Supplementary Source Codes

For the manuscript "A Bayesian psychophysics model of sense of agency" by Roberto Legaspi & Taro Toyoizumi Emails: {roberto.legaspi, taro.toyoizumi}@riken.jp

This supplementary information contains the MATLAB source codes that were used to generate the simulation data and plot the computation results for analyses.

Following is the order in which the main codes should be compiled and executed:

- 1. create SimulationData.m.
- 2. find muAO.m
- 3. compute PXisPrcShfts.m. The plots that were generated here were shown in Figs. 2 and 5b.
- 4. compute_PerTrialPrcShfts.m. The plots were shown in Figs. 3b, 3c, 3d and 3e, as well as 4c and 4d.
- 5. compute CCEPXi1.m. The plots that were generated from this were shown in Figs. 4a and 6a.
- 6. compute PerTrialCCE.m. The plots were shown in Figs. 4b and 6b.

The descriptions and objectives of each of the above are written in their codes. Note that to generate the results that correspond to the two intentional binding experiments that were studied, the variable *Expr* should be assigned the value 1 and 2 for Haggard et al.'s (Ref [3]) and Wolpe et al.'s (Ref [22]) studies, respectively.

Lastly, the following auxiliary source codes are called by the main codes described above:

- 1. soa IBexperiment.m
- 2. soa_IBTargets.m
- 3. soa InitMatrix.m
- 4. soa sortMatrices.m
- 5. soa plotPrcShfts.m
- 6. soa plotErrorBars.m
- 7. soa plotBehaviors.m

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\$ Objective: Create the noisy sensory input signals arriving at various times taoA and taoO
end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 Only if random generation should be repeatable rng(1,'twister');
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        % Cleaners
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     ExpR = 1; numCond = 3;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     close all
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    tAp=0; dist_tAt0=250; t0p=tAp+dist_tAt0;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      taoInstances = 35000;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     for CondB0 = 1:numCond
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    Simulation conditions
                        fnametaoA = sprintf('Exp%dCond%d_Vec_taoA.csv',ExpR,CondBO);
fnametaoO = sprintf('Exp%dCond%d_Vec_taoO.csv',ExpR,CondBO);
dlmwrite(fnametaoA, Vec_taoA,'delimiter',',');
dlmwrite(fnametaoO, Vec_taoO,'delimiter',',');
                                                                                                                                                                                                                                                                                                                                                                                       sizeVec_taoA = numel(Vec_taoA);
sizeVec_taoO = numel(Vec_taoO);
taoA_min = min(Vec_taoA); taoA_max = max(Vec_taoA);
taoO_min = min(Vec_taoO); taoO_max = max(Vec_taoO);
uVectaoA = mean(Vec_taoA); stdVectaoA = std(Vec_taoA);
uVectaoO = mean(Vec_taoO); stdVectaoO = std(Vec_taoO);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                figure; histfit(Vec_taoA);
figure; histfit(Vec_taoO);
%}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               Vec_taoA = normrnd(tAp + muA, sigmaA, [1 taoInstances]);
Vec_taoO = normrnd(tOp + muO, sigmaO, [1 taoInstances]);
                                                                                                                                                                                       % Store generated simulation data
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      % Generate statistics
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                figure; normplot(Vec_tao0);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 figure; normplot(Vec_taoA);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  % Check the generated data
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    % Generate from Gaussian distributions
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                [muA, sigmaA, mu0, sigma0] = soa_IBexperiment(ExpR, CondB0);
                                                                                                                                                         tprintf('==
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 Initialize baseline parameters with reported empirical data
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              % Number of taoA and taoO instances to be generated
% Experimental set-up
% Experimental set-up
% Haggard et al. (2002): ExpR = 1; NumCond = 3; (Voluntary, Involuntary, Sham)
% Wolpe et al. (2013) : ExpR = 2; NumCond = 3; (Low, Intermediate, High)
% Actual physical stimulus timings
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               % clears all variables from the workspace
% clears the command window
% closes all figures (such as plots)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        % %
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               Alterntaive: sigmaA .* randn(1,numInstances) + (tAp + muA); sigmaO .* randn(1,numInstances) + (tOp + muO);
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taoInstances = 35000;
ExpR = 1; numCond = 3;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   % Objective: Find the optimal value for the free parameter muAO using Haggard et al.'s data,
% with sigmaAO equal to 10ms.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       % Cleaners
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              sigmaA0 = 10;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       % Simulation Conditions
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       close all
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           clear
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          for muAO = [190 200 210 220 230 240 250]
                                                                                                                                                                                end
    fprintf('model
if muA0==190 |
                                                                                        modelEE = sumError/numCond;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              sumError = 0;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  for CondB0 = 1:numCond
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  \mathsf{fprintf}(\mathsf{'Action} and outcome perceptual shifts per condition given \mathsf{muA0}=\mathsf{%d}\setminus\mathsf{n}' \mathsf{muA0});
muAO==190 || (muAO~=190 && modelEE < min_modelEE)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    % Compute for model estimation errors given the reported empirical results [targPrcShftA, targPrcShft0] = soa_IBTargets(ExpR,CondBO); errPrcShft = abs(ruVec_PrcShftA - targPrcShftA);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             Vec_PrcShftA = (sigmaA^2 / sigmaTot2) * (Vec_tao0 - Vec_taoA - muA0);
Vec_PrcShft0 = -(sigma0^2 / sigmaTot2) * (Vec_tao0 - Vec_taoA - muA0);
uVec_PrcShftA = mean(Vec_PrcShftA); sdVec_PrcShftA = std(Vec_PrcShftA);
uVec_PrcShft0 = mean(Vec_PrcShftO); sdVec_PrcShft0 = std(Vec_PrcShftO);
ruVec_PrcShftA = round(uVec_PrcShftA); rsdVec_PrcShftA = round(sdVec_PrcShftA);
ruVec_PrcShftA = round(uVec_PrcShftO); rsdVec_PrcShftO = round(sdVec_PrcShftO);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          % Read from files taoA and taoO values derived from a Gaussian distribution fnametaoA = sprintf(Exp%dCond%d_Vec_taoA.csv',ExpR,CondBO); fnametaoO = sprintf(Exp%dCond%d_Vec_taoO.csv',ExpR,CondBO);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             sigmaTot2 = sigmaA^2 + sigma0^2 + sigmaA0^2;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             % Compute for sigma_Tot
                                                                                                                                                                                                                                                                                                                sumError = sumError + errPrcShft;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         % Compute the action and oputcome perceptual shifts
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      Vec_taoA = dlmread(fnametaoA);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              Vec_tao0 = dlmread(fnametao0);
                                                                                                                                                                                                                        fprintf('Condition %d:\t %0.1f(%0.2f)\t %0.1f(%0.2f)\n, CondBO, ruVec_PrcShftA, rsdVec_PrcShftA, ruVec_PrcShftO, rsdVec_PrcShftO);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 [muA, sigmaA, muO, sigmaO] = soa_IBexperiment(ExpR, CondBO);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             Get the reported empricial baseline parameters
                                                                                                                                                                                                                                                                                                                                                                                            {\sf errPrcShft} = ({\sf abs(ruVec\_PrcShftA} - {\sf targPrcShftA}) + {\sf abs(ruVec\_PrcShft0} - {\sf targPrcShft0}))/2;
                                                                                                                                                                                                                                                                                                                                                                                                                                            NOTE: Even when we consider the average of action and outcome estimation errors, the optimal result is the same.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           with sigmaAO equal to 10ms.
                                        error:\t%0.2f:\n\n;modelEE);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           % clears all variables from the workspace
% clears the command window
% closes all figures (such as plots)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       % Actual physical stimulus timings
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   Experimental set-up Haggard et al. (2002): ExpR = 1; NumCond = 3; (Vol,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       Number of taoA and taoO instances to be generated
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              To obtain discernible perceptual shifts,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              sigmaAO should be small
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   Invol, Sham)
```

end

end

min_modelEE = modelEE;
opt_muA0 = muA0;

