Cell Reports Methods, Volume 3

Supplemental information

Label-free cell segmentation

of diverse lymphoid tissues in 2D and 3D

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Figure S1 related to Figure 1 – Comparing label-free probability maps using reflectance data obtained using 488 nm or 638 nm laser excitation. The choice of excitation wavelength for generating the reflectance signal has minimal influence on the probability maps obtained from the network (left versus middle; difference shown right). The user can therefore reasonably use whatever is available on their individual microscope. For some applications, choosing a longer excitation wavelength may reduce fluorophore photobleaching / improve tissue penetrance and reflectance recovery - for instance, during 3-D Z-stack imaging in thicker tissue specimens.

Figure S2 related to Figure 1 – Number of first-encoder filters and encoder depth optimisation to define the best performing 2- D Unet model. Bars represent normalised training time whilst circles indicate label-free cell segmentation accuracies (assessed by Jaccard index). The best performing model used an encoder depth of 4 with 64 filters at the level of the first encoder (indicated, **). Of note, using 32 filters instead of 64 can achieve a training speed up of ~50% for a negligible (~1%) decrease in segmentation accuracy (indicated, *). Increasing the encoder depth to 5 did not further improve cell segmentation accuracies (bottom row).

Figure S3 related to Figure 1 – Spectral bandwidth saving achieved by the label-free cell segmentation strategy. a, Emission spectra for Hoechst 33342 and AlexaFluor 647 as might typically be used to delineate cell nuclei and cell cytoskeletons when carrying out fluorescence-based cell segmentation. **b**, Harnessing reflectance information, the label-free cell segmentation method described here removes the need for these fluorescence stains leaving the spectrum entirely open for sensitive experimental measurements with single-cell quantification.

Figure S4 related to Figure 2 – Label-free cell segmentation of confocal microscopy image-data collected from formalin-fixed, paraffin embedded tissue sections. a, In frozen cryostat sections, f-actin staining using phalloidin conjugates clearly delineates cell outlines providing ground truth to enable the presented label-free cell segmentation approach. **b**, In contrast, in formalin-fixed paraffin embedded (FFPE) tissue sections, phalloidin staining fails because solvent exposure during the fixation and paraffin embedding process degrades the actin cytoskeleton. **c**, Demonstrated here using murine Peyer's patch tissue sections, successful ground truth labelling can be restored in the FFPE section-type by switching to cell membrane (*i.e.,* phospholipid) staining using wheat germ agglutinin (WGA) fluorescence conjugates. **d/e** Comparison of the reflectance signal from the frozen and FFPE section-types. Cytoskeletal degradation appears to change the reflectance images observed from the FFPE tissue: the faint trace of the cell outlines visible in the frozen sections is no longer apparent and instead the intracellular regions appear to exhibit the highest reflectance signal. **f-h** Despite this, a relationship between the reflectance signal and a WGA-delineated ground truth is still determinable by the neural network allowing (**g/h**) successful label-free cell segmentation direct from the reflectance signal. **h**, Intersection over union (IOU) score distribution comparing a (**f**) hand-drawn segmentation and the (**g**) automated, label-free cell segmentation outcome. An IOU score of 1 represents a perfect, per-pixel overlap between the hand-drawn and automated cell segmentations. Within the comparison presented here, scores ≥ 0.6 are seen to represent a good match, approaching the limits of hand-drawing accuracy. By harnessing ground truth from other fluorescence labels, the label-free strategy can operate in *both* FFPE and frozen tissue-types. Given that tissue archiving in FFPE format is commonplace worldwide, this finding dramatically increases the application domain of the presented label-free cell segmentation strategy. *Scale bars: a/b = 20 microns; c/d = 100 microns; e/f = 75 microns; g/h = 50 microns.*

Figure S5 related to Figure 4 – Assessing 3-D label-free cell segmentation accuracies using mouse Peyer's patch tissue. a, Hand-drawn cell segmentations performed using the nuclei/actin fluorescence information for Z-planes (**a**) 57 in the XY dimension (**d**) 512 in ZY dimension and (**g**) 512 in the XZ dimension (unseen test image-data is 512x512x114 (X,Y,Z)). **b/e/h**, Automated cell segmentations for the same image-regions as (**a/d/g)** but achieved label-free direct from the reflectance signal. **c/f/i,** Cell-object intersection-over-union score distributions comparing – cell-object by cell-object – the (**a/d/g**) hand-drawn segmentations against the (**b/e/h**) automated, label-free cell segmentations. An IOU score of 1 represents perfect, per-pixel overlap between the hand-drawn and automated cell segmentations. Within the comparison presented here, scores ≥ 0.6 are seen to represent a good match, approaching the limits of hand-drawing accuracy. Encouragingly, the 3-D approach outperformed the segmentation accuracies achieved in 2-D (shown, **Figure 2**). *Scale bars equal 20 microns.*

Figure S6 related to Figure 4 – Fluorescence versus label-free nuclei predictions at Z-depths of ~10 and ~90 microns. Using reflectance information from a 638 nm excitation laser, the 3-D network is able to consistently recover nuclear information long after the blue nuclear stain (Hoechst 33342) has decayed from multiple scattering effects (bottom right versus middle right). The resultant pixel intensity histograms from the probability map images are extremely stable (bottom right). This is advantageous for achieving consistent, depth-invariant 3-D cell segmentation in thick tissue specimens.

Methods S1 – Related to Star Methods

Table of contents –

Setting up sequential reflectance imaging using a standard Zeiss LSM780 confocal microscope.

a, Once the fluorescence imaging sequences are set up, a new track for reflectance is added to the sequential scan. **b**, The desired excitation laser for reflectance imaging is selected (here, 561 nm). The choice of laser is not particularly important, but use of longer wavelengths may reduce fluorophore photobleaching and improve penetrance / recovery in thicker specimens (shown, **Figures S1/S6**). **c**, A photomultiplier detector (here Ch1) is turned on and the range set to approximately +/- 3 nm either side of the excitation wavelength (here 558 – 564 nm was entered, but the software rounds to display ~ 557 – 566 nm). **d**, The tick-box allowing reflected light to pass to the detector is turned on. **e**, The T80/R20 beam splitter is chosen (this indicates a transmission/reflection ratio of 80:20). **f**, A low laser excitation power (here, 1%) is entered. *N.B.,* use of a reflectance light path with high laser excitation power may damage the camera, so care should be taken here. The pinhole is set to ~ 1 airy unit, yielding an optical section of around ~ 1 micron with a high numerical aperture 40X or 63X objective. **g**, Running in 'live mode', the gain is slowly increased until the reflectance signal occupies approximately 80% of the range histogram (indicated, green box). Compressing the histogram in the range indicated yields a typical 'view' of the reflectance signal from a lymphoid tissue specimen (on display in the main image window).

Setting up sequential reflectance imaging using a standard Leica SP8 confocal microscope.

a, Once the fluorescence imaging sequence(s) are set up, a new track for reflectance is added to the sequential scan (here, 'Seq 4'). **b**, The desired excitation laser for reflectance imaging is turned on (here, 488 nm). The choice of laser is not particularly important, but use of longer wavelengths may reduce fluorophore photobleaching and improve penetrance / recovery in thicker specimens (shown, **Figures S1/S6**). A low laser excitation power (*e.g.,* 1%) is also specified at this step. *N.B.,* Use of a reflectance light path with high laser excitation powers could damage the camera, so care should be taken at this step. **c**, An appropriate beam splitter is chosen for the excitation line, or, the 'Autoselect' checkbox can be ticked to set this automatically. **d**, A photomultiplier detector (here PMT1) is turned on and the range set to approximately +/- 3 nm either side of the excitation wavelength (*i.e.,* here, 485-491 nm). **e**, Running in 'live mode', the gain is slowly increased until the reflectance signal occupies approximately 80% of the available intensity range. The main window shows a typical 'view' of the reflectance signal from a lymphoid tissue specimen under this setup.

Setting up simultaneous reflectance and fluorescence imaging using a standard Leica SP8 confocal microscope.

Once fluorescence excitation and collection are configured, (**a**) any remaining laser line can be used for reflectance imaging (*e.g.,* here, the 488 nm line is used). The choice of laser is not particularly important, but use of longer wavelengths may reduce fluorophore photobleaching and improve penetrance / recovery in thicker specimens (shown, **Figures S1/S6**). A low laser excitation power (*e.g.,* 1%) should also be specified here. Reflectance imaging with high laser excitation powers could damage the camera, so care should be taken at this step. **b**, An appropriate beam splitter for the excitation lasers is chosen, or the 'Autoselect' checkbox ticked to enable automatic setting. **c**, A free detector (here PMT2) is turned on and the range set to approximately +/- 3 nm either side of the excitation wavelength (*i.e.,* 485-491 nm). **d**, Running in 'live mode', the gain is slowly increased until the reflectance signal occupies approximately 80% of the available intensity range. The topright image in the main window shows a typical 'view' of the reflectance signal from a lymphoid tissue specimen under this setup. This approach allows reflectance data to be concomitantly collected alongside fluorescence without adding the additional run-time of further sequences. N.B., It is worth noting that in a similar way, a laser that is already being used for fluorescence excitation may also be used to obtain reflectance data (exemplified **page below**). For example, here, PMT2 could be moved up to collect reflectance from the 638 nm laser in the range 635-641 nm. Doing this has the advantage of reducing the photon budget for the sample. However, it also necessitates that enough excitation power is being used to obtain a good reflectance signal, and that a free detector can be moved within the necessary detection range. This is not always compatible with optimal fluorescence imaging – hence the setup shown here.

Setting up 'free' reflectance imaging alongside fluorescence collection using a standard Leica SP8 confocal microscope.

Once fluorescence excitation and collection are configured, (**a**) any remaining detector can be used to simultaneously collect the reflectance signal from one of the excitation lasers being used to stimulate fluorescence (*e.g.,* here, 'PMT2' is used to collect reflectance from the 638 nm laser line (b) – which is also being used to excite AlexaFluor 647). This is achieved by placing the detector approximately +/- 3 nm either side of the excitation wavelength (*i.e.,* 635-641 nm). **c**, Running in 'live mode', the gain is slowly increased until the reflectance signal occupies approximately 80% of the available intensity range. The top-right image in the main window shows a typical 'view' of the reflectance signal from a lymphoid tissue specimen under this setup. Simultaneous reflectance imaging has the advantage of reducing the photon budget for the sample, as the reflectance information is effectively recovered for 'free' by harnessing scatter from a laser that is already in use. However, this setup also necessitates that enough excitation power is available to obtain a good reflectance signal, and that a free detector can be moved into the necessary detection range. To achieve this here without saturating the AlexaFluor 647 signal (shown bottom-left in the main image window) the AlexaFluor647 detection range was narrowed (**d**) to ~ 700-750 nm. Where this setup cannot be accommodated one of the other options that instead use a dedicated laser for reflectance imaging should be utilised (shown, **three above pages).**

Windows 10: Running the label-free cell segmentation pipeline using standalone software

Running this software requires:

- Windows 10 machine (NVIDIA GPU desirable for model training)
- Label-free stain prediction standalone software (BioStudies download) \bullet
- MATLAB runtime 9.11 (installs automatically alongside software see below). \bullet

Note: This software is free to install. No MATLAB license is required to run this standalone software.

Installation Steps:

1. Install the Label Free Stain Prediction software by running the Windows 10 installer from the **BioStudies download**

2. Follow through the setup procedure to install the software:

- Check 'add shortcut to the desktop':

- When prompted, install MATLAB runtime (free; no license is required):

- click 'install' to install the label free stain prediction software and MATLAB runtime 9.11

3. Training 2-D or 3-D UNET model using the standalone software -A screencast video is included with the BioStudies archive.

- -Launch the Label Free Stain Prediction software from the desktop icon
- -Example 2-D and 3-D image data and training labels are included in the BioStudies download.

- To Train a 2-D or 3-D UNET model to predict the probability images needed to enable the label-free segmentation, load reflectance data and matching labels for 'Nuclei', 'Cell Outlines' (e.g. actin) and 'background/other' classes.

-The label images should be in tiff format with the stains represented as foreground (i.e., white). -2-D or 3-D data will be automatically detected.

- If desired, a ROI-mask can also be loaded to mask the outputted probability maps to the desired tissue region.

- If this isn't needed - just leave this box blank.

- Set the desired batch-size and number of training epochs and click 'Train Network'.

- After a few seconds, the loaded reflectance data and labels will be indicated in "Figure 1"

- Progress can be tracked in the Command Prompt console

- MAT formatted data and the trained model will be saved to folders on the desktop once training completes:

- Training with the example data takes \sim 6h on an NVIDIA 1080 GTX GPU. (Previously trained models are provided).

4. Using a pretrained 2-D or 3-D UNET model to generate probability images for label-free segmentation using unseen reflectance data.

-On the right-side of the software, load a pretrained model.

-This can be from Step 3 (above), or, example pretrained networks are provided in 'Folder 3' of the BioStudies download. Example unseen 'test' image-data is also provided in 'Folder 1' in 2-D and 3-D.

- Load 2-D or 3-D reflectance data:

- If desired, load a ROI-mask to limit the probability maps to the desired tissue region:
- (Leave blank if not required).
-

- Click 'Predict Labels' to generate the label-free probability images

- Progress can be tracked in the Command Prompt console

- Figure 1 demonstrates probability images for each class (central z-plane for 3-D data)

- Outputs are saved to the Desktop ready for loading into the CellProfiler pipelines enabling cell feature extraction (described below).

Windows 10: Running the label-free cell segmentation deep learning scripts on an NVIDIA GPU using MATLAB R2021b and the Deep Learning Toolbox

Running these deep learning scripts in MATLAB requires:

- \bullet MATLAB (version R2019a or later)
- Deep Learning Toolbox \bullet
- Image Processing Toolbox
- **Computer Vision Toolbox** \bullet

Installation Steps: 1. Install MATLAB

 \Box A Download MATLAR Simulink Str. \times +

https://ch.mathworks.com/downloads/web_downloads

- Login to your MathWorks account to access the downloads page at the link above.
- Download and run the installer for MATLAB R2021b.

2. Training a 2-D UNET Model

-A screencast video is included with the BioStudies archive.

- Download and unzip the MATLAB BioStudies project archive at a suitable location on your computer.

- Inside the MATLAB_2D_UNET folder, there is a sequentially-organised workflow starting with raw data and ending with a CellProfiler pipeline that obtains cell features from the label-free cell segmentation:

- To train a 2-D UNET model, open MATLAB and set the working directory to the "2_TRAIN_Unet" directory. Open the "A_TRAIN_UNET" script.

- Update the path to the training data (located in the "1_ImageData" folder).

- Update the path to tissue ROI mask which isolates the lymphoid follicle from the surrounding tissue (located in the "1_ImageData" folder).

- Update the path to the pixel classification labels (located in the "1 ImageData" folder)

- On Line 46, update the path to the pixel classification labels (located in the "1_ImageData" folder) used by the "pixelLabelDatastore" function.

D:\John\2021\MATLAB_biostudies\MATLAB_2D_UNET\2_TRAIN_Unet\A_TRAIN_UNET.m EDITOR 大 % % N & E Section Break \mathbb{Q} \geq ← □ ■ 图 Compare ▼ \triangleright profiler Q Find \blacktriangledown 国西区 Run and Advance Analyze Run
Section Run to End
Section Run to End New Open Save \bigoplus Print \blacktriangleright Go To Refactor Run Step Stop $\sqrt{\frac{1}{2}}$ Bookmark $\sqrt{\frac{1}{2}}$ $\frac{1}{\sqrt{6}}$ ANALYZE FILE NAVIGATE SECTION CODE **RUN** %% Create 'Datastores' for the reflectance information and matching pixel-class labels 36 % Read saved mat file containing reflectance info into an image datastore
% Directions for processing the mat file-type are in the accompanying 'matReader' function
reflectance_ds = imageDatastore([pwd, '/mat_training_data 37 38 39 40 41 % Read pixel labels into a pixel label datastore 42 PixelClassNames = ["LF_actin", "LF_nuclei", "BackgroundOther"]; 43 $\frac{44}{45}$ PixelLabel_ds = pixelLabelDatastore('D:\John\2021\MATLAB_biostudies\MATLAB_2D_UNET\1_ImageData\TRAIN_LABELS.png', PixelClassNames, Label Ids); 46

- At the bottom of the script on Line 195, update the path to the saved_network_directory. - This should be folder 3 of the workflow ("3_Saved_models").

- Run the script by clicking the green arrow at the top.

- Model training takes several hours (~ 4h on a NVIDIA 1080 Ti GPU)

- The newly-trained model will be saved in the "3_Saved_models" directory with a new time/date stamp.

D:\John\2021\MATLAB_biostudies\MATLAB_2D_UNET\2_TRAIN_Unet\A_TRAIN_UNET.m

3. Testing a pretrained 2-D model using unseen data

-A screencast video is included with the BioStudies archive.

- Change the MATLAB working directory to the "4_Test_Unet" directory. Open the "A_TEST_UNET" script.

- Change the path to the unseen test image (located in the "1_ImageData" folder). - Specify the ROI mask which identifies the lymphoid tissue (located in the "1 ImageData"

folder).

