

Supplementary Information: Backward transfer entropy: Informational measure for detecting hidden Markov models and its interpretations in thermodynamics, gambling and causality

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Supplementary note 1 | Detailed derivation of the inequality (12) in the main text. To simplify the calculation, we use the notation $\rho(a) := p(A = a)$ and $\rho(a|b) := p(A = a|B = b)$ for any random variables A and B . We also use the notation $\rho_B(a|b) := p_B(A = a|B = b)$ for any random variables A and B . We define ensemble average as $\langle \dots \rangle = \sum_{x_N^{(N)}, y_N^{(N)}} \rho(x_N^{(N)}, y_N^{(N)}) \dots$. We here consider the following non-Markovian interacting dynamics,

$$\rho(x_N^{(N)}, y_N^{(N)}) := \rho(x_1, y_1) \prod_{k'=1}^n \rho(x_{k'+1}|x_{k'}, y_1) \rho(y_{k'+1}|y_{k'}, x_1) \prod_{k=n+1}^{N-1} \rho(x_{k+1}|x_k, y_{k-n}) \rho(y_{k+1}|y_k, x_{k-n}), \quad (1)$$

with $n \geq 1$, and

$$\rho(x_N^{(N)}, y_N^{(N)}) := \rho(x_1, y_1) \prod_{k=1}^{N-1} \rho(x_{k+1}|x_k, y_k) \rho(y_{k+1}|y_k, x_k), \quad (2)$$

with $n = 0$.

To derive the inequality (12) in the main text, we calculate the difference between $I^n(X_N^{(N)} \rightarrow Y_N^{(N)}) - I^n(X_N^{\dagger(N)} \rightarrow Y_N^{\dagger(N)})$ and $-\Delta S_{\mathcal{X}B}$ in the case of $n \geq 1$ as follows;

$$\begin{aligned} & \Delta S_{\mathcal{X}B} + I^n(X_N^{(N)} \rightarrow Y_N^{(N)}) - I^n(X_N^{\dagger(N)} \rightarrow Y_N^{\dagger(N)}) \\ &= \Delta S_{\mathcal{X}B} - \sum_{k=1}^n \left[T_{X_N^{\dagger(1)} \rightarrow Y_N^{\dagger(k+1)}} - T_{X_N^{(1)} \rightarrow Y_N^{(k+1)}} \right] - \sum_{k=n+1}^{N-1} \left[T_{X_N^{\dagger(k-n)} \rightarrow Y_N^{\dagger(k+1)}} - T_{X_N^{(k-n)} \rightarrow Y_N^{(k+1)}} \right] - I(X_N; Y_N) + I(X_1; Y_1) \\ &= \left\langle \ln \left[\frac{\rho(x_1|y_1)}{\rho(x_N|y_N)} \prod_{k'=1}^n \frac{\rho(x_{k'+1}|x_{k'}, y_1)}{\rho_B(x_{k'}|x_{k'+1}, y_1)} \prod_{k=n+1}^{N-1} \frac{\rho(x_{k+1}|x_k, y_{k-n})}{\rho_B(x_k|x_{k+1}, y_{k-n})} \right] \right\rangle + \left\langle \ln \left[\prod_{k'=1}^n \frac{\rho(y_{k'+1}|y_{k'}, x_1)}{\rho(y_{k'+1}|y_{k'})} \prod_{k=n+1}^{N-1} \frac{\rho(y_{k+1}|y_k, x_{k-n})}{\rho(y_{k+1}|y_k)} \right] \right\rangle \\ &\quad + \left\langle \ln \prod_{k'=1}^n \frac{\rho(y_{N-k'}|y_N^{(k')})}{\rho(y_{N-k'}|x_N, y_{N-k'+1})} \prod_{k=n+1}^{N-1} \frac{\rho(y_{N-k}|y_N^{(k)})}{\rho(y_{N-k}|x_{N-k+n+1}, y_{N-k+1})} \right\rangle \\ &= \left\langle \ln \frac{\rho(x_1, y_1) \prod_{k'=1}^n \rho(x_{k'+1}|x_{k'}, y_1) \rho(y_{k'+1}|y_{k'}, x_1) \prod_{k=n+1}^{N-1} \rho(x_{k+1}|x_k, y_{k-n}) \rho(y_{k+1}|y_k, x_{k-n})}{\rho(x_N, y_N) \prod_{k'=n+1}^{N-1} \rho_B(x_{k'}|x_{k'+1}, y_{k'-n}) \prod_{m'=N-n}^{N-1} \rho(y_{m'}|y_{m'+1}, x_N) \prod_{k=1}^n \rho_B(x_k|x_{k+1}, y_1) \prod_{m=1}^{N-n-1} \rho(y_m|y_{m+1}, x_{m+n+1})} \right\rangle \\ &= \sum_{x_N^{(N)}, y_N^{(N)}} \rho(x_N^{(N)}, y_N^{(N)}) \ln \frac{\rho(x_N^{(N)}, y_N^{(N)})}{\tilde{\rho}(x_N^{(N)}, y_N^{(N)})}, \end{aligned} \quad (3)$$

