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# Extended vertical lists for temporal pattern mining from multivariate time series

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# Abstract

In this paper, the problem of mining complex temporal patterns in the context of multivariate time series is considered. A new method called the Fast Temporal Pattern Mining with Extended Vertical Lists is introduced. The method is based on an extension of the level-wise property, which requires a more complex pattern to start at positions within a record where all of the subpatterns of the pattern start. The approach is built around a novel data structure called the Extended Vertical List that tracks positions of the first state of the pattern inside records and links them to appropriate positions of a specific subpattern of the pattern called the prefix. Extensive computational results indicate that the new method performs significantly faster than the previous version of the algorithm for Temporal Pattern Mining; however, the increase in speed comes at the expense of increased memory usage.

# Keywords

frequent pattern mining; level-wise property; temporal patterns; time-interval patterns; vertical data format

# 1 | INTRODUCTION

Continuously expanding resources for computing, data storage, and transmission have enabled pattern mining in complex data sets emerging from various domains such as transaction databases (Agrawal, Imielinski, & Swami, 1993a; Agrawal, Imielinski, & Swami, 1993b), web mining (Srivastava, Cooley, Deshpande, & Tan, 2000), Internet of

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CONFLICT OF INTEREST

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Things (Chen et al., 2015; Tsai, Lai, Chiang, & Yang, 2014), medicine (Batal et al., 2016; Hauskrecht et al., 2013), fraud detection (Seeja & Zareapoor, 2014), finance (Tiple, Cavique, & Cavalheiro Marques, 2017), and so on. This paper demonstrates the problem of extracting temporal patterns (TPs) from multivariate time series records. The primary contribution of the paper is a faster algorithm for mining class-specific patterns that have temporal relations between their states. The motivation behind this contribution was to develop an algorithm that could be built into real-time analytical engines.

Frequent pattern mining is the problem of finding all TPs that appear frequently in a database (Agrawal et al., 1993a; Agrawal et al., 1993b); (Yun, Lee, & Lee, 2016). In the simplest case, such patterns are frequent itemsets or subsets of items that appear in a significant proportion of transactions of the database (Agrawal et al., 1993b). Sequential pattern mining is an extension of the frequent itemset mining where the order of items or subsets of items is available (Zaki, 2001; Ayres, Flannick, Gehrke, & Yiu, 2002). TPs arise in a natural way where additional temporal information (e.g., start and end times of the events) is available (Moskovitch & Shahar, 2015). This case is the primary focus of this paper. Frequent graph mining (Kuramochi & Karypis, 2001; Zaki, 2005) is another direction of frequent pattern mining with such applications as clustering of XML documents (Aggarwal, Ta, Wang, Feng, & Zaki, 2007), chemical compound classification (Deshpande, Kuramochi, Wale, & Karypis, 2005), and so on. Uncertain pattern mining is a relatively new research direction where each item is present in a database with a certain probability (Tong, Chen, Cheng, & Yu, 2012; Lee & Yun, 2017).

In this paper, a new algorithm called the Fast Temporal Pattern Mining with Extended Vertical Lists (FTPMwEVLs) for mining frequent TPs (FTPs) is introduced. The idea is to utilize the level-wise (Aggarwal & Han, 2014) property on the level of pattern positions inside records. The level-wise property states that a TP may appear only in the records where all of its subpatterns appear. For example, if pattern "heart rate (HR) is very high before blood pressure (BP) is low" is found in record *i*, then both its subpatterns "HR is very high" and "BP is low" must appear in record *i*. The level-wise property was used to reduce the search space for mining TPs (Batal et al., 2016; Moskovitch & Shahar, 2015) and similar notions as itemsets (Zaki, 2000) and sequential patterns (Ayres et al., 2002; Zaki, 2001) via the vertical data format (Zaki, 2000) that tracks the occurrences of the pattern inside records. We suggest a new data structure called the Extended Vertical List (EVL) that keeps track of positions of the first state of the TP inside the records and links them to the positions of a prefix of the TP (a subpattern obtained by removing the first state of the TP) inside the records. This idea allows to reduce the computational time of FTPMwEVL by a factor of several hundreds on several data sets (Section 5). The increase in speed comes at the cost of increased memory usage that is a common trade-off in such algorithms.

This paper continuous our previous work (Kocheturov & Pardalos, 2018) in the following ways: introduction of the EVL data structure, introduction of the smallest chain for faster pattern verification, and extensive computational results to demonstrate the effectiveness of the suggested approach. The algorithm is an improved version of the method for Frequent Pattern Mining by Batal, Valizadegan, Cooper, and Hauskrecht (2011), hereinafter referred to as the Fast Temporal Pattern Mining (FTPM), where the TP is defined with no additional

constraints. The output of the new algorithm coincides with the output of FTPM because it finds all FTPs. Therefore, the increased speed of mining is the main focus and the main result of this paper. The applicability of the mined patterns for a consecutive classification of the records was not analyzed.

The rest of the paper is organized as follows. We review related work and recent developments in Section 2. Section 3 provides a formal statement of the problem and all supporting definitions. We present the FTPMwEVL algorithm in Section 4 and provide the computational results in Section 5. Section 6 concludes the paper.

# 2 | RELATED WORK

The problem of mining FTPs considered in this paper deals with a special case of TPs called the time-interval relationship patterns that are referred to hereafter as TPs for simplicity. Each TP is a sequence of states, or time-interval events, with temporal relationships defined for each pair of the states (Definitions 1 and 2). Many multivariate time series classification methods are not applicable when records are composed of multivariate time series sampled unevenly in time. The FTP mining approach is a perfect candidate in this situation.