```
sigmaA0 = 10;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      muA0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     % Graph display fonts fontsize = 20; sizeBin = 200;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        \% Objective: Fit Haggard et al's data to find the optimal value for the free parameter P(Xi=1), \% muAO is 230ms and sigmaAO is 10ms.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  % % % %
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           arrPrcShftA = zeros(numCond, size_pXi1);
arrPrcShft0 = zeros(numCond, size_pXi1);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       size_pXi1 = numel(arrPXi1);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   LB = 0.0; INC = 0.1; UB = 1.0; arrPXi1 = LB:INC:UB;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           T = 250;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    % Interval length in consideration
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  % Cleaners
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   arrAOBinding = zeros(numCond, size_pXi1);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    % Data Matrices
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               % Optimal condition-independent parameters
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  ExpR = 1; numCond = 3;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           close all
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       clear
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        tAp=0; dist_tAt0=250; t0p=tAp+dist_tAt0;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                taoInstances = 35000;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         for CondB0 = 1:numCond
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            Simulation Conditions
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  Copyright
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                                                                                                                                                                                                                                                                                                                             indxPXi1 = size_pXi1 + 1;
for PXi_1 = UB:-INC:LB
    PXi_0 = 1 - PXi_1;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              % Read from files taoA and taoO values derived from a Gaussian distribution
fnametaoA = sprintf(Exp%dCond%d_Vec_taoA.csv',ExpR,CondBO);
fnametaoO = sprintf(Exp%dCond%d_Vec_taoO.csv',ExpR,CondBO);
                                                                                                                                                                                                                                                                                                                                                                                                                                                  Vec_taoA = dlmread(fnametaoA);
Vec_taoO = dlmread(fnametaoO);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  RIKEN Center for Brain Science
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 = 230;
                                                                                                                                                                              % Matrices to track optimal action and outcome estimates
Vec_PrcShftA = soa_InitMatrix(1,taoInstances);
Vec_PrcShft0 = soa_InitMatrix(1,taoInstances);
Vec_AOBinding = soa_InitMatrix(1,taoInstances);
                                                                                                                     for indx_tao = 1:taoInstances
                           taoA = Vec_taoA(indx_tao);
                                                            % Do for each pair of taoA and taoO
tao0 = Vec_tao0(indx_tao);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           \text{muA}\bar{0} is 230ms and sigmaAO is 10ms. Plot the action and outcome perceptual shifts given P(Xi=1) in the range [0.0,1.0] with 0.1 increments
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     % Number of taoA and taoO instances to be generated
% Experimental set-up
% Haggard et al. (2002): ExpR = 1; NumCond = 3; (Vol, Invol, Sham)
% Wolpe et al. (2013) : ExpR = 2; NumCond = 3; (Low, Int, High)
% Actual physical stimulus timings
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        % clears all variables from the workspace
% clears the command window
% closes all figures (such as plots)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           Large enough but finite constant
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```
soa_plotPrcShts(ExpR, arrPrcShftA, arrPrcShftO, arrPXi1, fontsize);
fnamePrcShft = sprintf('Exp%d_PXisPrcShfts.png',ExpR);
saveas(gcf,fnamePrcShft);
                                                                                                                                                                                                                                                                                                                                                                                              % Plot and store the perceptual shifts and action—outcome binding
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         end
                                                                            saveas(gcf, fnamePrcShft);
                                                                                                                soa_plotBehaviors(ExpR, arrAOBinding, arrPXi1, fontsize, 1);
fnamePrcShft = sprintf(Exp%d_PXisPrcShfts.png',ExpR);
Store the perceptual shifts
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  fprintf('\n');
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       arrPrcShftA(CondB0,indxPXi1) = uPrcShftA;
arrPrcShftO(CondB0,indxPXi1) = uPrcShftO;
arrAOBinding(CondB0,indxPXi1) = uAOBinding;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         ruVec_PrcShftA = round(uPrcShftA);
ruVec_PrcShft0 = round(uPrcShft0);
errPrcShftA = abs(ruVec_PrcShftA - targPrcShftA);
errPrcShft0 = abs(ruVec_PrcShft0 - targPrcShftO);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               uPrcShftA = mean(Vec_PrcShftA(:)); sdPrcShftA = std(Vec_PrcShftA(:));
uPrcShft0 = mean(Vec_PrcShft0(:)); sdPrcShft0 = std(Vec_PrcShft0(:));
uAOBinding = mean(Vec_AOBinding(:)); sdAOBinding = std(Vec_AOBinding(:));
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           indxPXi1 = indxPXi1 - 1;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    fprintf('uPercShfts :\t %0.2f(%0.2f)\t %0.1f(%0.1f)\n', uPrcShftA,
fprintf('Error in action perceptual shift: %0.2f\n', errPrcShftA);
fprintf('Error in outcome perceptual shift: %0.2f\n\n', errPrcShftO);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     fprintf('Condition %d \t P(Xi=1): %0.2f\n', CondBO, PXi_1);
fprintf('UPErcShftS :\t %0.2f(%0.2f)\t %0.1f(%0.1f)\n', UPrcShftA, sdPrcShftA, uPrcShftO,sdPrcShftO);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              [targPrcShftA, targPrcShft0] = soa_IBTargets(ExpR,CondB0);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      Compute for model estimation errors given the reported empirical results
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       % Compute for the posterior-ratio
Z1 = sqrt(2*pi)*sigmaA0*T;
Z0 = T^2;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                Vec_PrcShftA(1, indx_tao) = tAhat - taoA;
Vec_PrcShftO(1, indx_tao) = tOhat - taoO;
Vec_AOBinding(1, indx_tao) = 250 + (tOhat-taoO) - (tAhat-taoA);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          % Compute for strength of temporal binding if r > 1 % Causal
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           Theta = log((PXi_1*Z0)/(PXi_0*Z1));
sigmaTot2 = sigmaA^2 + sigmaO^2 + sigmaAO^2;
r = exp(Theta - ((taoO-taoA-muAO)^2/(2*sigmaTot2)));
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 else % Acausal
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        Get the reported empricial baseline parameters
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         [muA, sigmaA, muO, sigmaO] = soa_IBexperiment(ExpR, CondBO);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  tAhat = taoA + (sigmaA^2/sigmaTot2)*(tao0-taoA-muA0);
t0hat = tao0 - (sigmaO^2/sigmaTot2)*(tao0-taoA-muA0);
Xihat =1;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 tAhat = taoA;
tOhat = taoO;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            Xihat=0;
```

