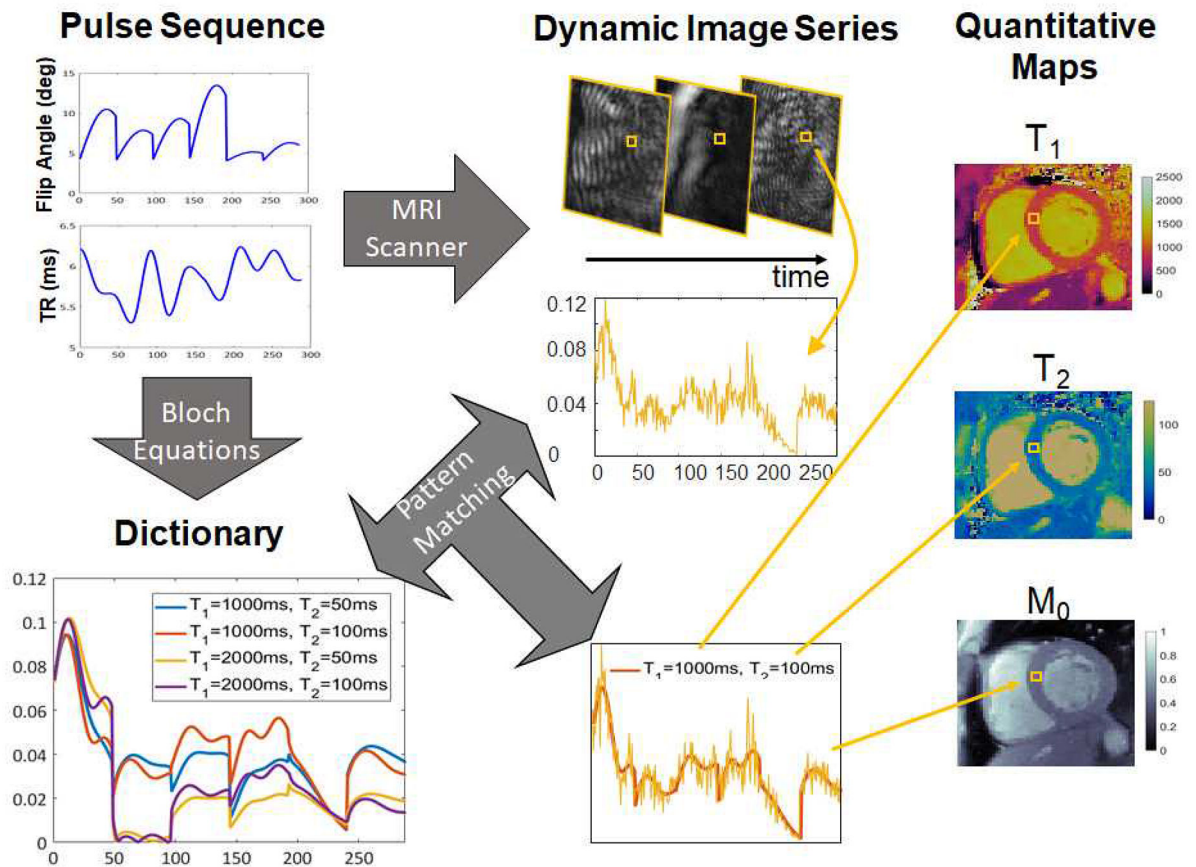


Figure 1. MRF workflow.

A pulse sequence with varying acquisition settings, such as flip angles and TRs, is used to acquire a series of highly accelerated images at the MRI scanner. A dictionary is generated covering a representative set of possible signal time courses that could result given the sequence employed. The actual signal time course at each pixel obtained from the accelerated image series is matched to the dictionary to find the best fit in the dictionary. The T_1 and T_2 values corresponding to that best fit are used as the quantitative values for that pixel.

