## Proof of Result 1

1. When y = x, the mean fitnesses in the two demes  $E_x$  and  $E_y$  are equal:

$$w_x = 1 + sx = 1 + sy = w_y, (S1.1)$$

and, from (8), the equilibrium equation is, (with  $\mu = \mu_B$ ),

$$(1+sx)x = (1-m)\left[(1-\mu)(1+s)x + \mu(1-x)\right] + m\left[(1-\mu)(1-x) + \mu(1+s)x\right].$$
 (S1.2)

Thus

$$(1+sx)x = (1+s)x[(1-m)(1-\mu) + m\mu] + (1-x)[\mu(1-m) + m(1-\mu)], (S1.3)$$

or

$$x + sx^{2} = (1+s)x[1-m-\mu+2m\mu] + (1-x)[m+\mu-2m\mu].$$
 (S1.4)

This is equivalent to

$$Q(x) = sx^{2} + [(s+2)(m+\mu-2m\mu) - s]x - (m+\mu-2m\mu) = 0.$$
 (S1.5)

Now, as  $0 < m, \mu < 1$ , we have

$$(m + \mu - 2m\mu) = m(1 - \mu) + \mu(1 - m) > 0.$$
 (S1.6)

Therefore

$$Q(0) = -(m + \mu - 2m\mu) < 0 \tag{S1.7}$$

and

$$Q(1) = (s+1)(m+\mu - 2m\mu) > 0.$$
 (S1.8)

As  $Q(\pm \infty) > 0$ , we conclude that the equation (S1.5) has a unique root  $x^*$  with  $0 < x^* < 1$ . Thus there is a unique symmetric polymorphism  $(\mathbf{x}^*, \mathbf{y}^*)$ , given by (13).

2. Near the equilibrium  $(\mathbf{x}^*, \mathbf{y}^*)$ , on the boundary where only *B* is present, (z - x) is small, and from (10), the internal local stability of  $(\mathbf{x}^*, \mathbf{y}^*)$  in the boundary is determined by the factor

$$C^* = \frac{(1-2\mu)(1+s)}{(1+sx^*)(1+sz^*)}.$$
(S1.9)

As  $x^* = z^*$ ,  $C^* < 1$  if  $(1+s) < (1+sx^*)^2$ , and as s > 0 this is true if  $s(x^*)^2 + 2x^* > 1$ . From the equilibrium equation (S1.5), as  $Q(x^*) = 0$  we have

$$s(x^{*})^{2} + 2x^{*} = -[(s+2)(m+\mu-2m\mu)-s]x^{*} + (m+\mu-2m\mu) + 2x^{*}$$
  
= -(s+2)(m+\mu-2m\mu-1)x^{\*} + (m+\mu-2m\mu). (S1.10)

Thus  $s(x^*)^2 + 2x^* > 1$  if and only if

$$(s+2)(1-m-\mu+2m\mu)x^* > (1-m-\mu+2m\mu).$$
(S1.11)

But  $(1 - m - \mu + 2m\mu) = (1 - m)(1 - \mu) + m\mu > 0$  as  $0 < m, \mu < 1$ , and so  $C^* < 1$  provided  $\mathbf{x}^* > \frac{1}{s+2}$ . As Q(1) > 0 and  $Q(x^*) = 0$ , it is sufficient to show that  $Q(\frac{1}{s+2}) < 0$ . Indeed

$$Q\left(\frac{1}{s+2}\right) = \frac{s}{\left(s+2\right)^2} + \left[(s+2)(m+\mu-2m\mu)-s\right]\frac{1}{s+2} - (m+\mu-2m\mu)$$
$$= \frac{s}{\left(s+2\right)^2} - \frac{s}{s+2} = -\frac{s(s+1)}{\left(s+2\right)^2} < 0.$$
(S1.12)

3. We compute  $Q(\frac{1}{2})$  using (14),

$$Q\left(\frac{1}{2}\right) = \frac{s}{4} + \frac{1}{2}\left[(s+2)(m+\mu-2m\mu) - s\right] - (m+\mu-2m\mu).$$
(S1.13)

In fact,

$$Q\left(\frac{1}{2}\right) = -\frac{s}{4} \left[1 - 2(m + \mu - 2m\mu)\right].$$
 (S1.14)

But  $1 - 2(m + \mu - 2m\mu) = (1 - 2m)(1 - 2\mu) > 0$  when  $0 < m, \mu < \frac{1}{2}$ , in which case  $Q(\frac{1}{2}) < 0$  and  $x^* > \frac{1}{2}$  as Q(1) > 0.

#### Proof of Result 2

If an asymmetric polymorphism exists, then (11) holds, namely, (with  $\mu = \mu_B$ ),

$$1 + sy = \frac{(1 - 2\mu)(1 + s)}{1 + sx}.$$
 (S2.1)

That is,

$$y = \frac{s(1-x) - 2\mu(1+s)}{s(1+sx)}, \qquad 1-y = \frac{s(1+s)x + 2\mu(1+s)}{s(1+sx)}. \qquad (S2.2)$$

Substituting these relations into the equilibrium equation for x from (8), we find, after some simplification, that

$$x = \frac{1-m}{1+sx} \left[ (1-\mu)(1+s)x + \mu(1-x) \right] + \frac{m}{s} (sx+2\mu+\mu s).$$
 (S2.3)

Equation (S2.3) is equivalent to the quadratic equation

$$T(x) = (1-m)s^2x^2 - sx[s(1-m) - \mu(s+2)(1-2m)] - \mu(2m+s) = 0.$$
 (S2.4)

As  $\mu, m, s$  are positive and m < 1, we have T(0) < 0 and  $T(\pm \infty) > 0$ , implying that T(x) has two real roots, one positive and one negative. Now

$$T(1) = (1-m)s^2 - s[s(1-m) - \mu(s+2)(1-2\mu)] - \mu(2m+s)$$
  
=  $\mu[s(s+2)(1-2m) - (2m+s)].$  (S2.5)

T(1;m) is a linear function of m and

$$T(1;0) = \mu s(s+1) > 0$$
  

$$T(1;\frac{1}{2}) = -\mu(2m+s) < 0$$
  

$$T(1;m_0) = 0.$$
  
(S2.6)

Hence if  $0 < m < m_0$ , T(1;m) > 0 and a unique  $0 < \hat{x} < 1$  exists such that  $T(\hat{x}) = 0$ . In order for  $\hat{x}$  to be an equilibrium, its corresponding  $\hat{y}$  should satisfy  $0 < \hat{y} < 1$ , where

$$1 - \hat{y} = \frac{1+s}{1+s\hat{x}}\frac{s\hat{x} + 2\mu}{s}$$
(S2.7)

and  $0 < \hat{y} < 1$  if and only if

$$(1+s)(s\hat{x}+2\mu) < s(1+s\hat{x}) \tag{S2.8}$$

or

$$\hat{x} < \frac{s - 2\mu(1+s)}{s}.$$
 (S2.9)

So  $0 < \hat{x} < 1$  if  $0 < \mu < \mu_0 = \frac{1}{2} \frac{s}{s+1}$ , and  $[s - 2\mu(1+s)] > 0$ . We compute  $T(\frac{s-2\mu(1+s)}{s})$ , which equals

$$(1-m)\left[s-2\mu(1+s)\right]^2 - \left[s-2\mu(1+s)\right]\left[s(1-m)-\mu(s+2)(1-2m)\right] - \mu(2m+s).$$
(S2.10)

 $\operatorname{So}$ 

$$T\left(\frac{s-2\mu(1+s)}{s}\right) = 2\mu^2(1+s)(s+2m) + s\mu(s+2)(1-2m) - \mu(2m+s).$$
(S2.11)

But when  $0 < m < m_0$ ,

$$T(1) = s\mu(s+2)(1-2m) - \mu(2m+s) > 0, \qquad (S2.12)$$

therefore  $T\left(\frac{s-2\mu(1+s)}{s}\right) > 0$ , and (S2.9) holds.

