

Dynamic modeling of personal protection control strategies
for vector-borne disease limits the role of diversity
amplification: Supplementary material

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S1 Effects of varied human recovery time

The following plots are the equivalent of Figs. 1 - 4 in the main text for a human recovery times $1/r = 1$ week and $1/r = 6$ months. The dynamic two-class model behaves more similarly to the static two-class model for shorter recovery times, and more similarly the one-class model for longer recovery times.

S1.1 One week recovery time

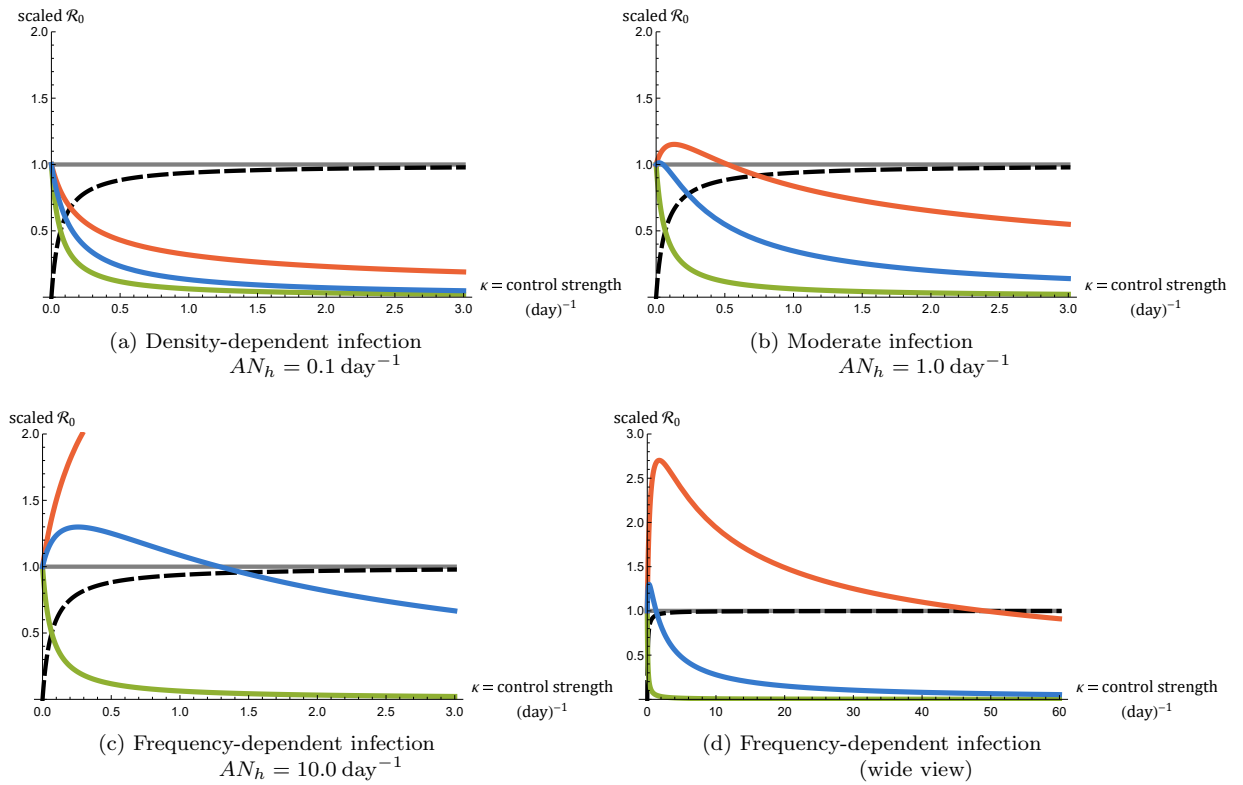


Figure S1: Dependencies of \mathcal{R}_0 on DEET ($1/\gamma = 15$ days) control strength for the dynamic two-class model (blue), static two-class model (red), and one-class model (green), where the human recovery time $1/r = 1$ week. Corresponding equilibrium proportions of protected hosts are given by the dashed black curve. Two-host models display diversity amplification at control strengths where respective scaled \mathcal{R}_0 curves rise above the gray $\mathcal{R}_0 = 1$ line.