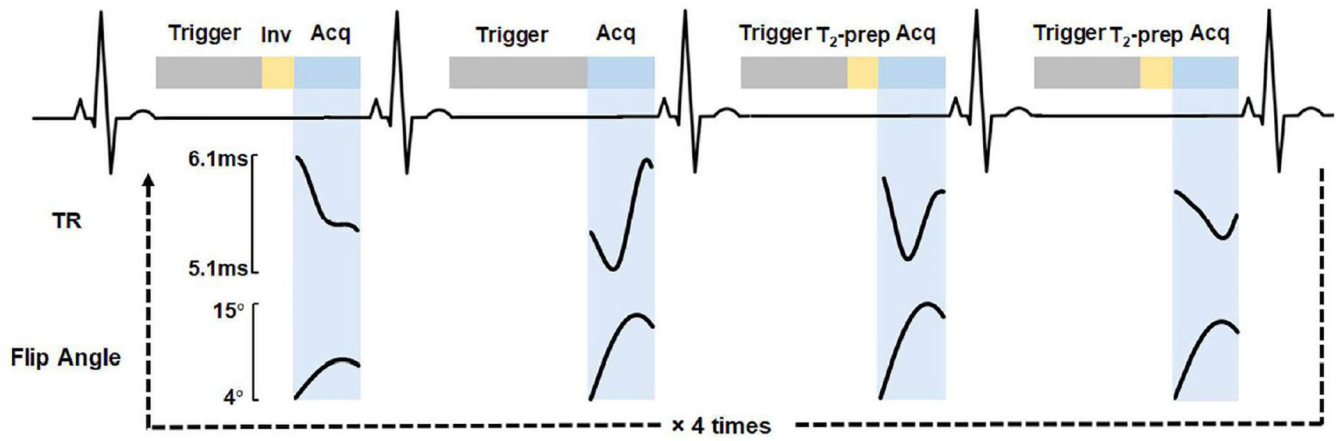


Figure 2. Diagram of the 16-heartbeat cMRF pulse sequence. Trigger delay, preparation pulses, and acquisition window are shown for the first four heartbeats.

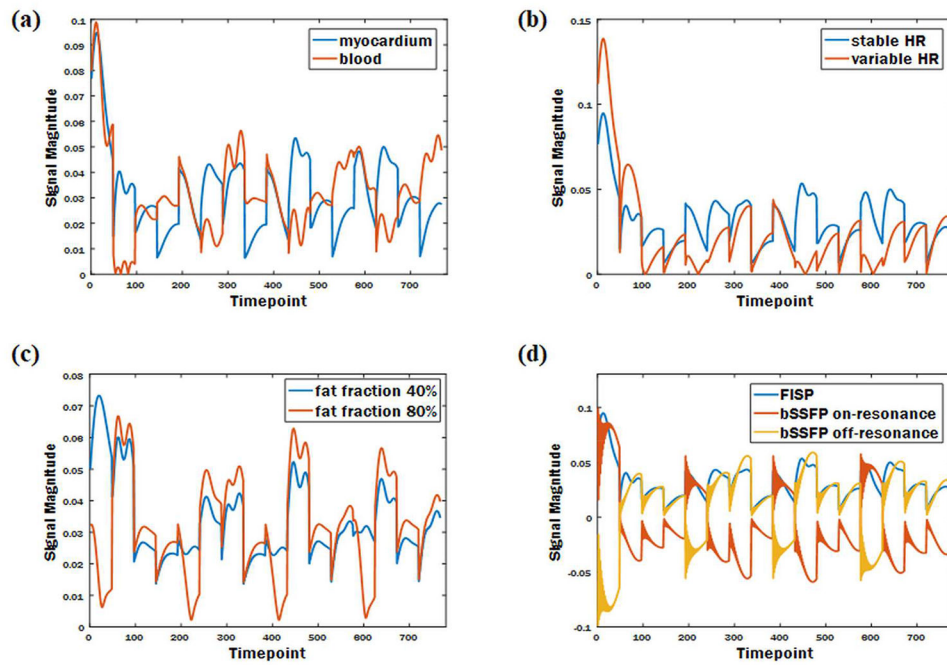


Figure 3. Example simulated signals demonstrating how different conditions lead to unique signal time courses.

Signal time courses affected by tissue composition (a); heart rate (b); fat fraction (c); sequence variant (d).

