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Intracranial Vessel Wall Segmentation Using Convolutional Neural Networks

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Abstract

Objective—To develop an automated vessel wall segmentation method using convolutional neural networks (CNN) to facilitate the quantification on magnetic resonance (MR) vessel wall images of patients with intracranial atherosclerotic disease (ICAD).

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Methods—Vessel wall images of 56 subjects were acquired with our recently developed whole-brain 3D MR vessel wall imaging (VWI) technique. An intracranial vessel analysis (IVA) framework was presented to extract, straighten, and resample the interested vessel segment into 2D slices. A U-net-like fully convolutional networks (FCN) method was proposed for automated vessel wall segmentation by hierarchical extraction of low- and high-order convolutional features.

Results—The network was trained and validated on 1160 slices and tested on 545 slices. The proposed segmentation method demonstrated satisfactory agreement with manual segmentations with Dice coefficient of 0.89 for the lumen and 0.77 for the vessel wall. The method was further applied to a clinical study of additional 12 symptomatic and 12 asymptomatic patients with >50% ICAD stenosis at the middle cerebral artery (MCA). Normalized wall index (NWI) at the focal MCA ICAD lesions was found significantly larger in symptomatic patients compared to asymptomatic patients.

Conclusion—We have presented an automated vessel wall segmentation method based on FCN as well as the IVA framework for 3D intracranial MR VWI.

Significance—This approach would make large-scale quantitative plaque analysis more realistic and promote the adoption of MR VWI in ICAD management.

Keywords

Vessel wall imaging; deep learning; segmentation; quantification; Intracranial Atherosclerotic Disease

I. Introduction

Intracranial atherosclerotic disease (ICAD) is an important cause of ischemic stroke worldwide [1–4]. The disease is characterized by the development, progression, and complication of atherosclerotic plaques in the vessel wall of the intracranial arteries [4]. Luminography imaging, routinely used in the diagnostic workup of ICAD, is restricted to the detection of luminal stenosis, which is, however, not a specific marker for confirming and risk-stratifying atherosclerotic plaques [5]. Magnetic resonance (MR) vessel wall imaging (VWI) is an emerging noninvasive imaging modality that can directly visualize the intracranial vessel wall and characterize plaque features due to excellent soft-tissue contrast [6–12]. Several VWI-derived morphological features, in particular quantitative measures such as wall area, remodeling ratio, and normalized wall index (NWI), have been investigated in ICAD patients and demonstrated the great potential for the identification of high-risk ICAD lesions [11, 13–20].

Morphological quantification of ICAD lesions based on MR VWI is currently of limited use in clinical practice. ICAD lesions are typically assessed by neuroradiologists in a qualitative fashion [21–23]. Dichotomized classification or ordinal scores are used to describe morphological features, which is reader experience-dependent and potentially unsatisfactory in accuracy and reproducibility. Thus, quantitative assessment of plaque morphology is highly desirable. Its feasibility has previously been demonstrated for two-dimensional (2D) VWI whereby cross-sectional images were used for manually tracing the lumen and outer vessel wall boundaries at each isolated plaque [11]. This segmentation step then allows for

subsequent quantitative analyses. However, when moving into the era of three-dimensional (3D) VWI [24], this manual approach to vessel segmentation becomes prohibitively time-consuming because of the need for analyzing a largely increased number of imaging slices from multiple plaques and/or arterial segments. An automated vessel wall segmentation method would make quantitative plaque analysis more realistic, which would in turn promote the adoption of 3D MR VWI in the clinical management of ICAD.

To date, there is a paucity of literature on automated segmentation of the vessel wall from intracranial MR VWI. A challenge unique to the intracranial vessel wall is that the ultra-thin, tortuous structure is immediately surrounded by brain parenchyma or cerebrospinal fluid (CSF) that may show similar contrast. Recent technological advancements, such as isotropic, high spatial resolution imaging [6, 8, 25, 26] and CSF signal suppression [8, 26–28], have achieved enhanced quality of vessel delineation, potentially facilitating automated segmentation. Qiao et al. has demonstrated the feasibility by using the software LAVA that employs a method of nonuniform rational B-spline surface modeling [14]. However, the software was originally developed for carotid vessels, more rigorous evaluations on intracranial vessels are warranted.