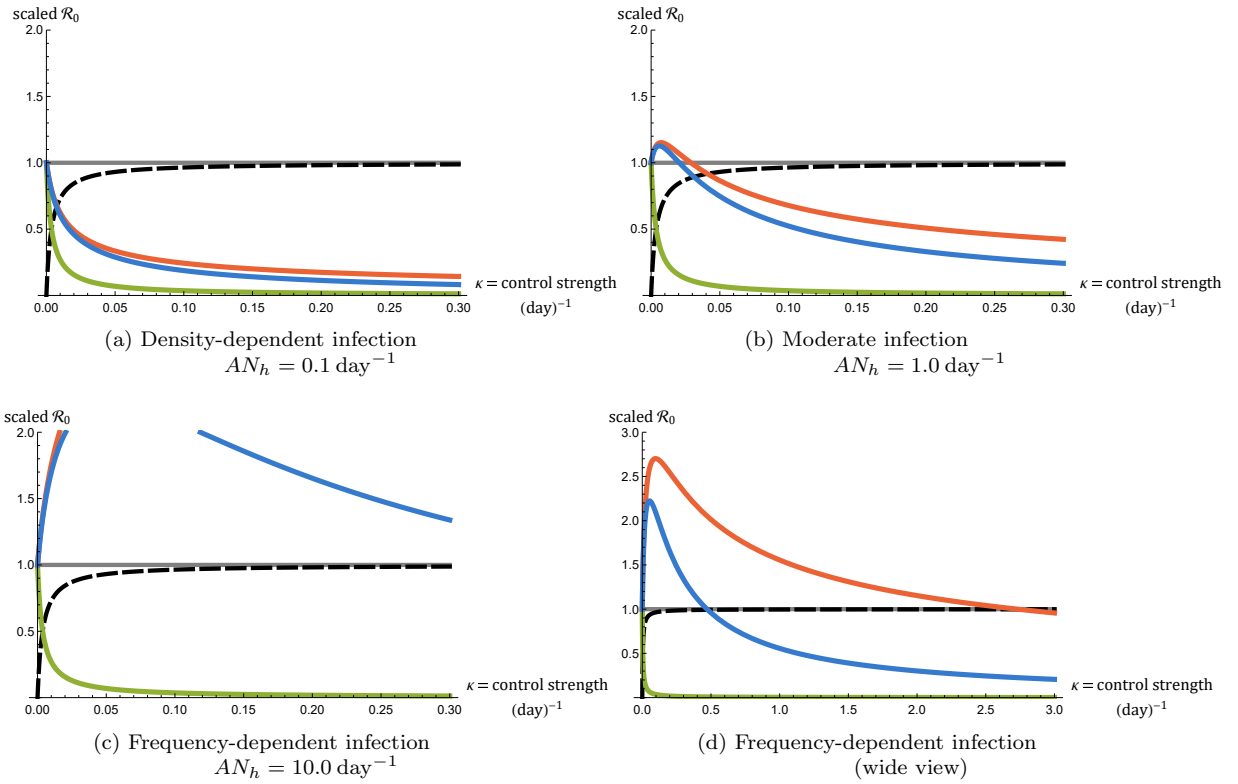


Figure S2: Dependencies of \mathcal{R}_0 on intermediate protection ($1/\gamma = 9$ months) control strength, where the human recovery time $1/r = 1$ week. Curve colors and styles are defined as in Fig. S1.