- Specify which pretrained network to use (pretrained networks are located in the "3_Saved_models" folder.

D:\John\2021\MATLAB_biostudies\MATLAB_2D_UNET\4_TEST_Unet\A_TEST_UNET.m

- Click the "Run" button to process the unseen reflectance data with the selected pretrained network:

- Probability maps for the LF-nuclei, LF-actin and Background/Other classes will be saved in the working directory named ready for input into the CellProfiler pipeline (filenames Ch 5 lm 001, Ch 6 lm 001, Ch 7 lm 001, respectively).

4. Training a 3-D UNET Model

-A screencast video is included with the BioStudies archive.

- Inside the MATLAB_3D_UNET folder, there is a sequentially-organised workflow starting with raw data and ending with a CellProfiler pipeline that obtains 3-D cell features from the labelfree cell segmentation:

- To train a 3-D UNET model, open MATLAB and set the working directory to the "2_TRAIN_Unet" directory. Open the "A_TRAIN_3D_UNET" script.

- Specify the path to the bioformats library. This is included inside the "2_TRAIN_Unet" folder ("bfmatlab").

- Update the path to the training data directory (located in the "1_ImageData/TRAIN/DATA" folder).

- Specify the channel number in the training data that contains the reflectance information (here, '3').

- Specify the location of the pixel classification training labels (located at

"1_ImageData/TRAIN/LABELS" folder.

- Specify the location to save the model when training completes. This should be the "3_Saved_models" directory.

- Click "Run" to commence model training.

- This takes considerable time (approximately 6h on a NVIDIA 1080Ti GPU card).

6. Testing a pretrained 3-D model using unseen data

-A screencast video is included with the BioStudies archive.

- Change the MATLAB working directory to the "4 Test Unet" directory. Open the "A_TEST_3D_UNET" script.

- Specify the path to the Bioformats library. (This is included inside the "4_TEST_Unet" folder ("bfmatlab").

- Specify the location of the unseen test image-data. This is located inside the "1 ImageData" folder at "1_ImageData/TEST/".

- Specify a pretrained 3-D Unet model from the "3_Saved_models" directory.

- Click "Run" to process the unseen reflectance data with the 3-D Unet model.

- Probability maps for the LF-nuclei, LF-actin and Background/Other classes will be saved as multipage. TIFF files in the working directory named ready for input into the CellProfiler pipeline (filenames Ch_3_lm_001, Ch_4_lm_001, Ch_5_lm_001, respectively).


```
% MATLAB SCRIPT: TRAIN 2D UNET
% All code, image-data and screen-cast tutorial videos available for download at
% the Biostudies database under accession number S-BSST742
clear
close all
c1c% Read in the reflectance data for training
Training data =
imread('D:\John\2021\MATLAB biostudies\MATLAB 2D UNET\1 ImageData\TRAIN IMAGE.ti
f', 3) ; % channel 3 is reflectance
% Read in the mask to isolated just the lymphoid tissue
mask =imread('D:\John\2021\MATLAB biostudies\MATLAB 2D UNET\1 ImageData\TRAIN IMAGE.ti
f', 4);
mask = unit16(intminarize(maxk));% Apply the mask to the training data
Training data = Training data \cdot* mask ;
% Rescale the training data in the interval [0 1]
Training data = double(1*mat2gray(Training data, [0 4095]));
% Read in the pixel-class labels created from the nuclei and actin staining
Training labels =
imread('D:\John\2021\MATLAB biostudies\MATLAB 2D UNET\1 ImageData\TRAIN LABELS.p
ng') ;
% Visually inspect the data and labels
figure(1)subplot(1,2,1)imshow(Training data, [])
title('Reflectance data')
subplot(1,2,2)imshow(Training labels, [])
title('Pixel classification labels')
%% Once happy with labels and data, commit the reflectance information data to
sub-directory in .mat format
if ~exist('mat training data', 'dir')
    mkdir('mat training data');
end
save([pwd, '/mat training data/', 'Training data.mat'], 'Training data');
%% Create 'Datastores' for the reflectance information and matching pixel-class
labels
% Read saved mat file containing reflectance info into an image datastore
% Directions for processing the mat file-type are in the accompanying
'matReader' function
reflectance ds = \text{imageDatabase}([pwd,'/mat training data/'], 'FileExtensions', '.mat', 'ReadFcn', @matReader) ;
% Read pixel labels into a pixel label datastore
PixelClassNames = ["LF_actin", "LF_nuclei", "BackgroundOther"];
Label Ids = 1:3; % these represent the pixel values in the labels png file
PixelLabel ds =
pixelLabelDatastore('D:\John\2021\MATLAB biostudies\MATLAB 2D UNET\1 ImageData\T
RAIN LABELS.pnq',...
```
PixelClassNames, Label Ids);

```
%% Define augmentation options
augmenter = imageDataAugmenter(...%%% description and defaults %%%
     'TillValue', 0, \ldots% define out-of-bounds points when resampling
\Omega'RandXReflection', true, ...
                                       % Random reflection in the left-right
direction false
     'RandYReflection', true, ...
                                       % Random reflection in the top-bottom
direction false
     'RandRotation', [0 360],...
                                       % Range of rotation, in degrees [0 0]
     'RandScale', [1 1], ...
                                       % Range of uniform (isotropic) scaling [1 1]
    'RandXScale', [1\ 1],...
                                       % Range of horizontal scaling [1 1]
     'RandYScale', [1\ 1], ...
                                       % Range of vertical scaling [1 1]
                                       % Range of horizontal shear [0 0]
     'RandXShear', [0 0], ...
     'RandYShear', [0 0],...
                                       % Range of vertical shear [0 0]
     'RandXTranslation', [0 0],...
                                       % Range of horizontal translation [0 0]
     'RandYTranslation', [0 0]...
                                       % Range of vertical translation [0 0]
    \mathcal{L}%% Create a training datastore comprising matching patches (256x256 pixels) of
image-data and training labels
training ds =randomPatchExtractionDatastore(reflectance ds, PixelLabel ds, [256, 256],...
     'PatchesPerImage',12000,'DataAugmentation',augmenter); % 743 draws == 1
epoch
%% CREATE THE UNET
% input layer 256x256x1
% encoder depth 4
% 64 filters at the level of the first encoder
lgraph = layerGraph();
tempLayers = [imageInputLayer([256 256 1], "Name", "ImageInputLayer")
    convolution2dLayer([3 3], 64, "Name", "Encoder-Stage-1-Conv-
1", "Padding", "same", "WeightsInitializer", "he")
    reluLayer("Name", "Encoder-Stage-1-ReLU-1")
    convolution2dLayer([3 3], 64, "Name", "Encoder-Stage-1-Conv-
2", "Padding", "same", "WeightsInitializer", "he")<br>reluLayer("Name", "Encoder-Stage-1-ReLU-2")];
lgraph = addLayers(lgraph, tempLayers);
tempLayers = [
    maxPooling2dLayer([2 2], "Name", "Encoder-Stage-1-MaxPool", "Stride", [2 2])
    convolution2dLayer([3 3], 128, "Name", "Encoder-Stage-2-Conv-
1", "Padding", "same", "WeightsInitializer", "he")
    reluLayer("Name", "Encoder-Stage-2-ReLU-1")
convolution2dLayer([3 3], 128, "Name", "Encoder-Stage-2-Conv-<br>2", "Padding", "same", "WeightsInitializer", "he")<br>reluLayer("Name", "Encoder-Stage-2-ReLU-2")];
lgraph = addLayers(lgraph, tempLayers);
tempLayers = [maxPooling2dLayer([2 2], "Name", "Encoder-Stage-2-MaxPool", "Stride", [2 2])
    convolution2dLayer([3 3], 256, "Name", "Encoder-Stage-3-Conv-
1", "Padding", "same", "WeightsInitializer", "he")
    reluLayer("Name", "Encoder-Stage-3-ReLU-1")
    convolution2dLayer([3 3], 256, "Name", "Encoder-Stage-3-Conv-
2", "Padding", "same", "WeightsInitializer", "he")
```

```
reluLayer("Name", "Encoder-Stage-3-ReLU-2")];
lgraph = addLayers(lgraph, tempLayers);tempLayers = [
    maxPooling2dLayer([2 2], "Name", "Encoder-Stage-3-MaxPool", "Stride", [2 2])
convolution2dLayer([3 3],512, "Name", "Encoder-Stage-4-Conv-<br>1", "Padding", "same", "WeightsInitializer", "he")
     reluLayer("Name", "Encoder-Stage-4-ReLU-1")
     convolution2dLayer([3 3],512, "Name", "Encoder-Stage-4-Conv-
2", "Padding", "same", "WeightsInitializer", "he")<br>reluLayer("Name", "Encoder-Stage-4-ReLU-2")];
lgraph = addLayers(lgraph, tempLayers);tempLayers = [dropoutLayer(0.5, "Name", "Encoder-Stage-4-DropOut")
    maxPooling2dLayer([2 2], "Name", "Encoder-Stage-4-MaxPool", "Stride", [2 2])
convolution2dLayer([3 3],1024, "Name", "Bridge-Conv-<br>1", "Padding", "same", "WeightsInitializer", "he")
     reluLayer("Name","Bridge-ReLU-1")
     convolution2dLayer([3 3],1024,"Name","Bridge-Conv-
2", "Padding", "same", "WeightsInitializer", "he")
     reluLayer("Name","Bridge-ReLU-2")
     dropoutLayer(0.5, "Name", "Bridge-DropOut")
transposedConv2dLayer([2 2],512, "Name", "Decoder-Stage-1-<br>UpConv", "BiasLearnRateFactor", 2, "Stride", [2 2], "WeightsInitializer", "he")
    reluLayer("Name","Decoder-Stage-1-UpReLU")];
lgraph = addLayers(lgraph, tempLayers);tempLayers = [
    depthConcatenationLayer(2, "Name", "Decoder-Stage-1-DepthConcatenation")
     convolution2dLayer([3 3],512, "Name", "Decoder-Stage-1-Conv-
1", "Padding", "same", "WeightsInitializer", "he")
     reluLayer("Name", "Decoder-Stage-1-ReLU-1")
    convolution2dLayer([3 3], 512, "Name", "Decoder-Stage-1-Conv-
2", "Padding", "same", "WeightsInitializer", "he")
    reluLayer("Name", "Decoder-Stage-1-ReLU-2")
     transposedConv2dLayer([2 2], 256, "Name", "Decoder-Stage-2-
UpConv", "BiasLearnRateFactor", 2, "Stride", [2 2], "WeightsInitializer", "he")
     reluLayer("Name","Decoder-Stage-2-UpReLU")];
lgraph = addLayers(lgraph, tempLayers);tempLayers = [depthConcatenationLayer(2, "Name", "Decoder-Stage-2-DepthConcatenation")
     convolution2dLayer([3 3], 256, "Name", "Decoder-Stage-2-Conv-
1", "Padding", "same", "WeightsInitializer", "he")
    reluLayer("Name","Decoder-Stage-2-ReLU-1")
convolution2dLayer([3 3],256, "Name", "Decoder-Stage-2-Conv-<br>2", "Padding", "same", "WeightsInitializer", "he")
     reluLayer("Name","Decoder-Stage-2-ReLU-2")
transposedConv2dLayer([2 2],128, "Name", "Decoder-Stage-3-<br>UpConv", "BiasLearnRateFactor", 2, "Stride", [2 2], "WeightsInitializer", "he")
     reluLayer("Name","Decoder-Stage-3-UpReLU")];
lgraph = addLayers(lgraph, tempLayers);tempLayers = [depthConcatenationLayer(2, "Name", "Decoder-Stage-3-DepthConcatenation")
     convolution2dLayer([3 3],128, "Name", "Decoder-Stage-3-Conv-
1", "Padding", "same", "WeightsInitializer", "he")
     reluLayer("Name", "Decoder-Stage-3-ReLU-1")
```

```
convolution2dLayer([3 3], 128, "Name", "Decoder-Stage-3-Conv-
2", "Padding", "same", "WeightsInitializer", "he")
    reluLayer("Name","Decoder-Stage-3-ReLU-2")
    transposedConv2dLayer([2 2],64,"Name","Decoder-Stage-4-
UpConv", "BiasLearnRateFactor", 2, "Stride", [2 2], "WeightsInitializer", "he")
    reluLayer("Name", "Decoder-Stage-4-UpReLU")];
lgraph = addLayers(lgraph, tempLayers);tempLayers = [depthConcatenationLayer(2, "Name", "Decoder-Stage-4-DepthConcatenation")
    convolution2dLayer([3 3], 64, "Name", "Decoder-Stage-4-Conv-
1", "Padding", "same", "WeightsInitializer", "he")
    reluLayer("Name", "Decoder-Stage-4-ReLU-1")
    convolution2dLayer([3 3], 64, "Name", "Decoder-Stage-4-Conv-
2", "Padding", "same", "WeightsInitializer", "he")<br>reluLayer("Name", "Decoder-Stage-4-ReLU-2")
    convolution2dLayer([1 1], 3, "Name", "Final-
ConvolutionLayer", "Padding", "same", "WeightsInitializer", "he")
    softmaxLayer("Name", "Softmax-Layer")
    pixelClassificationLayer("Name", "Seqmentation-Layer") |;
lgraph = addLayers(lgraph, tempLayers);clear tempLayers;
% encoder / decoder connections
lgraph = connectLayers(lgraph, "Encoder-Stage-1-ReLU-2", "Encoder-Stage-1-
MaxPool");
lgraph = connectLayers(lgraph, "Encoder-Stage-1-ReLU-2", "Decoder-Stage-4-
DepthConcatenation/in2");
lgraph = connectLayers(lgraph, "Encoder-Stage-2-ReLU-2", "Encoder-Stage-2-
MaxPool");
lgraph = connectLayers(lgraph, "Encoder-Stage-2-ReLU-2", "Decoder-Stage-3-
DepthConcatenation/in2");
lgraph = connectLayers(lgraph, "Encoder-Stage-3-ReLU-2", "Encoder-Stage-3-
MaxPool");
lgraph = connectLayers(lgraph, "Encoder-Stage-3-ReLU-2", "Decoder-Stage-2-
DepthConcatenation/in2");
lgraph = connectLayers(lgraph, "Encoder-Stage-4-ReLU-2", "Encoder-Stage-4-
DropOut');
lgraph = connectLayers(lgraph, "Encoder-Stage-4-ReLU-2", "Decoder-Stage-1-
DepthConcatenation/in2");
lgraph = connectLayers(lgraph, "Decoder-Stage-1-UpReLU", "Decoder-Stage-1-
DepthConcatenation/in1");
lgraph = connectLayers(lgraph,"Decoder-Stage-2-UpReLU","Decoder-Stage-2-
DepthConcatenation/in1");
lgraph = connectLayers(lgraph,"Decoder-Stage-3-UpReLU","Decoder-Stage-3-
DepthConcatenation/in1");
lgraph = connectLayers(lgraph, "Decoder-Stage-4-UpReLU", "Decoder-Stage-4-
DepthConcatenation/in1");
% analyzeNetwork(lgraph) % comment in to check structure and errors
plot(lgraph) % comment in to show network structure
%% Specify training options
options = trainingOptions('sgdm',...'InitialLearnRate', 0.05, ...
    'Momentum', 0.9, ...
    'L2Regularization', 0.0001, ...
    'MaxEpochs', 50, ...
    'MiniBatchSize', 12, ...
```

```
'LearnRateSchedule', 'piecewise',...
    'Shuffle', 'every-epoch', ...
    'GradientThresholdMethod', '12norm',...
    'GradientThreshold', 0.05, ...
    'Plots', 'training-progress', ...
    'VerboseFrequency', 20, ...
    'ExecutionEnvironment', 'auto');
%% Train and save the network
close all
% Specify location to save the network
saved network directory =
'D:\John\2021\MATLAB biostudies\MATLAB 2D UNET\3 Saved models\';
% Train the network
modelDateTime = datestr(now, 'dd-mmm-yyyy-HH-MM-SS');
[net, info] = trainNetwork(training ds, lgraph, options);
% Timestamp and save the network after training
save([saved_network_directory,'PeyersPatchBiostudies_',modelDateTime,'.mat'],...
    'net', 'options', 'augmenter', 'info');
```