## **Proof of Result 3**

The asymmetric equilibrium  $(\hat{\mathbf{x}}, \hat{\mathbf{y}})$  is determined by the solutions of the quadratic equation

$$T(x;\mu_B) = (1-m)s^2x^2 - sx[s(1-m) - \mu_B(s+2)(1-2m)] - \mu_B(2m+s) = 0.$$
(S3.1)

When  $\mu_B = 0$ , equation (S3.1) reduces to

$$T(x;0) = -(1-m)s^{2}x(1-x) = 0, \qquad (S3.2)$$

giving the two solutions  $\hat{x} = 0$  and  $\hat{x} = 1$ . As  $T(0; \mu_B) < 0$ , when  $\mu_B > 0$  the solution x = 0 shifts to a negative solution of (S3.1). Hence, when  $\mu_B$  is positive and small, the positive root  $\hat{x}(\mu_B)$  of  $T(x; \mu_B) = 0$  is close to x = 1. That is, when  $\mu_B$  is small the corresponding asymmetric equilibrium is close to the fixation of AB where  $\hat{x} = \hat{y} = 1$ . Moreover, by continuity, if  $\mu_B$  is small, their stability is the same. Near fixation of AB, w = 1 - x and z = 1 - y are small, and up to non-linear terms, when  $\mu_B = 0$ , we have

$$w' = \frac{1-m}{1+s}w + m(s+1)z$$

$$z' = \frac{m}{1+s}w + (1-m)(s+1)z.$$
(S3.3)

The characteristic polynomial  $P(\lambda)$  of (S3.3) is

$$P(\lambda) = \lambda^2 - (1-m) \left[ (1+s) + \frac{1}{1+s} \right] \lambda + (1-2m)$$
 (S3.4)

and

$$P(1) = 1 - (1 - m)\frac{(1 + s)^2 + 1}{1 + s} + 1 - 2m.$$
(S3.5)

In fact, it can be easily seen that

$$(1+s)P(1) = -s^2(1-m). (S3.6)$$

As  $P(+\infty) > 0$  and P(1) < 0, since s > 0, 0 < m < 1,  $P(\lambda)$  has a root larger than 1. Thus, when  $\mu_B$  is small, fixation in AB is internally locally unstable and so is the asymmetric equilibrium when  $\mu_B$  is small.

## **Proof of Result 4**

A straightforward computation shows that the  $4 \times 4$  matrix  $\mathbf{L}_{ex}$  can be written as

$$\mathbf{L}_{ex} = \begin{pmatrix} (1-m)A & (1-m)B & mC & mD \\ (1-m)D & (1-m)C & mB & mA \\ mA & mB & (1-m)C & (1-m)D \\ mD & mC & (1-m)B & (1-m)A \end{pmatrix},$$
(S4.1)

where

$$(1 + sx^*)A = (1 + s)(1 - \mu_b) + r(1 - x^*)[(s + 2)\mu_b - (s + 1)]$$

$$(1 + sx^*)B = (1 + s)rx^* + \mu_b[1 - (s + 2)rx^*]$$

$$(1 + sx^*)C = (1 - \mu_b) + rx^*[(s + 2)\mu_b - 1]$$

$$(1 + sx^*)D = (1 + s)\mu_b + r(1 - x^*)[1 - (s + 2)\mu_b].$$
(S4.2)

Observe that "formally" A, B, C, D are linear in  $\mu_b$ . Let  $A_0$  be the value of A when  $\mu_b = 0$  and  $A_1$  be its value when  $\mu_b = 1$ . Similarly we have  $B_0, B_1, C_0, C_1, D_0, D_1$ . In fact,

$$(1 + sx^{*})A_{0} = (1 + s)[1 - r(1 - x^{*})]$$

$$(1 + sx^{*})A_{1} = r(1 - x^{*})$$

$$(1 + sx^{*})B_{0} = (1 + s)rx^{*}$$

$$(1 + sx^{*})B_{1} = 1 - rx^{*}$$

$$(1 + sx^{*})C_{0} = 1 - rx^{*}$$

$$(1 + sx^{*})C_{1} = (1 + s)rx^{*}$$

$$(1 + sx^{*})D_{0} = r(1 - x^{*})$$

$$(1 + sx^{*})D_{1} = (1 + s)[1 - r(1 - x^{*})].$$
(S4.3)

As 0 < r < 1,  $0 < x^* < 1$  we have  $A_i, B_i, C_i, D_i$  positive for i = 0, 1. Hence, as A, B, C, Dare linear in  $\mu_b, A, B, C, D$  are all positive for  $0 < \mu_b < 1$ . Moreover we have

$$C_0 = B_1, \qquad C_1 = B_0, \qquad D_0 = A_1, \qquad D_1 = A_0.$$
 (S4.4)

Let  $S(\lambda) = \det(\mathbf{L}_{ex} - \lambda \mathbf{I})$  be the characteristic polynomial of  $\mathbf{L}_{ex}$ . The structure of  $\mathbf{L}_{ex}$ given in (S4.1) entails that  $S(\lambda)$  factors into the product of two quadratic polynomials  $S_1(\lambda)$  and  $S_2(\lambda)$ :

$$S(\lambda) = S_1(\lambda)S_2(\lambda), \qquad (S4.5)$$

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where

$$S_{1}(\lambda) = \lambda^{2} - \lambda [(1-m)(A+C) + m(B+D)] + (1-2m)(AC - BD)$$
  

$$S_{2}(\lambda) = \lambda^{2} - \lambda [(1-m)(A+C) - m(B+D)] + (1-2m)(AC - BD).$$
(S4.6)

See Balkau and Feldman (1973) for analogous calculations with migration modification. Consider first the roots of  $S_1(\lambda) = 0$ . These are real since the discriminant of  $S_1(\lambda) = 0$ is

$$\left[ (1-m)(A+C) + m(B+D) \right]^2 - 4(1-2m)(AC - BD) = \\ = \left[ (1-m)(A-C) + m(B-D) \right]^2 + 4m(1-m)(AD + BC) + 4(1-m)^2BD + 4m^2AC, \\ (S4.7)$$

which is positive since A, B, C, D are positive and 0 < m < 1.

In addition,

$$AC - BD = \left[ (1 - \mu_b) A_0 + \mu_b A_1 \right] \left[ (1 - \mu_b) (C_0 + \mu_b C_1) \right] - \left[ (1 - \mu_b) B_0 + \mu_b B_1 \right] \left[ (1 - \mu_b) D_0 + \mu_b D_1 \right].$$
(S4.8)

Since  $C_0 = B_1$ ,  $C_1 = B_0$ ,  $D_0 = A_1$ ,  $D_1 = A_0$ , (S4.8) reduces to

$$AC - BD = (1 - 2\mu_b)(A_0B_1 - A_1B_0).$$
(S4.9)

Substituting  $A_0, A_1, B_0, B_1$  from (S4.3) we have

$$(1 + sx^*)^2 (AC - BD) = (1 - 2\mu_b)(1 + s)(1 - r).$$
 (S4.10)

Since we assume 0 < m,  $\mu_b < \frac{1}{2}$ , the two roots of  $S_1(\lambda) = 0$  are positive. Both of these roots are less than 1 if and only if  $S_1(1) > 0$  and  $S'_1(1) > 0$ .

$$S'_{1}(1) = 2 - \left[ (1-m)(A+C) + m(B+D) \right].$$
(S4.11)

As  $C_0 = B_1, C_1 = B_0, D_0 = A_1, D_1 = A_0$ , we have

$$(A+C) = (1-\mu_b)(A_0+C_0) + \mu_b(A_1+C_1)$$
  
= (1-\mu\_b)(A\_0+C\_0) + \mu\_b(B\_0+D\_0), (S4.12)

$$(B+D) = (1-\mu_b)(B_0+D_0) + \mu_b(B_1+D_1)$$
  
=  $(1-\mu_b)(B_0+D_0) + \mu_b(A_0+C_0).$  (S4.13)

