

**Supplementary Information: Analysis of spatial-temporal gene expression patterns reveals dynamics
and regionalization in developing mouse brain**

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Supplementary file information

Supplementary Information: The ABA data processing procedures and the algorithm of finding local gene expression patterns. Supplementary Figures. The Matlab program source codes of analyzing ABA data.

Supplementary Dataset S1: The genes belonging to each global expression state.

Supplementary Dataset S2: Complete enrichment outcomes of GO categories.

Supplementary Dataset S3: The genes possessing each local pattern.

Supplementary Dataset S4: The complete GO category enrichment outcomes of spatial patterns.

Supplementary Dataset S5: The normalized RNAseq data of 17461 genes in the forebrain of Lhx2 knock-out mice.

Supplementary Dataset S6: The input data for the Matlab programs.

Allen Developing Mouse Brain Atlas (ABA) data preprocessing

ABA provides *In Situ* hybridization (ISH) data including an anatomic structure and a heatmap representation of gene expression for an experiment or a gene in 3D format (Lein et al., 2007). An individual ISH section images for each time-point are stacked into a single slide image to form one common space called 3D reference model. A position of each section in the brain or specimen is calculated to a reference section index across all time-points. Each ISH image is masked with grids to create a 3D summary of the gene expression and project the data to a common coordinate space of the 3D reference model to enable spatial comparison between data from different specimens. The resolution of the data grids varies with age and corresponds with the sampling density for that time-point. All images and quantified expression values by structure or as 3D grids including the annotation of the voxels are available for download via API service (<http://help.brain-map.org/display/devmouse/API>). In this study, we collected the quantified expression values as 3D grids. There are four steps to retrieve and parse the data form ABA. The whole data was automated under Linux environment.

1. We tracked a list of all gene and image-series IDs available on ABA from gene detail pages (see a prototype and example from Table 1). The data including gene identifiers, specimen related information (i.e. age) and meta-information for each image (i.e. path, dimension) comprising the image-series are available as XML format. The XML header shows a total number of genes and pages. There are 2005 genes and 19371 image-series IDs for 7 developmental ages (E11.5, E13.5, E15.5, E18.5, P4, P14 and P28). Note that the latest data has been updated in June, 2013. All XML files are zipped in ABA_xml.zip file. Java code written in ABA_xml_processing.java file is applied to parse the XML data. The summary gene and image-series information are summarized in aba_dev_allgenes_20120424.2.txt file with tab delimited format.

Prototype	http://developingmouse.brain-map.org/data/search/gene/index.xml?page=[i]&term=* where [i] is the page number ranging from 1 to 201.
Return type	XML file.
Comments	Each markup starting with tag gene contains gene and image series information. One gene ID

2. We further downloaded the 3D expression summaries of each image-series ID. There are 15531 and 5840 IDs with- and without 3D grid data files, respectively.

Prototype	<p>1. http://developingmouse.brain-map.org/grid_data/download/[ImageSeriesID]</p> <p>2. http://api.brain-map.org/grid_data/download/[ImageSeriesID]</p>	
Return type	<p>1. A zip file containing 5 files including image_series.xml, density.mhd, density.raw, intensity.mhd and intensity.raw.</p> <p>2. A zip file containing 3 files including data_set.xml, energy.mhd and energy.raw.</p>	
	image_series.xml	XML file containing information about the specimen and images. This file is returned if the volumes parameter is null.
	data_set.xml	
	density.raw	A raw uncompressed float (32bit) little-endian volume representing average expression density per voxel. Volume dimension is dependent on specimen age. Value of "-1" represents no data.
	intensity.mhd	A simple text header file in MetaImage format describing the volume.
	intensity.raw	A raw uncompressed float (32bit) little-endian volume representing average expression intensity per voxel. Volume dimension is dependent on specimen age. Value of "-1" represents no data.
	energy.mhd	A simple text header file in MetaImage format describing the volume. This file is returned if the volumes parameter is null.
	energy.raw	A raw uncompressed float (32-bit) little-endian volume representing average expression energy per voxel. A value of "-1" represents no data. This file is returned if the volumes parameter is null.
Comments	expression density	Expression density is the number of expressing pixels divided by the number image pixels overlapping the voxel. A value of "-1" indicates no data. This value represents the size of the sphere at each grid location.
	expression intensity	Expression intensity is the averaged inverted ISH grayscale value at expressing pixels within the span of the grid voxel. A value of "-1"

		<p>indicates no data. This value represents the color of the sphere at each grid location.</p>
	<p>expression energy</p>	<p>Expression energy is defined as (expression intensity * expression density). Anatomic search, temporal search, Neuroblast and AGEA features on the Atlas are all based on expression energy. A value of "-1" indicates no data.</p>
<p>Example</p>	<p>1. http://developingmouse.brain-map.org/grid_data/download/100073527</p> <p>image-series.xml file</p> <pre> <image-series> <age>E11.5</age> <created-at>2009-07-01T16:10:35-07:00</created-at> <days>11.5</days> <donor-id>9215</donor-id> <expression>true</expression> <failed>false</failed> <gene-id>93453</gene-id> <id>100073527</id> <is-experiment>true</is-experiment> <isembryonic>1</isembryonic> <medical-condition>TS19</medical-condition> <name>100073527</name> <organism>Mus musculus</organism> <plane-of-section>sagittal</plane-of-section> <project-code>0350</project-code> <published-at>2009-10-01</published-at> <qc-date>2009-07-16T12:54:17-07:00</qc-date> <race-or-strain>C57BL/6J</race-or-strain> <run-group-id>707117</run-group-id> <run-group-type>full set</run-group-type> <runplan-id>656</runplan-id> <sex>unknown</sex> <specimen-id>700715</specimen-id> <storage-directory>/external/devmouse/prod170/image_series_100073527/</storage-directory> <trv>...</trv> <tvr>...</tvr> <updated-at>2010-02-13T19:48:19-08:00</updated-at> <gene>...</gene> <images type="array">...</images> <probes type="array">...</probes> </image-series> </pre> <p>density.mhd</p> <pre> ObjectType = Image NDims = 3 BinaryData = True BinaryDataByteOrderMSB = False CompressedData = False TransformMatrix = 1 0 0 0 1 0 0 0 1 Offset = 0 0 -160 CenterOfRotation = 0 0 0 AnatomicalOrientation = RAI ElementSpacing = 80 80 80 DimSize = 70 75 40 ElementType = MET_FLOAT ElementDataFile = density.raw </pre>	

intensity.mhd

ObjectType = Image
NDims = 3
BinaryData = True
BinaryDataByteOrderMSB = False
CompressedData = False
TransformMatrix = 1 0 0 0 1 0 0 0 1
Offset = 0 0 -160
CenterOfRotation = 0 0 0
AnatomicalOrientation = RAI
ElementSpacing = 80 80 80
DimSize = 70 75 40
ElementType = MET_FLOAT
ElementDataFile = intensity.raw

2. http://api.brain-map.org/grid_data/download/100073527**data_set.xml**

```
<section-data-set>  
  <expression>true</expression>  
  <failed>false</failed>  
  <id>100073527</id>  
  <name nil="true"/>  
  <qc-date>2009-07-16T12:54:17Z</qc-date>  
  <reference-space-id>1</reference-space-id>  
  <section-thickness>20</section-thickness>  
  <specimen-id>700715</specimen-id>  
  <storage-directory>/external/devmouse/prod170/image_series_100073527/</storage-directory>  
  <weight>5200</weight>  
  <genes>...</genes>  
  <probes>...</probes>  
  <products>...</products>  
  <specimen>...</specimen>  
  <alignment3d>...</alignment3d>  
  <section-images>...</section-images>  
  <plane_of_section>sagittal</plane_of_section>  
  <age>E11.5</age>  
</section-data-set>
```

energy.mhd

ObjectType = Image
NDims = 3
BinaryData = True
BinaryDataByteOrderMSB = False
CompressedData = False
TransformMatrix = 1 0 0 0 1 0 0 0 1
Offset = 0 0 -160
CenterOfRotation = 0 0 0
AnatomicalOrientation = RAI
ElementSpacing = 80 80 80
DimSize = 70 75 40
ElementType = MET_FLOAT
ElementDataFile = energy.raw

3. We applied MATLAB code (see process_read3Dfiles.m) to read the intensity, density or energy values, extract the coordinates corresponding to the expression values and visualize their 3D images from raw files (i.e. intensity.raw, density.raw and energy.raw).