To define temporal relationships between states in a pattern, Allen's 13 temporal relations are usually used (Allen, 1984): *before, equal, meets, overlaps, during, starts, finishes*, and the other six are obtained by inverting. The first seven relations are enough if the states are ordered appropriately. In this paper, only two temporal relations *before* and *co-occurs* (the later combines *equal, meets, overlaps, during, starts*, and *finishes*) are used because the initial seven relations are ambiguous in the presence of noise and temporal data with a high sampling frequency (Batal, Fradkin, Harrison, Moerchen, & Hauskrecht, 2012), which leads to the problem of pattern segmentation (Moerchen, 2006).

After converting multivariate time series records to multivariate state sequences (MSSs; Definition 1), the number of state intervals per sequence was at the level of several hundreds for the data sets studied in this paper. In this situation, the breadth-first search algorithms are more efficient than those using depth-first search. Several depth-first algorithms were introduced over the years for mining of FTPs (Moskovitch & Shahar, 2015; Patel, Hsu, & Lee, 2008; Papapetrou, Kollios, Sclaroff, & Gunopulos, 2009; Winarko & Roddick, 2007; Wu & Chen, 2007). The approach by Moskovitch et al. named KarmaLego was reported to outperform other depth-first search methods (Moskovitch & Shahar, 2015). KarmaLego failed to mine all TPs for a majority of the data sets considered in Section 5; therefore, the computational section presents results for FTPMwEVL and FTPM only. Both methods are breadth-first search. The efficiency of bread-first search comes from the fact that careful pattern elimination is paramount when MSSs consist of a large number of state intervals.

# 3 | PROBLEM DEFINITION

We follow the definitions given in Batal et al. (2011) with slight modifications for the presentation to be self-contained.

Assume data set *D* of *n* records  $d_i = (x_1^i, x_2^i, ..., x_m^i, y_i), i = 1, ..., n$ , where each record is composed of *m* time series  $x_j^i \in X_j$  and an outcome, or class label,  $y_i \in Y$ . We start with reducing dimensionality by converting each time series into a set of temporal abstractions in the form

$$\langle (V_1, s_1, e_1), \dots, (V_k, s_k, e_k) \rangle,$$

where  $V_i \in \Sigma$  is a temporal abstraction that is in effect from start time  $s_i$  till end time  $e_i$ , for example, temporal abstraction ("low", 5, 12) means that the time variable was low from time moment 5 till time moment 12;  $\Sigma$  is the alphabet or set of possible abstractions (e.g.,  $\Sigma =$ {"low," "normal," and "high"}). For a given set of temporal abstractions, we also require  $s_1$  $e_1$   $s_2$  ...  $s_k$   $e_k$ , meaning that no abstraction can start earlier than any previous one finishes.

The alphabet  $\Sigma$  can be defined in several ways. In this paper, we focus on value and trend abstractions. Value abstraction can be defined in the following ways:  $\Sigma = \{\downarrow\downarrow, \downarrow, -, \uparrow, \uparrow\uparrow\}$ , where  $\downarrow\downarrow, \downarrow, -, \uparrow, \uparrow\uparrow$  stand for "very low," "low," "normal," "high," and "very high," respectively. Exact ranges for transformation may be defined by a field expert. Trend abstractions may include  $\Sigma = \{\rightarrow, \nearrow, \downarrow\}$ , where  $\rightarrow, \nearrow$ , and  $\downarrow$  stand for "steady," "increasing," and "decreasing," respectively. For this transformation, we used the approach by Keogh, Chu, Hart, and Pazzani (2004). If one decides to combine several ways and let the time abstractions overlap, copying the time series and applying one way per copy solve the issue.

#### Definition 1.

- S = (F, V) is a state, where *F* is a variable label and  $V \in \Sigma$  is an abstraction value.
- E = (F, V, s, e) is a state interval, where pair (F, V) forms a state and *s* and *e* are the start and end times of the state interval.
- $Z = \langle E_1, ..., E_l \rangle$  is a MSS with the states sorted according to the nondecreasing order of their start times:  $E_{i\cdot}s = E_{i+1} \cdot s$ , 1 = i = l 1.<sup>1</sup>

**Example 1.**  $S = (\text{HR}, \downarrow)$  is a *state* that indicates that temporal variable HR is at the low level. State interval  $E = (\text{HR}, \downarrow, 12, 15)$  extends the state by including information about its start and end time moments. Finally, an MSS combines several state intervals coming from different time series as in MSS  $Z = \langle E_1 = (\text{HR}, -, 0, 3), E_2 = (\text{BP}, \downarrow, 1, 9), E_3 = (\text{HR}, \downarrow, 4, 7), E_4 = (\text{HR}, -, 8, 11), E_5 = (\text{BP}, -, 10, 17), E_6 = (\text{HR}, \downarrow, 12, 14), E_7 = (\text{HR}, \downarrow\downarrow, 15, 19), E_8 = (\text{BP}, \downarrow, 18, 22), E_9 = (\text{HR}, \downarrow, 20, 29), E_{10} = (\text{BP}, \uparrow\uparrow, 23, 26), E_{11} = (\text{BP}, \downarrow, 27, 31), E_{12} = (\text{HR}, -, 30, 38), \text{ and } E_{13} = (\text{BP}, -, 32, 36) \rangle$  (Figure 1).

For two state intervals  $E_i$  and  $E_j$  with  $E_{i,s}$   $E_{j,s}$ , we say that  $E_i$  finishes before  $E_j$  if  $E_{i,e} < E_{j,s}$  and denote it as  $R(E_i, E_j) = b$ . Otherwise, we say that  $E_i$  co-occurs with  $E_j$  and denote it as  $R(E_i, E_j) = c$ .

<sup>&</sup>lt;sup>1</sup>If  $E_{i}s = E_{i+1}s$ , an order over the time variables is assumed to resolve the ambiguity.

