Supporting information

S2 Table. Results of the mixed ANOVA, coded according to the pathological side of patients' body (i.e. ipsilateral vs. contralateral to the affected/static hand), with *workspace* (ipsilateral vs. contralateral), *vision of the hands* (visible vs. invisible), *position of the static hand* (inside vs. outside the workspace) and *distance of the line from the starting position* (short vs. intermediate vs. long) as within-participant factors, and *which hand is used* (left vs. right) and *group* (CRPS vs. control) as between-participant factors.

Factors	F	р	η^2_{p}
Group	2.559	.122	.090
Which hand is used	6.063	.021	.189
Group imes Which hand is used	5.483	.027	.174
Workspace	0.035	.853	.001
Workspace imes Group	4.320	.048	.142
Workspace \times Which hand is used	0.479	.495	.018
Workspace \times Group \times Which hand is used	1.110	.302	.041
Vision of the hands	3.632	.068	.123

Vision of the hands \times Group	8.606	.007	.249
Vision of the hands \times Which hand is used	0.041	.841	.002
Vision of the hands \times Group \times Which hand is used	0.000	.989	.000
Position of the static hand	0.437	.515	.017
Position of the static hand \times Group	0.840	.368	.031
Position of the static hand \times Which hand is used	3.773	.063	.127
Position of the static hand \times Group \times Which hand is used	2.826	.105	.098
Line distance	2.298	.111	.081
<i>Line distance</i> \times <i>Group</i>	1.948	.153	.070
<i>Line distance</i> \times <i>Which hand is used</i>	2.905	.064	.100
<i>Line distance</i> \times <i>Group</i> \times <i>Which hand is used</i>	3.680	.032	.124
Workspace \times Vision of the hands	0.008	.931	.000
Workspace \times Vision of the hands \times Group	0.013	.908	.001
Workspace \times Vision of the hands \times Which hand is used	0.046	.832	.002
<i>Workspace</i> \times <i>Vision of the hands</i> \times <i>Group</i> \times <i>Which hand is used</i>	0.103	.749	.004

Workspace \times Position of the static hand	0.309	.583	.012
Workspace \times Position of the static hand \times Group	0.996	.327	.037
Workspace \times Position of the static hand \times Which hand is used	0.069	.795	.003
Workspace \times Position of the static hand \times Group \times Which hand is used	0.438	.514	.017
<i>Vision of the hands</i> × <i>Position of the static hand</i>	1.712	.202	.062
<i>Vision of the hands</i> \times <i>Position of the static hand</i> \times <i>Group</i>	2.225	.148	.079
Vision of the hands \times Position of the static hand \times Which hand is used	0.082	.777	.003
Vision of the hands \times Position of the static hand \times Group \times Which hand is used	2.736	.110	.095
Workspace \times Vision of the hands \times Position of the static hand	3.625	.068	.122
Workspace \times Vision of the hands \times Position of the static hand \times Group	0.027	.871	.001
Workspace \times Vision of the hands \times Position of the static hand \times Which hand is used	0.377	.544	.014
Workspace \times Vision of the hands \times Position of the static hand \times Group \times Which hand is used	0.007	.935	.000
Workspace \times Line distance	3.318	.044	.113
Workspace \times Line distance \times Group	1.398	.256	.051
Workspace \times Line distance \times Which hand is used	5.621	.006	.178

Workspace \times Line distance \times Group \times Which hand is used	6.150	.004	.191
<i>Vision of the hands</i> \times <i>Line distance</i>	0.920	.405	.034
Vision of the hands \times Line distance \times Group	0.032	.968	.001
Vision of the hands \times Line distance \times Which hand is used	0.085	.918	.003
Vision of the hands \times Line distance \times Group \times Which hand is used	0.022	.978	.001
<i>Workspace</i> \times <i>Vision of the hands</i> \times <i>Line distance</i>	4.250	.036	.140
Workspace \times Vision of the hands \times Line distance \times Group	2.394	.101	.084
Workspace \times Vision of the hands \times Line distance \times Which hand is used	5.188	.020	.166
Workspace \times Vision of the hands \times Line distance \times Group \times Which hand is used	0.474	.625	.018
Position of the static hand \times Line distance	6.787	.002	.207
Position of the static hand \times Line distance \times Group	1.800	.175	.065
Position of the static hand \times Line distance \times Which hand is used	1.740	.186	.063
Position of the static hand \times Line distance \times Group \times Which hand is used	0.887	.418	.033
<i>Workspace</i> × <i>Position of the static hand</i> × <i>Line distance</i>	2.319	.108	.082
Workspace \times Position of the static hand \times Line distance \times Group	1.426	.249	.052

Workspace \times Position of the static hand \times Line distance \times Which hand is used	2.788	.071	.097
Workspace \times Position of the static hand \times Line distance \times Group \times Which hand is used	1.966	.150	.070
<i>Vision of the hands</i> \times <i>Position of the static hand</i> \times <i>Line distance</i>	0.711	.496	.027
<i>Vision of the hands</i> \times <i>Position of the static hand</i> \times <i>Line distance</i> \times <i>Group</i>	0.671	.515	.025
<i>Vision of the hands</i> \times <i>Position of the static hand</i> \times <i>Line distance</i> \times <i>Which hand is used</i>	0.068	.934	.003
<i>Vision of the hands</i> \times <i>Position of the static hand</i> \times <i>Line distance</i> \times <i>Group</i> \times <i>Which hand is used</i>	1.101	.340	.041
Workspace \times Vision of the hands \times Position of the static hand \times Line distance	0.710	.497	.027
Workspace \times Vision of the hands \times Position of the static hand \times Line distance \times Group	0.512	.602	.019
Workspace \times Vision of the hands \times Position of the static hand \times Line distance \times Which hand is used	0.001	.999	.000
Workspace \times Vision of the hands \times Position of the static hand \times Line distance \times Group \times Which hand is used	1.951	.152	.070