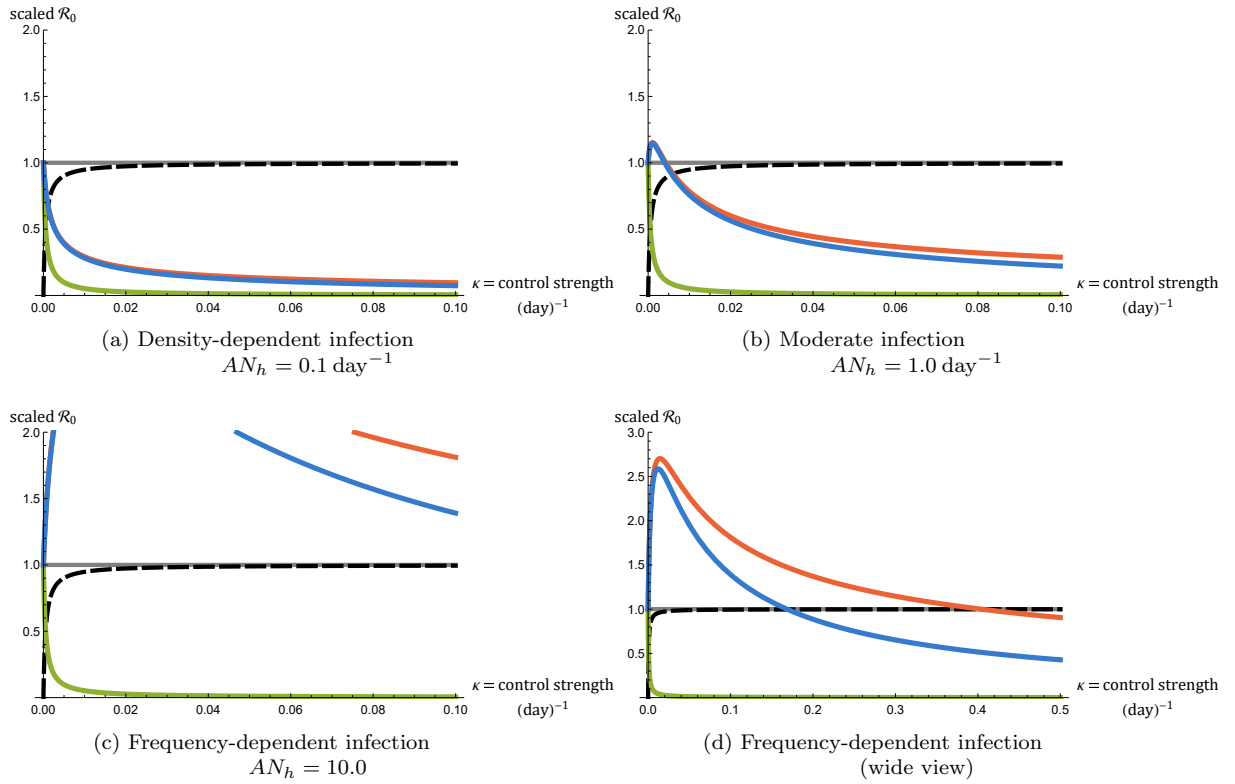


Figure S3: Dependencies of \mathcal{R}_0 on bed net ($1/\gamma = 5$ years) control strength, where the human recovery time $1/r = 1$ week. Curve colors and styles are interpreted as in Fig. S1.