2-D Unet architecture schematic. The network uses an input layer for the reflectance data of 256x256x1 (x, y, channels). The best performing three-class Unet architecture uses an encoder depth of 4 with 64 filters at the level of the first encoder (shown, **Figure S2**). The network uses complete up-convolutional expansion to yield outputted probability maps that are identically sized to the input layer.

```
% MATLAB SCRIPT: TEST 2D UNET
% All code, image-data and screen-cast tutorial videos available for download at
% the Biostudies database under accession number S-BSST742
clear
close all
_{\text{clc}}% Load the reflectance data from the unseen test image
TEST DATA =imread('D:\John\2021\MATLAB biostudies\MATLAB 2D UNET\1 ImageData\TEST IMAGE.tif
',3); 8 3 is reflectance channel
% Load the mask for the lymphoid tissue region
Mask =imread('D:\John\2021\MATLAB biostudies\MATLAB 2D UNET\1 ImageData\TEST IMAGE.tif
', 4);Mask = double(imbinarize(Mask)) ;
% Rescale the test data [0 1]
TEST DATA rescaled = double(1*mat2gray(TEST DATA, [0 4095]));
% Mask the rescaled data
TEST DATA rescaled = TEST DATA rescaled .* Mask ;
% Load a pretrained network
load('D:\John\2021\MATLAB biostudies\MATLAB 2D UNET\3 Saved models\Rescaled0-
1 2DUNET S7-RL-SA enc-4 filt-64 e50.mat') ;
%% Patch the reflectance data through the network
% Set the patch sizes to be passed to the net
patchSize = [2048 2048]; % decrease if insufficient GPU memory eg., [1024 1024]
% Segment blockwise then reassemble in full
% Define image dimensions
[height, width, nChannel] = size(TEST DATA rescaled);
patch = zeros([patchSize, nChannel], \overline{like\overline{}, TEST DATA rescaled);
% Pad image to have dimensions as multiples of patchSize
padSize(1) = patchSize(1) - mod(height, patchSize(1));padSize(2) = patchSize(2) - mod(width, patchSize(2));im_pad = padarray (TEST_DATA_rescaled, padSize, 0, 'post');
[height pad, width pad, nChannel pad] = size(im pad);
% Preallocate some matrices to receive the network outputs
out Uncertainty Scores = zeros([size(im pad,1), size(im pad,2)], 'double');
out Pmap cat1 = out Uncertainty Scores;
out Pmap cat2 = out Uncertainty Scores;
out Pmap_cat3 = out_Uncertainty_Scores;
% Loop through blocks of 'patchSize'
    for loop = 1:patchSize(1):height pad
        for j = 1: patchSize(2): width pad
            for p = 1: nChannel
                patch(:,:,p) = squeeze(im_pad(loop:loop+patchSize(1)-1,...j:j+patchSize(2)-1,p);
            end
            % deploy net
```
```
[patch seg, Scores, allScores] = semanticseg(patch, net,
'OutputType', 'double',...
                 'ExecutionEnvironment', 'auto'):
            % catch what comes out
            out Uncertainty Scores(loop:loop+patchSize(1)-1, j:j+patchSize(2)-1)
= Scores:
            out Pmap cat1(loop:loop+patchSize(1)-1, j:j+patchSize(2)-1) =
allScores(:,(:, 1);out Pmap cat2(loop:loop+patchSize(1)-1, j:j+patchSize(2)-1) =
allScores(:, :, 2);out Pmap cat3(loop:loop+patchSize(1)-1, j:j+patchSize(2)-1) =
allScores(:, :, 3);end
    end
% Remove padding from the network outputs
out Uncertainty Scores = out Uncertainty Scores(1:height, 1:width);
out Pmap cat1 = out Pmap cat1(1:height, 1:width);
out_Pmap_cat2 = out_Pmap_cat2(1:height, 1:width);
out Pmap cat3 = out Pmap cat3(1:height, 1:width);
%% visualise network outputs
figure(2)clf(figure(2))ax1 = subplot(2, 3, 1);imshow(out Pmap cat1, [])
title('LF-actin')
ax2 = subplot(2, 3, 2) ;
imshow(out Pmap_cat2,[])
title('LF-nuclei')
ax3 = subplot(2, 3, 3);imshow(out_Pmap_cat3, []title('Background/other')
ax4 = subplot(2, 3, 5);imshow(out Uncertainty Scores, [])
title('Uncertainty')
linkaxes([ax1ax2ax3ax4], 'xy')
%% Map to 16-bit and save for loading into CellProfiler
uil6 PMAP cat1_xy = uint16(65535 *mat2gray(out Pmap cat1, [0 1])) ;
imwrite(uil6 PMAP catl xy, ['Ch 6 Im 001','.tiff']) ;
uil6 PMAP cat2 xy = uint16(65535 *mat2gray(out Pmap cat2, [0 1])) ;
imwrite(uil6 PMAP cat2 xy, ['Ch 5 Im 001', '.tiff']) ;
uil6 PMAP cat3 xy = \text{uint16}(65535* \text{mat2gray}(\text{out\_Pmap\_cat3, [0 1]})) ;
imwrite(uil6 PMAP cat3 xy, [Ch 7 Im 001', ' . tiff']) ;
```

```
% MATLAB SCRIPT: Train 3D UNET
% All code, image-data and screen-cast tutorial videos available for download at
% the Biostudies database under accession number S-BSST742
clear
close all
c1c% Specify path to bioformats library
addpath('D:\John\2021\MATLAB biostudies\MATLAB 3D UNET\2 TRAIN Unet\bfmatlab\')
% Specify directory containing training data
Training data directory =
'D:\John\2021\MATLAB biostudies\MATLAB 3D UNET\1 ImageData\TRAIN\DATA\' ;
% Specify channel number in training data that contains reflectance information
RL training directory = 3;
% Specify directory containing training labels
Training labels path =
'D:\John\2021\MATLAB biostudies\MATLAB 3D UNET\1 ImageData\TRAIN\LABELS\';
%% COMMIT TRAINING DATA TO DIRECTORY rescaled [0 1] IN MAT FORMAT
if ~exist('mat training data', 'dir')
    mkdir('mat training data');
end
for loop = 1:2counter = springitft('803d', loop);
    % find metadata describing file
    reader = bfGetReader([Training data directory, 'TRAIN ', counter, '.tif']);
    omeMeta = reader.getMetadataStore();
    number of channels = omeMeta.getChannelCount(0);
    stackSizeZ = omeMeta.getPixelsSizeZ(0).getValue(); \frac{1}{2} number of Z slices
    % Load reflectance information
    for z plane = 1:stackSizeZiPlane = reader.getIndex(zplane -1, RL_training_directory -1, 0) + 1; %
because zplanes and channels are numbered from zero
        channel zimage{zplane} = bfGetPlane(reader, iPlane);
    end
    IM DATA = cat(3, channel \ zimage: : ) ;
    IM DATA = double(1*mat2gray(IM DATA, [0 65535]));
    save([pwd,'/mat_training_data/','TRAIN_DATA_',counter,'.mat'], 'IM_DATA') ;
end
%% COMMIT TRAINING LABELS TO DIRECTORY IN MAT FORMAT
if ~exist('mat training labels', 'dir')
    mkdir('mat training labels');
end
for loop = 1:2counter = sprintf('%03d', loop);
        % load label information
        for zplane = 1:stackSizeZiplane =imread([Training labels path, 'LABELS ', counter, '.tif' ], zplane);
```

```
label zimage{zplane} = iplane;
        end
         IM LABELS = cat(3, label zimage(:));
         IM LABELS = double(IM LABELS) ;
         save([pwd,'/mat_training_labels/','TRAIN_LABELS ',counter,'.mat'],
'IM LABELS');
end
% Once data is prepared for training, clear workspace
clear ;
%% Create 'Datastores' for the reflectance information and matching pixel-class
labels
% Read saved mat file containing reflectance info into an image datastore
% Directions for processing the mat file-type are in the accompanying 'matRead'
function
data_location = [pwd, '\mat training data\'] ;
volReader = \theta(x) JWmatRead(x) ;
reflectance ds =
imageDatastore(data location, 'FileExtensions', '.mat', 'ReadFcn', volReader);
% Read pixel labels into a pixel label datastore
label location = [pwd, ' \text{ training labels}'] ;
labelReader = \ell(x) JWLabelRead(x);
classNames = ["LFNuclei", "LFActin", "BackgroundOther"];
pixelLabelID = 1:3; % these represent the pixel values in the labels file
PixelLabel ds = pixelLabelDatastore(label location, classNames, pixelLabelID, ...
    'FileExtensions','.mat','ReadFcn',labelReader);
%% Set up patch extraction from reflectance datastore
patchesize = [64 64 32];patchPerImage = 375;MiniBatchSize = 8; % set the batch size
reflectance patches ds =
randomPatchExtractionDatastore(reflectance ds, PixelLabel ds, patchSize, 'PatchesPe
rImage', patchPerImage);
reflectance patches ds. MiniBatchSize = MiniBatchSize;
% Augment the patches using 'augment3dPatch' function
Training ds = transform(reflectance patches ds, @JWaugment3dPath);
%% CREATE THE 3D UNET
% input layer 64x64x32x1
% encoder depth 4
% 32 filters at the level of the first encoder
lgraph = layerGraph();
tempLayers = [image3dInputLayer([64 64 32 1], "Name", "ImageInputLayer")<br>convolution3dLayer([3 3 3], 32, "Name", "Encoder-Stage-1-Conv-<br>1", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name", "Encoder-Stage-1-BN-1")
    reluLayer("Name", "Encoder-Stage-1-ReLU-1")
convolution3dLayer([3 3 3], 64, "Name", "Encoder-Stage-1-Conv-<br>2", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name", "Encoder-Stage-1-BN-2")
    reluLayer("Name", "Encoder-Stage-1-ReLU-2")];
lgraph = addLayers(lgraph, tempLayers);
```

```
tempLayers = [
    maxPooling3dLayer([2 2 2], "Name", "Encoder-Stage-1-MaxPool", "Stride", [2 2 2])
convolution3dLayer([3 3 3],64, "Name", "Encoder-Stage-2-Conv-<br>1", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name", "Encoder-Stage-2-BN-1")
    reluLayer("Name","Encoder-Stage-2-ReLU-1")
    convolution3dLayer([3 3 3], 128, "Name", "Encoder-Stage-2-Conv-
2", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name", "Encoder-Stage-2-BN-2")
    reluLayer("Name", "Encoder-Stage-2-ReLU-2")];
lgraph = addLayers(lgraph, tempLayers);
tempLayers = [maxPooling3dLayer([2 2 2], "Name", "Encoder-Stage-2-MaxPool", "Stride", [2 2 2])
convolution3dLayer([3 3 3],128, "Name", "Encoder-Stage-3-Conv-<br>1", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name", "Encoder-Stage-3-BN-1")
    reluLayer("Name", "Encoder-Stage-3-ReLU-1")
    convolution3dLayer([3 3 3], 256, "Name", "Encoder-Stage-3-Conv-
2", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name", "Encoder-Stage-3-BN-2")
    reluLayer("Name", "Encoder-Stage-3-ReLU-2")];
lgraph = addLayers(lgraph, tempLayers);
tempLayers = [maxPooling3dLayer([2 2 2], "Name", "Encoder-Stage-3-MaxPool", "Stride", [2 2 2])
    convolution3dLayer([3 3 3], 256, "Name", "Encoder-Stage-4-Conv-
1", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name", "Encoder-Stage-4-BN-1")
    reluLayer("Name","Encoder-Stage-4-ReLU-1")
convolution3dLayer([3 3 3],512, "Name", "Encoder-Stage-4-Conv-<br>2", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name", "Encoder-Stage-4-BN-2")
    reluLayer("Name", "Encoder-Stage-4-ReLU-2")];
lgraph = addLayers(lgraph, tempLayers);tempLayers = [maxPooling3dLayer([2 2 2], "Name", "Encoder-Stage-4-MaxPool", "Stride", [2 2 2])
convolution3dLayer([3 3 3],512, Name", "Bridge-Conv-<br>1", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name","Bridge-BN-1")
    reluLayer("Name", "Bridge-ReLU-1")
    convolution3dLayer([3 3 3], 1024, "Name", "Bridge-Conv-
2", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name", "Bridge-BN-2")
    reluLayer("Name","Bridge-ReLU-2")
    transposedConv3dLayer([2 2 2], 1024, "Name", "Decoder-Stage-1-
UpConv", "BiasLearnRateFactor", 2, "Stride", [2 2 2], "WeightsInitializer", "he")];
lgraph = addLayers(lgraph, tempLayers);tempLayers = [concatenationLayer(4,2,"Name","Decoder-Stage-1-Concatenation")
    convolution3dLayer([3 3 3],512, "Name", "Decoder-Stage-1-Conv-
1", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name", "Decoder-Stage-1-BN-1")
    reluLayer("Name", "Decoder-Stage-1-ReLU-1")
    convolution3dLayer([3 3 3],512, "Name", "Decoder-Stage-1-Conv-
2", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name","Decoder-Stage-1-BN-2")
```

```
reluLayer("Name","Decoder-Stage-1-ReLU-2")
    transposedConv3dLayer([2 2 2], 512, "Name", "Decoder-Stage-2-
UpConv", "BiasLearnRateFactor", 2, "Stride", [2 2 2], "WeightsInitializer", "he") ];
lgraph = addLayers(lgraph, tempLayers);tempLayers = [
    concatenationLayer(4,2,"Name","Decoder-Stage-2-Concatenation")
convolution3dLayer([3 3 3], 256, "Name", "Decoder-Stage-2-Conv-<br>- "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name","Decoder-Stage-2-BN-1")
    reluLayer("Name","Decoder-Stage-2-ReLU-1")
    convolution3dLayer([3 3 3], 256, "Name", "Decoder-Stage-2-Conv-
2", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name","Decoder-Stage-2-BN-2")
    reluLayer("Name", "Decoder-Stage-2-ReLU-2")
    transposedConv3dLayer([2 2 2], 256, "Name", "Decoder-Stage-3-
UpConv", "BiasLearnRateFactor", 2, "Stride", [2 2 2], "WeightsInitializer", "he") |;
lgraph = addLayers(lgraph, tempLayers);
tempLayers = [concatenationLayer(4,2,"Name","Decoder-Stage-3-Concatenation")
    convolution3dLayer([3 3 3], 128, "Name", "Decoder-Stage-3-Conv-
1", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name","Decoder-Stage-3-BN-1")
    reluLayer("Name", "Decoder-Stage-3-ReLU-1")
convolution3dLayer([3 3 3],128, "Name", "Decoder-Stage-3-Conv-<br>2", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name","Decoder-Stage-3-BN-2")
    reluLayer("Name","Decoder-Stage-3-ReLU-2")
transposedConv3dLayer([2 2 2],128, "Name", "Decoder-Stage-4-<br>UpConv", "BiasLearnRateFactor", 2, "Stride", [2 2 2], "WeightsInitializer", "he")];
lgraph = addLayers(lgraph, tempLayers);tempLayers = [concatenationLayer(4,2,"Name","Decoder-Stage-4-Concatenation")
convolution3dLayer([3 3 3], 64, "Name", "Decoder-Stage-4-Conv-<br>1", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name","Decoder-Stage-4-BN-1")
    reluLayer("Name","Decoder-Stage-4-ReLU-1")
    convolution3dLayer([3 3 3], 64, "Name", "Decoder-Stage-4-Conv-
2", "Padding", "same", "WeightsInitializer", "he")
    batchNormalizationLayer("Name","Decoder-Stage-4-BN-2")
    reluLayer("Name","Decoder-Stage-4-ReLU-2")
    convolution3dLayer([1 1 1],3, "Name", "Final-
ConvolutionLayer", "Padding", "same", "WeightsInitializer", "he")
    softmaxLayer("Name","Softmax-Layer")
    pixelClassificationLayer("Name","Segmentation-Layer")];
lgraph = addLayers(lgraph, tempLayers);clear tempLayers;
% encoder / decoder connections
lgraph = connectLayers(lgraph, "Encoder-Stage-1-ReLU-2", "Encoder-Stage-1-
MaxPool");
lgraph = connectLayers(lgraph, "Encoder-Stage-1-ReLU-2", "Decoder-Stage-4-
Concatenation/in2");
lgraph = connectLayers(lgraph, "Encoder-Stage-2-ReLU-2", "Encoder-Stage-2-
MaxPool");
lgraph = connectLayers(lgraph, "Encoder-Stage-2-ReLU-2", "Decoder-Stage-3-
Concatenation/in2");
```

```
lgraph = connectLayers(lgraph, "Encoder-Stage-3-ReLU-2", "Encoder-Stage-3-
MaxPool");
lgraph = connectLayers(lgraph, "Encoder-Stage-3-ReLU-2", "Decoder-Stage-2-
Concatenation/in2"):
lgraph = connectLayers(lgraph, "Encoder-Stage-4-ReLU-2", "Encoder-Stage-4-
MaxPool");
lgraph = connectLayers(lgraph, "Encoder-Stage-4-ReLU-2", "Decoder-Stage-1-
Concatenation/in2");
lgraph = connectLayers(lgraph, "Decoder-Stage-1-UpConv", "Decoder-Stage-1-
Concatenation/in1"):
lgraph = connectLayers(lgraph, "Decoder-Stage-2-UpConv", "Decoder-Stage-2-
Concatenation/in1");
lgraph = connectLayers(lgraph, "Decoder-Stage-3-UpConv", "Decoder-Stage-3-
Concatenation/in1");
lgraph = connectLayers(lgraph, "Decoder-Stage-4-UpConv", "Decoder-Stage-4-
Concatenation/in1");
% analyzeNetwork(lgraph) % comment in to check structure and errors
plot(lgraph) % comment in to show network structure
%% Specify training options
options = trainingOptions('adam', ...
    'MaxEpochs', 150, ...
    'InitialLearnRate', 5e-4, \ldots'LearnRateSchedule', 'piecewise', ...
    'LearnRateDropPeriod', 5, ...
    'LearnRateDropFactor', 0.95, ...
    'Plots', 'training-progress', ...
    'Verbose', true, ...
    'VerboseFrequency', 20, ...
    'Shuffle', 'every-epoch',... %
    'ExecutionEnvironment', 'auto',...
    'MiniBatchSize', MiniBatchSize);
%% Train and save the network
close all
% Specify location to save the network
saved network directory =
'D:\John\2021\MATLAB biostudies\MATLAB 3D UNET\3 Saved models\';
% Train the network
modelDateTime = datestr(now, 'dd-mmm-yyyy-HHMM');
[net, info] = trainNetwork(Training ds, lgraph, options);% Timestamp and save the network after training
save([saved network directory, 'MLN Biostudies ', modelDateTime, '.mat'], 'net', 'opt
ions', 'info');
```