```
fnamePrcShftA = sprintf('Exp%d_arrPrcShftA.csv',ExpR);
fnamePrcShft0 = sprintf('Exp%d_arrPrcShft0.csv',ExpR);
dlmwrite(fnamePrcShftA, arrPrcShftA, 'delimiter',',');
dlmwrite(fnamePrcShft0, arrPrcShft0, 'delimiter',',');
%
                                 Notes to METHODS:

- Estimates of the perceptual shift in action timing alone was sufficient to indicate the optimal P(Xi=1) value. However, note the following.

- Although the optimal P(Xi=1) value for the voluntary and involuntary conditions is 1.0, the result is saturated. Hence, report P(Xi=1)=0.9 for both conditions.

- Report P(Xi=1)=0.1 for the sham condition, assuming causality is less frequently detected.

- Although the ptimal P(Xi=1) value for the intermediate tone uncertainty condition is 0.5, the outcome binding behavior is not consistent with the reported outcome binding. Report P(Xi=1)=0.6 for the intermediate tone uncertainty condition since it also best minimized the estimation error while reproducing the reported action and outcome bindings.
```

% % %

```
sigmaA0 = 10;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            muA0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       % Graph display fonts fontsize = 20; sizeBin = 200;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        % Objective: Compute the trial-to-trial temporal binding and repulsion effects,
% as well as the baseline and operant temporal bindings,
% as functions of temporal disparity, i.e., tao0-taoA
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         Vec_taoI = zeros(numCond,taoInstances);
Vec_OpPrcShfts = zeros(numCond,taoInstances);
Vec_BsPrcShfts = zeros(numCond,taoInstances);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             % Interval length in consideration
T = 250;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      % Optimal condition—independent parameters
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            taoInstances = 35000;
ExpR = 2; numCond = 3;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              clear
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       % Cleaners
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             Vec_PrcShftA = zeros(numCond,taoInstances);
Vec_PrcShft0 = zeros(numCond,taoInstances);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          % Data Matrices
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    % Simulation Conditions
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      close all
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        tAp=0; dist_tAt0=250; t0p=tAp+dist_tAt0;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         for CondB0 = 1:numCond
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  Copyright
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end
                                                                                                                                                                                                                                                                                                                                                                                                                                            % Simulated using the fitted P(Xi=1) optimal values
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    % Read from files taoA and taoO values derived from a Gaussian distribution
fnametaoA = sprintf(Exp%dCond%d_Vec_taoA.csv,ExpR,CondBO);
fnametaoO = sprintf(Exp%dCond%d_Vec_taoO.csv,ExpR,CondBO);
                                                                                                                                                                                         elseit ExpR==2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  Vec_taoA = dlmread(fnametaoA);
Vec_tao0 = dlmread(fnametao0);
                                                                                                                                                                                                                                                                                                                                                                                                                        if ExpR==1
                                             if CondBO == 1

PXi_1 = 0.9;

PXi_1 = 0.6;

PXi_1 = 0.6;

else PXi_1 = 0.5;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          = 230;
                                                                                                                                                                                                                                                                               else
                                                                                                                                                                                                                                                                                                   PXi_1 = 0.9;
elseif CondB0 == 2
PXi_1 = 0.9;
                                                                                                                                                                                                                                                                                                                                                                                            if CondBO == 1
                                                                                                                                                                                                                                              PXi_1 = 0.1;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      % Number of taoA and taoO instances to be generated
% Experimental set-up
% Haggard et al. (2002): ExpR = 1; NumCond = 3; (Vol, Invol, Sham)
% Wolpe et al. (2013) : ExpR = 2; NumCond = 3; (Low, Int, High)
% Actual physical stimulus timings
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             % clears all variables from the Workspace % clears the Command Window
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             % Large enough but finite constant
```

 $PXi_0 = 1 - PXi_1;$