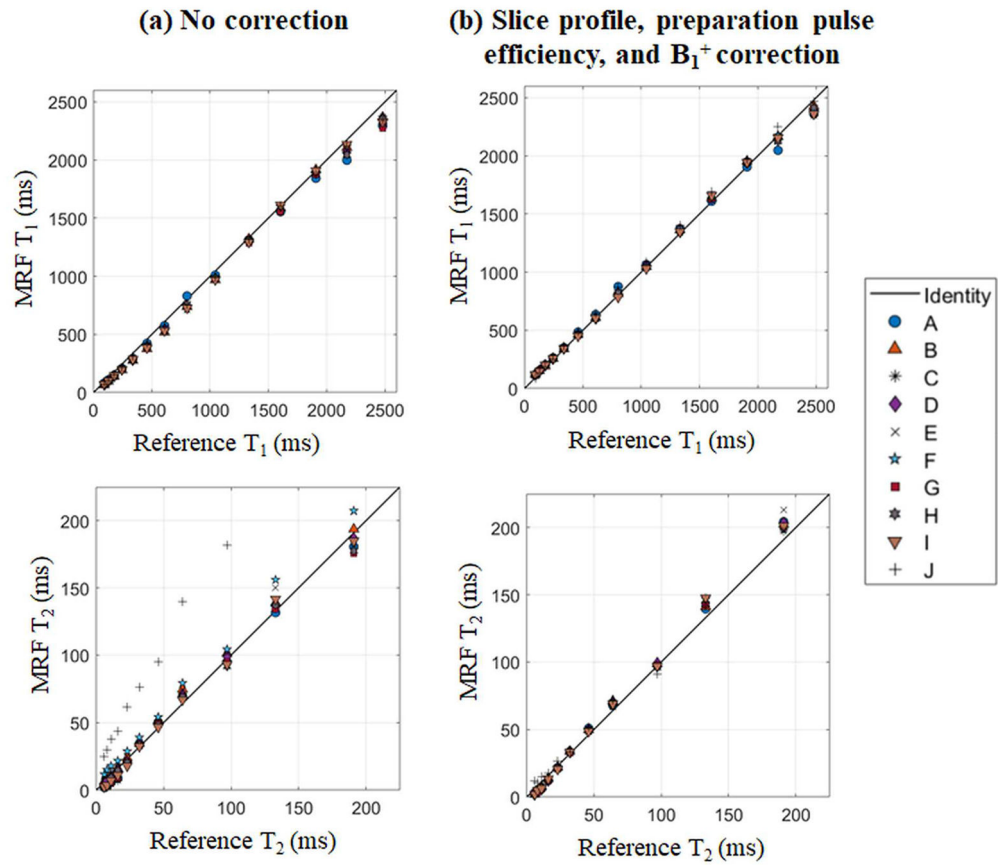


Figure 4. cMRF measurements vs. ISMRM/NIST reference in phantom experiments. The cMRF dictionary was simulated using (a) no corrections and (b) slice profile, preparation pulses efficiency, and B_1^+ corrections.