Input	A pair of *.raw and *.mhd file. For instance, [density.raw and density.mhd] or [intensity.raw and intensity.mhd] or [energy.raw and energy.mhd].
Output	<ol style="list-style-type: none"> 1. [expressionType]_raw_[image-seriesID].coor 2. [expressionType]_[image-seriesID].coor 3. [expressionType]_[image-seriesID].png <p>where [expressionType] represents a file of interest (i.e. density, intensity or energy). A file with “coor” extension is the text file containing coordinates of image and the corresponding expression values. A “raw” tag means to a raw data from *.raw file. A file without “raw” tag represents a file containing normalized expression values. All output files were put into the same folder as input file. The voxel 3D coordinates are reconstructed in RAI orientation (+x = right, +y=anterior, +z= inferior). The expression values are normalized by applying the cumulative distribution function (CDF) value with the range [0, 1] to the entire matrix. A value of “0” indicates that coordinate is not valid. Only valid values are collected.</p>
Example	<p>Input: [intensity.raw and intensity.mhd] of image-series ID 100073527.</p> <p>Output:</p> <ol style="list-style-type: none"> 1. intensity_raw_100073527.coor <p>- A dimension size of 3D image is 70 x 75 x 40.</p>

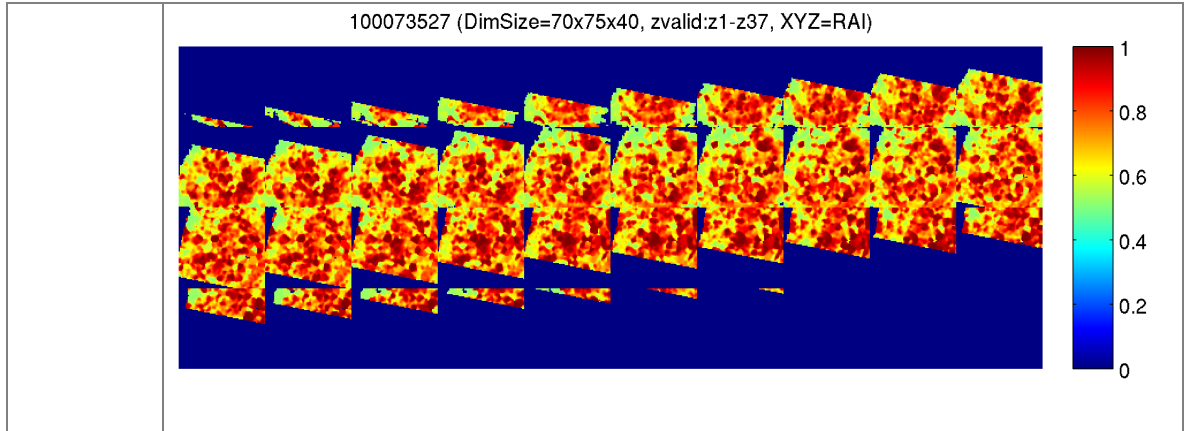
x	y	z	values
59	6	1	104.153831481934
60	12	1	106.769218444824
61	12	1	105.989677429199
60	13	1	106.020446777344
61	13	1	103.108413696289
62	13	1	86.1428604125977
63	13	1	86.1428680419922
64	13	1	86.1428680419922
60	14	1	105.230545043945
61	14	1	98.8087539672852
62	14	1	86.1428604125977
63	14	1	86.1428680419922
64	14	1	86.1428680419922
61	15	1	94.1960906982422
62	15	1	87.1479721069336
63	15	1	86.1428527832031
64	15	1	86.1428604125977
61	16	1	90.6747665405273
62	16	1	87.9549865722656
...

2. intensity_100073527.coor

x	y	z	values
59	6	1	0.54393116157709
60	12	1	0.551150243572653
61	12	1	0.548983566588498
60	13	1	0.549035947790312
61	13	1	0.541145434026033
62	13	1	0.515002452393033
63	13	1	0.51503102395766
64	13	1	0.51503102395766
60	14	1	0.546864508878719
61	14	1	0.532326344411406
62	14	1	0.515002452393033
63	14	1	0.51503102395766
64	14	1	0.51503102395766
61	15	1	0.524073924161864
62	15	1	0.516202458107337
63	15	1	0.514992928538158
64	15	1	0.515002452393033
61	16	1	0.52018342944526
62	16	1	0.517045319263812
...

3. intensity_100073527.png

- The coordinates of axis Z from 1 to 37 contain valid expression intensity values.



Structure Ontology Hierarchy

The structure ontology hierarchy was downloaded from the following webpage http://api.brain-map.org/api/v2/structure_graph_download/13.json. The json file was parsed and reformatted into a more readable tabular-form file *brain_anno.csv* for easier lookup of each structure with its annotation.

Mouse gene ontology

The document of GO terms for all mouse genes was downloaded from mouse genome informatics from the Gene Ontology Data section of the following website: <ftp://ftp.informatics.jax.org/pub/reports/index.html#homology>.

Algorithm of identifying the recurrent local expression patterns

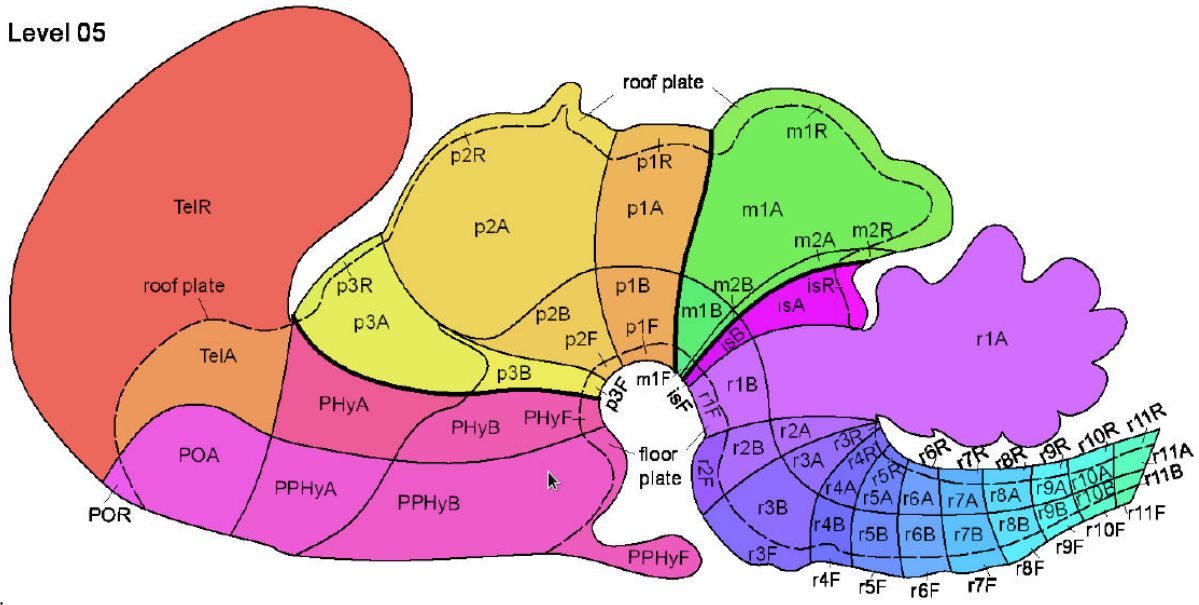
1. For each gene at each time point, convert its expression data $f_i(x, y, t)$ into binary values $f_i^{\hat{\theta}}(x, y, t)$ according to the aforementioned quantization procedure.
2. Extract the contiguous regions where $f_i^{\hat{\theta}}(x, y, t)=1$ from all gene-time point combinations.
3. Select the contiguous regions that pass five filtering criteria: (1) they cover more than 2 substructures, (2) the corresponding $f_i(x, y, t)$ is not labeled as globally expressed, (3) their sizes are less than one half of all substructures with valid data, (4) their sizes are at least 75% of the

sizes of their convex hulls, and (5) the numbers of substructures outside the regions and inside their convex hulls are smaller than 8. We name the contiguous regions that pass those criteria as local components. There are 3847 local components in the ABA data.