```
[sortedtaoI(1,:), sortIndx1] = sort(Vec_taoI(1,:));
[sortedtaoI(2,:), sortIndx2] = sort(Vec_taoI(2,:));
[sortedtaoI(3,:), sortIndx3] = sort(Vec_taoI(3,:));
sortedPrcShftA = soa_sortMatrices(Vec_PrcShftA, sortIndx1, sortIndx2, sortIndx3);
sortedPrcShft0 = soa_sortMatrices(Vec_PrcShft0, sortIndx1, sortIndx2, sortIndx3);
sortedOpPrcShfts = soa_sortMatrices(Vec_OpPrcShfts, sortIndx1, sortIndx2, sortIndx3);
sortedBsPrcShfts = soa_sortMatrices(Vec_BsPrcShfts, sortIndx1, sortIndx2, sortIndx3);
                                                                                                                                                                                                                                                                                                 soa_plotErrorBars(ExpR, sortedtaoI, sortedPrcShftA, fontsize,
fnamePrcShft = sprintf(Exp%d_perTrialPrcShftA.png',ExpR);
saveas(gcf,fnamePrcShft);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    end
                            soa_plotErrorBars(ExpR, sortedtaoI, sortedOpPrcShfts, fontsize, 1, sizeBin);
fnamePrcShft = sprintf(Exp%d_perTrialOperantPrcShfts.png;ExpR);
                                                                                                                               soa_plotErrorBars(ExpR, sortedtaoI, sortedBsPrcShfts, fontsize, 1,
fnamePrcShft = sprintf(Exp%d_perTrialBaselinePrcShfts.png,ExpR);
                                                                                                                                                                                                                                soa_plotErrorBars(ExpR, sortedtaoI, sortedPrcShft0, fontsize, 1, sizeBin);
fnamePrcShft = sprintf(Exp%d_perTrialPrcShft0.png;ExpR);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         % Plot and store the perceptual shifts
saveas(gct,tnamePrcShtt);
                                                                                             saveas(gcf, fnamePrcShft);
                                                                                                                                                                                                    saveas(gcf, fnamePrcShft);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       sortedtaoI = Vec_taoI;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          for indx_tao = 1:taoInstances
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                Theta = log((PXi_1*Z0)/(PXi_0*Z1));
sigmaTot2 = sigmaA^2 + sigma0^2 + sigmaA0^2;
r = exp(Theta - ((tao0-taoA-muA0)^2/(2*sigmaTot2)));
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               else % Acausal
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             Z1 = sqrt(2*pi)*sigmaA0*T;
Z0 = T^2;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              Vec_BsPrcShfts(CondBO, indx_tao)
Vec_OpPrcShfts(CondBO, indx_tao)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               Vec_PrcShftA(CondBO, indx_tao)
Vec_PrcShftO(CondBO, indx_tao)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     if r > 1 % Causa
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                taoA = Vec_taoA(indx_tao);
tao0 = Vec_taoO(indx_tao);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           % Do for each pair of taoA
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               Vec_taoI(CondBO, indx_tao)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          [muA, sigmaA, muO, sigmaO] =
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        Compute for the posterior-ratio
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            Get the reported empricial baseline parameters
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 Compute for strength of temporal binding
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  Xihat =1;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 tAhat = taoA + (sigmaA^2/sigmaTot2)*(taoO-taoA-muAO);
tOhat = taoO - (sigmaO^2/sigmaTot2)*(taoO-taoA-muAO);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               Xihat=0;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              t0hat = tao0;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                tAhat = taoA;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           and tao0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                soa_IBexperiment(ExpR, CondB0);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               = tAhat - taoA;
= t0hat - taoO;
= taoO - taoA;
= t0hat - tAhat;
= taoO - taoA;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    tAhat;
                                                                                                                                                                                                                                                                                                                                                                         ,1
                                                                                                                                                                                                                                                                                                                                                                               sizeBin);
```

% % %

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size_pXi1 = numel(arrPXi1);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           % Interval length in consideration T = 250;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            sigmaA0 = 10;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                muA0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       taoInstances = 35000;
ExpR = 2; numCond = 3;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           % Graph display fonts fontsize = 20; sizeBin = 200;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           % Objective: Compute the Confidence on Causal Estimate (CCE) along P(Xi=1) % values in the range [0.0,1.0] with increments of 0.1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  LB = 0.0; INC = 0.1; UB = 1.0; arrPXi1 = LB:INC:UB;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           % Optimal condition—independent parameters
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               close all
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          clear
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        % Cleaners
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         arrCCE = zeros(numCond, size_pXi1);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   % Data Matrices
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              tAp=0; dist_tAt0=250; t0p=tAp+dist_tAt0;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   for CondB0 = 1:numCond