Convolutional neural network (CNN) is a recently emerged deep-learning technique that can be used for image segmentation [29]. Inspired by neurons that make up the human brain, CNN organizes neural networks as a layered and hierarchical architecture with sufficient flexibility to represent complex multisource data, reveal hidden patterns, and build models for prediction. As a type of CNN, fully convolutional networks (FCN) have been successfully used in segmentation tasks [30]. In addition to convolutional layers for feature extraction and pooling layers for feature contraction, FCN introduces upsampling layers to expand the contracted features back to the same size of the input image, which is ideal for segmentation. Following this idea, a U-shaped deep convolutional network called U-net was proposed that employs multiple upsampling layers along with skip connections between the downsampling and upsampling paths to help recover fine-grained information [31].

In this work, we developed a U-net-like CNN segmentation method that can identify vessel wall boundaries in cross-sectional vessel wall images as pre-reformatted from whole-brain 3D MR VWI data [8, 32]. As a preliminary application demonstration, the method was then applied in a prospective VWI study to determine the difference in a plaque burden metric, NWI, between symptomatic and asymptomatic ICAD patients.

II. Materials and Methods

A. Human Subjects

We retrospectively reviewed our institutional MR VWI database, and prepared a dataset for the segmentation network development. Briefly, a total of 56 patients with diagnosed brain ischemia (i.e. ischemic stroke or transient ischemic attack) secondary to ICAD were selected. Enrollment criteria included: at least one >50% intracranial diameter stenosis on MR angiography or CT angiography within the ischemic territory, ⩾ 1 atherosclerotic risk factor (hypertension, diabetes mellitus, hyperlipidemia, and cigarette smoking), and exclusion of other etiologic causes such as coexistent >50% ipsilateral extracranial stenosis,

nonatherosclerosis vasculopathy (e.g. dissection, vasculitis, or Moyamoya disease), and cardioembolism based on thorough evaluations.

We prepared a second dataset to further demonstrate the clinical use of the proposed framework. For that purpose, we prospectively recruited 12 symptomatic and 12 asymptomatic patients with age matched to investigate the difference in the NWI of ICAD lesions. All subjects had one >50% stenosis at the M1 segment of a unilateral middle cerebral artery (MCA) on MR angiography or CT angiography and ⩾ 1 atherosclerotic risk factor. Symptomatic subjects qualified if there was an ischemic stroke or transient ischemic attack in the territory of the stenotic MCA within the past 8 weeks and had received thorough evaluations to exclude other etiologic causes. Asymptomatic subjects were considered for inclusion if no ischemic events had occurred in the territory of the stenotic MCA and no nonatherosclerosis vasculopathy had been documented.

The above studies were approved by the local ethics committee and the informed consent were waived for the retrospective study and obtained from prospectively recruited subjects.

B. Imaging Protocol

Intracranial vessel wall images were acquired on a 3-Tesla whole-body MR system (MAGNETOM Verio; Siemens Healthcare, Erlangen, Germany) equipped with a 32-channel head coil (Siemens Healthcare) using our recently developed whole-brain 3D VWI sequence [8]. The imaging parameters include: 3D sagittal orientation; TR/TE=900/15 ms; field of view=70×170 mm^2; 240 slices with spatial resolution=0.53 mm isotropic without any interpolation. With this, VWI of entire intracranial vasculatures can be completed in 8 minutes with enhanced T1 contrast weighting and CSF-signal suppression.

C. Image Preprocessing

We propose an intracranial vessel analysis (IVA) framework that provides integrated vessel wall image analysis (Fig. 1). All images were preprocessed by a neuroradiologist (over 10 years of experience) using an in-lab intracranial vessel analysis software plug-in built on Horos, a free, open source medical image viewer (http://www.horosproject.org). Briefly, a 3D image set acquired using an MR VWI sequence was first reformatted for optimal visualization of a vessel segment of interest (e.g. pathology involved). For each patient, a vessel segment implicated in ICAD was selected. The start and end points of the vessel segment were then manually designated. Vessel centerline tracking was then performed in Horos with manual modifications if necessary. After that, 3D curved multiplanar reconstruction (MPR) was used to straighten the segment, and consecutive 2D cross-sectional slices with 0.5-mm slice thickness were thus reconstructed and exported in DICOM format. Note that the in-plane resolution was upsampled to 0.1 mm for the resulting 2D slices. Depending on the interrogated vessel segment (i.e. the terminal internal carotid artery, the M1 of the middle cerebral artery, the vertebral artery, or the basilar artery) and the long-axis diffuseness of the interest of ICAD lesions, 17 to 50 contiguous cross-sectional images, covering both normal and thickened vessel wall parts, were generated from each subject. These 2D slices were manually delineated for the lumen and vessel wall by an

expert rater using ITK-Snap software (http://itksnap.org), providing the ground truth for the training and validation of segmentation model.