3-D Unet architecture schematic. The network uses an input layer for the reflectance data of 64x64x64x1 (x, y, z, channels). The three-class Unet architecture uses an encoder depth of 4 with 64 filters at the level of the first encoder. The network uses complete up-convolutional expansion to yield outputted probability maps that are identically sized to the input layer.

```
% MATLAB SCRIPT: TEST 3D UNET
% All code, image-data and screen-cast tutorial videos available for download at
% the Biostudies database under accession number S-BSST742
clear
close all
c1c% Specify path to bioformats library
addpath('D:\John\2021\MATLAB biostudies\MATLAB 3D UNET\4 TEST Unet\bfmatlab\')
% Specify directory containing test data
Test data directory =
'D:\John\2021\MATLAB biostudies\MATLAB 3D UNET\1 ImageData\TEST\' ;
% Specify channel number in test data that contains reflectance information
RL channel number = 2;
% COMMIT REFLECTANCE TEST DATA TO DIRECTORY RESCALED [0 1] IN MAT FORMAT
if ~exist('mat_test_data', 'dir')
    mkdir('mat test data');
end
for loop = 1:1counter = sprintf('%03d',loop);
    % find metadata describing file
    reader = bfGetReader([Test data directory,'TEST ', counter, '.tif' | ) ;
    omeMeta = reader.getMetadataStore();
    number of channels = omeMeta.getChannelCount(0);
    stackSizeZ = omeMeta.getPixelsSizeZ(0).getValue(); \frac{1}{2} number of Z slices
    % Load reflectance information
    for zplane = 1:stackSizeZiPlane = reader.getIndex(zplane -1, RL channel number -1, 0) + 1; %because zplanes and channels are numbered from zero
        channel zimage{zplane} = bfGetPlane(reader, iPlane);
    end
    IM DATA = cat(3, channel_zimage,: ) ;
    IM DATA = double(1*mat2gray(IM DATA, [0 65535])); % rescale zero-one
    save([pwd, '/mat test data/', 'TEST DATA ', counter, '.mat'], 'IM DATA') ;
end
clear
& *
% load the trained 3D Unet network
load('D:\John\2021\MATLAB biostudies\MATLAB 3D UNET\3 Saved models\MLN Biostudie
s 27-May-2021-1355.mat') ;
% load the rescaled reflectance test data
load([pwd,'/mat_test_data/','TEST_DATA_001.mat']);
%% Patch the reflectance data through the network
% Set the patch sizes to be passed to the net
patchSize = [256 256 64];% Segment blockwise then reassemble in full
% Define image dimensions
```

```
[height, width, depth, nChannel] = size(IM DATA);
patch = zeros([patchSize, nChannel], 'like', IM DATA);
number of height patches =ceil(height/patchSize(1));
number_of_width_patches =ceil(width/patchSize(2));<br>number_of_width_patches =ceil(width/patchSize(2));<br>number_of_depth_patches =ceil(depth/patchSize(3));
% Pad image to have dimensions as multiples of patchSize
height pad = number of height patches*patchSize(1);
width pad = number of width patches*patchSize(2);
depth pad = number of depth patches*patchSize(3);
% Amount to pad different dimensions of image
padSize(1) = height pad - height;padsize(2) = width pad - width;padsize(3) = depth pad - depth;% Pad the image by correct amounts
im pad = padarray (IM DATA, padSize, 0, 'post');
% Preallocate some matrices to catch the probability maps
out Uncertainty Scores = zeros([size(im pad,1), size(im_pad,2), size(im_pad,3)],
'double'); % needs to match OutputType in semanticseq below
out scores from network all classes=zeros([size(im pad,1), size(im pad,2),
size(im pad, 3), 3], 'double');% Loop through blocks of 'patchSize'
for loop height = 1:number of height patches
    for loop width = 1:number of width patches
        for loop_depth = 1:number_of depth patches
             start height position=(loop height-1)*patchSize(1)+1;
             end height position=loop height*patchSize(1);
            start width position=(loop width-1)*patchSize(2)+1;
            end width position=loop width*patchSize(2);
             start depth position=(loop depth-1)*patchSize(3)+1;
            end depth position=loop depth*patchSize(3);
            patch to deploy =...
im pad(start height position:end height position, start width position:end width
position, start depth position: end depth position, :);
             % deploy net
             [patch seg, Scores, allScores] = semanticseg(patch to deploy, net,
'OutputType', 'double',...
             'ExecutionEnvironment', 'auto');
out Uncertainty Scores(start height position: end height position, start width pos
ition: end width position, start depth position: end depth position)...
            =Scores;
out scores from network all classes (start height position:end height position, st
art width position: end width position, start depth position: end depth position, :)
\ddots=allScores;
```
end

```
end
% Script is general for n classes to this point
out Pmap catl = out scores from network all classes(:,:,:,1);
out Pmap cat2 = out scores from network all classes(:,,:,,:,2);out Pmap cat3 = out scores from network all classes(:,:,:,3);
% Remove padding from probability maps
out Uncertainty Scores = out Uncertainty Scores(1:height, 1:width, 1:depth);
out Pmap catl = out Pmap cat 1(1:height, 1:width, 1:depth);out Pmap cat2 = out Pmap cat2(1:height, 1:width, 1:depth);
out Pmap cat3 = out Pmap cat3(1:height, 1:width, 1:depth);
%% visualise network outputs
figure(2)clf(figure(2))ax1 = subplot(2, 3, 1);imshow(out Pmap cat1(:,:,60),[])
title('LF-nuclei')
ax2 = subplot(2, 3, 2) ;
imshow(out Pmap cat2(:,:,60), [])
title('LF-actin')
ax3 = subplot(2, 3, 3);imshow(out Pmap cat3(:,:,60), [])
title('Background/other')
ax4 = subplot(2, 3, 5);imshow(out Uncertainty Scores(:,:,60), [])
title('Uncertainty')
linkaxes(\lceil ax1 \rceil ax2 \rceil ax3 \rceil, 'xy')%% Map to 16-bit and save for loading into CellProfiler
uil6 PMAP cat1 xy = uint16(65535 *mat2gray(out Pmap cat1, [0 1])) ;
uil6 PMAP cat2 xy = uint16(65535*mat2gray(out Pmap cat2, [0 1])) ;
uil6 PMAP cat3 xy = uint16(65535 *mat2gray(out Pmap cat3, [0 1])) ;
data to save = cat(4,uid6) PMAP catl xy, uil6 PMAP cat2 xy, uil6 PMAP cat3 xy);
% Map to 16-bit and save for loading into CellProfiler
for loop = 1:3CP channel number = num2str(loop +2) ;
   MultiChImgTile = data to save(:,:,:,:]oop) ;
   % spec a fiji description
   fiji descr = \lceil'ImaqeJ=1.52p' newline ...
               'images=' num2str(size(MultiChImgTile,3)*...
                                 size(MultiChImgrile, 4) *...
                                 size(MultiChImgTile,5)) newline...
               'channels=' num2str(size(MultiChImgTile,4)) newline...
               'slices=' num2str(size(MultiChImgTile,3)) newline...
               'frames=' num2str(size(MultiChImqTile,5)) newline...
               'hyperstack=true' newline...
               'mode=grayscale' newline...
               'loop=false' newline...
               'min=0.0' newline...
               'max=65535.0']; % bitdepth spec
   t = Tiff(['Ch ', CP channel number, 'Im ', '001', '.tif'], 'w') ;
```
end

```
tagstruct. ImageLength = size(MultiChImgTile, 1);
    tagstruct. ImageWidth = size(MultiChImgTile,2);
    tagstruct.Photometric = Tiff.Photometric.MinIsBlack;
    tagstruct.BitsPerSample = 16;tagstruct.SamplesPerpixel = 1;tagstruct. Compression = Tiff. Compression. None; %% lzw is not compatible w
CP4 out-of-box
    tagstruct.PlanarConfiguration = Tiff.PlanarConfiguration.Chunky;
    tagstruct.SampleFormat = Tiff.SampleFormat.UInt;
    tagstruct. ImageDescription = fiji descr;
        for frame = 1:size(MultiChImgFile, 5)for slice = 1:size(MultiChImgFile, 3)for channel = 1:size(MultiChImgrile, 4)t.setTag(tagstruct)
                    t.write(im2uint16(MultiChImgTile(:,:,slice,channel,frame)));
                    t.writeDirectory(); % saves a new page in the tiff file
                end
            end
        end
        t.close()
end
```
Windows 10: Running the label-free cell segmentation deep learning scripts on an NVIDIA GPU using Python 3.6 and Tensorflow-gpu 1.9.0

In brief, it is recommended to use these deep learning files with:

- Python 3.6 \bullet
- \bullet Tensorflow-gpu 1.9.0
- **Keras 2.1.5**
- Numpy 1.18.1 \bullet
- Scipy 1.4.1 \bullet
- \bullet Java SE Development Kit 11.0
- Python-bioformats 1.5.2
- CUDA Toolkit 9.0 / cuDNN v7.6.4

Installation Steps:

1. Install Visual Studio Express Community 2017

https://visualstudio.microsoft.com/dev-essentials/#software

- This is necessary to enable the install of the CUDA toolkit.
- At the link above, join Visual Studio Development Essentials (free sign-up).
- Use the search tool to find, download and install Visual Studio Express Community 2017.
- Using the recommended configurations at every step of the installation works fine.

- Restarting your PC after installing Visual Studio is a probably a good idea.

2. Install CUDA Toolkit 9.0 and accompanying patches for Windows 10.

- Tensorflow-GPU 1.9.0 requires CUDA 9.0 - not whatever the latest version of the toolkit is. - This is available at the Nyidia website "CUDA Toolkit Archive" --> select CUDA Toolkit 9.0 https://developer.nvidia.com/cuda-toolkit-archive

\equiv \otimes **nvidia.** Developer

CUDA Toolkit Archive

Home

Previous releases of the CUDA Toolkit, GPU Computing SDK, documentation and developer drivers can be found using the links below. Please select the release you want from the list below, and be sure to check www.nvidia.com/drivers for more recent production drivers appropriate for your hardware configuration.

Download Latest CUDA Toolkit Learn More about CUDA Toolkit 11

Latest Release

CUDA Toolkit 11.5.1 (November 2021), Versioned Online Documentation

Archived Releases

CUDA Toolkit 11.5.0 (October 2021), Versioned Online Documentation CUDA Toolkit 11.4.3 (November 2021), Versioned Online Documentation CUDA Toolkit 11.4.2 (September 2021). Versioned Online Documentation CUDA Toolkit 11.4.1 (August 2021), Versioned Online Documentation CUDA Toolkit 11.4.0 (June 2021), Versioned Online Documentation CUDA Toolkit 11.3.1 (May 2021), Versioned Online Documentation CUDA Toolkit 11.3.0 (April 2021), Versioned Online Documentation CUDA Toolkit 11.2.2 (March 2021), Versioned Online Documentation CUDA Toolkit 11.2.1 (Feb 2021), Versioned Online Documentation CUDA Toolkit 11.2.0 (Dec 2020), Versioned Online Documentation CUDA Toolkit 11.1.1 [Oct 2020], Versioned Online Documentation CUDA Toolkit 11.1.0 (Sept 2020), Versioned Online Documentation CUDA Toolkit 11.0 Update1 (Aug 2020), Versioned Online Documentation CUDA Toolkit 11.0 (May 2020), Versioned Online Documentation CUDA Toolkit 10.2 (Nov 2019), Versioned Online Documentation CUDA Toolkit 10.1 update2 (Aug 2019), Versioned Online Documentation CUDA Toolkit 10.1 update1 (May 2019), Versioned Online Documentation CUDA Toolkit 10.1 (Feb 2019), Online Documentation CUDA Toolkit 10.0 (Sept 2018), Online Documentation CUDA Toolkit 9.2 (May 2018), Online Documentation CUDA Toolkit 9.1 (Dec 2017), Online Documentation CUDA Toolkit 9.0 (Sept 2017), Online Documentation **IDA Toolkit & O GA? IFah 2017L Online Documentat**

- Select the target platform as Windows, X86_64, version 10 and the installer type as exe(local)

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Download Installers for Windows 10 x86_64

The base installer is available for download below. There are 4 patches available. These patches require the base installer to be installed first.

- First install the "base installer" following the standard, "express configurations" options.

- Then install Patches 1-4 sequentially in order by just following the on-screen prompts after each download.

3. Install cuDNN v7.6.4 for CUDA 9.0

- To download and install cuDNN, first join the NVIDIA Developer Program - which is free. https://developer.nvidia.com/cudnn-download-survey

- Once signed in, proceed the cuDNN download page and click archived cuDNN releases: https://developer.nvidia.com/rdp/cudnn-archive

cuDNN Download

Home

- Scroll down to the option to download cuDNN v7.6.4 for CUDA 9.0 and download the library for Windows 10.

- Unzip the downloaded cuDNN .zip file.

- Inside are three files which need to be copied to the correct folder subdirectories of your Window 10 installation of the CUDA 9.0 toolkit:

- These files are cudnn64_7.dll, cudnn.h and cudnn.lib:

1. cudnn64_7.dll

Copy the file from the unzipped cuDNN download folder at e.g., <unzipped_download>/cudnn-9.0-windows10-x64-v7.6.2.24\cuda\bin\cudnn64_7.dll

and paste it into the NVIDIA GPU computing toolkit v9.0 subdirectory 'bin' located at e.g., C:\Program Files\NVIDIA GPU Computing Toolkit\CUDA\v9.0\bin\

2. cudnn.h

Copy the file from the unzipped cuDNN download folder at e.g., <unzipped_download>/cudnn-9.0-windows10-x64-v7.6.2.24\cuda\include\cudnn.h

and paste it into the NVIDIA GPU computing toolkit v9.0 subdirectory 'include' located at e.g., C:\Program Files\NVIDIA GPU Computing Toolkit\CUDA\v9.0\include\

3. cudnn.lib

Copy the file from the unzipped cuDNN download folder at e.g., <unzipped_download>/cudnn-9.0-windows10-x64-v7.6.2.24\cuda\lib\x64\cudnn.lib

and paste it into the NVIDIA GPU computing toolkit v9.0 subdirectory 'include' located at e.g., C:\Program Files\NVIDIA GPU Computing Toolkit\CUDA\v9.0\lib\x64\

4. Check that the CUDA environment variables are set in Windows 10

- On the right-side, of the dialogue that opens, click "Advanced system settings"

- In the "System Properties" dialogue box, click
"Environment Variables" at the bottom

 \times

Environment Variables

- Make sure in the bottom window (labelled "System Variables") that variables named CUDA PATH and CUDA PATH V9.0 exist and point to the correct locations e.g.,

C:\Program Files\NVIDIA GPU Computing Toolkit\CUDA\v9.0\bin

and

C:\Program Files\NVIDIA GPU Computing Toolkit\CUDA\v9.0\libnvvp

respectively.

- These paths should be auto-installed. If they are missing on your system, they can be added by clicking the "New" button below the system variables bottom panel and entering the name and path into the dialogue box for your system.

5. Install Python 3.6.8

- To install Python version 3.6.8 navigate to the previous release at: https://www.python.org/downloads/release/python-368/

Files

- Scroll to the bottom of the page and download the "Windows x86-64 executable installer" with description "AMD64/EM64T/x64".

- Once downloaded, follow the on-screen prompts to install Python 3.6.8.

- Check the box to add Python to the Windows path.

6. Install Java Development Kit 11

- This is used by Python-bioformats to enable read/write of image-data.

- Download and install Java Development kit 11

https://www.oracle.com/java/technologies/downloads/#java11

- Once Java SE Development Kit 11 is installed, set the JAVA_HOME environment variable and add the Java development kit to the Windows path. To do this, as above, open a File Explorer window, right-click on the 'This PC' option and select 'Properties' from the drop-down menu.

The control panel will pop up as a separate window. Select 'Advanced system settings' from the list appearing at the right of the window.

In the 'system properties' dialogue that opens, select 'Environment Variables'. This will cause the environment variables window to appear. To set the 'JAVA_HOME' variable, Click the 'New' button option at the bottom of this window in the 'System variables' section.

