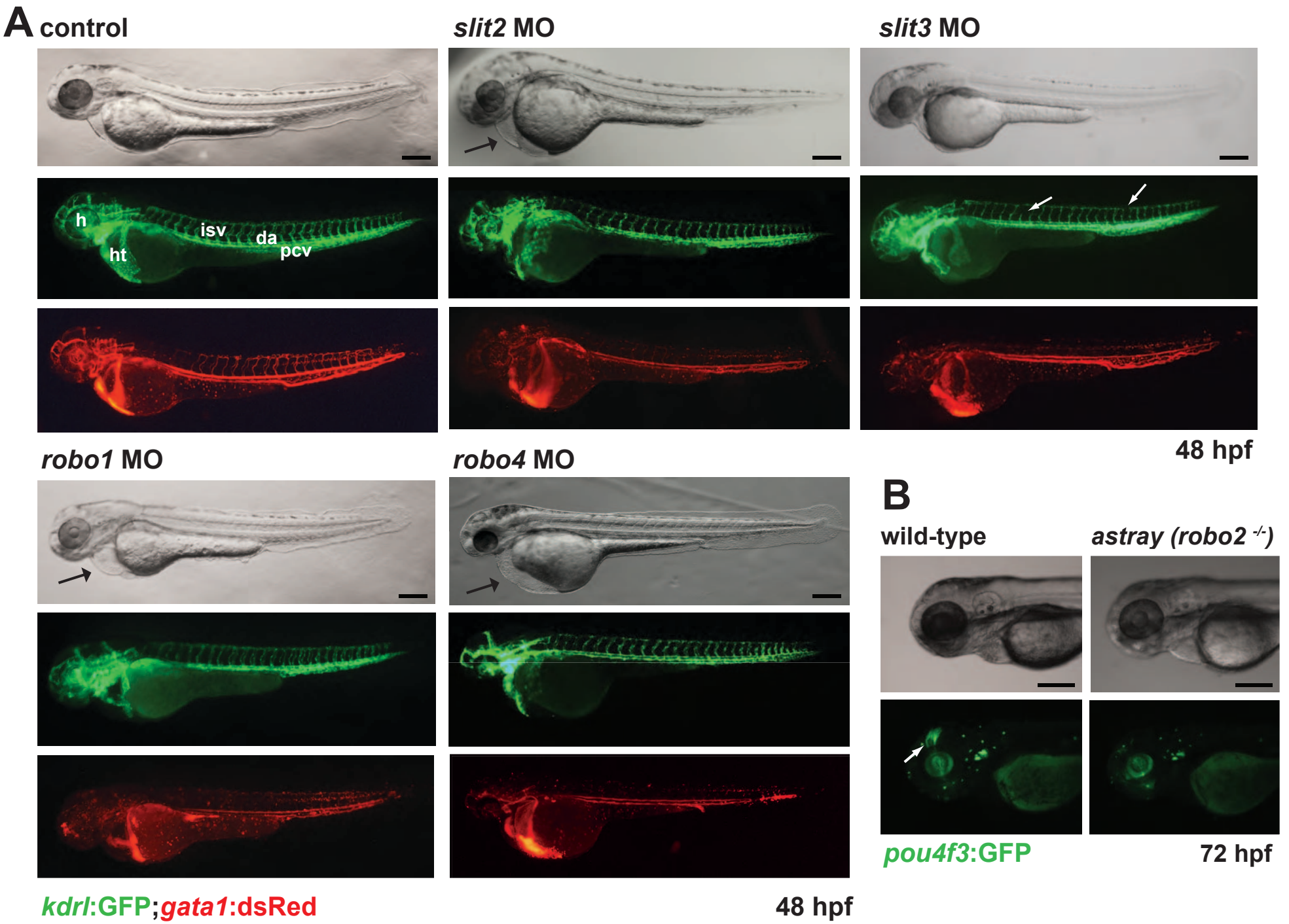
A control
slit2 MO
slit3 MO
h
ht
isv
da
pcv
48 hpf
robo1 MO
robo4 MO
kdrl:GFP;gata1:dsRed
48 hpf
B
wild-type
astray (robo2 -/-)
pou4f3:GFP
72 hpf