

Supporting Information

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SI Materials and Methods

Chamber Preparation and Cell Culturing. A 14-mm hole was drilled in the center of a regular 35-mm cell culture plate (BD Biosciences). A 25-mm circular glass coverslip coated with poly-D-lysine was fixed by silicone grease (Corning) to cover this cavity. Chambers were mounted from parts cut out of Thermanox plastic coverslips (Nunc). Double-sided sticky gasket (Emsdium) was used to attach the “pillars” to the coverslip (Fig. S1A and C). Bridges were attached to the top of these pillars by BF-6 glue (Verteks Ltd.). Thus, the two bridges separated three compartments (Fig. S1A and C): two outer and one central. To guide directional axon growth, cells were cultured with a growth-factor gradient whose formation was facilitated by providing a growth factor-rich cell-culture medium in one of the outer chambers (referred to as a “+” chamber). The bridge, separating the central chamber from the “+” chamber was termed the “+” bridge. Media lacking growth factors was added to the opposite outer chamber and, therefore, this chamber and its bridge were designated as the “-” bridge. A hydrophobic pen was used to mark the whole cover slide and the top of the bridges to prevent the leakage of neurotrophic factor (NF)-containing media.

A mixture of four NFs was used: NGF (R&D Systems), NT-3 (Promega), BDNF (Promega), and glial cell line-derived neurotrophic factor (R&D Systems). When preparing dissociated neuron cultures, matrigel [95%, (MG); BD Biosciences] was allowed to seal the space under the bridge by way of surface tension. MG/NF mixture (20 ng/mL each) was used to load the “+” bridge, whereas pure MG was applied to the “-” bridge. MG was allowed to solidify in a CO₂ incubator within 3 to 5 min. Subsequently, the central chamber was coated by laminin (30 µg/mL; Cultex mouse laminin, R&D Systems; 2 to 4 h at 4 °C). Sensory neurons were isolated according to published protocols (1). Cells were plated at 90% confluence in DMEM/F12 supplemented with N2 and 10% fetal calf serum. The medium in the central chamber was replaced with DMEM/F12, supplemented with N2 (Gibco), 2% B27 (Gibco), gentamicin, and NFs (1 ng/mL each) 2 h after plating. Media were replaced in every compartment every other day. Mechanical stimuli were applied to the “+” bridge (Fig. S1A, C, and D’’).

Stimulation Setup. A piezo bender (Physik Instrumente GmbH) was used to provide mechanical stimulation. This bender is equipped with an integrated piezo sensor that monitors the bender current position. A small clip carrying an iron pin (probe) was attached to the tip of the bender (Fig. S1E). Probes were calibrated under the microscope. The bender was controlled by driving voltage applied by a computer-controlled system run in an open feedback loop: that is, the voltage applied to the piezo controller was transmitted into the driving voltage of the bender. This process allowed for accurate probe positioning above the bridge. We estimated the probe’s positioning accuracy to be within 1.6 µm. A computer program was developed to control the stimulation device, perfusion valve controller, and data acquisition and integration (i.e., exact time, duration, and strength of mechanical or chemical stimulation in synchrony with Ca²⁺ imaging).

Magnitude of Mechanical Stimuli. In a series of calibration experiments, we identified the maximum amplitude of static indentation (80 µm), which neither disintegrated the axons nor detached them from the slide surface. Therefore, we have applied static indentation up to 60 to 70 µm in a routine experiment. Maximal vibration magnitudes were 40 to 50 µm, because we reasoned that vibration stimuli would be more destructive to the gel and

axons. Furthermore, saturated vibration responses were often observed at 30- to 40-µm vibration amplitudes. Thus, the maximal amplitude of vibration stimuli was generally 10 to 20 µm smaller than that used for static indentation. Trains of successive stimuli were programmed, including both static indentation (from 20 to 70 µm indentation, ramp 900 mm/s, duration 5–10 s) and vibration (different magnitude of displacement, frequency, and duration, as indicated).

Probe Positioning. The probe was first visually positioned above the center of the “+” bridge. Subsequently, the probe was slowly lowered while monitoring the sensor voltage (through the embedded piezo sensor monitoring the actual bender position). As soon as the probe came into contact with the bridge, their simultaneous initial bend was reflected by a change in the bender’s sensor voltage. According to the manufacturer’s specification, 1 mV of sensor voltage corresponds to 40 nm of bender tip displacement, with the bender’s stiffness specified at 10 mN/µm. As soon as a 1- to 2-mV change of sensor voltage was observed, the bender was slightly retracted. Using a calibrated Von Frey hair filament and by observing plastic bridge bending under microscope, we estimated the stiffness of the bridge to be about 0.5 mN/µm. We approximate that when the sensor’s voltage change is noticeable (1–2 mV), the bender itself has already bent up to 80 nm. This theory corresponds to ≈1.6 µm of bridge bending. Thus, when the probe was positioned, the bridge was temporarily bent to 1.6 µm (note the thickness of the MG sandwich being ≈270 µm), which we have considered as an inherent and negligible probe positioning error, given the range of mechanical stimulation ranging from 20 to 70 µm.

