Appendix A: Table 1

Article Name + Article Web Link	Uppe r limb / or lower limb	Sev erit Y	Assessm ent scale	Roboti c / Exosk eleton Techn ology (Devic e)	D O F	Actuat or type	Data source / Control input	Of-the- shelf (commer cial) / OR Prototyp e & type model of device if commerc ial product	Exoskeleto n Function / Wearable Exoskeleto n placement	Clinica trail / or Home - based rehabi litatio n	Virtual reality / Augmented Rehabilitatio n Intervention ? Yes/No	Sa mpl e Size	Durati on of Exosk eleton VR Rehab ilitatio n progra m	Time of each VR - AR- GM task/session	Rehabil itation game difficul ty level	Real-time feedback - Game	Feedback	Results/improvements
(Lamberc y et al., 2011)	Upper limb	597 .5 ± 294 .1 day s	Fugl- Meyer Motor Assessm ent (FMA)	Haptic Knob (end- effect or device)	2	Motor	forearm and hand	Commer cial	arm and hand function	Clinica I	Games	13	18 hours	60 minutes	Not mentio ned	A score of the game was provided as a feedback to the patient, which was then used to adjust the difficulty level of the game.	Image and game are used during study in order to calculate score based on the timing and precision of the task	Thirteen subjects successfully completed robot-assisted therapy, with significantly improved hand and arm motor functions (average 3.00 points increase on the FM and 4.55 on the MI). Also, it was concluded that as distal training in a functional way could benefit the whole arm so there would not be a need to do whole arm training in robot- assisted neurorehabilitation.
(Klamrot h- Margans ka et al., 2014)	Upper limb	52± 44 (7 – 171)	Fugl- Meyer Motor Assessm ent (FMA)	ARMin (in 3D works pace)	7	Motor	Arm motor impairment	Commer cial	Arm and Shoulder	Clinica I	Virtual Reality (Games)	38	24 sessio ns	45 minutes	Adjuste d by therapi st	Not mentioned	Audio - Visual feedback was provided to patients to increase motivation	Robotic training of the affected arm with ARMin was found to be more effective than conventional therapy in terms of motor function (FMA-UE: F = 4·1, p = 0·041, mean difference: 0·78 points, confidence interval [0·03 - 1·53]).
(Khor et al., 2017)	Upper limb	7.9 ± 6.6 mo nth s	Fugl- Meyer Motor Assessm ent (FMA)	prove d to b	1	1 actuat or	forearm and wrist	Commer cial	arm and hand function	Clinica I & Home	VR Game	7	30	30min robot- assisted	Not mentio ned	VR game provided during the robotic therapy have helped to engage users in a multi-sensory simulated environment that included real-time visual, auditory and tactile feedback	VR game provided during the robotic therapy have helped to engage users in a multi- sensory simulated environment that included real- time visual, auditory and tactile feedback	Improvement of active range of motion was detected in both pronation-supination (75.59%, p = 0.018) and wrist flexion- extension (56.12%, p = 0.018) after the training

(Acosta et al., 2011)	Upper limb	2- 15y ear s	Fugl- Meyer Motor Assessm ent (FMA)	Arm Coordi nation Traini ng 3D (ACT3 D) syste m	6	Motor	Shoulder	Commer cial	Shoulder	Clinica I	Video Game	7	56	3 minutes + 1 minutes rest	Difficul ty level was based on the require ment for reachin g movem ents of the game.	Game feedback was provided to the patient in the form of an avatar.	Visual feedback on reaching performance through Air Hockey 3D game is given to impaired people/auditory feedback (buzzing noise) was also provided	Reaching distances achieved with the avatar feedback were greater on average than those achieved with Air Hockey 3D across conditions. Therefore results showed that video games and robotic systems that target specific impairments could be developed that would be useful for stroke rehabilitation.
(Wolf et al., 2015)	Upper limb	less tha n 6 mo nth s	Fugl- Meyer Motor Assessm ent (FMA)	Hand Mento r Pro (HMP)	N ot m e n t i o n e d	Motor	Hand	Commer cial	Hand	Home	Video Game	47	40 days (120 hours)	3 hrs/day	Same throug hout the therap y and patient s were given training	Not mentioned	HMP used a pneumatic artificial muscle to facilitate movement about the wrist and fingers while providing visual biofeedback about the quality and quantity of wrist movements.	Significant improvements were found in a group of patients showing an increase in ARAT scores and WMFT tasks.
(Ueki et al., 2012)	Upper limb	Not pro vid ed	Torque measure ment device	Hand Motio n Assist Robot (Exosk eleton)	1 8	Servo motor	Hand (thumb and finger)	Commer cial	Hand	Clinica I	Virtual Reality	6 hea lthy and 6 stro ke pati ent s	-	20 min	Change d accordi ng to movabl e range	Not mentioned	Scores are recorded, and the GUI showed the three scores (today, best, and last time) by status bars.	The response of the motion assist mechanism showed that hand motion assisted robot has good-to-excellent properties and a high potential for providing hand rehabilitation therapy by self-motion control.
(Grimm et al., 2016)	Upper limb	8- 156 mo nth s	Fugl- Meyer Motor Assessm ent (FMA)	Armeo Spring	7	Not availa ble	Shoulder, elbow and wrist joints	Commer cial	Arm	Clinica I	Virtual Reality	5	4 weeks /20 sessio ns	20	The level of difficult y for the exercis e was adjuste d by a perfor mance- depend ent real- time adaptat ion algorith	Feedback as to the movement quality, i.e., the absence or presence of compensatory movements was provided.	The subjects received brain self-regulation and proprioceptive feedback and closed-loop virtual reality feedback from their three- dimensional movements.	There was an improvement of kinematic parameters and therefore was significant motor improvements in grip force and elbow movement.