D. FCN-based Vessel Wall Segmentation

We propose a U-net-like FCN architecture to segment the vessel wall from 2D cross-sectional image slices, as shown in Fig. 2A. The network architecture consists of an encoding path followed by a decoding path. The encoding path includes 3 convolutional units, where each of them is composed of a convolutional layer, batch normalization layer, parametric rectified linear unit (PReLU) activation layer [33], and another convolution layer. Adjacent convolutional units are connected by a max-pooling layer for downsampling the image to half its size. An input 2D image sized 128×128, corresponding to a field of view of $(12.8mm)^2$, is first processed to improve the local contrast using contrast-limited adaptive histogram equalization (CLAHE). CLAHE performs histogram equalization in local regions, and neighborhood regions are combined to eliminate artificially induced boundaries. The contrast, especially in homogeneous areas, will be limited to avoid amplifying any noise that might be present in the image. The contrast-enhanced images are then sent to the first convolutional unit in which a total of 32 learnable filters of size $K = 3$ are used to convolute with the input image, respectively, producing 32 feature maps. The size of resulting feature maps O is the same as the input image size W according to the equation $O = (W - K + 2P)/S + 1$, where we set the stride $S = 1$ and padding $P = 1$. The following batch normalization, PReLU activation, and convolution layers also have the same filter size and feature map number. The max-pooling layer downsamples the image to 64×64. Subsequent convolutional units further increase feature map numbers while reducing image size, resulting in hierarchical extraction of low- and high-order convolutional features.

The features derived from the above encoding path later undergo a decoding path that reverses the convolution process. An upsampled segmentation result that eventually has the same dimension as the input image is generated. Similarly, 3 convolutional units with the same settings as mentioned above are used. Each of them is concatenated with a corresponding unit in the encoding path through a skip connection to help the decoding path better recover spatially detailed information by reusing feature maps. The skip connection has previously proved useful to alleviate the gradient vanish problems in network optimization [34].

The proposed FCN network architecture is modified from the originally introduced U-net [31] in several aspects. In the decoding path, instead of direct upsampling, we employ a transposed convolution layer that achieves transformation in the opposite direction of a normal convolution [35]. This layer is trainable and promises better performance. Moreover, PReLU is used for the activation function after each convolution layer instead of the commonly used rectified linear unit (ReLU) [33]. This is because the PReLU does not have the saturate problem and thus avoids the “dead features” caused by zero gradients in ReLU.

Given the input is a 2D image slice, the output is designed as a multi-class image in a form of a 128×128×3 matrix, where the three channels are for the background, lumen, and vessel wall, respectively. Comparing to the approach that only segment the vessel wall, this multi-class segmentation may achieve a better segmentation performance in both the lumen and

vessel wall since the relative position of them could potentially be utilized. Thus, the final activation function is set as softmax instead of sigmoid, where the former one guarantees the sum of three channels is 1 in all pixels while the latter one estimates each channel separately. Fig. 2B demonstrates an example of the input image, intermediate segmentation, and final results.

Dice coefficient is used to evaluate the overlapping ratio between automated segmentation and manual ground truth. Conventionally, Dice is defined as: $D = 2(A \cap M)/(|A| + |M|)$, where the nominator represents twice the number of pixels with the same label in automated segmentation A and manual result M and the denominator represents the total number of pixels. Note that in our work the output segmentation from FCN is a probability map. To take advantage of this information instead of using the Dice on a thresholded map, we define a soft Dice coefficient: $D' = 2 * sum(A * M)/(sum(A * A) + sum(M * M))$, where the A is a probability map, A and M are reshaped as vectors, and the $(*)$ is a dot operation. Dice ranges from 0 to 1, where 1 means perfect match between automated and manual segmentations. The Dice is computed separately for the lumen and vessel wall so that they have equal importance and the result is not dominated by the one with more voxels. Moreover, to accommodate multi-class results, the loss function is defined as: $L = -1 * (D'_{lumen} + D'_{wall})/2$. The background channel is not included as it is the counterpart of other two channels.

E. Implementation

The neural network was implemented in Keras with backend of Tensorflow (https://keras.io). The loss function is the mean Dice coefficient of the lumen and vessel wall. Network optimization is realized with Adam gradient descent. The learning rate is 1e-5 with a batch size of 64. The training time on 1030 slices took around 1 hour on a NVIDIA GeForce GTX 1080Ti 8GB GPU, including 7 seconds for training an epoch and we set the maximum epoch number as 500 and keep the best model determined by the performance in validation data, although the algorithm training generally converges around 200 epochs. For testing, it takes around 0.1 ms on an unseen slice.