Hence,

$$(1-m)(A+C) + m(B+D) = (1-m_b)(A_0 + C_0) + m_b(B_0 + D_0), \qquad (S4.14)$$

where

$$m_b = m + \mu_b - 2m\mu_b. (S4.15)$$

Substituting for  $A_0, B_0, C_0, D_0$ , gives

$$S_1'(1) = (1 + sx^*)^{-1} [r + rsx^* + s(1 - r)(2x^* - 1) + m_b(1 - r)(s + 2)].$$
(S4.16)

Now s > 0, 0 < r < 1,  $m_b = m(1 - \mu_b) + \mu_b(1 - m) > 0$ , and  $x^* > \frac{1}{2}$  if 0 < m,  $\mu_B < \frac{1}{2}$ . Therefore S'(1) > 0 provided 0 < m,  $\mu_B < \frac{1}{2}$ . Using (S4.11) and (S4.16) it is easily seen that S(1) > 0 if

$$(1+sx^*)^{-2}(1-r)\left\{(x^*)^2s^2+sx^*\left[-s+m_b(s+2)\right]-sm_b\right\}>0.$$
 (S4.17)

Using the equation  $Q(x^*) = 0$  from (14), we have

$$s(x^*)^2 + [(s+2)m_B - s]x^* - m_B = 0, \qquad (S4.18)$$

where

$$m_B = m + \mu_B - 2m\mu_B. \tag{S4.19}$$

Therefore (S4.17) is satisfied if and only if

$$(m_b - m_B)(1 + sx^*)^{-2}(1 - r)s[x^*(2 + s) - 1] > 0.$$
 (S4.20)

As  $x^* > \frac{1}{2}$ , by Result 1, and  $0 < m < \frac{1}{2}$ , (S4.20) holds if and only if  $m_b > m_B$ , which is true if and only if  $\mu_b > \mu_B$ .

It is not obvious that the roots of  $S_2(\lambda) = 0$  are real. However, as the matrix  $\mathbf{L}_{ex}^*$  is positive, the Perron-Frobenius theory ensures that its largest eigenvalue in magnitude is positive. Therefore we just have to ensure that when both eigenvalues are real and positive they are less than 1; when they are real, both are positive or both are negative

since  $(1-2m)(1-2\mu_b)(AC-BD)$  is positive for 0 < m,  $\mu_b < \frac{1}{2}$ . The conditions for this are that both  $S_2(1)$  and  $S'_2(1)$  are positive. But

$$S_{2}(1) = 1 - [(1 - m)(A + C) - m(B + D)] + (1 - 2m)(AC - BD)$$
  
> 1 - [(1 - m)(A + C) + m(B + D)] + (1 - 2m)(AC - BD) = S\_{1}(1), (S4.21)

and  $S_1(1) > 0$  when 0 < m,  $\mu_b < \frac{1}{2}$  and  $\mu_b > \mu_B$ , so also  $S_2(1) > 0$ . Similarly

$$S'_{2}(1) = 2 - \left[ (1 - m)(A + C) - m(B + D) \right]$$
  
> 2 - \left[ (1 - m)(A + C) + m(B + D) \right] = S'\_{1}(1). (S4.22)

Thus, when  $S'_1(1) > 0$  also  $S'_2(1) > 0$ .

#### **Proof of Result 5**

At a symmetric equilibrium y = x, and also, by (32),  $\tilde{y} = \tilde{x}$ . Thus (30) and (31) imply that

$$\tilde{x} = \frac{\left[(s+1)(1-m_B) - m_B\right]x + m_B}{sx+1}$$
(S5.1)

and

$$x = \frac{\left[(1 - m_B) - m_B(s+1)\right]\tilde{x} + m_B(1+s)}{(1+s) - s\tilde{x}}.$$
 (S5.2)

Substituting (S5.1) into (S5.2) gives the quadratic equation

$$(s+2)m_B\left\{sx^2 + \left[2 - m_B(s+2)\right]x - (1 - m_B)\right\} = 0.$$
 (S5.3)

As  $0 < m, \mu_B < 1$ , s > 0 and  $m_B = m(1 - \mu_B) + \mu_B(1 - m) > 0$ , x satisfies the equation R(x) = 0 with R(x) given in (36). As  $0 < m_B < 1$  we have R(0) < 0, and as  $R(\pm \infty) > 0$ , R(x) = 0 has two real roots, one positive and one negative. Observe that

$$R(1) = s + [2 - m_B(s+2)] - (1 - m_B) = (1 - m_B)(s+1) > 0$$
 (S5.4)

and

$$R\left(\frac{1}{2}\right) = \frac{s}{4} + \frac{1}{2} \cdot \left[2 - m_B(s+2)\right] - (1 - m_B) = \frac{s}{4}(1 - 2m)(1 - 2\mu_B) \tag{S5.5}$$

as  $1 - 2m_B = 1 - 2m - 2\mu_B + 4m\mu_B = (1 - 2m)(1 - 2\mu_B)$ . Therefore when  $0 < m, \mu_B < \frac{1}{2}$  we have  $R(\frac{1}{2}) > 0$  and  $0 < \bar{x} < \frac{1}{2}$ .

## **Proof of Result 6**

In view of (33), the symmetric equilibrium  $(\bar{\mathbf{x}}, \bar{\mathbf{y}})$  is internally stable if

$$\frac{(1-2\mu)^2(1+s)^2}{(1+s\bar{x})^2 \left[1+s(1-\bar{x})\right]^2} < 1,$$
(S6.1)

as  $\bar{x} = \bar{y}$  and  $\tilde{x} = \tilde{y}$ , where, by (S5.1)

$$\tilde{x} = \frac{\left[(s+1)(1-m_B) - m_B\right]\bar{x} + m_B}{s\bar{x} + 1}.$$
(S6.2)

Thus

$$1 + s(1 - \tilde{x}) = (1 + s) - s \cdot \frac{\left[(1 + s) - m_B(2 + s)\right]\bar{x} + m_B}{s\bar{x} + 1}.$$
 (S6.3)

Hence

$$(1+s\bar{x})[1+s(1-\tilde{x})] = (1+s)(1+s\bar{x}) - s[(1+s) - m_B(s+2)]\bar{x} - sm_B, \quad (S6.4)$$

or

$$(1+s\bar{x})[1+s(1-\tilde{x})] = (1+s) + sm_B[(s+2)\bar{x}-1].$$
(S6.5)

For condition (S6.1) to be satisfied, since  $(1 + s\bar{x})[1 + s(1 - \tilde{x})] > 0$ , it is sufficient that

$$(1+s) + sm_B[(s+2)\bar{x} - 1] > (1+s), \qquad (S6.6)$$

or that  $\bar{x} > \frac{1}{s+2}$ . But

$$R\left(\frac{1}{s+2}\right) = \frac{s}{\left(s+2\right)^2} + \left[2 - m_B(s+2)\right]\frac{1}{s+2} - (1 - m_B),\tag{S6.7}$$

or

$$R\left(\frac{1}{s+2}\right) = \frac{s}{\left(s+2\right)^2} + \frac{2}{s+2} - 1 = -\frac{s(1+s)}{\left(s+2\right)^2} < 0.$$
 (S6.8)

Thus  $R(\frac{1}{s+2}) < 0$  and R(1) > 0, and so  $\bar{x} > \frac{1}{s+2}$  as desired.