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(Forreste r et al., 2011)	Lower limb	> 6 mo nth s	Robot- based measure s to evaluate ankle impairm ent and gait function	Ankle bot	3	Not availa ble	Ankle	Commer cial	Ankle	Clinica I	Video games	8	6 weeks /3 times weekl y	60 minutes	Easy- to- difficult	Not mentioned	Visual feedback was presented during movement	Improved paretic ankle motor control was seen as increased target success, along with faster and smoother movements. Walking velocity also increased significantly, whereas durations of paretic single support increased, and double support decreased.
(Mirelma n et al., 2010)	Lower limb	> 2 yea rs	Two factorial (training regime time) repeated measure s analysis of variance	Rutger s ankle rehabi litatio n syste m (RARS)	6	Not availa ble	Foot	Commer cial	Foot	Clinica I	Virtual Reality	18	4 weeks /3 times per week	60 minutes	Not applica ble	Not applicable	Feedback is provided with VR - visual and auditory feedback	The ankle profiles of the affected side showed an increase in the peak plantar flexion moment, and ankle power generation.
(Comani et al., 2015)	Upper limb	sub - acu te sta ge	Motricity Index/Ba rthel Index	Trackh old	N ot m e n t i o n e d	Motor	Arm	Commer cial	Arm	Clinica I	Virtual Reality	3	13 sessio ns	-	Not applica ble	Not applicable	Feedback is provided with VR - visual and auditory feedback	The patterns of activation with specific features and recovery trajectories for each patient was observed and improvements were observed.
(Connelly et al., 2010)	Upper limb	-	Fugl- Meyer Motor Assessm ent (FMA)	PneuG love	6	Servo motor	Hand	Commer cial	Hand	Clinica I	Virtual Reality	14	6 Weeks	60 minutes	Not applica ble	Not applicable	Wide5 Head Mounted Display (HMD) is used as a display device to provide a measure of haptic feedback.	Significant increases in the upper extremity Fugl-Meyer Assessment scores were achieved.

(Delbress ine et al., 2012)	Upper limb	-	Not mention ed	Sensor Jacket	N o t m t i o n e d	-	Chest and Shoulder	Prototyp e	Chest	Clinica I	Games	12	NA	40 minutes	Difficul ty level was changi ng as per particip ants.	Real time is provided through a graphical representation consisting of two bars, one for the shoulder and one for trunk movement.	Vibrotactile feedback is provided on the corresponding body part on a graphical interface.	Need more improvement in choosing the right game for patients.
(Gijbels et al., 2011)	Upper limb	27 ± 10 yea rs	TEMPA	Armeo Spring	5	Non roboti c actuat or / Passiv e syste m	Arm	Commer cial	Arm	Clinica I	Virtual Reality	10	8 weeks / 3 times per week	30 minutes	Not applica ble	Not applicable	Auditory and visual performance feedback during and after practice	TEMPA scores improved (p = 0.02), while a trend towards significance was found for the 9HPT (p = 0.05)
(House et al., 2016)	Upper limb	Ave rag e of 98 (45) mo nth s	Fugl- Meyer Motor Assessm ent (FMA)	Bright Arm Duo Arm Suppo rt	N o t m e n t o n e d	Electri cəl actuat ors	Arm	Commer cial	Arm	Clinica I	Games	7	8 weeks	20 min - 50 min	Games	Nine games included summative performance feedback which provided positive reinforcement and were meant as morale boosters.	Feedback of the table current status was made available to the therapist at the laptop station or output display	The most significant improvement was in grasp strength of the affected arm from an average of 7.6 N pretherapy to 17.2 N post- therapy
(Buschfo rt et al., 2010)	Upper limb	4.3 we eks	Fugl- Meyer- Assessm ent and Action Research Arm Test	Arm studio	N ot m e n t o n e d	Not availa ble	Arm	Commer cial	Arm	Clinica I	Games	24	3 weeks /15 sessio ns	30-45 min	Games	Not mentioned	Computer biofeedback, via a wireless mouse connected to the combining rod, is optional.	The arm studio provides high-intensity impairment oriented training may have great potential for the rehabilitation of the upper limb of severely affected patients after stroke in terms of cost effectiveness and customizable effects.
(Cameira o et al., 2012)	Upper limb	133 4± 297 day s	Barthel Index, Motricity Index22, Modified Ashwort h Scale, Fugl- Meyer Assessm	RGS- Haptic (RGS- H)	6	Not availa ble	Arm	Prototyp e	Arm	Clinica I	Virtual Reality	14	5 weeks (4 days a week)	35 min	Difficul ty level was update d online by a psycho metrica lly validat	Not applicable	Visual feedback was presented during movement	Improvements were assessed more in patients allocated to the RGS-H group (average rating of 3.7 against 2.8 for RGS and 2.9 for RGS-E).