F. Experimental Settings

The first dataset was used for the training, validation, and testing of the segmentation model. We randomly split the imaging data of 56 patients into 30 patients for training (1030 slices), 6 patients for validation (130 slices), and 20 patients for testing (545 slices). For data augmentation, the 2D slices in training data were randomly flipped in vertical and horizontal directions. Using the Dice metric, the baseline U-net from [31] was compared in testing subjects with the approaches involving additional components including batch normalization, PReLU, CLAHE, and dropout for further evaluations. Following vessel segmentation, morphological measurements were also derived for consecutive cross sectional images in the testing group, including wall area A_{wall}, lumen area A_{lumen}, and NWI defined as $NWI = A_{wall}/(A_{wall} + A_{lumen})$, where the index ranges from 0 to 1, and the closer to 1 the heavier plaque burden). For each of these metrics, all measurements along the analyzed vessel segment were compared between the automatic and manual segmentation approaches using the Pearson correlation analysis.

In the second dataset, the proposed segmentation method was applied to the VWI data of the M1 arterial segment in age-matched symptomatic and asymptomatic ICAD patients. Wall and lumen areas as well as NWI were generated following automated segmentation. The three metrics at the slice with the peak NWI (by definition corresponding to the highest plaque burden) were analyzed for the differences between the two groups. Moreover, after including neighbouring 2 and 4 slices, these metrics were respectively averaged over totally 3 and 5 slices and then undergo comparisons. Two-sample t-tests were used for the comparison of quantification metrics and Chi-square tests used for comparison of patient demographics between the two patient groups. A p-value less than 0.05 indicated statistical significance.

III. Results

A. Segmentation network evaluation

As shown in Fig. 3, on the testing subjects, the baseline U-net achieved a Dice coefficient of 0.852 for the lumen and 0.712 for the vessel wall when comparing automated and manual results. The performance kept improving when successively adding batch normalization (0.866 and 0.715, respectively), PReLU (0.872 and 0.757, respectively), and CLAHE (0.889 and 0.767, respectively). The addition of dropout, however, showed the lowest performance (0.752 and 0.369, respectively). As a result, our finalized network included batch normalization, PReLU activation, and CLAHE for image preprocessing and excluded the dropout procedure.

Fig. 4 shows the segmentation results from 10 subjects as well as their manual segmentations for references. Our method was able to locate the vessel region and provide reasonable segmentation, even when the boundaries in neighboring tissues were essentially invisible to naked eyes. Example curves of lumen area, wall area, and NWI (defined as the wall area divided by the summation of wall area and lumen area) for automated and manual segmentations, respectively, along a vessel segment of 2 test subjects were shown in Fig. 5. The average Pearson correlations between the curves on all test subjects were 0.89, 0.84, 0.88, respectively, on lumen area, wall area, and NWI.

Fig. 6 demonstrates the feasibility of NWI quantification in large-range anterior circulation vasculatures (from the intracranial internal carotid artery to the MCA M2) on a subject using the IVA framework and proposed segmentation approach. The vessels of interest underwent centerline tracking, straighten, and slicing. Following automated vessel wall segmentation, a NWI versus slice curve was derived.

B. Clinical Applications in ICAD patients

We also demonstrate the use of IVA in clinical application of ICAD patients. MCA stenosis is a major component of ICAD, which could be symptomatic or asymptomatic. Recent studies suggest they may belong to distinct groups associated with different stroke risks [11]. Table I shows the demographic data of the recruited 24 patients. VWI images were acquired and the proposed framework was used for image processing. The consecutive 2D slices from

the arterial segments of interest underwent segmentation analysis and quantification including lumen area, wall area, and NWI.

The slice with a peak NWI, corresponding to the location with the most severe plaque burden, was chosen for comparisons (Table II). To test the robustness, we further included the neighboring 2 and 4 slices, along with itself. The lumen area and wall area in symptomatic patients were slightly smaller and larger, respectively, than those of asymptomatic patients, but the differences did not reach a statistical significance ($p > 0.05$ from two-sample t-tests). However, the peak NWI in symptomatic patients were significantly higher than that of asymptomatic patients ($p = 0.0312$), and the difference became more prominent when including neighboring slices ($p = 0.0073$ for 3 slices and $p = 0.0045$ for 5 slices).

IV. Discussion

In this work, we developed an automated vessel wall segmentation method for the intracranial arteries based on convolutional neural networks. The proposed method achieved good agreements with manual segmentation. With this method, a significant difference in lesion NWI between symptomatic patients and asymptomatic patients was detected, although lumen area and raw wall area were comparable in the two groups.