TP is the next level of abstraction, which allows removing exact values of start and end times and focuses on temporal relationships of the state intervals.

#### Definition 2.

 $P = (\langle S_1, ..., S_k \rangle, R)$  is a TP of size k (|P| = k) with states  $S_1, ..., S_k$ , where R is a (upper triangular) matrix describing pairwise temporal relationships between the states:  $R_{i,j} \in \{b, c\}, 1 \quad i < j \quad k^2$ 

#### **Definition 3.**

Given MSS  $Z = \langle E_1, E_2, ..., E_l \rangle$  and TP  $P = (\langle S_1, ..., S_k \rangle, R)$   $(k \ l)$ , we say that Z contains P, denoted as  $P \in Z$ , if there is a mapping  $\pi : \{1, ..., k\} \rightarrow \{1, ..., l\}$  that matches every state  $S_i$  in P to a state interval  $E_{\pi(i)}$  in Z such that:

- 1.  $S_{i}F = E_{\pi(i)}F$  and  $S_{i}V = E_{\pi(i)}V$ , 1 *i k*,
- 2.  $\pi(i) < \pi(j), i < j,$
- 3.  $R(E_{\pi(i)}, E_{\pi(j)}) = R_{ij}, i < j.$

The first requirement guarantees that each state of P matches an appropriate state interval in Z, whereas the rest of the constraints enforce that the temporal relations in P correspond to a correct overlapping of the state intervals in Z.

**Example 2**.  $P = (\langle S_1, S_2, S_3 \rangle, R)$  is a TP of Size 3 (Figure 2a) with states  $S_1 = (\text{HR}, -), S_2 = (\text{BP}, -), S_3 = (\text{HR}, \downarrow)$  and relationships matrix  $R = (R_{1,2}, R_{1,3}, R_{2,3})$ , where  $R_{1,2} = c, R_{1,3} = b$ , and  $R_{2,3} = c$ . The MSS in Figure 1 contains this TP because state intervals  $E_4 = (\text{HR}, -, 8, 11), E_5 = (\text{BP}, -, 10, 17), \text{ and } E_6 = (\text{HR}, \downarrow, 12, 14)$  match the states of *P* and the time relationships are satisfied. For example,  $E_4 \cdot e = 11 > 10 = E_5 \cdot s$ , and therefore, state intervals 4 and 5 co-occur ( $R(E_4, E_5) = c$ ).

#### **Definition 4.**

 $\widetilde{P}$  is a subpattern of *P*, denoted as  $\widetilde{P} \subset P$ , where  $|\widetilde{P}| = \widetilde{k}$ , |P| = k, |P| = k, and  $\widetilde{k} < k$ , if there is mapping  $\pi: \{1, ..., \widetilde{k}\} \rightarrow \{1, ..., k\}$  such that:

 $\widetilde{S}_i = S_{\pi(i)}, 1 \le i \le \widetilde{k}$ , where  $\widetilde{S}_i$  and  $S_{\pi(i)}$  are states in  $\widetilde{P}$  and P, respectively,

 $\pi(i) < \pi(i), i < j,$ 

$$\widetilde{R}_{i, j} = R_{\pi(i), \pi(i)}, \ 1 \le i \le \widetilde{k}$$

•  $\widetilde{P}$  is a prefix of *P*, denoted as  $\widetilde{P} = \text{prefix}(P)$ , if

 $\widetilde{P} \subset P$  $\widetilde{k} = k - 1$  $\pi(i) = i + 1, i = 1, ..., \widetilde{k}$ 

 $<sup>{}^{2}</sup>R_{i,j}$  is defined for states *i* and *j* of the pattern.  $R(E_{i}, E_{j})$  is computed for state intervals *i* and *j* of the MSS.

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In other words, prefix(P) is a subpattern of *P* obtained by removing the first state of *P*.

**Example 3**. TP *P* in Figure 2a has three subpatterns: the subpattern without the last state (Figure 2b), the subpattern without the middle state (Figure 2c), and its prefix, the subpattern without the first state (Figure 2d).

From the previous definitions, the following corollary easily follows:

**Corollary 1.** If  $\tilde{P} \subset P$  and  $P \in Z$ , then  $\tilde{P} \in Z$ .

The goal is to mine class-specific TPs that appear in a majority of MSSs belonging to a particular class. For this purpose, we use the threshold  $\theta \in [0, 1]$  and define the minimum support. Assume that  $D = \{Z_1, ..., Z_n\}$  is a data set of *n* MSSs and  $Y = \{y_1, ..., y_c\}$  is a set of possible classes. Let  $D_i$  denote a set of records from D, which belong to class  $y_i$  (each record belongs to exactly one class).  $Z_i \in D_i$  denotes that record j is in class  $y_i$ .

#### Definition 5.

• For a given TP *P* and class *y*, the support of *P* in class *y*, denoted as support(P,  $D_y$ ), is defined as a number of MSSs from  $D_y$  that contain *P*.

$$\operatorname{support}(P, D_y) = \left| \left\{ Z \in D_y : P \in Z \right\} \right|.$$

• *P* is a FTP in *D* if for some class *y*,

 $\operatorname{support}(P, D_y) \ge \theta \times |D_y|$ .

In other words, *P* is an FTP in *D* if the proportion of MSSs containing *P* is not smaller than threshold  $\theta$  for at least one class.