			ent, Chedoke Arm and Hand Activity Inventor y (CAHAI), Nine Hole Peg Test and Box and Block Test.												ed adaptiv e controll er, or Person alized Trainin g Module			
(da Silva Cameirã o et al., 2011)	Upper limb	3 we eks	Fugl- Meyer Motor Assessm ent (FMA)	Data Gloves	N o t m e n t i o n e d	Not availa ble	Hand	Prototyp e	Hand	Clinica I	Virtual Reality	8	12 weeks	20 min	New difficult y setting was comput ed taking into accoun t the previou s respon ses of the user	Not applicable	Sensory feedback of one's actions in terms of movement patterns and movement outcomes was provided.	Rehabilitation Gaming System speeds-up the recovery of the deficits of the upper extremities, with particular emphasis on functional aspects related to the performance of the activities of daily living.
(Liao et al., 2012)	Upper limb	23. 90 ± 13. 39 mo nth s	Fugl- Meyer Motor Assessm ent (FMA)	Bi- Manu- Track	N o t m e n t o n e d	Not availa ble	Arm	Not mention ed	Arm	Clinica I	Games	10	20 sessio ns/ 4 weeks (5 days a week)	90-105 minutes a day	Not mentio ned	Real-time visual feedback about the actions or force.	Variety of variety of sensorimotor feedback such as visual and auditory feedback during training sessions is provided.	The robot-assisted therapy group handled more daily tasks with the impaired arm than the control group. Also motor function was greatly improved.
(Hsieh et al., 2011)	Upper limb	21. 33 (7.1 7) mo nth s for Gro up 1 and 13.	Fugl- Meyer Motor Assessm ent (FMA)	Bi- Manu- Track	N ot m e n t i o n e d	Not availa ble	Arm	Not mention ed	Arm	Clinica I	Games	6	4 weeks (5 days a week)	90-105 min/d,	Not mentio ned	Visual movement feedback was provided from the game	The therapist also provided the verbal feedback with the visual feedback from the game.	Post hoc analyses revealed that the higher intensity RT group showed significantly better improvements in motor ability than the lower intensity RT group (P = .04)

		00 (7.0 4) for Gro up 2																
(Zhang et al., 2011)	Upper limb	-	Wolf Motor Function Test (WMFT) and Fugl Meyer Assessm ent (FMA).	RUPER T	5	Pneu matic (PAMs)	Arm	Commer cial	Arm and Shoulder	Home	Virtual Reality	2	once/ weekd ay for 4 weeks	45	Change d by therapi st.	Not applicable	-	Out of 2 patients, 1 showed improvements in movement smoothness on targets whereas second patient did not experience ascending nor descending trend in smoothness.
(Frisoli et al., 2012)	Upper limb	Bet we en 3 and 9 yea rs	Fugl- Meyer Assessm ent scale and Modified Ashwort h scale	L-Exos	4	Electri c motor s	Arm	Commer cial	Arm	Clinica I	Virtual Reality	9	18 sessio ns/6 weeks	60 minutes	Not applica ble	Not applicable	-	There was an improvement of the motor performance and the reduction of the muscular spasticity.
(Mihelj et al., 2012)	Upper limb	128 ± 64 day s	-	Haptic Maste r robot	3	DC brush ed motor s	Arm	Commer cial	Arm	Clinica I	Virtual Reality (Games)	16	Twice a week/ 2 weeks	Minimum 5 minutes	Adjuste d by therapi st	Not applicable	Visual and Acoustic feedback is provided.	Helps in increasing motivation of patients in rehabilitation process.
(Sivan et al., 2014)	Upper limb	24. 8 (17. 8) mo nth s	Optotrak kinemati c variables , Fugl Meyer Upper Extremit y motor subscale (FM-UE), Action Research Arm Test (ARAT), Medical Research Council (MRC)	Home- based Comp uter Assist ed Arm Rehab ilitatio n (hCAA R) roboti c device	_	-	Hand	-	Hand	Home	Games	17	8 weeks	Mean device usage time 520 min	Level was changi ng as per the extent of worksp ace used.	Not mentioned	Visual and auditory feedback of the target location and the movement of the joystick was provided.	The percentage improvement in the median movement time at A1 was by 19%, path length improved by 15% and jerk improved by 19%