MR VWI is increasingly being adopted in ICAD studies. However, current plaque analysis heavily relies on qualitative assessment of a few plaque features through expert image review. This is in part due to the fact that a proper computer-aided tool for quantitative plaque analysis is unavailable. Vessel wall segmentation is a challenging task but prerequisite for automating quantitative analysis. For medical images of anatomic structures other than intracranial vessels, deep learning has shown its advantages in object localization and segmentation over conventional methods such as histogram thresholding, shape filters, and surface models. Our study, the first report to our knowledge, presented a deep-learning based approach for automated segmentation of intracranial vessels.

There are only few semi-automatic segmentation methods previously proposed for extracranial vessels [17, 36–39]. These methods may not be robust when applying to smaller vessels, for example intracranial arteries, due to the possible leak at low-contrast outer wall boundary. Advantageous over conventional machine-learning approaches where features are hand-engineered, FCN can automatically learn the comprehensive data-driven features from training data. In this work, specifically, we proposed a U-net-like FCN to strengthen the capacity of resolving the outer wall boundary. Our results suggest that the combination of baseline U-net with three other components, including batch normalization PReLU, and CLAHE, are necessary for a high performance in segmentation. Also, we performed a multi-class segmentation to extract both lumen and wall instead of only segmenting wall, which is a superior strategy as the latter approach may result into a C-shape segmentation for the wall that is difficult to restore lumen or wall through post-processing such as morphological opening (see Fig. S1 in the supplementary material). As we continue to accumulate the image and label data, the neural network weights could be further tuned for improved segmentation performance.

The utility of the automated vessel wall segmentation method was demonstrated in this study. When integrated into an intracranial vessel analysis framework, the proposed method permitted efficient analysis for large-range anterior circulation vasculatures, which is otherwise tremendously time-consuming in a manual fashion (see Fig. S2 in the supplementary material). In addition, a significantly higher NWI was observed in symptomatic ICAD lesions compared to asymptomatic ones despite their similar severity of stenosis. More importantly, NWI exhibited a stronger association with symptomatic lesions compared to wall and lumen areas. Hence, it is anticipated that this marker may have significant clinical value for early identifying event-prone plaques or informing the response of medical management in ICAD patients. Our results also highly suggest that the most stenotic location of a focal ICAD lesion is associated with a locally peak NWI. Whether this finding would hold true and could be utilized to automatically detect focal ICAD lesions is worthy of investigations in the future.

In this study, we proposed to simplify the segmentation task by straightening the vessel and using 2D cross-sectional slices. The reason is that the original vessels are tortuous in 3D space that is difficult for manual rater to delineate. Also, automated segmentation of 3D images would need a lot more training data to learn the segmentation in that complex environment. Result checking find most failure cases are at the vessel branching area, where one vessel is splitting to two or more vessels and so the vessel wall boundary in this 2D slice is no longer the general circle shape (see Fig. S3 in the supplementary material). To improve this, we could include more vessel branching slices in the training sample and so the program could learn this shape better. Second, neighboring cross-sectional slices from the same vessel may provide additional regularization for the segmentation results. The program could be extended to work on multiple 2D slices or even 3D images to get better overall structure information. Third, we measured the NWI as well as the areas of lumen and wall in this study. In future work, we would further evaluate vessel wall thickness, or eccentricity index (EI) [40] when considering the effects of stenosis, as relevant clinical parameters in a multi-center large-scale clinical study.

V. Conclusion

We have presented an automated vessel wall segmentation method for intracranial arteries based on convolutional neural networks. The proposed method achieved good agreements with manual rater in terms of Dice coefficient, lumen area, wall area, and NWI. With the method, a significant difference in lesion NWI between symptomatic patients and asymptomatic patients was detected, although lumen area and raw wall area were comparable in the two groups. Such an automated vessel segmentation approach would permit large-scale quantitative plaque analysis and promote the adoption of MR VWI in ICAD management.

Supplementary Material

Refer to Web version on PubMed Central for supplementary material.