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## Proof of Result 7

As the transformation T of the population state is  $T = T_2 \circ T_1$ , where  $T_i$  corresponds to phase i, with selection of type i, for i = 1, 2, and as  $\tilde{\mathbf{x}} = T_1 \bar{\mathbf{x}}$ ,  $\bar{\mathbf{x}} = T_2 \tilde{\mathbf{x}}$ , following the analysis for the case without cycles, the linear approximation matrix  $\mathbf{L}_{ex}$  becomes

$$\mathbf{L}_{\mathrm{ex}} = \mathbf{L}_{\mathrm{ex}}^2 \cdot \mathbf{L}_{\mathrm{ex}}^1, \tag{S7.1}$$

where, as in (S4.1) and (S4.2), we have

$$\mathbf{L}_{ex}^{1} = \begin{pmatrix} (1-m)\bar{A} & (1-m)\bar{B} & m\bar{C} & m\bar{D} \\ (1-m)\bar{D} & (1-m)\bar{C} & m\bar{B} & m\bar{A} \\ m\bar{A} & m\bar{B} & (1-m)\bar{C} & (1-m)\bar{D} \\ m\bar{D} & m\bar{C} & (1-m)\bar{B} & (1-m)\bar{A} \end{pmatrix}, \qquad (S7.2)$$
$$\mathbf{L}_{ex}^{2} = \begin{pmatrix} (1-m)\tilde{A} & (1-m)\tilde{B} & m\tilde{C} & m\tilde{D} \\ (1-m)\tilde{D} & (1-m)\tilde{C} & m\tilde{B} & m\tilde{A} \\ (1-m)\tilde{D} & (1-m)\tilde{C} & m\tilde{B} & m\tilde{A} \\ m\tilde{A} & m\tilde{B} & (1-m)\tilde{C} & (1-m)\tilde{D} \\ m\tilde{D} & m\tilde{C} & (1-m)\tilde{B} & (1-m)\tilde{A} \end{pmatrix}, \qquad (S7.3)$$

and

$$(1+s\bar{x})\overline{A} = (1+s)(1-\mu_b) + r(1-\bar{x})[(s+2)\mu_b - (s+1)]$$

$$(1+s\bar{x})\overline{B} = (1+s)r\bar{x} + \mu_b[1-(s+2)r\bar{x}]$$

$$(1+s\bar{x})\overline{C} = (1-\mu_b) + r\bar{x}[(s+2)\mu_b - 1]$$

$$(1+s\bar{x})\overline{D} = (1+s)\mu_b + r(1-\bar{x})[1-(s+2)\mu_b],$$
(S7.4)

$$\begin{bmatrix} 1 + s(1 - \tilde{x}) \end{bmatrix} \widetilde{A} = (1 - \mu_b) + r(1 - \tilde{x}) \begin{bmatrix} (2 + s)\mu_b - 1 \end{bmatrix}$$
  

$$\begin{bmatrix} 1 + s(1 - \tilde{x}) \end{bmatrix} \widetilde{B} = (1 + s)\mu_b + r\tilde{x} \begin{bmatrix} 1 - (s + 2)\mu_b \end{bmatrix}$$
  

$$\begin{bmatrix} 1 + s(1 - \tilde{x}) \end{bmatrix} \widetilde{C} = (1 + s)(1 - \mu_b) + r\tilde{x} \begin{bmatrix} (s + 2)\mu_b - (s + 1) \end{bmatrix}$$
  

$$\begin{bmatrix} 1 + s(1 - \tilde{x}) \end{bmatrix} \widetilde{D} = \mu_b + r(1 - \tilde{x}) \begin{bmatrix} (s + 1) - (s + 2)\mu_b \end{bmatrix}.$$
  
(S7.5)

When we multiply  $\mathbf{L}_{ex}^2$  by  $\mathbf{L}_{ex}^1$  we find that the product  $\mathbf{L}_{ex}$  has the following structure:

$$\mathbf{L}_{\mathrm{ex}} = \begin{pmatrix} a & e & h & d \\ b & f & g & c \\ c & g & f & b \\ d & h & e & a \end{pmatrix}, \qquad (S7.6)$$

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where

$$a = (1 - m)^{2} \widetilde{A} \overline{A} + (1 - m)^{2} \widetilde{B} \overline{D} + m^{2} \widetilde{C} \overline{A} + m^{2} \widetilde{D} \overline{D}$$

$$b = (1 - m)^{2} \widetilde{D} \overline{A} + (1 - m)^{2} \widetilde{C} \overline{D} + m^{2} \widetilde{B} \overline{A} + m^{2} \widetilde{A} \overline{D}$$

$$c = m(1 - m) \left[ \widetilde{A} \overline{A} + \widetilde{B} \overline{D} + \widetilde{C} \overline{A} + \widetilde{D} \overline{D} \right]$$

$$d = m(1 - m) \left[ \widetilde{D} \overline{A} + \widetilde{C} \overline{D} + \widetilde{B} \overline{A} + \widetilde{A} \overline{D} \right]$$

$$e = (1 - m)^{2} \widetilde{A} \overline{B} + (1 - m)^{2} \widetilde{B} \overline{C} + m^{2} \widetilde{C} \overline{B} + m^{2} \widetilde{D} \overline{C}$$

$$f = (1 - m)^{2} \widetilde{D} \overline{B} + (1 - m)^{2} \widetilde{C} \overline{C} + m^{2} \widetilde{B} \overline{B} + m^{2} \widetilde{A} \overline{C}$$

$$g = m(1 - m) \left[ \widetilde{A} \overline{B} + \widetilde{B} \overline{C} + \widetilde{C} \overline{B} + \widetilde{D} \overline{C} \right]$$

$$h = m(1 - m) \left[ \widetilde{D} \overline{B} + \widetilde{C} \overline{C} + \widetilde{B} \overline{B} + \widetilde{A} \overline{C} \right].$$
(S7.7)

Let  $D(\lambda) = \det(\mathbf{L}_{ex} - \lambda \mathbf{I})$  be the characteristic polynomial of  $\mathbf{L}_{ex}$ . From (S7.6),  $D(\lambda)$  factors into  $2 \times 2$  determinants:

$$D(\lambda) = \begin{vmatrix} a+d-\lambda & e+h & 0 & 0\\ b+c & f+g-\lambda & 0 & 0\\ c & g & f-g-\lambda & b-c\\ d & h & e-h & a-d-\lambda \end{vmatrix}.$$
 (S7.8)

Therefore  $D(\lambda)$  can be written

$$D(\lambda) = D_1(\lambda)D_2(\lambda), \qquad (S7.9)$$

where

$$D_1(\lambda) = \lambda^2 - (a+d+f+g)\lambda + (a+d)(f+g) - (b+c)(e+h)$$
  

$$D_2(\lambda) = \lambda^2 - (a-d+f-g)\lambda + (a-d)(f-g) - (b-c)(e-h).$$
(S7.10)

As 0 < m < 1 and  $\overline{A}, \overline{B}, \overline{C}, \overline{D}$  and  $\widetilde{A}, \widetilde{B}, \widetilde{C}, \widetilde{D}$  are all positive, the matrix  $\mathbf{L}_{ex}$  is a positive matrix and its largest eigenvalue in magnitude is positive. Observe that the discriminant of  $D_1(\lambda)$  is

$$(a+d+f+g)^{2} - 4[(a+d)(f+g) - (b+c)(e+h)], \qquad (S7.11)$$

which is positive and equal to

$$[(a+d) - (f+g)]^2 + 4(b+c)(e+h).$$
(S7.12)

In addition, (a + d + f + g) is positive. Therefore  $D_1(\lambda)$  has real roots, and its largest root in magnitude is positive. Thus this positive root is less than 1 if  $D_1(1) > 0$  and  $D'_1(1) > 0$ .

