

Hv1 Proton Channel Opening Is Preceded by a Voltage-independent Transition

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SUPPLEMENTARY INFORMATION

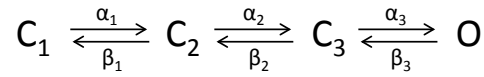
Kinetic analysis

Current recordings were fitted to a first-order ordinary differential equation system representing a four-state sequential model (Fig. 2A) using MatLab. The transition rates were considered to exponentially depend on the membrane potential. The forward (α) and backward (β) rates were defined as:

$$\alpha_i = \alpha_{0i} e^{z_{\alpha i} V / kT} \quad (1)$$

$$\beta_i = \beta_{0i} e^{-z_{\beta i} V / kT} \quad (2)$$

where, α_{0i} and β_{0i} are the rate constants at 0 mV of the i -th transition; z_{α} and z_{β} are the charge (valence) associated with the i -th transition; V is the membrane potential; k and T are the Boltzmann constant and the absolute temperature. In terms of differential equations, a sequential 4-state model (below) can be described as follows:



$$\frac{dC_1}{dt} = -\alpha_1 C_1 + \beta_1 C_2$$

$$\frac{dC_2}{dt} = \alpha_1 C_1 - (\beta_1 + \alpha_2) C_2 + \beta_2 C_3$$

$$\frac{dC_3}{dt} = \alpha_2 C_2 - (\beta_2 + \alpha_3) C_3 + \beta_3 O$$

$$\frac{dO}{dt} = \alpha_3 C_3 - \beta_3 O$$

Rearranging these differential equation into matrix form yields

$$\frac{\partial}{\partial t} \begin{pmatrix} C_1 \\ C_2 \\ C_3 \\ 0 \end{pmatrix} = \begin{pmatrix} -\alpha_1 & \beta_1 & 0 & 0 \\ \alpha_1 & -(\beta_1 + \alpha_2) & \beta_2 & 0 \\ 0 & \alpha_2 & -(\beta_2 + \alpha_3) & \beta_3 \\ 0 & 0 & \alpha_3 & -\beta_3 \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \\ C_3 \\ 0 \end{pmatrix}$$

In general, these kinds of systems can be expressed as

$$\frac{\partial}{\partial t} \vec{S} = \mathbf{A} \vec{S} \quad (3)$$

$$\vec{S} = \begin{pmatrix} C_1 \\ C_2 \\ C_3 \\ 0 \end{pmatrix}; \quad \mathbf{A} = \begin{pmatrix} -\alpha_1 & \beta_1 & 0 & 0 \\ \alpha_1 & -(\beta_1 + \alpha_2) & \beta_2 & 0 \\ 0 & \alpha_2 & -(\beta_2 + \alpha_3) & \beta_3 \\ 0 & 0 & \alpha_3 & -\beta_3 \end{pmatrix}$$

where, \vec{S} is a column vector (state vector) the elements of which correspond to the population fraction of each state and \mathbf{A} is the matrix (state matrix) containing the rate constants governing the reaction. The general solution of this system has the form

$$\vec{S}(t) = \vec{\eta} e^{\lambda t} \quad (4)$$

From this proposed solution, the derivative of the state vector is

$$\frac{\partial}{\partial t} \vec{S}(t) = \lambda \vec{\eta} e^{\lambda t} \quad (5)$$

Replacing 4 and 5 in 3 yields

$$\lambda \vec{\eta} e^{\lambda t} = \mathbf{A} \vec{\eta} e^{\lambda t}$$

Rearranging this equation yields

$$\mathbf{A} \vec{\eta} e^{\lambda t} - \lambda \vec{\eta} e^{\lambda t} = \vec{0} \quad \Rightarrow \quad (\mathbf{A} - \lambda \mathbf{I}) \vec{\eta} e^{\lambda t} = \vec{0} \quad (6)$$

where, \mathbf{I} is an identity matrix of the same dimension than \mathbf{A} . Because $e^{\lambda t} > 0$, equation 7 becomes

$$(\mathbf{A} - \lambda \mathbf{I}) \vec{\eta} = \vec{0} \quad (7)$$

In this latter equation, the scalar λ and the vector $\vec{\eta}$ are known as the eigenvalue and eigenvector of the matrix A . In general, there are as many eigenvalue-eigenvectors pairs as elements in the state vector. For this particular case, there are 4 eigenvalues and eigenvectors. Finally, the general solution of this kind of system will be:

$$\vec{S}(t) = \sum_{i=1}^n c_i \vec{\eta}_i e^{\lambda_i t} \quad (8)$$

where, n is the number of states and c_i are integration constants. To calculate these latter values, Equation 8 was evaluated at time zero, making the exponential equal to 1. Thus,

$$\vec{S}(0) = \sum_{i=1}^n c_i \vec{\eta}_i \quad (9)$$

At time 0, the values for $\vec{S}(t)$ correspond to those of the initial condition. Therefore, the values of c_i can be readily calculated, since Equation 9 is an algebraic system of n equation with n unknown (c_i). Replacing the calculated c_i in equation 8 gives an expression that yields by fractional population of each state of the model in time.

