

Online Data Supplements: Expanded Methods

I. *Boundary Conditions:*

Boundary conditions required for flow analysis were taken from a number of measured data bases since at present there is no single data source for all the required inputs.

Inlet, Outlet and Left Ventricle Pressures: $P_A(t)$, $P_V(t)$ and $LVP(t)$ respectively, were taken from Hurst & Logue (6). The signals were modified for a specific heart rate by changing the diastolic time fraction (DTF , the period from minimal to maximal time derivative of LVP divided by the cardiac period (2)) taken from measured data (2). This modification is a close approximation for the complex relation between DTF and additional flow conditions (2). The signals amplitudes were modified as well: since the feed artery to the analyzed network is a distal (order 8) epicardial artery (rather than the coronary aortic outlet), the inlet pressure magnitude was scaled down to 100/70 mmHg in systole/diastole ((11); Fig. ODS-1A). Similarly, the outlet pressure (of the network's drain vein) was taken to follow aortic pressure waveform, but delayed so as to peak during aortic valve closure (16). The pressure magnitude was taken as 25/5 mmHg (11, 16).

Myocardial Activation (Fig. ODS-1B), lasting 0.26 seconds at endocardium (13), was taken to vary between 0 at diastole to 1 during peak activation. Depolarization was taken to initiate at the endocardium and propagate towards the epicardium at velocity of 50 cm/s (1) while repolarization propagates in the opposite direction at the same velocity.

Sarcomere Stretch Ratio (SSR) has been observed to be highly coupled to ventricular volume (54, 60). Thus, the ventricular volume waveform (6) was used for the SSR waveform, subject to 5% elongation from early to end diastole (15), and 16% shortening

25 from end-diastole to end-systole (15, 17) as depicted in Fig. ODS-1C. Ventricular wall
26 thickening was taken from measured data (4).

27 **II. Stochastic Reconstruction of the Coronary Network**

28 The reconstruction is based on morphometric data for porcine coronary vasculature (8-10).
29 Briefly, arteries and veins are assigned orders ranging from 1 to 11 and from -1 to -12 in
30 the arterial and venal networks, respectively. The terms “segment” and “element” are
31 applied to a vessel portion between two vessel junctions and to a sequence of segments of
32 the same order which are connected in series, respectively. Capillaries are also grouped,
33 into those stemming from arterioles (Coa), venules (Cov) or other capillaries (Coo), and
34 cross-connecting capillaries (Ccc).

35 **Microvascular Network:** The microvascular network reconstruction was carried out based
36 on the morphometric data of Kassab et al. (8-10) regarding vessel lengths, vessel
37 connectivity, and capillary branching pattern, and subject to two data-based constraints: i)
38 the distance between arteriolar and venular domains (average of 510 μm , (8)), and ii) the
39 ratio between arteriolar and venular segments (roughly 1 to 2, (9, 10)). One arteriole and
40 two venules were located 510 μm apart. They were assigned order 1 and order -1,
41 respectively. Arterial and venular capillaries (Coa and Cov) were attached to these
42 corresponding vessels, according to connectivity data (9, 10) (see figure ODS-2A). The
43 lengths of vessels were assigned according to the measured statistical data. Utilizing the
44 branching patterns, Coo and Ccc were connected to the arterial and venular capillaries (Fig.
45 ODS-2B). Subsequently, additional arterioles and venules were connected to the
46 previously posed vessels, thus increasing the orders of the input and output vessels (Fig.
47 ODS-2C). This process was iterated until the gaps between arteriolar and venular domains

48 were bridged by capillaries, resulting in a network fed by one order 3 arteriole and two
49 order -3 venules. In Tables ODS-1 to ODS-4 the reconstructed capillary branching pattern,
50 arterial and connectivity matrices, and lengths and diameters of each order were compared
51 to the measured data (8-10). A student T-test showed no statistically significant differences
52 between the data and reconstructed network.