Name the new variable 'JAVA_HOME' and use the 'Browse Directory' option to specify the path to JDK 11. Select 'OK' to create this new variable:

To add JDK11 to the Windows path, Click on the exisiting 'Path' system variable and click the 'Edit' button. A new window will appear. Click new and type '%JAVA_HOME%\bin'.

- Click 'OK' to apply changes and close all opened windows.

7. Setup a virtual environment and install the dependencies necessary to run the code

- Download and unzip the "Python_biostudies" folder from the BioStudies project archive to a suitable location on your computer.

- Run command prompt as administrator:

- To do this, Search "CMD", right-click on "Command Prompt" from the search results dialogue and click "Run as administrator":

- Using the 'cd' command, change the current directory to the unzipped python scripts folder downloaded from Biostudies e.g.,

- Make a new subdirectory 'veny' and initialise an instance of Python inside it e.g..

C:\Users\John\20211118 Python biostudies>python -m venv ./venv

- Activate the newly-created virtual environment e.g.,

C:\Users\John\20211118 Python biostudies>venv\Scripts\activate.bat

- Update pip to the latest version (N.B., this is critical to the successful install of javabridge with Python 3.6)

(venv) C:\Users\John\20211118_Python_biostudies>python -m pip install --upgrade pip

- Using the "requirements.txt" file included in the BioStudies download, install the required dependencies and the Spyder 4.0 Integrated Development Environment (IDE) to the newlycreated virtual environment e.g.,

(venv) C:\Users\John\20211118_Python_biostudies>pip install -r requirements.txt

8. Training a 2-D UNET model

- A screencast video is included with the BioStudies project archive.

- Download and unzip the Python BioStudies project archive at a suitable location on your computer.

- Inside the 2D_UNET_Python folder, there is a sequentially-organised workflow starting with raw data and ending with a CellProfiler pipeline that obtains cell features from the label-free cell segmentation:

- In command prompt with the virtual environment active, type 'Spyder' to start the Spyder4 IDE.

- To train a 2-D UNET model, set the Spyder working directory to the "2 TRAIN Unet" directory. Open the "A_TRAIN_UNET" script.

- Update the path saving the training data and pixel classification labels in numpy format. - This should be inside the"2 TRAIN Unet" directory.

- The script will save the model along with checkpoint values taken during training. You should specify where these files are to be saved. This should be folder 3 of the workflow: ("3_Saved_models").

- To start model training, click the green arrow button at the top of the Spyder dialogue or type the script name at the command line.

- Model training takes several hours $($ \sim 4h on a NVIDIA GTX 1080 Ti GPU)

- The newly-trained model will be saved in the "3_Saved_models" directory.

9. Testing a pretrained 2-D model using unseen data

- A screencast video is included with the BioStudies project archive.

- Change the Spyder working directory to the "4_Test_Unet" directory. Open the

"A_TEST_UNET" script.

- Change the path to the unseen test image (located in the "1_ImageData" folder).

- Specify which pretrained network to use (pretrained networks are located in the "3 Saved models" folder

 $et($,
ight<mark>;('C:/Users/John/20211118 Python biostudies/Pyth</mark> del fully train

- Clicking the green arrow button or type the file name at the command line to process the unseen reflectance data with the selected pretrained network:

- Probability maps for the LF-nuclei, LF-actin and Background/Other classes will be saved in the working directory named ready for input into the CellProfiler pipeline (filenames Ch_5_lm_001, Ch_6_lm_001, Ch_7_lm_001, respectively).

10. Training a 3-D UNET Model

- A screencast video is included with the BioStudies project archive.

- Inside the 3D_UNET_Python folder, there is a sequentially-organised workflow starting with raw data and ending with a CellProfiler pipeline that obtains 3-D cell features from the labelfree cell segmentation:

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- To train a 3-D UNET model, open Spyder and set the working directory to the "2 TRAIN Unet" directory. Open the "A_TRAIN_UNET_3D" script.

- Specify the checkpoint path during model training:

- Specify the location to save the model when training completes. This should be the "3_Saved_models" directory.

- Click "Run" to commence model training.
- This takes considerable time (approximately 6h on a NVIDIA GTX 1080 Ti GPU card).

11. Testing a pretrained 3-D UNET Model using unseen data

- A screencast video is included with the BioStudies project archive.

- Change the Python working directory to the "4_Test_Unet" directory. Open the

"A TEST UNET 3D" script.

- Specify the location of the unseen test image-data. This is located inside the "1_ImageData" folder at "1 ImageData/TEST/".

- Specify the channel containing the reflectance information (here, '2').

- Specify where the unseen data should be stored upon conversion to Numpy format. This should be inside the "4_Test_Unet" folder.

- Specify a pretrained 3-D Unet model from the "3_Saved_models" directory.

#%% load the trained 3D Unet net rк
/20211118_Python_biostudies/Python/3D_UNET_PYTHON/3D_UNET_PYTHON/3_Saved_models/my_h53D_model.h5") n-risined_model.load_weights("C:/Users/John/20211118_Python_biostudies/Python/3D_UNET_PYTHON/3D_UNET_PYTHON/3_Saved_models/my_h53D_model_updated.h5")
pretrained_model.load_weights("C:/Users/John/20211118_Python_biostudies/

- Click the green arrow to process the unseen reflectance data with the 3-D Unet model.