Finally, having found $\vec{S}(t)$ and the fraction of open channels ($O(t)$) which is the last element of the vector $\vec{S}(t)$, current can be calculated using the following expression:

$$I(t) = O(t)G_{MAX}(V - V_{H^+})$$

where, G_{MAX} is the maximum conductance for protons, V is the membrane potential, and V_{H^+} is the reversal potential for protons.

Table S1

	pH _I 4.5 (n=5)		pH _I 5.5 (n=5)		pH _I 6.5 (n=8)	
	mean	S.D.	mean	S.D.	mean	S.D.
$\alpha_{0,1}$	4.5940×10^{-4}	2.9×10^{-4}	2.1092×10^{-4}	8.0×10^{-5}	3.6745×10^{-4}	2.8×10^{-4}
$\beta_{0,1}$	3.7759×10^{-7}	1.0×10^{-7}	8.8539×10^{-7}	2.8×10^{-7}	3.6000×10^{-6}	1.6×10^{-6}
$z_{\alpha 1}$	7.4982×10^{-1}	2.6×10^{-1}	4.8815×10^{-1}	7.3×10^{-2}	1.6265×10^{-1}	7.4×10^{-2}
$z_{\beta 1}$	2.0726	5.1×10^{-1}	2.0954	5.9×10^{-1}	2.4175	1.6×10^{-1}
$\alpha_{0,2}$	1.3196×10^{-3}	6.4×10^{-4}	2.4286×10^{-4}	1.6×10^{-4}	3.943×10^{-5}	2.8×10^{-5}
$\beta_{0,2}$	4.4267×10^{-3}	2.6×10^{-3}	2.0368×10^{-2}	1.1×10^{-2}	1.1001×10^{-1}	5.0×10^{-2}
$z_{\alpha 2}$	1.0120	1.3×10^{-1}	9.8428×10^{-1}	1.5×10^{-1}	9.2826×10^{-1}	8.4×10^{-2}
$z_{\beta 2}$	2.0705	2.8×10^{-1}	1.8043	9.9×10^{-1}	1.5173	2.0×10^{-1}
$\alpha_{0,3}$	1.5538×10^{-2}	3.8×10^{-3}	1.1932×10^{-2}	6.0×10^{-3}	6.6033×10^{-3}	1.5×10^{-3}
$\beta_{0,3}$	8.6658×10^{-4}	6.3×10^{-4}	1.5240×10^{-3}	3.8×10^{-4}	1.654×10^{-3}	6.7×10^{-4}
$z_{\alpha,3}$	1.3479×10^{-5}	1.0×10^{-5}	1.4769×10^{-5}	6.1×10^{-6}	2.965×10^{-5}	1.2×10^{-5}
$z_{\beta,3}$	1.6309×10^{-7}	1.1×10^{-7}	5.1742×10^{-7}	2.2×10^{-7}	2.7365×10^{-7}	1.2×10^{-7}

Table S1.- Fitted average parameters for forward and backward transitions. Values for $\alpha_{0,1}$ and $\beta_{0,1}$ are in ms^{-1} . Values for z are in e^- .

