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A Validated Orthopaedic Surgical Simulation Model for Training and Evaluation of Basic Arthroscopic Skills

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Background: To our knowledge, there is currently no validated educational model to evaluate and teach basic arthroscopic skills that is widely accessible to orthopaedic residency training programs. The primary objective was to design and to validate a surgical simulation model by demonstrating that subjects with increasing level of training perform better on basic arthroscopic simulation tasks. The secondary objective was to evaluate inter-rater and intrarater reliability of the model.

Methods: Prospectively recruited participants were divided by level of training into four groups. Subjects performed six basic arthroscopic tasks using a box model: (1) probing, (2) grasping, (3) tissue resection, (4) shaving, (5) tissue liberation and suture-passing, and (6) knot-tying. A score was calculated according to time required to complete each task and deductions for technical errors. A priori total global score, of a possible 100 points, was calculated by averaging scores from all six tasks using equal weights.

Results: A total of forty-nine participants were recruited for this study. Participants were grouped by level of training: Group 1 (novice: fifteen medical students and interns), Group 2 (junior residents: twelve postgraduate year-2 or postgraduate year-3 residents), Group 3 (senior residents: sixteen postgraduate year-4 or postgraduate year-5 residents), and Group 4 (six arthroscopic surgeons). The mean total global score (and standard deviation) differed significantly between groups (p < 0.001): 29.0 ± 13.6 points for Group 1, 40.3 ± 12.1 points for Group 2, 57.6 ± 7.4 points for Group 3, and 72.4 ± 3.0 points for Group 4. Pairwise comparison with Tukey correction confirmed construct validity by showing significant improvement in overall performance by increasing level of training between all groups (p < 0.05). The model proved to be highly reliable with an intraclass correlation coefficient of 0.99 for both inter-rater and intra-rater reliability.

Conclusions: A simulation model was successfully designed to teach and evaluate basic arthroscopic skills showing good construct validity. This arthroscopic simulation model is inexpensive, valid, and reliable and has the potential to be implemented in other training programs.

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A VALIDATED ORTHOPAEDIC SURGICAL SIMULATION MODEL FOR TRAINING AND EVALUATION OF BASIC ARTHROSCOPIC SKILLS

There has been a recent emphasis to incorporate medical simulation models into structured educational curricula in response to ongoing concerns over work-hour restrictions, patient safety, and the impact of fellowship training on residency education^{1,2}. A survey of surgical residents found that 26% of trainees worried about not feeling confident to operate independently before the end of their training³. Although arthroscopic procedures are among the most commonly performed surgical procedures in orthopaedics, they are technically challenging for most learners and difficult for educators to teach⁴. Senior residents have reported feeling that they are less prepared in arthroscopic surgical procedures compared with open surgical procedures and thinking that there is insufficient time dedicated to arthroscopic training⁵.

The American Board of Orthopaedic Surgery (ABOS) and the Orthopaedic Surgery Residency Review Committee (RRC) of the Accreditation Council for Graduate Medical Education recently approved mandates to implement surgical simulation training in all orthopaedic residency programs⁶. The changes in program requirements were primarily targeted to postgraduate year 1 (PGY-1) by introducing basic motor skills training commonly used in the initial management of orthopaedic patients in the emergency department and operating room. The Surgical Skills Task Force developed a structured educational curriculum consisting of seventeen simulation modules that is now offered on the ABOS web site⁶. These serve as a guide to individual residency programs to facilitate the development of their own skills program at their respective institutions. However, the content of these modules and the performance metrics have yet to be evaluated for validity and reliability. The ABOS acknowledges the need for dedicated studies to refine and to improve future models⁶.

Simple box trainers have been proven to be highly effective in teaching basic technical skills in areas of urology, gynecology, and general surgery^{$7-10$}. However, no such model has been validated for arthroscopic skills training in orthopaedic surgery. The purpose of this study was to construct and to validate a box model consisting of training modules with reliable performance metrics that are directed at evaluating specific psychomotor elements that are fundamental to arthroscopy. Our primary objective was to assess construct validity of the model using a global score assigned for the overall model. The secondary objective was to evaluate inter-rater and intra-rater reliability using the same global score. To assess validity, we hypothesized that subjects with increasing level of training in arthroscopy would perform better on basic arthroscopic simulation tasks. Our second hypothesis was that the model would show moderate to high inter-rater and intra-rater reliability.

