Algorithm 1 General algorithm used to estimate the diffusion coefficient from the billiard approach. We assume that the coordinate system is located at the center of the billiard.

procedure ESTIMATE $D(p_0, p_f, R, L)$ 1: $d_0 = ||p_f - p_0||$ 2: $d_1 = F_s(p_0, p_f, L, R) + F_c(p_0, p_f, L, R)$ 3: Using $\tilde{\rho}(d, t) = \rho(d_0, t) + \rho(d_1, t)$, where $\rho(d, t) = \frac{1}{4\pi Dt} \exp\left(-\frac{d^2}{4Dt}\right)$ perform a maximum likelihood estimation using D as fitting parameter. **end procedure**

function $F_s(p_0, p_f, L, R)$ $(x_0, y_0) \leftarrow p_0$ $(x_f, y_f) \leftarrow p_f$

$$\begin{aligned} x_{c}^{v} &= \frac{(R-y_{0})(x_{f}-x_{0})}{2R-y_{f}-y_{0}} + x_{0} \\ x_{c}^{b} &= \frac{(-R-y_{0})(x_{f}-x_{0})}{-2R-y_{f}-y_{0}} + x_{0} \\ \text{if } &|x_{c}^{u}| \leq L/2 \text{ then} \\ &p_{c} &= (x_{c}^{u}, R) \\ &d_{u} &= ||p_{c} - p_{0}|| + ||p_{c} - p_{f}|| \\ \text{else} \\ &d_{u} &= 0 \\ \text{end if} \\ \text{if } &|x_{c}^{b}| \leq L/2 \text{ then} \\ &p_{c} &= (x_{c}^{b}, -R) \\ &d_{b} &= ||p_{c} - p_{0}|| + ||p_{c} - p_{f}|| \\ \text{else} \\ &d_{b} &= 0 \\ \text{end if} \\ \text{return } d_{u} + d_{b} \\ \text{end function} \end{aligned}$$

function $F_c(p_0, p_f, L, R)$ $p_f \mapsto p_f - \frac{L}{2}$ $P_c = (x_c, y_c) \leftarrow \text{solution from (8)}$ $d_r = \sum_{\substack{p_c \in P_c \\ x_c > 0}} ||p_c - p_0|| + ||p_c - p_f||$ $p_f \mapsto p_f + \frac{L}{2}$ $P_c = (x_c, y_c) \leftarrow \text{solution from (8)}$ $d_l = \sum_{\substack{p_c \in P_c \\ x_c < 0}} ||p_c - p_0|| + ||p_c - p_f||$ return $d_r + d_l$ end function # Reflection points on straight segments

x-coordinate of the upper point

x-coordinate of the bottom point

- # Reflection points on curved segments
- # The next computation is done with the origin at (L/2, 0)
- # May give more than one solution. In that case P_c is an array of tuples $p_c = (x_c, y_c)$
- # Add up all 1-bounce distances of points reflecting on the right circular segment
- # The next computation is done with the origin at (-L/2, 0)
- # May give more than one solution. In that case P_c is an array of tuples $p_c = (x_c, y_c)$
- # Add up all 1-bounce distances of points reflecting on the left circular segment