## **Supplementary Figure 1**



**Supplementary Figure 1**. MANCIE workflow. If the rows in the associated matrix and the main matrix do not match, the summarization step converts the associated matrix to a summarized associated matrix with matched rows. The combination step integrates the main matrix with the summarized associated matrix into the adjusted matrix.

# **Supplementary Figure 2**



dot represents a cell line sample, with x- and yaxes representing the mean and coefficient of variation, respectively, of the CG-content distribution of all reads in the DNase-seq dataset. The size of the dot represents the magnitude of adjustment of MANCIE, measured by the Euclidean distance between the sample data vectors before and after MANCIE adjustment.

### **Supplementary Figure 3**



**Supplementary Figure 3**. (**a**) The Kaplan-Meier plots for an example showing differences in survival prediction accuracy and the improvement in P-value, using the Beer gene signature. Patient samples were separated into two groups according to the trained risk score using the gene signature with the expression data. High-risk group is labeled in red and low-risk group is labeled in black. The high-risk group is better separated from the lowrisk group by using the MANCIE-adjusted expression data (right), compared with using the raw data (left).

(**b**) Distribution of P-value scores (-log10Pvalue) for the prognostic prediction with the Beer gene signature, comparing raw expression data (top) and MANCIE-adjusted expression data (bottom), from TCGA lung cancer (LUAD) cohort.

#### **Choosing Combination Cupplementary Figure 4**



**Supplementary Figure 4**. P-value improvement on the METABRIC data (**a**) and the 6 gene signatures from TCGA data (**b**) under combinations of different MANCIE parameters. Y-axis indicates the difference of P-value scores similar to **Fig. 3c**. Each box plot represents a parameter setting, labeled as (cutoff1, cutoff2) at the bottom.

#### Supplementary Note 1

#### Theoretical Support for MANCIE: an Approximation of Rigorous Statistical Inference

**Problem Description.** Let  $m_i = (m_{i1}, \dots, m_{iK})$  be the *i*-th row (i.e., feature) of the main matrix M, and  $c_i = (c_{i1}, \dots, c_{iK})$  be its counterpart in the associated matrix C, where each  $k \in \{1, \dots, K\}$  stands for one sample or condition. Since  $(m_{ik}, c_{ik})^T$  are observations of feature i from different biological experiments which often contain a lot of uncertainty, it's natural to assume that they are the noised version of the underlying "truth"  $(m_{ik}^*, c_{ik}^*)^T$ , i.e.,

$$
(m_{ik}, c_{ik})^T = (m_{ik}^*, c_{ik}^*)^T + \varepsilon_{ik},
$$

where  $\varepsilon_{ik}$  is a two-dimensional noise vector. MANCIE aims to remove noise in  $m_i$  by borrowing information from  $c_i$ , i.e., inferring  $m_i^* = (m_{i1}^*, \dots, m_{iK}^*)$  based on both  $m_i$  and  $c_i$ .

**Statistical Model & Inference.** To simplify the problem, let's assume that both  $\{(m_{ik}^*, c_{ik}^*)^T\}_{k=1}^K$ and  $\{\varepsilon_{ik}\}_{k=1}^K$  are i.i.d. samples of Gaussian distributions, i.e.,

$$
(m_{ik}^*, c_{ik}^*)^T \sim N(\mu_i, \Sigma_i) \text{ and } \varepsilon_{ik} \sim N(\mathbf{0}, \Delta_i),
$$
  
where  $\Sigma_i = \begin{pmatrix} 1 & \rho_i \\ \rho_i & 1 \end{pmatrix}$ ,  $\Delta_i = \begin{pmatrix} \delta_{im}^2 & 0 \\ 0 & \delta_{ic}^2 \end{pmatrix}$ ,  $\{(m_{ik}^*, c_{ik}^*)^T\}_{k=1}^K$  and  $\{\varepsilon_{ik}\}_{k=1}^K$  are independent  
of each other, and  $\rho_i > 0$ . Clearly,  $\delta_{im}^2$  and  $\delta_{ic}^2$  stands for the noise-signal ratio of  $m_i$  and  $c_i$   
respectively, where a larger  $\delta^2$  means lower quality of the data. Here, we assume that  $\delta_{ic}^2 \ge \delta_{im}^2$   
as the main matrix usually enjoys better quality.

Under this model, we have

$$
(m_{ik}, c_{ik})^T \mid (m_{ik}^*, c_{ik}^*)^T \sim N((m_{ik}^*, c_{ik}^*)^T, \Delta_i),
$$

$$
(m_{ik}, c_{ik})^T \sim N(\mu_i, \Sigma_i + \Delta_i).
$$

And, it's easy to check that

$$
\tilde{\rho}_i = cor(m_i, c_i) = \frac{\rho_i}{\sqrt{(1 + \delta_{im}^2)(1 + \delta_{ic}^2)}} \le \rho_i = cor(m_i^*, c_i^*),
$$

i.e., the correlation coefficient of the observed data  $(m_i, c_i)$  is always smaller than the true correlation coefficient  $cov(c_i^*, m_i^*)$ , and the difference depends on the noise level  $(\delta_{im}^2, \delta_{ic}^2)$ . Without loss of generality, we can also assume that  $\mu_i = 0$  for any feature i (i.e., the observed data are centralized).