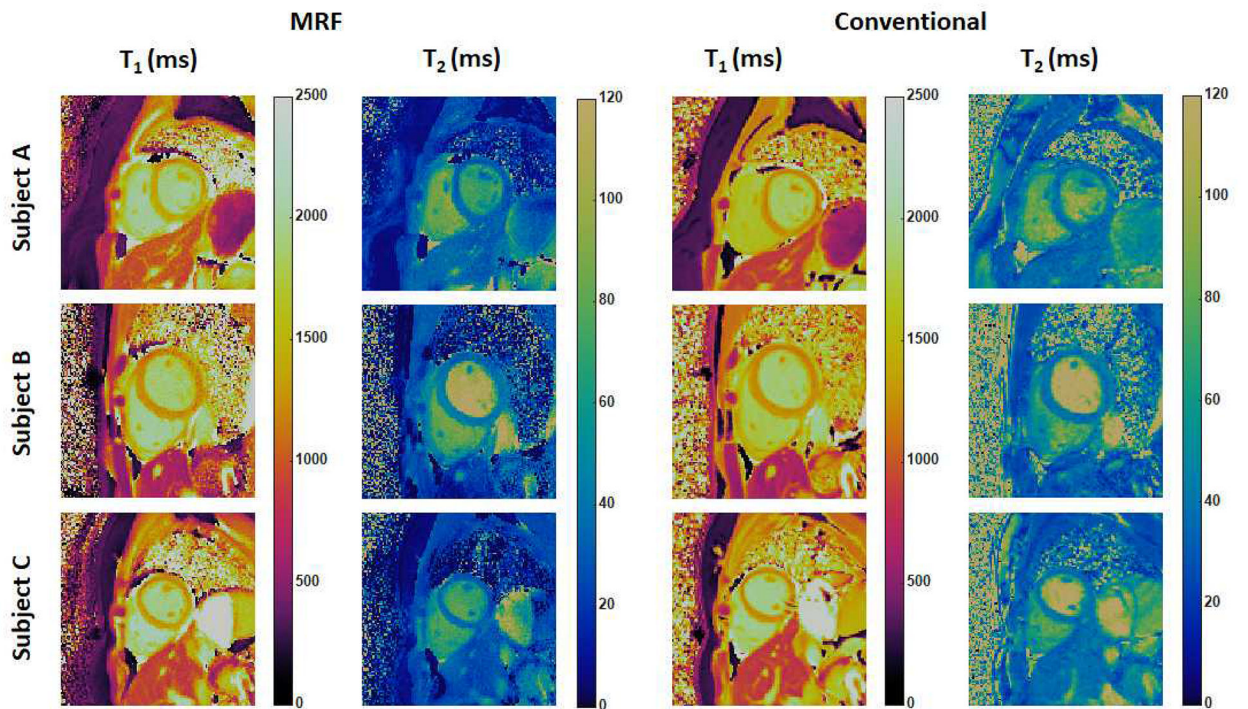


Figure 5. Representative cMRF maps in healthy subjects at 3T. cMRF maps (collected with the 16-heartbeat pulse sequence) are compared with conventional T₁ and T₂ maps acquired using MOLLI and T₂-prepared bSSFP sequence.

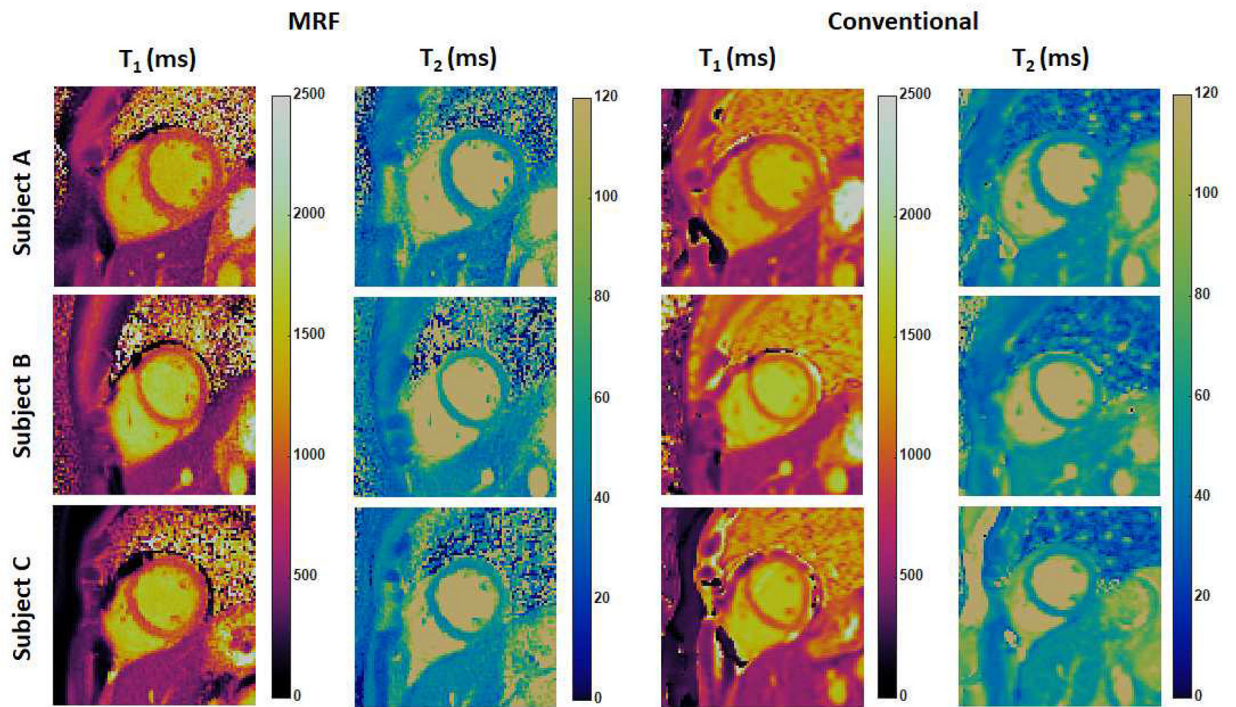


Figure 6. Representative cMRF maps in healthy subjects at 1.5T.
cMRF maps (collected with the 15-heartbeat pulse sequence) are compared with conventional T_1 and T_2 maps acquired using MOLLI and T_2 -prepared bSSFP sequence.