where we used $\rho(y_{k'+1}|y_{k'}^{(k')}, x_1) = \rho(y_{k'+1}|y_{k'}, x_1)$ with $k' \leq n$, $\rho(y_{k+1}|y_k^{(k)}, x_{k-n}) = \rho(y_{k+1}|y_k, x_{k-n})$ with $k \geq n+1$, $\rho(y_{N-k'}|x_N, y_N^{(k')}) = \rho(y_{N-k'}|x_N, y_{N-k'+1})$ with $k' \leq n$, $\rho(y_{N-k}|x_{N-k+n+1}, y_N^{(k)}) = \rho(y_{N-k}|x_{N-k+n+1}, y_{N-k+1})$ with $k \geq n+1$, and $\tilde{\rho}(x_N^{(N)}, y_N^{(N)})$ is defined as

$$\tilde{\rho}(x_N^{(N)}, y_N^{(N)}) := \rho(x_N, y_N) \prod_{k'=n+1}^{N-1} \rho_B(x_{k'}|x_{k'+1}, y_{k'-n}) \prod_{m'=N-n}^{N-1} \rho(y_{m'}|y_{m'+1}, x_N) \prod_{k=1}^n \rho_B(x_k|x_{k+1}, y_1) \prod_{m=1}^{N-n-1} \rho(y_m|y_{m+1}, x_{m+n+1}). \quad (4)$$

In the case of $n = 0$, we have

$$\begin{aligned}
& \Delta S_{\mathcal{X}B} + I^0(X_N^{(N)} \rightarrow Y_N^{(N)}) - I^0(X_N^{\dagger(N)} \rightarrow Y_N^{\dagger(N)}) \\
&= \Delta S_{\mathcal{X}B} - \sum_{k=1}^{N-1} \left[T_{X_k^{\dagger(1)} \rightarrow Y_{k+1}^{(k+1)}} - T_{X_k^{(1)} \rightarrow Y_{k+1}^{(k+1)}} \right] - I(X_N; Y_N) + I(X_1; Y_1) \\
&= \left\langle \ln \left[\frac{\rho(x_1|y_1)}{\rho(x_N|y_N)} \prod_{k=1}^{N-1} \frac{\rho(x_{k+1}|x_k, y_k)}{\rho_B(x_k|x_{k+1}, y_k)} \right] \right\rangle + \left\langle \ln \left[\prod_{k=1}^{N-1} \frac{\rho(y_{k+1}|y_k, x_k)}{\rho(y_{k+1}|y_k^{(k)})} \right] \right\rangle + \left\langle \ln \prod_{k=1}^{N-1} \frac{\rho(y_{N-k}|y_N^{(k)})}{\rho(y_{N-k}|x_{N-k+1}, y_{N-k+1})} \right\rangle \\
&= \left\langle \ln \frac{\rho(x_1, y_1) \prod_{k=1}^{N-1} \rho(x_{k+1}|x_k, y_k) \rho(y_{k+1}|y_k, x_k)}{\rho(x_N, y_N) \prod_{k=1}^{N-1} \rho_B(x_k|x_{k+1}, y_k) \prod_{k=1}^{N-1} \rho(y_k|y_{k+1}, x_{k+1})} \right\rangle \\
&= \sum_{x_N^{(N)}, y_N^{(N)}} \rho(x_N^{(N)}, y_N^{(N)}) \ln \frac{\rho(x_N^{(N)}, y_N^{(N)})}{\tilde{\rho}(x_N^{(N)}, y_N^{(N)})},
\end{aligned} \tag{5}$$