**Corollary 2.** If  $\tilde{P} \subset P$  and  $\tilde{P}$  is not FTP in D, then P is not FTP in D.

Corollary 2 is a straightforward consequence of Corollary 1 and Definition 5. It is referred to as the level-wise property (Aggarwal & Han, 2014). FTPM as it was given in (Batal et al., 2011) is a breadth-search procedure for finding all FTPs. First, all FTPs of Size 1 are found. Then, a list of candidate TPs of Size 2 is generated. After that, each candidate TP is validated for being an FTP and a list of FTPs of Size 2 is formed. The procedure is repeated until all FTPs are found or some stopping criteria are met; for example, size is no more than a predefined value  $k_{max}$  (see Algorithm 1). Other schemes like depth-first search are possible, but the breadth-search paradigm is important for eliminating incoherent candidate TPs as it can be seen later.

#### Algorithm 1

The high-level description of FTPM algorithm.

Require: D, FTPs of size 1 return FTPs

```
FTPs \leftarrow FTPs of size 1
new-FTPs \leftarrow FTPs of size 1
while |new-FTPs| > 0 and no other criteria are met do
candidates \leftarrow CreateCandidates(new-FTPs, FTPs of size 1)
new-FTPs \leftarrow \emptyset
for all P \in candidates do
if P is FTP in D then
new-FTPs \leftarrow new-FTPs u{P)
end if
end for
FTPs \leftarrow FTPs U new-FTPs
end while
```

The most computationally expensive part of this framework is validating if a candidate TP is frequent. Thus, further careful elimination of infrequent TPs at the step of creating candidates is important. Based on Corollary 2, a TP is frequent only if all of its subpatterns are frequent. For a pattern of size k, we need to verify only if subpatterns of size k - 1 are frequent due to transitivity.

An idea of assigning to each FTP a list of record identifiers that contain it:  $P.ids = \{i : P \in Z_i\}$ , reduces the search space drastically (Batal et al., 2016). It is based on the vertical data format (Zaki, 2000, 2001). Due to Corollary 1, a candidate TP of size k + 1 will appear only in records where all its subpatterns appear as well. Therefore, we need to check only its subpatterns of size k because record id lists of the subpatterns of smaller sizes include the list for at least one subpattern of size k. Such a list is called the *list of potential records*. For a given TP P, it is denoted as  $Pp_ids$  and can be computed as follows:

$$P \cdot p\_ids = \bigcap_{\widetilde{P} \in \operatorname{sub}(P)} \widetilde{P} \cdot ids = \bigcap_{\widetilde{P} \in \operatorname{sub}_k(P)} \widetilde{P} \cdot ids,$$

where  $\operatorname{sub}(P) = \{ \widetilde{P} : \widetilde{P} \subset P \}$  and  $\operatorname{sub}_k(P) = \{ \widetilde{P} : \widetilde{P} \subset P \text{ and } |\widetilde{p}| = k \}$ .

If for all classes the number of the potential records is smaller than the corresponding minimal support values, then this pattern is not frequent, and it can be discarded.

# 4 | FREQUENT TEMPORAL PATTERN MINING WITH EXTENDED VERTICAL LISTS

In this section, we present our approach for FTP mining. The main idea is that, for given MSS and FTP, we keep track of positions (indices of the state intervals in the MSS) where the first state of the pattern appears inside the record. We say that the pattern starts at those positions.

Assume that FTPs of all sizes 1, ..., *k* have been found. A coherent candidate TP P(|P| = k + 1) constructed from FTP  $P_0(|P_0| = k)$  and state *S* (see Batal et al, 2016 for relevant

discussion) has exactly k + 1 subpatterns of size k ( $|sub_k(P)| = k + 1$ ). Some subpatterns may be identical: for example, all subpatterns of Size 2 are the same for the pattern with three identical sates (HR, –), (HR, –), and (HR, –). From  $sub_k(P)$ , no more than k patterns (some may be identical) start with state S, and all of them are in

```
sub_k(P) \setminus prefix(P).
```

It is straightforward to see that *P* cannot start at a position *i* inside *Z* if at least one of the subpatterns from  $sub_k(P) \setminus prefix(P)$  does not start at the same position.

**Example 4**. Assume that we want to find if MSS Z(Figure 1) contains TP P(Figure 2a):

 $p = (\langle (\text{HR}, -), (\text{BP}, -), (\text{HR}, \downarrow) \rangle, R)$ 

with  $R_{1,2} = c$ ,  $R_{1,3} = b$ ,  $R_{2,3} = c$ . Pattern *P* has two subpatterns  $P_1$  (Figure 2b) and  $P_2$  (Figure 2c) that have the same first state (HR, –):

$$P_1 = (\langle (\text{HR}, -), (\text{BP}, -) \rangle, R_{1,2} = c)$$

$$P_2 = \left( \langle (\mathrm{HR}, -), (\mathrm{HR}, \downarrow), \rangle, R_{1,2} = b \right),$$

 $P_1$  starts at Positions 4 and 12 in Z, while  $P_2$  starts at Positions 1 and 4. Thus, *P* may potentially start only at Position 4 where both the subpatterns start. Those positions are potential because there are also time relationships between the states that were not checked yet.

*Remark* 1.  $P_2$  appears 5 times in MSS Z because states (HR, –) and (HR,  $\downarrow$ ) of  $P_2$  match the following pairs of the state intervals of Z:  $(E_1, E_3)$ ,  $(E_1, E_6)$ ,  $(E_1, E_9)$ ,  $(E_4, E_6)$ , and  $(E_4, E_9)$  (in all the cases, time relationship  $R_{1,2} = b$  is satisfied). However, we require the positions of the first state to be relevant only; therefore, Positions 1 and 4 are used.

One may want to store all possible appearances of *P* in MSS *Z*. However, the number of such appearances may grow rapidly (Remark 1). This requires significant memory storage. In turn, storing only starting positions of *P* in the MSS requires significantly less memory because the starting positions are always inside the intersection of the starting positions of the subpatterns form  $sub_k(P)$ \prefix(*P*). Therefore, the number of starting positions is a nonincreasing function of pattern size. Such a trade-off gives the desired speed-up under a reasonable memory consumption increase (Section 5).

