First Author, Year published	Subjects (n)	Phase	Rehabilitation Robot	Evaluation activity	Loss of somatosensation (feed-forward)		Paresis & Loss of somatosensation (feedback)			Loss of fractionated movement		Abnormal muscle tone				
					Plan	Inter-limb coordination	Temporal efficiency	Accuracy	Efficacy	Movement Efficiency	Intra-limb coordination	Range (ROM)	Ease	Smoothness $\dot{x},\dot{\theta}$	Smoothness $\ddot{x},\ddot{\theta}$	Smoothness $\dddot{x},\dddot{\theta}$	Smoothness -sub
Reinkens-meyer [128] **2000**	3	Chronic	ARM-Guide	Multi-level PTP	③							③					
Burgar [129] **2000**	21	Chronic	MIME	• Shape tracing • Multi-level PTP						③							
Kahn [62] **2001**	14	Chronic	ARM-Guide	Multi-level PTP			③	❸				③		❸			
Rohrer [1] **2002**	31	Acute (n=12) Chronic (n=19)	MIT-Manus	CO-PTP			① ③						❶	❶❶		❸	
Lum [83] **2002**	27	Chronic	MIME	Targeted Reaching								❸*					
Lum [63] **2004**	13	Chronic	MIME	Multi-level PTP			❸										
Daly [71] **2005**	12	Chronic	InMotion2	CO-PTP				❸						❸			
Toth [85] **2005**	8	Sub-acute (n=2) Chronic (n=6)	REHAROB	Therapist guided full ROM slow movement								②③					
Colombo [68] **2005**	16	Chronic	MEMOS	Shape tracing				③	❸ ❸❸				❸				
Kahn [14] **2006**	19	Chronic	ARM-Guide	Multi-level PTP				❸				❸❸	❸❸	③			
Lum [84] **2006**	27	Sub-acute	MIME	Multi-level PTP								❸					
Colombo [27] **2006**	19	Chronic	MEMOS	Shape tracing				❸	❸ ❸❸	❸			❸				

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Sanchez [74] **2006**	5	Chronic	T-WREX	• Free reaching • PTP				❸❸	③			③③					
Dipietro [39] **2007**	117	Chronic	MIT-Manus InMotion2	Circle drawing				❸* ❸*			❸*						
Chang [55] **2007**	20	Chronic	BFIAMT	Reach and touch	❸ ❸		❸									❸	
Fazekas [87] **2007**	15	Chronic	REHAROB	Therapist guided full ROM slow movement								③❸					
Beer [77] **2008**	5	Chronic	MACARM	Multi-level PTP						③ ③							
Colombo [13] **2008**	22	Sub-acute (n=9) Chronic (n=13)	MEMOS	Shape tracing				②❸	❷❸	❷③			❷❸	❷❸		② ③	
Iwamuro [54] **2008**	10	Chronic	T-WREX	Multi-level PTP	❸							❸				❸	
Sanguineti [56] **2009**	9	Chronic	BdF	Outward PTP reaching													❸
	10	Chronic	BdF	Tracking									❸				
	6	Chronic	BdF	Bimanual forward/ backward reaching		③ ③							③				
Squeri [75] **2009**	4	Chronic	BdF	Bimanual forward/ backward reaching					③				③				
Nef [44] **2009**	3	Chronic	ARMin	• Passive mobilization • Active virtual catch & hit								③ ③③					

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Lewis [29] **2009**	15	Chronic	Haptic MASTER	Voluntary constrained reaching	③		③					❸		③			
				Voluntary free reaching	③		③					③		③			
				Assisted constrained reaching	③		③					❸		③			
				Assisted free reaching	③		③					③		③			
Vergaro [69] **2010**	10	Chronic	BdF	Tracking figure-8				❸					❸				
Dukelow [58] **2010**	45	Sub-acute	KINARM	Bimanual matching		❷ ❷❷											
Coderre [18] **2010**	52	Sub-acute	KINARM	CO-PTP	❷❷ ❷❷ ❷②		❷		❷	❷			②	❷❷			
Conroy [51] **2011**	62	Chronic	InMotion2 InMotion (Linear)	• CO-PTP • Multi-level reaching	❸		③	③③					③③	③			
Mazzoleni [52] **2011**	17	Chronic	InMotion2	CO-PTP	③			③③					③		③		
Zollo [10] **2011**	24	Chronic	InMotion2 InMotion3	Unperturbed & resistive point-to-point	❸*		③			❸*			❸	❸❸		❸	③③ ③
Squeri [57] **2011**	1	Chronic	BdF	CO-PTP		③ ③③											
Abdullah [70] **2011**	8	Sub-acute	Uni of Guelph Therapeutic Robotic Sys.	Shape tracing				②									
Johnson [11] **2011**	7	Chronic	BiAS-ADLER	Drink		③❸	❸						③				
				Pour		③③	❸						③				

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Mazzoleni [59] **2012**	11	Chronic	InMotion2	CO-PTP								③	③		
Panarese [67] **2012**	18	Chronic	MEMOS	Square and Diamond path PTP				❸	❸				❸	❸	
Dukelow [20] **2012**	100	Sub-acute	KINARM	Bimanual matching		❷ ❷❷									
				CO-PTP	❷ ❷❷		❷							❷	
Frisoli [64] **2012**	7	Chronic	L-Exos	Sagittal CO-PTP			❸							❸*	
Frisoli [61] **2012**	8	Chronic	L-Exos	Sagittal CO-PTP			❸							❸*	
Mazzoleni [53] **2013**	50	Sub-acute (n=25) Chronic (n=25)	InMotion3	CO-PTP	❷ ❸								❷❸	❷❸ ❷③	② ❸
Wu [15] **2013**	53	Chronic	Bi-ManuTrack	Reach and press			③			❸					③
Simkins [89] **2013**	15	Chronic	EXO-UL7	Constrained reaching, Pong-style games								❸			
Semrau [19] **2013**	113	Chronic	KINARM	Bimanual matching	❸* ❸*					❸			❸		

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