Acknowledgments

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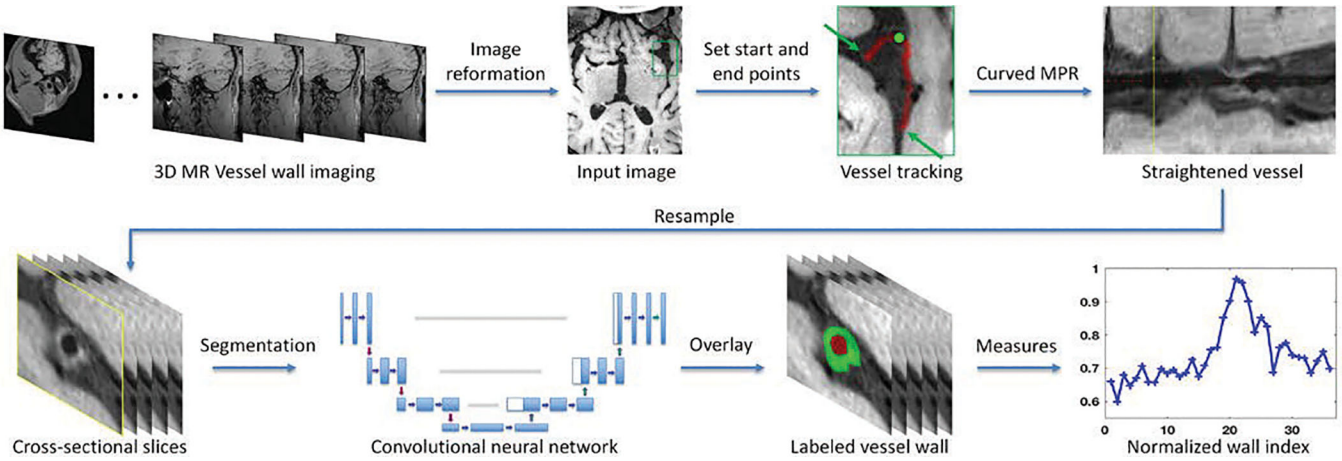

Fig. 1.

Image processing pipeline proposed in IVA framework. Top row shows the image preparing steps and bottom row demonstrates the image segmentation and quantification steps. The originally acquired 3D VWI image set is first reviewed to identify the interested intracranial vessel (the green box). Then this region is zoomed up where the start and end points of the vessel could be manually designated. It is followed by vessel centerline tracking and vessel straighten using curved MPR (the yellow line in the “Straightened vessel” panel corresponds to the location marked by a greed dot in the “vessel tracking” panel), and sliced into contiguous cross-sectional 2D slices that will in turn undergo vessel segmentation and quantification analysis.

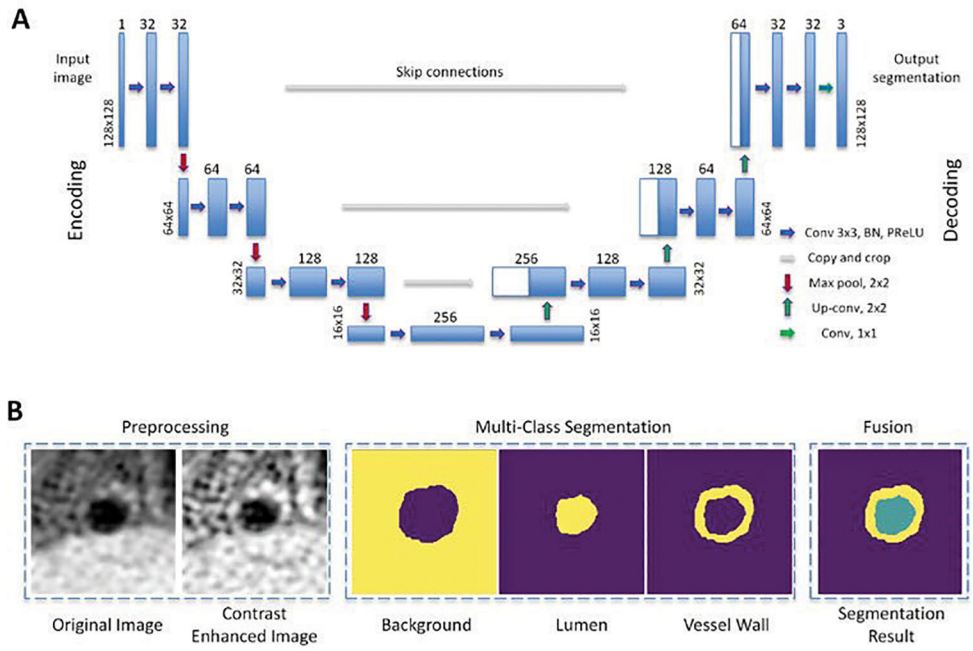

Fig. 2.

Illustration of the (A) architecture of the proposed FCN segmentation and (B) examples of input image, intermediate result, and final segmentation.