In general, for each TP, we assign an EVL, a structure containing information on which MSSs contain the TP, starting positions of the TP inside the MSSs, and the indices of (or links to) the starting positions of the *prefix* of the TP inside the MSSs.

#### **Definition 6.**

- Let *P.EVL* denote EVL associated with *P*.
- Let *P.EVL*[*Z*].*pos* denote starting positions of *P* (positions of the first state of *P*) inside MSS *Z*.
- Let *P.EVL*[*Z*].*ind* denote indices of specific starting positions of prefix(*P*) (positions of the first state of prefix(*P*)) inside MSS *Z*. For position *i* ∈ *P.EVL*[*Z*].*pos*, a corresponding specific index of the prefix position is the index of the smallest prefix position in *Z*, which is larger than *i*:

$$P \cdot EVL[Z] \cdot ind[i] = \min\{j: \widetilde{P} \cdot EVL[Z] \cdot pos[j] > p\},\$$

where  $\tilde{P} = \text{prefix}(P)$  and p = P.EVL[Z].pos[i].

**Example 5.** TP  $P = (\langle S_1, S_2, S_3 \rangle, R)$  (Figure 2a) has states  $S_1 = (\text{HR}, -), S_2 = (\text{BP}, -), S_3 = (\text{HR}, \downarrow)$  and relationships matrix  $R = (R_{1,2}, R_{1,3}, R_{2,3})$ , where  $R_{1,2} = c, R_{1,3} = b$ , and  $R_{2,3} = c$ . Its prefix is  $P_0 = \text{prefix}(P) = (\langle (\text{BP}, -), (\text{HR}, \downarrow) \rangle, (R_{1,2} = c))$  (Figure 2d). In turn, the prefix of  $P_0$  consists of a single state:  $P_{00} = \text{prefix}(P_0) = \text{prefix}(\text{prefix}(P)) = (\langle (\text{HR}, \downarrow) \rangle, \emptyset)$ .

Now, for MSS Z in Figure 1,  $P_{00}.EVL[Z].pos = \{3, 6, 9\}$  because state (HR,  $\downarrow$ ) corresponds to the state intervals  $E_3$ ,  $E_6$ , and  $E_9$  of Z.  $P_{00}EVL[Z].ind = \emptyset$  because  $P_{00}$  does not have a prefix.  $P_0.EVL[Z].pos = \{5\}$  because state (BP, –) corresponds to the state interval  $E_5$  of Z (Remark 1).  $P_0.EVL[Z].ind = \{2\}$ . Finally,  $P.EVL[Z].pos = \{4\}$ , and  $P.EVL[Z].ind = \{1\}$ .

Now, we are ready to present the pseudo-code of the FTPMwEVL algorithm (Algorithm 2).

The EVL data structure allows to achieve three main results. First, it reduces the number of potential starting positions of a candidate TP *P* by intersecting the starting positions of its subpatterns from  $sub_k(P)\prefix(P)$  as in Example 4 and later linking the potential positions to the smallest starting positions of prefix(*P*). Therefore, EVL reduces the number of candidate TPs to check in general (see Algorithm 3 for the pseudo-code). For some MSSs from the data set, the set of potential starting positions may be empty after the intersection meaning that these MSSs will never contain *P* and they can be skipped.

Second, to verify that a candidate TP *P* is indeed inside FTP *Z*, we need to check that the the states of *P* match the state intervals of *Z* and the temporal relationships are satisfied according to Definition 2. However, instead of looking through all possible combinations of appropriate state intervals, EVL allows to check a significantly smaller amount of state intervals combinations: We need to check only the possible starting locations of *P*, from which we can navigate directly to the appropriate state intervals matching the first state of prefix(*P*). But these are the already found starting positions of prefix(*P*); therefore, we may skip some state intervals matching the first state of prefix(*P*), and so on (see Algorithm 4).

# Algorithm 2

# The FTPMwEVL algorithm.

Require: D, FTPs of size 1 return FTPs
FTPs ← FTPs of size 1
new-FTPs ← FTPs of size 1
while $ \text{new-FTPs}  > 0$ and no other criteria are met <b>do</b>
candidates ← CreateCandidates(new-FTPs, FTPs of size 1)
new-FTPs $\leftarrow \emptyset$
for all $P \in$ candidates do
$exposure \leftarrow exposure(P)$
if not FindPotentialPositionsAndIndices(D,P) then
continue
end if
for all $id \in Pp\_ids$ do
<i>new-positions</i> $\leftarrow \emptyset$
$new\_indices \leftarrow \emptyset$
$i \leftarrow 1$
while <i>i</i>   <i>P.EVL</i> [ <i>id</i> ]. <i>pos</i>   do
$pos \leftarrow PEVL[id].pos[i]$
$ind \leftarrow P.EVL[id].ind[i]$
$index \leftarrow Search(prefix(P), D, id, ind, \{pos\}, exposure)$
if $index > -1$ then
$new_positions \leftarrow new_positions \cup \{pos\}$
$new\_indices \leftarrow new\_indices \cup \{index\}$
end if
$i \leftarrow i + 1$
end while
$P.EVL[id].pos \leftarrow new_positions$
$PEVL[id].ind \leftarrow new_indices$
if $PEVL[id].pos = \emptyset$ then
$P.p\_ids \leftarrow P.p\_ids \setminus id$
end if
end for
if P is FTP in D then
new-FTPs $\leftarrow$ new-FTPs U{ <i>P</i> }
end if
end for
FTPs ← FTPs U new-FTPs
end while

Third, EVL allows to check only a portion of the states of *P*. For this purpose, the find the smallest starting chain of *P*.