where we used $\rho(y_{k+1}|y_k^{(k)}, x_k) = \rho(y_{k+1}|y_k, x_k)$, $\rho(y_N|x_{N-k+1}, y_N^{(k)}) = \rho(y_{N-k}|x_{N-k+1}, y_{N-k+1})$, and $\tilde{\rho}(x_N^{(N)}, y_N^{(N)})$ is defined as

$$\tilde{\rho}(x_N^{(N)}, y_N^{(N)}) := \rho(x_N, y_N) \prod_{k=1}^{N-1} \rho_B(x_k|x_{k+1}, y_k) \prod_{m=1}^{N-1} \rho(y_m|y_{m+1}, x_{m+1}). \tag{6}$$

The function $\tilde{\rho}(x_N^{(N)}, y_N^{(N)})$ is nonnegative, and satisfies the normalization of the probability;

$$\begin{aligned}
& \sum_{x_N^{(N)}, y_N^{(N)}} \tilde{\rho}(x_N^{(N)}, y_N^{(N)}) \\
&= \sum_{x_N^{(N)}, y_N^{(N)}} \rho(x_N, y_N) \prod_{k'=n+1}^{N-1} \rho_B(x_{k'}|x_{k'+1}, y_{k'-n}) \prod_{m'=N-n}^{N-1} \rho(y_{m'}|y_{m'+1}, x_N) \prod_{k=1}^n \rho_B(x_k|x_{k+1}, y_1) \prod_{m=1}^{N-n-1} \rho(y_m|y_{m+1}, x_{m+n+1}) \\
&= \sum_{x_N^{(N-n)}, y_N^{(N)}} \rho(x_N, y_N) \prod_{k'=n+1}^{N-1} \rho_B(x_{k'}|x_{k'+1}, y_{k'-n}) \prod_{m'=N-n}^{N-1} \rho(y_{m'}|y_{m'+1}, x_N) \prod_{m=1}^{N-n-1} \rho(y_m|y_{m+1}, x_{m+n+1}) \\
&= \sum_{x_N^{(N-n-1)}, y_N^{(N-1)}} \rho(x_N, y_N) \prod_{k'=n+2}^{N-1} \rho_B(x_{k'}|x_{k'+1}, y_{k'-n}) \prod_{m'=N-n}^{N-1} \rho(y_{m'}|y_{m'+1}, x_N) \prod_{m=2}^{N-n-1} \rho(y_m|y_{m+1}, x_{m+n+1}) \\
&= \dots \\
&= \sum_{x_N^{(1)}, y_N^{(n+1)}} \rho(x_N, y_N) \prod_{m'=N-n}^{N-1} \rho(y_{m'}|y_{m'+1}, x_N) \\
&= \sum_{x_N^{(1)}, y_N^{(1)}} \rho(x_N, y_N) \\
&= 1,
\end{aligned} \tag{7}$$

with $n \geq 1$, and

$$\begin{aligned}
& \sum_{x_N^{(N)}, y_N^{(N)}} \tilde{\rho}(x_N^{(N)}, y_N^{(N)}) \\
&= \sum_{x_N^{(N)}, y_N^{(N)}} \rho(x_N, y_N) \prod_{k=1}^{N-1} \rho_B(x_k | x_{k+1}, y_k) \prod_{m=1}^{N-1} \rho(y_m | y_{m+1}, x_{m+1}) \\
&= \sum_{x_N^{(N-1)}, y_N^{(N-1)}} \rho(x_N, y_N) \prod_{k=2}^{N-1} \rho_B(x_k | x_{k+1}, y_k) \prod_{m=2}^{N-1} \rho(y_m | y_{m+1}, x_{m+1}) \\
&= \dots \\
&= \sum_{x_N^{(1)}, y_N^{(1)}} \rho(x_N, y_N) \\
&= 1,
\end{aligned} \tag{8}$$

with $n = 0$.

