S1 Appendix. Proof of Inequality between the Active and Passive Stiffness Matrices Assume from Eq 27 that we can write:

$$\mathbf{K}_{\mathrm{a}} = -\mathbf{K}_{\mathrm{p}} \tag{53a}$$

$$\mathbf{J}^{\mathrm{T}}\mathbf{K}_{\mathrm{c}}\mathbf{J} = -\frac{\partial \mathbf{J}}{\partial \mathbf{q}}^{\mathrm{T}}\mathbf{w}.$$
 (53b)

However it can be shown through proof by contradiction that this equality is impossible. First consider that the work done on the endpoint is:

$$W = \frac{1}{2} \delta \mathbf{x}^{\mathrm{T}} \mathbf{K}_{\mathrm{c}} \delta \mathbf{x} = \frac{1}{2} \delta \mathbf{q}^{\mathrm{T}} \mathbf{J}^{\mathrm{T}} \mathbf{K}_{\mathrm{c}} \mathbf{J} \delta \mathbf{q} \ge 0 \ \forall \delta \mathbf{q}$$
(54)

where the relationship $\delta \mathbf{x} = \mathbf{J} \delta \mathbf{q}$ has been used Eq 3. Under this condition $\mathbf{J}^{\mathrm{T}} \mathbf{K}_{\mathrm{c}} \mathbf{J}$ is at least positive semi-definite. It follows from Eq 53b that $\frac{\partial \mathbf{J}}{\partial \mathbf{q}}^{\mathrm{T}} \mathbf{w}$ is negative semi-definite and, by extension, symmetric. Expanding this matrix we have:

$$\frac{\partial \mathbf{J}}{\partial \mathbf{q}}^{\mathrm{T}} \mathbf{w} = \begin{bmatrix} \frac{\partial \mathbf{J}_{1}^{\mathrm{T}} \mathbf{w}}{\partial q_{1}} & \cdots & \frac{\partial \mathbf{J}_{1}^{\mathrm{T}}}{\partial q_{n}} & \mathbf{w} \\ \vdots & \ddots & \vdots \\ \frac{\partial \mathbf{J}_{n}}{\partial q_{1}}^{\mathrm{T}} \mathbf{w} & \cdots & \frac{\partial \mathbf{J}_{n}}{\partial q_{n}}^{\mathrm{T}} \mathbf{w} \end{bmatrix} \in \mathbb{R}^{n \times n}$$
(55)

Then from symmetry it must be that:

$$\frac{\partial \mathbf{J}_{i}}{\partial q_{j}}^{\mathrm{T}} \mathbf{w} = \mathbf{w}^{\mathrm{T}} \frac{\partial \mathbf{J}_{j}}{q_{i}}$$
(56a)

$$\frac{\partial \mathbf{J}_{i}}{\partial q_{j}} = \frac{\partial \mathbf{J}_{j}}{\partial q_{i}}.$$
(56b)

But we know that this is not true Eq 11. Thus, $\frac{\partial \mathbf{J}}{\partial \mathbf{q}}^{\mathrm{T}} \mathbf{w}$ is not symmetric and $\mathbf{K}_{\mathrm{a}} = -\mathbf{K}_{\mathrm{p}}$ cannot be a solution to Eq 27.