Now, assume that both  $\Sigma_i$  and  $\Delta_i$  are known. Based on the Bayes rule, we have the following posterior distribution for  $(m_{ik}^*, c_{ik}^*)^T$ :

$$
f((m_{ik}^{*}, c_{ik}^{*})^{T} | (m_{ik}, c_{ik})^{T})
$$
  
\n
$$
\propto \pi((m_{ik}^{*}, c_{ik}^{*})^{T}) \cdot f((m_{ik}, c_{ik})^{T} | (m_{ik}^{*}, c_{ik}^{*})^{T})
$$
  
\n
$$
\propto \exp \left\{-\frac{1}{2}(m_{ik}^{*}, c_{ik}^{*})\sum_{i}^{T} (m_{ik}^{*}, c_{ik}^{*})^{T}\right\} \times
$$
  
\n
$$
\exp \left\{-\frac{1}{2}[(m_{ik}, c_{ik}) - (m_{ik}^{*}, c_{ik}^{*})]\Delta_{i}^{-1}[(m_{ik}, c_{ik}) - (m_{ik}^{*}, c_{ik}^{*})]^{T}\right\}
$$
  
\n
$$
\sim N((\sum_{i}^{-1} + \Delta_{i}^{-1})^{-1}\Delta_{i}^{-1}(m_{ik}, c_{ik})^{T}, (\sum_{i}^{-1} + \Delta_{i}^{-1})^{-1}),
$$

which means that the best guess for the unknown  $(m_{ik}^*, c_{ik}^*)^T$  should be the posterior mean

$$
\nu_{ik} = (\Sigma_{i}^{-1} + \Delta_{i}^{-1})^{-1} \Delta_{i}^{-1} (m_{ik}, c_{ik})^{T}
$$
  
 
$$
\propto \begin{pmatrix} \delta_{ic}^{2} + 1 - \rho_{i}^{2} & \rho_{i} \delta_{im}^{2} \\ \rho_{i} \delta_{ic}^{2} & \delta_{im}^{2} + 1 - \rho_{i}^{2} \end{pmatrix} \begin{pmatrix} m_{ik} \\ c_{ik} \end{pmatrix}.
$$

Since we are interested in improving the main matrix, we will only focus on

$$
E(m_{ik}^* \mid m_{ik}, c_{ik}) \propto m_{ik} + \frac{\rho_i \delta_{im}^2}{\delta_{ic}^2 + (1 - \rho_i^2)} \cdot c_{ik}.
$$

MANCIE as an Approximation of Rigorous Statistical Inference. In practice, however, we can only estimate  $(\Sigma_i + \Delta_i)$  from the observed data  $m_i$  and  $c_i$ , and neither  $\Sigma_i$  or  $\Delta_i$  is estimable on their own. Therefore,  $h(\rho_i) = \frac{\rho_i \delta_{im}^2}{\delta_{ic}^2 + (1 - \rho_i^2)}$ , and thus  $E(m_{ik}^* \mid m_{ik}, c_{ik})$ , cannot be precisely known. Fortuanately, the following facts hold for  $h(\rho_i)$ :

\n- (F<sub>1</sub>) 
$$
h(\rho_i) \approx 0
$$
 if  $\rho_i$  is very close to 0,
\n- (F<sub>2</sub>)  $h(\rho_i) \approx \frac{\rho_i \delta_{im}^2}{\delta_{ic}^2 + 1}$  if  $\rho_i$  is close to 0,
\n- (F<sub>3</sub>)  $h(\rho_i) \approx \frac{\delta_{im}^2}{\delta_{ic}^2}$  if  $\rho_i$  is very close to 1,
\n

which correspond to the three scenarios (a), (b) and (c) in the subsection of "Removing noise in matrix" respectively under proper conditions.

Clearly,  $(F_1)$  matches to scenarios (a). Let  $\tilde{m}_i = \frac{m_i}{\sqrt{\delta_{im}^2 + 1}}$  and  $\tilde{c}_i = \frac{c_i}{\sqrt{\delta_{ic}^2 + 1}}$  be the rescaled data (i.e., "scale( $m_i$ )" and "scale( $c_i$ )" in the paper). The new vector  $m'$  defined in scenarios (b) is:

$$
m'_i = \tilde{m}_i + \tilde{\rho}_i \cdot \tilde{c}_i = \frac{m_i}{\sqrt{\delta_{im}^2 + 1}} + \frac{\rho_i}{\sqrt{(\delta_{im}^2 + 1)(\delta_{ic}^2 + 1)}} \cdot \frac{c_i}{\sqrt{\delta_{ic}^2 + 1}} \propto m_i + \frac{\rho_i}{\delta_{ic}^2 + 1} \cdot c_i,
$$

which matches to  $(F_2)$  when  $\delta_{im}^2$  is close to 1. For scenarios (c), because  $cor(m_i, c_i) = \sum_i + \Delta_i$ , the first principle component of  $cor(m_i, c_i)$  is  $(1, \frac{r_i + \sqrt{r_i^2 + 4}}{2})$  $\frac{\sqrt{r_i^2+4}}{2}$ ), where  $r_i = \frac{\delta_{ic}^2 - \delta_{im}^2}{\rho_i}$ . Thus, the new vector  $m'$  defined in this scenario is

$$
m_i' \propto m_i + \frac{r_i + \sqrt{r_i^2 + 4}}{2}c_i,
$$

which degenerates to  $(m_i + c_i)$  when  $r_i$  is close to 0 (this happens when  $\delta_{im}^2 \approx \delta_{ic}^2$  and the difference  $\delta_{ic}^2 - \delta_{im}^2$  is small compared to  $\rho_i$ ). Considering that  $h(\rho_i)$  also degenerates to 1 when  $\delta_{im}^2 \approx \delta_{ic}^2$  in  $(F_3)$ , we find that  $(F_3)$  matches to scenarios (c) when  $\delta_{im}^2$  and  $\delta_{ic}^2$  are close to each other. Summarizing all three cases, we conclude that MANCIE is a proper approximation of rigorous statistical inference when the noise-signal ratio in both the main matrix and association matrix are close to 1.