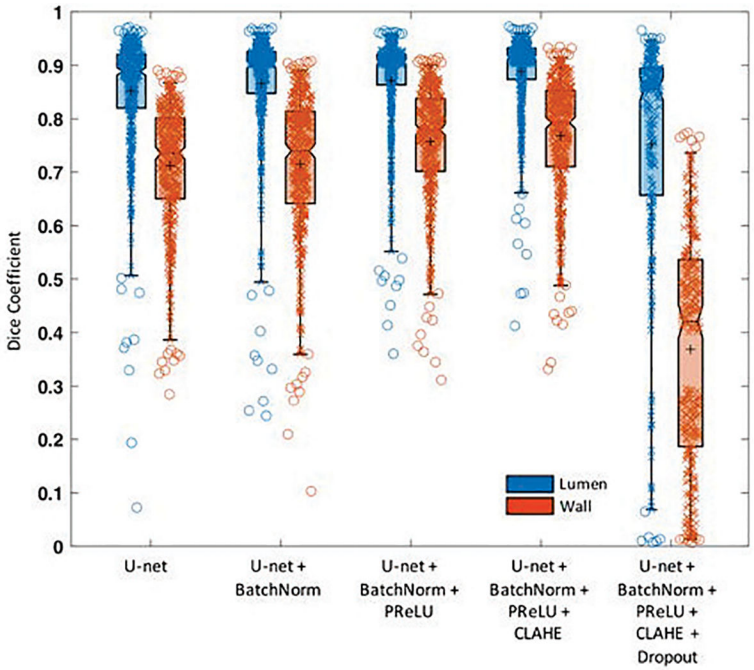

Fig. 3.

Segmentation performance evaluation on different methods. Boxplot shows the median with 25th and 75th percentiles. The "+" symbol points the mean and "o" shows the outliers. In this work, we adopted the U-net+BatchNorm+PReLU+CLAHE method that has Dice coefficient of 0.889±0.041 and 0.767±0.104 for lumen and vessel wall, respectively.

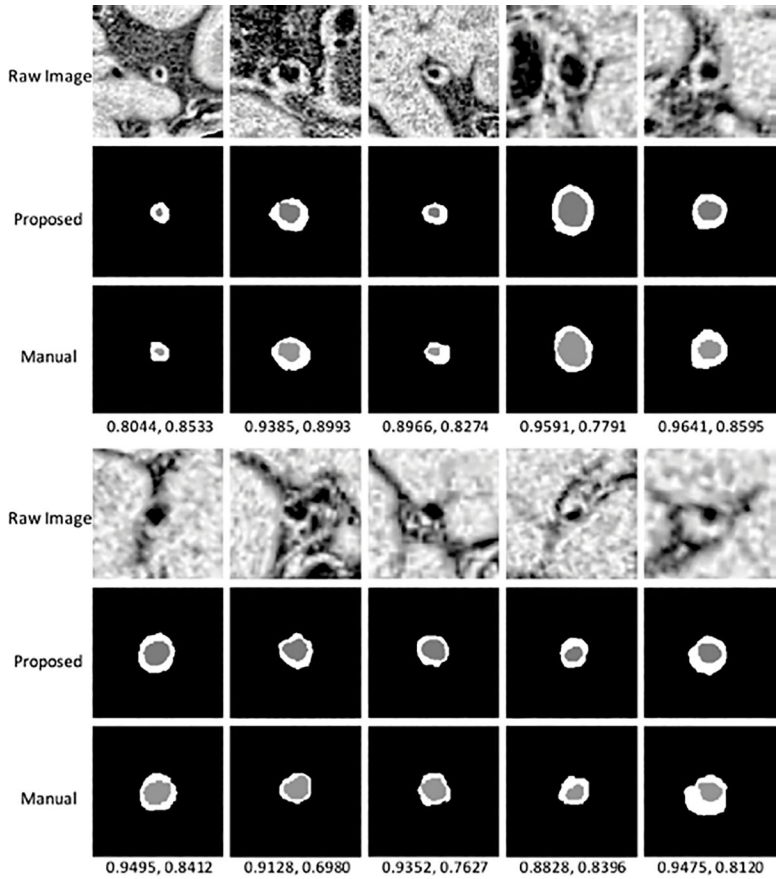

Fig. 4.

Illustration of segmentation results from 10 random subjects. The numbers below the manual results show Dice coefficient of lumen and vessel wall, respectively.