Provided that the “bridge” is significantly wider than the area from which we have recorded, we estimated that a variation in the displacement of the bridge along the stretch of the recorded area could not exceed 1% (see below), which should not affect the results we obtained.

Distance from the Soma to the Stimulating Bridge Does Not Correlate with Sensitivity or Response Profile. The geometry of the chamber invariably results in recorded cells being situated at varying distances from the bridge. To confirm that this does not affect cellular responses, we correlated the distance of a static neuron from the bridge with the minimum bridge indentation required to evoke a threshold somatic Ca²⁺ response ($\Delta R/R_0$ threshold = 0.2). We found no correlation (Fig. S2A), suggesting that the static neurons’ sensitivity to mechanical stimuli is not dependent on their somatic distance to the bridge. In fact, none of the mechanosensitive subtypes described below showed any correlation between their response characteristics and their location in the chamber.

Estimation of Pressure Differences on Axons at Different Positions Along the Bridge. Axons grow under the bridge grossly parallel to each other and perpendicular to the bridge (Fig. S1B). Because we always captured Ca²⁺ responses from neurons situated within 0.5 × 0.5 mm² adjacent to the centrum of the spring (Fig. S1D’’’, yellow square), we reasoned that their axons situated also within the ±0.25-mm area along the central axis of the bridge. With this assumption, we estimated (Fig. S5) that difference in the thickness of the gel after compression (which presumably correlates to local pressure experienced by axons) above the middle of the bent bridge and 0.25 mm beside it does not exceed 1%. Such a difference should be considered as negligible.

Fine Aspects of Mechanical Stimulation. Our first attempts to record receptor currents (RCs) using conventional design plates failed because of the recorded cells being situated too close to the stimulus source (the bridge). At such distance, stimulation resulted in gel squeezed out from under the bridge and pressing onto the cells' somata. Recording in such conditions did not allow us to distinguish signals generated at axons from those produced by somatic stimulation. To address this issue, we introduced stretched capron fibers above and perpendicular to the proximal part of axons (Fig. S3). This modification reduced the threshold of mechanical stimuli, minimizing the gel displacement from under the bridge and allowing for artifact-free recordings from neurons proximal to the bridge. To ensure that the generated currents resulted from the stimulation on axons, and not the soma, several cells ($n = 5$) situated at the same distance from the capron fiber were recorded. Among these cells, some responded to stimulation with action potentials (APs). Among the proximal responders, not all exhibited RCs when recorded during stimulation, presumably because of longer axonal distances from the site of RC generation and to subsequent signal attenuation below acceptable signal-to-noise levels. Overall, our results help excluding the involvement of somatic mechanosensitive channel activation.

Mechanical stimuli applied to the bridge of conventional design chambers (i.e., without fibers) can result into two types of mechanical disturbances of axons: vertical compression and, possibly, longitudinal stretching. The specific effects of each on stimulation response (both in our system and in vivo) are difficult to distinguish. The presence of fibers with constant amplitude of stimulation should increase the probability of a more focal compression without

significant stretching. Because the introduction of capron fibers reduces the stimulus amplitude required to evoke reliable responses by 2- to 3-fold, the recorded neuronal response under such design is much more likely to be elicited by local focal compression stimuli. Interestingly, when being activated at lower stimulation amplitudes, the response profiles observed in plates with and without capron fibers were comparable, indicating that modes of mechanical activation of channels are similar in both cases.

Similar mechanosensitive channels can potentially exhibit different responses when activated in neuronal somata, which is largely spherical in shape, and in axons. Theoretically, differences could be caused by both extracellular matrix components and the cytoskeleton, both of which are implicated in mechanoreception (2, 3). One indication for this effect is the fact that many mechanical-sensitive units in vivo fire APs during the release phase of static indentation (4). However, corresponding RCs have not been recorded in studies where soma was stimulated by poking. In our system, we often recorded APs at the release phase of static indentation (Fig. 1E), similar to those reported ex vivo.

Increasing focal compression by introducing capron fibers also allowed us to address the question of distribution of mechanically gated channels along the axons. Plates where fibers were situated on top of proximal versus distal parts of axons demonstrated similar sensitivity profiles. This observation suggests that mechanosensitive channels are expressed along the whole length of axons and not at any specific segment, which is the case in a neuropathic/inflammatory pain model but not in a normal situation in vivo.

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