Materials and Methods

Full approval for this study was granted by the research ethics committee at our institution. A nominal group technique was used to generate ideas for designing a pilot arthroscopic simulation skills model and establishing evaluation criteria¹¹. To establish face validity, the content development group consisted of a panel of four senior arthroscopic surgeons and senior orthopaedic residents. A preliminary list of basic arthroscopic skills and tasks was derived from expert opinion and review of the literature. After structured

discussions, a refined list of arthroscopic tasks based on consensus opinion was generated. Each task was designed to incorporate different basic skills such as handling tissue with the dominant and the nondominant hand, camera spatial orientation, optimizing depth perception, and using multiple instruments while working in different planes. A modified version of the McGill Inanimate System for Training and Evaluation of Laparoscopic Skills (MIS-TELS) scoring metrics system was adapted to our model¹². The maximum allotted time for each task was determined by ensuring that the members of the content development group could finish the exercises with sufficient time remaining.

Eligible subjects were voluntarily recruited in February and March 2014. All subjects signed an informed consent form and no stipend was given. The participants included fourth-year medical students applying to orthopaedic residency programs, orthopaedic residents, and subspecialtytrained arthroscopic surgeons, all from a single institution. Orthopaedic fellows and members of the content development group were excluded. To assess construct validity, participants were grouped by level of training: Group 1 (novice: medical students and PGY-1 residents), Group 2 (junior residents: PGY-2 and PGY-3 residents), Group 3 (senior residents: PGY-4 and PGY-5 residents), and Group 4 (arthroscopic surgeons). Each subject performed six basic arthroscopic tasks using a box model: (1) probing, (2) grasping, (3) tissue resection, (4) shaving, (5) tissue liberation and suturepassing, and (6) tissue approximation and arthroscopic knot-tying. The training box was opaque and measured $23 \times 18 \times 15$ cm. The sides of the box were composed of a synthetic membrane in which standardized premade portals were placed. Portal placement varied according to the exercise being performed. The optical system consisted of a 30° arthroscope, camera, light source, and video monitor (Arthrex, Naples, Florida).

Before beginning each task, the participants watched a short, twominute video showing proper performance of each exercise. Participants were videotaped using a camera focused exclusively on the video monitor. Audio was muted to prevent identification of any participant. Participants were assigned a random identification number selected from sealed envelopes for subsequent scoring. The grading was done by two independent and blinded reviewers (R.P.C. and J.C.S.) during two sessions held four weeks apart, a delay previously used for measuring intra-rater reliability^{13,14}. A score was assigned for each task based on time to complete the task and deductions incurred for technical errors (Total Score = Timing Score – Penalty Score). The following is a complete description of how the scores were calculated. Given that some tasks had different maximum raw scores, the scores for each task were transformed to a scale from 0 to 100. A final global score of a possible 100 points was calculated by averaging the scores from all six tasks using equal weights.

Description of How Scores Were Calculated for Each Task

For each exercise, a timing score was calculated by subtracting the time to completion from a maximum allotted time in seconds. Precision was objectively scored by calculating a penalty score for each exercise as described below. A total score for each task was calculated by subtracting a penalty score from the timing score (Total Score = Timing Score – Penalty Score). For example, the maximum allotted time for task 1 is 180 seconds. If a participant were to complete task 1 in eighty seconds, he or she would obtain a timing score of 100 points. If he or she then received a 40-point deduction for a penalty score, the total score for task 1 would be 60 points. The lowest possible total score was 0, as no negative scores were assigned.

Task 1: Triangulation and Probing (Maximum Time, 180 Seconds; Maximum Score, 180 Points)

The participant had to identify three synthetic tissue tears of differing morphology hidden in separate locations. The probe was used to uncover a hidden symbol beneath each tear (Fig. 1-A). When the test proctor determined that the entire symbol was visualized, the participant was instructed to proceed. Five points were deducted each time the probe left the field of view. This error parameter reflects economy of movement and has been applied to other scoring

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Fig. 1

Basic arthroscopic skills tasks. Fig. 1-A Triangulation and probing. Fig. 1-B Grasping and transferring objects. Fig. 1-C Tissue resection. Fig. 1-D Tissue-shaving. Fig. 1-E Tissue liberation and suture-passing. Fig. 1-F Tissue approximation and arthroscopic knot-tying.

systems¹⁵. Failure to identify all three symbols within the maximum allotted time resulted in a score of 0. This task simulated triangulation and probing used during diagnostic arthroscopy.

Task 2: Grasping and Transferring Objects (Maximum Time, 360 Seconds; Maximum Score, 360 Points)

Three black objects and three red objects were positioned beneath Styrofoam balls at standardized locations (Fig. 1-B). The participant had to use a grasper to transfer the objects onto a series of pegs. The right hand was first used to transfer the black objects, followed by the left hand to transfer the red objects. The standardized locations for the objects were chosen so that it would be impossible to complete the task without changing hands. Twenty points were deducted for contacting the Styrofoam balls, as seen in motion analysis scoring with inadvertent tissue collision^{16,17}. Ten points were deducted each time an object was dropped 12 . This task simulated grasping of intra-articular loose bodies inside a knee joint.