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  Simulation Conditions
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          % Read from files taoA and taoO values derived from a Gaussian distribution
fnametaoA = sprintf(Exp%dCond%d_Vec_taoA.csv',ExpR,CondBO);
fnametaoO = sprintf(Exp%dCond%d_Vec_taoO.csv',ExpR,CondBO);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              Vec_taoA = dlmread(fnametaoA);
Vec_tao0 = dlmread(fnametao0);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          RIKEN Center for Brain Science
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                for PXi_1 = UB:-INC:LB
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      indxPXi1 = size_pXi1 + 1;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             = 230;
                                                                                                                                                                                                                                                                                                for indx_tao = 1:taoInstances
                                                                                                                                                                                                                                                                                                                                                         Vec_CCE = soa_InitMatrix(1,taoInstances);
                                                                                                                                                                                                                                                                                                                                                                                                                       PXi_0 = 1 - PXi_1;
                                                                                                                                                                          % Do for each pair of taoA and tao0
taoA = Vec_taoA(indx_tao);
tao0 = Vec_taoO(indx_tao);
% Compute CCE
Z1 = sqrt(2*pi)*sigmaA0*T;
                                                                                      [muA, sigmaA, mu0, sigma0] = soa_IBexperiment(ExpR, CondB0);
                                                                                                                    Get the reported empricial baseline parameters
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         % Number of taoA and taoO instances to be generated
% Experimental set-up
% Haggard et al. (2002): ExpR = 1; NumCond = 3; (Vol, Invol, Sham)
% Wolpe et al. (2013) : ExpR = 2; NumCond = 3; (Low, Int, High)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          % clears all variables from the Workspace % clears the Command Window
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      % Large enough but finite constant
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   % Actual physical stimulus timings
```

```
sigmaA0 = 10;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 muA0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             taoInstances = 35000;
ExpR = 1; numCond = 3;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     % Graph display fonts fontsize = 20; sizeBin = 200;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        % Published: August 14, 2019
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               Vec_CCE = soa_InitMatrix(numCond,taoInstances);
Vec_taoI = soa_InitMatrix(numCond,taoInstances);
Vec_Pc = soa_InitMatrix(numCond,taoInstances);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       % Interval length in consideration T = 250;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               close all
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   % Cleaners
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       % Objective: Compute the trial-to-trial Confidence on Causal Estimate (CCE)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   % Data Matrices
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          % Optimal condition-independent parameters
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           tAp=0; dist_tAt0=250; t0p=tAp+dist_tAt0;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          clear
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              for CondB0 = 1:numCond
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              s Simulation Conditions
                                                                                                                                                                                                                                                                     elseif ExpR=2

if CondB0 == 1

PXi_1 = 0.9;

PXi_1 = 0.6;

elseif CondB0 == 2

PXi_1 = 0.6;

else PXi_1 = 0.5;
                                                 % Read from files taoA and taoO values derived from a Gaussian distribution
fnametaoA = sprintf(Exp%dCond%d_Vec_taoA.csv',ExpR,CondBO);
fnametaoO = sprintf(Exp%dCond%d_Vec_taoO.csv',ExpR,CondBO);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        % Simulated using the fitted P(Xi=1) optimal values
Vec_taoA = dlmread(fnametaoA);
Vec_tao0 = dlmread(fnametaoO);
                                                                                                                                                              PXi_0 = 1 - PXi_1;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    if ExpR==1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     if CondB0 == 1
PXi_1 = 0.9;
elseif CondB0 == 2
PXi_1 = 0.9;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 = 230;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 else
                                                                                                                                                                                                                                                                                                                                                                                                                                                                 PXi_1 = 0.1;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           % Number of taoA and taoO instances to be generated
% Experimental set-up
% Haggard et al. (2002): ExpR = 1; NumCond = 3; (Vol, Invol, Sham)
% Wolpe et al. (2013) : ExpR = 2; NumCond = 3; (Low, Int, High)
% Actual physical stimulus timings
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            % clears all variables from the Workspace % clears the Command Window
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     % Large enough but finite constant
```