# Definition 7.

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- $\widetilde{P}$  is a smallest starting chain of *P*, denoted  $\widetilde{P}$  = chain(P), if
  - **1.**  $\widetilde{k} = \min\{l: \nexists j > l \text{ and } i \le l \text{ such that } R_{i, j} = c\}$
  - **2.**  $\widetilde{P} \subset P, |\widetilde{P}| = \widetilde{k}$
  - 3.  $\pi(i) = i, i = 1, ..., \tilde{k}$
- Exposure of *P*, denoted as *exposure*(*P*), is computed as follows:

 $exposure(P) = \begin{cases} |chain(P)| + 1 & \text{if } chain(P) \neq P, \\ |P|, & \text{otherwise}. \end{cases}$ 

### Algorithm 3

Function FindPotentialPositionsandIndices(D, P).

Require: D, P return Boolean
subpatterns $\leftarrow$ sub <sub>k</sub> (P) \ prefix(P)
<b>if</b> subpatterns = $\emptyset$ <b>then return</b> False
end if
$P \cdot p_{-}ids = \cap \widetilde{P} \in sub_{k}(P) \ \widetilde{P} \cdot ids$
if not PotentiallyFrequent(P) then return False
end if
for $id \in Pp_ids$ do
$P.EVL[id].pos \rightarrow \cap \widetilde{P} \in \text{subpatterns} \ \widetilde{P}.EVL[id].pos$
<i>i</i> =1
while <i>i</i>   <i>P.EVL</i> [ <i>id</i> ]. <i>pos</i>   do
pos = P.EVL[id].pos[i]
if $\{j : prefix(P).EVL[id].pos[j] > pos\} = \emptyset$ then
$P\!EV\!L[id].pos \leftarrow P\!EV\!L[id].pos \setminus pos$
else
$PEVL[id].ind[i] = \min\{j : prefix(P).EVL[id].pos[j] > pos\}$
$i \leftarrow i + 1$
end if
end while
if $P.EVL[id].pos = \emptyset$ then
$P.p\_ids \leftarrow P.p\_ids \setminus id$
end if
end for
if not PotentiallyFrequent(P) then return False
end if
return True

#### Algorithm 4

Function Search(P, D, id, ind, positions, exposure).

Require: R D, id, i, positions, exposure return Integer
<i>i</i> =1
while <i>i</i>   <i>P.EVL</i> [ <i>id</i> ]. <i>pos</i>   do
if Check accumulated time relationships in D[id] then
if $exposure = 0$ then return $i$
end if
$pos \leftarrow PEVL[id].pos[i]$
$ind \leftarrow P.EVL[id].ind[i]$
<b>return</b> Search(prefix( $P$ ), $D$ , $id$ , $ind$ , $positions \cap \{pos\}$ , $exposure - 1$ )
end if
$i \leftarrow i + 1$
end while
return – 1

In other words, by the smallest starting chain, we mean the smallest nonempty subpattern at the beginning of P, such that all states of it are strictly *before* the remaining states of P(see Figure 3 for an example). For many long patterns, the corresponding smallest starting chain may be relatively small.

When we check if *P* is inside an MSS, we need to traverse only the states of chain(*P*) and the first state of  $P_{end}$  if any is present because chain(*P*) may be pattern *P* itself. It is easy to see since after we have arrived at the last state of chain(*P*) by recursive search function (Algorithm 4) and checked that all time relationship between the states of chain(*P*) are satisfied, we need to verify only that all the states of  $P_{chain}$  are *before* the next state of *P* after chain(*P*) because all the states of chain(*P*) will be before all the rest of the states of *P* by transitivity. Thus, we need to check |chain(P)| + 1 first states of *P*, if *P* chain(*P*), and all |P| states of *P*, otherwise.

# 5 | COMPUTATIONAL RESULTS

To evaluate the performance of the FTPMwEVL algorithm, we tested it against FTPM on real-life data sets. The TP was defined as in Definition 2 for both algorithms.

All computations were carried out on a virtual server machine with 100 GB of memory and 20 virtual cores with processor speed equivalent to 2.5 GHz each. Only one core was utilized for single-thread computations. C++11 was used as a programming language. All computation times show actual pattern mining time taken by the algorithms after any preprocessing steps such as loading data and converting it into the abstraction domain.

It is important to state that the returned TPs were entirely identical for both algorithms. It leaves computational time and memory usage as the only criteria for algorithm comparison.

For both Tables 1 and 2, the following notation was used. In column "max k," Inf stands for no upper limit on the size of TPs. In column "mem. ratio," *NA* means that the memory ratio is not available due to the fact that FTPM algorithm was not able to find all FTPs in time limit.

#### 5.1 | Acute kidney injury data set

The acute kidney injury (AKI) data set consists of n = 5,202 medical records composed of time series taken during surgical procedures (Korenkevych et al., 2016; Thottakkara et al., 2016). Each record has an outcome associated with it: 1 if AKI was diagnosed after the surgery (2,769 records), and 0, otherwise (2,433 records).

Using the University of Florida Integrated Data Repository, we have previously assembled a single center cohort of perioperative patients by integrating multiple existing clinical and administrative databases at University of Florida Health (Korenkevych et al., 2016; Thottakkara et al., 2016). We included all patients admitted to the hospital for longer than 24 hr following any operative procedure between January 1, 2000, and November 30, 2010. This data set was integrated with the laboratory, the pharmacy, and the blood bank databases and intraoperative database (Centricity Perioperative Management and Anesthesia, General Electric Healthcare, Inc.) to create a comprehensive intraoperative database for this cohort. The study was designed and approved by the Institutional Review Board of the University of Florida Privacy Office.