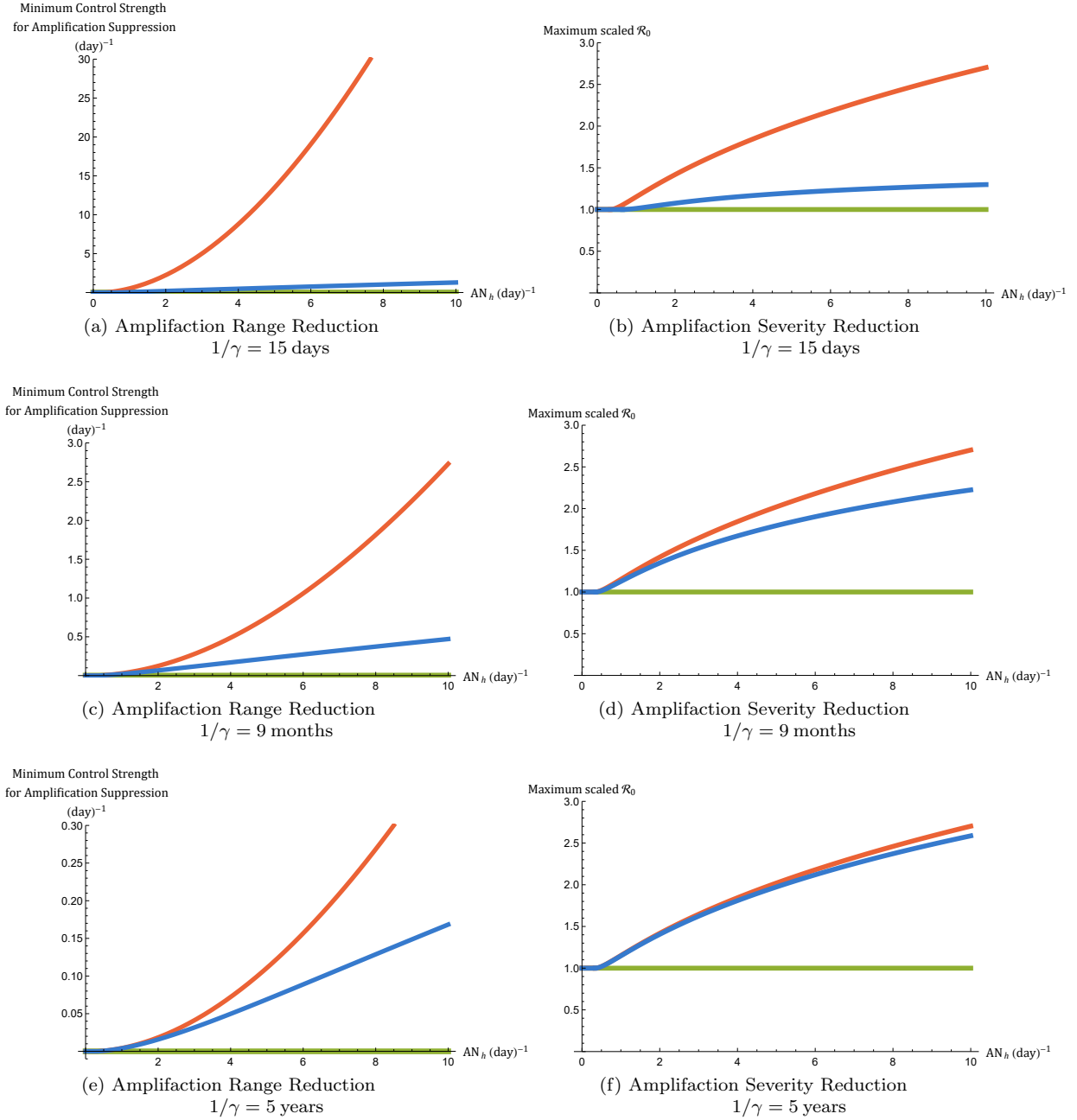


Figure S4: Illustrations of amplification range and strength reduction as functions of AN_h using the dynamic two-class model (blue), static two-class model (red), and one-class model (green), where the human recovery time $1/r = 1$ week. The minimum control strength for amplification suppression is the value of control strength κ^* such that scaled \mathcal{R}_0 exceeds unity for all control strengths $\kappa \in [0, \kappa^*]$. The maximum scaled \mathcal{R}_0 is the value of scaled \mathcal{R}_0 at the peak of a model's \mathcal{R}_0 vs κ curve for a given value of AN_h .

