

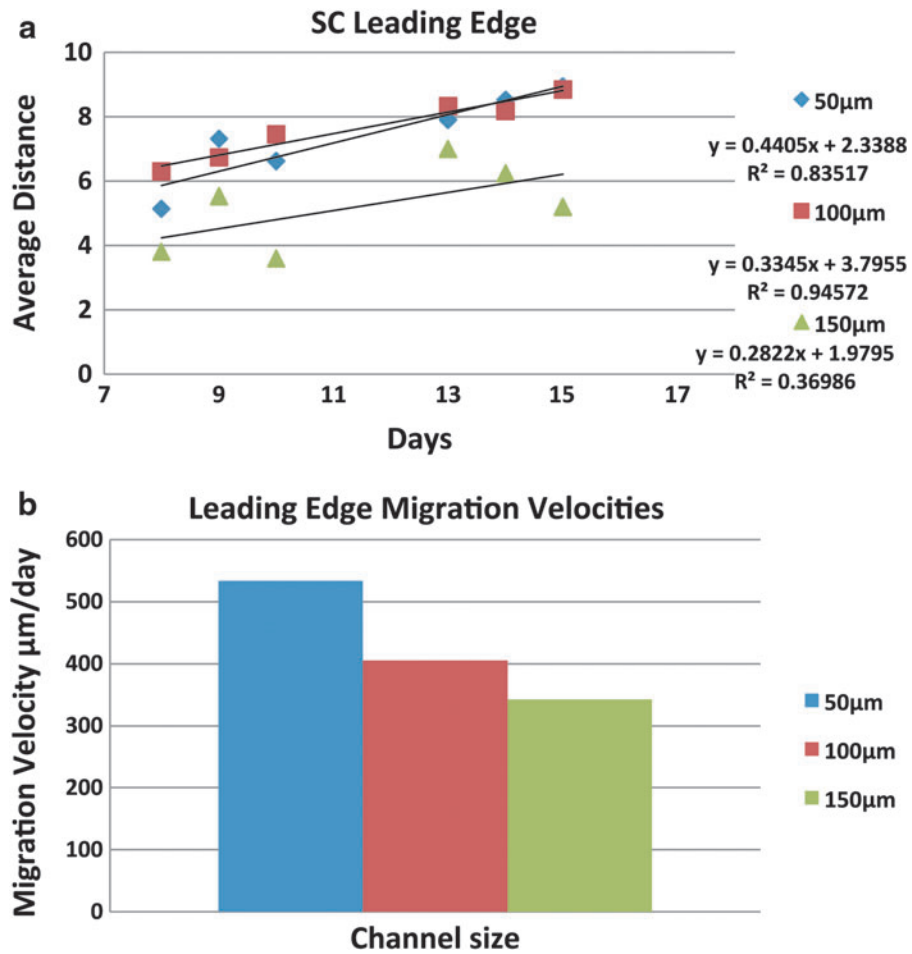
Supplementary Data

	9	8	7	6	5	4	3	2	1	
		1	0	4	5	6	5	2	3	1
		2	0	0	0	2	1	0	0	2
2		6	0	0	6	8	14	10	5	3
		4	2	6	5	4	5	0	0	4
		1	15	3	0	1	0	1	4	5
4		6	6	2	0	12	11	3	0	6
8		11	5	2	22	6	17	1	3	7
			2	5	5	5	5	3	1	8
		21	28	11	5	4	2	3	2	9
2		17	20	13	19	7	12	19	28	10
2		0	0	2	7	10	5	0	9	11

SUPPLEMENTARY FIG. S1. Grid pattern for data acquisition. For each set of experiments, the images were taken daily of each sample in a grid pattern for the entire 1×1 cm patterned surface. The grid is composed of successive rectangular images (1600×1200 pixel) that are numbered sequentially (*column* and *row*) from one end to the other end of the microgrooves and from *top* to *bottom*. The number of cells in each image were counted and entered into each grid.

	9	8	7	6	5	4	3	2	1	
		1	0	4	5	6	5	2	3	1
		2	0	0	0	2	1	0	0	2
2		6	0	0	6	8	14	10	5	3
		4	2	6	5	4	5	0	0	4
		1	15	3	0	1	0	1	4	5
4		6	6	2	0	12	11	3	0	6
8		11	5	2	22	6	17	1	3	7
			2	5	5	5	5	3	1	8
		21	28	11	5	4	2	3	2	9
2		17	20	13	19	7	12	19	28	10
2		0	0	2	7	10	5	0	9	11

SUPPLEMENTARY FIG. S2. Definition of leading edge. The leading edge is defined as the furthest location that the cells traversed in each *row* and is highlighted in *yellow*. An equivalent distance (*e*) of image *x*-*y* was calculated by multiplying the *column* number (*x*) by the actual length of the image (*l*).



SUPPLEMENTARY FIG. S3. Calculation of migration velocities. **(a)** The average distance the cells traverse based on the *column* number is plotted over time, and the y-axis indicates the *column* number in the images. **(b)** The slope from **(a)** is then converted into microns per day by multiplying the actual distance in the image (1212.12 µm) to obtain the migration velocity.

	9	8	7	6	5	4	3	2	1	
	0	1	0	0	0	0	0	0	0	01
	0	1	0	0	0	0	0	0	0	02
	1	0	0	0	0	0	0	0	0	03
	0	1	0	0	0	0	0	0	0	04
	0	1	0	0	0	0	0	0	0	05
	1	0	0	0	0	0	0	0	0	06
	1	0	0	0	0	0	0	0	0	07
	0	0	1	0	0	0	0	0	0	08
	0	1	0	0	0	0	0	0	0	09
	1	0	0	0	0	0	0	0	0	010
	1	0	0	0	0	0	0	0	0	011

SUPPLEMENTARY FIG. S4. Binary method. The binary method counts images as yes (1) or no (0), and it converts the entire grid into a binary field where only the images marked as “1,” highlighted in *yellow*, are selected for subsequent calculations.