53 **Arterial and Venous Trees:** The order of arteries to first penetrate the cardiac wall ranges
54 between 6 and 8 (7). Hence, the feeding artery was chosen to be an order 8. The number of
55 generations arising from this arterial element, and the order of each segment in the tree
56 were assigned based on the segment-to-element data (10). The order of the most distal
57 segments was set to 4, thus matching the order of the reconstructed microvascular inlet
58 arteriole. The length of each segment in the tree was assigned to fit the statistical data (8-
59 10), while maintaining monotonic reduction of diameters along the element. The venous
60 tree was reconstructed in a similar manner.

61

62 **III. The Deformation Gradient Tensors**

63 The deformation gradient F is determined by the mapping of coordinates between two
64 loading configurations. Specifically, the transition between stress-free (*sf* subscript) and un-
65 tethered (*unt*) configurations, combined with tissue incompressibility, leads to (5):

66

$$\begin{aligned}
67 \quad \mathbf{F}_{sf \rightarrow unt}^{v/m} &= \begin{bmatrix} \frac{\Theta_0^{v/m} r_{sf}^{v/m, in}}{\pi r_{unt}^{v/m, in} \Lambda_{unt, sf}^{v/m}} & 0 & 0 \\ 0 & \frac{\pi r_{unt}^{v/m, in}}{\Theta_0^{v/m} r_{sf}^{v/m, in}} & 0 \\ 0 & 0 & \Lambda_{unt, sf}^{v/m} \end{bmatrix} \quad (\text{ODS 1})
\end{aligned}$$

68 Here the superscript v/m denotes the specific cylinder: either vessel wall (v) or
69 myocardium (m). Θ_0 is the opening angle (Fig. 3), r^{in} is the cylinder internal radius, and Λ
70 is the axial stretch as defined in the main text. The deformation gradients associated with
71 the transitions between un-tethered and unloaded (*unld*) configurations, and between
72 unloaded and loaded configurations are:

$$\begin{aligned}
73 \quad \mathbf{F}_{unt \rightarrow unld}^{v/m} &= \begin{bmatrix} \frac{r_{unt}^{v/m, in}}{r_{unld}^{v/m, in} \Lambda_{unld, unt}^{v/m}} & 0 & 0 \\ 0 & \frac{r_{unld}^{v/m, in}}{r_{unt}^{v/m, in}} & 0 \\ 0 & 0 & \Lambda_{unld, unt}^{v/m} \end{bmatrix} \quad (\text{ODS 2})
\end{aligned}$$

$$\begin{aligned}
74 \quad \mathbf{F}_{unld \rightarrow load}^{v/m} &= \begin{bmatrix} \frac{r_{unld}^{v/m, in}}{r_{load}^{v/m, in} \lambda_z} & 0 & 0 \\ 0 & \frac{r_{load}^{v/m, in}}{r_{unld}^{v/m, in}} & 0 \\ 0 & 0 & \lambda_z \end{bmatrix} \quad (\text{ODS 3})
\end{aligned}$$

75 Here λ_z , the vessel dynamic axial stretch (see Appenix B), has the same level at both
76 cylinders.

77

78 **IV. Vessel and Myocardium Material laws**

79 Following previous studies, the description of the multiaxial material laws of vessel wall
 80 (19) and of the passive and active myocardium (12) are based on pseudostrain energy
 81 functions:

82

$$W_v = \frac{C_{v,1}}{2} (\exp(Q_v) - 1);$$

$$83 \quad W_{m,pas} = C_{m,1} (\exp(Q_m) - 1); \quad (ODS 4)$$

$$W_{m,act} = W_{m,pas} + C_{m,5} + C_{m,6}(I_1 - 3)(I_4 - 1) + C_{m,7}(I_1 - 3)^2 + C_{m,8}(I_4 - 1)^2 + C_{m,9}(I_1 - 3) + C_{m,10}(I_4 - 1)$$

