



**Figure S5:** Determining the safe level of resection based on cell death sensitivity ( $\beta_{ap}$ ), an intrinsic perioperative factor. (A-C) Phase portrait of quiescent and replicating cell fractions for varying levels of cell death sensitivity parameter ( $\beta_{ap}$ ). All other parameters were set to the optimal levels given in Table 1 of the manuscript. The filled circle markers in A-C represent different levels of resection. The red dashed curves represent trajectories for the critical level of resection at and above which failure occurs. (A)  $\beta_{ap} = 0.01$ , yields a threshold of liver failure at 77% resection. (B)  $\beta_{ap} = 0.03$ , yields a threshold of liver failure at 62% resection. (C)  $\beta_{ap} = 0.06$ , for which all levels of resection lead to failure. Therefore, if cell death sensitivity of a virtual patient is high, the attractor of liver recovery vanishes leading to only one attractor of liver failure. As a consequence, even the smallest level of resection in such patients is likely to result in liver failure, suggesting that surgical resection may not be a viable option. (D) Influence of cell death sensitivity parameter  $\beta_{ap}$  on the threshold of liver failure, which monotonically decreased with increasing cell death sensitivity. Red cross markers in panel D represent the threshold of failure for the corresponding phase planes A-C. Our results suggest that increasing  $\beta_{ap}$  results in the shrinkage of the attractor for liver recovery with a simultaneous increase in the attractor region for liver failure.