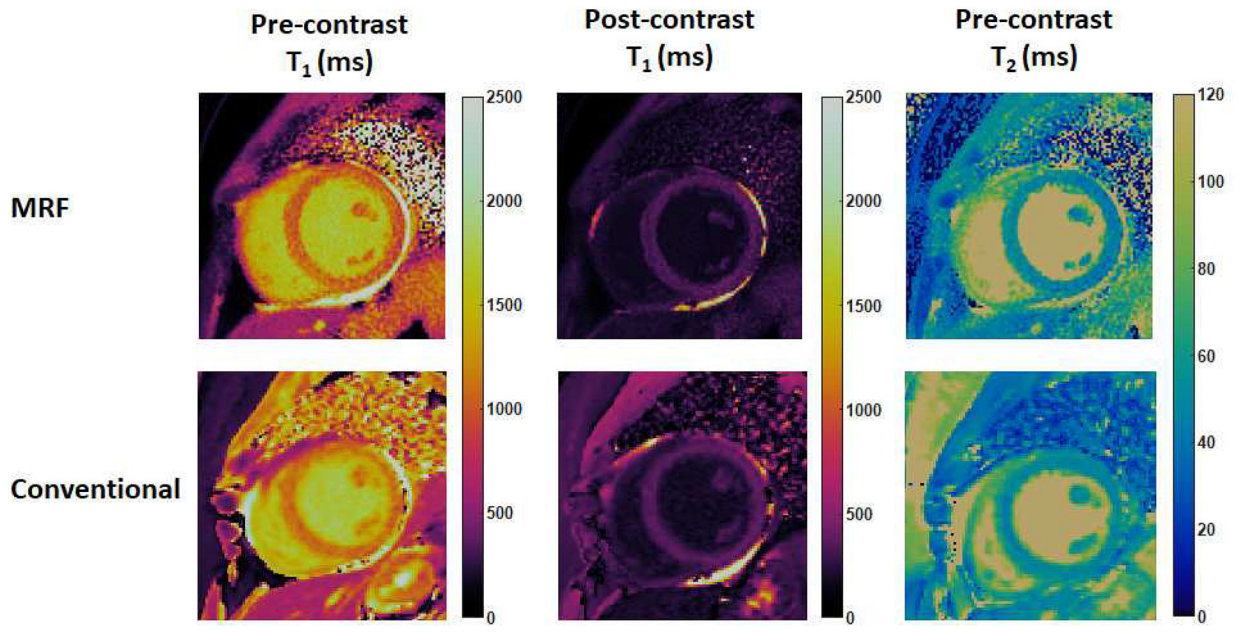


Figure 7. cMRF results in a patient with dilated cardiomyopathy at 1.5T. cMRF maps (collected with the 15-heartbeat pulse sequence) are compared with conventional T₁ and T₂ maps acquired using MOLLI and T₂-prepared bSSFP sequence.

