Estimating the superiority of a drug to a placebo when all and only those patients at risk are treated with the drug

(clinical trials/estimation under biased sampling/u, v method)

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ABSTRACT It is shown that, under certain assumptions, one can estimate the difference between the effect of a treatment and that of a placebo even when the treatment has been given to all and only those patients who are at risk (as evidenced by a screening examination).

A new drug is to be tested for its effect on, say, hypertension. For a patient randomly chosen from some population let

 θ = the patient's "true" (unobservable) blood pressure

 $x =$ the patient's blood pressure reading obtained at a screening examination before any treatment is undertaken.

We shall assume that given θ , x is $N(\theta, \sigma^2)$, where σ is a constant, known or unknown. We make no assumption about how θ is distributed in the population.

Suppose that if $x > a$ the patient is regarded as at risk. A standard method for evaluating the new drug is to allocate randomly half of all such patients to the new drug and half to a placebo. Suppose, however, that for ethical or other reasons we have adopted the following allocation protocol:

(if $x > a$, the patient is treated with the drug (A) If $x \le a$, the patient is treated with a placebo.

Let

 $y =$ the blood pressure reading of the patient after treatment.

From the observed values $(x_1, y_1), \ldots, (x_n, y_n)$ for *n* patients, we want to estimate the parameter

 τ = mean effect of the drug, as compared to the placebo, over the population at risk $(x > a)$.

It is not clear a priori that a consistent estimator of τ can be found under the allocation protocol (A) , but in the section below we shall show how to do this under an assumption (3) below) concerning y.

Consistent Estimation of τ . LEMMA. Assume that (θ, x) is a random vector such that for some constant $\sigma > 0$,

$$
given \theta, x \text{ is } N(\theta, \sigma^2). \qquad [1]
$$

If $u(\cdot)$ is of bounded variation (b.v.) and absolutely continuous (a.c.) on $(-\infty, \infty)$, then

$$
E[u(x)\theta] = E[xu(x)] - \sigma^2 Eu'(x). \qquad [2]
$$

Proof. $\theta E[u(x)|\theta]$

$$
\begin{split}\n&= \frac{\theta}{\sigma} \int u(x) \varphi \bigg(\frac{x - \theta}{\sigma} \bigg) dx \qquad (\varphi(x) = (2\pi)^{-1/2} \exp(-x^2/2)) \\
&= -\int u(x) \bigg(\frac{x - \theta}{\sigma} \bigg) \varphi \bigg(\frac{x - \theta}{\sigma} \bigg) dx + \frac{1}{\sigma} \int x u(x) \varphi \bigg(\frac{x - \theta}{\sigma} \bigg) dx \\
&= \sigma \int u(x) \varphi' \bigg(\frac{x - \theta}{\sigma} \bigg) dx + E[xu(x)]\theta] \\
&= -\sigma \int \varphi \bigg(\frac{x - \theta}{\sigma} \bigg) u'(x) dx + E[xu(x)]\theta] \\
&= -\sigma^2 E[u'(x)]\theta] + E[xu(x)]\theta],\n\end{split}
$$

which, since θ is arbitrary, implies Eq. 2.

THEOREM 1. Assume that (θ, x, y) **is a random vector such** that assumption ¹ holds and also that for some constants a and c, hich, since θ is arbitrary, in

THEOREM 1. Assume that (the at assumption 1 holds and α
 $E[y|\theta, x] = \theta + c$

here by definition
 $\delta_a(x) = \begin{cases} 1 \\ 0 \end{cases}$

ad t(...) is arbitrary. If $u(\cdot)$ is in

$$
E[y|\theta, x] = \theta + c + \delta_a(x) \cdot t(\theta, x),
$$
 [3]

where by definition

$$
[\theta, x] = \theta + c + \delta_a(x) \cdot t
$$

ion

$$
\delta_a(x) = \begin{cases} 1 & \text{if } x > a \\ 0 & \text{if } x \le a \end{cases}
$$

and $t(\cdot, \cdot)$ is arbitrary. If $u(\cdot)$ is b.v. and a.c. on $(-\infty, \infty)$, then

 $E[u(x)(y - x)] + \sigma^2 Eu'(x) = cEu(x) + E[u(x)\delta_a(x)t(\theta, x)].$ [4]

Proof. By assumption 3,

$$
E[u(x)y|\theta, x] = u(x)[\theta + c + \delta_a(x)t(\theta, x)],
$$

so from formula 2 it follows that

$$
E[u(x)y] = E[xu(x)] - \sigma^2 Eu'(x) + cEu(x) + E[u(x)\delta_a(x)t(\theta, x)],
$$

$$
E[u(x)\delta_a(x)t(\theta, x)],
$$

which was to be proved.

Setting $u = 1$ in formula 4 gives the following. COROLLARY 1. Under assumptions ¹ and 3,

$$
E[\delta_a(x)t(\theta, x)] = E(y - x) - c.
$$
 [5]

We shall also need the following.