S1.2 Six month recovery time

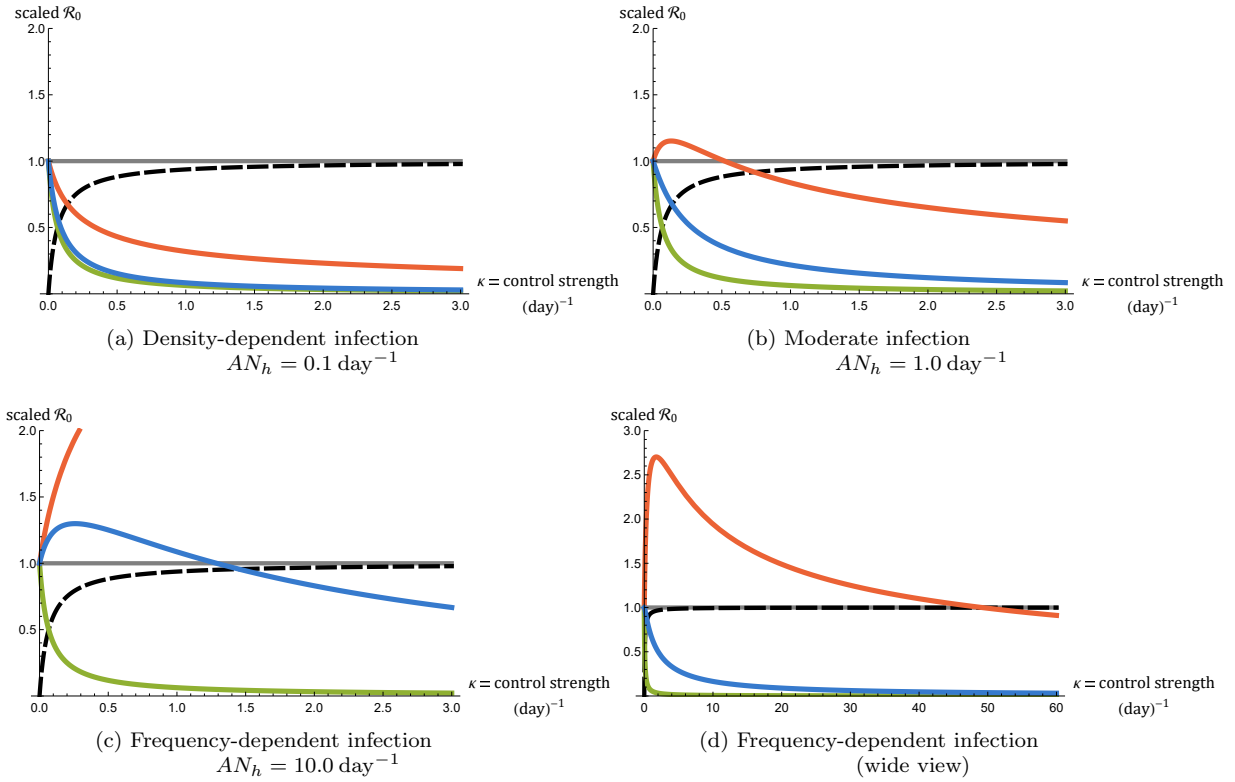


Figure S5: Dependencies of \mathcal{R}_0 on DEET ($1/\gamma = 15$ days) control strength for the dynamic two-class model (blue), static two-class model (red), and one-class model (green), where the human recovery time $1/r = 6$ months. Corresponding equilibrium proportions of protected hosts are given by the dashed black curve. Two-host models display diversity amplification at control strengths where respective scaled \mathcal{R}_0 curves rise above the gray $\mathcal{R}_0 = 1$ line.