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As the largest eigenvalue of  $\mathbf{L}_{ex}$  is positive, for stability of  $(\bar{\mathbf{x}}, \bar{\mathbf{y}})$  we require that if the eigenvalues associated with  $D_2(\lambda)$  are real and at least one is positive, they are both less than 1. Again the conditions for this are  $D_2(\lambda) > 0$  and  $D'_2(1) > 0$ . Observe that

$$D'_{1}(1) = 2 - (a + d + f + g)$$
  

$$D'_{2}(1) = 2 - (a - d + f - g) = D'_{1}(1) + 2(d + g) > D'_{1}(1).$$
(S7.13)

In view of (S7.13), for the largest eigenvalue of  $\mathbf{L}_{ex}$  to be less than one, we require

$$D_1(1) > 0, \qquad D'_1(1) > 0, \qquad D_2(1) > 0.$$
 (S7.14)

We now compute the constant terms of  $D_1(\lambda)$  and  $D_2(\lambda)$ . We already know, based on the properties of the matrices  $\mathbf{L}_{ex}^1$  and  $\mathbf{L}_{ex}^2$  that the constant terms of both  $D_1(\lambda)$  and  $D_2(\lambda)$ are the same and are equal to

$$(1-2m)^2 \left(\overline{A}\,\overline{C} - \overline{B}\,\overline{D}\right) \left(\widetilde{A}\widetilde{C} - \widetilde{B}\widetilde{D}\right). \tag{S7.15}$$

With the same technique used to compute (S4.10), we deduce that

$$(1+s\overline{x})^2 \left(\overline{A}\,\overline{C} - \overline{B}\,\overline{D}\right) = (1-2\mu_b)\,(1+s)(1-r),\tag{S7.16}$$

and similarly

$$[1 + s(1 - \tilde{x})]^2 \left( \widetilde{A}\widetilde{C} - \widetilde{B}\widetilde{D} \right) = (1 - 2\mu_b)(1 + s)(1 - r).$$
 (S7.17)

Therefore the constant terms of both  $D_1(\lambda)$  and  $D_2(\lambda)$  are the same and are equal to

$$(1-2m)^{2} (1-2\mu_{b})^{2} (1+s\bar{x})^{-2} [1+s(1-\tilde{x})]^{-2} (1+s)^{2} (1-r)^{2}, \qquad (S7.18)$$

which is positive, and so  $D_1(\lambda)$  has two positive roots. Also, as a, b, c, d are all positive,

$$D_{2}(1) = 1 - (a - d + f - g) + (a - d)(f - g) - (b - c)(e - h)$$
  
> 1 - (a + d + f + g) + (a + d)(f + g) - (b + c)(e + h) = D\_{1}(1). (S7.19)

Hence for the symmetric equilibrium to be externally stable, we require that  $D_1(1)$  and  $D'_1(1)$  are both positive.

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Now from (S6.5) we know that

$$(1+s\bar{x})[1+s(1-\tilde{x})] = (1+s) + sm_B[(s+2)\bar{x}-1].$$
(S7.20)

As  $\bar{x} > \frac{1}{s+2}$  we have

$$(1+s\bar{x})\left[1+s\left(1-\tilde{x}\right)\right] > (1+s). \tag{S7.21}$$

Thus the equal constant terms of  $D_1(\lambda)$  and  $D_2(\lambda)$  given in (S7.18) are positive and less than 1. As a result it is impossible for the two positive roots of  $D_1(\lambda)$  to both be larger than 1, and they are both less than 1 provided  $D_1(1) > 0$ . Hence the external stability of the symmetric equilibrium requires that

$$D_1(1) = 1 - (a + d + f + g) + (a + d)(f + g) - (b + c)(e + h)$$
(S7.22)

is positive (the last summand in (S7.22) is given in (S7.18)). We now compute a+d+f+g.

Computation of (a + d + f + g)

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We have

$$(a+d+f+g) = \left[ (1-m)^2 \widetilde{A} + m^2 \widetilde{C} + m(1-m) \left( \widetilde{B} + \widetilde{D} \right) \right] \overline{A} + \left[ (1-m)^2 \widetilde{C} + m^2 \widetilde{A} + m(1-m) \left( \widetilde{B} + \widetilde{D} \right) \right] \overline{C} + \left[ (1-m)^2 \widetilde{B} + m^2 \widetilde{D} + m(1-m) \left( \widetilde{A} + \widetilde{C} \right) \right] \overline{D} + \left[ (1-m)^2 \widetilde{D} + m^2 \widetilde{B} + m(1-m) \left( \widetilde{A} + \widetilde{C} \right) \right] \overline{B}.$$
(S7.23)

As  $\overline{A}, \overline{B}, \overline{C}, \overline{D}$  and also  $\widetilde{A}, \widetilde{B}, \widetilde{C}, \widetilde{D}$  given in (S7.4) and (S7.5), respectively, are all linear functions of  $\mu_b$ , where  $0 \le \mu_b \le 1$ , we can represent them as  $\overline{A} = (1 - \mu_b)\overline{A}_0 + \mu_b\overline{A}_1$ , etc. Hence

$$(1+s\bar{x})\overline{A}_{0} = (1+s) [1-r(1-\bar{x})] = (1+s\bar{x})\overline{D}_{1}$$

$$(1+s\bar{x})\overline{B}_{0} = (1+s)r\bar{x} = (1+s\bar{x})\overline{C}_{1}$$

$$(1+s\bar{x})\overline{C}_{0} = 1-r\bar{x} = (1+s\bar{x})\overline{B}_{1}$$

$$(1+s\bar{x})\overline{D}_{0} = r(1-\bar{x}) = (1+s\bar{x})\overline{A}_{1},$$

$$[1+s(1-\tilde{x})] \widetilde{A}_{o} = 1-r(1-\tilde{x}) = [1+s(1-\tilde{x})] \widetilde{D}_{1}$$

$$[1+s(1-\tilde{x})] \widetilde{B}_{o} = r\bar{x} = [1+s(1-\tilde{x})] \widetilde{C}_{1}$$

$$[1+s(1-\tilde{x})] \widetilde{C}_{o} = (1+s) [1-r\tilde{x}] = [1+s(1-\tilde{x})] \widetilde{B}_{1}$$

$$[1+s(1-\tilde{x})] \widetilde{D}_{o} = (1+s)r(1-\tilde{x}) = [1+s(1-\tilde{x})] \widetilde{A}_{1}.$$

$$(S7.25)$$

$$[1+s(1-\tilde{x})] \widetilde{D}_{o} = (1+s)r(1-\tilde{x}) = [1+s(1-\tilde{x})] \widetilde{A}_{1}.$$

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Since

$$m_b = m + \mu_b - 2m\mu_b = m(1 - \mu_b) + \mu_b(1 - m)$$
  

$$1 - m_b = 1 - m - \mu_b + 2m\mu_b = (1 - m)(1 - \mu_b),$$
(S7.26)

we can write

$$(a+d+f+g) = \left[ (1-m)(1-m_b)\tilde{A}_0 + (1-m)m_b\tilde{D}_0 + m(1-m_b)\tilde{B}_0 + m \cdot m_b\tilde{C}_0 \right] \overline{A} \\ + \left[ (1-m)(1-m_b)\tilde{C}_0 + (1-m)m_b\tilde{B}_0 + m(1-m_b)\tilde{D}_0 + m \cdot m_b\tilde{A}_0 \right] \overline{C} \\ + \left[ (1-m)(1-m_b)\tilde{B}_0 + (1-m)m_b\tilde{C}_0 + m(1-m_b)\tilde{A}_0 + m \cdot m_b\tilde{D}_0 \right] \overline{D} \\ + \left[ (1-m)(1-m_b)\tilde{D}_0 + (1-m)m_b\tilde{A}_0 + m(1-m_b)\tilde{C}_0 + m \cdot m_b\tilde{B}_0 \right] \overline{B}.$$
(S7.27)