84 where v, m pas and act subscripts denote vessel, myocardium passive and active,
 85 respectively, I_1 and I_4 are the first and fourth strain invariants respectively, and

$$86 \quad Q_v = C_{v,2}E_{\Theta\Theta}^2 + C_{v,3}E_{ZZ}^2 + C_{v,4}E_{RR}^2 + 2(C_{v,5}E_{\Theta\Theta}E_{ZZ} + C_{v,6}E_{ZZ}E_{RR} + C_{v,7}E_{\Theta\Theta}E_{RR}) \quad (ODS 4a)$$

$$Q_m = C_{m,2}(I_1 - 3)^2 + C_{m,3}(I_1 - 3)(I_4 - 1) + C_{m,4}(I_4 - 1)^2$$

87 E_{ii} are the components of the Green-Lagrange strain tensor, and $C_{i,j}$ are specimen-
 88 dependent parametrs which were previously estimated from data for vessel (19) and for
 89 myocardium (12).

90

91 **V. Determining the Stress-Free Configuration**

92 To derive the stress-free configuration from the vessel cast (input) one, the internal and
 93 external radii of both cylinders (vessel wall and myocardium) at the three unknown
 94 configurations (unloaded, un-tethered and stress-free) are required. In addition to these 12
 95 unknowns, 3 axial stretches need to be determined: the stretches of both vessel wall and
 96 myocardium due to closure of the opening angle ($\Lambda_{unt,sf}^v$ and $\Lambda_{unt,sf}^m$, respectively), and the

97 myocardium stretch due to tethering, $\Lambda_{untl,unt}^m$. The vessels' tethering stretch $\Lambda_{untl,unt}^v$ is a
98 measured input. Hence the total number of unknowns is 15.

99 The cast internal and external radii are known from the data (3, 8-10, 14, 18).
100 Hence, in each unknown configuration and for each tissue (vessel and myocardium), for
101 each given internal radius the incompressibility condition (Eq. B2 in Appendix B) yields
102 the corresponding external one. Additionally, the assumption of common interface between
103 cylinders at each of the above three configurations eliminates three more unknowns. Thus
104 the number of unknowns is reduced from 15 to 6 (i.e., the vessel internal radii in stress-free,
105 un-tethered and unloaded configurations; $r_{sf}^{v,in}$, $r_{unt}^{v,in}$ and $r_{untl}^{v,in}$, respectively, and the three
106 unknown axial stretches listed above).

107 **VI. Computational Scheme for Flow Analysis:**

108 The solution of the ODE system described by Eqs. 1 and D1 in the main text must satisfy
109 periodicity condition. This was fulfilled using the shooting method, i.e., after an initial
110 guess of the intravascular pressure in each vessel, the numerical scheme was carried out for
111 several cardiac cycles until solutions at consecutive cycles converged to within preset
112 tolerance. This tolerance was set as follows: the maximum allowed pressure difference (at
113 any of the vessels) between the beginning and the end of a cardiac cycle should be <0.1
114 mmHg. Numerical accuracy of the final solution was ascertained based on the criteria that
115 the maximum difference between total flows into the feeding artery and out of its draining
116 vein during a cardiac cycle was <5% of the total inflow.

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119 **REFERENCES**

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170 **FIGURE LEGENDS**

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172 **Figure ODS-1:** Model input boundary conditions. A) Left-ventricle (LVP (t), solid),
173 feeding ($P_A(t)$, dash) and draining ($P_V(t)$, dots) pressure signals, under heart rate of 120
174 beats per minute. X-axis - time (in seconds), starting with endocardial activation. Y-axis -
175 pressure (in mmHg, data taken from reference (6) and modified following (2, 11, 16)). B)
176 Activation (13) at subepicardium (dash-dot) and subendocardium (solid). Time difference
177 between the two signals is due to the finite velocity of activation propagation (1). C)
178 Sarcomere stretch ratio (SSR(t), dash), reconstructed from LV volume (6), and
179 myocardium wall thickening ((4), solid).