Thus Eqs. (3) and (5) are given by the Kullback-Libler divergence between $\rho(x_N^{(N)}, y_N^{(N)})$ and $\tilde{\rho}(x_N^{(N)}, y_N^{(N)})$. Because of the nonnegativity of the Kullback-Libler divergence [1], we have Eq. (12) in the main text

$$-\Delta S_{XB} \leq -\sum_{k=1}^n \left[T_{X_1^{(1)} \rightarrow Y_{k+1}^{(k+1)}} - T_{X_1^{(1)} \rightarrow Y_{k+1}^{(k+1)}} \right] - \sum_{k=n+1}^{N-1} \left[T_{X_{k-n}^{(1)} \rightarrow Y_{k+1}^{(k+1)}} - T_{X_{k-n}^{(1)} \rightarrow Y_{k+1}^{(k+1)}} \right] - I(X_N; Y_N) + I(X_1; Y_1), \tag{9}$$

for $n \geq 1$, and

$$-\Delta S_{XB} \leq -\sum_{k=1}^{N-1} \left[T_{X_k^{(1)} \rightarrow Y_{k+1}^{(k+1)}} - T_{X_k^{(1)} \rightarrow Y_{k+1}^{(k+1)}} \right] - I(X_N; Y_N) + I(X_1; Y_1), \tag{10}$$

for $n = 0$. The equality holds if and only if $\rho(x_N^{(N)}, y_N^{(N)}) = \tilde{\rho}(x_N^{(N)}, y_N^{(N)})$. In the case of $n = 0$, this condition is given by

$$\rho(x_1, y_1) \prod_{k=1}^{N-1} \rho(x_{k+1} | x_k, y_k) \rho(y_{k+1} | y_k, x_k) = \rho(x_N, y_N) \prod_{k=1}^{N-1} \rho_B(x_k | x_{k+1}, y_k) \prod_{m=1}^{N-1} \rho(y_m | y_{m+1}, x_{m+1}) \tag{11}$$

$$\rho(x_N, y_N) \prod_{k=1}^{N-1} \rho(x_k, y_k | y_{k+1}, x_{k+1}) = \rho(x_N, y_N) \prod_{k=1}^{N-1} \rho_B(x_k | x_{k+1}, y_k) \prod_{m=1}^{N-1} \rho(y_m | y_{m+1}, x_{m+1}) \tag{12}$$

$$\prod_{k=1}^{N-1} \rho(x_k | y_k, y_{k+1}, x_{k+1}) = \prod_{k=1}^{N-1} \rho_B(x_k | x_{k+1}, y_k), \tag{13}$$

which implies the backward probability $\rho_B(x_k | x_{k+1}, y_k)$ is equivalent to the original probability $\rho(x_k | y_k, y_{k+1}, x_{k+1})$. In a continuous limit, this fact implies the equality in the generalized second law (10) holds when the dynamics of \mathcal{X} has a local reversibility, i.e., $\rho = \rho_B$.

Supplementary note 2 | Detailed calculation of Eqs. (17) and (18) in the main text.

