## File S3

## **Proof of Result 3**

The asymmetric equilibrium  $(\hat{\mathbf{x}}, \hat{\mathbf{y}})$  is determined by the solutions of the quadratic equation

$$T(x;\mu_B) = (1-m)s^2x^2 - sx[s(1-m) - \mu_B(s+2)(1-2m)] - \mu_B(2m+s) = 0.$$
(S3.1)

When  $\mu_B = 0$ , equation (S3.1) reduces to

$$T(x;0) = -(1-m)s^{2}x(1-x) = 0, \qquad (S3.2)$$

giving the two solutions  $\hat{x} = 0$  and  $\hat{x} = 1$ . As  $T(0; \mu_B) < 0$ , when  $\mu_B > 0$  the solution x = 0 shifts to a negative solution of (S3.1). Hence, when  $\mu_B$  is positive and small, the positive root  $\hat{x}(\mu_B)$  of  $T(x; \mu_B) = 0$  is close to x = 1. That is, when  $\mu_B$  is small the corresponding asymmetric equilibrium is close to the fixation of AB where  $\hat{x} = \hat{y} = 1$ . Moreover, by continuity, if  $\mu_B$  is small, their stability is the same. Near fixation of AB, w = 1 - x and z = 1 - y are small, and up to non-linear terms, when  $\mu_B = 0$ , we have

$$w' = \frac{1 - m}{1 + s} w + m(s + 1)z$$

$$z' = \frac{m}{1 + s} w + (1 - m)(s + 1)z.$$
(S3.3)

The characteristic polynomial  $P(\lambda)$  of (S3.3) is

$$P(\lambda) = \lambda^2 - (1-m) \left[ (1+s) + \frac{1}{1+s} \right] \lambda + (1-2m)$$
 (S3.4)

and

$$P(1) = 1 - (1 - m)\frac{(1 + s)^2 + 1}{1 + s} + 1 - 2m.$$
(S3.5)

In fact, it can be easily seen that

$$(1+s)P(1) = -s^2(1-m). (S3.6)$$

As  $P(+\infty) > 0$  and P(1) < 0, since s > 0, 0 < m < 1,  $P(\lambda)$  has a root larger than 1. Thus, when  $\mu_B$  is small, fixation in AB is internally locally unstable and so is the asymmetric equilibrium when  $\mu_B$  is small.