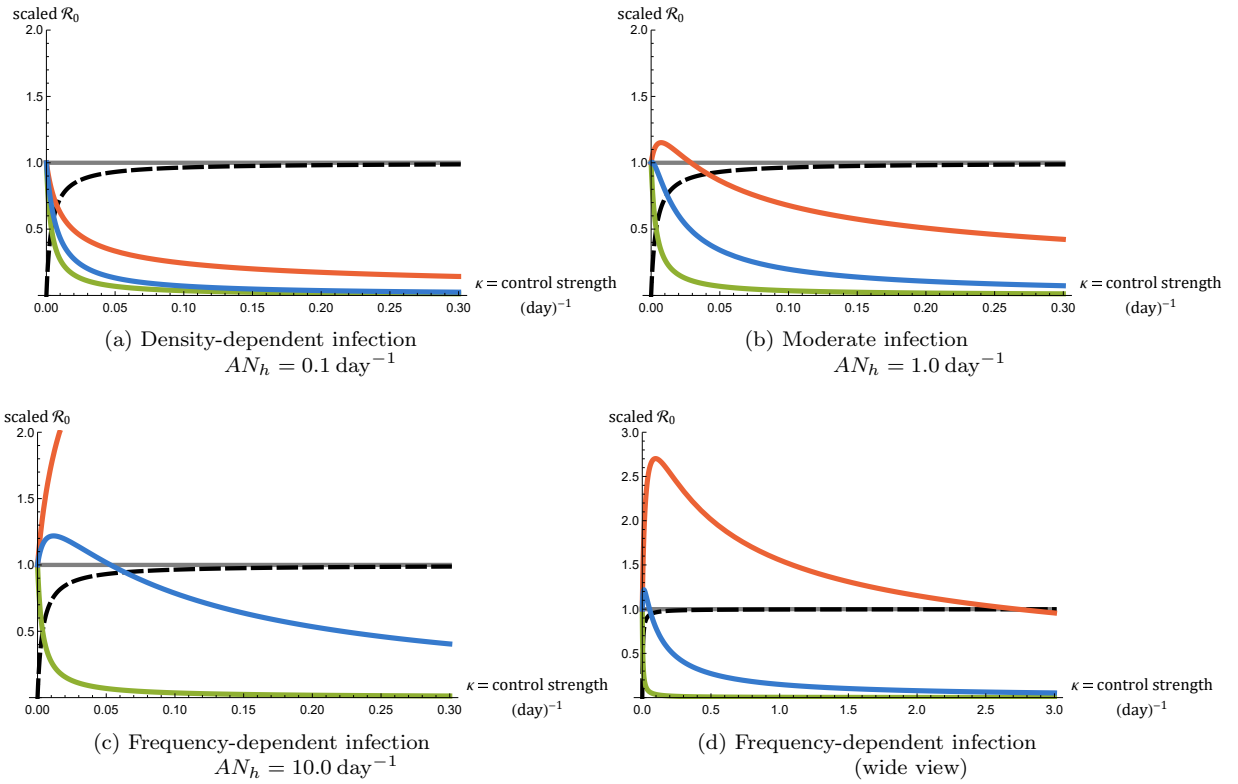


Figure S6: Dependencies of \mathcal{R}_0 on intermediate protection ($1/\gamma = 9$ months) control strength, where the human recovery time $1/r = 6$ months. Curve colors and styles are defined as in Fig. S1.

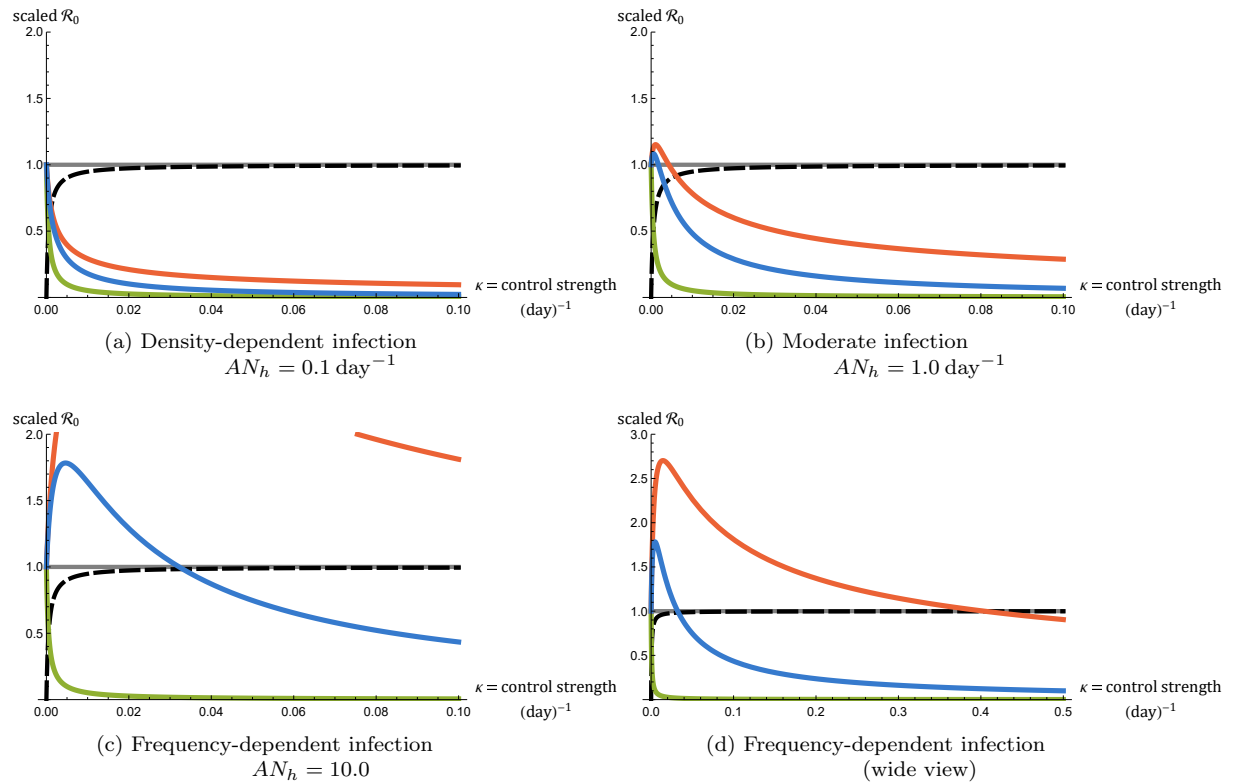


Figure S7: Dependencies of \mathcal{R}_0 on bed net ($1/\gamma = 5$ years) control strength, where the human recovery time $1/r = 6$ months. Curve colors and styles are interpreted as in Fig. S1.