180

181 **Figure ODS-2:** A schematic of steps of the microvascular network reconstruction. A) One
182 order 1 and two order -1 segments are located $510 \mu\text{m}$ apart, and Coa and Cov capillaries
183 are added. B) Coo and Ccc capillaries are added while preserving branching pattern ratio.
184 C) Arterioles and venules are added to enable bridging the gap between domains.

185 **Table ODS-1: Capillary branching patterns.** Comparison between reconstructed network
 186 and Kassab et al. (8) statistical data.

Junction Pattern	Data	Reconstructed Network
T	0.2	0.19
Y	0.21	0.22
H	0.53	0.53
Hp	0.06	0.06

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190 **Table ODS-2: Reconstructed arteriolar connectivity matrix.** Comparison between
 191 reconstructed network and Kassab et al. (10) statistical data (in brackets).

Daughter Order	Mother Order		
	1	2	3
0	3 (3.2)	0 (0.67)	0 (0.15)
1	0 (0.14)	2 (2.04)	1 (0.63)
2		0 (0.09)	3 (2.24)
3			0 (0.07)

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195 **Table ODS-3: Reconstructed venular connectivity matrix.** Comparison between
 196 reconstructed network and Kassab et al. (9) statistical data (in brackets).

Daughter Order	Mother Order		
	-1	-2	-3
0	2.7 (2.56)	0 (0.42)	0 (0.35)
-1	0 (0.105)	2 (2.47)	1 (0.77)
-2		0 (0.11)	3 (2.44)
-3			0 (0.07)

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198 **Table ODS-4: The Vessels' lengths and diameters: Comparison between reconstructed**
 199 *microvascular network and data (8-10). Asterisks stand for arterioles' diameters which*
 200 *were altered according to their intramural location (see Appendix B).*

Vessel Type	Data		Reconstructed Network		p-value (reconstructed vs. data)
	n	Mean (SD)	n	Mean (SD)	
	Segment Length (microns)				
Order 3	177	72 (49)	3	70.4 (33.7)	0.47
Order 2	326	72 (45)	3	75.5 (35.5)	0.44
Order 1	506	56 (38)	14	58.8 (39.0)	0.40
Order -1	251	51 (41)	19	49.5 (29.0)	0.42
Order -2	313	56 (41)	8	55.4 (33.4)	0.48
Order -3	263	63 (43)	4	66.5 (34.1)	0.43
Coa	222	52 (32.3)	21	48.5 (30.9)	0.31
Cov	34	45 (30.5)	33	43.7 (19.8)	0.42
Ccc	161	21.1 (15.5)	20	20.2 (6.0)	0.31
Coo	86	54.5 (43)	49	56.8 (25.6)	0.35
Segment Diameter (microns)					
Order 3	266	18.7 (2.6)	3	18.4 (1.0)*	0.34
Order 2	539	13.0 (1.7)	3	13.2 (0.8)*	0.38
Order 1	835	9.2 (0.94)	14	9.1 (0.5)*	0.19
Order -1	251	10.8 (1.7)	19	11.1 (1.0)	0.14
Order -2	313	17.6 (3.0)	8	17.1 (1.8)	0.24
Order -3	263	30 (4.3)	4	29.4 (3.9)	0.38
Coa	222	6.2 (1.1)	21	6.1 (0.6)	0.35
Cov	34	7.0 (1.2)	33	6.9 (0.7)	0.36
Ccc	161	5.5 (1.2)	20	5.5 (0.8)	0.44
Coo	86	5.7 (1.4)	49	5.6 (0.7)	0.22