Task 3: Tissue Resection (Maximum Time, 420 Seconds; Maximum Score, 420 Points)

A piece of synthetic material was fixed in the shape of a loop. The material had two separate areas, each measuring 2×1.5 cm and containing three colored zones: an inner red zone, a middle blue zone, and an outer green zone (Fig. 1-C). The participant used an "up-biting" resector to completely remove the inner red zones without removing green material. The blue zone gave the participant a margin of error. Five points were deducted for each small square of green material that was removed and 5 points were deducted for each small red square that remained. This task simulated skills required in knee meniscal resection (Video 1).

Task 4: Tissue-Shaving (Maximum Time, 360 Seconds; Maximum Score, 360 Points)

A piece of synthetic material was suspended upside-down. The undersurface of the object had a marked area measuring 5×3.5 cm and contained an inner red zone, a middle blue zone, and an outer green zone (Fig. 1-D). The participant had to use a mechanically powered shaver to remove the inner red zone without damaging the outer green material. The blue zone gave the participant a margin of error. Five points were deducted for each small square of green material that was removed and 5 points were deducted for each small red square that remained. This task simulated skills required in shoulder acromioplasty.

Task 5: Tissue Liberation and Suture-Passing (Maximum Time, 300 Seconds; Maximum Score, 300 Points)

The participant used a tissue elevator to release synthetic material adherent to a wood block by Velcro (Fig. 1-E). The participant then used a suture-passing instrument to pass a number-2 suture through a standardized target on the material. Twenty-five points were deducted for passing suture outside the target. This task simulated skills required in shoulder labral repair.

Task 6: Tissue Approximation and Arthroscopic Knot-Tying (Maximum Time, 240 Seconds; Maximum Score, 240 Points) Subjects first watched a three-minute video on how to perform an arthroscopic sliding knot¹⁸. A piece of synthetic material containing a premade tear measuring 3.5 cm was attached over a spherical surface. Both sides of the tear had marked targets through which the subject needed to pass two limbs of a suture (Fig. 1-F). The subject approximated the tear edges by performing a slidinglocking knot followed by three half hitches. Twenty points were deducted for failure to pass the suture through the marked targets. Failure to tie an arthroscopic sliding-locking knot resulted in a 50-point deduction. Twenty-five points were deducted for incomplete tissue approximation. Only the suturepassing portion of this exercise was timed. This task simulated skills required in rotator cuff repair.

Two trials were performed for each task to allow subjects to familiarize themselves with the model and handling of the instruments 19 . Only the scores from the second trial were used in the statistical analysis to allow for a learning curve. The data were initially assessed for normality, and

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*The values are given as the mean and the standard deviation, in points. †The values are given as the p value.

continuous variables are reported as the mean and the standard deviation. Construct validity was measured using one-way analysis of variance (ANOVA) to assess differences in performance between groups for each task and total global score. A post hoc pairwise comparison with Tukey correction was used to compare the overall performance with level of training. Reliability was calculated using an intraclass correlation coefficient. Interrater reliability was measured between two blinded observers with use of the penalty scores and the total global score, and intra-rater reliability was measured for the same observer at four weeks apart. Significance was set at p < 0.05.

Source of Funding

There was no financial support for this study. The arthroscopic equipment was provided on loan from Arthrex (Naples, Florida).

Results

A total of forty-nine participants were voluntarily recruited for this study, which included thirty-six of forty residents from our training program. Participants were grouped by level of training: Group 1 (fifteen medical students and interns), Group 2 (twelve PGY-2 or PGY-3 residents), Group 3 (sixteen PGY-4 or PGY-5 residents), and Group 4 (six arthroscopic surgeons).

The mean timing scores, penalty scores, and total scores for each task are shown for each group in Table I. The ANOVA for each individual task showed a significant

Fig. 2

Box-and-whisker plot comparing overall performance (total global score) by level of training. The box height represents the 25% to 75% interquartile range, and the means of each group are shown by the diamonds. The whiskers represent the range of maximum and minimum scores for each group.

difference in scores according to the level of training $(p =$ 0.0015 for task 5 and $p < 0.001$ for all other tasks). The mean total global score of a maximum 100 points differed

*The values are given as the group difference between the mean global score and the adjusted 95% confidence interval (determined with use of the Tukey correction), in points.

significantly between groups ($p < 0.001$): 29.0 \pm 13.6 points for Group 1, 40.3 ± 12.1 points for Group 2, 57.6 ± 7.4 points for Group 3, and 72.4 ± 3.0 points for Group 4 (Fig. 2). A pairwise comparison using a Tukey correction further showed significant improvement in overall performance by increasing level of training between all groups ($p < 0.05$) (Table II). Finally, the intraclass correlation coefficient for inter-rater reliability of the penalty scores was 0.96 and the mean intra-rater intraclass correlation coefficient for both reviewers was 0.99 (Table III). The intraclass correlation coefficient for the total global score was 0.99 for inter-rater reliability and 0.99 for intra-rater reliability.