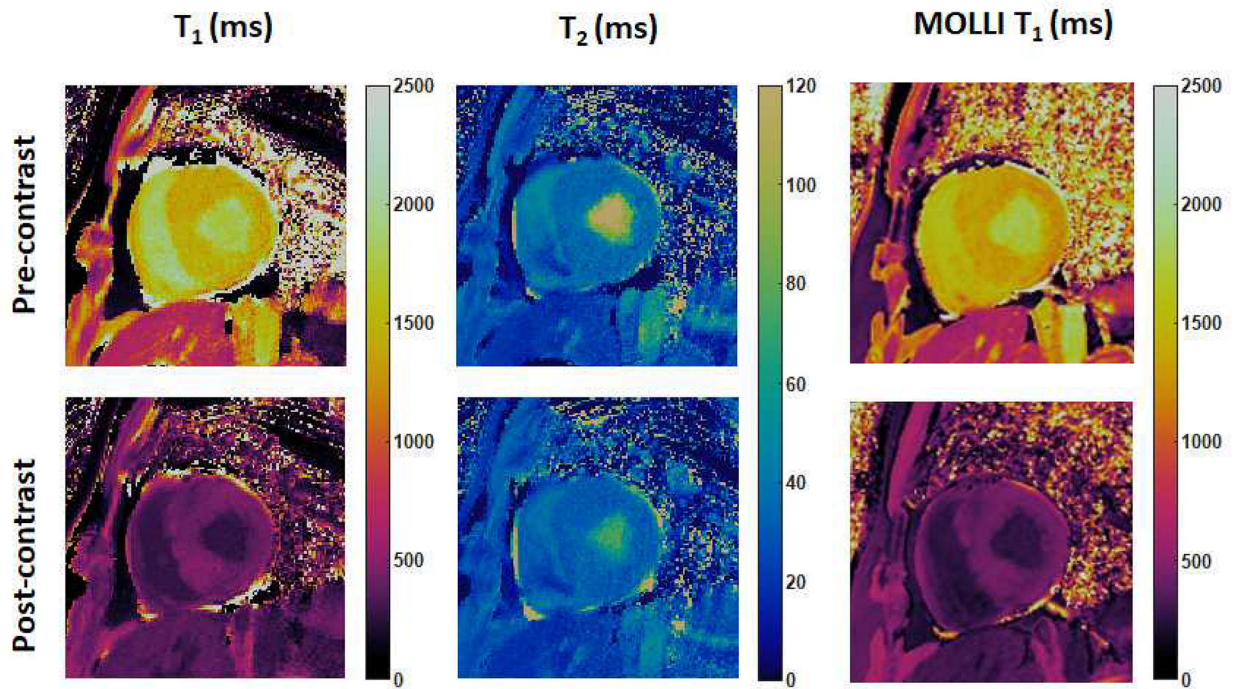


Figure 8. cMRF results in a patient with hypertrophic cardiomyopathy at 3T.
cMRF maps were collected with the 15-heartbeat pulse sequence and compared with MOLLI T_1 maps.

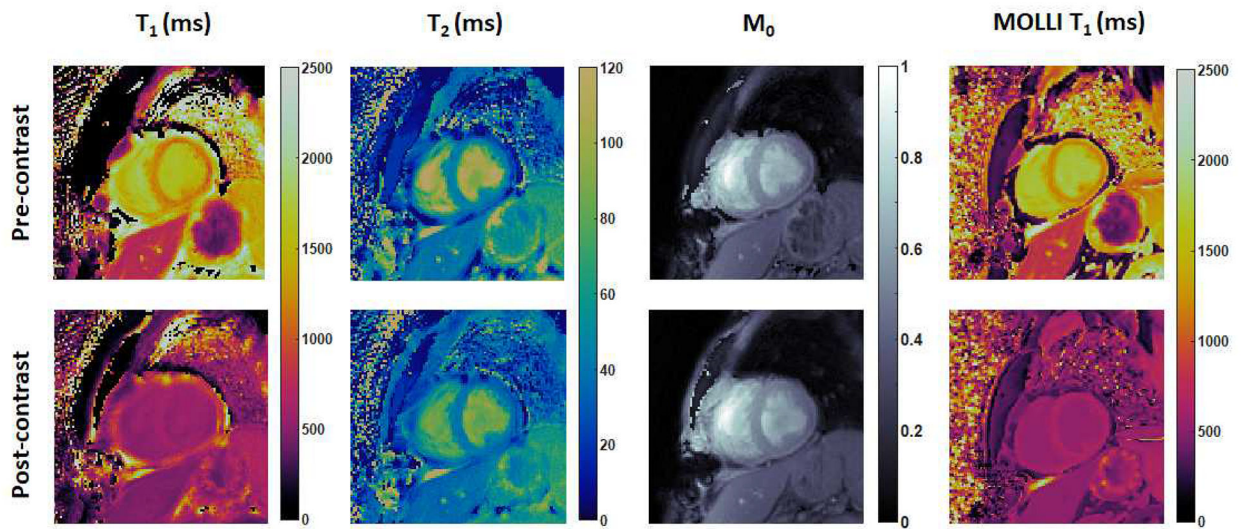


Figure 9. cMRF results in heart transplant recipients at 3T.
cMRF maps were collected with the 15-heartbeat pulse sequence and compared with MOLLI T_1 maps.