Figure S1

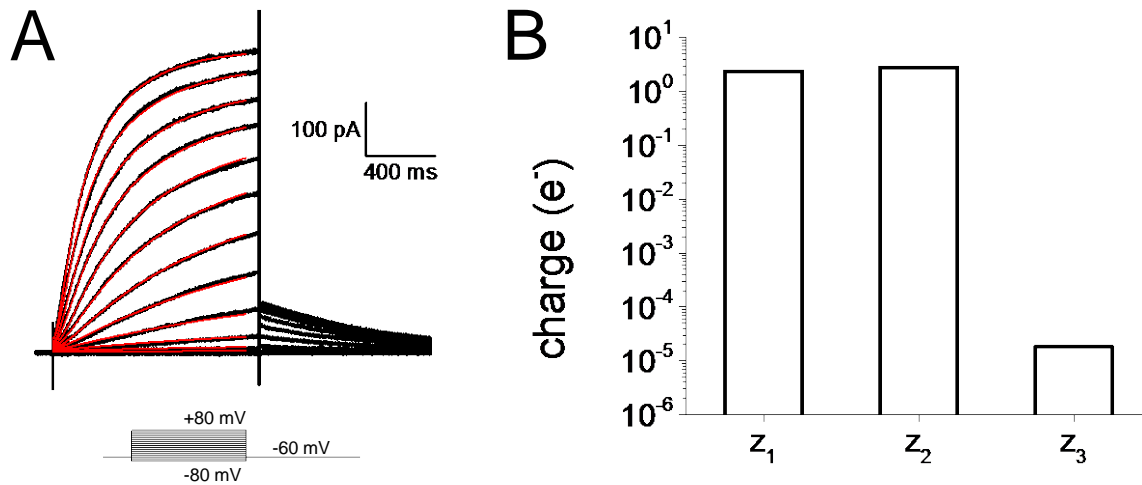


Figure S1- Simultaneous fitting of activating currents to a multi-state model. (A) A four-state sequential model was used to fit the activation kinetics of Hv1, where the first 3 states of the model are non-conductive (closed, C_1 - C_3). All forward (α_i) and backward (β_i) transition rates are considered essentially voltage-sensitive (Eqs. 1 and 2 in Materials and Methods). (B) Simultaneous fitting of currents traces recorded at potentials ranging from -40 to +80 mV at pH_i 4.5 and pH_o 6.5. Traces between -80 and -50 were not included in the fitting process. (C) There were two parameters for each transition rate, one is the rate at 0 mV (α_0 or β_0 , accordingly) and the other is the apparent charge associated with the rate ($z_{\alpha 0}$ and $z_{\beta 0}$, accordingly). The total charge of the transitions between two states was obtained by the sum of the individuals charges. As shown in the graph, the gating charge associated with the first and second transitions, z_1 and z_2 , respectively, displayed values of $\sim 2.5 e^-$ each, while the last transition showed about $2 \times 10^{-5} e^-$.

Figure S2

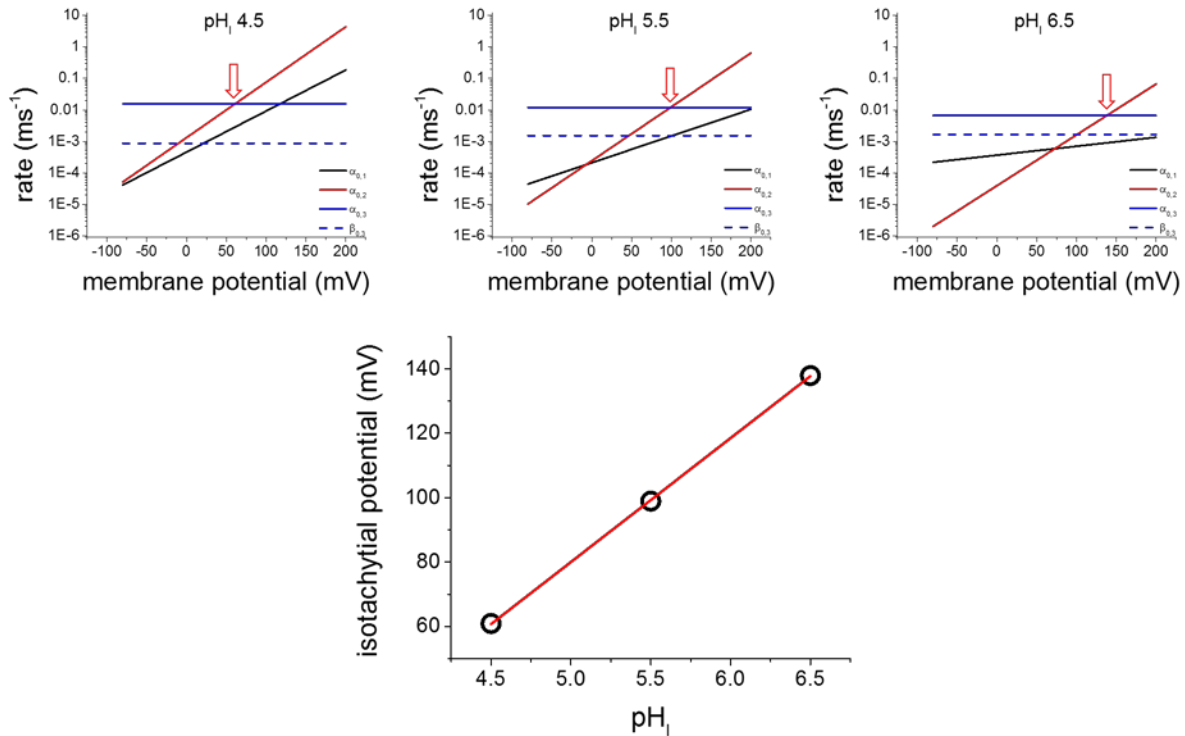


Figure S2.- *Top*) Calculated values of α_1 (black), α_2 (red) and α_3 (blue) as a function of the membrane potential at pH_i 4.5 (left), 5.5 (center) and 6.5 (right). *Bottom*) Plot of the membrane potential at which α_2 equals α_3 as a function of pH_i . At voltages above these potentials, or isotachytal potentials (V_{IT} ; from the Greek words ἴσος (isos) = equal and ταχύτητα (tachýtita) = speed), the last transition can be considered to be rate-limiting. Noteworthy, a linear fit of V_{IT} versus pH_i plot yielded a slope of 38.5 ± 0.3 mV/ ΔpH_i , which matches the pH_i sensitive of the overall voltage-dependence of Hv1. The V_{IT} was

$$\text{calculated using the equation } V_{IT} = \frac{kT \ln(\alpha_{0,2}/\alpha_{0,3})}{z_{\alpha,3} - z_{\alpha,2}}.$$