COROLLARY 2. Under assumptions 1 and 3, if $u_1(\cdot)$ and

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Abbreviations: b.v., bounded variation; a.c., absolutely continuous; a.s., almost surely.

 $u_2(\cdot)$ are b.v. and a.c. on $(-\infty, \infty)$ and vanish for $x > a$, then

$$
\begin{cases}\nE[u_1(x)(y-x)] + \sigma^2 E u_1'(x) = c E u_1(x) \\
E[u_2(x)(y-x)] + \sigma^2 E u_2'(x) = c E u_2(x)\n\end{cases}
$$
\n[6]

and hence

$$
c = \frac{Eu'_2(x) \cdot E[u_1(x)(y - x)] - Eu'_1(x) \cdot E[u_2(x)(y - x)]}{Eu'_2(x) \cdot Eu_1(x) - Eu'_1(x) \cdot Eu_2(x)}
$$
[7]

provided that the denominator is not 0.

We now define the parameter τ by

$$
\tau = E[t(\theta, x)|x > a] = \frac{E[\delta_a(x)t(\theta, x)]}{E\delta_a(x)}
$$

$$
= \frac{E(y - x) - c}{E\delta_a(x)} \qquad \text{(by formula 5).} \qquad [8]
$$

(In the case of hypertension we hope that t , and hence τ , is negative.)

We can estimate c and τ by

$$
c_n = \frac{\sum_{i=1}^{n} u'_2(x_i) \cdot \sum_{i=1}^{n} u_1(x_i)(y_i - x_i) - \sum_{i=1}^{n} u'_1(x_i) \cdot \sum_{i=1}^{n} u_2(x_i)(y_i - x_i)}{\sum_{i=1}^{n} u'_2(x_i) \cdot \sum_{i=1}^{n} u_1(x_i) - \sum_{i=1}^{n} u'_1(x_i) \cdot \sum_{i=1}^{n} u_2(x_i)}
$$
[9]

and

$$
\tau_n = \frac{\sum\limits_{1}^{n} (y_i - x_i) - nc_n}{\sum\limits_{1}^{n} \delta_a(x_i)},
$$
 [10]

where by hypothesis (θ, x, y) , (θ_1, x_1, y_1) , ... are independent, identically distributed random vectors such that assumptions 1 and 3 hold. It is clear from formulas 7-10 that the following theorem holds.

THEOREM 2. As $n \to \infty$,

 $c_n \rightarrow c$, $\tau_n \rightarrow \tau$ a.s.

Moreover, $\sqrt{n(c_n - c)}$ and $\sqrt{n(\tau_n - \tau)}$ have limiting normal distributions with 0 means.

Remark 1. The functions $u_1(\cdot)$ and $u_2(\cdot)$ in formulas 6, 7, and 9 are assumed to be b.v. and a.c., vanishing for $x > a$, and such that the denominator of formula 7 is not 0. Subject to these restrictions, they are arbitrary. We do not know how to choose them so as to minimize the limiting variance of $\sqrt{n}(c_n - c)$ or $\sqrt{n}(\tau_n - \tau)$.

Remark 2. If σ is known, instead of using formulas 9 and 10 we can estimate c by

$$
c_n^* = \frac{\sum_{i=1}^{n} u_1(x_i)(y_i - x_i) + \sigma^2 \sum_{i=1}^{n} u'_1(x_i)}{\sum_{i=1}^{n} u_1(x_i)}
$$
 [11]

and τ by

$$
\tau_n^* = \frac{\sum_{i=1}^{n} (y_i - x_i) - nc_n^*}{\sum_{i=1}^{n} \delta_a(x_i)},
$$
 [12]

provided that $u_1(\cdot)$ is b.v. and a.c., vanishes for $x > a$, and $Eu_1(x) \neq 0.$

Remark 3. An inspection of the proofs shows that all the foregoing formulas remain valid even if the b.v. functions $u(·)$ occurring in formulas 2, 4, 6, and 7 are not a.c., provided that we always replace

$$
Eu'(x)
$$
 by $\int f(x)du(x)$, [13]

where $f(\cdot)$ is the probability density function of the random variable x . In particular, choosing

$$
u_1(x) = 1 - \delta_a(x), \quad u_2(x) = 1 - \delta_b(x)
$$
 for some $b < a$, [14]

we obtain the formulas

$$
c = \frac{E[(1 - \delta_a(x))(y - x)] - \sigma^2 f(a)}{E[1 - \delta_a(x)]}
$$

$$
c = \frac{f(b)E[(1 - \delta_a(x))(y - x)] - f(a)E[(1 - \delta_b(x))(y - x)]}{f(b)E[1 - \delta_a(x)] - f(a)E[1 - \delta_b(x)]}
$$

$$
[15]
$$

which can be used when σ is known or unknown to estimate c (and hence τ), provided that we have consistent density estimators $f_n(a)$, $\tilde{f}_n(b)$ of $f(a)$ and $f(b)$. Such estimators are available, and have an $n^{-1/2}$ rate of convergence, if we make the *additional assumption* that for some α and $\beta > 0$,

$$
\theta \text{ is } N(\alpha, \beta^2). \tag{16}
$$

For then x will (from assumption 1) be $N(\alpha, \gamma^2)$ with $\gamma^2 = \beta^2$ + σ^2 , and hence

$$
f(x) = \frac{1}{\gamma} \varphi \bigg(\frac{x - \alpha}{\gamma} \bigg). \tag{17}
$$