Two time variables were chosen for examination: mean arterial BP and HR. The value abstractions were used to convert time series from time domain to abstraction domain with percentile values [0.1, 0.25, 0.75, 0.9] and support threshold  $\theta$  (see Definition 5) ranging from 0.5 to 0.9. The comparative data (see Table 1) indicates the superior performance of FTPMwEVL from the computational time point of view. For  $\theta = 0.7$ , FTPMwEVL found all FTPs (there were no FTPs of size more than 18) in 39.58 s using 3,134.2 MB of memory, whereas FTPM spent 34,280.4 s and 402.31 MB to achieve the same result. Therefore, the speed-up was of magnitude 866, whereas the new algorithm used only 7.79 times more memory. We set the computational time limit to 24 h (86,400 s). In this time frame, FTPM was able to mine all FTPs only for  $\theta$  0.7. For  $\theta = 0.6$ , FTPMwEVL found all FTPs (no FTPS of size more than 22), yet FTPM managed to mine FTPs of Size 10 or lower and some of Size 11. In this case, FTPMwEVL took 50.25 s (not shown in the table) to mine all FTPs of Size 11 or lower, and the speed-up column reflects ratio 8,6400s/50.25s = 1,719.3. For  $\theta$ = 0.5, we limited the maximum FTP size to 12 due to FTPMwEVL memory consumption considerations. Still, FTPM mined only FTPs of Size 7 or lower and some of Size 8 in 86,400 s.

As can be seen in Figure 4, the EVLs start working significantly better than the regular vertical lists with increasing FTP size, which happens due to the better indexing strategy that allows eliminating more candidate TPs and validating that a TP is not an FTP faster. Table 1 demonstrates a phenomenon of exponential growth of computational time and memory usage with decreasing threshold level that is the main limitation of this pattern mining paradigm.

# 5.2 | UCR time series classification archive

The remaining data sets were taken from UCR Time Series Classification Archive (Chen et al., 2015). Out of 85 data sets available, only those that have two classes were picked what resulted in 31 data sets. In this archive, each record has only one time series that was converted into two series of time-interval states using both trend and value abstractions. Percentiles [0.1, 0.25, 0.75, 0.9] for value abstractions were used to mine patterns in the UCR data sets, where, for example, all values falling between percentiles 0.1 and 0.25 were considered as low. For trend abstractions, a segment was considered increasing if the slope was positive, and nonincreasing, otherwise. The support threshold  $\theta$  and maximum size k varied in ranges [0.2, 0.8] and [5,  $\infty$ ], respectively, depending on the data set complexity: We pushed the memory consumption of FTPMwEVL to the limit. Therefore, Table 2 reflects the most difficult cases from FTPMwEVL memory usage point of view.

FTPMwEVL was slower only on three data sets. The most significant speed-up of magnitude 3,685.85 was achieved on data set "computers." For this case, FTPMwEVL found all FTPs up to the predefined maximum size k = 14 (it was set on this level due to memory considerations) in 446.08 s having used 26,100.1 MB of memory. FTPM mined all FTPs of Size 8 or lower and some of Size 9 in the time frame of 86,400 s. Similar to the AKI data set, the speed-up column reflects ratio 86,400s/23.44s = 3,685.85, where 23.44 s is the running time of FTPMwEVL to find all FTPs of Size 9 or lower. Speed-up of 30 times or more was achieved on four other data sets: the values in bold font. However, after removing these outliers, the speed-up was on the level of 2.34 on average for the remaining data sets. The memory consumption was 4.15 time higher for FTPMwEVL on average. In the worst case, 35,566.5 MB of memory was allocated to store all FTPs, which is not a concern for modern computational clusters.

# 6 | CONCLUDING REMARKS AND FUTURE RESEARCH DIRECTIONS

In this paper, a new algorithm for mining FTPs was presented where the concept of EVL was utilized. It outperformed the existing approach on many real-life data sets in terms of computational time with minor exceptions. EVL requires more memory to be stored, which is a typical trade-off in such a type of algorithms. The proof of concept is that server clusters and personal computers have enough memory nowadays. Moreover, memory is becoming cheaper significantly faster than CPU, as well as the memory size becomes five times of its previous size every 2 years (see http://www.jcmit.com/), whereas CPU resources only double during the same time frame (Moore et al., 1975). Thus, the problem of using large amounts of memory is becoming less and less critical.

The speed-up was achieved due to EVL that works in two main directions: elimination of more candidate TPs and faster verification of whether a candidate TP is an FTP or not. The candidate elimination by EVL works under the assumption that if a pattern is an FTP than all, its subpatterns are FTPs as well.

For other concepts of TP like recent TP (RTP) in Batal et al. (2016), this assumption does not hold. Thus, the candidate elimination phase will not work here, and only less efficient techniques like the vertical data format should be utilized instead. Still, the concept of

positions and indices will work for RTPs because the prefix of an RTP is an RTP itself. Therefore, EVLs can give a partial speed-up for Frequent RTP Mining too. The approach can be generalized and applied to other domains where the notion of pattern is defined in other ways.

Testing the applicability of the mined FTPs for classification purposes was out of the scope of this paper. Therefore, full scale evaluation of the quality of the found FTPs will be addressed in our future research. Despite the fact that other multivariate time series classification algorithms are not directly applicable here, there are several feature engineering strategies, including different distance measures to capture associations in time series, to compare against the methodology of TP ining.

Presence of noise and high-frequency sampling leads to a large number of state intervals per MSS and, therefore, to a large number of FTPs. Therefore, the effect of smoothing and noise reduction strategies is expected to effect the classification performance.

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# FIGURE 1.