- Probability maps for the LF-nuclei, LF-actin and Background/Other classes will be saved as multipage.TIFF files in the working directory named ready for input into the CellProfiler pipeline (filenames Ch_3_lm_001, Ch_4_lm_001, Ch_5_lm_001, respectively).


```
% PYTHON SCRIPT: TRAIN 2D UNET
% All code, image-data and screen-cast tutorial videos available for download at
% the Biostudies database under accession number S-BSST742
# -*- coding: utf-8 -*-
Created on Mon Sep 20 23:58:04 2021
@author: Paul
#Import all required modules
from PIL import Image
import cv2
import matplotlib.pyplot as plt
import matplotlib.pyplot as plt
import skimage
from skimage import data
from skimage.filters import threshold otsu
import cv2
import os
import numpy as np
import skimage.transform as trans
import tensorflow
from tensorflow.keras.models import *
from tensorflow.keras.layers import *
from tensorflow.keras.optimizers import *
from tensorflow.keras.callbacks import ModelCheckpoint, LearningRateScheduler
from tensorflow.keras import backend as keras
from tensorflow.keras.preprocessing.image import ImageDataGenerator
import sklearn.feature extraction
from sklearn.datasets import load sample image
from sklearn. feature extraction import image
from datetime import datetime
from keras.utils import to categorical
from tensorflow.python.keras.optimizers import *
import skimage.io
import h5py # this was missing
#88# Read in the reflectance data for training
Training data holder =
skimage.io.imread('C:/Users/John/20211118 Python biostudies/Python/2D UNET PYTHO
N/2D PeyersPatch/1 ImageData/TRAIN IMAGE.tif')
Training data = Training data holder[0,0,:,:,2]
#Read in the mask to isolated just the lymphoid tissue
mask = Training data holder[0,0,:,:,3]
thresh = threshold otsu(Training data)
mask = mask > threshmask = mask * 1mask = np.util6(maxk)# Apply the mask to the training data
```

```
Training data = np.multiply(Training data, mask);
Training data = np.double(Training data);# Rescale the training data in the interval [0 1]
Training data norm holder = np{\cdot}zeros((8551, 5701), np{\cdot}double)Training data norm = cv2.normalize(Training data, Training data norm holder,
1.0, 0.0, cv2. NORM MINMAX)#Read in the pixel-class labels created from the nuclei and actin staining
Training labels holder =
skimage.io.imread('C:/Users/John/20211118 Python biostudies/Python/2D UNET PYTHO
N/2D PeyersPatch/1 ImageData/TRAIN LABELS.png') ;
Training labels = np.where(Training labels holder == 3, 0, ...)Training labels holder)
#% Visually inspect the data and labels
figl, (ax1, ax2) = plt.subplots(1, 2) # figure1ax1.imshow(Training data norm)
axl.set title('Reflectance data')
ax2.imshow(Training labels)
ax2.set title('Pixel classification labels')
#%% Once happy with labels and data, commit the reflectance information data to
sub-directory in .npy format
MYDTR ='C:/Users/John/20211118 Python biostudies/Python/2D UNET PYTHON/2D PeyersPatch/2
TRAIN Unet/npy training data/'
CHECK FOLDER = os.path.isdir(MYDIR)
# If folder doesn't exist, then create it.
if not CHECK FOLDER:
   os.makedirs(MYDIR)
np.save(os.path.join(MYDIR, 'Training_data'), Training_data_norm)
# Create matrices to store training data
Patching data = np \cdot zeros( (8551, 5701, 2))Patching data[:,:,0] = Training data norm
Patching data[:,:,1] = Training labels
#Create a training data comprising matching patches (256x256 pixels) of image-
data and training labels
Patched images =
sklearn.feature extraction.image.extract patches 2d(Patching data, patch size =
[256, 256], max patches=12000, random state=None)
#88# CREATE THE UNET
# input layer 256x256x1
# encoder depth 4
# 64 filters at the level of the first encoder
def unet(pretrained weights = None, input size=(256, 256, 1), n class=3):
```

```
inputs = tensorflow.keras.Input(shape=input size)
    conv1 = Conv2D(64, 3, activation = 'relu', dilation rate=2,padding = 'same'.\text{kernel initialization} = 'he normal') (\text{inputs})conv1 = BatchNormalization() (conv1)conv1 = Conv2D(64, 3, activation = 'relu', dilation rate=2, padding = 'same',kernel initializer = 'he normal')(conv1)
    conv1 = BatchNormalization() (conv1)pool1 = MaxPooling2D(pool_size=(2, 2))(conv1)conv2 = Conv2D(128, 3, activation = 'relu', dilation rate=2,padding ='same', kernel initializer = 'he normal')(pooll)
    conv2 = BatchNormalization() (conv2)conv2 = Conv2D(128, 3, activation = 'relu', dilation rate=2, padding ='same', kernel initializer = 'he normal')(conv2)
    conv2 = BatchNormalization() (conv2)pool2 = MaxPooling2D(pool size=(2, 2))(conv2)conv3 = Conv2D(256, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(pool2)
    conv3 = BatchNormalization() (conv3)conv3 = Conv2D(256, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(conv3)
    conv3 = BatchNormalization() (conv3)pool3 = MaxPooling2D(pool size=(2, 2))(conv3)conv4 = Conv2D(512, 3, activation = 'relu', padding = 'same',\text{kernel } \text{initializer} = \text{ 'he normal ' } (\text{pool3})conv4 = BatchNormalization() (conv4)conv4 = Conv2D(512, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(conv4)
    conv4 = BatchNormalization() (conv4)drop4 = Dropout(0.5)(conv4, training=True)pool4 = MaxPooling2D(pool size=(2, 2))(drop4)conv5 = Conv2D(1024, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(pool4)
    conv5 = BatchNormalization() (conv5)conv5 = Conv2D(1024, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(conv5)
    conv5 = BatchNormalization() (conv5)drop5 = Dropout(0.5)(conv5, training=True)up6 = Conv2D(512, 2, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(UpSampling2D(size = (2,2))(drop5))
    merge6 = concatenate(\frac{1}{\text{drop4},\text{up6}}, axis = 3)
    conv6 = Conv2D(512, 3, activation = 'relu', padding = 'same',kernel_initializer = 'he_normal')(merge6)
    conv6 = Conv2D(512, 3, activation = 'relu', padding = 'same',\text{kernel initializer} = \text{he normal} (conv6)
    up7 = Conv2D(256, 2, activation = 'relu', padding = 'same',kernel_initializer = 'he_normal')(UpSampling2D(size = (2,2))(conv6))
    merge7 = concatenate([conv3, up7], axis = 3)
    conv7 = Conv2D(256, 3, activation = 'relu', padding = 'same',\text{kernel initialization} = 'he normal') (\text{merge7})conv7 = Conv2D(256, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(conv7)
    up8 = Conv2D(128, 2, activation = 'relu', padding = 'same',
```
 $\text{kernel}_\text{indا}$ initializer = 'he_normal')(UpSampling2D(size = $(2,2)$)(conv7))

```
merge8 = concatenate([conv2, up8], axis = 3)conv8 = Conv2D(128, 3, activation = 'relu', padding = 'same',\text{kernel initializer} = \text{ 'he normal' } (\text{merge8})conv8 = Conv2D(128, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(conv8)
    up9 = Conv2D(64, 2, activation = 'relu', padding = 'same',\text{kernel\_initializer} = \text{ 'he\_normal'} (UpSampling2D(size = (2,2)) (conv8))
    merge9 = concatenate([conv1, up9], axis = 3)
    conv9 = Conv2D(64, 3, activation = 'relu', padding = 'same',\text{kernel initialization} = 'he normal') (\text{merge9})conv9 = Conv2D(64, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(conv9)
    conv10 = Conv2D(n class, 1, activation = 'softmax') (conv9)model = tensorflow.keras.Model(inputs = inputs, outputs = conv10)model.compile(optimizer = Adam(lr = 0.0001), loss ='sparse categorical crossentropy', metrics = ['sparse categorical accuracy'])
    if(pretrained weights):
     model=keras.models.load model(pretrained weights)
    return model
#%% Split data into image and label data and reshape ready for training
trainX = Patched images[:, :, : , 0]trainX = np.asarray(trainX).reshape((12000, 256, 256, 1))trainY = Patched images[:,:,:,1]
trainY = np.asarray(trainY).reshape((12000, 256, 256, 1))#Define model for data
model = unet(pretrained weights = None, input size = (256, 256, 1), n class=3)
# Define augmentation options
def get train augmented(trainX=trainX, trainY=trainY, BATCH SIZE=12):
    aug_X = ImageDataGenerator(rotation_range=360, zoom_range=[1,1],
width shift range=[0,0], height shift range=[0,0], horizontal flip=True,
vertical_flip = True, shear_range = 0, fill_mode = "constant", cval=0.0)
    aug Y = ImageDataGenerator(rotation range=360, zoom range=[1,1],
width_shift_range=[0,0], height_shift_range=[0,0], horizontal_flip=True,
vertical_flip = True, shear_range = 0, fill_mode = "constant", cval=0.0)
    aug X.fit(trainX, augment=True, seed=1)
    aug Y.fit(trainY, augment=True, seed=1)
    X train augmented = aug X.flow(trainX, batch size=BATCH SIZE, shuffle=True,
seed=1)
```

```
Y train augmented = aug Y.flow(trainY, batch size=BATCH SIZE, shuffle=True,
seed=1)
    train generator = zip(X train augmented, Y train augmented)for (X train augmented, Y train augmented) in train generator:
        yield (X train augmented, Y train augmented)
#%% Define path to safe network, time stamp network
checkpoint filepath ='C:/Users/John/20211118 Python biostudies/Python/2D UNET PYTHON/2D PeyersPatch/3
Saved models/'
now = datetime.now()dt string = now.strftime("%d/%m/%Y%H:%M:%S")
NAME =dt string
Name file = 'PeyersPatchBiostudies '
checkpoint filepath name = checkpoint filepath + Name file+dt string
checkpoint dir = os.path.dimme(checkpoint filepath name)#Specify that weights are to be saved
model checkpoint callback = tensorflow.keras.callbacks.ModelCheckpoint(
    filepath=checkpoint dir,
    save weights only=True,
   monitor='val accuracy',
   mode='max',
   save best only=True)
# Specify training options
BATCH SIZE = 12
NUM EPOCHS = 50#Augment training data
train generator = get train augmented(trainX=trainX, trainY=trainY,
BATCH SIZE=BATCH SIZE)
#Train and save the network
history = model.fit generator(train generator,
steps per epoch=len(trainX)/(BATCH SIZE*2), epochs=NUM EPOCHS,
callbacks=[model checkpoint callback])
#Plot progress # this plots over the view of the data
plt.findure(2)plt.plot(history.history['sparse categorical accuracy'])
plt.title('Model accuracy')
plt.ylabel('accuracy')
plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.savefig('Training plot.png')
plt.show()#Save final fully trained model as a .h5 file
model.save("C:/Users/John/20211118_Python_biostudies/Python/2D_UNET_PYTHON/2D_Pe
yersPatch/3_Saved_models/my_h5_model.h5")
checkpoint filepath name h5 = checkpoint filepath + Name file+dt string+'.h5'
model.save(checkpoint filepath name h5)
```

```
% PYTHON SCRIPT: TEST 2D UNET
% All code, image-data and screen-cast tutorial videos available for download at
% the Biostudies database under accession number S-BSST742
# -*- coding: utf-8 -*-
Created on Tue Sep 21 02:46:52 2021
@author: Paul
#Import all required modules
import skimage
from skimage import data
from skimage.filters import threshold otsu
from tensorflow.keras.preprocessing.image import ImageDataGenerator
import sklearn.feature extraction
from sklearn.datasets import load sample image
from sklearn. feature extraction import image
import matplotlib.cm as cm
import matplotlib.pyplot as plt
import matplotlib.cbook as cbook
from matplotlib.path import Path
from matplotlib.patches import PathPatch
import PIL
import numpy as np
import cv2
import tensorflow
from tensorflow.keras.models import *
from tensorflow.keras.layers import *
from tensorflow.keras.optimizers import *
from tensorflow.keras.callbacks import ModelCheckpoint, LearningRateScheduler
from tensorflow.keras import backend as keras
from tensorflow.keras.preprocessing.image import ImageDataGenerator
import sklearn.feature extraction
from sklearn.datasets import load sample image
from sklearn. feature extraction import image
from datetime import datetime
from keras.utils import to categorical
from tensorflow.python.keras.optimizers import *
import skimage.io
#%% Load the reflectance data from the unseen test image
TEST DATA =
skimage.io.imread('C:/Users/John/20211118 Python biostudies/Python/2D UNET PYTHO
N/2D PeyersPatch/1 ImageData/TEST IMAGE.tif');
Test data = TEST DATA[0,0,:,:,2]# Load the mask for the lymphoid tissue region
Mask = TEST DATA[0,0,:,:,3]
thresh = threshold otsu(Test data)
Mask = Mask > threshMask = Mask*1Mask = np.util6(Mask)# Rescale the test data [0 1]
# Mask the rescaled data
Test data = np.multiply(Test data, Mask);
Test data = np.double(Test data);
```
```
Test data norm holder = np{\text{-}zeros}(11247, 7610), np.double)
Test data rescaled = cv2.normalize(Test data, Test data norm holder, 1.0, 0.0,
cv2.NORM MINMAX)
#88# Define model for testing
def unet(pretrained weights = None, input size=(256,256,1), n class=3):
   inputs = tensorflow.keras.Input(shape=input size)
   conv1 = Conv2D(64, 3, activation = 'relu', dilation rate=2,padding = 'same',\text{kernel initializer} = \text{he normal} (inputs)
   conv1 = BatchNormalization() (conv1)conv1 = Conv2D(64, 3, activation = 'relu', dilation rate=2,padding = 'same',kernel initializer = 'he normal')(conv1)
   conv1 = BatchNormalization() (conv1)pool1 = MaxPooling2D(pool size=(2, 2))(conv1)conv2 = Conv2D(128, 3, activation = 'relu', dilation rate=2,padding ='same', kernel initializer = 'he normal')(pooll)
   conv2 = BatchNormalization() (conv2)conv2 = Conv2D(128, 3, activation = 'relu', dilation rate=2, padding ='same', kernel initializer = 'he normal')(conv2)
   conv2 = BatchNormalization() (conv2)pool2 = MaxPooling2D(pool size=(2, 2))(conv2)conv3 = Conv2D(256, 3, activation = 'relu', padding = 'same',kernel_initializer = 'he_normal')(pool2)
   conv3 = BatchNormalization() (conv3)conv3 = Conv2D(256, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(conv3)
   conv3 = BatchNormalization() (conv3)pool3 = MaxPooling2D(pool_size=(2, 2))(conv3)conv4 = Conv2D(512, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal' (pool3)conv4 = BatchNormalization() (conv4)conv4 = Conv2D(512, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(conv4)
   conv4 = BatchNormalization() (conv4)drop4 = Dropout(0.5)(conv4, training=True)pool4 = MaxPooling2D(pool size=(2, 2))(drop4)conv5 = Conv2D(1024, 3, activation = 'relu', padding = 'same',\text{kernel initialization} = 'he normal') (pool4)conv5 = BatchNormalization() (conv5)conv5 = Conv2D(1024, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(conv5)
   conv5 = BatchNormalization() (conv5)drop5 = Dropout(0.5)(conv5, training=True)up6 = Conv2D(512, 2, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(UpSampling2D(size = (2,2))(drop5))
   merge6 = concatenate(\frac{1}{\text{drop4},\text{up6}}, axis = 3)
   conv6 = Conv2D(512, 3, activation = 'relu', padding = 'same',\text{kernel initializer} = \text{ 'he normal'} (\text{merge6})conv6 = Conv2D(512, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(conv6)
```

```
up7 = Conv2D(256, 2, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(UpSampling2D(size = (2,2))(conv6))
   merge7 = concatenate(\overline{[{\text{conv3}, \text{up7}}]}, axis = 3)
   conv7 = Conv2D(256, 3, activation = 'relu', padding = 'same',\text{kernel } initializer = 'he normal') (\text{merge7})conv7 = Conv2D(256, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(conv7)
   up8 = Conv2D(128, 2, activation = 'relu', padding = 'same',kernel initializer = 'he_normal')(UpSampling2D(size = (2,2))(conv7))
   merge8 = concatenate([conv2, upp8], axis = 3)
   conv8 = Conv2D(128, 3, activation = 'relu', padding = 'same',\text{kernel } initializer = 'he normal') (merge8)conv8 = Conv2D(128, 3, activation = 'relu', padding = 'same',\text{kernel initialization} = \text{ 'he normal ')} (\text{conv8})upp = Conv2D(64, 2, activation = 'relu', padding = 'same',kernel initializer = 'he_normal')(UpSampling2D(size = (2,2))(conv8))
   merge9 = concatenate([conv1, up9], axis = 3)
   conv9 = Conv2D(64, 3, activation = 'relu', padding = 'same',\text{kernel initialization} = 'he normal') (\text{merge9})conv9 = Conv2D(64, 3, activation = 'relu', padding = 'same',kernel initializer = 'he normal')(conv9)
   conv10 = Conv2D(n class, 1, activation = 'softmax') (conv9)model = tensorflow.keras.Model(inputs = inputs, outputs = conv10)model.compile(optimizer = Adam(lr = 0.0001), loss ='sparse categorical crossentropy', metrics = ['sparse categorical accuracy'])
   if(pretrained weights):
     model=keras.models.load model(pretrained weights)
   return model
#88# Patch the reflectance data through the network
# Set the patch sizes to be passed to the net
patchSize = [256, 256]Test data rescaled =
np.asarray(Test data rescaled).reshape((Test data rescaled.shape[0],
Test data rescaled.shape[1], 1))
# Seqment blockwise then reassemble in full
# Define image dimensions
[height, width, nChannel] = np.shape (Test data rescaled)
```

```
patch = np{\text{-}zeros([patchSize[0], patchSize[1]},nChannel], dtype=Test data rescaled.dtype);
# Pad image to have dimensions as multiples of patchSize
padsize = np.empty([1, 2])padSize[0,0] = patchSize[0] - np.remainder(height, patchSize[0]);padSize[0,1] = patchSize[1] - np.remainder(width, patchSize[1]);Starting shape = np.shape(Test data rescaled)
a1 = Starting\_shape[0]+padsize[0,0]a2 = Starting shape[1]+padsize[0,1]im pad = np{\text{-}zeros([int(a1),int(a2)]})im pad[:Test data rescaled.shape[0],:Test data rescaled.shape[1]] =
Test data rescaled[:, :, 0]im pad = np.asarray(im pad).reshape((im pad.shape[0], im pad.shape[1],1))
[height pad, width pad, nChannel pad] = np.shape(im pad);
# Preallocate some matrices to receive the network outputs
out Uncertainty Scores = np{\text{-}zeros([np{\text{-}}shape(im\ pad)[0], np{\text{-}}shape(im\ pad)[1]],
'double');out Pmap cat1 = np \cdot zeros([np \cdot shape(im pad)[0], np \cdot shape(im pad)[1]], 'double');out Pmap cat2 = np.zeros([np.shape(im pad)[0], np.shape(im pad)[1]], 'double');
out Pmap cat3 = np.zeros([np.shape(im pad)[0], np.shape(im pad)[1]], 'double');
# Load a pretrained network
pretrained model = unet()pretrained_model.load_weights('C:/Users/John/20211118_Python_biostudies/Python/2
D UNET PYTHON/2D PeyersPatch/3 Saved models/my h5 model fully trained.h5')
# Loop through blocks of 'patchSize'
for loop in range(1, int(height_pad), int(patchSize[0])):
    print(loop)
    for j in range(1,int(width pad), int(patchSize[1])):
        for p in range(1, (nChannel+1)):
            PP3 = np.empty([1, 256, 256, 1])
            im pad touse =im pad[(loop-1):((loop-1)+patchSize[0]),(j-1):((j-
1) + (patchSize[1]))]
            patch[:, :, 0] = np.squeeze(im pad house, axis=None)PP3[0, : , : , : ] =patch
            # deploy net
            predictions = pretrained model.predict(PP3)scores = np.max(predictions, axis=3)predictions.argmax(axis=3)
            out Uncertainty_Scores[(loop-1):(loop+patchSize[0]-1), (j-
1):(j+patchSize[1]-1)] = scores;
            out Pmap catl[(loop-1):(loop+patchSize[0]-1), (j-1):(j+patchSize[1]-
1)] = predictions[0,:,:,0];
            out Pmap cat2[(loop-1):(loop+patchSize[0]-1), (j-1):(j+patchSize[1]-
1)] = predictions[0, :, :, 1];out Pmap cat3[(loop-1):(loop+patchSize[0]-1), (j-1):(j+patchSize[1]-
1)] = predictions[0,:,:,2];
```

```
out Uncertainty Scores = out Uncertainty Scores[0:height, 0:width];
out Pmap cat1 = out Pmap cat1[0:height, 0:width];
out Pmap cat2 = out Pmap cat2[0:height, 0:width];
out Pmap cat3 = out Pmap cat3[0:height, 0:width];
image to plot = np{\text{-}zeros}( (11247, 7610, 3))image to plot[:,:,0] = out Pmap catl
image to plot[:,:,1] = out Pmap cat2
image to plot[:,:,2] = out Pmap cat3
#%% visualise network outputs
fig, (ax1, ax2, ax3, ax4) = plt.subplots(1, 4, sharey=True)fig.set size inches(14, 12)
im = ax1.imshow(out Pmap cat1)ax1.title.set text('Background/Other')
im = ax2.imshow(out) Pmap cat2)
ax2.title.set text('LF-Actin')
im = ax3.imshow(out) Pmap cat3)
ax3.title.set text('LF-Nuclei')
im = ax4.inshow(out Uncertainty Scores)ax4.title.set_text('Uncertainty')
plt.savefig('Predictions.png')
#%% Map to 16-bit and save for loading into CellProfiler
# Background/other
data norm holder = np{\text{-}zeros}(11247, 7610), np.uint16)
uil6 PMAP cat1 xy = cv2.normalize(out Pmap cat1, data norm holder, 65535.0,
0.0, cv2.NORM MINMAX)
imq data2 = (uil6 PMAP cat1 xy).astype(dtype=np.uint16)rawtiff=PIL.Image.fromarray(img data2)
rawtiff.save('Ch 7 Im 001'+'.tiff')
# LF-Actin
data norm holder = np{\cdot}zeros((11247, 7610), np{\cdot}uint16)uil6 PMAP cat2 xy = cv2.normalize(out) Pmap cat2, data norm holder, 65535.0,
0.0, cv2. NORM MINMAX)
img data2 = (ui16 PMAP cat2 xy).astype(dtype=np.uint16)
rawtiff=PIL.Image.fromarray(img data2)
rawtiff.save('Ch 6 Im 001'+'.tiff')
# LF-Nuclei
data norm holder = np{\cdot}zeros((11247, 7610), np{\cdot}uint16)uil6 PMAP cat3 xy = cv2.normalize(out Pmap cat3, data norm holder, 65535.0,
0.0, cv2. NORM MINMAX)
img data2 = (uil6 PMAP cat3 xy).astype(dtype=np.uint16)rawtiff=PIL.Image.fromarray(img data2)
rawtiff.save('Ch 5 Im 001'+'.tiff')
```
% PYTHON SCRIPT: TRAIN 3D UNET % All code, image-data and screen-cast tutorial videos available for download at % the Biostudies database under accession number S-BSST742 $#$ -*- coding: utf-8 -*-Created on Mon Jun 14 15:21:44 2021 @author: Paul from PIL import Image import javabridge import bioformats javabridge.start vm(class path=bioformats.JARS) import cv2 import matplotlib.pyplot as plt import matplotlib.pyplot as plt import skimage from skimage import data from skimage.filters import threshold otsu import os import numpy as np import skimage.transform as trans import numpy as np import tensorflow from tensorflow.keras.models import * from tensorflow.keras.layers import * from tensorflow.keras.optimizers import * from tensorflow.keras.callbacks import ModelCheckpoint, LearningRateScheduler from tensorflow.keras import backend as keras from tensorflow.keras.preprocessing.image import ImageDataGenerator import sklearn.feature extraction from sklearn.datasets import load sample image from sklearn. feature extraction import image from datetime import datetime from keras.utils import to categorical from tensorflow.python.keras.optimizers import * import random import matplotlib.pyplot as plt from mpl toolkits.mplot3d.art3d import Poly3DCollection import numpy as np from skimage import exposure, io, util #%% Specify directory containing training data Training data directory = 'C:/Users/John/20211118 Python biostudies/Python/3D UNET PYTHON/3D UNET PYTHON/1 ImageData/TRAIN/DATA/' # Specify channel number in training data that contains reflectance information RL training directory = 3 ; # Specify directory containing training labels Training labels path = 'C:/Users/John/20211118 Python biostudies/Python/3D UNET PYTHON/3D UNET PYTHON/1 ImageData/TRAIN/LABELS/';

```
# COMMIT TRAINING DATA TO DIRECTORY rescaled [0 1] IN MAT FORMAT
MYDTR
='C:/Users/John/20211118 Python biostudies/Python/3D UNET PYTHON/3D UNET PYTHON/
1 ImageData/TRAIN/LABELS/mat training data/'
CHECK FOLDER = os.path.isdir(MYDIR)# If folder doesn't exist, then create it.
if not CHECK FOLDER:
    os.makedirs(MYDIR)
Training labels holder =
skimage.io.imread('C:/Users/John/20211118 Python biostudies/Python/3D UNET PYTHO
N/3D UNET PYTHON/1 ImageData/TRAIN/LABELS/LABELS 001.tif') ;
Training labels = np.where(Training labels holder == 3, 0, ...)Training labels holder)
#88for i in range(0,2):
    loop = i+1counter = '00'+str(loop)# find metadata describing file
    TOTAL path = Training data directory+'TRAIN '+counter+'.tif'
    reader = bioformats. ImageReader (TOTAL path)
    NUMBERIMAGES = reader.rdr.getSeriesCount(TOTAL path)
    number of channels = reader.rdr.getSizeC(TOTAL path)
    Xlength = reader.rdr.getSizeX(TOTAL path)
    Ylength = reader.rdr.getSizeY(TOTAL path)stackSizeZ = reader.rdr.getSizeZ(TOTAL path)# number of Z slices
    channel zimage = np.zeros((Xlength, Ylength, stackSizeZ))
    # Load reflectance information
    for zplane in range(1, stackSizeZ+1):
        channel zimage[:,:,(zplane-1)] = bioformats.load image(TOTAL path,z =
(zplane-1), c= (RL training directory-1))
    IM DATA = channel zimage
    IM DATA = np.double(IM DATA);DIM = IM DATA.shapeIM DATA norm holder = np{\text{-}zeros} (DIM[0], DIM[1], DIM[2]), np.double)
    IM DATA norm = cv2.normalize(IM DATA, IM DATA norm holder, 1.0, 0.0,cv2.NORM MINMAX)
    pw = os.getcwd()FILENAME = pw+'\lceil \n\rangle training data\\'+'TRAIN DATA '+counter
    FOLDER CHECK = pw+'\l\n\psi training data\\'
    CHECK FOLDER = os.path.isdir(FOLDER CHECK)if not CHECK FOLDER:
        os.makedirs(FOLDER_CHECK)
    np.save(FILENAME, IM DATA norm)
```

```
pw = os.getcwd()#%% COMMIT TRAINING LABELS TO DIRECTORY IN MAT FORMAT
FOLDER NAME = pw+'\ln py training labels\\'
CHECK FOLDER2 = os.path.isdir(FOLDER NAME)if not CHECK FOLDER2:
    os.\mathtt{makedirs} (FOLDER NAME)
for i in range(0,2):
    loop = i +1counter = '00'+str(loop)label zimage = [];
    label zimage = np.zeros((Xlength, Ylength, stackSizeZ))
    # load label information
    for zplane in range(1, stackSizeZ+1):
        TOTAL path = Training labels path+'LABELS '+counter+'.tif'
        iplane = bioformats.load image(TOTAL path, z=(zplane-1), c=0, rescale =
False )
        label zimage[:,:,(zplane-1)] = iplane
    IM LABELS = np.double(label zimage);DIM = IM LABELS.shapeIM LABELS norm holder = np{\text{-}zeros((DIM[0],DIM[1],DIM[2])}, np.double)
    IM LABELS norm holder[:,:,:] = label zimage[:,:,:]
    pw = os.getcwd()FILENAME = pw+'\lceil \n\rangle_training_labels\lceil +'\n\rceil_{LABELS}'+counterFOLDER_CHECK = pw+'\l\nupy_training_labels\l'CHECK FOLDER = os.path.isdir(FOLDER CHECK)if not CHECK FOLDER:
        os.makedirs(FOLDER CHECK)
    np.save(FILENAME, IM_LABELS_norm_holder)