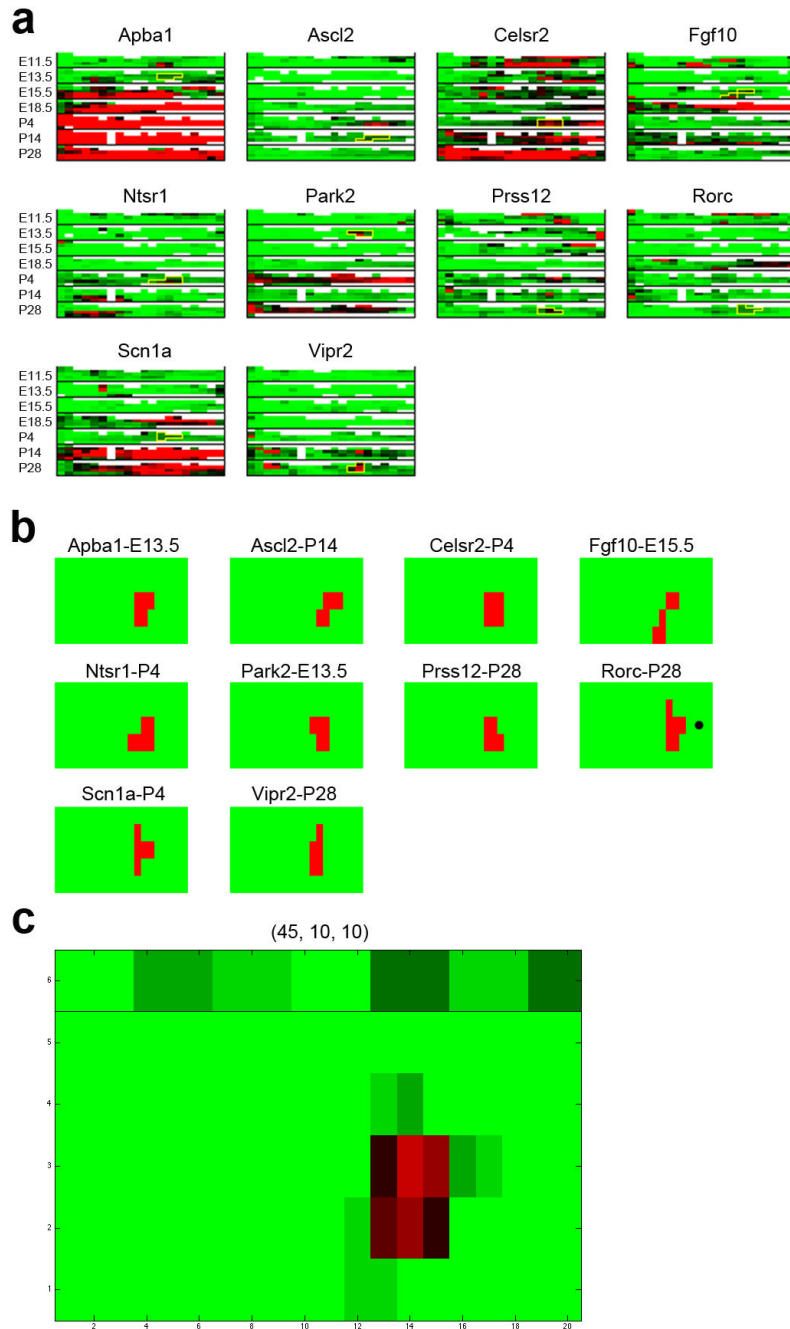
4. For each pair of components, we define their similarity as the ratio of the size of their intersection to the maximal size of the two components. Calculate the similarity matrix between all pairs of local components.
5. Apply a graph theory based clustering algorithm to the similarity matrix.
 - 5.1 Sort the similarity scores in a decreasing order.
 - 5.2 Initially set a graph of 3847 isolated nodes and the threshold value to the maximal similarity score. Repeat the following procedures:
 - 5.2.1 Lower the threshold to the next value in the ranked list.
 - 5.2.2 Add edges to the node pairs whose similarity scores exceed the current threshold.
 - 5.2.3 Expand and merge old cliques (maximally complete subgraphs) from previous steps with newly added edges.
 - 5.2.4 Find new cliques among the newly added edges.
 - 5.2.5 Stop when the current threshold value ≤ 0.5 .
 - 5.3 Initially set each clique as a cluster. Repeat the following procedures:
 - 5.3.1 Sort clusters by their sizes.
 - 5.3.2 Pick two mergeable clusters with the largest sizes. Two clusters are mergeable if at least 70% of the inter-cluster edges have similarity score ≥ 0.4 . Merge the chosen clusters.
 - 5.3.3 Stop when no cluster pairs are mergeable.
 - 5.4 Report the clusters with at least 10 members.

The outputs of the algorithm are clusters of overlapped contiguous regions. Each cluster corresponds to a recurrent local expression pattern.

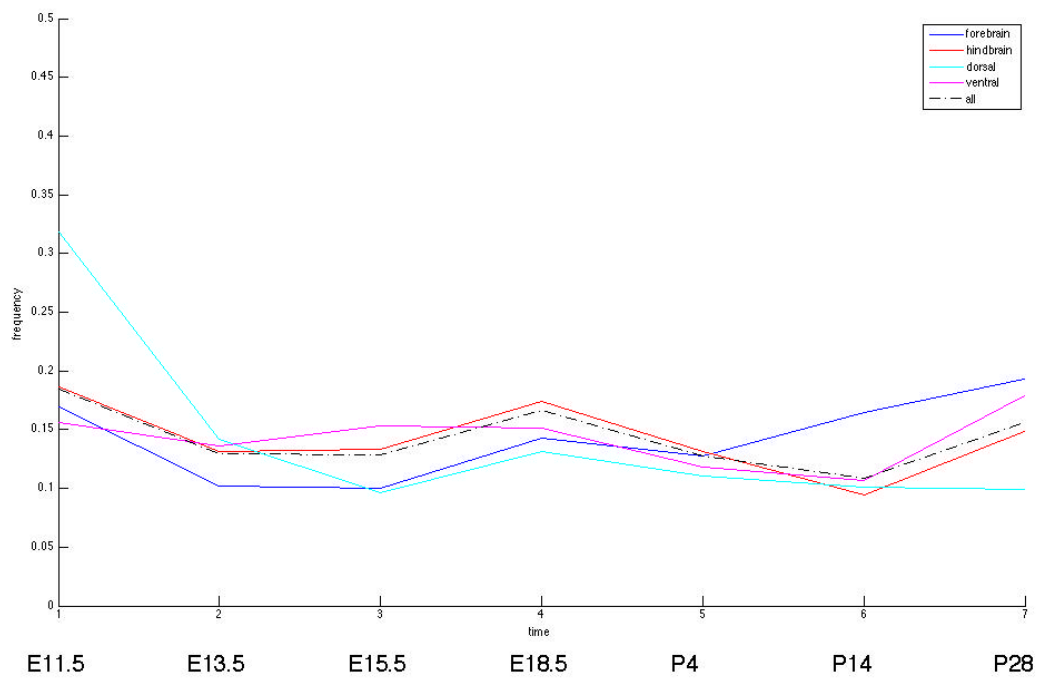
Level 05



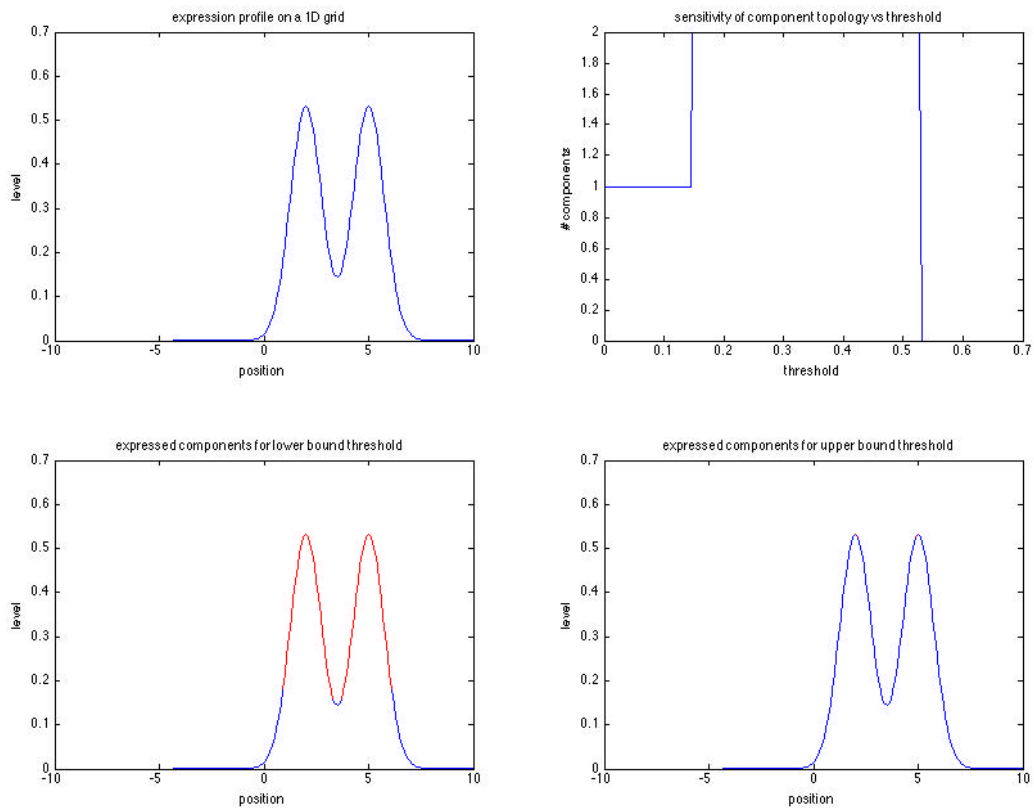
Supplementary Figure S1: Level 5 substructures of a mouse brain. Adapted from the ABA manual.