We consider the following Markovian interacting dynamics

$$\rho(x_N^{(N)}, y_N^{(N)}) = \rho(x_1, y_1) \prod_{k=1}^{N-1} \rho(x_{k+1} | x_k, y_k) \rho(y_{k+1} | x_k, y_k). \tag{14}$$

From Eq. (14), we have $\rho(y_k | y_N^{(N-k)}, x_{k+1}) = \rho(y_k | y_{k+1}, x_{k+1})$ and $\rho(y_{k+1} | y_k^{(k)}, x_k) = \rho(y_{k+1} | y_k, x_k)$. We also have an identity $\rho(y_k | y_{k+1}) \rho(y_{k+1}) = \rho(y_{k+1} | y_k) \rho(y_k)$. Thus we can calculate the additivity Eq. (17) in the main text as

follows;

$$\begin{aligned}
& I^0(X_N^{(N)} \rightarrow Y_N^{(N)}) - I^0(X_N^{\dagger(N)} \rightarrow Y_N^{\dagger(N)}) \\
&= \sum_{k=1}^{N-1} [T_{X_k^{(1)} \rightarrow Y_{k+1}^{(k+1)}} - T_{X_{k+1}^{(1)} \rightarrow Y_{k+1}^{\dagger(k+1)}}] + I(X_1; Y_1) - I(X_N; Y_N) \\
&= I(X_1; Y_1) + \sum_{k=1}^{N-1} I(X_k; Y_{k+1} | Y_k^{(k)}) - I(X_N; Y_N) - \sum_{k=1}^{N-1} I(X_{k+1}; Y_k | Y_N^{(N-k)}) \\
&= \left\langle \ln \left[\frac{\rho(y_N) \rho(y_1 | x_1)}{\rho(y_1) \rho(y_N | x_N)} \prod_{k=1}^{N-1} \frac{\rho(y_k | y_N^{(N-k)})}{p(y_k | y_N^{(N-k)}, x_{k+1})} \frac{p(y_{k+1} | y_k^{(k)}, x_k)}{p(y_{k+1} | y_k^{(k)})} \right] \right\rangle \\
&= \left\langle \ln \left[\frac{\rho(y_1 | x_1)}{\rho(y_N | x_N)} \prod_{k=1}^{N-1} \frac{\rho(y_k | y_{k+1}) \rho(y_{k+1})}{p(y_k | y_{k+1}, x_{k+1})} \frac{\rho(y_{k+1} | y_k, x_k)}{\rho(y_{k+1} | y_k) \rho(y_k)} \right] \right\rangle \\
&= I(X_1; Y_1) + \sum_{k=1}^{N-1} I(X_k; Y_{k+1} | Y_k) - I(X_N; Y_N) - \sum_{k=1}^{N-1} I(X_{k+1}; Y_k | Y_{k+1}) \\
&= \sum_{k=1}^{N-1} [I(X_k; Y_{k+1} | Y_k) + I(X_k; Y_k) - I(X_{k+1}; Y_k | Y_{k+1}) - I(X_{k+1}; Y_{k+1})] \\
&= \sum_{k=1}^{N-1} \left[I^0(X_{k+1}^{(2)} \rightarrow Y_{k+1}^{(2)}) - I^0(X_{N-k+1}^{\dagger(2)} \rightarrow Y_{N-k+1}^{\dagger(2)}) \right]. \tag{15}
\end{aligned}$$

The difference between a tighter bound and DIF is calculated as follows;

$$\begin{aligned}
& I^0(X_{k+1}^{(2)} \rightarrow Y_{k+1}^{(2)}) - I^0(X_{N-k+1}^{\dagger(2)} \rightarrow Y_{N-k+1}^{\dagger(2)}) + I_{\text{flow}}^k \\
&= I(X_k; \{Y_k, Y_{k+1}\}) - I(X_{k+1}; \{Y_k, Y_{k+1}\}) - I(X_k; Y_k) + I(X_{k+1}; Y_k) \\
&= I(X_k; Y_{k+1} | Y_k) - I(X_{k+1}; Y_{k+1} | Y_k) \\
&= \left\langle \ln \left[\frac{\rho(y_{k+1} | y_k, x_k)}{\rho(y_{k+1} | y_k, x_{k+1})} \right] \right\rangle \tag{16}
\end{aligned}$$

For the bipartite Markov jump process [2] or two dimensional Langevin dynamics without any correlation between thermal noises in \mathcal{X} and \mathcal{Y} [3], the ratio between two transition rates in \mathcal{Y} , i.e., $\langle \ln[\rho(y_{k+1} | y_k, x_k) / \rho(y_{k+1} | y_k, x_{k+1})] \rangle$ is up to order $O(\Delta t^2)$.