#88NUMBER batch = 1de<sub>1</sub>channel zimage, IM LABELS, IM DATA, label zimage
# Prepare to extract patches
patchPerImage = 375;xrand = random.shape(range(0, 959), patchPerImage)yrand = random.shape(range(0, 959), patchPerImage)zrand = np.random-choice(78, patchPerImage, replace=True)# Define random patch extraction and augmentarion of patches
def get_train_patched(xrand, yrand, zrand, BATCH_SIZE, batch_number =
NUMBER batch, trainXm=IM DATA norm, trainYm=IM LABELS norm holder):
    patched data image = np{\cdot}zeros( (BATCH SIZE, 64, 64, 32))
    patched data labels = np{\cdot}zeros( (BATCH SIZE, 64, 64, 32))
    for i in range(0, BATCH SIZE):
        val = (i + batch number)-1;
        patched data image[i, :, :, :] =
trainXm[(xrand[val]):(xrand[val]+64),(yrand[val]):(yrand[val]+64),(zrand[val]):(
zrand[val]+32) ];
```

```
patched data labels[i, : , : , :] =
trainYm[(xrand[val]):(xrand[val]+64),(yrand[val]):(yrand[val]+64),(zrand[val]):(
zrand[val] + 32)]:
   return patched data image, patched data labels
def get train augmented(trainXm, trainYm, BATCH SIZE, batch number =
NUMBER batch):
   for i in range(0, BATCH SIZE):
       rand number = random.sample(range(BATCH SIZE), 1)
       my arr = (np.rot90, np.flipud, np.fliplrif int(rand number[0])<3:
           trainXm[i,:,:,:] = my arr[int(rand number[0])](trainXm[i,:,:,:])
           train Ym[i, i, j, j] = my arr(int(rand number[0])) (trainYm[i, i, j, j])elif int(rand number[0]) ==3:
           trainXm[i,:,:,:] = np.fliplr(trainXm[i,:,:,:])trainYm[i,:,:,:] = np.flipt(trainYm[i,:,:,:])trainXm[i,:,:,:] = np.rot90(trainXm[i,:,:,:])trainYm[i,:,:,:] = np.rot90(trainYm[i,:,:,:])else:
           trainXm[i,:,:,:] = trainXm[i,:,:,:]trainYm[i,:,:,:] = trainYm[i,:,:,:]return trainXm, trainYm
#88# CREATE THE 3D UNET
# input layer 64x64x32x1
# encoder depth 4
# 32 filters at the level of the first encoder
def unet3(pretrained weights = None, input size= (64, 64, 32, 1), n class=4):
   inputs = tensorflow.keras.Input(shape=input size)
   conv1 = Conv3D(32, kernel size=(3, 3, 3), dilation rate=2,padding = 'same',\text{kernel } \text{initializer} = \text{ 'he normal' } (\text{inputs})conv1 = BatchNormalization() (conv1)conv1 = \text{Activation('relu')(conv1)}conv1 = Conv3D(64, Kernel_size=(3, 3, 3), dilation_rate=2,padding = 'same',kernel initializer = 'he normal')(conv1)
   conv1 = BatchNormalization() (conv1)up1 = Activation('relu')(conv1)
   pool1 = MaxPooling3D(pool_size=(2,2,2), strikes = (2,2,2))(up1)conv2 = Conv3D(64, kernel size=(3, 3, 3), dilation rate=2,padding = 'same',\text{kernel } \text{initializer} = \text{ 'he normal ' } (\text{pool1})conv2 = BatchNormalization() (conv2)conv2 = \text{Activation('relu')(conv2)}conv2 = Conv3D(128, Kernel size=(3, 3, 3), dilation_rate=2,padding = 'same',kernel_initalizer = 'he_normal') (up1)conv2 = BatchNormalization() (conv2)up2 = Activation('relu')(conv2)
   pool2 = MaxPooling3D(pool size=(2,2,2), strikes=(2,2,2)) (up2)
```

```
conv3 = Conv3D(128, Kernel_size=(3, 3, 3), dilation_rate=2,padding = 'same',kernel initializer = 'he normal')(pool2)
    conv3 = BatchNormalization() (conv3)conv3 = Activation('relu')(conv3)conv3 = Conv3D(256, kernel size=(3, 3, 3), dilation rate=2,padding = 'same',kernel initializer = 'he normal')(conv3)
    conv3 = BatchNormalization() (conv3)up3 = Activation('relu')(conv3)
    pool3 = MaxPooling3D(pool_size=(2,2,2), strikes = (2,2,2))(up3)conv4 = Conv3D(256, kernel size=(3, 3, 3), dilation rate=2,padding ='same', kernel initializer = 'he normal')(pool3)
    conv4 = BatchNormalization() (conv4)conv4 = Activation('relu')(conv4)conv4 = Conv3D(512, kernel size=(3, 3, 3), dilation rate=2,padding ='same', kernel initializer = 'he normal')(conv4)
    conv4 = BatchNormalization() (conv4)up4 = Activation('relu')(conv4)
    pool4 = MaxPooling3D(pool size=(2,2,2), strikes=(2,2,2)) (up4)conv5 = Conv3D(512, kernel size=(3, 3, 3), dilation rate=2,padding ='same', kernel initializer = 'he normal')(pool4)
    conv5 = BatchNormalization() (conv5)conv5 = \text{Activation('relu')(conv5)}conv5 = Conv3D(1024, \text{kernel size}=(3, 3, 3), \text{dilation_rate}=2, \text{padding} ='same', kernel initializer = 'he normal')(conv5)
    conv5 = BatchNormalization() (conv5)conv5 = \text{Activation('relu')(conv5)}drop5 = Conv3DTranspose(1024, kernel size=(2, 2, 2), strikes=(2, 2, 2),activation = 'relu', dilation rate=2, padding = 'same', kernel initializer =
'he normal')(conv5)
    merge6 = concatenate([drop5, up4], axis = 4)
    conv6 = Conv3D(512, kernel size=(3, 3, 3), dilation rate=2,padding ='same', kernel initializer = 'he normal')(merge6)
    conv6 = BatchNormalization() (conv6)conv6 = Activation('relu')(conv6)conv6 = Conv3D(512, kernal size=(3, 3, 3), dilation rate=2,padding ='same', kernel initializer = \overline{he} normal')(conv6)
    conv6 = BatchNormalization() (conv6)conv6 = Activation('relu')(conv6)drop6 = Conv3DTranspose(512, kernel_size=(2, 2, 2), strikes=(2, 2, 2),activation = 'relu', dilation rate=2, padding = 'same', kernel initializer =
'he normal')(conv6)
    merge7 = concatenate(\frac{1}{\pi}grop6, up3], axis = 4)
    conv7 = Conv3D(256, Kernel size=(3, 3, 3), dilation rate=2, padding = 'same',kernel initializer = 'he normal')(merge7)
    conv7 = BatchNormalization() (conv7)conv7 = Activation('relu')(conv7)conv7 = Conv3D(256, Kernel size=(3, 3, 3), dilation rate=2,padding = 'same',\text{kernel}_\text{initializer} = \text{ 'he}_\text{normal} (conv7)
    conv7 = BatchNormalization() (conv7)conv7 = Activation('relu')(conv7)drop7 = Conv3DTranspose(256, Kernel_size=(2, 2, 2), strikes=(2, 2, 2),activation = 'relu', dilation rate=2, padding = 'same', kernel initializer =
'he_normal')(conv7)
    merge8 = concatenate([drop7,up2], axis = 4)
    conv8 = Conv3D(128, kernal size=(3, 3, 3), dilation rate=2,padding ='same', kernel initializer = 'he normal')(merge8)
```

```
conv8 = BatchNormalization() (conv8)conv8 = \text{Activation('relu')(conv8)}conv8 = Conv3D(128, kernal size=(3, 3, 3), dilation rate=2,padding ='same', kernel initializer = 'he normal')(conv8)
    conv8 = BatchNormalization() (conv8)conv8 = \text{Activation('relu')(conv8)}drop8 = Conv3DTranspose(128, Kernel size=(2, 2, 2), strikes=(2, 2, 2),activation = 'relu', dilation rate=2, padding = 'same', kernel initializer =
'he_normal')(conv8)
    conv8 = BatchNormalization() (drop8)conv8 = \text{Activation('relu')(conv8)}drop8 = Conv3DTranspose(128, Kernel size=(2, 2, 2), strikes=(2, 2, 2),activation = 'relu', dilation rate=2, padding = 'same', kernel initializer =
'he normal')(conv7)
    merge9 = concatenate([drop8, up1], axis = 4)
    conv9 = Conv3D(64, kernel size=(3, 3, 3), dilation rate=2,padding = 'same',\text{kernel initialization} = 'he normal') (\text{merge9})conv9 = BatchNormalization() (conv9)conv9 = Activation('relu')(conv9)conv9 = Conv3D(64, kernel size=(3, 3, 3), dilation rate=2, padding = 'same',kernel initializer = 'he normal')(conv9)
    conv9 = BatchNormalization() (conv9)conv9 = Activation('relu')(conv9)conv9 = Conv3D(n class, Kernel size=(1, 1, 1), activation = 'softmax')(conv9)model = tensorflow.keras.Model(inputs = inputs, outputs = conv9)model.compile(optimizer = Adam(lr = 0.0005), loss ='sparse_categorical_crossentropy', metrics = ['sparse_categorical_accuracy'])
    if(pretrained weights):
     model=keras.models.load model(pretrained weights)
    return model
#%% Specify location to save the network
checkpoint filepath =
'C:/Users/John/20211118 Python biostudies/Python/3D UNET PYTHON/3D UNET PYTHON/3
Saved models/'
now = datetime.now()dt string = now.strftime("%d/%m/%Y%H:%M:%S")
NAME =dt string
Name file = 'PeyersPatchBiostudies '
checkpoint_filepath_name = checkpoint_filepath + Name_file+dt_string
checkpoint dir = os.path.dirname(checkpoint filepath name)
model checkpoint callback = tensorflow.keras.callbacks.ModelCheckpoint(
    filepath=checkpoint dir,
    save weights only=True,
    monitor='val accuracy',
    mode='max'save best only=True)
#Specify training options
```

```
BATCH SIZE = 8NUM EPOCHS = 50batchPerImage = 375:steps = np.floor(patchPerImage/8);NUMBER batch = 1;
start = 0;
finish = 8:storeX = np{\textcdot}zeros((375,64,64,32,1))
storeY = np{\cdot}zeros((375, 64, 64, 32, 1))#Extract patches
for i in range(1, int(t)(steps)):
    [patched data image, patched data labels]=get train patched(xrand, yrand,
zrand, BATCH SIZE, batch number = NUMBER batch, trainXm=IM DATA norm,
trainYm=IM LABELS norm holder)
    [trainXmgg, trainYmgg] =get train augmented (BATCH SIZE=8, trainXm=patched data image,
trainYm=patched data labels, batch number = NUMBER batch)
    trainYmgg = trainYmgg.reshape((8, 64, 64, 32, 1))
    trainXmqq = trainXmqq.reshape((8, 64, 64, 32, 1))
    trainXmgg = trainXmgg.astype('float32')
    trainYmgq = trainYmgq.astyle('float32')storeX[start:finish,:,:,:,:] = trainXmgqstoreY[start: finish, : , : , : , :] = trainYmggstart = finishfinish = start+8NUMBER batch = NUMBER batch+1
[patched data image, patched data labels]=get train patched(xrand, yrand, zrand,
BATCH SIZE=(patchPerImage-finish), batch number = NUMBER batch,
trainXm=IM DATA norm, trainYm=IM LABELS norm holder)
[trainXmqq, trainYmqq] = qet train auqmented(BATCH SIZE=(patchPerImaqe-
finish), trainXm=patched data image, trainYm=patched data labels, batch number =
NUMBER batch)
trainYmqq = trainYmqq.reshape((patchPerImaqe-finish, 64, 64, 32, 1))
trainXmgg = trainXmgg.readispe((patchPerImage-finish, 64, 64, 32, 1))trainXmgg = trainXmgg.astype('float32')
trainYmgg = trainYmgg.astype('float32')
\texttt{storeX}[\texttt{finish:patchPerImage}, :, :, :, :] = \texttt{trainX}storeY[finish:patchPerImage, : , : , : , : ] = trainYmggmodel = unet3(pretrained weights = None, input size =(64, 64, 32, 1), n class=4)#change to 3
```

```
#%% Train the model
history = model.fit(storeX,
    storeY,
    batch size = BATCH SIZE,
    epochs = NUM EPOCHS, callbacks=[model checkpoint callback])plt.plot(history.history['sparse categorical accuracy'])
plt.title('Model accuracy')
plt.ylabel('accuracy')<br>plt.xlabel('epoch')
plt.legend(['train', 'test'], loc='upper left')
plt.savefig('Training_plot.png')
plt.show()
```

```
model.save("C:/Users/John/20211118 Python biostudies/Python/3D UNET PYTHON/3D UN
ET PYTHON/3 Saved models/my h53D model.h5")
```
% PYTHON SCRIPT: TEST 3D UNET % All code, image-data and screen-cast tutorial videos available for download at % the Biostudies database under accession number S-BSST742 $#$ -*- coding: utf-8 -*-Created on Mon Sep 20 16:37:00 2021 @author: Paul from PIL import Image import javabridge import bioformats javabridge.start vm(class path=bioformats.JARS) import cv2 import matplotlib.pyplot as plt import matplotlib.pyplot as plt import skimage from skimage import data from skimage.filters import threshold otsu import os import numpy as np import skimage.transform as trans import numpy as np import tensorflow from tensorflow.keras.models import * from tensorflow.keras.layers import * from tensorflow.keras.optimizers import * from tensorflow.keras.callbacks import ModelCheckpoint, LearningRateScheduler from tensorflow.keras import backend as keras from tensorflow.keras.preprocessing.image import ImageDataGenerator import sklearn.feature extraction from sklearn.datasets import load sample image from sklearn. feature extraction import image from datetime import datetime from keras.utils import to categorical from tensorflow.python.keras.optimizers import * import random import matplotlib.pyplot as plt from mpl toolkits.mplot3d.art3d import Poly3DCollection import numpy as np from skimage import exposure, io, util from skimage import data from tensorflow.keras.preprocessing.image import ImageDataGenerator import sklearn.feature extraction from sklearn.datasets import load sample image from sklearn. feature extraction import image import matplotlib.cm as cm import matplotlib.cbook as cbook from matplotlib.path import Path from matplotlib.patches import PathPatch import math import json import numpy as np import PIL import imageio

```
#%% Specify directory containing test data
Test data directory =
'C:/Users/John/20211118 Python biostudies/Python/3D UNET PYTHON/3D UNET PYTHON/1
ImageData/TEST/'
# Specify channel number in test data that contains reflectance information
RL channel number = 2;
#COMMIT REFLECTANCE TEST DATA TO DIRECTORY RESCALED [0 1] IN MAT FORMAT
MYDIR
='C:/Users/John/20211118 Python biostudies/Python/3D UNET PYTHON/3D UNET PYTHON/
4 TEST Unet/npy test data/'
CHECK FOLDER = os.path.isdir(MYDIR)# If folder doesn't exist, then create it.
if not CHECK FOLDER:
    os.makedirs(MYDIR)
for i in range(0,1):
    loop = i+1counter = '00'+str(loop)TOTAL path = Test data directory+'TEST '+counter+'.tif'
    # find metadata describing file
    reader = bioformats. ImageReader (TOTAL path)
    NUMBERIMAGES = reader.rdr.getSeriesCount(TOTAL path)
    number of channels = reader.rdr.getSizeC(TOTAL path)
    Xlenqth = reader.rdr.qetsizeX(TOTAL path)Ylength = reader.rdr.getSizeY(TOTAL path)
    stackSizeZ = reader.rdr.getSizeZ(TOTAL path)
    channel zimage = np{\text{-}zeros(} (Xlength, Ylength, stackSizeZ))
    # Load reflectance information
    for zplane in range(1, stackSizeZ+1):
        channel zimage[:,:,(zplane-1)] = bioformats.load image(TOTAL path,z =
(zplane-1), c= (RL channel number-1))
    IM_DATA = channel_zimageIM DATA = np.double(IM DATA);DIM = IM DATA.shapeIM DATA norm holder = np \cdot zeros((DIM[0],DIM[1],DIM[2]), np \cdot double)IM DATA norm = cv2.normalize(IM DATA, IM DATA norm holder, 1.0, 0.0,
cv2.NORM MINMAX)
    pw = os.getcwd()FILENAME = pw+'\\npy_test_data\\'+'TEST_DATA_'+counter
    FOLDER CHECK = pw+'\ln py test data\\'
    CHECK FOLDER = os.path.isdir(FOLDER CHECK)if not CHECK FOLDER:
        os.makedirs(FOLDER CHECK)
    np.save(FILENAME, IM_DATA_norm)
```

```
#88
#Redefine network
def unet3(pretrained weights = None, input size= (64, 64, 32, 1), n class=4):
    inputs = tensorflow.keras.Input(shape=input size)
    conv1 = Conv3D(32, Kernel size=(3, 3, 3), dilation rate=2, padding = 'same',\text{kernel initialization} = 'he normal') (\text{inputs})conv1 = BatchNormalization() (conv1)conv1 = Activation('relu')(conv1)conv1 = Conv3D(64, Kernel size=(3, 3, 3), dilation_rate=2,padding = 'same',kernel initializer = 'he normal')(conv1)
    conv1 = BatchNormalization() (conv1)up1 = Activation('relu')(conv1)
    pool1 = MaxPooling3D(pool_size=(2,2,2), strikes = (2,2,2))(up1)conv2 = Conv3D(64, Kernel size=(3, 3, 3), dilation rate=2,padding = 'same',kernel initializer = 'he normal')(pool1)
    \overline{\text{conv2}} = BatchNormalization()(conv2)
    conv2 = Activation('relu')(conv2)conv2 = Conv3D(128, Kernel size=(3, 3, 3), dilation rate=2, padding = 'same',kernel initializer = 'he normal')(up1)
    conv2 = BatchNormalization() (conv2)up2 = Activation('relu')(conv2)
    pool2 = MaxPooling3D(pool size=(2,2,2), strikes=(2,2,2))(up2)conv3 = Conv3D(128, Kernel_size=(3, 3, 3), dilation rate=2,padding = 'same',\text{kernel}_\text{initializer} = \text{'he}_\text{normal} (pool2)
    conv3 = BatchNormalization() (conv3)conv3 = \text{Activation('relu')(conv3)}conv3 = Conv3D(256, Kernel size=(3, 3, 3), dilation rate=2, padding = 'same',kernel initializer = 'he normal')(conv3)
    conv3 = BatchNormalization() (conv3)up3 = Activation('relu')(conv3)
    pool3 = MaxPooling3D(pool size=(2,2,2), strikes=(2,2,2))(up3)conv4 = Conv3D(256, kernel size=(3, 3, 3), dilation_rate=2,padding ='same', kernel initializer = 'he normal')(pool3)
    conv4 = BatchNormalization() (conv4)conv4 = \text{Activation('relu')(conv4)}conv4 = Conv3D(512, kernel size=(3, 3, 3), dilation rate=2,padding ='same', kernel initializer = 'he normal')(conv4)
    conv4 = BatchNormalization() (conv4)up4 = Activation('relu')(conv4)
    pool4 = MaxPooling3D(pool_size=(2,2,2), strikes = (2,2,2))(up4)conv5 = Conv3D(512, Kernel_size=(3, 3, 3), dilation_rate=2,padding ='same', kernel initializer = 'he normal')(pool4)
    conv5 = BatchNormalization() (conv5)conv5 = \text{Activation('relu')(conv5)}conv5 = Conv3D(1024, Kernel_size=(3, 3, 3), dilation_rate=2,padding ='same', kernel initializer = 'he normal')(conv5)
    conv5 = BatchNormalization() (conv5)conv5 = \text{Activation('relu')(conv5)}drop5 = Conv3DTranspose(1024, kernel size=(2, 2, 2), strikes=(2, 2, 2),activation = 'relu', dilation_rate=2,padding = 'same', kernalinitializer ='he normal')(conv5)
    merge6 = concatenate([drop5, up4], axis = 4)
    conv6 = Conv3D(512, kernal size=(3, 3, 3), dilation rate=2,padding ='same', kernel initializer = 'he normal')(merge6)
    conv6 = BatchNormalization() (conv6)conv6 = Activation('relu')(conv6)conv6 = Conv3D(512, kernel size=(3, 3, 3), dilation rate=2,padding ='same', kernel initializer = 'he normal')(conv6)
```

```
conv6 = BatchNormalization() (conv6)conv6 = Activation('relu')(conv6)drop6 = Conv3DTranspose(512, kernel size=(2, 2, 2), strikes=(2, 2, 2),activation = 'relu', dilation rate=2, padding = 'same', kernel initializer =
'he normal')(conv6)
    merge7 = concatenate(\lceil \text{drop6}, \text{up3} \rceil, axis = 4)
    conv7 = Conv3D(256, Kernel size=(3, 3, 3), dilation rate=2, padding = 'same',kernel_initializer = 'he_normal')(merge7)
    conv7 = BatchNormalization() (conv7)conv7 = Activation('relu')(conv7)conv7 = Conv3D(256, Kernel_size=(3, 3, 3), dilation_rate=2,padding = 'same',kernel initializer = 'he normal')(conv7)
    conv7 = BatchNormalization() (conv7)conv7 = Activation('relu')(conv7)drop7 = Conv3DTranspose(256, Kernel size=(2, 2, 2), strikes=(2, 2, 2),activation = 'relu', dilation rate=2, padding = 'same', kernel initializer =
'he normal')(conv7)
    merge8 = concatenate(\frac{1}{\pi}grop7, up2], axis = 4)
    conv8 = Conv3D(128, \text{kernel size}=(3, 3, 3), \text{dilation rate}=2, \text{padding} ='same', kernel initializer = 'he normal')(merge8)
    conv8 = BatchNormalization() (conv8)conv8 = Activation('relu')(conv8)conv8 = Conv3D(128, kernel size=(3, 3, 3), dilation rate=2,padding ='same', kernel initializer = \overline{he} normal')(conv8)
    conv8 = BatchNormalization() (conv8)conv8 = \text{Activation('relu')(conv8)}drop8 = Conv3DTranspose(128, Kernel size=(2, 2, 2), strikes=(2, 2, 2),activation = 'relu', dilation rate=2, padding = 'same', kernel initializer =
'he_normal')(conv8)
    conv8 = BatchNormalization() (drop8)conv8 = \text{Activation('relu')(conv8)}drop8 = Conv3DTranspose(128, Kernel size=(2, 2, 2), strikes=(2, 2, 2),activation = 'relu', dilation rate=2, padding = 'same', kernel initializer =
'he normal')(conv7)
    merge9 = concatenate([drop8, up1], axis = 4)
    conv9 = Conv3D(64, Kernel_size=(3, 3, 3), dilation rate=2,padding = 'same',\text{kernel initialization} = 'he normal') (\text{merge9})conv9 = BatchNormalization() (conv9)conv9 = Activation('relu')(conv9)conv9 = Conv3D(64, \text{kernel\_size}=(3, 3, 3), \text{ dilation\_rate}=2, padding = 'same',kernel initializer = 'he normal')(conv9)
    conv9 = BatchNormalization() (conv9)conv9 = Activation('relu')(conv9)conv9 = Conv3D(n \text{ class}, \text{kernel size}=(1, 1, 1), \text{activation} = 'softmax') (conv9)
```

```
model = tensorflow.keras.Model(inputs = inputs, outputs = conv9)model.compile(optimizer = Adam(lr = 0.0005), loss ='sparse categorical crossentropy', metrics = ['sparse categorical accuracy'])
```

```
if(pretrained weights):
     model=keras.models.load model(pretrained weights)
   return model
#%% load the trained 3D Unet network
#model.load weights("C:/Users/John/20211118 Python biostudies/Python/3D UNET PYT
HON/3D UNET PYTHON/3 Saved models/my h53D model.h5")
pretrained model = unet3()pretrained model.load weights("C:/Users/John/20211118 Python biostudies/Python/3
D UNET PYTHON/3D UNET PYTHON/3 Saved models/my h53D model updated.h5")
#%% Patch the reflectance data through the network
# Set the patch sizes to be passed to the net
patchSize = [64, 64, 32]# Seqment blockwise then reassemble in full
# Define image dimensions
Shape overall = np.shape(IM DATA norm)height = Shape overall[0]
width = Shape overall[1]depth = Shape overall[2]if len(Shape overall) == 3:nChannel = 1else:
   nChannel = Shape overall[3]patch = np{\text{-}zeros([patchSize[0],patchSize[1],patchSize[2],}nChannel], dtype=IM DATA norm.dtype);
number_of_height_patches = math.ceil(height/patchSize[0]);
number of width patches = math.ceil(width/patchSize[1]);
number of depth patches = math.ceil(depth/patchSize[2]);
#Pad image to have dimensions as multiples of patchSize
height pad = number of height patches*patchSize[0];
width pad = number of width patches*patchSize[1];
depth_pad = number_of_depth_patches*patchSize[2];
# Amount to pad different dimensions of image
padSize = np.empty([1, 3])# Pad the image by correct amounts
padsize[0,0] = height pad;padsize[0,1] = width_pad;padSize[0,2] = depth pad;Starting shape = np.shape(IM DATA norm)
a1 = padSize[0,0]a2 = padSize[0,1]a3 = padSize[0,2]im pad = np{\text{-}zeros}([int(a1),int(a2),int(a3)])im pad[:IM DATA norm.shape[0],:IM DATA norm.shape[1],:IM DATA norm.shape[2]] =
IM DATA norm[:, :, :]
```

```
im pad = np.asarray(im pad).reshape((im pad.shape[0],
im pad.shape[1], im pad.shape[2], 1))
[height pad, width pad, depth pad, nChannel pad] = np.shape(im pad);
#Preallocate some matrices to catch the probability maps
out Uncertainty Scores = np.zeros([height pad, width pad, depth pad], 'double');
out scores from network all classes = np.zeros([height pad, width pad,
depth pad, 4], \sqrt{3} double');
#Loop through blocks of 'patchSize'
for loop height in range(1, number of height patches+1):
    for loop width in range(1, number of width patches+1):
        for loop depth in range(1, number of depth patches+1):
            PP3 = np.empty([1, 64, 64, 32, 1])
            start height position=(loop height-1)*patchSize[0];
            end height position=loop height*patchSize[0];
            start width position=(loop width-1)*patchSize[1];
            end width position=loop width*patchSize[1];
            start depth position=(loop depth-1)*patchSize[2];
            end depth position=loop depth*patchSize[2];
patch to deploy=im pad[start height position:end height position, start width pos
ition: end width position, start depth position: end depth position, : );
            PP3[0,:,:,:]=patch to deploy
            # deploy net
            predictions = pretrained model.predict(PP3)
            scores = np.max(predictions, axis=4)predictions.argmax(axis=3)
out Uncertainty Scores[start height position:end height position, start width pos
ition: end width position, start depth position: end depth position | = scores
```

```
out scores from network all classes [start height position: end height position, st
art width position: end width position, start depth position: end depth position, 0]
=predictions[0, : , : , : , 0];
```

```
out scores from network all classes [start height position:end height position, st
art width position: end width position, start depth position: end depth position, 1]
=predictions[0, : , : , : , 1];
```

```
out scores from network all classes [start height position: end height position, st
art width position: end width position, start depth position: end depth position, 2]
=predictions[0, :, :, :, 2];
```

```
out scores from network all classes [start height position: end height position, st
art width position: end width position, start depth position: end depth position, 3]
=predictions[0, : , : , : , 3];
```

```
#Script is general for n classes to this point
out_Pmap_cat1 = out scores from network all classes[:,:,:,0]:
out Pmap cat2 = out scores from network all classes[:,:,:,1];
out Pmap cat3 = out scores from network all classes[:, :, : , ?];
out Uncertainty Scores = out Uncertainty Scores[0:height, 0:width, 0:depth];
#Remove padding from probability maps
out Pmap cat1 = out Pmap cat1[0:height, 0:width, 0:depth];
out Pmap cat2 = out Pmap cat2[0:height, 0:width, 0:depth];
out Pmap cat3 = out Pmap cat3[0:height, 0:width, 0:depth];
#%%visualise network outputs
fiq, (ax1, ax2, ax3, ax4) = plt.subplots(1, 4, sharey=True)fiq.set size inches(14, 12)
im = ax1.imshow(out Pmap cat1[:, :, 59])ax1.title.set text('Background/Other')
im = ax2.imshow(out) Pmap cat2[:,:,59])
ax2.title.set_text('LF-nuclei')
im = ax3.imshow(out Pmap cat3[:, :, 59])ax3.title.set text('LF-actin')
im = ax4.\overline{imshow}(out Uncertainty Scores[:, :, 59])ax4.title.set_text('Uncertainty')
plt.savefig('Predictions.png')
#%%Map to 16-bit and save for loading into CellProfiler
data norm holder = np.zeros((1024, 1024, 107), np.uint16)
uil6 PMAP catl xy = cv2.normalize(out Pmap cat1, data norm holder, 65535.0,0.0, cv2. NORM MINMAX)
data norm holder = np{\text{-}zeros}(1024, 1024, 107), np.uint16)
uil6 PMAP cat2 xy = cv2.normalize(out Pmap cat2, data norm holder, 65535.0,0.0, cv2. NORM MINMAX)
data norm holder = np{\text{-}zeros}(1024, 1024, 107), np.uint16)
uil6 PMAP cat3 xy = cv2.normalize(out Pmap cat3, data norm holder, 65535.0,
0.0, cv2. NORM MINMAX)
data to save = np{\cdot}zeros((1024,1024,107,3))data to save[:,:,:,0] = ui16 PMAP catl xy
data to save[:,:,:,1] = ui16 PMAP cat2 xy
data_to_save[:, :, :, 2] = uil6_PMAP_cat3_Ny#%% write files out as multipage tiff
for channel in range(0,3):
    image to save = (data to save[:, :, :, chamnel]), as type(dtype = np.util6)rearranged image to save = np.transpose(image to save, axes=[2,0,1])imageio.mimwrite('Ch '+str(channel+3)+' lm 001'+'.tiff', rearranged image to sav
e)
```
Extracting single-cell features using label-free cell segmentation and CellProfiler 4