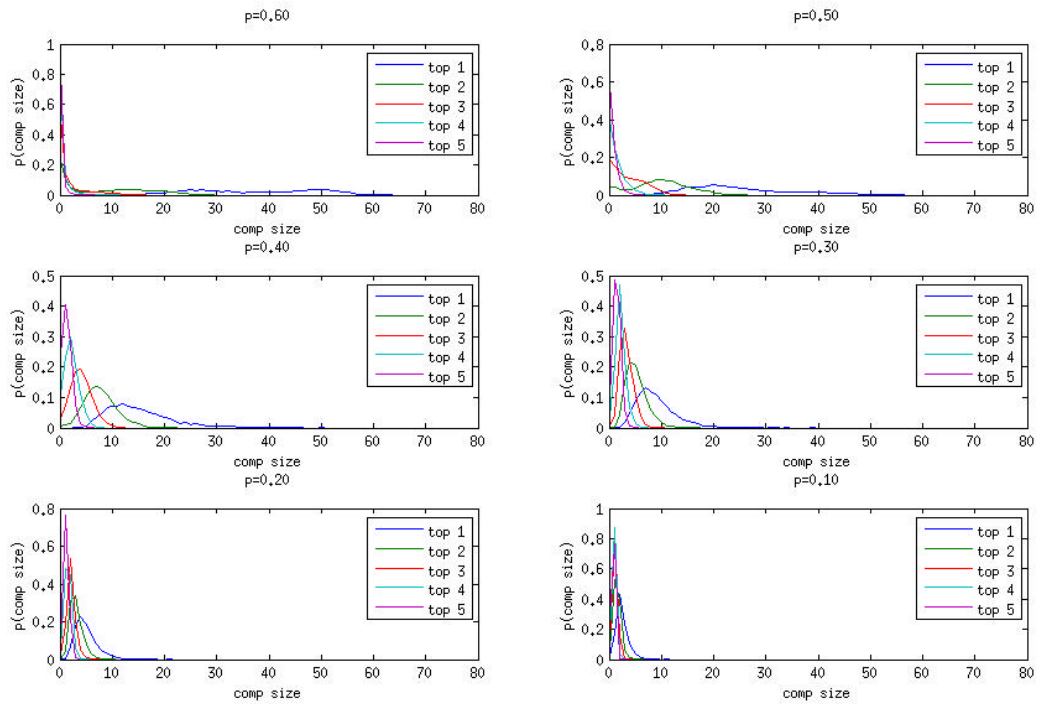
Supplementary Figure S2: An example of the recurrent local spatial expression pattern 45. The top panels display the expressions of the 10 genes possessing the pattern. The middle panels display the members of pattern 45 as expressed regions in the 10 genes. The bottom panel summarizes the occurrence frequency of each time point (the top bar) and substructure (the red rectangle) in the pattern.



Supplementary Figure S3: The temporal occurrence distributions of the four groups constructed from level 5 substructures.



Supplementary Figure S4: A toy example illustrating the difference of choosing the lower and upper bounds in the valid interval as the threshold for expression quantization.



Supplementary Figure S5: The component size distributions derived from random binary matrices. Each panel shows the experiments with a decreasing probability of assigning 1 to the random matrix entries. In each panel, the size distributions of top 5 components are reported.

Matlab Program Source Codes for Analyzing the ABA Data

```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% Matlab programs for analyzing the spatial-temporal ABA expression data.
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
```

```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% ABACodes_mainprogram.m.
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
```

```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% The main program for analyzing the spatial-temporal ABA expression data.
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
```

```
% The inputs of the program include the processed mouse brain gene
expression data, names of genes, names of substructures in the grid, and
names of the time points.
```

```
% The brain gene expression data is a four-dimensional array:
braindata(gene index,substructure along the anterior-posterior
axis,substructure index along the dorsal-ventral axis, time).
% The outputs are stored in a Matlab file designated by outputfilename.
```

```
% In the ABA data we analyzed, we use the following inputs.
%ngenes=1826; nx=20; ny=5; ntimesteps=7;
%gridnames{1}{1}='PPHyF'; gridnames{1}{2}='PPHyB';
gridnames{1}{3}='PPHyA'; gridnames{1}{4}='POA'; gridnames{1}{5}='POR';
%gridnames{2}{1}='PHYF'; gridnames{2}{2}='PHYB'; gridnames{2}{3}='PHYA';
gridnames{2}{4}='TelA'; gridnames{2}{5}='TelR';
%gridnames{3}{1}='p3F'; gridnames{3}{2}='p3B'; gridnames{3}{3}='p3A';
gridnames{3}{4}='p3R'; gridnames{3}{5}='';
%gridnames{4}{1}='p2F'; gridnames{4}{2}='p2B'; gridnames{4}{3}='p2A';
gridnames{4}{4}='p2R'; gridnames{4}{5}='';
%gridnames{5}{1}='p1F'; gridnames{5}{2}='p1B'; gridnames{5}{3}='p1A';
gridnames{5}{4}='p1R'; gridnames{5}{5}='';
%gridnames{6}{1}='m1F'; gridnames{6}{2}='m1B'; gridnames{6}{3}='m1A';
gridnames{6}{4}='m1R'; gridnames{6}{5}='';
%gridnames{7}{1}='m2F'; gridnames{7}{2}='m2B'; gridnames{7}{3}='m2A';
gridnames{7}{4}='m2R'; gridnames{7}{5}='';
%gridnames{8}{1}='isF'; gridnames{8}{2}='isB'; gridnames{8}{3}='isA';
gridnames{8}{4}='isR'; gridnames{8}{5}='';
%gridnames{9}{1}='r1F'; gridnames{9}{2}='r1B'; gridnames{9}{3}='r1A';
gridnames{9}{4}=''; gridnames{9}{5}='';
%gridnames{10}{1}='r2F'; gridnames{10}{2}='r2B'; gridnames{10}{3}='r2A';
gridnames{10}{4}=''; gridnames{10}{5}='';
%gridnames{11}{1}='r3F'; gridnames{11}{2}='r3B'; gridnames{11}{3}='r3A';
gridnames{11}{4}='r3R'; gridnames{11}{5}='';
%gridnames{12}{1}='r4F'; gridnames{12}{2}='r4B'; gridnames{12}{3}='r4A';
gridnames{12}{4}='r4R'; gridnames{12}{5}='';
```



```

%gridnames{13}{1}='r5F'; gridnames{13}{2}='r5B'; gridnames{13}{3}='r5A';
gridnames{13}{4}='r5R'; gridnames{13}{5}='';
%gridnames{14}{1}='r6F'; gridnames{14}{2}='r6B'; gridnames{14}{3}='r6A';
gridnames{14}{4}='r6R'; gridnames{14}{5}='';
%gridnames{15}{1}='r7F'; gridnames{15}{2}='r7B'; gridnames{15}{3}='r7A';
gridnames{15}{4}='r7R'; gridnames{15}{5}='';
%gridnames{16}{1}='r8F'; gridnames{16}{2}='r8B'; gridnames{16}{3}='r8A';
gridnames{16}{4}='r8R'; gridnames{16}{5}='';
%gridnames{17}{1}='r9F'; gridnames{17}{2}='r9B'; gridnames{17}{3}='r9A';
gridnames{17}{4}='r9R'; gridnames{17}{5}='';
%gridnames{18}{1}='r10F'; gridnames{18}{2}='r10B';
gridnames{18}{3}='r10A'; gridnames{18}{4}='r10R'; gridnames{18}{5}='';
%gridnames{19}{1}='r11F'; gridnames{19}{2}='r11B';
gridnames{19}{3}='r11A'; gridnames{19}{4}='r11R'; gridnames{19}{5}='';
%gridnames{20}{1}='my1F'; gridnames{20}{2}='my1B';
gridnames{20}{3}='my1A'; gridnames{20}{4}='my1R'; gridnames{20}{5}='';
%times{1}='E11.5';
%times{2}='E13.5';
%times{3}='E15.5';
%times{4}='E18.5';
%times{5}='P4';
%times{6}='P14';
%times{7}='P28';

```

```

function ABACodes_mainprogram(ngenes, nx, ny, gridnames, ntimesteps,
times, braindata, outputfilename)

```

```

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%
% Generate robust components for each gene expression data.
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%

```

```

% Vary thresholds of expression values and choose the clustering with the
longest durations in threshold values.

```

```

lwdvalthre=0.2;
uppvalthre=1.0;
tmp=braindata(:);
tmp(find(~(tmp>=0)))=0;
tmp=tmp(find(tmp>=0));
valthre=prctile(tmp,70);
clear genecomponents;
xlabel=zeros(nx,ny);
for il=1:nx
    for i2=1:ny
        str=gridnames{il}{i2};
        if (length(str)>0)
            xlabel(il,i2)=1;
        end
    end
end

```

```

for n=1:ngenes

```



```

% Reactivate small but recurrent components.
% The matched components at other time steps should not be too large.
% Very small components (<=2 substructures) have to find matched ones in
two more time points.
% Discard very small components (<=2 substructures).
distthre=2; newgenecompsselected=genecompsselected; foldthre=3;
smallcompsize=2;
for n=1:ngenes
    for t1=1:ntimesteps
        for i1=1:genecomponents{n}{t1}.ncomponents
            if (genecompsselected{n}{t1}(i1)==0)
                matches=zeros(1,ntimesteps);
                for t2=1:ntimesteps
                    if (t1~=t2)
                        for i2=1:genecomponents{n}{t2}.ncomponents
                            points1=genecomponents{n}{t1}.components{i1};
                            points2=genecomponents{n}{t2}.components{i2};
                            n1=length(points1(:,1)); n2=length(points2(:,1));
                            dists=nx*ny*ones(n1,n2);
                            for j1=1:n1
                                for j2=1:n2
                                    d=points1(j1,:)-points2(j2,:); dists(j1,j2)=norm(d,2);
                                end
                            end
                        end
                    end
                    if
((min(min(dists(:)))<=distthre)&(n1<=(foldthre*n2))&(n2<=(foldthre*n1)))
                        matches(t2)=matches(t2)+1;
                    end
                end
            end
        end
    end
    if (n1<=smallcompsize)
        newgenecompsselected{n}{t1}(i1)=0;
    elseif ((n1>smallcompsize)&(sum(matches>0)>0))
        newgenecompsselected{n}{t1}(i1)=1;
    end
end
end
end
end