Discussion

The purpose of this study was to develop and validate a model consisting of different novel box modules that simulate basic skills commonly used across a wide range of arthroscopic procedures. The intention was to create a model that could eventually be used as an educational tool to evaluate and to teach fundamental arthroscopic skills to orthopaedic trainees. The results of this study confirmed construct validity by showing significant improvement in overall performance between all groups according to the level of training. Internal consistency of the model was also demonstrated by showing that all six tasks discriminated well between groups when analyzed individually.

When creating an objective scoring system to assess surgical skills, time to completion has been a popular parameter^{16,20,21}. Although speed is an important measure of effiA VALIDATED ORTHOPAEDIC SURGICAL SIMULATION MODEL FOR TRAINING AND EVALUATION OF BASIC ARTHROSCOPIC SKILLS

ciency, it cannot fully detail the psychomotor skills that the trainee lacks. With this in mind, we designed performance metrics that rewarded both efficiency and precision. To ensure that the scoring system was objective and reproducible, the reliability of the measuring system was tested by evaluating inter-rater and intra-rater reliability. The overall model proved to be highly reliable, with 0.99 intraclass correlation coefficients for both inter-rater and intra-rater reliability. The exceptionally high reliability of our model is partially attributed to the fact that timing scores accounted for one of two components in the calculation of the overall global score. The timing scores are objective and remained constant between raters. Therefore, only the penalty scores accounted for the variability between raters, which is used to measure the intraclass correlation coefficients. Some of the most inexperienced participants who incurred the highest number of penalties also scored 0 on their timing score because of their inability to complete the task in the allotted time. This resulted in a total score of 0 for that task, thus making obsolete any discrepancy between raters when recording penalty scores for these participants. This further minimized the subjectivity in the scoring metric and variability between raters, where one would expect to have the highest variability. However, this would only partially contribute to a high intraclass correlation coefficient when analyzing the raw data and the mean scores for Group 1, as few participants actually scored 0 during individual tasks (Table I). A more plausible explanation is that both timing and penalty scores in this model have a high intra-rater and inter-rater reliability. The fact that some of the participants scored 0 for some of the tasks could also result in a floor effect in our scoring system. However, the overall scores were confirmed to be normally distributed, ensuring no floor or ceiling effect in our scoring metrics.

The box trainer model designed in this study is inexpensive, is reusable, and requires little maintenance. Costs are given in U.S. dollars. The total cost of designing and building the model was \$800. However, this value is an overestimate of the true cost to build the model as a substantial portion of the material was wasted on earlier prototypes. The modular synthetic tissue components used in the tissue resection and shaving tasks (tasks 3 and 4) cost \$50 and provided enough material for approximately 100 trials. In contrast, human cadavers have limited availability, poor cadaveric tissue compliance, and high cost, all of which substantially limit their use²². The use of live animals is also problematic because of ethical concerns and the need for specialized facilities. Recent advances in virtual reality technology have demonstrated its potential for enhancing surgical skills training^{16,21,23}. However, studies evaluating the preferences of surgical residents have found no difference between video box trainers and virtual reality simulators²⁴. Financial considerations and high startup costs are also obstacles to widespread adoption of virtual reality simulators²⁵. In fact, 87% of orthopaedic program directors identified a lack of available funding as the most important barrier to implementing a formal surgical skills program¹.

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Fidelity is the degree to which the device simulates reality. In the current study, the box model had inherent limitations typical of other low-fidelity models. This model was not designed to assess aspects such as fluid management, portal placement, and application of varus or valgus stresses to work in different intra-articular compartments of the knee. However, when learning basic skills, fidelity has been shown to be much less important than other factors, such as feedback, repetition, and individualized learning²⁶. Studies in other subspecialties have shown no difference in the performance and learning of surgical skills between low-fidelity and high-fidelity models²⁷. This model was intended to teach essential motor skills such as visual-spatial perception and hand-eye coordination. This objective is supported by the fact that low-fidelity box models have proven learning benefits in other surgical disciplines^{7,9,10}. MISTELS¹² is a low-fidelity model that has been successfully validated and implemented into a variety of surgical training programs, including its incorporation into the Fundamentals of Laparoscopic Surgery (FLS) training course, a certification requirement by the American Board of Surgery²⁸. Low-fidelity models, when applied correctly to appropriate learners, can confer the same learning benefit as high-fidelity models²⁷.

This model is currently one of the largest studies evaluating a surgical simulation model in orthopaedic sur $gery^{29-32}$. Our validated and reliable model is appropriate for teaching basic arthroscopic skills. As programs begin to adopt competency-based curricula, valid and reliable simulation tools that are practical and affordable will be essential to help improve resident learning and structured assessment. \blacksquare

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