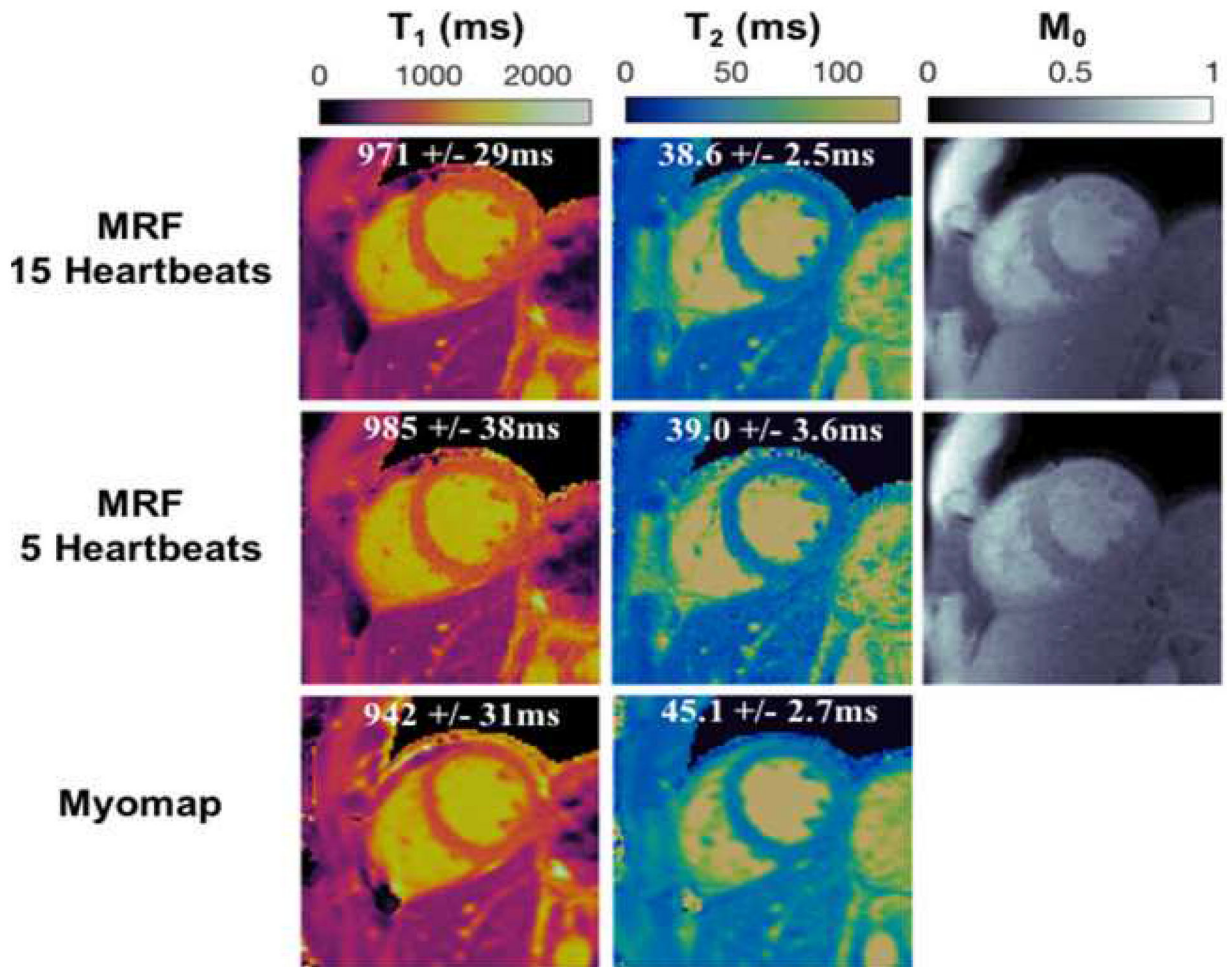


Figure 10. 5-heartbeat cMRF results at 1.5T.

T_1 , T_2 , and proton density (M_0) maps acquired using a 15-heartbeat breath-hold (top row) cMRF sequence and a 5-heartbeat breath-hold (middle row) cMRF sequence compared with conventional T_1 and T_2 maps (bottom row).