for indx_tao = 1:taoInstances

```
% Do for each pair of taoA and taoO
taoA = Vec_taoA(indx_tao);
taoO = Vec_taoA(indx_tao);
% Get the reported empricial baseline parameters
[muA, sigmaA, muO, sigmaO] = soa_IBexperiment(ExpR, CondBO);
% Compute CCE
Z1 = sqrt(2*pi)*sigmaAO*T;
Z0 = I^2;
Theta = log((PXi_1*Z0)/(PXi_0*Z1));
SigmaTot2 = sigmaAO*2 + sigmaDO*2 + sigmaTot2)) + log(sigmaAO/sqrt(sigmaTot2));
Yec_CCE(CondBO, indx_tao) = (sqrt(sigmaTot2)) + log(sigmaAO/sqrt(sigmaTot2));
Yec_CCE(CondBO, indx_tao) = (sqrt(sigmaTot2)) / (2*pi*sigmaAv*sigmaO*sigmaAO)) *..

Vec_taoI(CondBO, indx_tao) = taoO-taoA;
end
end
end
end
end
end
end
store trial-to-trial CCE as function of temporl disparity
sortedtaoI(1,:), sortIndx1] = sort(Vec_taoI(1,:));
[sortedtaoI(2,:), sortIndx2] = sort(Vec_taoI(2,:));
[sortedtaoI(3,:), sortIndx3] = sort(Vec_taoI(2,:));
[sortedtaoI(3,:), sortIndx3] = sort(Vec_taoI(3,:));
[sortedtaoI(3,:), sortIndx3] = sort(Vec_taoI(3,:));
[sortedtaoI(3,:), sortIndx3] = sort(Vec_taoI(2,:));
[sortedtaoI(3,:), sortIndx3] = sort(Vec_taoI(2,:));
[sortedtaoI(3,:), sortIndx3] = sort(Vec_taoI(3,:));
[sortedtaoI(3,:), sortIndx3] = sort(Vec_taoI(2,:));
[sortedtaoI(3,:), sortIndx3] = sort(Vec_taoI(3,:));
[sortedtaoI(3,:), sortIndx3] = sort
```

```
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                                                                                                                                                                                                                                                      elseif experiment_case == 2
% Wolpe et al. 2013 (Exp Brain Res): Uncertainty is with the outcome
% Different tone (i.e., the outcome) conditions
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    if experiment_case == 1
% Haggard et al., 2002 (Nat Neurosci): Seminal intentional binding experiment
% Different keypress (i.e., the action) conditions
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              % Objective: Return the means and standard deviations of the reported baseline action and outcome timing judgment errors
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         function [mu_A, sigma_A, mu_0, sigma_0] = soa_IBexperiment(experiment_case, condition)
end
                          end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          if condition == 1
mu_A = 6; sigma_A = 66;
elseif condition == 2
                                                                                                                                                                                                                                                                                                                                                                                                                                                  mu_A = 83; sigma_A = 83;
elseif condition == 3
                                                                         elseif condition == 3
                                                                                                                              elseif condition == 2
                                                                                                                                                                             mu_A = -8; sigma_A = 75;
if condition == 1
                                                                                                                                                                                                                                                                                                                                                                    mu_0 = 15; sigma_0 = 72;
                                                                                                                                                                                                                                                                                                                                                                                                      end
                                                                                               mu_0 = 46; sigma_0 = 66;
                                                                                                                                                       mu_0 = 35; sigma_0 = 61;
                                              mu_0 = 95; sigma_0 = 90;
                                                                                                                                                                                                                                                                                                                                                                                                                         mu_A = 32; sigma_A = 78;
```

```
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% Lab for Neural Computation and outcome perceptual shifts
% Objective: Return the reported action and outcome perceptual shifts
% Objective: Return the reported action and outcome perceptual shifts
% Objective: Return the reported action and outcome perceptual shifts
% Objective: Return the proposed action and outcome perceptual shifts
% Objective: Return the reported action and outcome perceptual shifts
further shifts
for the operant conditions

if experiment = 1
    trgtprcShftA, trgtprcShftA = 15;
    trgtprcShftA = 15;
    trgtprcShftA = -27;
    trgtprcShftA = -27;
    trgtprcShftA = -3;
    trgtprcShftA = -3;
    trgtprcShftA = -3;
    trgtprcShftA = 39;
    trgtprcShftA = 39;
    trgtprcShftA = 39;
    trgtprcShftA = 31;
    trgtprcShftA = 31;
    trgtprcShftA = 31;
    trgtprcShftA = 32;
    trgtprcShftA = 33;
    trgtprcShftA = 33;
    trgtprcShftA = 32;
    trgtprcShftA = -105;
    end
```

```
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%
% Objective: Instantiate a rows-by-cols matrix with zero values
function [matrix_] = soa_InitMatrix(rows_, cols_)
matrix_ = zeros(rows_, cols_);
```

```
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% Objective: Sort the cotents of the matrices
function [sortedMatrix] = soa_sortMatrices(vectMatrix, sortIndx1, sortIndx2, sortIndx3)
sortedMatrix(1,:) = vectMatrix(1,sortIndx1);
sortedMatrix(2,:) = vectMatrix(2,sortIndx2);
sortedMatrix(3,:) = vectMatrix(3,sortIndx3);
```

