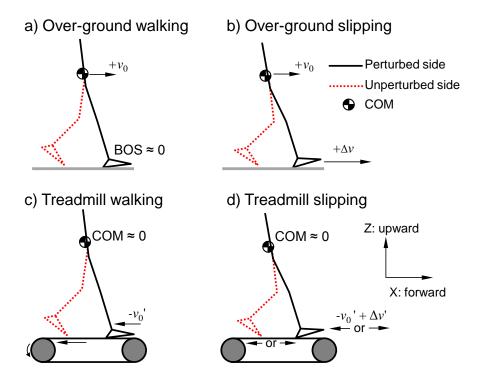
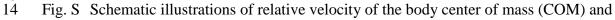
- 1 **Online Supplement**
- 2

3

## A. The mechanisms of slip induced on the treadmill

4 During over-ground walking, the velocity of the base of support (BOS) is near stationary 5 (its velocity  $\approx 0$ ) during a single stance phase, while the velocity of the body center of 6 mass (COM) is in forward direction nearly at a constant level  $(+v_0)$ . (Here the positive 7 sign for velocity means that it is in the forward direction, Fig. S-a). The relative velocity 8 between the COM and the BOS is  $+v_0 - 0 = v_0$ . In a over-ground slip, the BOS of the 9 slipping foot moves with the moveable platform carrying a forward velocity  $(+\Delta v)$  while 10 the body COM still travels with the forward velocity  $(+v_0)$  (Fig. S-b). (There is little 11 change in the absolute velocity of the COM during a slip.) The relative velocity between 12 the two is now  $+v_0 - (+\Delta v)$ , or  $v_0 - \Delta v$ . Consequently, it causes the slip disturbance of  $\Delta v$ .





- 15 base of support (BOS) during a) over-ground walking, b) over-ground slipping
- 16 perturbation, c) treadmill walking, and d) treadmill slipping perturbation.
- 17

13

1 During a treadmill walking, the body COM absolute velocity is near 0 (Fig. S-c). When 2 the treadmill belt moves in the backward direction with stance foot on top of it travelling 3 at a constant velocity ( $-v_0'$ , Fig. S-c), the relative velocity between the two is 0 - ( $-v_0'$ ) = 4  $v_0$ ' (Fig. S-c). When the moving belt suddenly gets a forward acceleration that reduces its 5 backward velocity by the amount of  $+\Delta v'$ , the belt (or BOS) velocity is now  $(-v_0' + \Delta v')$ . 6 We found that when this happens, the absolute COM velocity did little change; that it 7 remains  $\approx 0$ . The relative velocity between the two is then 0 - ( $-v_0' + \Delta v'$ ), or it is equal to  $v_0' - \Delta v'$  with a slip disturbance of  $\Delta v'$  (Fig. S-d). The treadmill velocity of  $v_0'$  has been 8 9 set in a manner comparable to average walking velocity of  $v_0$ . The treadmill belt 10 disturbance of  $\Delta v'$  has therefore an effect comparable to the slip disturbance of  $\Delta v$  during 11 over-ground walking. 12

13 B. Kinematics of slip induced on the treadmill

14 Each slip trial on treadmill always began with 1.5-s ramp up, followed by an 15 approximately 4-second, steady state, moving belt speed ( $v_0$ ) of -1.2 m/s (negative means 16 moving backward, Fig. 2c). Based on the average results of the moveable-platform kinematics during a slip (Table 2), the initial slip acceleration (a) was set at 12 m/s<sup>2</sup> in the 17 perturbation profile first used in the treadmill-slip training (Figs. 2c and 3, Table 2). The 18 19 duration ( $\Delta t$ ) was set at 0.2 s in this and in all profiles. From equation A, the final belt 20 moving speed at the end of this perturbation ( $v_f$  at instant D in Fig. 2c) was then 1.2 m/s 21 (positive means moving forward), or a *peak slip velocity equivalent* of 2.4 m/s and the 22 slip distance (l) be 0.24 m.

23

$$l = \frac{1}{2} \left( v_f - v_0 \right) \Delta t$$

$$a = \frac{v_f - v_0}{\Delta t}$$
(A)