Supplementary note 3 | Comparison between a tighter bound in Eq. (16) and the result in [Ito, S., & Sagawa, T., Phys. Rev. Lett. 111, 180603 (2013)].

We compare a tighter bound in Eqs. (18) with our previous result in Ref. [3]. For the non-Markovian interacting dynamics

$$\rho(x_N^{(N)}, y_N^{(N)}) := \rho(x_1, y_1) \prod_{k'=1}^n \rho(x_{k'+1} | x_{k'}, y_1) \rho(y_{k'+1} | y_{k'}, x_1) \prod_{k=n+1}^{N-1} \rho(x_{k+1} | x_k, y_{k-n}) \rho(y_{k+1} | y_k, x_{k-n}), \tag{17}$$

with $n \geq 1$, the previous result in Ref. [3] gives the following bound of the entropy change in \mathcal{X} and bath,

$$\begin{aligned}
-\Delta S_{\mathcal{X}B} &\leq -\langle \Theta \rangle \\
&:= I(X_1; Y_1) + \sum_{k=1}^n T_{X_1^{(1)} \rightarrow Y_{k+1}^{(k+1)}} + \sum_{k=n+1}^{N-1} T_{X_{k-n}^{(1)} \rightarrow y_{k+1}^{(k+1)}} - I(X_N; Y_N^{(N)}) \\
&:= I^n(X_N^{(N)} \rightarrow Y_N^{(N)}) - I(X_N; Y_N) - \sum_{k=1}^{N-1} T_{X_{k+1}^{(1)} \rightarrow Y_{k+1}^{\dagger(k+1)}} \tag{18}
\end{aligned}$$

where we used the identity $I(X_N; Y_N^{(N)}) = I(X_N; Y_N) + \sum_{k=1}^{N-1} T_{X_{k+1}^{(1)} \rightarrow Y_{k+1}^{\dagger(k+1)}}$. Here, $I(X_1; Y_1)$ corresponds to the initial correlation term I_{ini} , $\sum_{k=1}^n T_{X_1^{(1)} \rightarrow Y_{k+1}^{(k+1)}} + \sum_{k=n+1}^{N-1} T_{X_{k-n}^{(1)} \rightarrow y_{k+1}^{(k+1)}}$ corresponds the transfer entropy term $\sum_l I_{\text{tr}}^l$,

and $I(X_N; Y_N^{(N)})$ corresponds to the final correlation term I_{fin} in Ref. [3]. The difference between $-\langle \Theta \rangle$ and $I^n(X_N^{(N)} \rightarrow Y_N^{(N)}) - I^n(X_N^{\dagger(N)} \rightarrow Y_N^{\dagger(N)})$ can be calculated as the difference of BTE,

$$-\langle \Theta \rangle - [I^n(X_N^{(N)} \rightarrow Y_N^{(N)}) - I^n(X_N^{\dagger(N)} \rightarrow Y_N^{\dagger(N)})] = - \sum_{k=n+1}^{N-1} [T_{X_N^{\dagger(1)} \rightarrow Y_N^{\dagger(k+1)}} - T_{X_N^{\dagger(k-n)} \rightarrow Y_N^{\dagger(k+1)}}]. \quad (19)$$

Due to the conditional Markov chain

$$\rho(x_N, x_{N-k+n+1}, y_{N-k}|y_N^{(k)}) = \rho(x_N|x_{N-k+n+1}, y_N^{(k)})\rho(x_{N-k+n+1}|y_{N-k}, y_N^{(k)})\rho(y_{N-k}|y_N^{(k)}), \quad (20)$$

we have the data processing inequality[1]

$$T_{X_N^{\dagger(1)} \rightarrow Y_N^{\dagger(k+1)}} = I(X_N; Y_{N-k}|Y_N^{(k)}) \leq I(X_{N-k+n+1}; Y_{N-k}|Y_N^{(k)}) = T_{X_N^{\dagger(k-n)} \rightarrow Y_N^{\dagger(k+1)}}. \quad (21)$$