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```
% Objective: Graph the action and outcome perceptual shifts as functions the strenth of the causal prior
set(gca, 'FontSize', fontsize);
set(gca, 'Box', 'on');
set(lgnd, 'Color', 'none');
set(gca, 'color', 'white');
set(gca, 'FontSize', fontsize);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          F = figure;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              elseif experiment == 2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   function F = soa_plotPrcShts(experiment, arrPrcShftA, arrPrcShftO, arrPXi1, fontsize)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           linewidth =
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               experiment == 1
% Haggard et al., 2002 (Nat Neurosci): Seminal intentional binding experiment
% Different keypress (i.e., the action) conditions
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     plot(arrPXi1,arrPrcShftA(1,:);Color', [0 0 250/255], 'LineStyle','--', 'Linewidth', linewidth); plot(arrPXi1,arrPrcShftA(1,:);Color', [0 0 250/255], 'LineStyle','---', 'Linewidth', linewidth); plot(arrPXi1,arrPrcShftA(2,:);Color', [0 140/255 255/255], 'LineStyle','--', 'Linewidth', linewidth); plot(arrPXi1,arrPrcShftA(3,:);Color', [0 140/255 255/255], 'LineStyle','--', 'Linewidth', linewidth); plot(arrPXi1,arrPrcShftA(3,:);Color', [0 240/255 255/255], 'LineStyle','--', 'Linewidth', linewidth); plot(arrPXi1,arrPrcShftO(3,:);Color', [0 240/255 255/255], 'LineStyle','--', 'Linewidth', linewidth); plot(arrPXi1,arrPrcShftO(3,:);Color', [0 240/255 255/255], 'LineStyle','---', 'Linewidth', linewidth); plot(arrPXi1,arrPrcShftO(3,:);Color', [0 240/255 255/255], 'LineStyle', '---', 'Linewidth', linewidth', lin
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     % Wolpe et al. 2013 (Exp Brain Res): Uncertainty is with the outcome bifferent tone (i.e., the outcome) conditions
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           set(lgnd.BoxFace, 'ColorType', 'truecoloralpha', 'ColorData', uint8(255*[1; 1; 1; 0.8]));
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        *" stegerior voluntary Action', 'Tone', 'Involuntary MEP',' Tone', 'Sham TMS',' Tone', 'Location', 'northwest');