Substitute into (S7.27)

$$\overline{A} = (1 - \mu_b)\overline{A}_0 + \mu_b\overline{D}_0, \qquad \overline{B} = (1 - \mu_b)\overline{B}_0 + \mu_b\overline{C}_0,$$
  

$$\overline{C} = (1 - \mu_b)\overline{C}_0 + \mu_b\overline{B}_0, \qquad \overline{D} = (1 - \mu_b)\overline{D}_0 + \mu_b\overline{A}_0,$$
(S7.38)

to obtain

$$(a+d+f+g) = (1-m_b)^2 \left[ \widetilde{A}_0 \overline{A}_0 + \widetilde{B}_0 \overline{D}_0 + \widetilde{C}_0 \overline{C}_0 + \widetilde{D}_0 \overline{B}_0 \right] + m_b (1-m_b) \left[ \left( \widetilde{B}_0 + \widetilde{D}_0 \right) \left( \overline{A}_0 + \overline{C}_0 \right) + \left( \widetilde{A}_0 + \widetilde{C}_0 \right) \left( \overline{B}_0 + \overline{D}_0 \right) \right] + m_b^2 \left[ \widetilde{A}_0 \overline{C}_0 + \widetilde{B}_0 \overline{B}_0 + \widetilde{C}_0 \overline{A}_0 + \widetilde{D}_0 \overline{D}_0 \right].$$

$$(S7.29)$$

Equation (S7.29) can also be written as

$$(a+d+f+g) = (1-2m_b) \left[ \widetilde{A}_0 \overline{A}_0 + \widetilde{B}_0 \overline{D}_0 + \widetilde{C}_0 \overline{C}_0 + \widetilde{D}_0 \overline{B}_0 \right] + m_b \left[ \left( \widetilde{B}_0 + \widetilde{D}_0 \right) \left( \overline{A}_0 + \overline{C}_0 \right) + \left( \widetilde{A}_0 + \widetilde{C}_0 \right) \left( \overline{B}_0 + \overline{D}_0 \right) \right] + m_b^2 \left[ \left( \widetilde{A}_0 + \widetilde{C}_0 \right) \left( \overline{A}_0 + \overline{C}_0 \right) + \left( \widetilde{B}_0 + \widetilde{D}_0 \right) \left( \overline{B}_0 + \overline{D}_0 \right) - \left( \widetilde{A}_0 + \widetilde{C}_0 \right) \left( \overline{B}_0 + \overline{D}_0 \right) + \left( \widetilde{B}_0 + \widetilde{D}_0 \right) \left( \overline{A}_0 + \overline{C}_0 \right) \right],$$

$$(S7.30)$$

or as

$$(a+d+f+g) = (1-2m_b) \left[ \widetilde{A}_0 \overline{A}_0 + \widetilde{B}_0 \overline{D}_0 + \widetilde{C}_0 \overline{C}_0 + \widetilde{D}_0 \overline{B}_0 \right] + m_b \left[ \left( \widetilde{B}_0 + \widetilde{D}_0 \right) \left( \overline{A}_0 + \overline{C}_0 \right) + \left( \widetilde{A}_0 + \widetilde{C}_0 \right) \left( \overline{B}_0 + \overline{D}_0 \right) \right] + m_b^2 \left( \widetilde{A}_0 + \widetilde{C}_0 - \widetilde{B}_0 - \widetilde{D}_0 \right) \left( \overline{A}_0 + \overline{C}_0 - \overline{B}_0 - \overline{D}_0 \right).$$
(S7.31)

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From (S7.24) and (S7.25),

$$(1+s\bar{x})[1+s(1-\tilde{x})]\left[\tilde{A}_{0}\bar{A}_{0}+\tilde{B}_{0}\bar{D}_{0}+\tilde{C}_{0}\bar{C}_{0}+\tilde{D}_{0}\bar{D}_{0}\right] = (1+s)\left[2(1-r)+r^{2}\right]+r^{2}s(s+1)\bar{x}-r^{2}s\tilde{x}-r^{2}s^{2}\bar{x}\tilde{x},$$
(S7.32)

$$(1+s\bar{x})[1+s(1-\tilde{x})]\left[\left(\tilde{B}_{0}+\tilde{D}_{0}\right)(\bar{A}_{0}+\bar{C}_{0})+\left(\tilde{A}_{0}+\tilde{C}_{0}\right)(\bar{B}_{0}+\bar{D}_{0})\right]=2r^{2}(1+s\bar{x})[1+s(1-\bar{x})]+r(1-r)(s+2)\left[(s+2)+s\left(\bar{x}-\tilde{x}\right)\right],(S7.33)$$

$$(1+s\overline{x})[1+s(1-\widetilde{x})]\left(\widetilde{A}_0+\widetilde{C}_0-\widetilde{B}_0-\widetilde{D}_0\right)\left(\overline{A}_0+\overline{C}_0-\overline{B}_0-\overline{D}_0\right) = (s+2)^2(1-r)^2.$$
(S7.34)

Remember that by (S7.18)

$$(1+s\bar{x})^{2} [1+(1-\tilde{x})]^{2} [(a+d)(f+g)-(b+c)(e+h)] =$$
  
=  $(1-2m)^{2} (1-2\mu_{b})^{2} (s+1)^{2} (1-r)^{2}.$  (S7.35)

But

$$(1-2m)(1-2\mu_b) = 1 - 2(m+\mu_b - 2m\mu_b) = 1 - 2m_b.$$
 (S7.36)

Therefore

$$(1+s\bar{x})^{2} [1+(1-\tilde{x})]^{2} [(a+d)(f+g) - (b+c)(e+h)] =$$

$$= (1-2m_{b})^{2} (s+1)^{2} (1-r)^{2}.$$
(S7.37)

Combining all of this, we get that  $D_1(1) = 1 - (a+d+f+g) + (a+d)(f+g) - (b+c)(e+h)$ , which we compute as

$$1 - (1 - 2m_b) \frac{(1+s) \left[2(1-r) + r^2\right] + r^2 s(s+1)\bar{x} - r^2 s \tilde{x} - r^2 s^2 \bar{x} \tilde{x}}{(1+s\bar{x})[1+s(1-\tilde{x})]} - m_b \frac{2r^2(1+s\bar{x})[1+s(1-\tilde{x})] + r(1-r)(s+2)[(s+2) + s(\bar{x}-\tilde{x})]}{(1+s\bar{x})[1+s(1-\tilde{x})]} - m_b^2 \frac{(s+2)^2 (1-r)^2}{(1+s\bar{x})[1+s(1-\tilde{x})]} + \frac{(1-2m_b)^2 (s+1)^2 (1-r)^2}{(1+s\bar{x})^2 [1+s(1-\tilde{x})]^2}.$$
(S7.38)

Observe that

$$r^{2}[(1+s) + s(s+1)\bar{x} - s\tilde{x} - s^{2}\bar{x}\tilde{x}] = r^{2}(1+s\bar{x})[1+s(1-\tilde{x})], \qquad (S7.39)$$

so (S7.38) simplifies to

$$1 - r^{2} - (1 - 2m_{b})\frac{2(1+s)(1-r)}{(1+s\bar{x})[1+s(1-\tilde{x})]} - m_{b}\frac{r(1-r)(s+2)[(s+2)+s(\bar{x}-\tilde{x})]}{(1+s\bar{x})[1+s(1-\tilde{x})]} - m_{b}^{2}\frac{(s+2)^{2}(1-r)^{2}}{(1+s\bar{x})[1+s(1-\tilde{x})]} + \frac{(1-2m_{b})^{2}(s+1)^{2}(1-r)^{2}}{(1+s\bar{x})^{2}[1+s(1-\tilde{x})]^{2}}.$$
(S7.40)

Clearly  $D_1(1)$  of (S7.40) has a factor of (1 - r), and in fact

$$D_1(1) = (1 - r)f(r), (S7.41)$$

where f(r) is a linear function of r, for  $0 \le r \le 1$ . Now

$$f(1) = 2 - (1 - 2m_b) \frac{2(1+s)}{(1+s\bar{x})[1+s(1-x)]} - m_b \frac{(s+2)[(s+2)+s(\bar{x}-\tilde{x})]}{(1+s\bar{x})[1+s(1-\tilde{x})]}.$$
 (S7.42)

Following (S6.7) we have

$$(1+s\bar{x})[1+s(1-\tilde{x})] = (1+s) + sm_B[(s+2)\bar{x}-1].$$
(S7.43)

We also have an equivalent expression for (S7.43) in terms of  $\tilde{x}$ , namely

$$(1+s\bar{x})[1+s(1-\tilde{x})] = (1+s) + sm_B[(s+1) - (s+2)\tilde{x}].$$
(S7.44)