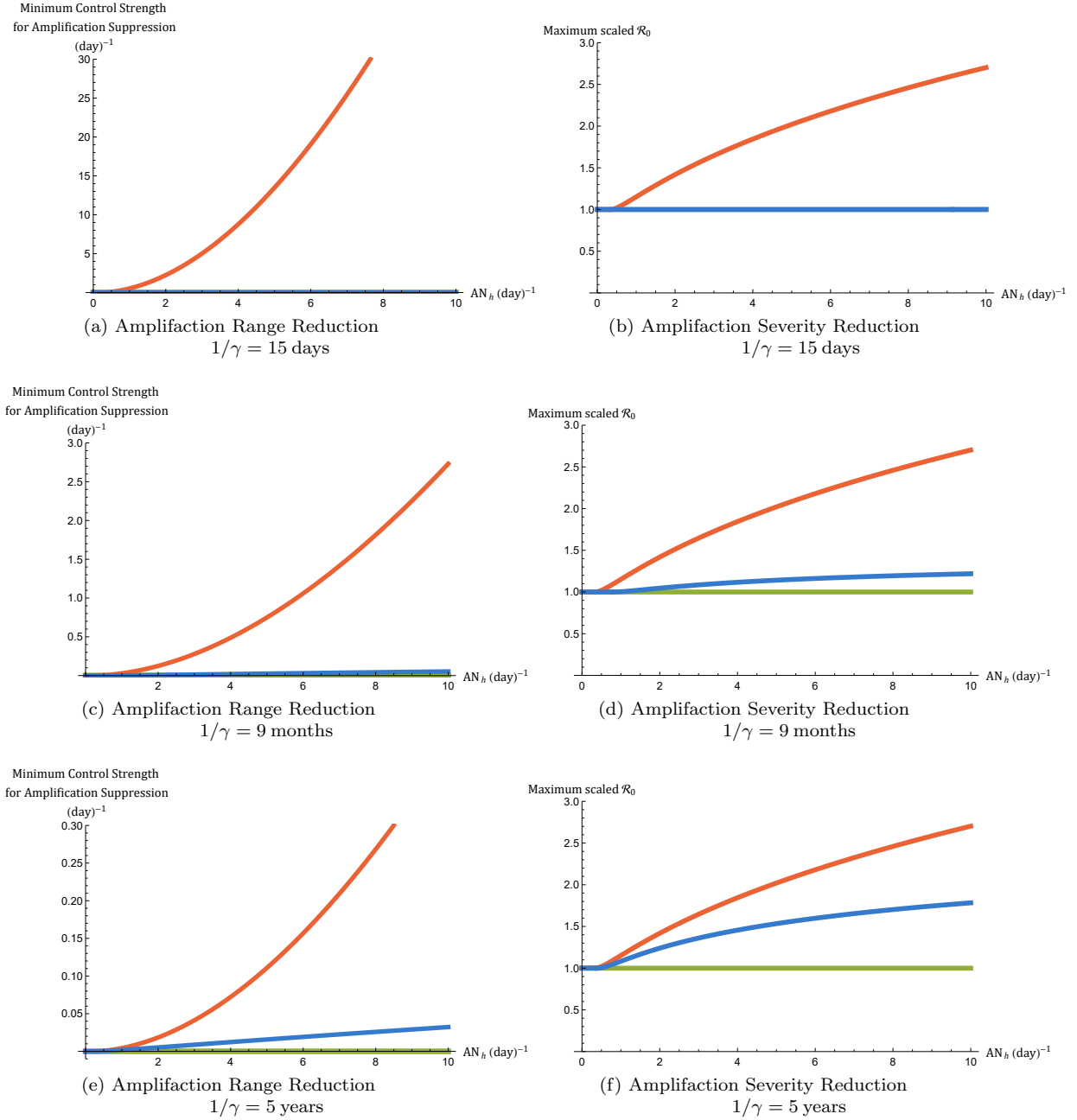


Figure S8: Illustrations of amplification range and strength reduction as functions of AN_h using the dynamic two-class model (blue), static two-class model (red), and one-class model (green), where the human recovery time $1/r = 6$ months. The minimum control strength for amplification suppression is the value of control strength κ^* such that scaled \mathcal{R}_0 exceeds unity for all control strengths $\kappa \in [0, \kappa^*]$. The maximum scaled \mathcal{R}_0 is the value of scaled \mathcal{R}_0 at the peak of a model's \mathcal{R}_0 vs κ curve for a given value of AN_h .