lgnd = legend('Voluntary action',' and tone', 'Involuntary action',' and tone', 'Sham',' and tone', 'Location', 'northwest', 'Orientation',' vertical');

lgnd.FontSize = 18;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 set(lgnd.BoxFace, 'ColorType', 'truecoloralpha', 'ColorData', uint8(255*[1; 1; 1; 0.8]));
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             lgnd.FontSize = 18;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  9n
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           2;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 'Action', ' and high uncertainty tone', 'Location', 'northwest');
```

% %

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```
if experiment == 1
  % Haggard et al., 2002 (Nat Neurosci): Seminal intention
  % Different keypress (i.e., the action) conditions
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            elseif experiment == 2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          markerSize);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            markerSize);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     markerSize);
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         markerSize = 27;
lineWidth = 0.1;
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       function F = soa_plotErrorBars(experiment, arrAxes, arrBehavior, fontsize,
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             % Objective: Plot the
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                                                                                                                               lgnd = legend('Low uncertainty', 'Intermediate uncertainty', 'High uncertainty', 'Location', 'northwest');
set(lgnd.BoxFace, 'colorType', 'truecoloralpha', 'ColorData', uint8(255*[1; 1; 0.8]));
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set(gca, 'Box', 'on');
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legend('Voluntary condition', 'Involuntary condition', 'Sham condition', 'Location', 'northwest');
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hold

end
set(gca,'FontSize', fontsize);

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Function to graph the Added 09/06/2017

SoA

related

measures

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function F = soa_plotBehaviors(experiment, arrBehavior, arrPXi1, fontsize, behavior)
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                                                                                                                                                                                                                                                                                                                                                             ylabel('Judgment of Agency');
elseif behavior == 3
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xlabel('P(\xi=1) of Prior');
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plot(arrPXi1, arrBehavior(2,:);Color',
plot(arrPXi1, arrBehavior(3,:);Color',
hold off;
                           if behavior == 1
    lgnd = legend('Voluntary condition', 'Involuntary condition', 'Sham condition', 'Location', 'northwest');
elseif behavior == 3
                                                                                                                                                                                                                                                                ylabel('Bias in Outcome Estimates');
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plot(arrPXi1,arrBehavior(2,:);Color',
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plot( arrPXi1, arrBehavior(2,:),'r', arrPXi1, arrBehavior(1,:),'b', arrPXi1, arrBehavior(3,:),'k', 'Linewidth', linewidth);
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plot(arrPXi1,arrBehavior(2,:),'r','Linewidth',3);
plot(arrPXi1,arrBehavior(3,:),'Color', [0 0 0]+0.05*13,'Linewidth',3);
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lgnd = legend('Voluntary condition', 'Involuntary condition', 'Sham condition', 'Location', 'northwest');
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[0 140/255 255/255], 'LineStyle','-', 'Linewidth', linewidth);
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set(gca,'FontSize', fontsize);
set(gca, 'Box', 'on');
set(gca, 'Box', 'on');
%set(lgnd, 'Color', 'none');
set(gca,'color', 'white');
set(lgnd.BoxFace, 'ColorType', 'truecoloralpha', 'ColorData', uint8(255*[1; 1; 1; 0.8]));
% If you want to bold %ylabel('Feeling of Agency', 'FontWeight', 'bold');
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         elseif experiment == 3
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        elseif experiment == 2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               lgnd = legend('Active, Instructed', 'Passive, Instructed', 'Location', 'northeast');
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     end
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              lgnd = legend('Low uncertainty condition', 'Intermediate uncertainty condition', 'High uncertainty condition', 'Location', 'northeast');
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      lgnd = legend('Voluntary condition', 'Involuntary condition', 'Sham condition', 'Location', 'northwest');
```