Also, whereas  $\bar{x} > \frac{1}{s+2}$ , we have  $\tilde{x} < \frac{s+1}{s+2}$ . Applying all of this to (S7.42) and using the fact that

$$(1+s\bar{x})[1+s(1-\tilde{x})] = (1+s) + \frac{1}{2}sm_B[s+(s+2)(\bar{x}-\tilde{x})], \qquad (S7.45)$$

we get that

$$(1+s\bar{x})[1+s(1-\tilde{x})]f(1) = 2(s+1) + sm_B[s+(s+2)(\bar{x}-\tilde{x})] -2(1-2m_b)(s+1) - m_b(s+2)[(s+2)+s(\bar{x}-\tilde{x})] = s^2m_B - m_b\left[(s+2)^2 - 4(s+1)\right] + s(s+2)(m_B - m_b)(\bar{x}-\tilde{x}) = s^2(m_B - m_b) + s(s+2)(m_B - m_b)(\bar{x}-\tilde{x}).$$
(S7.46)

Thus

$$(1+s\bar{x})[1+s(1-\tilde{x})]f(1) = s(m_B - m_b)[s+(s+2)(\bar{x}-\tilde{x})].$$
(S7.47)

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But as  $(s+2)\bar{x} > 1$ ,  $(s+2)\tilde{x} < (s+1)$ ,

$$s + (s+2)(\bar{x} - \tilde{x}) = [(s+2)\bar{x} - 1] + [(s+1) - (s+2)\tilde{x}] > 0.$$
 (S7.48)

It follows that the sign of f(1) is the same as the sign of  $(m_B - m_b)$ .

We now compute f(0):

$$f(0) = 1 - (1 - 2m_b) \frac{2(1+s)}{(1+s\bar{x})[1+s(1-\tilde{x})]} - m_b^2 \frac{(s+2)^2}{(1+s\bar{x})[1+s(1-\tilde{x})]} + \frac{(1 - 2m_b)^2 (s+1)^2}{(1+s\bar{x})^2 [1+s(1-\tilde{x})]^2}.$$
(S7.49)

Using the expression (S7.43) for the product of the two mean fitnesses, we get

$$(1+s\bar{x})^{2} [1+s(1-\tilde{x})]^{2} f(0) = \{(1+s) + sm_{B} [(s+2)\bar{x}-1]\}^{2}$$
$$-2(1-2m_{b})(s+1) \{(1+s) + sm_{B} [(s+2)\bar{x}-1]\}$$
$$-m_{b}^{2}(s+2) \{(1+s) + sm_{B} [(s+2)\bar{x}-1]\}$$
$$+(1-2m_{b})^{2} (s+1)^{2}.$$
(S7.50)

In (S7.50) we replace the  $\bar{x}^2$  term using the equilibrium equation (36) to give

$$(1+s\bar{x})^{2} \left[1+s(1-\tilde{x})\right]^{2} f(0) = (m_{B}-m_{b})s \left\{m_{b}s(s+1) - m_{B}^{2} \left(s+2\right)^{2} + m_{B} \left[(s+1)(s+4) - m_{b} \left(s+2\right)^{2}\right] + m_{B}(s+2)\bar{x} \left[m_{B} \left(s+2\right)^{2} + m_{b} \left(s+2\right)^{2} - 4(s+1)\right]\right\}.$$

$$(S7.51)$$

The right-hand side of (S7.51) is  $(m_B - m_b)s$  multiplied by

$$m_b s(s+1) + m_B (s+2)^2 (m_B + m_b) [\bar{x}(s+2) - 1] + m_B (s+1) [(s+4) - 4\bar{x}(s+2)].$$
(S7.52)

We will show that (S7.52) is always positive. In fact, (S7.52) is equal to

$$m_b s(s+1) + m_B \cdot m_b (s+2)^2 \left[ \bar{x}(s+2) - 1 \right] + m_B^2 (s+2)^2 \left[ \bar{x}(s+2) - 1 \right] + m_B (s+1) \left[ (s+4) - 4\bar{x}(s+2) \right].$$
(S7.53)

From the equilibrium equation (36) we get that

$$m_B[(s+2)\bar{x}-1] = s\bar{x}^2 + 2\bar{x} - 1.$$
 (S7.54)

Hence (S7.53) is equal to

$$m_b s(s+1) + m_B \cdot m_b (s+2)^2 \left[ \bar{x}(s+2) - 1 \right] + m_B (s+2)^2 \left[ s \bar{x}^2 + 2\bar{x} - 1 \right] + m_B (s+1) \left[ (s+4) - 4\bar{x}(s+2) \right].$$
(S7.55)

The last two terms have a factor  $m_B$  that multiplies

$$(s+1)(s+4) - (s+2)^{2} + (s+2)^{2} \bar{x}(2+s\bar{x}) - 4\bar{x}(s+1)(s+2) =$$

$$= s + (s+2)\bar{x}[(s+2)(2+s\bar{x}) - 4(s+1)]$$

$$= s + (s+2)\bar{x}[(s+2)s\bar{x} - 2s]$$

$$= s [(s+2)^{2} \bar{x}^{2} - 2(s+2)\bar{x} + 1] = s[(s+2)\bar{x} - 1]^{2},$$
(S7.56)

which is positive. To sum up, f(0) also has the same sign of  $(m_B - m_b)$ , and so

$$D_1(1) = (1 - r)s(m_B - m_b)\Delta(r), \qquad (S7.57)$$

where  $\Delta(r)$  is a linear function of r that is positive for all  $0 \le r \le 1$ . As  $(m_B - m_b) = (1 - 2m)(\mu_B - \mu_b)$ , this proves the following result.

## **Proof of Result 8**

*i.* In a constant environment, the mean fitness  $w^*$  at the symmetric equilibrium  $(\bar{\mathbf{x}}^*, \bar{\mathbf{y}}^*)$ is  $w^* = 1 + sx^*$ , and it is a decreasing function of  $\mu_B$  if  $\frac{\partial x^*}{\partial \mu_B}$  is negative, or equivalently if  $\frac{\partial x^*}{\partial m_B}$  is negative (since  $m_B = m + \mu_B(1-2m)$  and  $0 \le m < \frac{1}{2}$ ). Using the equilibrium equation (14),

$$\frac{\partial x^*}{\partial m_B} = \frac{1 - (s+2)x^*}{2sx^* + [(s+2)m_B - s]}.$$
(S8.1)

As  $x^* > \frac{1}{s+2}$ , in order for  $\frac{\partial x^*}{\partial m_B}$  to be negative, it is sufficient that

$$x^* > \frac{s - m_B(s+2)}{2s}.$$
 (S8.2)

This follows easily from the fact that Q(x) of (14) satisfies Q(0) < 0,  $Q(x^*) = 0$ , and  $Q\left(\frac{s-m_B(s+2)}{2s}\right) < 0.$ 

ii. With a fitness cycle of period 2, the mean fitness  $\bar{w}$  at the symmetric equilibrium  $(\bar{\mathbf{x}}, \bar{\mathbf{y}})$  is

$$\bar{w} = (1+s) + sm_B [(s+2)\bar{x} - 1].$$
 (S8.3)

 $\bar{w}$  is an increasing function of  $\mu_B$  if  $\frac{\partial \bar{w}}{\partial \mu_B} > 0$  or equivalently if  $\frac{\partial \bar{w}}{\partial m_B} > 0$ . Now

$$\frac{\partial \bar{w}}{\partial m_B} = s \left[ (s+2)\bar{x} - 1 \right] + s(s+2)m_B \frac{\partial \bar{x}}{\partial m_B}.$$
(S8.4)

Thus  $\frac{\partial \bar{w}}{\partial m_B} > 0$  provided  $\frac{\partial \bar{x}}{\partial m_B} > 0$ . Using the equilibrium equation R(x) = 0 for  $\bar{x}$ , we have

$$\frac{\partial \bar{x}}{\partial m_B} = \frac{\bar{x}(s+1) - 1}{2s\bar{x} + \left[2 - m_B(s+2)\right]}.$$
(S8.5)

Since  $\left[\bar{x}(s+1)-1\right] > 0$ , we conclude that  $\frac{\partial \bar{x}}{\partial m_B} > 0$  if

$$\bar{x} > \frac{m_B(s+2) - 2}{2s},$$
 (S8.6)

which follows from R(0) < 0,  $R(\bar{x}) = 0$ , and  $R\left(\frac{m_B(s+2)-2}{2s}\right) < 0$ .