- Download and install CellProfiler4 from the CellProfiler website. https://cellprofiler.org

1.2-D CellProfiler Pipeline

-A screencast video is included with the BioStudies archive.

- Folder 5 "5 CellProfiler cell measurements" in the 2-D BioStudies project archive contains example data, a CellProfiler pipeline and the subsequent CellProfiler single-cell outputs:

- The image-data (inside 1_Structured_test_data) contains four immunofluorescence channels followed by the probability maps obtained for the label-free nuclei, actin and background/other classes from either the Python or MATLAB deep learning scripts (channels 5, 6 and 7, respectively).

- Open CellProfiler 4 and load the image analysis pipeline from the "2_CellProfiler_pipeline" folder.

- Drag-and-drop the "1_structured_test_data" folder into the CellProfiler image-window to load the 2-D image-data:

- Choose where to save the outputted cell features by clicking on the "Output Settings" tab at the bottom-left of the CellProfiler dialogue.

- To run the CellProfiler pipeline and save the cell features and other pipeline outputs at the specified location, click "Analyse Images" at the bottom-left of the CellProfiler screen.

- Previously-saved CellProfiler outputs are also available inside the "3_Outputs" folder:

2.3-D CellProfiler Pipeline

-A screencast video is included with the BioStudies archive.

- Folder 5 "5 CellProfiler cell measurements" in the 3-D BioStudies project archive contains example data, a 3-D CellProfiler pipeline and the subsequent CellProfiler single-cell outputs:

- The image-data (inside 1_Structured_test_data) contains two immunofluorescence channels followed by the 3-D probability maps obtained for the label-free nuclei, actin and background/other classes from either the Python or MATLAB deep learning scripts (channels 3, 4 and 5, respectively).

- Open CellProfiler 4 and load the image analysis pipeline from the "2_CellProfiler_pipeline" folder.

- Drag-and-drop the "1_structured_test_data" folder into the CellProfiler image-window to load the 2-D image-data:

- Choose where to save the outputted cell features by clicking on the "Output Settings" tab at the bottom-left of the CellProfiler dialogue.

- To run the CellProfiler pipeline and save the cell features and other pipeline outputs at the
specified location, click "Analyse Images" at the bottom-left of the CellProfiler screen.

- Previously-saved CellProfiler outputs are also available inside the "3_Outputs" folder:

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2-D Cell Profiler image analysis pipelines. This section presents screenshots of a CellProfiler image analysis pipeline used to achieve label-free cell segmentation in 2-D from the Unet network outputs, and to measure the intensity and size/shape features of identified cellobjects. To use the image analysis pipeline with new image data, the 'IdentifyPrimaryObjects' module simply needs adjusting so that the 'typical diameter of objects' size-range matches the pixel scaling of the new images. For newcomers to CellProfiler, we recommend downloading the image-data and pipeline from BioStudies database https://www.ebi.ac.uk/biostudies/ under accession number S-BSST742. This enables the pipeline to be run with the data described in the manuscript and allows the user to see how each module works.

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CellProfiler 4.1.3: CP413_PeyersPatchTestData_CellOutlines.cpproj* (D:\John\2020\20200417_2D_LABEL_FREE_SEGMENTATION_PROJECTS\20210522_2D_biostudies\2_Final 2D Peyers Patch example\MATLAB\2D_PeyersPatch... - \Box

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3-D CellProfiler pipeline. This section presents screenshots of a CellProfiler image analysis pipeline used to achieve label-free cell segmentation in 3-D from the Unet network outputs and to measure the intensity and size/shape features of identified cell-objects. To use the image analysis pipeline with new image data, the 'IdentifyPrimaryObjects' module simply needs adjusting so that the 'typical diameter of objects' size-range matches the pixel scaling of the new images. For newcomers to CellProfiler, we recommend downloading the imagedata and pipeline from BioStudies database https://www.ebi.ac.uk/biostudies/ under accession number S-BSST742. This enables the pipeline to be run with the data described in the manuscript and allows the user to see how each module works.

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