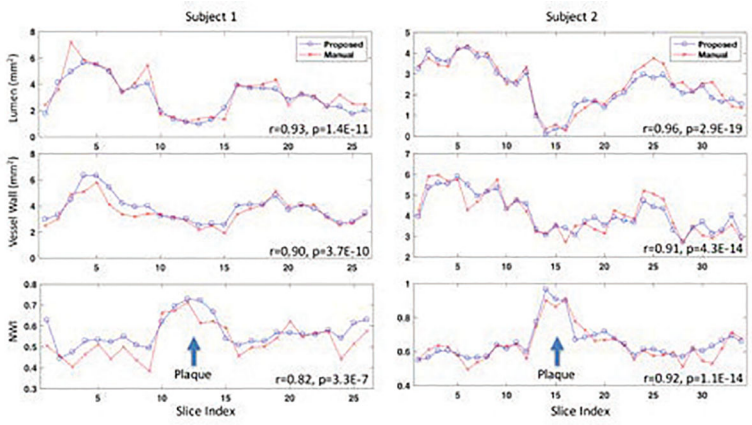

Fig. 5.

Results of lumen area, wall area, and NWI from 2 testing subjects, showing comparable patterns for determining plaque existence and measuring its characteristics.

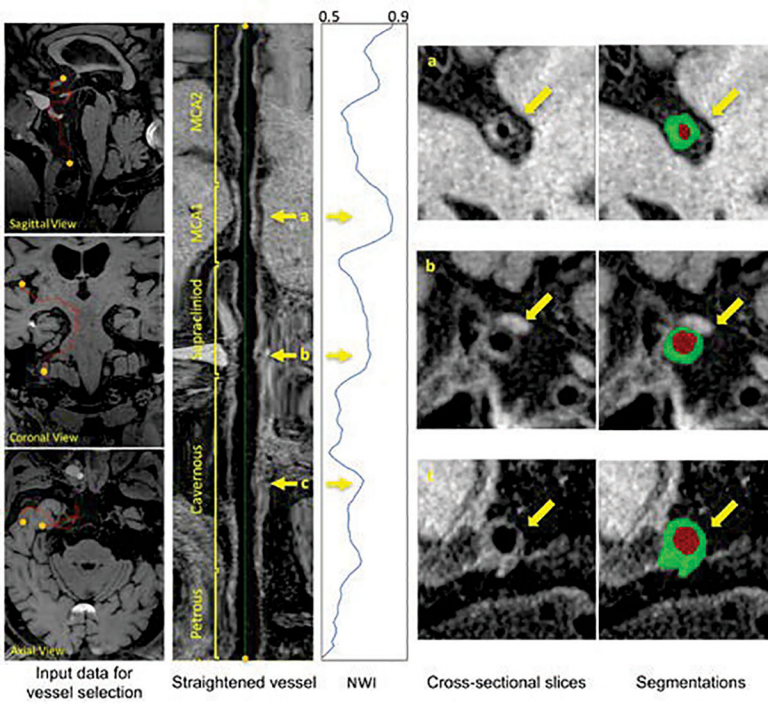

Fig. 6.

Illustrations of the anterior circulation vessel wall analysis for a subject. From left to right, after defining the start and ending points, the intracranial internal carotid artery and middle cerebral artery are centerline tracked and straightened. The sliced images are then processed with the proposed segmentation and used to calculate NWI. Three interested locations in the vessel, as marked by yellow arrows, could be further checked for the NWI values, cross-sectional slices and their corresponding segmentations.

TABLE I.

Demographic data of 24 patients

	Symptomatic	Asymptomatic	p-value
Number	12	12	-
Age (yrs)	48.1±10.9	49.2±13.1	0.83
Male	6 (50%)	9 (75%)	0.23
Stenosis located in the left MCA (others are at right MCA)	6 (50%)	6 (50%)	1

TABLE II.

Morphology analysis of vessel in 24 patients with a high-grade (>50% diameter stenosis) intracranial atherosclerotic plaques at the middle cerebral artery M1 segment.

		Symptomatic (n=12)		Asymptomatic (n=12)		t	p
		Mean	Std	Mean	Std		
Lumen area (mm^2)	Peak slice	1.31	0.62	1.63	0.76	−1.14	0.2647
	3 slices	1.59	0.54	1.90	0.71	−1.18	0.2494
	5 slices	1.96	0.57	2.29	0.74	−1.22	0.2369
Wall area (mm^2)	Peak slice	7.53	1.60	6.62	1.92	1.26	0.2218
	3 slices	7.41	1.15	6.36	1.84	1.66	0.1104
	5 slices	7.35	1.19	6.27	1.73	1.77	0.0904
NWI	Peak slice	0.86	0.04	0.81	0.06	2.30	0.0312 *
	3 slices	0.83	0.04	0.77	0.05	2.96	0.0073 *
	5 slices	0.79	0.04	0.73	0.05	3.16	0.0045 *

Note: “Std” denotes standard deviation. Two-sample t-tests were used for group comparison, where t and p were provided.

* denotes significance reached ($p<0.05$).