```

```

genecompsselected=newgenecompsselected;

```

```

% Remove the discarded components.
clear newgenecomponents;
for n=1:ngenes
    for t=1:ntimesteps
        twodmat=zeros(nx,ny);
        for i1=1:nx
            for i2=1:ny
                twodmat(i1,i2)=braindata(n,i1,i2,t);
            end
        end
    end
end

```

```

end
end
subset=find(genecompsselected{n}{t}==1);
if (length(subset)<=0)
    newgenecomponents{n}{t}.ncomponents=0;
    newgenecomponents{n}{t}.components={};
else
    newgenecomponents{n}{t}.ncomponents=length(subset);
    for i=1:newgenecomponents{n}{t}.ncomponents
        j=subset(i);
        points=genecomponents{n}{t}.components{j};
        selected=zeros(1,length(points(:,1)));
        for k=1:length(selected)
            if (twodmat(points(k,1),points(k,2))>=0)
                selected(k)=1;
            end
        end
        points=points(find(selected==1),:);
        newgenecomponents{n}{t}.components{i}=points;
    end
end
end
end
end

```

```

% Generate mappings between components.
distthre=2; foldthre=2; comparablefoldthre=0.75; smallcompsizethre=2;
largecompsizethre=20;
clear genelineages ngenetotalcomps genetotalcomplists genecompmappings
genemappingtypes genelineagetopologies;
for n=1:ngenes

```

```

[ngenetotalcomps{n},genetotalcomplists{n},genecompmappings{n}]=generate_co
mpmapping(braindata,newgenecomponents{n},expressionstates(n,:),distthre,fo
ldthre,comparablefoldthre,smallcompsizethre,largecompsizethre);
end

```

```

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%
% Find localized spatial-temporal expression patterns.
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%%%

```

```

% A component is localized if (1)its conex hull is not much larger than
the component, (2)it is not very large.
% Only consider the components with lineage relations to other components.
largecompthre=50; fracthre=0.75; holethre=8; largecompfracthre=0.5;
clear localized;
for n=1:ngenes
    for t=1:ntimesteps
        localized{n}{t}=zeros(1,newgenecomponents{n}{t}.ncomponents);
    end
end

```

```

if (expressionstates(n,t)<=0)
    twodmat=zeros(nx,ny);
    for i1=1:nx
        for i2=1:ny
            twodmat(i1,i2)=braindata(n,i1,i2,t);
        end
    end
    nvalidentries=sum(twodmat(:)>=0);
    for i=1:newgenecomponents{n}{t}.ncomponents

ind=find((genetotalcomplots{n}(:,1)==t)&(genetotalcomplots{n}(:,2)==i));
    if
((sum(genecompmappings{n}(ind,:)>0)>0)|(sum(genecompmappings{n}(:,ind)>0)>
0))
        points=newgenecomponents{n}{t}.components{i};
npoints=length(points(:,1));
        s=find((points(:,1)>=0)&(points(:,2)>=0));
        if ((length(s)/nvalidentries)<=largecompfracthre)&(npoints>2))
            % Handle the colinear cases.
            if (collinear(points)==1)
                if (length(unique(points(:,1)))>1)
                    [yy,ii]=sort(points(:,1)); points=points(ii,:);
K=transpose([1:npoints 1]);
                else
                    [yy,ii]=sort(points(:,2)); points=points(ii,:);
K=transpose([1:npoints 1]);
                end
            else
                K=convhull(points(:,1),points(:,2));
            end
            minx=min(points(:,1)); maxx=max(points(:,1));
            miny=min(points(:,2)); maxy=max(points(:,2));
            ncands=0; cand=[];
            for x=minx:maxx
                for y=miny:maxy
                    if (twodmat(x,y)>=0)
                        ncands=ncands+1; cand(ncands,:)=[x y];
                    end
                end
            end
            indicators=inpolygon(cand(:,1),cand(:,2),points(K,1),points(K,2));
            r=npoints/sum(indicators==1);
            if ((r>=fracthre)&((sum(indicators==1)-npoints)<holethre))
                localized{n}{t}(i)=1;
            end
        end
    end
end
end
end
end
end

% Extract localized clusters.

```

```

nlocalclusters=0; clear localclusters localclusterinfo;
for n=1:ngenes
    for t=1:ntimesteps
        for i=1:newgenecomponents{n}{t}.ncomponents;
            if
((localized{n}{t}(i)==1)&(length(newgenecomponents{n}{t}.components{i}(:,1)
))>=5))
                nlocalclusters=nlocalclusters+1;
                localclusterinfo(nlocalclusters,:)=[n t i];
                localclusters{nlocalclusters}=newgenecomponents{n}{t}.components{i};
            end
        end
    end
end
end

```

```

% Group localized clusters together.
% Compute pairwise similarities of clusters.
% Similarity of clusters i and j are |intersect(i,j)|/max(|cluster
i|,|cluster j|).
clusim=zeros(nlocalclusters,nlocalclusters);
for n=1:(nlocalclusters-1)
    clusim(n,n)=1;
    zz1=zeros(nx,ny);
    for i=1:length(localclusters{n}(:,1))
        zz1(localclusters{n}(i,1),localclusters{n}(i,2))=zz1(localclusters{n}(i,1)
,localclusters{n}(i,2))+1;
    end
    k1=sum(sum(zz1>0));
    for m=(n+1):nlocalclusters
        zz2=zeros(nx,ny);
        for i=1:length(localclusters{m}(:,1))
            zz2(localclusters{m}(i,1),localclusters{m}(i,2))=zz2(localclusters{m}(i,1)
,localclusters{m}(i,2))+1;
        end
        k2=sum(sum(zz2>0));
        k3=sum(sum((zz1>0)&(zz2>0)));
        clusim(n,m)=k3/max(k1,k2);
        clusim(m,n)=clusim(n,m);
    end
end
end

```

```

% Find cliques and clusters from the similarity graph.
wthrel=0.5; wthre2=0.4;

```

```

[ncliques,cliques,nclus,clus]=find_cliques_clusters(clusim,wthrel,wthre2);

```

```

% Groups consist of >= 10 localized clusters.
ngroups=0; clear groups; sizethre=10;
for n=1:nclus
    if (length(clus{n})>=sizethre)

```

```

    ngroups=ngroups+1; groups{ngroups}=clus{n};
end
end

% Assign genes to each group.
% One gene may consists of patterns belonging to multiple groups.
% Also, specify assignments for each time point.
groupassignments=zeros(ntimesteps,ngroups,ngenes);
for m=1:ngroups
    for n=1:length(groups{m})
        i=groups{m}(n); ind=localclusterinfo(i,1); t=localclusterinfo(i,2);
        groupassignments(t,m,ind)=1;
    end
end

save(outputfilename,'genecomponents','expressionstates','newgenecomponents',
    'nlocalclusters','localclusters','groupassignments');

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% detect_stable_clusters.m
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

% Detect stable clusters on 2D grids.
% Vary the threshold value and trace the evolution of each connected
component. Report components with long survival durations.
% If the upper limit of the first interval is small, then do not choose
the first interval as many weak points will be included.

function [ncomponents, components] = detect_stable_clusters(twodmat,
refmat, lwdvalthre, uppvalthre, valthre)

[nx,ny]=size(twodmat);

vals=twodmat(:); vals=unique(vals);
vals=vals(find((vals>=0)|(vals<0)));
vals=sort(vals);

% Fill the missing entries with the neighboring valid values.
newtwodmat=twodmat;
for il=1:nx
    for i2=1:ny
        if ((refmat(il,i2)>0)&(~(twodmat(il,i2)>=0)))
            nentries=0; entries=[];
            if ((il>1)&(twodmat(il-1,i2)>=0))
                nentries=nentries+1; entries(nentries)=twodmat(il-1,i2);
            end
        end
    end
end

```



```

elseif ((i1<nx)&(twodmat(i1+1,i2)>=0))
    nentries=nentries+1; entries(nentries)=twodmat(i1+1,i2);
elseif ((i2>1)&(twodmat(i1,i2-1)>=0))
    nentries=nentries+1; entries(nentries)=twodmat(i1,i2-1);
elseif ((i2<ny)&(twodmat(i1,i2+1)>=0))
    nentries=nentries+1; entries(nentries)=twodmat(i1,i2+1);
elseif ((i1>1)&(i2>1)&(twodmat(i1-1,i2-1)>=0))
    nentries=nentries+1; entries(nentries)=twodmat(i1-1,i2-1);
elseif ((i1<nx)&(i2>1)&(twodmat(i1+1,i2-1)>=0))
    nentries=nentries+1; entries(nentries)=twodmat(i1+1,i2-1);
elseif ((i1>1)&(i2<ny)&(twodmat(i1-1,i2+1)>=0))
    nentries=nentries+1; entries(nentries)=twodmat(i1-1,i2+1);
elseif ((i1<nx)&(i2<ny)&(twodmat(i1+1,i2+1)>=0))
    nentries=nentries+1; entries(nentries)=twodmat(i1+1,i2+1);
end
newtwodmat(i1,i2)=mean(entries);
end
end
end

```

```

nnodes=0; coords=[];
for i1=1:nx
    for i2=1:ny
        if (refmat(i1,i2)>0)
            nnodes=nnodes+1; coords(nnodes,:)=[i1 i2];
        end
    end
end
end

```

```

% If the minimum value >= uppvalthre, then all data points belong to one
component.