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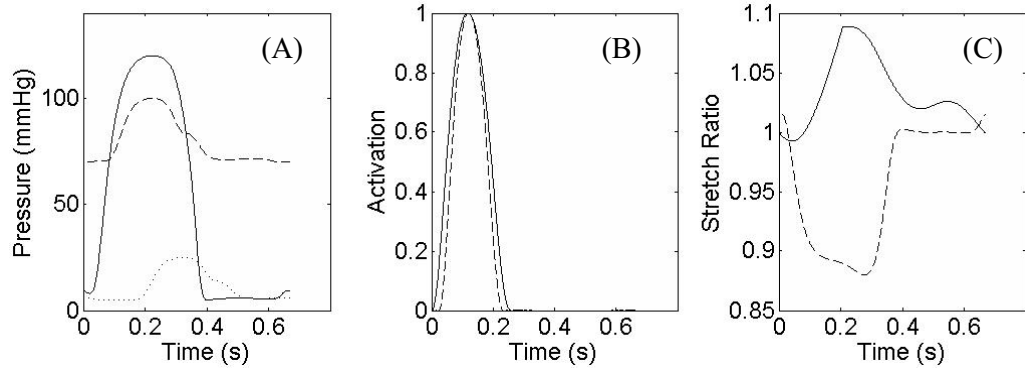


Figure ODS-1

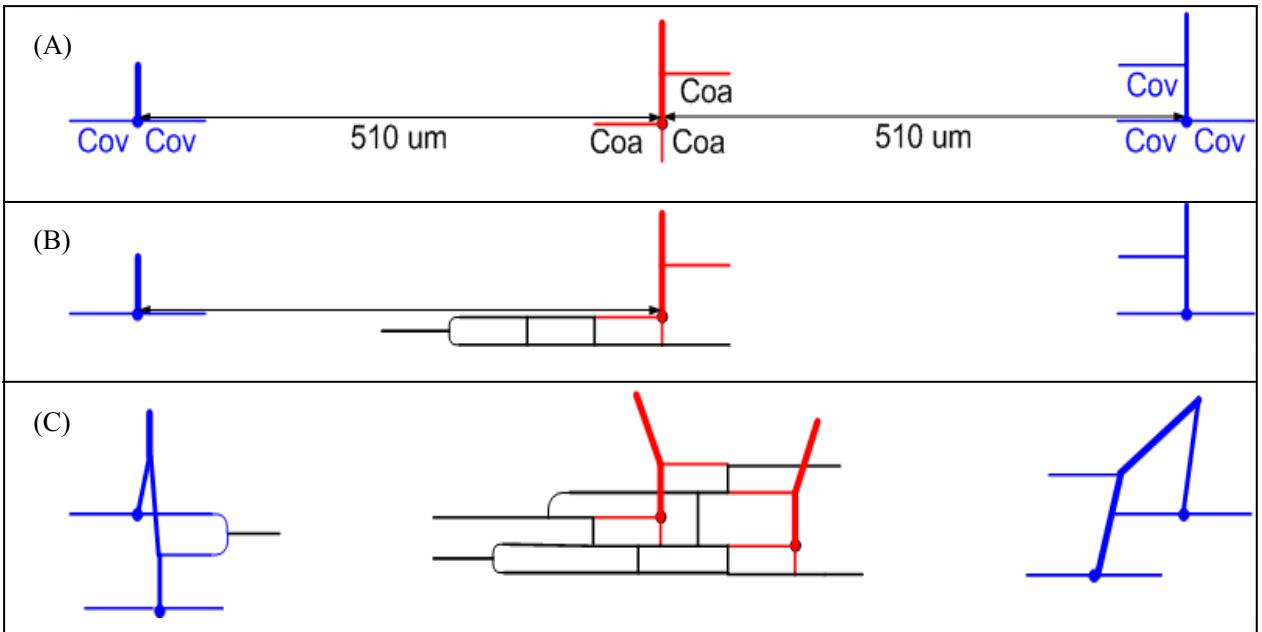


Figure ODS-2