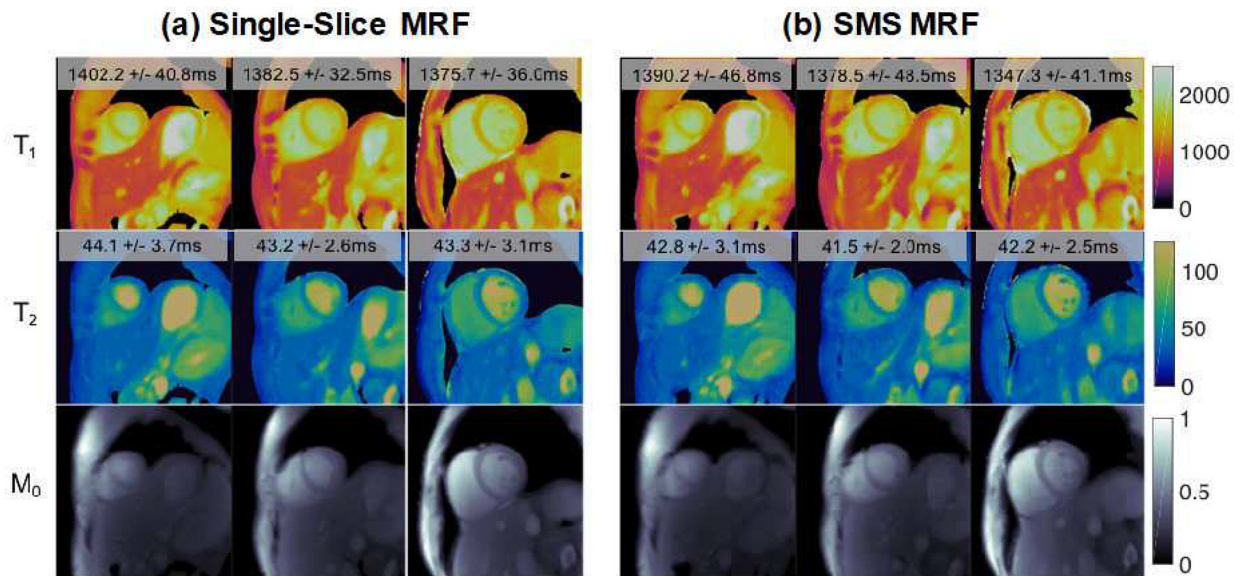
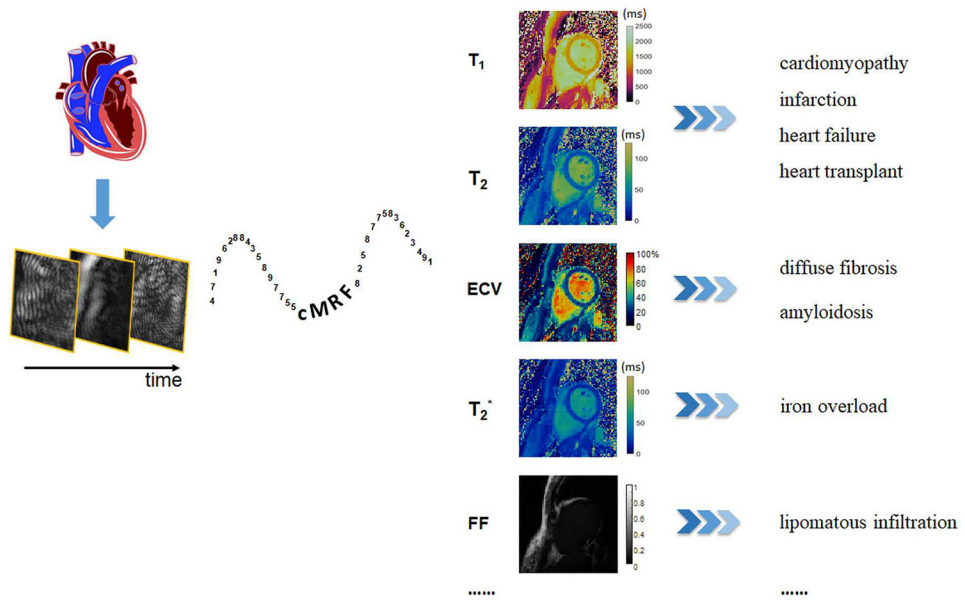


Figure 11. SMS cMRF results at 3T.

Representative T_1 , T_2 , and proton density (M_0) maps acquired using single-slice MRF in three separate breath-holds (a) and SMS cMRF maps collected in a single breath-hold (b). Low rank reconstruction was applied for both SMS and single-slice MRF.



Central Illustration. The potential of cMRF.

cMRF is a powerful tool to measure multiple tissue properties in the myocardium simultaneously, which may allow seamless investigation of an array of myocardial diseases.