But as $n \to \infty$,

$$
\overline{x} = \frac{1}{n} \sum_{1}^{n} x_i \to \alpha, \qquad s^2 = \frac{1}{n} \sum_{1}^{n} (x_i - \overline{x})^2 \to \gamma^2 \qquad \text{a.s.,}
$$

and hence for any fixed x, as $n \to \infty$

$$
f_n(x) = \frac{1}{s} \varphi \bigg(\frac{x - \overline{x}}{s} \bigg) \to f(x) \qquad \text{a.s.}
$$

We may therefore estimate $f(a)$ and $f(b)$ by

$$
f_n(a) = \frac{1}{s} \varphi \bigg(\frac{a - \overline{x}}{s} \bigg), \qquad f_n(b) = \frac{1}{s} \varphi \bigg(\frac{b - \overline{x}}{s} \bigg) \qquad [18]
$$

and define (for use when σ is known)

$$
c_n^* = \frac{\sum_{i=1}^{n} [1 - \delta_a(x_i)] (y_i - x_i) - n \sigma^2 f_n(a)}{\sum_{i=1}^{n} [1 - \delta_a(x_i)]}
$$
 [19]

and (for use when σ is unknown)

$$
c_n =
$$
\n
$$
f_n(a) \sum_{1}^{n} [1 - \delta_b(x_i)] (y_i - x_i) - f_n(b) \sum_{1}^{n} [1 - \delta_a(x_i)] (y_i - x_i)
$$
\n
$$
f_n(a) \sum_{1}^{n} [1 - \delta_b(x_i)] - f_n(b) \sum_{1}^{n} [1 - \delta_a(x_i)]
$$
\n[20]

to obtain consistent estimators of c with $n^{-1/2}$ rates of convergence. It would, however, be safer to use formula 9 or 11 instead of formula 20 or 19 if it is not certain that θ is in fact normally distributed.

Remark 4. From formula 8 and the first part of formula 15 it follows that

$$
\tau = \frac{E(y - x) - c}{E\delta_a(x)}
$$
\n
$$
= \frac{E(y - x)}{E\delta_a(x)} - \frac{E[(1 - \delta_a(x)(y - x)] - \sigma^2 f(a)}{E[1 - \delta_a(x)]E\delta_a(x)}
$$
\n
$$
= \frac{E[1 - \delta_a(x)]E(y - x) - E[(1 - \delta_a(x))(y - x)] + \sigma^2 f(a)}{E\delta_a(x) \cdot E[1 - \delta_a(x)]}
$$
\n
$$
= \frac{E[\delta_a(x)(y - x)]}{E\delta_a(x)} - \frac{E[(1 - \delta_a(x))(y - x)]}{E[1 - \delta_a(x)]}
$$
\n
$$
+ \frac{\sigma^2 f(a)}{E\delta_a(x)E[1 - \delta_a(x)]}.
$$

Thus, under (A) , the statistic

(average of $y_i - x_i$ for those treated with drug) –

(average of $y_i - x_i$ for those treated with placebo) [21]

converges as $n \rightarrow \infty$ to

$$
\tau-\frac{\sigma^2f(a)}{P(x>a)\cdot P(x\leq a)},
$$

which is less than τ , so that even if t and hence τ is 0 the value of the statistic 21 will usually be negative.

Remark 5. If we replace the unknown constant in assumption 3 by any linear combination

$$
c_1g_1(x) + \ldots + c_kg_k(x) \qquad \qquad [22]
$$

of known functions with unknown coefficients c_1, \ldots, c_k , then it is clear how to generalize formulas 6 and 9 to estimate these coefficients by using functions $u_i(x)$, $j = 1, \ldots, k + 1$.

Remark 6. When in assumption 3 the function $t(\theta, x)$ is a constant and y, given θ and x, is $N(\theta + c + \delta_a(x) \cdot t, \sigma^2)$, the method of conditional maximum likelihood can be used to estimate t , as by Robbins and Zhang (1) . There are some technical difficulties in the present case, and we defer a comparison with the method for consistent estimation of τ described above to a later date.

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1. Robbins, H. & Zhang, C.-H. (1988) Proc. Nati. Acad. Sci. USA 85, 3670-3672.