An example of a multivariate state sequence (MSS) with time variables heart rate (HR) and blood pressure (BP)



# FIGURE 2.

Temporal pattern (TP) and its subpatterns: (a) an example of a TP, (b) the subpattern without the last state, (c) the subpattern without the middle state, (d) the prefix (or parent), the subpattern without the first state





An example of a temporal pattern (TP) and its smallest starting chain

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# FIGURE 4.

Computational time in seconds for Fast Temporal Pattern Mining with Extended Vertical List (FTPMwEVL) and FTPM on acute kidney injury data set for mining Frequent Temporal Pattern of sizes from 1 to 18 (there were no FTPs of a size larger than 19), given that all FTPs of smaller sizes were already found. Threshold  $\theta$  was set at 0.7. Total computational time was 3,4280.4 and 39.58 s for FTPM and FTPMwEVL, respectively. Memory usage was 402.31 and 3,134.2 MB. Thus, FTPMwEVL achieved a significant speed-up of magnitude **866** while consuming 7.79 times more memory

#### TABLE 1

Computational time comparison of FTPMwEVL and FTPM on AKI data sets

		FTPM			FTI	PMwEVL			
θ	Max k	k	Second	MB	k	Second	MB	Speed-up	Mem. ratio
0.9	Inf	7	0.16	1.86	7	0.1	15.8	1.06	8.49
0.8	Inf	12	465.5	24.92	12	2.3	198.5	204.27	7.96
0.7	Inf	18	34,280.4	402.31	18	39.6	3,134.2	866	7.79
0.6	Inf	10	>86400	NA	22	621.1	35,566.1	>1,719.3	NA
0.5	12	7	>86400	NA	12	467.8	28,950.4	>998.93	NA

Abbreviations: AKI, acute kidney injury; FTPMwEVL, Fast Temporal Pattern Mining with Extended Vertical List; NA, not applicable.

#### TABLE 2

Computational time comparison of FTPMwEVL and FTPM on UCR data sets

			FTPM			FTI	PMwEVL			
Data set	θ	Max k	k	Second	MB	k	Second	МВ	Speed-up	Mem. ratio
BeetleFly	0.8	8	8	702.0	5,577.2	8	275.5	1,8367.7	2.55	3.29
BirdChicken		Inf	18	742.9	1,564.4	18	269.9	4,873.5	2.75	3.12
Coffee		10	10	560.1	4,108.8	10	283.5	13,107.4	1.98	3.19
Computers	0.8	14	8	>86,400	NA	14	446.1	26,100.1	>3,685.8	NA
DistalPhalanx OutlineCorrect	0.7	Inf	16	160.3	1,435.1	16	113.3	5,382.6	1.41	3.75
Earthquakes	0.8	7	7	905.4	923.7	7	220.1	14,340.2	4.11	15.52
ECG200	0.6	Inf	18	2,349.7	3,225.3	18	300.5	11,863.1	7.82	3.68
ECGFiveDays	0.5	Inf	19	336.3	1,181.4	19	226.1	3,509.4	1.49	2.97
FordA	0.8	5	5	214.9	1,462.2	5	113.4	11,068.7	1.90	7.57
FordB	0.8	5	5	125.9	891.0	5	59.9	6,461.7	2.10	7.25
Gun_Point	0.2	Inf	18	35.3	129.6	18	27.0	377.7	1.31	2.91
Ham	0.8	7	7	783.8	5,894.6	7	310.5	26,318.9	2.52	4.46
HandOutlines	0.8	12	12	87.3	2,847.4	12	134.9	9,917.5	0.65	3.48
Herring	0.8	10	10	470.7	3,186.7	10	177.9	10,216.7	2.65	3.21
ItalyPowerDemand	0.2	Inf	13	1.2	16.8	13	1.4	46.4	0.86	2.75
Lighting2	0.8	8	8	50,929.9	6,080.6	8	495.1	35,555.4	102.87	5.85
MiddlePhalanx OutlineCorrect	0.7	Inf	17	301.6	2,689.2	17	184.3	9,633.6	1.64	3.58
MoteStrain	0.2	Inf	20	402.5	1,109.5	20	380.6	2,316.5	1.06	2.09
PhalangesOutlines Correct	0.5	Inf	14	96.6	1,115.3	14	71.9	4,035.1	1.34	3.62
ProximalPhalanx OutlineCorrect	0.4	Inf	19	588.0	4,271.8	19	307.5	15,383.3	1.91	3.60
ShapeletSim	0.8	7	6	>86,400	NA	7	378.1	25,489.8	>228.52	NA
SonyAIBORobot Surface	0.8	10	10	1,387.0	5,255.8	10	474.6	14,650.9	2.92	2.79
SonyAIBORobot SurfaceII	0.8	10	10	2,222.3	6,619.7	10	701.0	21,730.3	3.17	3.28
Strawberry	0.7	Inf	18	200.4	1,701.7	18	105.9	6,042.2	1.89	3.55
ToeSegmenta-tion1	0.8	8	8	754.7	2,904.8	8	181.5	11,128.0	4.16	3.83
ToeSegmenta-tion2	0.8	8	8	845.9	3,076.6	8	188.2	10,987.0	4.49	3.57
TwoLeadECG	0.2	Inf	17	15.1	93.5	17	15.2	2,43.1	0.99	2.60
wafer	0.7	Inf	11	>86,400	NA	29	275.6	10,952.4	>660.73	NA
Wine	0.7	Inf	22	481.8	4,288.6	22	354.8	14,043.6	1.36	3.27
WormsTwoClass	0.8	7	7	5,459.6	2,183.7	7	148.7	11,036.3	36.75	5.05
yoga	0.4	Inf	16	410.3	3,593.7	16	215.6	8,825.3	1.90	2.46

Abbreviations: FTPMwEVL, Fast Temporal Pattern Mining with Extended Vertical List; NA, not applicable.