```

```

if (vals(1)>=uppvalthre)
    ncomponents=1;
    components{1}=coords;
    return;
end

```

```

% If the maximum value <= lwdvalthre, then there is no component.

```

```

if (vals(length(vals))<=lwdvalthre)
    ncomponents=0; components=[];
    return;
end

```

```

G=zeros(nnodes,nnodes);
for i=1:nnodes
    c1=coords(i,1:2); G(i,i)=1;
    for j=(i+1):nnodes
        c2=coords(j,1:2); flag=0;
        if ((c1(1)==c2(1))&(abs(c1(2)-c2(2))==1))
            flag=1;
        elseif ((c1(2)==c2(2))&(abs(c1(1)-c2(1))==1))

```

```

    flag=1;
elseif ((abs(c1(1)-c2(1))==1)&(abs(c1(2)-c2(2))==1))
    flag=1;
end
if (flag==1)
    G(i,j)=1; G(j,i)=1;
end
end
end

% Generate the evolutionary history of clusters.
% Record the number of cluster for each threshold value.
nclusters=0; clusters={}; ncs=zeros(1,length(vals));
for ind=1:length(vals)
    val=vals(ind);
    [a,b]=find(newtwodmat>=val);
    nsubnodes=length(a);
    inds=zeros(1,nsubnodes);
    for i=1:nsubnodes
        k=find((coords(:,1)==a(i))&(coords(:,2)==b(i)));
        inds(i)=k;
    end
    subG=G(inds,inds);
    [ncomps,comps]=find_conn_comps(nsubnodes,subG);
    ncs(ind)=ncomps;
    nnewclusters=nclusters; newclusters=clusters;
    for n=1:ncomps
        pas=[]; npas=0;
        for i=1:nclusters
            if (sum(ismember(comps{n}.comps,clusters{i}.comps)==1)==comps{n}.n)
                npas=npas+1; pas(npas,:)=[i clusters{i}.birth];
            end
        end
        if (npas>0)
            k=find(pas(:,2)>=max(pas(:,2))); k=pas(k,1);
        else
            k=0;
        end
        nnewclusters=nnewclusters+1;
        newclusters{nnewclusters}.birth=ind;
        newclusters{nnewclusters}.death=length(vals);
        newclusters{nnewclusters}.pa=k;
        newclusters{nnewclusters}.chl=[];
        if (k>0)
            newclusters{k}.death=ind;
            newclusters{k}.chl(1+length(newclusters{k}.chl))=nnewclusters;
        end
        newclusters{nnewclusters}.comps=comps{n}.comps;
    end
    nclusters=nnewclusters; clusters=newclusters;
end
end

```

```

% Calculate the survival duration of each threshold interval.
nintervals=1; intervals=[1 0]; curn=ncs(1);
for ind=2:length(vals)
    if (ncs(ind)~=curn)
        intervals(nintervals,2)=ind-1; curn=ncs(ind);
        nintervals=nintervals+1; intervals(nintervals,1)=ind;
    end
end
intervals(nintervals,2)=length(vals);
intervalds=intervals(:,2)-intervals(:,1);

% Only consider the intervals within the range of [lwdvalthre,uppvalthre].
% If the upper value of the first interval < valthre, then do not consider
the first interval.

isselected=zeros(1,nintervals);
startind=min(find(vals>=lwdvalthre));
endind=max(find(vals<=uppvalthre));
for i=1:nintervals
    if ((intervals(i,2)>=startind)&(intervals(i,1)<=endind))
        isselected(i)=1;
    end
end
if ((nintervals>1)&(vals(intervals(1,2))<valthre))
    isselected(1)=0;
end
selected=find(isselected==1);
if (length(selected)>0)
    intervalds=intervals(selected,2)-intervals(selected,1);
    k=find(intervalds>=max(intervalds)); k=k(1); k=selected(k);
    vall=vals(intervals(k,1));
    val2=vals(intervals(k,2));
    if (vall<lwdvalthre)
        if (val2>uppvalthre)
            %val=lwdvalthre;
            val=valthre;
        else
            val=val2;
        end
    else
        val=vall;
    end
else
    val=valthre;
end

[a,b]=find(newtwodmat>=val);
nsubnodes=length(a);
inds=zeros(1,nsubnodes);
for i=1:nsubnodes
    k=find((coords(:,1)==a(i))&(coords(:,2)==b(i)));
    inds(i)=k;
end

```

```

end
subG=G(inds,inds);
[ncomps,comps]=find_conn_comps(nsubnodes,subG);
ncomponents=ncomps; clear components;
for n=1:ncomponents
    components{n}=zeros(comps{n}.n,2);
    for i=1:comps{n}.n
        j=inds(comps{n}.comps(i));
        components{n}(i,:)=[coords(j,1) coords(j,2)];
    end
end
end

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% find_random_cluster_size_distribution.m.
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

% Calculate the distribution of top k cluster sizes when randomly set
substructures in a 2D grid to 1s.
% The probability of setting value 1 is the probability that the
substructure expression >= the given threshold value.
% Use this distribution to determine the small clusters to throw away when
constructing the lineages of spatial-temporal patterns.

function clsizedists = find_random_cluster_size_distribution(bkgdata,
refmat, valthre, ndraws, ntops)

% Determine the probability of setting value 1.
tmp=bkgdata(:); tmp=tmp(find(tmp>=0)); p=sum(tmp>=valthre)/length(tmp);
[nx,ny]=size(refmat);

nnodes=0; coords=[];
for i1=1:nx
    for i2=1:ny
        if (refmat(i1,i2)>0)
            nnodes=nnodes+1; coords(nnodes,:)=[i1 i2];
        end
    end
end

G=zeros(nnodes,nnodes);
for i=1:nnodes
    c1=coords(i,1:2); G(i,i)=1;
    for j=(i+1):nnodes
        c2=coords(j,1:2); flag=0;
        if ((c1(1)==c2(1))&(abs(c1(2)-c2(2))==1))
            flag=1;
        elseif ((c1(2)==c2(2))&(abs(c1(1)-c2(1))==1))
            flag=1;
        elseif ((abs(c1(1)-c2(1))==1)&(abs(c1(2)-c2(2))==1))
            flag=1;
        end
    end
end

```

```

    end
    if (flag==1)
        G(i,j)=1; G(j,i)=1;
    end
end
end

% Randomly generate binary patterns and count the max cluster size.
maxclsize=sum(refmat(:)>0); clsizedists=zeros(ntops,maxclsize+1);
for drawind=1:ndraws

    randmat=rand(nx,ny); randmat(find(refmat<=0))=0;
    tmpmat=zeros(nx,ny);
    tmpmat(find(randmat>=(1-p)))=1;
    [a,b]=find(tmpmat>0);
    nsubnodes=length(a);
    inds=zeros(1,nsubnodes);
    for i=1:nsubnodes
        k=find((coords(:,1)==a(i))&(coords(:,2)==b(i)));
        inds(i)=k;
    end

    if (length(inds)<=0)
        ncomps=0;

    else
        subG=G(inds,inds);
        [ncomps,comps]=find_conn_comps(nsubnodes,subG);
    end

    % Count the top k cluster sizes.
    % The components obtained from find_conn_comps are sorted by their sizes.
    for k=1:ntops
        if (k<=ncomps)
            l=comps{k}.n;
        else
            l=0;
        end
        clsizedists(k,l+1)=clsizedists(k,l+1)+1;
    end

end

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% generate_compmapping.m.
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

% Generate the mappings between components.