			and Modified Ashwort h Scale (MAS), Chedoke Arm and Hand Activity Inventor y (CAHAI) and ABILHAN D															
(Amirabd ollahian et al., 2014)	Upper limb	11 mo nth s (± 6 mo nth s).	Fugl- Meyer Motor Assessm ent (FMA)	SCRIP T Protot ype 1 (SP1)	-	-	Hand (thumb and finger)	Prototyp e	Hand	Home	Games	12	6 Weeks	30 min per day,	Game difficult y increas es when lateral movem ent of the arm are added to the flexion. and extensi on of the hand	Not mentioned	(Bio) feedback is provided about patient's performance	The study showed the feasibility of independent home-based training with the SCRIPT system.
(Stein et al., 2011)	Upper limb	> 6 mo nth s	Fugl- Meyer Motor Assessm ent (FMA)	Amad eo	-	Not menti oned	Fingers and Hand	-	Hand	Clinica I	Games	12	6 Weeks /3 days per week	1 hour	Change d as per user.	Visual feedback was provided using two games.	Not mentioned	Improvements were found in multiple measures of motor performance, including the Upper Extremity Fugl-Meyer, the Motor Activity Log, the Manual Ability Measure-36, and the Jebsen Hand Function Test.
(Dovat et al., 2010)	Upper limb	2 yea rs to 6 yea rs	Fugl- Meyer Motor Assessm ent (FMA)	HandC ARE	R ob t c d e v i c e	DC brush ed motor s	Hand and Fingers	Not mention ed	Fingers	Clinica I	Games	2	8 weeks (two sessio ns per week)	20 min	Not mentio ned	Games were based on visual feedback and provided virtual reality environments.	Used multi- sensory feedback to increase motivation.	There was a noticeable improvement in the Chedocke-McMaster impairment inventory which illustrated the potential of the HandCARE exercises and validated the use of the proposed metrics to evaluate hand and finger function.

(Novak et al., 2014)	Upper limb	2 yea rs to 21 yea rs	Fugl- Meyer Motor Assessm ent (FMA)	ARMin IV	7	-	Arm	Commer cial	Arm and forearm	Clinica I	Games	30 uni mp aire d and 8 imp aire d	Once	Three 5-min rounds	Game difficult y was varied during the practic e round and finally set at a level approp riate for subject s	-	Feedback was taken from participants using questionnaires.	Study showed that stroke patients prefer playing two-player rehabilitation game as compared to single-player one, as they enjoy being able to talk and otherwise interact with the other person.
(Merians et al., 2010)	Upper limb	6 (5) yea rs	Fugl- Meyer Motor Assessm ent (FMA)	Cyber Glove	-	-	Hand	Commer cial	Hand	Clinica I	Virtual Reality (Games)	11	2 weeks	2-3 Hour/session	Not mentio ned		Visual and auditory feedback	Limb control was effective and there were robust changes in functional tests of upper extremity motor control, the Wolf Motor Function Test, the Jebsen Test of Hand Function and the 9-hole Peg Test.
(Kan et al., 2011)	Upper limb	227 day s	Chedoke- McMaste r Stroke Assessm ent (CMSA)	Roboti c device	-	-	Trunk	Not mention ed	-	Clinica I	Virtual Reality	1		Three times a week for two weeks	Not applica ble	Visual feedback on hand position and target location	Feedback was taken from participants using questionnaires.	POMDPs (a partially observable Markov decision process) have promising potential to provide autonomous upper-limb rehabilitation for stroke patients.
(Simkins et al., 2012)	Upper limb	> 6 mo nth s	Chedoke- McMaste r Stroke Assessm ent (CMSA)	EXO	N ot m e n t o n e d	-	Arm	Commer cial	Arm	Clinica I	Games	10	12 sessio ns	90 min	-	Not mentioned	Feedback was taken from participants using questionnaires.	Subjects preferred static games to dynamic games when attending sessions for post- rehabilitation with the help of an exoskeleton.