Therefore, a tighter bound in inequality Eq. (16) is tighter than a bound in the previous result [3],

$$-\Delta S_{XB} \leq I^n(X_N^{(N)} \rightarrow Y_N^{(N)}) - I^n(X_N^{\dagger(N)} \rightarrow Y_N^{\dagger(N)}) \leq -\langle \Theta \rangle. \quad (22)$$

Supplementary note 4 | Detailed derivation of the inequality (20) in the main text.

The set of side information x_k satisfies $x_{k-1} = \{s_1, \dots, s_k\} \subset x_k$. Thus we have $\rho(y_{k+1}|y_k^{(k)}, x_k^{(k)}) = \rho(y_{k+1}|y_k^{(k)}, x_k)$ and $\rho(x_{k+1}|y_k^{(k)}, x_k^{(k)}) = \rho(x_{k+1}|y_k^{(k)}, x_k)$. The joint probability is given by

$$\rho(x_N^{(N)}, y_N^{(N)}) = \rho(x_1, y_1) \prod_{k=1}^{N-1} \rho(x_{k+1}|y_k^{(k)}, x_k)\rho(y_{k+1}|y_k^{(k)}, x_k). \quad (23)$$

Thus, we can calculate as follows;

$$\begin{aligned} & -G + \sum_{k=1}^N \langle \ln o_k \rangle - S(Y_N^{(N)}) + I^0(X_N^{(N)} \rightarrow Y_N^{(N)}) \\ &= -\langle \ln f_1(y_1|x_1) \rangle - \sum_{k=1}^{N-1} \langle \ln f_{k+1}(y_{k+1}|y_k^{(k)}, x_k) \rangle + \langle \ln \rho(y_N^{(N)}) \rangle + \left\langle \ln \left[\frac{\rho(x_1, y_1)}{\rho(x_1)\rho(y_1)} \right] \right\rangle + \left\langle \ln \left[\prod_{k=1}^{N-1} \frac{\rho(y_{k+1}|y_k^{(k)}, x_k)}{\rho(y_{k+1}|y_k^{(k)})} \right] \right\rangle \\ &= \left\langle \ln \left[\frac{\rho(x_1, y_1)}{f_1(y_1|x_1)\rho(x_1)} \prod_{k=1}^{N-1} \frac{\rho(y_{k+1}|y_k^{(k)}, x_k)}{f_{k+1}(y_{k+1}|y_k^{(k)}, x_k)} \right] + \ln \frac{\rho(y_N^{(N)})}{\pi(x_N^{(N)}, y_N^{(N)})} \right\rangle \\ &= \left\langle \ln \left[\frac{\rho(x_1, y_1)}{f_1(y_1|x_1)\rho(x_1)} \prod_{k=1}^{N-1} \frac{\rho(x_{k+1}|y_k^{(k)}, x_k)\rho(y_{k+1}|y_k^{(k)}, x_k)}{\rho(x_{k+1}|y_k^{(k)}, x_k)f_{k+1}(y_{k+1}|y_k^{(k)}, x_k)} \right] \right\rangle \\ &= \sum_{x_N^{(N)}, y_N^{(N)}} \rho(x_N^{(N)}, y_N^{(N)}) \ln \frac{\rho(x_N^{(N)}, y_N^{(N)})}{\pi(x_N^{(N)}, y_N^{(N)})}, \end{aligned} \quad (24)$$

where $\pi(x_N^{(N)}, y_N^{(N)})$ is defined as

$$\pi(x_N^{(N)}, y_N^{(N)}) := f_1(y_1|x_1)\rho(x_1) \prod_{k=1}^{N-1} \rho(x_{k+1}|y_k^{(k)}, x_k)f_{k+1}(y_{k+1}|y_k^{(k)}, x_k). \quad (25)$$