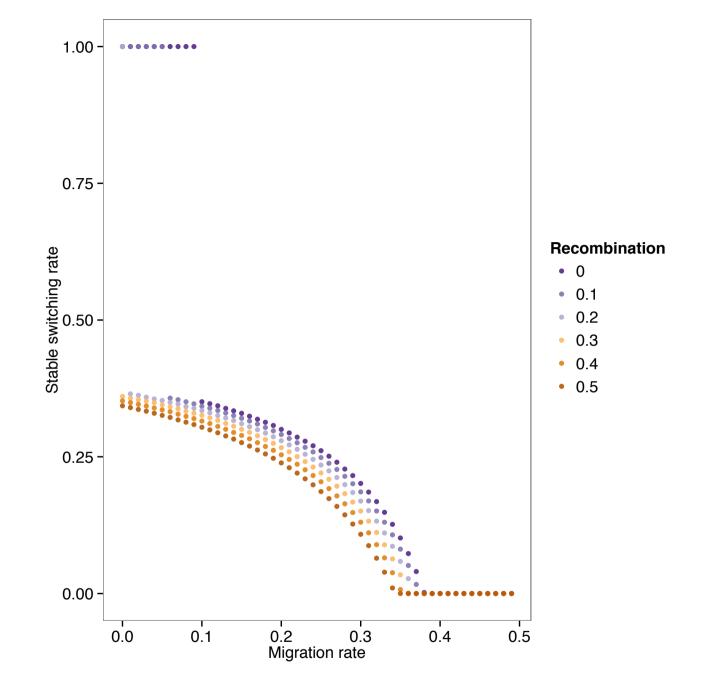
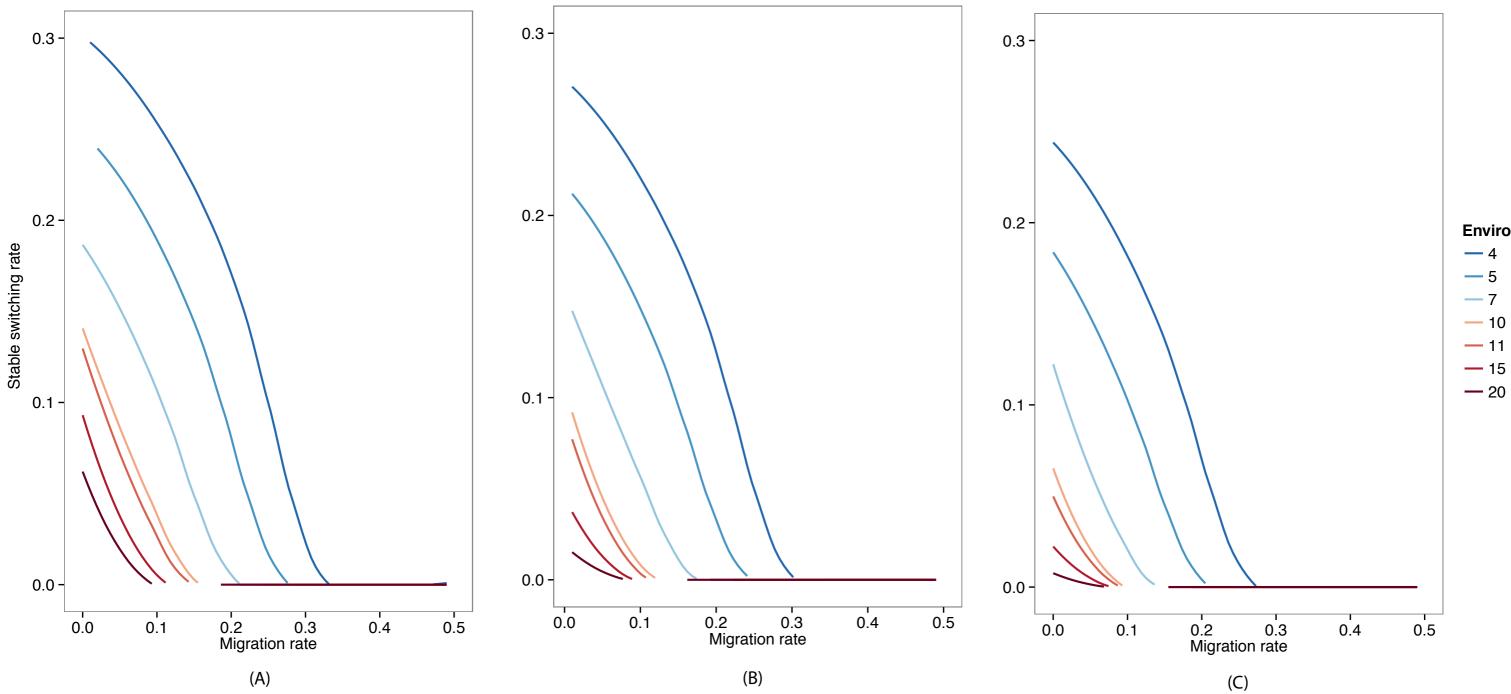


Figure S1. The evolutionarily stable switching rate as function of migration and recombination rate, n = 3. The symmetric selection coefficient s = 0.4. Recombination rates shown in the legend. The stable switching rate for n = 3 is sensitive to the interplay of recombination and migration rates, with sudden possible discontinuities in the stable switching rate.



# Environmental rate

Figure S2. The evolutionarily stable switching rate as function of migration and environmental rate of change, n > 3 for different recombination rates. The symmetric selection coefficient s = 0.4. The rate of environmental change n shown in the legend. The plotted curves represent a fit to the data using a generalized additive model with penalized cubic regression splines. In panel **A**, r = 0. In panel **B**, r = 0.25. In panel **C**, r = 0.5.

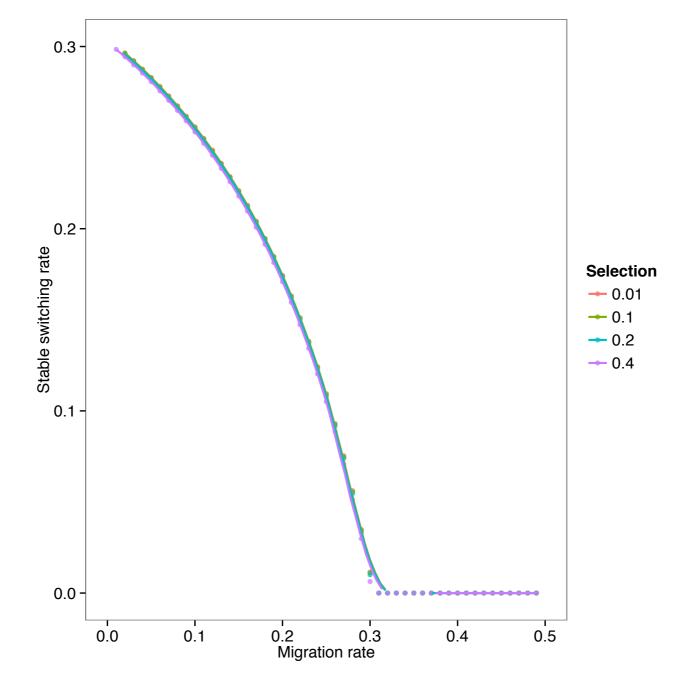


Figure S3. The evolutionarily stable switching rate as function of migration and symmetric selection coefficient s. Recombination rate is r = 0. The environment changes every n = 4 generations. The symmetric selection coefficient s shown in the legend. The plotted curves represent a fit to the data using a generalized additive model with penalized cubic regression splines. The stable switching rate is invariant to the strength of symmetric selection between the two demes.