```

```

function [ntotalcomps, totalcomplist, compmappings] =
generate_compmapping(genedata, genecomponent, expressionstate, distthre,
foldthre, comparablefoldthre, smallcompsizethre, largecompsizethre)

[subgenes,nx,ny,ntimesteps]=size(genedata);

% Establish possible links between components.
% Two components are linked if they satisfy the following conditions:
% (1)Component sizes > smallcompsizethre. (2)One precedes the other.
% (3)Their locations are overlapped or close. (4)None of them specifies
whole-brain expression.
nnodes=0; nodes=[];
for t=1:ntimesteps
    for i=1:genecomponent{t}.ncomponents
        nnodes=nnodes+1; nodes(nnodes,:)= [t i];
    end
end
G=zeros(nnodes,nnodes);
for ind1=1:nnodes
    for ind2=1:nnodes
        if ((ind1~=ind2)&(nodes(ind1,1)<nodes(ind2,1)))
            t1=nodes(ind1,1); i1=nodes(ind1,2);
            t2=nodes(ind2,1); i2=nodes(ind2,2);
            n1=length(genecomponent{t1}.components{i1}(:,1));
            n2=length(genecomponent{t2}.components{i2}(:,1));
            if
((expressionstate(t1)~=1)&(expressionstate(t2)~=1)&(n1>smallcompsizethre)&
(n2>smallcompsizethre))
                points1=genecomponent{t1}.components{i1};
                points2=genecomponent{t2}.components{i2};
                d=mindist(points1,points2);
                if (d<=distthre)
                    G(ind1,ind2)=1;
                end
            end
        end
    end
end
end

% Filter out noisy links.
% (1)If one component links to components at multiple time points, then
only keep the links with the closest time point.
newG=zeros(nnodes,nnodes);
for ind=1:nnodes
    subset=find(G(ind,:)>0);
    if (length(subset)>0)
        ts=nodes(subset,1); mint=min(ts);
        subset2=subset(find(ts<=mint));
        newG(ind,subset2)=1;
    end
end
end

```

```

% (2)If one component links to multiple components, then either only one
heritage link sustains or this is a fission event.
% If only one child component has a comparable size to the parent
component and all other child components are small, then discard the links
to small components.
% If no child component has a comparable size to the parent component and
all the child components are smaller than the parent component, then keep
the links to all components.
% If multiple child components have comparable or larger sizes as the
parent component, then only keep one link to the component of the most
similar size.
% If multiple child components have comparable or larger sizes as the
parent component, then only keep one links to the component of the closest
distance.
G=newG;
newG=zeros(nnodes,nnodes);
for ind=1:nnodes
    subset=find(G(ind,:)>0);
    if (length(subset)>1)
        cpa=length(genecomponent{nodes(ind,1)}.components{nodes(ind,2)}(:,1));
        cchildren=zeros(1,length(subset));
        for i=1:length(subset)

cchildren(i)=length(genecomponent{nodes(subset(i),1)}.components{nodes(sub
set(i),2)}(:,1));
            end
            nlarge=sum(cchildren>=(comparablefoldthre*cpa));
            nsmall=sum(cchildren<(comparablefoldthre*cpa));
            if (nlarge==1)
                k=find(cchildren>=(comparablefoldthre*cpa)); k=subset(k);
                newG(ind,k)=1;
            elseif (nlarge==0)
                newG(ind,subset)=1;
            else
                ds=1e10*ones(1,length(cchildren));
                for i=1:length(subset)
                    points1=genecomponent{nodes(ind,1)}.components{nodes(ind,2)};

points2=genecomponent{nodes(subset(i),1)}.components{nodes(subset(i),2)};
                    ds(i)=mindist(points1,points2);
                end
                k=find(ds<=min(ds)); k=subset(k);

                %cr=abs(log2(cchildren/cpa));
                %k=find(cr<=min(cr)); k=subset(k);
                %k=find(cchildren>=max(cchildren)); k=subset(k);
                newG(ind,k)=1;
            end
        elseif (length(subset)==1)
            newG(ind,subset)=1;
        end
    end
end

```

```

% (3)If multiple components link to one component, then either only one
heritage link sustains or this is a fusion event.
% If only one parent component has a comparable size to the child
component and all other parent components are small, then discard the
links from small components.
% If no parent component has a comparable size to the child component and
all the parent components are smaller than the child component, then keep
the links from all components.
% If multiple parent components have comparable or larger sizes as the
child component, then only keep one link from the component of the most
similar size.
% If multiple parent components have comparable or larger sizes as the
child component, then only keep one link from the component of the closest
distance.
G=newG;
newG=zeros(nnodes,nnodes);
for ind=1:nnodes
    subset=find(G(:,ind)>0);
    if (length(subset)>1)

cchild=length(genecomponent{nodes(ind,1)}.components{nodes(ind,2)}(:,1));
    cpas=zeros(1,length(subset));
    for i=1:length(subset)

cpas(i)=length(genecomponent{nodes(subset(i),1)}.components{nodes(subset(i)
),2)}(:,1));
        end
        nlarge=sum(cpas>=(comparablefoldthre*cchild));
        nsmall=sum(cpas<(comparablefoldthre*cchild));
        if (nlarge==1)
            k=find(cpas>=(comparablefoldthre*cchild)); k=subset(k);
            newG(k,ind)=1;
        elseif (nlarge==0)
            newG(subset,ind)=1;
        else
            ds=1e10*ones(1,length(cpas));
            for i=1:length(subset)
                points1=genecomponent{nodes(ind,1)}.components{nodes(ind,2)};

points2=genecomponent{nodes(subset(i),1)}.components{nodes(subset(i),2)};
                ds(i)=mindist(points1,points2);
            end
            k=find(ds<=min(ds)); k=subset(k);

            %cr=abs(log2(cpas/cchild));
            %k=find(cr<=min(cr)); k=subset(k);
            %k=find(cpas>=max(cpas)); k=subset(k);
            newG(k,ind)=1;
        end
    elseif (length(subset)==1)
        newG(subset,ind)=1;
    end
end
G=newG;

```



```

ntotalcomps=nnodes;
totalcomplist=nodes;
compmappings=G;

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% mindist.m.
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

% Calculate the minimum distance between two sets of points.
% Discard the points with NaN entries.

function md = mindist(points1, points2)

n1=length(points1(:,1)); n2=length(points2(:,1));
dists=1e20*ones(n1,n2);
for i=1:n1
    for j=1:n2
        vec1=points1(i,:); vec2=points2(j,:);
        if ((sum(~((vec1>=0)|(vec1<=0)))==0)&(sum(~((vec2>=0)|(vec2<=0)))==0))
            d=vec1-vec2; dists(i,j)=norm(d,2);
        end
    end
end

md=min(dists(:));

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% find_cliques_clusters.m.
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

% Find maximal cliques and clusters in an undirected graph.
% wthre1=0.8; wthre2=0.65;

function [ncliques, cliques, nclus, clus] = find_cliques_clusters(W,
wthre1, wthre2)

[nnodes,nnodes]=size(W);

% Sort graph similarities above the threshold.
nweights=0; clear weights;
[a,b]=find(W>=wthre1);
ss=find(a<b);
weights(:,1)=a(ss); weights(:,2)=b(ss);
nweights=length(weights(:,1));
for i=1:nweights
    weights(i,3)=W(weights(i,1),weights(i,2));
end

%nweights=0; clear weights;
%for n=1:nnodes

```

```

% for m=(n+1):nnodes
%   if (W(n,m)>=wthrel)
%     nweights=nweights+1; weights(nweights,:)= [n m W(n,m)];
%   end
% end
%end

[Y,I]=sort(unique(weights(:,3)),'descend'); sweights=Y;
nweights=length(sweights);

ncliques=0; clear cliques; flag=1; curind=1; thre=sweights(curind);

while (flag==1)

% Try to merge cliques obtained from previous steps with the new edges.
clmemberships=zeros(1,nnodes);
if (ncliques>0)
G=zeros(ncliques,ncliques);
for i=1:ncliques
set1=cliques{i}; G(i,i)=1;
for j=(i+1):ncliques
set2=cliques{j};
if (sum(sum(W(set1,set2)<thre))==0)
G(i,j)=1; G(j,i)=1;
end
end
end
[ncomps,comps]=find_conn_comps(ncliques,G);
newids=zeros(1,ncliques); nnewids=0;
for n=1:ncomps
subset=comps{n}.comps;
if (sum(sum(G(subset,subset)==0))==0)
nnewids=nnewids+1; newids(subset)=nnewids;
else
tmpG=G(subset,subset);
visited=zeros(1,length(subset)); flag2=1;
while (flag2==1)
subset2=find(visited==0);
if (length(subset2)==0)
flag2=0;
else
ds=sum(tmpG(:,subset2));
vs=zeros(1,length(subset2));
for i=1:length(subset2)
subset3=[find(visited==1) subset2(i)];
if (sum(sum(tmpG(subset3,subset3)==0))==0)
vs(i)=1;
end
end
if (sum(vs==1)>0)
maxd=max(ds(find(vs==1)));
i=find((ds>=maxd)&(vs==1)); i=i(1);
visited(subset2(i))=1;
else