The function $\pi(x_N^{(N)}, y_N^{(N)})$ satisfies the normalization of the probability,

$$\begin{aligned}
\sum_{x_N^{(N)}, y_N^{(N)}} \pi(x_N^{(N)}, y_N^{(N)}) &= \sum_{x_N^{(N)}, y_N^{(N)}} f_1(y_1|x_1) \rho(x_1) \prod_{k=1}^{N-1} f_{k+1}(y_{k+1}|y_k^{(k)}, x_k) \rho(x_{k+1}|y_k^{(k)}, x_k) \\
&= \sum_{x_{N-1}^{(N-1)}, y_{N-1}^{(N-1)}} f_1(y_1|x_1) \rho(x_1) \prod_{k=1}^{N-2} f_{k+1}(y_{k+1}|y_k^{(k)}, x_k) \rho(x_{k+1}|y_k^{(k)}, x_k) \\
&= \dots \\
&= \sum_{x_1, y_1} f_1(y_1|x_1) \rho(x_1) \\
&= \sum_{x_1} \rho(x_1) \\
&= 1,
\end{aligned} \tag{26}$$

where we used $\sum_{y_1} f_1(y_1|x_1) = 1$ and $\sum_{y_{k+1}} f_{k+1}(y_{k+1}|y_k^{(k)}, x_k) = 1$.

Thus Eq. (24) is the Kullback-Libler divergence between $p(x_N^{(N)}, y_N^{(N)})$ and $\pi(x_N^{(N)}, y_N^{(N)})$. Because of the nonnegativity of the Kullback-Libler divergence [1], we have Eq. (20) in the main text

$$-G + \sum_{k=1}^N \langle \ln o_k \rangle - S(Y_N^{(N)}) + I^0(X_N^{(N)} \rightarrow Y_N^{(N)}) \geq 0. \tag{27}$$

The equality holds if and only if $p(x_N^{(N)}, y_N^{(N)}) = \pi(x_N^{(N)}, y_N^{(N)})$. This condition is given by

$$\begin{aligned}
\rho(x_1, y_1) \prod_{k=1}^{N-1} \rho(x_{k+1}|y_k^{(k)}, x_k) \rho(y_{k+1}|y_k^{(k)}, x_k) &= f_1(y_1|x_1) \rho(x_1) \prod_{k=1}^{N-1} \rho(x_{k+1}|y_k^{(k)}, x_k) f_{k+1}(y_{k+1}|y_k^{(k)}, x_k) \\
\rho(y_1|x_1) \prod_{k=1}^{N-1} \rho(y_{k+1}|y_k^{(k)}, x_k) &= f_1(y_1|x_1) \prod_{k=1}^{N-1} f_{k+1}(y_{k+1}|y_k^{(k)}, x_k),
\end{aligned} \tag{28}$$

which implies the bet fraction f_k is equivalent to the original probability ρ , i.e., the proportional betting is optimal.

- [1] Cover, T. M., & Thomas, J. A., “Elements of Information Theory” (John Wiley and Sons, New York, 1991).
- [2] Hartich, D., Barato, A. C., & Seifert, U., Stochastic thermodynamics of bipartite systems: transfer entropy inequalities and a Maxwell’s demon interpretation. *J. Stat. Mech.* (2014) P02016.; In Appendix C, authors have shown that the ratio $\langle \ln[\rho(y_{k+1}|y_k, x_k)/\rho(y_{k+1}|y_k, x_{k+1})] \rangle$ is up to $O(\Delta t^2)$ for the bipartite Markov jump system [Eq. (C.11)].
- [3] Ito, S., & Sagawa, T., Information thermodynamics on causal networks. *Phys. Rev. Lett.* **111**, 180603 (2013); In supplementary information C, Eqs. (15) and (16) can be interpreted as the fact that the ratio $\langle \ln[\rho(y_{k+1}|y_k, x_k)/\rho(y_{k+1}|y_k, x_{k+1})] \rangle$ is up to $O(\Delta t^2)$ for two dimensional Langevin dynamics without any correlation between thermal noises in \mathcal{X} and \mathcal{Y} .