Algorithm 1 An iterative algorithm to solve the MDGP with inaccurate data

1: procedure lsbuild(V, E, l, u) $\begin{aligned} D &= [d_{ij}] = [t_{ij}l_{ij} + (1 - t_{ij})u_{ij}], \forall (i, j) \in E; \\ \mathcal{B} &= \mathbf{cliquer}(G(V, E)); \end{aligned}$ ▷ Approximated EDM with  $t_{ij} \in [0, 1]$ 2:  $\triangleright$  Initial base (clique). 3:  $U\Sigma U^t = svd(D')$ , where  $D' = [d_{ij}], \forall (i, j) \in \mathcal{B}$ ; 4: Define  $\tilde{\Sigma}$  as the diagonal matrix with the three biggest eigenvalues of  $\Sigma$ ; 5:Define  $\tilde{U}$  as the matrix with the columns of U associated to the eigenvalues in  $\tilde{\Sigma}$ ; 6:  $x_j = [\tilde{U}\Sigma^{1/2}]_j, j \in \mathcal{B};$ 7:  $\triangleright [M]_j$  represents the *j*-th row of the matrix M. Refine  $x = [x_j], j \in \mathcal{B}$  using the model given by the eq. (3); 8:  $L = V - \mathcal{B};$  $\triangleright$  List of non fixed coordinates. 9: while L is not empty do 10:  $K = \{j \in L : \text{node } j \text{ has at least four neighbors in } \mathcal{B}\};$ 11:for  $j \in K$  do 12:Solve the linear system given by the eq. (4); 13:end for 14: $\triangleright$  Update L L = L - K;15: $\mathcal{B}=\mathcal{B}\cup K;$  $\triangleright \text{ Update } \mathcal{B}$ 16:Refine  $x = [x_j], j \in \mathcal{B}$  using the model given by the eq. (3); 17:18: end while 19: end procedure