```

```

        flag2=0;
    end
end
end
end
tmpset=subset(find(visited==1));
nnewids=nnewids+1; newids(tmpset)=nnewids;
for i=1:length(subset)
    j=subset(i);
    if (ismember(j,tmpset)==0)
        nnewids=nnewids+1; newids(j)=nnewids;
    end
end
end
end
end
for n=1:ncliques
    k=newids(n); clmemberships(cliques{n})=k;
end

nnewcliques=nnewids; clear newcliques;
for n=1:nnewcliques
    newcliques{n}=find(clmemberships==n);
end
ncliques=nnewcliques; cliques=newcliques;

end

% Sort nodes not belonging to existing cliques according to their
connectivity.
conns=-1*ones(1,nnodes);
for n=1:nnodes
    if (clmemberships(n)<=0)
        k=sum(W(n,:)>=thre); conns(n)=k;
    end
end
[sortedconns,sortednodes]=sort(conns,'descend');

% Try to assign newly emerged nodes to existing cliques.
% If there are multiple candidate cliques then choose the largest one.
if (ncliques>0)
    for m=1:nnodes
        if (sortedconns(m)>0)
            n=sortednodes(m); cands=[]; candsizes=[];
            for i=1:ncliques
                if (sum(W(n,cliques{i})<thre)==0)
                    cands(1+length(cands))=i;
                    candsizes(1+length(candsizes))=length(cliques{i});
                end
            end
            if (length(cands)>0)
                [Y,I]=sort(candsizes,'descend'); k=cands(I(1));
                clmemberships(n)=k;
            end
        end
    end
end
end

```

```

end
for n=1:ncliques
    subset=find(clmemberships==n);
    cliques{n}=subset;
end
end

% Try to generate new cliques from the newly emerged nodes.
% Start with singleton cliques.
conns=zeros(1,nnodes);
subset=find(clmemberships<=0);
for n=1:nnodes
    if (clmemberships(n)<=0)
        conns(n)=sum(W(n,subset)>=thre);
    end
end
[Y,I]=sort(conns,'descend');
nnewcliques=sum(conns>0); clear newcliques;
for n=1:nnewcliques
    newcliques{n}=I(n);
end

% Iteratively merge two cliques until no pairs are mergeable.
flag2=1;
while (flag2==1)
    mergeable=0; i=1; inds=zeros(1,2);
    while ((i<=(nnewcliques-1))&(mergeable==0))
        j=i+1; set1=newcliques{i};
        while ((j<=nnewcliques)&(mergeable==0))
            set2=newcliques{j};
            if (sum(sum(W(set1,set2)<thre))==0)
                mergeable=1; inds=[i j];
            end
            j=j+1;
        end
        i=i+1;
    end
    if (mergeable==1)
        i=inds(1); j=inds(2);
        newcliques{i}=union(newcliques{i},newcliques{j});
        for k=j:(nnewcliques-1)
            newcliques{k}=newcliques{k+1};
        end
        nnewcliques=nnewcliques-1;
    else
        flag2=0;
    end
end

% Add new cliques to the records.
% Only consider cliques with more than one member.
n=1;
%for n=1:nnewcliques

```

```

while ((n<=nnewcliques)&(length(newcliques{n})>1))
  %if (length(newcliques{n})>1)
  cliques{ncliques+n}=newcliques{n};
  %end
  n=n+1;
end
%ncliques=nnewcliques;
ncliques=ncliques+n-1;

% Sort cliques by their sizes.
clsizes=zeros(1,ncliques);
for n=1:ncliques
  clsizes(n)=length(cliques{n});
end
[Y,I]=sort(clsizes,'descend');
clear newcliques nnewcliques;
for n=1:ncliques
  newcliques{n}=cliques{I(n)};
end
cliques=newcliques;

% Stop when curind reaches the upper limit.
curind=curind+1;
if (curind>nsweights)
  flag=0;
else
  thre=sweights(curind);
  if (thre<wthrel)
    flag=0;
  end
end

end

% Merge cliques into clusters.
nclus=ncliques; clus=cliques; flag=1;

while (flag==1)

  % Sort clusters by sizes.
  clsizes=zeros(1,nclus);
  for n=1:nclus
    clsizes(n)=length(clus{n});
  end
  [Y,I]=sort(clsizes,'descend');
  clear newclus;
  for m=1:nclus
    n=I(m); newclus{m}=clus{n};
  end
  clus=newclus; clear newclus;

  % Choose two mergeable clusters.

```

```

mergeable=0; i=1; inds=zeros(1,2);
while ((i<=(nclus-1))&(mergeable==0))
    j=i+1;
    while ((j<=nclus)&(mergeable==0))
        set1=clus{i}; n1=length(set1);
        set2=clus{j}; n2=length(set2);

        %n1=length(set1); n2=length(set2);

        % Compute the intra-cluster mean score.
        tmpW1=W(set1,set1); tmpW1=triu(tmpW1);
        tmpW2=-1*ones(length(set1),length(set1)); tmpW2=tril(tmpW2);
        tmpW=tmpW1+tmpW2;
        for k=1:length(set1)
            tmpW(k,k)=tmpW1(k,k);
        end
        v1=sum(sum(tmpW(find(tmpW>=0))));
        tmpW1=W(set2,set2); tmpW1=triu(tmpW1);
        tmpW2=-1*ones(length(set2),length(set2)); tmpW2=tril(tmpW2);
        tmpW=tmpW1+tmpW2;
        for k=1:length(set2)
            tmpW(k,k)=tmpW1(k,k);
        end
        v2=sum(sum(tmpW(find(tmpW>=0))));
        val1=(v1+v2)/((n1*(n1+1)/2)+(n2*(n2+1)/2));

        % Compute the inter-cluster mean score.
        tmpW=W(set1,set2); v3=sum(sum(tmpW));
        val2=v3/(n1*n2);

        % Compute the joint mean score.
        val3=(v1+v2+v3)/((n1*(n1+1)/2)+(n2*(n2+1)/2)+n1*n2);

        % Count the fraction of inter-cluster entries with scores >= threshold.
        f=sum(sum(W(set1,set2)>=wthre2))/(n1*n2);

        % Check if the difference of the mean correlation coefficients is
small.
        % Do not merge singletons.
        % Also do not merge if the joint cluster mean correlation <= wthrel.
        %if (((val1-val2)<=diffthre)&(n1>1)&(n2>1)&(val3>=wthrel))
        %if (val2>=0.65)
        %if (f>=0.9)
        %if (val2>=wthre2)
        if (f>=0.7)
        %if (f>=0.9)
            mergeable=1; inds=[i j];
        end

        j=j+1;
    end
    i=i+1;
end

```

```

% Merge two clusters.
if (mergeable==1)

    i=inds(1); j=inds(2);
    clus{i}=union(clus{i},clus{j});
    for k=j:(nclus-1)
        clus{k}=clus{k+1};
    end
    nclus=nclus-1;
else
    flag=0;
end

end

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% find_conn_comps.m.
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

% Find all connected components of a graph.

function [nconncomps, conncomps] = find_conn_comps(nnodes, G)

% Recursively label nodes in the graph until all nodes are labeled.
labeled=zeros(1,nnodes); flag=1;

% Label all the singletons.
k=0;
for i=1:nnodes
    tmp=find(G(i,:)>0);
    if (length(tmp)==0)
        k=k+1; labeled(i)=k;
    end
end

while (flag==1)

% Check if all nodes are labeled.
n=0;
for i=1:nnodes
    if (labeled(i)==0)
        n=n+1;
    end
end

% If yes, then return.
if (n==0)
    flag=0;

% Otherwise pick up an unlabeled node and recursively label its neighbors.

```

```

else
i=1; j=0;
while ((i<=nnodes)&(j==0))
if (labeled(i)==0)
j=i;
end
i=i+1;
end
k=k+1;
labeled=recurse_label2(j,nnodes,G,labeled,k);
end

end

% Find the connected components from the labels.
nconncomps=k; clear conncomps;
for i=1:nconncomps
conncomps{i}.n=0;
conncomps{i}.comps=[];
end

for i=1:nnodes
j=labeled(i);
conncomps{j}.n=conncomps{j}.n+1;
conncomps{j}.comps(conncomps{j}.n)=i;
end

% Sort the connected components by size.
tmp=zeros(1,nconncomps);
for i=1:nconncomps
tmp(i)=conncomps{i}.n;
end
[Y,I]=sort(tmp,'descend'); clear tmp2;
for i=1:nconncomps
tmp2{i}=conncomps{I(i)};
end
conncomps=tmp2;

% Discard the connected components which do not have type 1 or type 2
nodes.
discard=zeros(1,nconncomps);
for i=1:nconncomps
if (conncomps{i}.n<=0)
discard(i)=1;
end
end
tmp=find(discard==0);
for i=1:length(tmp)
tmp2{i}=conncomps{tmp(i)};
end
nconncomps=length(tmp); conncomps=tmp2;

clear tmp tmp2 Y I discard;

```



```

%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% recurse_label2.m.
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

% Recursively label nodes in a graph.
% Difference from recurse_label.m: not on a bipartite graph.

function labeled = recurse_label2(ind, nnodes, G, labeled, label)

% Label the target node.
labeled(ind)=label;

% Recursively visit neighbors.
tmp=find(G(ind,:)>0);

% If all neighbors are labeled, then return.
if (sum(labeled(tmp)==0)>0)
for i=1:length(tmp)
if (labeled(tmp(i))==0)
labeled=recurse_label2(tmp(i),nnodes,G,labeled,label);
end
end
end
end

```